

# Approximability of Constraint Satisfaction Problems

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October 2009

# Constraint Satisfaction Problems (CSPs)

## Definition (CSP)

A CSP (denoted  $\text{CSP}_q(\mathcal{F})$ ), specified by

- finite domain  $[q] = \{0, 1, \dots, q - 1\}$
- *constraint language*  $\mathcal{F}$ : a collection of relations over  $[q]$ , i.e., functions  $f : [q]^{a(f)} \rightarrow \{0, 1\}$  ( $a(f)$  = arity of  $f$ )

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## Definition (CSP instance)

Variable set  $V$ .

A collection  $\mathcal{C}$  of constraints  $\{(f, S)\}$  where  $f \in \mathcal{F}$ ;  $S = a(f)$ -tuple from  $V$

Question: Is there an assignment  $\sigma : V \rightarrow [q]$  that satisfies all constraints?

i.e.,  $f(\sigma|_S) = 1$  for each  $(f, S) \in \mathcal{C}$ .

Boolean CSP,  $q = 2$ , most basic and of special interest.

CSPs capture many well studied problems in NP.

- $\mathcal{F}$  = CNF formulae: SAT
- $\mathcal{F}$  = not all equal: Graph or hypergraph  $q$ -colorability
- $\mathcal{F}$  = affine constraints: Solving linear equations

Rich set of problems based on structure of constraints in underlying  $\mathcal{F}$ .

Yet, just two possibilities complexity theoretically ...

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*More specifically,  $CSP_2(\mathcal{F})$  is polynomial time solvable if every  $f \in \mathcal{F}$  is*

- *0-valid*
- *1-valid*
- *a conjunction of Horn clauses (i.e.,  $(x_1 \wedge \dots \wedge x_k \rightarrow 0)$  or  $(x_1 \wedge x_2 \wedge \dots \wedge x_k \rightarrow x_{k+1})$ )*
- *a conjunction of dual Horn clauses*
- *a 2CNF formula, or*
- *a conjunction of affine equations*

*and is NP-complete otherwise.*

Dichotomy conjectured for every  $q$  [Feder-Vardi], proved for  $q = 3$  [Bulatov]

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satisfy *all* constraints with maximum (minimum) fraction of 1's.



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satisfy *all* constraints with maximum (minimum) fraction of 1's.
- Let's focus on unweighted Max CSP
  - Example Max CUT.  $\mathcal{F} = \{\text{cut}\}$  where  $\text{cut}(x, y) = \mathbf{1}(x \neq y)$ .  
Note  $\text{CSP}(\text{cut})$  is in P. Optimization version Max CUT is NP-hard.

Schaefer's theorem can be strengthened for the following "PCP-like" statement:

## Theorem (Khanna, Sudan, Williamson)

*For every Boolean constraint language  $\mathcal{F}$ , either  $\text{CSP}(\mathcal{F})$  is polytime decidable, or there exists  $\delta_{\mathcal{F}} < 1$  such that it is NP-hard to distinguish satisfiable instances of  $\text{CSP}(\mathcal{F})$  from instances of Max CSP( $\mathcal{F}$ ) where at most  $\delta_{\mathcal{F}}$  fraction of constraints are satisfiable.*

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However, even for Schaefer's tractable  $\mathcal{F}$  (other than 0-valid and 1-valid cases),  $\text{Max CSP}(\mathcal{F})$  is NP-hard.

## Question

Which tractable  $\mathcal{F}$  lead to easy optimization versions?

## Theorem (Creignou;KSW)

*For every Boolean constraint language  $\mathcal{F}$ , Max CSP( $\mathcal{F}$ ) is polynomial time solvable or APX-complete.*

# Dichotomy theorem for Boolean Max CSP

## Theorem (Creignou;KSW)

*For every Boolean constraint language  $\mathcal{F}$ ,  $\text{Max CSP}(\mathcal{F})$  is polynomial time solvable or APX-complete.*

*$\text{Max CSP}(\mathcal{F})$  is polytime solvable iff  $\mathcal{F}$  is 0-valid, 1-valid, or 2-monotone.*

$(f(x_1, \dots, x_k))$  is 2-monotone if it is expressible as a 2 term DNF:

$$(x_{i_1} \wedge x_{i_2} \wedge \dots \wedge x_{i_p}) \vee (\neg x_{j_1} \wedge \dots \wedge \neg x_{j_q}).$$

$\mathcal{F}$  is 2-monotone if every  $f \in \mathcal{F}$  is 2-monotone.)

# Dichotomy theorem for Boolean Max CSP

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$\mathcal{F}$  is 2-monotone if every  $f \in \mathcal{F}$  is 2-monotone.)

The 2-monotone case reduces to  $s$ - $t$  Min Cut.

# Approximating CSPs

Essentially all Max CSP problems are NP-hard, and in fact APX-hard, i.e., hard to approximate within some absolute constant  $< 1$ .

## Main goal in theory of CSP approximability

Identify **approximation threshold**  $\tau_{\mathcal{F}}$  of Max CSP( $\mathcal{F}$ ) for all (or at least interesting?)  $\mathcal{F}$ !

- Factor  $\tau_{\mathcal{F}}$  approximation algorithm (algorithm that finds assignment satisfying a fraction  $\geq \tau_{\mathcal{F}} \cdot \text{Opt}$  of constraints)
- Hardness of obtaining ratio  $\tau_{\mathcal{F}} + \varepsilon$  approximation for every  $\varepsilon > 0$ .

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Above quest has been very successful

- probably beyond even original expectations
- we now “almost know” the tight answer for *every* CSP.



- ① Positive results: Efficient algorithms with provable approximation ratios.
- ② Negative results: Achieving certain approx. ratio is NP-hard (or hard under some other complexity assumption)

Let's discuss some algorithmic results first.

# A mindless approximation algorithm

## Random assignment

For each variable independently, assign a value uniformly at random from the domain  $[q]$ .

Algorithm completely ignores structure of constraints!

In expectation, algorithm satisfies fraction  $\geq r_{\mathcal{F}} = \min_{f \in \mathcal{F}} r_f$  of constraints. ( $r_f = \text{prob. that } f(a) = 1 \text{ for random } a \in [q]^{a(f)}.$ )

Can be derandomized via conditional expectations.

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## Examples of random assignment threshold

- $\mathcal{F} = E3SAT$ :  $7/8$
- $\mathcal{F} = 2SAT$ :  $1/2$
- $\mathcal{F} = \text{affine constraints over } \mathbb{F}_p$ :  $1/p$
- $\mathcal{F} = k\text{-CUT}$ :  $1 - 1/k$
- $\mathcal{F} = 3MAJ$ :  $1/2$

# Approximation Algorithms

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- In fact, now we know this is sometimes not possible!
- Most pervasive (essentially only) technique:
  - 1 Solve a convex relaxation of the Max CSP
  - 2 "Round" the solution to an assignment

We will discuss the simplest case, when the convex relaxation is a linear program (LP), first.

# Linear Programming

Integer Linear Program formulation of Max SAT (with variables  $x_1, \dots, x_n$  and clauses  $C_1, \dots, C_m$ ):

Maximize  $\frac{1}{m} \cdot \sum_{j=1}^m z_j$  subject to

$$\sum_{x_i \in C_j^{\text{pos}}} y_i + \sum_{x_i \in C_j^{\text{neg}}} (1 - y_i) \geq z_j \quad \forall j = 1, 2, \dots, m$$

$$y_i \in \{0, 1\} \quad \forall i = 1, 2, \dots, n$$

$$0 \leq z_j \leq 1 \quad \forall j = 1, 2, \dots, m$$

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Linear program: Relax  $y_i \in \{0, 1\}$  to  $0 \leq y_i \leq 1$ .

Can solve resulting LP in polynomial time.

Easy exercise

Above LP can decide Horn Satisfiability.



# Rounding fractional solution

Need to convert fractional solution  $y_i$  to an assignment to  $x_i$ .  
Can interpret  $y_i \in [0, 1]$  as extent to which  $x_i = 1$ .

## Randomized rounding

For each  $i$  independently, set  $x_i \leftarrow 1$  with prob.  $y_i$ .

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Prob. that  $C_j$  with  $k$  literals is satisfied

$$= 1 - \prod_{x_i \in C_j^{\text{pos}}} (1 - y_i) \prod_{x_i \in C_j^{\text{neg}}} y_i$$

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# Max SAT algorithm

- Expected fraction of clauses satisfied  
 $\geq \min_k \left( 1 - (1 - 1/k)^k \right) \cdot \frac{1}{m} \sum_j z_j.$
- For optimal LP solution,  $\frac{1}{m} \sum_j z_j \geq \text{Opt}.$

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- Implies 3/4 approximation algorithm for Max 2SAT. (Random assignment gives 1/2)
- $1 - 1/e$  approximation for Max SAT.

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- $1 - 1/e$  approximation for Max SAT.
- Output better of two randomized algorithms: LP randomized rounding and random assignment  
 $\Rightarrow$  3/4 approximation for Max SAT.

# Integrality gap

Can we do better than  $3/4$  by this method (at least for Max 2SAT)?

No, since we get  $3/4$  times the optimum of the *LP*.

## Definition (Integrality gap)

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For Max 2SAT instance with 4 clauses

$$(x_1 \vee x_2) \quad (x_1 \vee \neg x_2) \quad (\neg x_1 \vee x_2) \quad (\neg x_1 \vee \neg x_2)$$

- Every assignment satisfies 3 clauses. Integral Opt =  $3/4$
- Assigning  $y_1 = y_2 = 1/2$  gives LP solution of value 1.

Thus  $3/4$  is the best possible approximation factor using this LP.

Note: Closer the integrality gap is to 1, the better the relaxation.

## Question

Could a smarter, more powerful LP yield a better approximation ratio?

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Answer: No.

For Max CUT, integrality gap is close to  $1/2$  for basic as well as more powerful LPs. [de la Vega-Mathieu], [Charikar,Makarychev,Makarychev]

- Implies  $3/4$  gap for Max 2SAT
- Beating random cut is not possible via LPs!

Let's now digress slightly:

- How does one write a canonical “basic” LP relaxation for every CSP?
- What are these more powerful strengthenings of the basic LP?

# A general LP relaxation

CSP asks for a global integral assignment to all variables  $V$ .

To make it convex, can allow probability distributions over assignments.

- Same value as integral optimum + Too many variables.

Compromise: Insist on distributions on *local* assignments, say up to  $s$  variables ( $s \geq k$ , the arity)

- For each  $S \subset V$ ,  $|S| \leq s$ , a local distribution  $\mu_S$  over  $[q]^{|S|}$ .
- Nonnegative variables  $y_{i,a}$  for each  $i \in V$  and  $a \in [q]$ , with  $\sum_a y_{i,a} = 1$ .

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Maximize  $\sum_{(f,S) \in \mathcal{C}} \mathbb{E}_{x \sim \mu_S} [ f(x) ]$  subject to:

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Stronger relaxation: Insist on consistency on all subsets of size  $r$ , for some  $1 \leq r \leq s$ .

# Semidefinite Programming

# Max Cut

Input: Graph  $G = (\{1, 2, \dots, n\}, E)$

Find  $x_i \in \{-1, 1\}$  for  $i = 1, 2, \dots, n$  that maximizes

$$\frac{1}{|E|} \sum_{(i,j) \in E} \frac{1 - x_i x_j}{2} .$$



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Objective function linear in  $y_{ij} = x_i x_j$ . Matrix  $Y = \{y_{ij}\}$ ,  $Y = xx^T$ .

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Semidefinite Relaxation: Maximize  $\frac{1}{|E|} \sum_{(i,j) \in E} \frac{1 - y_{ij}}{2}$  subject to

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Can solve above to any desired accuracy in polynomial time [Alizadeh].

Set of PSD matrices is convex, and it is possible to find optimum of linear function over it.

## A vector view

Since a positive semidefinite matrix  $Y$  admits Cholesky decomposition  $Y = V^T V$ , the semidefinite program (SDP) finds vectors  $v_i$ ,  $1 \leq i \leq n$ , with  $\|v_i\| = 1$  maximizing

$$\frac{1}{|E|} \sum_{(i,j) \in E} \frac{1 - \langle v_i, v_j \rangle}{2}.$$

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## Key question

How to “round” vector solution to a Boolean cut?

## Goemans-Williamson

Pick random hyperplane through the origin. Two hemispheres correspond to two sides of cut.

Pick random vector  $r$  and set

$$x_i = \text{sign}(\langle v_i, r \rangle) .$$

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Intuition: If  $(i, j)$  has large contribution  $(1 - \langle v_i, v_j \rangle)/2$  to objective function, then angle between  $v_i, v_j$  is large, and there is a good chance that  $v_i, v_j$  are separated by a random hyperplane.

# Rounding analysis

Local analysis for each edge  $(i, j)$ .

$\theta$  = angle between  $v_i$  and  $v_j$ .

Contribution to SDP objective function

$$\frac{1 - \langle v_i, v_j \rangle}{2} = \frac{1 - \cos \theta}{2}$$

Probability that we cut edge  $(i, j)$

$$\Pr_r[\text{sign}(\langle v_i, r \rangle) \neq \text{sign}(\langle v_j, r \rangle)] = \frac{\theta}{\pi}.$$



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Minimum quotient gives approximation factor

$$\alpha_{GW} = \min_{\theta} \frac{2\theta}{\pi(1 - \cos \theta)} \approx 0.8785 .$$

# Other Boolean 2CSPs

SDP based algorithms beat the mindless (random assignment) algorithm for all Boolean 2CSPs.

- Max 2SAT:  $\alpha_{GW} = 0.8785\dots$   
Many subsequent improvements: [Feige-Goemans] 0.931;  
[Lewin-Livnat-Zwick] 0.94016.
- Max 2CSP: [GW] 0.796.  
[LLZ] improved this to 0.87401.

Natural SDP relaxations; more complicated rounding.

# Relaxation for 2SAT

Unit vectors  $v_i$  for variables  $x_i$ , and a global unit vector  $b_0$  (representing False).

For clause  $(x_i \vee x_j)$ : contribution to objective function

$$\frac{3 - \langle b_0, v_i \rangle - \langle b_0, v_j \rangle - \langle v_i, v_j \rangle}{4}$$

SDP maximizes sum of above over all clauses.

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SDP maximizes sum of above over all clauses.

Can also add “triangle inequalities”

$$\langle (b_0 \pm v_i), (b_0 \pm v_j) \rangle \geq 0 .$$

# SDP for general CSP

Variables  $V = \{x_1, \dots, x_n\}$ , Domain  $[q]$ . Constraints  $\mathcal{C}$ .

SDP variables and vectors:

- Vectors  $v_{i,a}$  for  $1 \leq i \leq n$  and  $a \in [q]$ .
- For each constraint  $(f, S) \in \mathcal{C}$ , a local distribution  $\mu_{(f,S)}$  over  $[q]^S$  (assignments to variables in  $S$ ).

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Variables  $V = \{x_1, \dots, x_n\}$ , Domain  $[q]$ . Constraints  $\mathcal{C}$ .

SDP variables and vectors:

- Vectors  $v_{i,a}$  for  $1 \leq i \leq n$  and  $a \in [q]$ .
- For each constraint  $(f, S) \in \mathcal{C}$ , a local distribution  $\mu_{(f,S)}$  over  $[q]^S$  (assignments to variables in  $S$ ).

Maximize  $\sum_{(f,S) \in \mathcal{C}} \mathbb{E}_{x \sim \mu_{(f,S)}} [f(x)]$  subject to:

- 1  $\sum_{a \in [q]} \langle v_{i,a}, v_{i,a} \rangle = 1 \quad \forall i$
- 2  $\mu_{(f,S)}(x) \geq 0$  and  $\sum_x \mu_{(f,S)}(x) = 1 \quad \forall (f, S) \in \mathcal{C}$ .
- 3  $\langle v_{i,a}, v_{j,b} \rangle = \Pr_{x \sim \mu_{(f,S)}} [x_i = a \text{ and } x_j = b]$   
 $\forall (f, S) \in \mathcal{C}; \quad x_i, x_j \in S; \quad a, b \in [q].$

In words..

Consistency of local integral distributions on pairs + positive semidefiniteness of pairwise joint probabilities.

# Hardness of approximation results

Starting point for inapproximability results is the famous **PCP theorem**.

## Theorem (PCP theorem)

*For some absolute constant  $\rho < 1$ , there is a polynomial time reduction from NP-complete problem 3SAT to Max 3SAT mapping  $\phi \mapsto \psi$  such that:*

- *(Perfect) completeness: If  $\phi$  is satisfiable, then so is  $\psi$ .*
- *Soundness: If  $\phi$  is not satisfiable, then every assignment satisfies at most  $\rho$  fraction of  $\psi$ 's clauses.*



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Original proof [Arora-Safra], [Arora-Lund-Motwani-Sudan-Szegedy]:

Algebraic techniques: arithmetization, low-degree testing; query parallelization, proof composition, etc.

New proof [Dinur]: expander graphs, iterative amplification of gap.

These give **poor** inapproximability constants  $\rho$ .

# An optimal result

Subsequent improvements to the constants culminated in the following striking optimal result:

## Theorem (Håstad)

*For every integer  $q \geq 2$  and all  $\varepsilon, \delta > 0$ , it is NP-hard to approximate Max E3-LIN-mod- $q$  within  $\frac{1}{q} + \varepsilon$ .*

- *Hard to tell if linear system is  $(1 - \varepsilon)$ -satisfiable or at most  $(\frac{1}{q} + \delta)$ -satisfiable.*

Mindless random assignment algorithm achieves approximation ratio  $1/q$ .

# A powerful result

Gives many other tight (or best known) results by gadgets.

Reduce Max E3-Lin-mod-2 to Max E3SAT

- Replace  $x \oplus y \oplus z = 0$  by 4 clauses  $(\neg x \vee \neg y \vee \neg z)$ ,  $(\neg x \vee y \vee z)$ ,  $(x \vee \neg y \vee z)$ ,  $(x \vee y \vee \neg z)$ .
- Gives  $7/8 + \varepsilon$  inapproximability factor for Max E3SAT.

Gives  $2/3 + \varepsilon$  inapprox. factor for Max 3MAJ. Also tight.

$21/22 + \varepsilon$  for Max 2SAT,  $16/17 + \varepsilon$  for Max CUT,  $15/16 + \varepsilon$  for Max NAE3SAT, etc.

- (Probably) not tight, but remain best known NP-hardness bounds.

# Perfect completeness

- Reducing 3LIN to 3SAT shows that it is hard to satisfy more than  $7/8$  of clauses in a  $(1 - \epsilon)$ -satisfiable formula.
- Inherent for 3LIN
- What about satisfiable 3SAT formulae?

- Reducing 3LIN to 3SAT shows that it is hard to satisfy more than  $7/8$  of clauses in a  $(1 - \epsilon)$ -satisfiable formula.
- Inherent for 3LIN
- What about satisfiable 3SAT formulae?

## Theorem (Håstad)

*For every  $\delta > 0$ , given an E3SAT formula  $\phi$ , it is NP-hard to distinguish between the cases when  $\phi$  is satisfiable and when  $\phi$  is at most  $(\frac{7}{8} + \delta)$ -satisfiable.*

Next:

- 1 Some details about such tight hardness results.
- 2 Approximation resistance

Followed by reductions from Unique Games.

# Label Cover

Starting point for strong inapproximability results is almost always the **Label Cover** problem.

Parameterized by integer  $R$ . Denote by  $\text{LabelCover}(R)$ .

- 2CSP over large domain (of size  $R$ )
- “Projection” constraints

# Label Cover

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- 2CSP over large domain (of size  $R$ )
- “Projection” constraints

Instance consists of:

- 1 Bipartite graph  $G = (V, W, E)$ .
- 2 For each  $e \in E$ , a function  $\pi_e : [R] \rightarrow [R]$ .

The value of an assignment (labeling)  $\ell : V \cup W \rightarrow [R]$  is the fraction of edges  $e = (v, w)$  for which  $\pi_e(\ell(w)) = \ell(v)$ .

Optimization goal: Find labeling with maximum value.



# Hardness of Label Cover

## Theorem (PCP theorem + Raz's parallel repetition)

*There exists an absolute constant  $\gamma_0 > 0$  such that for all  $R$  it is NP-hard to tell if an instance of  $\text{LabelCover}(R)$  has value 1 or value at most  $1/R^{\gamma_0}$ .*

By picking  $R$  large enough, get arbitrarily large gap for a rather nice 2CSP (over a large alphabet).

# Reducing from Label Cover

Gadget: “Encode” the projection constraint  $\pi(\ell(w)) = \ell(v)$  on labels  $\ell(v), \ell(w)$  belonging to large alphabet  $[R]$  as (a collection of) simple *tests* on *few bits*.

- Test should correspond to target CSP
- For example, for Max E3-LIN-Mod-2, check parity of 3 bits  
( $x \oplus y \oplus z = 0/1$ )

Must necessarily have larger soundness error, but amazingly can get the optimal bound for many CSPs (3LIN, 3SAT, 4-set-splitting, etc.)

To reduce projection constraint to some Boolean CSP:

- Expect Boolean tables  $f$  and  $g$  encoding  $\ell(v)$  and  $\ell(w)$  respectively (as per some code  $C$ ).
- Check binary constraints on few locations of  $f$  and  $g$  (example  $f(x) \oplus g(y) \oplus g(z) = 0$ )

Property we would like to guarantee:

- 1 *Completeness*: For  $a, b$  satisfying  $\pi(b) = a$ , legal encoding  $f, g$  of  $a, b$  satisfies all (or most of) the binary constraints.
- 2 *Soundness*: If  $f, g$  satisfy more than  $s + \delta$  fraction of constraints, then can “decode”  $f, g$  into “consistent” labels.

Which “code” to use (for binary encoding of labels)?

Great suggestion by [Bellare-Goldreich-Sudan]: **Long code**

Long code encoding LC maps  $[R]$  to  $\{0, 1\}^{2^R}$

- Long encoding of  $a \in [R]$ , denoted  $LC^{(a)}$ , is a Boolean function  $\{0, 1\}^R \rightarrow \{0, 1\}$
- $LC^{(a)}(x) = x_a$ . “Dictator” function — projection on the  $a$ 'th coordinate.

Long code is the *most redundant* of all codes!! (When  $R$  is a constant, we can afford it.)

Redundancy enables (approximate) checking of global property (namely, the projection constraint on  $[R]$ ) by very local constraints.

# Long code testing

- Given tables/functions  $f : \{0, 1\}^R \rightarrow \{0, 1\}$  and  $g : \{0, 1\}^R \rightarrow \{0, 1\}$ , and a projection constraint  $\pi : [R] \rightarrow [R]$ .
- Goal: Check if  $f$  and  $g$  are long codes of “consistent” values  $a$  and  $b$  that satisfy  $\pi(b) = a$ .
- Only allowed to query very few (randomly picked) locations of  $f, g$ , and check they obey a local constraint.

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A 3-query test (aimed at showing hardness for Max E3LIN-Mod-2):

- Pick  $x, y \in \{0, 1\}^R$  independently and u.a.r.
- Define  $z \in \{0, 1\}^R$  by  $z_j = y_j \oplus x_{\pi(j)}$ .
- With prob.  $1/2$  check  $f(x) \oplus g(y) \oplus g(z) = 0$ ,  
and with prob.  $1/2$  check  $f(x) \oplus g(y) \oplus g(\bar{z}) = 1$   
(here  $\bar{z}$  denotes the coordinate-wise complement of the bit vector  $z$ ).

# Is this a good test?

Completeness: Suppose  $f(x) = x_a$  and  $g(y) = y_b$  and  $\pi(b) = a$ . Then

$$g(z) = z_b = y_b \oplus x_{\pi(b)} = y_b \oplus x_a .$$

So  $f(x) \oplus g(y) \oplus g(z) = x_a \oplus y_b \oplus (y_b \oplus x_a) = 0$ .

Similarly  $f(x) \oplus g(y) \oplus g(\bar{z}) = 1$

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Thus *all* 3LIN constraints are satisfied.

Soundness?

## Question

If most 3LIN constraints are satisfied, does it mean that  $f, g$  are “like” long codes (in some reasonable sense)?

Answer: NO.



**Polymorphisms:** For linear equations mod 2, xor of an odd number of satisfying assignments gives another satisfying assignment.

The functions  $g(y) = y_1 \oplus y_2 \oplus \cdots \oplus y_{2k+1}$  and  $f(x) = x_{\pi(1)} \oplus x_{\pi(2)} \oplus \cdots \oplus x_{\pi(2k+1)}$  also satisfy all constraints.

For  $k$  large,  $g$  is “not like” any long code.

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For  $k$  large,  $g$  is “not like” any long code.

Håstad’s insight: add noise to attenuate linear functions of many variables ( “dampen high frequencies” )

- Must lose perfect completeness as satisfiability of linear equations is in P.

## 3LIN test with noise

- Sample  $x, y \in \{0, 1\}^R$  independently and u.a.r.
- Sample  $\mu \in \{0, 1\}^R$  as follows: for each  $j \in [R]$  independently

$$\mu_j = \begin{cases} 0 & \text{with prob. } 1 - \varepsilon \\ 1 & \text{with prob. } \varepsilon \end{cases}$$

- Define  $z \in \{0, 1\}^R$  by  $z_j = x_{\pi(j)} \oplus y_j \oplus \mu_j$ .
- With prob.  $1/2$  check  $f(x) \oplus g(y) \oplus g(z) = 0$ ,  
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Completeness: If  $g(y) = y_b$  and  $f(x) = x_{\pi(b)}$ ,  $(1 - \varepsilon)$  of the 3LIN constraints are satisfied (whenever  $\mu_b = 0$ ).

### Easy calculation

For odd  $k$ , probability that xor of  $k$  long codes (i.e., linear function of  $k$  variables) satisfies the tested 3LIN constraint equals  $\frac{1}{2} + \frac{(1-2\varepsilon)^k}{2}$ .

# Soundness for general functions

By expressing  $f, g$  (or rather  $(-1)^f, (-1)^g$ ) as a linear combination of linear functions (“Fourier-Walsh” expansion), can prove that if  $(1/2 + \delta)$  of the 3LIN checks are satisfied, then there must exist

$$S, T \subset [R], \quad |S|, |T| \leq c(\delta, \varepsilon), \quad S \cap \pi(T) \neq \emptyset$$

for which  $f$  (resp.  $g$ ) has non-trivial agreement with the linear function  $\bigoplus_{i \in S} x_i$  (resp.  $\bigoplus_{j \in T} y_j$ ).

- In fact,  $\exists$  distributions  $D_f$  and  $D_g$  on  $2^{[R]}$  for which above happens with good probability (for  $(S, T) \in_R D_f \times D_g$ ).

$\exists$  a *randomized “decoding” procedure*  $\text{Dec}$  mapping a Boolean function on  $\{0, 1\}^R$  to  $[R]$  such that, when  $f, g$  satisfy above condition,

$$\Pr[\text{Dec}(f) = \pi(\text{Dec}(g))] > \alpha(\delta, \varepsilon) .$$

# Overall reduction from Label Cover

Plug in long code test on functions  $f_u, g_v$  for every edge  $e = (u, v)$  with projection constraint  $\pi_e$ .

Completeness  $(1 - \varepsilon)$ : Just use long codes of a satisfying assignment to Label Cover instance.

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- Run Dec independently for each  $f_u$  and each  $g_v$ .
- Averaging:  $\geq \delta$  fraction of edges  $(u, v)$  are *good*, i.e.,  $\geq (1/2 + \delta)$  of 3LIN constraints on the long code test for  $(f_u, g_v)$  are satisfied.
- For each good edge, decoded labels are consistent with prob.  $\alpha(\delta, \varepsilon)$ .
- Labeling output by Dec satisfies expected  $\delta \cdot \alpha(\delta, \varepsilon)$  fraction of Label Cover constraints.
- Pick  $R$  large enough so that  $\delta \cdot \alpha(\delta, \varepsilon) > R^{-\gamma_0}$ .



# Approximation resistance

# Beating random assignment

- Max E3LIN-Mod-2, Max E3SAT, Max 4-set splitting, etc. are **approximation resistant**, in the sense that beating the mindless random assignment algorithm is NP-hard.
- Max 2SAT, Max CUT, Max 2CSP admit non-trivial approximations (via semidefinite programming).

## Question

Which predicates lead to approximation resistant Max CSPs?

Every 2CSP (over any domain  $[q]$ ) is **not** approximation resistant.  
[Goemans-Williamson], [Engebretsen-G], [Håstad]

Bounded occurrence CSPs approximable beyond random assignment threshold [Håstad]

Complete answer for Boolean 3CSPs

- Approximation resistant iff implied by parity or its complement, otherwise admits non-trivial approximation. [Håstad] + [Zwick]

[Hast] classified 354 of the 400 essentially different arity 4 Boolean CSPs (79 approximation resistant).

# Approximation resistance results

Large  $k$ :

- Boolean  $k$ CSP with  $2^{O(\sqrt{k})}$  satisfying assignments that is approximation resistant. [Samorodnitsky-Trevisan], [Håstad-Khot]
- No predicate with  $\leq c \cdot k$  satisfying assignments is approximation resistant [Hast; Charikar-Makarychev-Makarychev]
- Random predicate is approx. resistant w.h.p. [Håstad]\*

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- Random predicate is approx. resistant w.h.p. [Håstad]\*

If there is a pairwise independent distribution supported within the satisfying assignments of the predicate, then it is approximation resistant\* [Austrin-Mossel]

- Implies earlier result of [Samorodnitsky-Trevisan] that Max  $k$ CSP is hard to approximate with a factor  $\Theta(k/2^k)^*$

For more details, go to Per Austrin's talk.

\* assuming the Unique Games conjecture

# Approximability of 2CSPs

Label Cover + Long Code ( $LC^2$ ) framework  $\implies$  many powerful hardness results for CSPs of arity 3 and above.

What about 2CSPs where SDPs give non-trivial (and sometimes bizarre irrational) approximation ratios?

Good 2-query tests for testing consistency (as per projection  $\pi$ ) of a pair of purported long codes  $f, g$ ?

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Good 2-query tests for testing consistency (as per projection  $\pi$ ) of a pair of purported long codes  $f, g$ ?

Here's a natural test (that "saves" one query in Håstad's test):

- Pick  $x \in \{0, 1\}^R$  u.a.r, and noise vector  $\mu \in \{0, 1\}^R$  s.t.  $\mu_l = 0$  with prob.  $1 - \varepsilon$  for each  $l \in [R]$ .
- For each  $j \in [R]$ , set  $y_j = x_{\pi(j)} \oplus \mu_j$ .
- With prob.  $1/2$ , check  $f(x) \oplus g(y) = 0$ ,  
with prob.  $1/2$ , check  $f(x) \oplus g(\bar{y}) = 1$ .

# Good test?

- Query  $y \in \{0, 1\}^R$  to table  $g$  is highly non-uniform.
- $y \approx x \circ \pi$  reveals lot of information about  $\pi$ :  $y_k = y_l$  whenever  $\pi(k) = \pi(l)$  and independent otherwise.
- Thus can “piece together” many inconsistent  $g$ , say a different long code for each part of the hypercube corresponding to the different projection constraints  $\pi_e$  in which  $w$  participates.
  - No hope of decoding a single global label  $\ell(w)$  for  $w$ .
- What would/could fix this?



# Unique Games CSP

Khot's insight: This problem goes away if  $\pi$  is a *bijection*.

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Reduce from special case of LabelCover( $R$ ) called UniqueGames( $R$ ).

Same as Label Cover, except for each  $e \in E$ , the projection constraint  $\pi_e$  is a **bijection**. Formally, instance consists of

- 1 Bipartite graph  $G = (V, W, E)$ .
- 2 For each  $(v, w) \in E$ , a bijection  $\pi_{w \rightarrow v} : [R] \rightarrow [R]$ .

Goal: Find labeling  $\ell : V \cup W$  with maximum "value", where value = fraction of edges  $(v, w) \in E$ ,  $\pi_{w \rightarrow v}(\ell(w)) = \ell(v)$ .

Example of UniqueGames( $R$ ): E2-Lin-mod- $R$ .

- Equations of form  $x_i - x_j \equiv c_{ij} \pmod{R}$ .

## Theorem (Easy)

*Given a UniqueGames( $R$ ) instance, telling if it is satisfiable (i.e., admits labeling with value 1) is in  $P$ .*

# Complexity of Unique Games

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*Given a UniqueGames( $R$ ) instance, telling if it is satisfiable (i.e., admits labeling with value 1) is in  $P$ .*

## Unique Games conjecture — UGC [Khot]

For every  $\varepsilon, \delta > 0$ , there is a large enough  $R$  such that given an instance  $\mathcal{I}$  of UniqueGames( $R$ ), it is hard to distinguish between the following two cases:

- 1  $\mathcal{I}$  admits a labeling with value  $\geq 1 - \varepsilon$ .
- 2 All labelings to  $\mathcal{I}$  have value  $\leq \delta$ .

Small amount of noise renders problem inapproximable...

# Why UGC?

UGC has some powerful implications:

- Many optimal inapproximability results: Vertex Cover on graphs and hypergraphs, *every* CSP, *every* ordering CSP.
- Led to new integrality gap constructions (and important consequences for metric embeddings)

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- Led to new integrality gap constructions (and important consequences for metric embeddings)

Notorious conjecture; no consensus either way ...

- Seemingly no plausible avenue to prove it currently?  
Suffices to prove conjecture for  $\delta = 0.99$ , or even  $\delta = 1 - \epsilon^{0.51}$ .
- Attempts to disprove (based on natural SDP) have failed, but potential of strengthened SDPs not fully ruled out.
- **Not** approximation resistant (it is a 2CSP).  
 $\approx 1/R^{\epsilon/2}$  approximation known. Any improvement would refute UGC.

Testing bijection constraint  $\pi(b) = a$  given purported long codes  $f, g$  of  $a, b$ :

- Pick  $x \in \{0, 1\}^R$  u.a.r, and  $\varepsilon$ -biased noise vector  $\mu \in \{0, 1\}^R$ .
- Set  $y = x \circ \pi \oplus \mu$ , i.e., for each  $j \in [R]$ ,  $y_j = x_{\pi(j)} \oplus \mu_j$ .
- With prob.  $1/2$ , check  $f(x) \oplus g(y) = 0$ ,  
with prob.  $1/2$ , check  $f(x) \oplus g(\bar{y}) = 1$ .

Now that  $\pi$  is a bijection, turns out it is enough to just test **one** function (essentially assume  $\pi = \text{Id}$ ).

# Dictatorship testing

Given access to  $f : \{0,1\}^R \rightarrow \{0,1\}$ .

Make few queries to  $f$ , according to some clever distribution, and check constraint  $\Gamma$  on queried bits.

- $\Gamma$  corresponds to target CSP of interest. Eg. for Max CUT, check  $f(x) \neq f(y)$ .

Aim: Test must distinguish dictator functions from functions far from every dictator.



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Aim: Test must distinguish dictator functions from functions far from every dictator.

**Completeness** For every  $i \in [R]$ , if  $f$  is the dictator function  $f(x) = x_i$ , test accepts with probability  $\geq c$ .

**Soundness** If  $\text{Influence}_i(f)$  is “small” for every  $i \in [R]$ , then test accepts with probability  $\leq s$ .

$$\text{Influence}_i(f) = \Pr_x[f(x) \neq f(x \oplus e_i)]$$

Why dictatorship tests?

# Dictatorship test for Max Cut

Parameter  $\rho > 1/2$ .

Testing a function  $f : \{0, 1\}^R \rightarrow \{0, 1\}$

- Pick  $x \in \{0, 1\}^R$  u.a.r.
- For each  $j \in [R]$ ,

$$y_j = \begin{cases} x_j & \text{with prob. } 1 - \rho \\ \bar{x}_j & \text{with prob. } \rho \end{cases}$$

- Check the CUT constraint  $f(x) \neq f(y)$ , accept if so.

## Completeness

When  $f$  a dictator, say  $f(x) = x_i$ ,

Probability test accepts  $= \rho$ .

# Dictatorship test for Max Cut

## Soundness

What's the best  $f$  that has no influential coordinates?

# Dictatorship test for Max Cut

## Soundness

What's the best  $f$  that has no influential coordinates?

Answer: Majority function.

Also,  $\Pr_{x,y}[\text{Maj}(x) \neq \text{Maj}(y)] \rightarrow \frac{\arccos(1-2\rho)}{\pi}$  for large  $R$ .

## Theorem (Majority is Stablest (Mossel-O'Donnell-Oleszkiewicz))

For all  $\rho > 1/2$  and  $\varepsilon > 0$ , there is a small enough  $\tau = \tau(\rho, \varepsilon) > 0$  s.t. if

$$\Pr_{x,y}[f(x) \neq f(y)] \geq \frac{\arccos(1-2\rho)}{\pi} + \varepsilon,$$

then for some  $i \in [R]$ ,  $\text{Influence}_i(f) \geq \tau$ .

# Dictatorship test for Max Cut

## Soundness

What's the best  $f$  that has no influential coordinates?

Answer: Majority function.

Also,  $\Pr_{x,y}[\text{Maj}(x) \neq \text{Maj}(y)] \rightarrow \frac{\arccos(1-2\rho)}{\pi}$  for large  $R$ .

## Theorem (Majority is Stablest (Mossel-O'Donnell-Oleszkiewicz))

For all  $\rho > 1/2$  and  $\varepsilon > 0$ , there is a small enough  $\tau = \tau(\rho, \varepsilon) > 0$  s.t. if

$$\Pr_{x,y}[f(x) \neq f(y)] \geq \frac{\arccos(1-2\rho)}{\pi} + \varepsilon,$$

then for some  $i \in [R]$ ,  $\text{Influence}_i(f) \geq \tau$ .

Therefore, get  $\rho - \varepsilon$  vs.  $\frac{\arccos(1-2\rho)}{\pi} + \varepsilon$  gap (for any  $1/2 < \rho < 1$ ).

- or  $\frac{1-\cos\theta}{2} - \varepsilon$  vs.  $\frac{\theta}{\pi} + \varepsilon$  where  $\theta = \arccos(1 - 2\rho) \in (\pi/2, \pi)$ .
- Same as SDP optimum vs. cut found by random hyperplane rounding!
- Optimizing over  $\theta$ , gives 0.8785.. hardness factor for Max CUT [Khot-Kindler-Mossel-O'Donnell]

# Approximate polymorphism perspective

Polymorphism combines many satisfying assignments to produce a new satisfying assignment.

- Dictator/projection functions  $\Leftrightarrow$  trivial polymorphism

“Approximate polymorphism” combines assignments satisfying  $\text{Opt}$  fraction of constraints to a new assignment.

- Dictator function: preserves fraction  $\text{Opt}$  of satisfied constraints.
- What's the best *non-influential* polymorphism?

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Majority is a (non-trivial) polymorphism for CSP(cut).

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In the context of Max CUT:

- Majority is the *best* “low-influence” approximate polymorphism.
- Given  $R$  distributions over assignments that satisfy a specific cut constraint with probability  $\rho$ 
  - coordinate-wise majority satisfies that constraint with probability  $\approx \frac{\arccos(1-2\rho)}{\pi}$
  - And this is largest possible for combining functions with no influential variable.

More about this in Prasad Raghavendra’s talk after lunch.



# Constructing dictatorship tests

For Max Cut, we “cooked” up a natural test.

In general, how to get a good dictatorship test for a CSP?

## Very general answer [Raghavendra]

Can convert **any** integrality gap instance for the “canonical” semidefinite program into dictatorship test with matching parameters!

- Instance with SDP opt  $c$  and integral optimum  $s \implies$  Dictatorship test with completeness  $c - \epsilon$  and soundness  $s + \epsilon$ .

Proof proceeds via a rounding algorithm for the SDP.

## Corollary

*Assuming UGC, the canonical SDP delivers the best possible approximation ratio, for **every** CSP.*

# Recall the SDP

Local integral distributions that are consistent on pairs + positive semidefiniteness of pairwise joint probabilities.

Maximize  $\sum_{(h,S) \in \mathcal{C}} \mathbb{E}_{x \sim \mu_{(h,S)}}[h(x)]$  subject to:

- 1  $\sum_{a \in [q]} \langle v_{i,a}, v_{i,a} \rangle = 1 \quad \forall i$
- 2  $\mu_{(h,S)}(x) \geq 0$  and  $\sum_x \mu_{(h,S)}(x) = 1 \quad \forall (h,S) \in \mathcal{C}$ .
- 3  $\langle v_{i,a}, v_{j,b} \rangle = \Pr_{x \sim \mu_{(h,S)}}[x_i = a \wedge x_j = b]$   
 $\forall (h,S) \in \mathcal{C}; \quad x_i, x_j \in S; \quad a, b \in [q].$

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Dictatorship test for function  $f : [q]^R \rightarrow \{0, 1\}$ :

- Pick a random constraint  $(h, S) \in \mathcal{C}$ . Let  $k = |S|$  be its arity.
- Pick  $k$  vectors  $y^{(1)}, y^{(2)}, \dots, y^{(k)} \in [q]^R$  where for each  $i \in [R]$  independently, the  $i$ 'th coordinates  $(y_i^{(1)}, y_i^{(2)}, \dots, y_i^{(k)}) \in_R \mu_{(h,S)}$  are chosen as per the local integral distribution.\*
- Check the constraint  $h(f(y^{(1)}), f(y^{(2)}), \dots, f(y^{(k)}))$

\* Actually, one samples from a slightly noisy version of  $\mu_{(h,S)}$

# Canonical SDP for Boolean case

Unit vectors  $v_i$  for variables  $x_i$ , and a global unit vector  $b_0$  (representing False).

Value of any constraint on  $x_i, x_j$  can be expressed as linear function of  $\langle b_0, v_i \rangle$ ,  $\langle b_0, v_j \rangle$ , and  $\langle v_i, v_j \rangle$ .

SDP maximizes sum of this linear function over all constraints, subject to

$$\langle b_0, b_0 \rangle = 1; \quad \langle v_i, v_i \rangle = 1 \quad \forall i$$

And the “triangle inequalities”

$$\langle (b_0 \pm v_i), (b_0 \pm v_j) \rangle \geq 0$$

for all  $i, j$  for which  $x_i, x_j$  participate in a constraint.

# A permutation problem

Topological sorting: Given a directed *acyclic* graph, can order its vertices so that all edges go forward.

- What if digraph is only “nearly” acyclic, say 1% of the edges need to be removed to make it acyclic?
- Can one find an ordering such that most of the edges go forward?
- Equivalently, find acyclic subgraph with maximum fraction of edges.

Picking a random ordering (or better of any ordering and its reverse) finds acyclic subgraph with at least  $1/2$  the edges.

## Theorem [G.-Manokaran-Raghavendra]

Assuming UGC, this is best possible.

$\forall \epsilon, \delta > 0$ , given a  $(1 - \epsilon)$ -acyclic graph, it is UG-hard to find an acyclic subgraph with  $(1/2 + \delta)$  edges.

# Max Acyclic Subgraph as a CSP

Max Acyclic Subgraph can be expressed “like” a 2CSP:

- Variables = vertices of graph
- Edge  $x \rightarrow y$  = constraint  $x < y$
- Large domain  $[n]$  where  $n$  = number of vertices.

Even though it is not a usual 2CSP due to growing domain size, UniqueGames hardness shown by relating it to a “proxy” CSP over a bounded domain.

# Ordering CSP

Ordering constraint of arity  $k =$  subset  $\Pi$  of  $k!$  possible permutations

- MAS:  $x_i < x_j$        $\Pi = \{12\}$
- Betweenness:  $x_j$  between  $x_i$  and  $x_\ell$ .  
 $\Pi = \{123, 321\}$  applied to triple  $(x_i, x_j, x_\ell)$ .

Instance of ordering  $k$ CSP  $\Pi$ :

- Input:  $n$  variables and collection of  $k$ -tuples of variables.
- Goal: Find global ordering for which max. fraction of input  $k$ -tuples are locally ordered according to a permutation in  $\Pi$ .

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**Theorem (Charikar, G., Håstad, Manokaran)**

**Every ordering CSP is approximation resistant.**

- *UG-hard to distinguish  $(1 - \varepsilon)$ -satisfiable instances from at most  $\frac{|\Pi|}{k!} + \delta$ -satisfiable instances, for any  $\varepsilon, \delta > 0$ .*



# Summary

- Lot of progress on approximability of CSPs, both from algorithms and hardness side.
- Natural semidefinite programming relaxation + suitable rounding  $\Rightarrow$  best known approximation algorithms for all CSPs.
  - In fact, achieves *the optimal* approximation ratio, under the Unique Games conjecture.
- Many unconditional tight hardness results also known
  - Show approximation resistance of several CSPs
  - A 2CSP called Label Cover is the canonical starting point, of which Unique Games is a particularly nice special case
  - Reduction method: Long code + dictatorship testing.
- “Approximate polymorphisms” (with low influences) give an explanation for the source of a CSP’s approximation threshold.

# Some Challenges

- 1 Prove or disprove the Unique Games conjecture.
- 2 Approximability of *satisfiable* CSPs?
- 3 Classification of approximation resistant CSPs?