

Machine Learning 10-701

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Today:

- Graphical models
- Bayes Nets:
 - Representing distributions
 - Conditional independencies
 - Simple inference
 - Simple learning

Readings:

- Required:
- Bishop chapter 8, through 8.2

Graphical Models

- Key Idea:
 - Conditional independence assumptions useful
 - but Naïve Bayes is extreme!
 - Graphical models express sets of conditional independence assumptions via graph structure
 - Graph structure plus associated parameters define joint probability distribution over set of variables/nodes
- Two types of graphical models:
 - Directed graphs (aka Bayesian Networks)
 - Undirected graphs (aka Markov Random Fields)

today

Graphical Models – Why Care?

- Among most important ML developments of the decade
- Graphical models allow combining:
 - Prior knowledge in form of dependencies/independencies
 - Observed data to estimate parameters
- Principled and ~general methods for
 - Probabilistic inference
 - Learning
- Useful in practice
 - Diagnosis, help systems, text analysis, time series models, ...

Conditional Independence

Definition: X is conditionally independent of Y given Z, if the probability distribution governing X is independent of the value of Y, given the value of Z

$$(\forall i, j, k) P(X = x_i | Y = y_j, Z = z_k) = P(X = x_i | Z = z_k)$$

Which we often write $\underbrace{P(X|Y, Z)} = \underbrace{P(X|Z)}$

E.g., $P(\text{Thunder} | \text{Rain}, \text{Lightning}) = P(\text{Thunder} | \text{Lightning})$

Marginal Independence

Definition: X is marginally independent of Y if

$$(\forall i, j) P(X = x_i, Y = y_j) = P(X = x_i)P(Y = y_j)$$

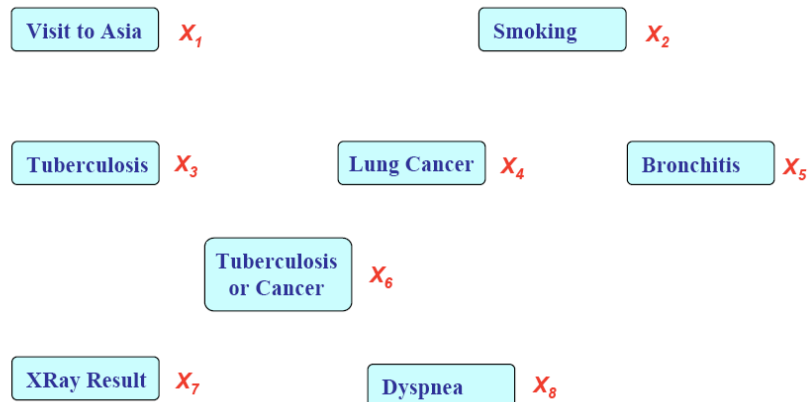
Equivalently, if

$$(\forall i, j) P(X = x_i | Y = y_j) = P(X = x_i)$$

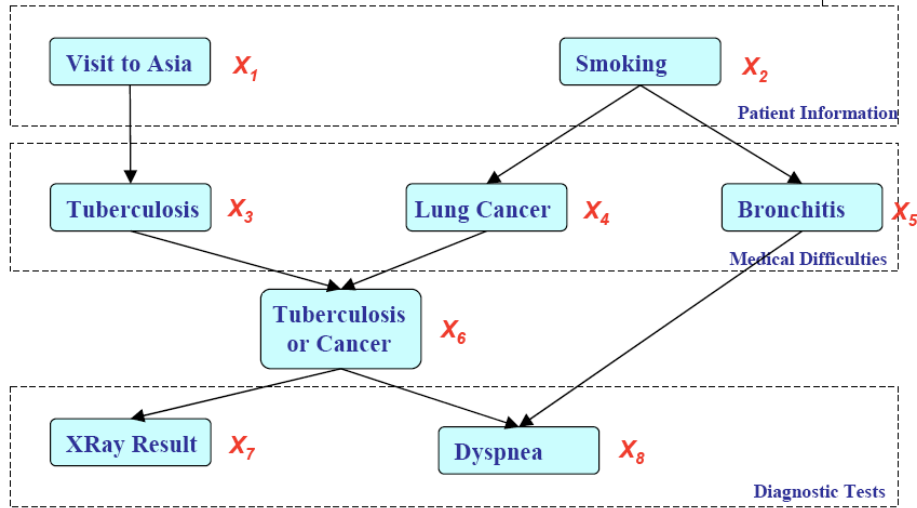
Equivalently, if

$$(\forall i, j) P(Y = y_j | X = x_i) = P(Y = y_j)$$

Represent Joint Probability Distribution over Variables



Describe network of dependencies

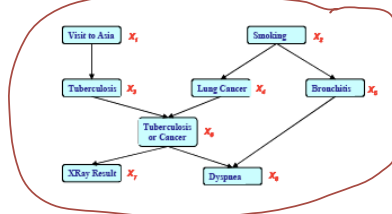


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4

Bayesian Networks define Joint Distribution in terms of this graph, plus parameters

- If X_i 's are **conditionally independent** (as described by a **PGM**), the joint can be factored to a product of simpler terms, e.g.,



$$P(X_1, X_2, X_3, X_4, X_5, X_6, X_7, X_8) = P(X_1) P(X_2) P(X_3 | X_1) P(X_4 | X_2) P(X_5 | X_2) P(X_6 | X_3, X_4, X_5) P(X_7 | X_6) P(X_8 | X_5, X_6)$$

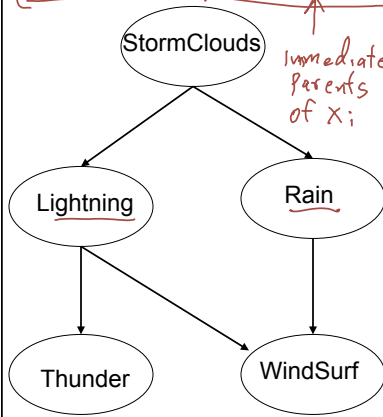
- Why we may favor a PGM?
 - Representation cost: how many probability statements are needed?
 - $2+2+4+4+4+8+4+8=36$, an 8-fold reduction from $2^8!$
 - Algorithms for systematic and efficient inference/learning computation
 - Exploring the graph structure and probabilistic (e.g., Bayesian, Markovian) semantics
 - Incorporation of domain knowledge and causal (logical) structures

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6

Bayesian Network

$$P(x_1, \dots, x_n) = \prod_i P(x_i | Pa(x_i))$$



Bayes network: a directed acyclic graph defining a joint probability distribution over a set of variables

Each node denotes a random variable

A conditional probability distribution (CPD) is associated with each node N , defining $P(N | Parents(N))$

Parents	$P(W Pa)$	$P(\neg W Pa)$
L, R	0	1.0
L, $\neg R$	0	1.0
$\neg L$, R	0.2	0.8
$\neg L$, $\neg R$	0.9	0.1

WindSurf

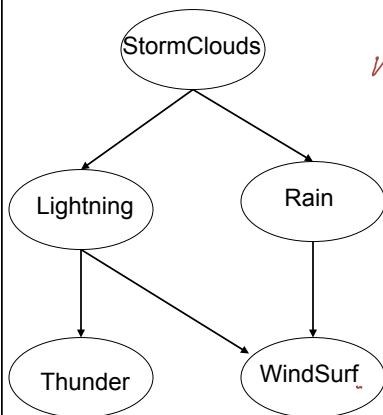
The joint distribution over all variables in the network is defined in terms of these CPD's, plus the graph

Bayesian Network

What can we say about conditional independencies in a Bayes Net?

One thing is this:

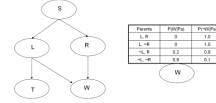
Each node is conditionally independent of its non-descendants, given only its immediate parents.



Parents	$P(W Pa)$	$P(\neg W Pa)$
L, R	0	1.0
L, $\neg R$	0	1.0
$\neg L$, R	0.2	0.8
$\neg L$, $\neg R$	0.9	0.1

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Bayesian Networks Definition



A Bayes network represents the joint probability distribution over a collection of random variables

A Bayes network is a directed acyclic graph and a set of CPD's

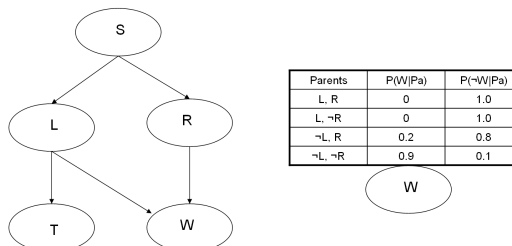
- Each node denotes a random variable
- Edges denote dependencies
- CPD for each node X_i defines $P(X_i | Pa(X_i))$
- The joint distribution over all variables is defined as

$$P(X_1 \dots X_n) = \prod_i P(X_i | Pa(X_i))$$

$Pa(X)$ = immediate parents of X in the graph

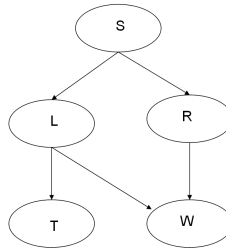
Some helpful terminology

- ✓ $Parents = Pa(X)$ = immediate parents
- $Antecedents$ = parents, parents of parents, ...
- $Children$ = immediate children
- ✓ $Descendants$ = children, children of children, ...



Bayesian Networks

- CPD for each node X_i describes $P(X_i | Pa(X_i))$



Parents	P(W Pa)	P(¬W Pa)
L, R	0	1.0
L, ¬R	0	1.0
¬L, R	0.2	0.8
¬L, ¬R	0.9	0.1



Chain rule of probability:

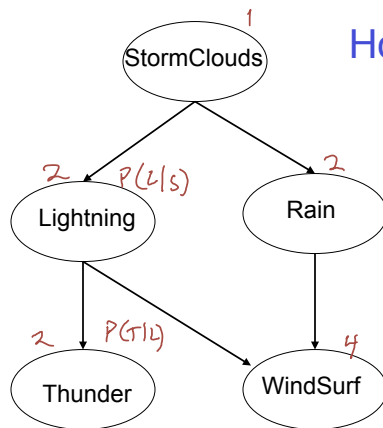
$$P(S, L, R, T, W) = P(S)P(L|S)P(R|S, L)P(T|S, L, R)P(W|S, L, R, T)$$

But in a Bayes net: $P(X_1 \dots X_n) = \prod_i P(X_i | Pa(X_i))$

$$P(S, L, R, T, W) = P(S) P(L|S) P(R|S) P(T|L) P(W|L, R)$$

$$(\forall s, l, r, t, w) P(S=s, L=l, \dots) = P(S=s) P(L=l|S=s) \dots \quad \text{''}$$

How Many Parameters?



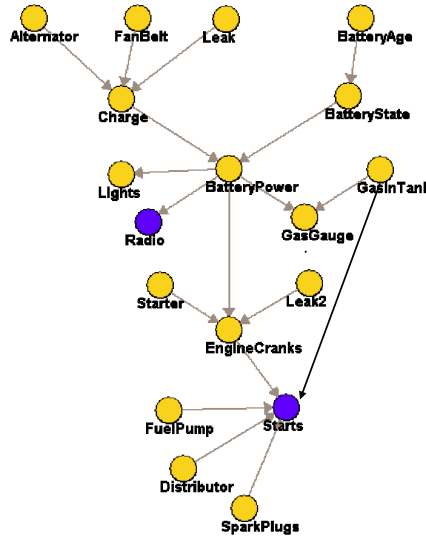
Parents	P(W Pa)	P(¬W Pa)
L, R	0 ✓	1.0
L, ¬R	0 ✓	1.0
¬L, R	0.2 ✓	0.8
¬L, ¬R	0.9 ✓	0.1

WindSurf

In full joint distribution? $2^5 - 1 = 31$

Given this Bayes Net? = 11

Bayes Net



Inference:

$P(\text{BattPower}=t \mid \text{Radio}=t, \text{Starts}=f)$

Most probable explanation:

What is most likely value of Leak, BatteryPower given Starts=f?

Active data collection:

What is most useful variable to observe next, to improve our knowledge of node X?

Algorithm for Constructing Bayes Network

- Choose an ordering over variables, e.g., X_1, X_2, \dots, X_n
- For $i=1$ to n
 - Add X_i to the network
 - Select parents $Pa(X_i)$ as minimal subset of $X_1 \dots X_{i-1}$ such that

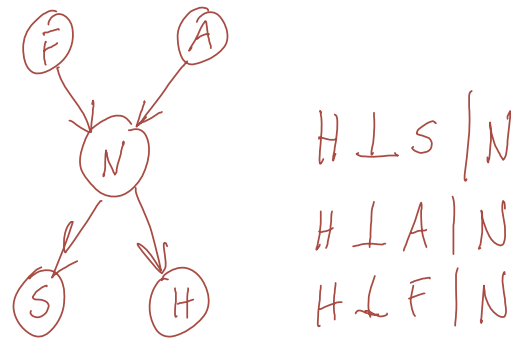
$$P(X_i \mid Pa(X_i)) = P(X_i \mid X_1, \dots, X_{i-1})$$

Notice this choice of parents assures

$$\begin{aligned} P(X_1 \dots X_n) &= \prod_i P(X_i \mid X_1 \dots X_{i-1}) && \text{(by chain rule)} \\ &= \prod_i P(X_i \mid Pa(X_i)) && \text{(by construction)} \end{aligned}$$

Example

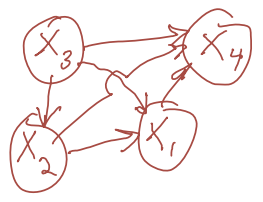
- Bird flu and Allergies both cause Nasal problems
- Nasal problems cause Sneezes and Headaches



H ⊥ S | N
 H ⊥ A | N
 H ⊥ F | N

What is the Bayes Network for X_1, \dots, X_n with NO assumed conditional independencies?

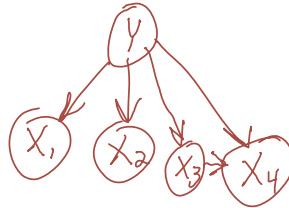
$$P(X_1, X_2, X_3, X_4) \stackrel{\text{Chain Rule}}{=} P(X_1) P(X_2|X_1) P(X_3|X_1, X_2) P(X_4|X_1, X_2, X_3)$$



What is the Bayes Network for Naïve Bayes?

$$P(Y | x_1, \dots, x_4)$$

$$P(Y, x_1, x_2, \dots, x_4) = P(Y) P(x_1 | Y) P(x_2 | Y) \dots P(x_4 | Y)$$

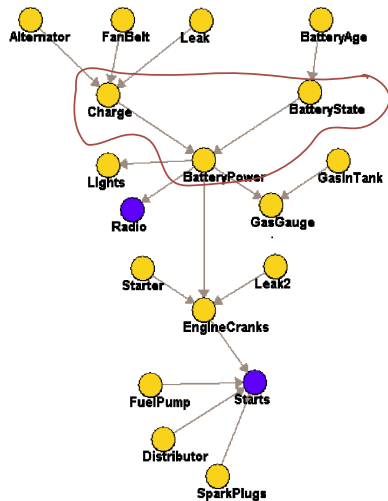


$$P(x_3, x_4 | Y) = P(x_3 | Y, x_4) P(x_4 | Y)$$

$$= P(x_4 | Y, x_3) P(x_3 | Y)$$

$$x_1 \perp x_2 | Y$$

What do we do if variables are mix of discrete and real valued?



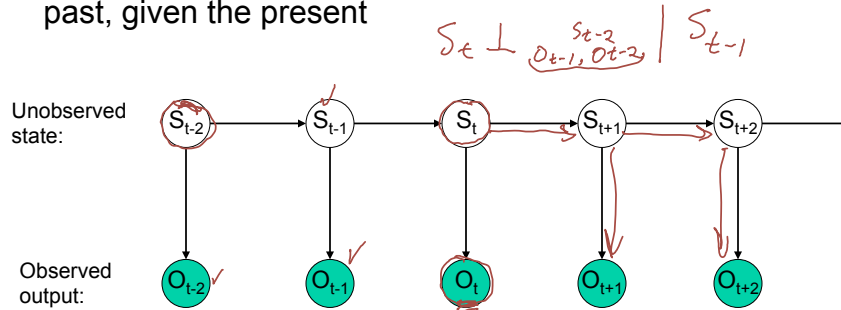
eg.

$$P(BP | BS, C) = N(\mu_{BS, C}, \sigma_{BS, C}^2)$$

↑
real valued

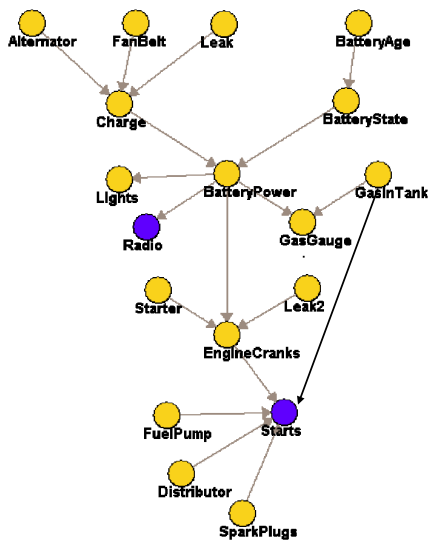
Bayes Network for a Hidden Markov Model

Assume the future is conditionally independent of the past, given the present



$$P(S_{t-2}, O_{t-2}, S_{t-1}, \dots, O_{t+2}) = P(S_{t-2}) P(O_{t-2} | S_{t-2}) P(S_{t-1} | S_{t-2}) \\ P(O_{t-1} | S_{t-1}) P(S_t | S_{t-1}) \dots$$

How Can We Train a Bayes Net



1. when graph is given, and each training example gives value of every RV?

Easy: use data to obtain MLE or MAP estimates of θ for each CPD

$$P(X_i | \text{Pa}(X_i); \theta)$$

e.g. like training the CPD's of a naïve Bayes classifier

2. when graph unknown or some RV's unobserved?

this is more difficult... later...