

## 15-451/651 Algorithm Design & Analysis, Spring 2026

### Homework #2 Solutions

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1. (\*, dynamic product maintenance mod arbitrary  $M$ )

(a) Show that given a tree where each node  $p$  is associated with a non-negative integer  $x_p$ , and a fixed modulus  $M$ , the product of each subtree mod  $M$ ,

$$\prod_{q \in \text{SUBTREE}(p)} x_q,$$

for all nodes  $p$ , can be computed in  $O(n)$  time.

**Solution:** Store the product of the subtree mod  $M$  as state in node:

$$DP[i] = \prod_{j: j \in \text{Subtree}(i)} v_j \pmod{M}$$

$DP[i] = (v[i] \times DP[i.l] \times DP[i.r]) \pmod{M}$  where  $l$  is the left child and  $r$  is the right child.

(b) Using the DP state from the above part, or some other method of your choice, give a data structure that maintains the product of a set of  $n$  non-negative integers mod  $M$  under modifications in  $O(\log n)$  time per update, and only performs multiplications modulo  $M$  on non-negative integers of value at most  $O(n^{10}M^{10})$ .

Note that  $M$  may not be prime, and the intended solution does not use any number theory beyond the fact that  $(a \cdot b) \equiv ((a \pmod{M}) \cdot b) \equiv ((a \pmod{M}) \cdot (b \pmod{M})) \pmod{M}$ .

**Solution:** Take a complete balanced binary tree with leaves set to  $x_1, \dots, x_n$  in order, and maintain the above value for the product of all leaves in each subtree.

Each internal node is  $\text{product[left]} * \text{product[right]} \pmod{M}$ . We can make modifications in  $O(\log n)$  by updating the path to the root, and can query the root which is the product of all the numbers in  $O(1)$ .

2. (\*\* weighted  $k$ -independent set) Give an algorithm that takes a tree with weights on the vertices, returns the maximum weight of a subset of exactly  $k$  vertices such that no two vertices in the set are adjacent, in time  $O(n^{10}k^{10})$ .

**Solution:** DP state is  $DP[i][k][0]$  is the max weight of a subset of  $k$  independent elements in subtree of  $i$  without root used,  $DP[i][k][1]$  is the max weight where the root is used.

Transitions:

Let the children of  $i$  be  $1 \dots d$ . We want to distribute  $k$  between whether  $i$  is in the set, and how many from subtree  $j$  is in the set,  $k_j$ .

If root is not in the set, then each child can be in or out of the set

$$DP[i][k][0] = \max_{k_1 + \dots + k_d = k} \sum_{j \in \text{Children}(i)} \max\{DP[j][k_j][0], DP[j][k_j][1]\}$$

If root is used, each children must be unused,

$$DP[i][k][1] = w_i + \max_{k_1 + \dots + k_d = k-1} \sum_{j \in \text{Children}(i)} DP[j][k_j][0]$$

Base case:  $DP[i][0][1] = 0$ ,  $DP[i][1][1] = w_i$ .

This DP as given takes time  $O(nk^{d_{\max}})$ , where  $d_{\max}$  is the maximum number of children of a node: the transitions involve  $d$  numbers,  $k_1 \dots k_d$ , each can be up to  $k$ .

To make it faster, define DP states on the children prefix  $\text{DPpartial}[i][i_1][k][0]$  for  $0 \leq i_1 \leq |\text{Children}(i)|$  to be the maximum weight in the tree induced by  $i$  and its first  $i_1$  children, using  $k$  nodes excluding  $i$ . The base case is then

$$\text{DPpartial}[i][i_1][k][0] = \begin{cases} 0 & \text{if } k = 0 \\ -\infty & \text{otherwise} \end{cases}$$

and the transition (for the children list  $\text{Children}(i) = \langle j_1 \dots j_d \rangle$ ) is

$$\text{DPpartial}[i][i_1][k][0] = \max_{0 \leq k_1 \leq k} \text{DPpartial}[i][i_1-1][k-k_1][0] + \max\{DP[j_{i_1}][k_1][0], DP[j_{i_1}][k_1][1]\}$$

for each  $i_1 > 0$ . Once we compute this, we can let  $DP[i][k][0] = \text{DPpartial}[i][d][k][0]$  for each  $k$ .

Similarly, for the case where we do take  $i$ , define  $\text{DPpartial}[i][i_1][k][1]$  for  $0 \leq i_1 \leq |\text{Children}(i)|$  to be the maximum weight in the tree induced by  $i$  and its first  $i_1$  children, using  $k$  nodes including  $i$ . The base case is

$$\text{DPpartial}[i][i_1][k][1] = \begin{cases} w_i & \text{if } k = 1 \\ -\infty & \text{otherwise} \end{cases}$$

and the transition is

$$\text{DPpartial}[i][i_1][k][1] = \max_{0 \leq k_1 \leq k} \text{DPpartial}[i][i_1-1][k-k_1][1] + DP[j_{i_1}][k_1][0]$$

for each  $i_1 > 0$ , and when done we set  $DP[i][k][1] = \text{DPpartial}[i][d][k][1]$ .

For running time, the most immediate bound is to look at all dimensions:

- (a) there are at most  $n$  nodes,
- (b) each has at most  $n$  children,
- (c) the number of things taken is up to  $k$ ,
- (d) the number of values of  $k_1$  is  $k$ ,
- (e) and taken/not taken is 2 states,

so  $O(n^2 k^2)$ .

One can get to  $O(nk^2)$  by observing that the total number of children of all nodes is  $O(n)$ . Another way to see this is to count things in the other direction: each node has at most 1 parent.

### UNNECESSARY tighter bounds

We can actually prove a tighter bound of  $O(nk)$ ...

First note that it's actually bounded by the smaller size of a child subtree:

$$\min\{k, \text{Size}[p]\} \cdot \min\{k, \text{Size}[q_1], \text{Size}[q_2]\}.$$

We can actually prove that this total cost in a tree is smaller.

**Lemma 1.** *In a binary tree with  $n$  nodes, for any value  $k$ , the total of the value in Equation 2 summed over all nodes is  $O(nk)$ .*

*Proof.* We will prove this in two steps, we first handle the case where  $\text{SIZE}[p] \leq k$ . This implies that the size of both children of  $p$  are also at most  $k$  as well.

Note that whenever  $x = x_1 + x_2$  and  $x_1 \leq x_2$ , we get via  $x_1 \leq x/2 \leq x_2$ :

$$x_1^2 + x_2^2 + x_1 \cdot x \leq x_1^2 + x_2^2 + 2x_1x_2 = (x_1 + x_2)^2 = x^2.$$

for any  $y \leq x/2$ . So we get that as long as  $\text{SIZE}[p] \leq O(k)$ , the cost is at most  $O(k \cdot \text{SIZE}[p])$ . So we can prove by induction on the value  $x$  that a node  $x$  incurs a cost of at most  $x^2$ .

For the case where the size of  $p$  is more than  $k$ , observe that there are at most  $O(n/k)$  nodes with both children having size at most  $k$ . So the total cost among such nodes is at least

$$O(n/k) \cdot O(k^2) = O(nk).$$

Then the remaining case is that one of the children has size  $< k$ , but  $p$  has size more than  $k$ . For this case, observe that we can charge a cost of  $k$  to all nodes in the smaller subtree. Such nodes are never charged again, because in that subtree there are no more nodes of size more than  $k$ . So once again we get a contribution of  $O(nk)$ .  $\square$

One additional trick that can be done to this problem is that we can reduce the total memory usage to  $O(\log n \cdot k)$ . We always recurse onto the child with bigger size first, and use tail recursion to directly pass up the size  $k$  knapsack table. This ensures that the only things we need to keep 'on the stack' are the  $O(\log n)$  ancestors with successively doubling sizes.

3. (\*\* pareto optimum points) Give an algorithm that takes a length  $n$  array of 2-tuples  $(a_i, b_i)$  and computes for **each**  $i$  whether there is some  $j < i$  such that  $i$  is larger than  $j$  in both attributes, aka.  $a_i > a_j$  and  $b_i > b_j$ , in a total time of  $O(n \log n)$ .

**Solution:** First, use sort to reduce all key values to the range  $1 \dots n$ .

Build a tree on an array  $B[1 \dots n]$  that supports:

- Modify  $B[i]$
- Query for prefix min, the minimum of  $B[1 \dots i]$  for some  $i$ .

Loop through the items in increasing order, for each  $i$ , query for the minimum  $b$  in the tree where  $a < a_i$ , by querying for the minimum of

$$B[1 \dots (a_i - 1)].$$

If it's less than  $a_i$ , then  $a_i$  has such a  $j$ .

Then update  $B[a_i]$  in the tree with  $b_i$ .

This is  $O(n)$  update/query operations, giving a total of  $O(n \log n)$ .