Gabriel: Towards Wearable Cognitive Assistance

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Cognitive Decline



Can Wearable Technology Help?

Continuously capture, interpret, and give guidance





"Barack is saying hello to you"



"Please stop and check traffic"

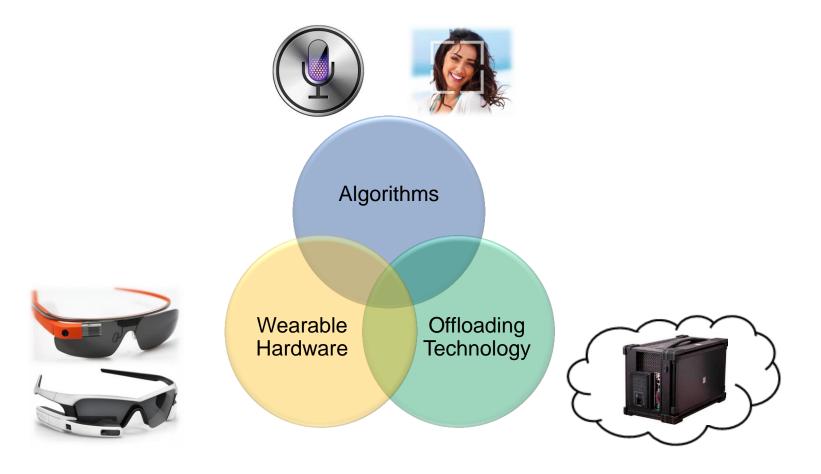


"Your dog wants to go out for a walk"



Why Today?

Advances in 3 Independent Arenas

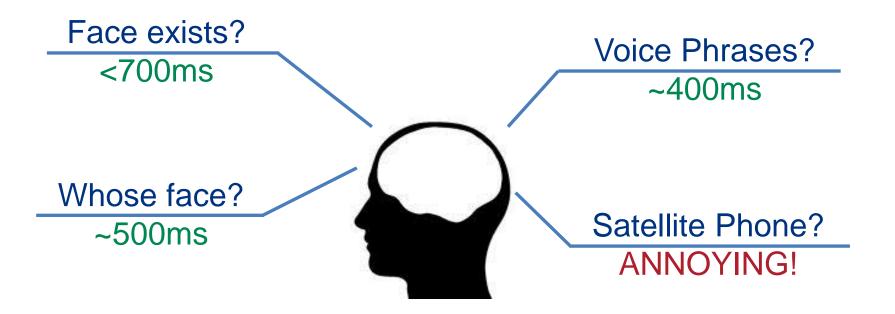


Challenges – Architecture

- 1. Crisp Interactive Response
- 2. Graceful Degradation of Services
- 3. Coarse-grain Parallelism

C1. Crisp Interactive Response

Humans are fast and sensitive



Goal: Latency of infrastructure = tens of millisecond

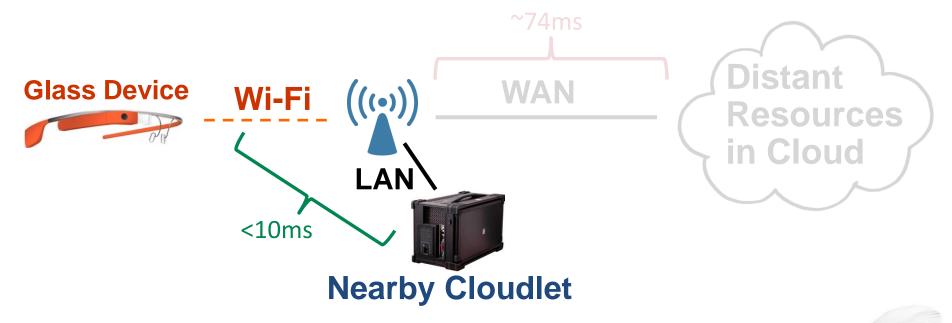
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S1. Crisp Interactive Response

Choice 1: standalone apps

Choice 2: offload to cloud

Choice 3: offload to cloudlets

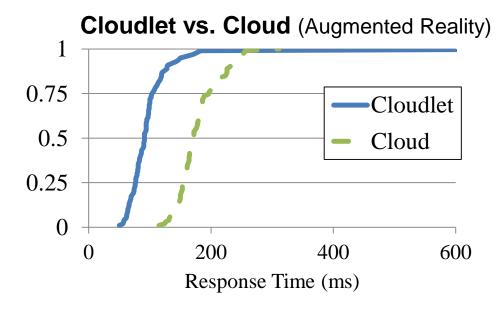


Exp. – Cloudlet Shortens Latency

Offloading vs. Standalone (OCR)

Offloading saves latency and energy

Metric	Standalone	With Offload
Per-image speed (s)	10.49	1.28
Per-image energy(J)	12.84	1.14



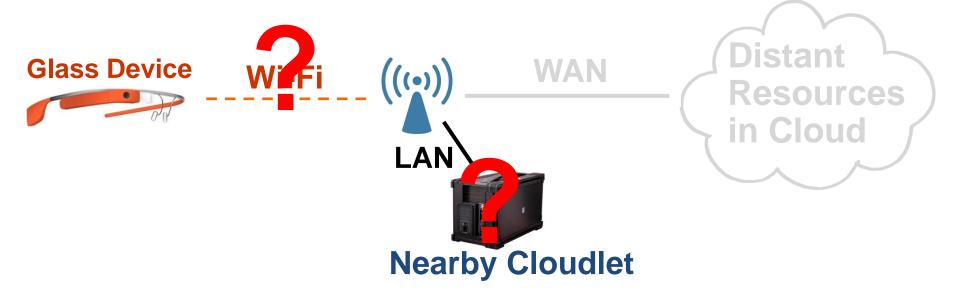
Cloudlet shortens response time

C2. Graceful Degradation of Services

What if offloading impossible?

Situation 1: No cloudlet

Situation 2: No network

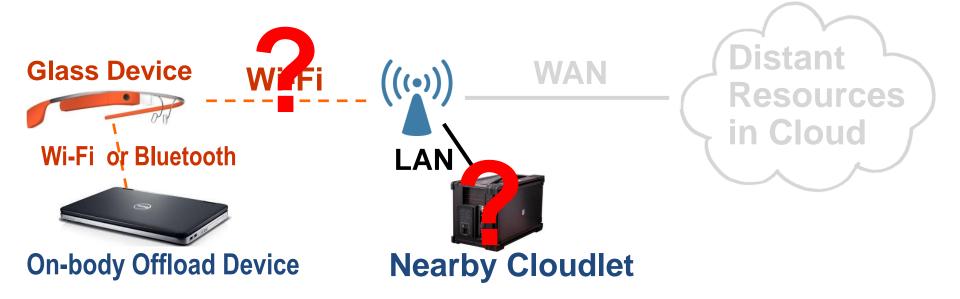


Goal: still work during failures – with performance drop

S2. Graceful Degradation of Services

Use fallback resources

No cloudlet No network



Application-specific fidelity vs. Crispness & battery life

Don't reinvent the wheel

Face recognition Object detection Activity inference OCR

Goal: reuse existing work, but...

Programming languages are different





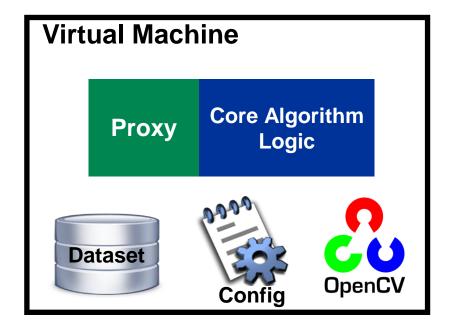




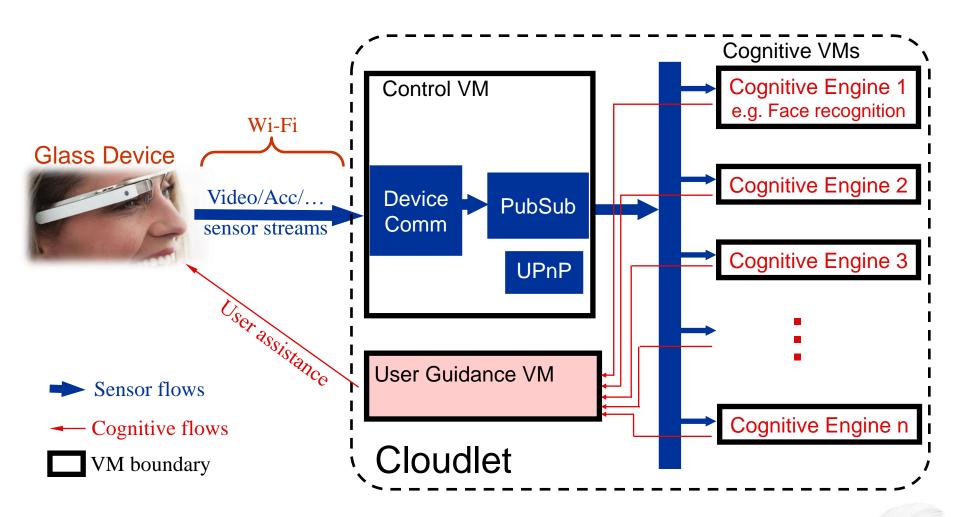
Mac OS

Runtime systems are different (different OSes, closedsource, etc.) Linux

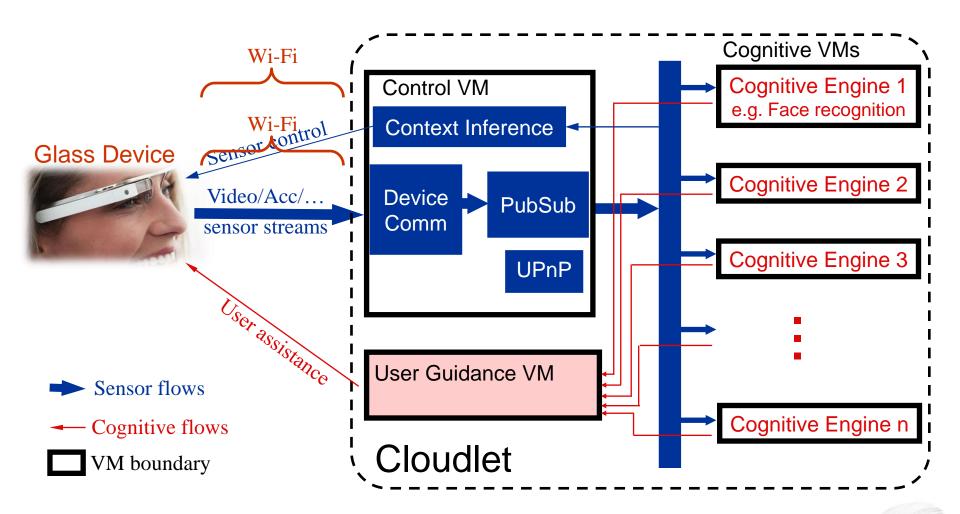
VM Ensemble and PubSub Backbone



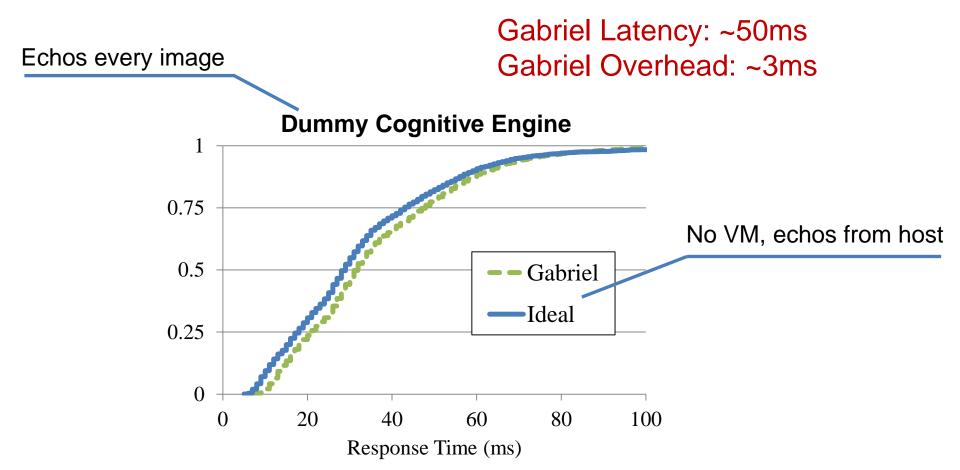
VM Ensemble and PubSub Backbone

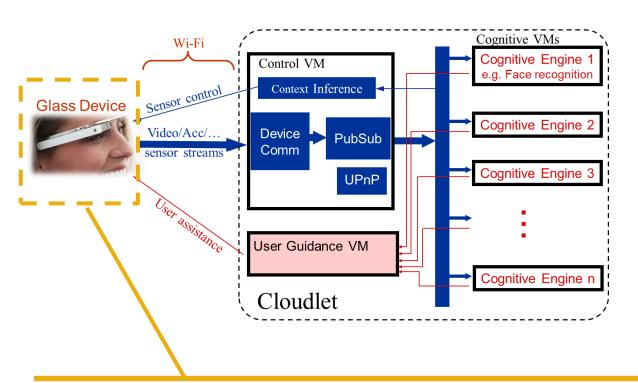


VM Ensemble and PubSub Backbone



Exp. – Gabriel Overhead





Prototype

Back-end Server

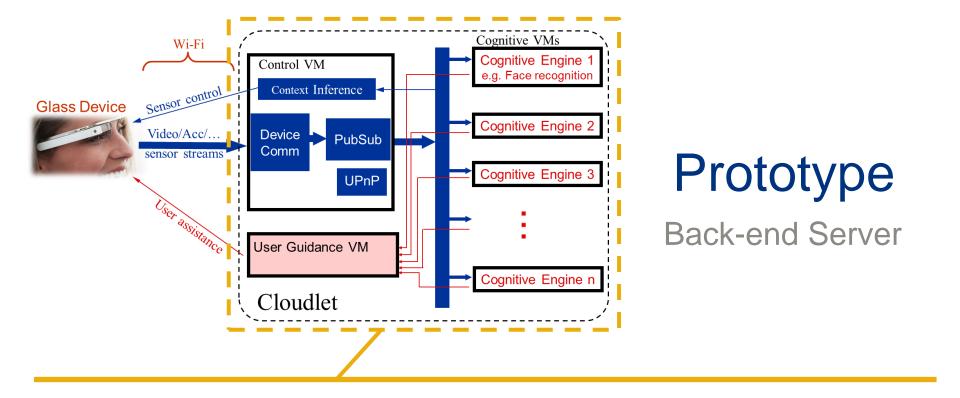
GDK Preview

TCP Connection

Speech Guidance

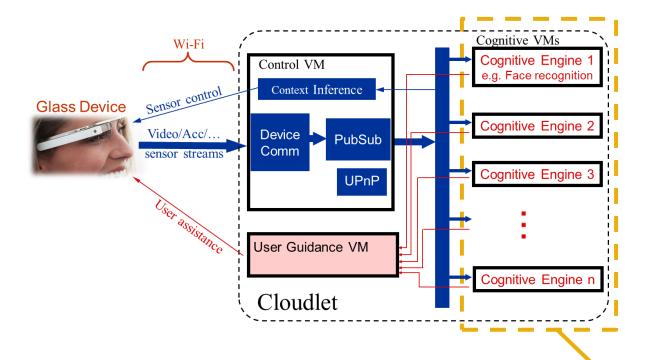


Ice pack to cool down Glass



Cloudlet: 4 advanced desktop machines

Running OpenStack – Virtualized Cloud Computing Platform



Prototype

Cognitive Engines











Face Recognition

Object Recognition (1. MOPED 2. STF)

OCR (1. Tesseract 2 VeryPDF)

Motion Classifier

Augmented Reality

Activity Detection

Commercial Product

Based on Accelerometer

Exp. – Full System Performance

Cognitive Engines are slower

	Cognitive Engine	FPS		Glass Life				
Cognitive Engine		FF3	1%	10%	50%	90%	99%	Glass Lile
	Face Recognition	4.4	196	389	659	929	1175	
	Object (MOPED)	1.6	877	962	1207	1647	2118	
	Object (STF)	0.4	4202	4371	4609	5055	5684	
	OCR (Open)	14.4	29	41	87	147	511	~1 hour
	OCR (Comm)	2.3	394	435	522	653	1021	_
	Motion Classifier	14.0	126	152	199	260	649	
	Augmented Reality	14.1	48	72	126	192	498	

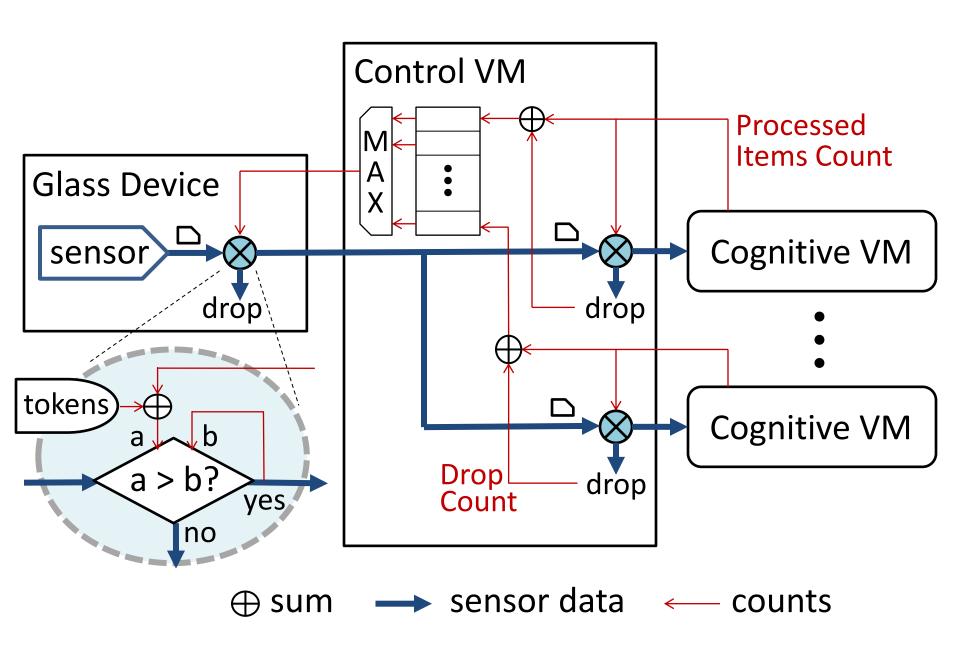
Gabriel architecture allows easy upgrade.

Exp. – Full System Performance

Cognitive Engines require different FPS

On weither Francisco	EDO						
Cognitive Engine	FPS	1%	10%	50%	90%	99%	Glass Life
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Gabriel uses two-level token-based flow control

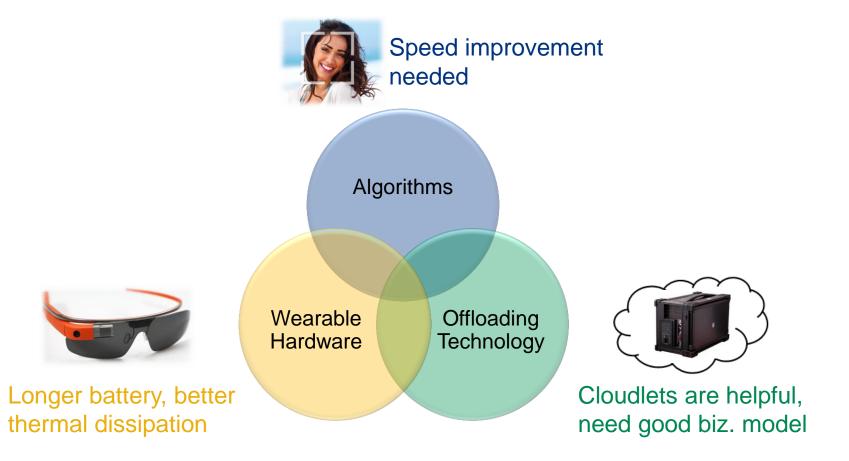


More in the Paper

- Token-based flow control improves response time a lot
- 2. Gabriel supports multi-VM parallelism
- 3. Tradeoff between fidelity reduction and crisp user interaction

Conclusion & Future Work

Gabriel: low-latency, flexible architecture

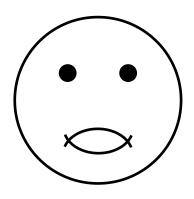


Gabriel:

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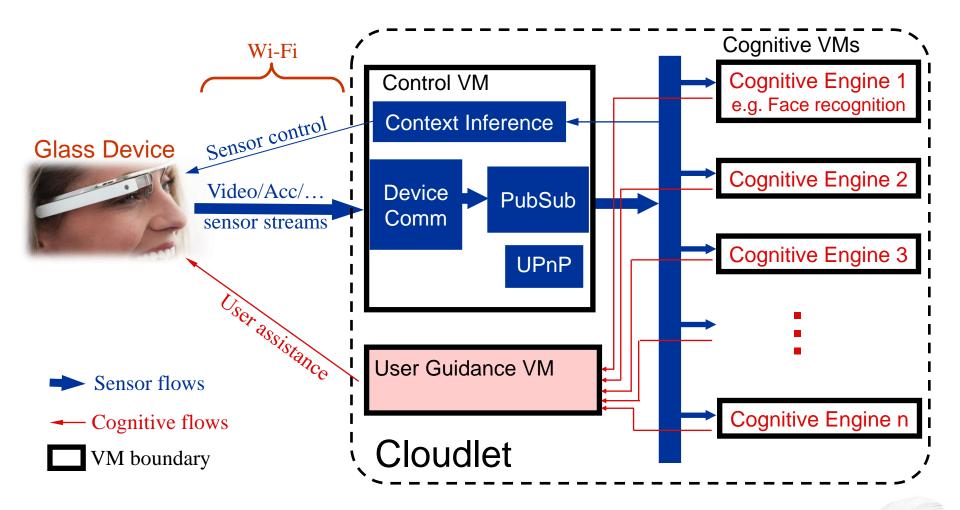
Contact: Kiryong Ha (krha@cmu.edu) Zhuo Chen(zhuoc@cs.cmu.edu)

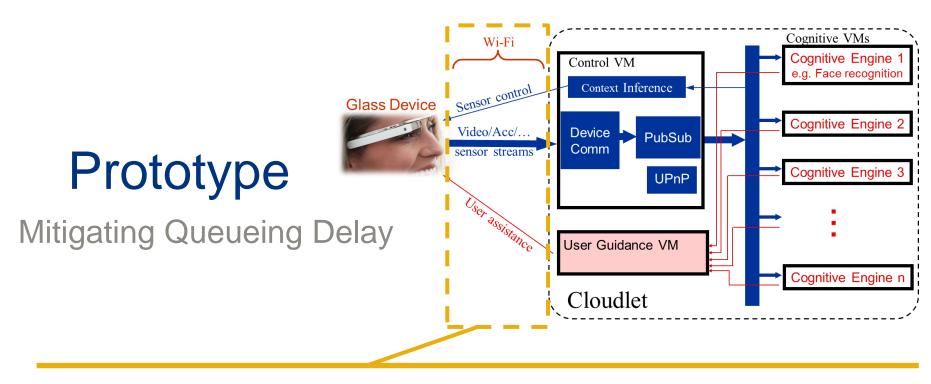
Carnegie Mellon University



Backup

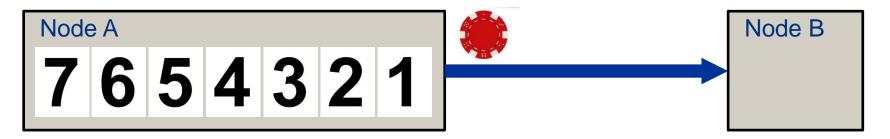
VM Ensemble and PubSub Backbone

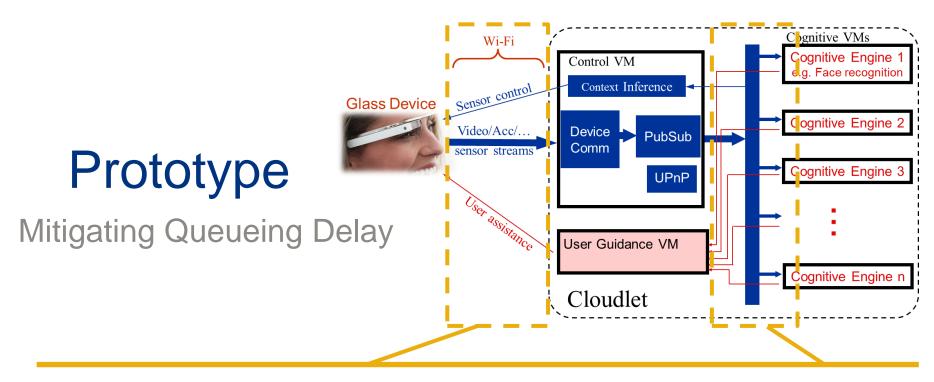




Queues hurt latency:

token-based flow control





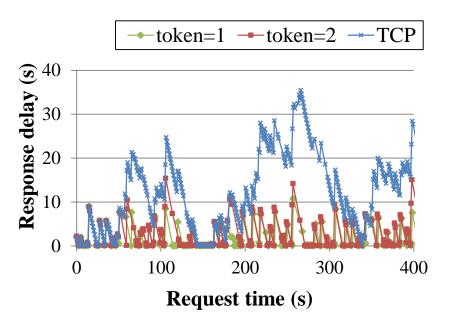
Queues hurt latency:

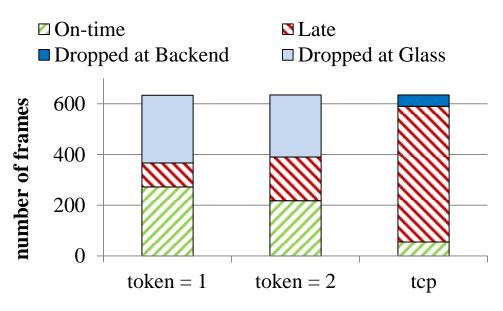
token-based flow control



Throughput vs. Latency

Exp. – Queuing Delay Mitigation





Fidelity vs. Response Time

	R	esponse	Gl	ass	G	lass	Fall	oack		
		Time		energy		ower	device			
			p	per		power				
			fra	me						
Cloudlet				boo	137	buil	ding	car	chair	dog
1080p	12	1000-			·	Duin		122	22	
Laptop		1080p		240	00		875	122	22	1004
1080p	27	720p					_			
720p	12	False n	ieg.	5	56		5	4	$\mid 0 \mid$	39
480p	6	False p	os.]	19		137	52	1	14
360p	4	480p								
Netbook		False n	eg.	12	24		19	11	2	83
480p	32	False p	os.	2	24		219	136	2	25
360p	20	360p								
		False n	ieg.	22	23		39	14	3	122
		False p	os.	2	23		273	176	5	35

S1. Crisp Interactive Response

Justification of offloading

Table 1: Evolution of hardware performance

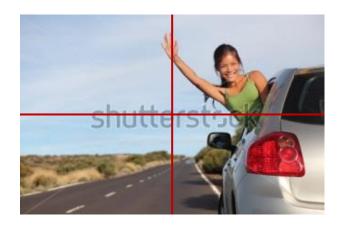
	Typical	Server	Typical Handheld or Wearable		
Year	Processor	Speed	Device	Speed	
1997	Pentium [®] II	$266~\mathrm{MHz}$	Palm Pilot	$16~\mathrm{MHz}$	
2002	Itanium®	1 GHz	Blackberry 5810	$133~\mathrm{MHz}$	
2007	Intel [®] Core TM 2	9.6 GHz (4 cores)	Apple iPhone	$412~\mathrm{MHz}$	
2011	Intel [®] Xeon [®] X5	32 GHz (2x6 cores)	Samsung Galaxy S2	2.4 GHz (2 cores)	
2013	Intel [®] Xeon [®] E5	64 GHz (2x12 cores)	Samsung Galaxy S4	6.4 GHz (4 cores)	
			Google Glass OMAP 4430	2.4 GHz (2 cores)	

Table 2: Experiment result with OCR

Metric	Standalone	With Offload
Per-image speed (s)	10.49 (0.23)	1.28 (0.12)
Per-image energy (J)	12.84 (0.36)	1.14 (0.11)

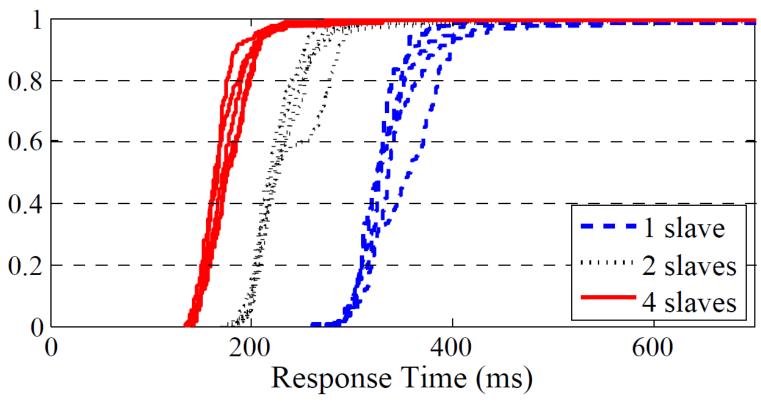
Scale-Out of Cognitive Engines

- Cognitive Engine: Motion Classifier
 - Slaves run in separate VMs
- Feature extraction



- Classification
 - A subset of classes for each slave
 - Waving
 - Clapping
 - ...

Scale-Out of Cognitive Engines



# of slaves	1	2	4
Frame Rate / fps	9.8	15.9	19.0