

# MFCS

## Functions

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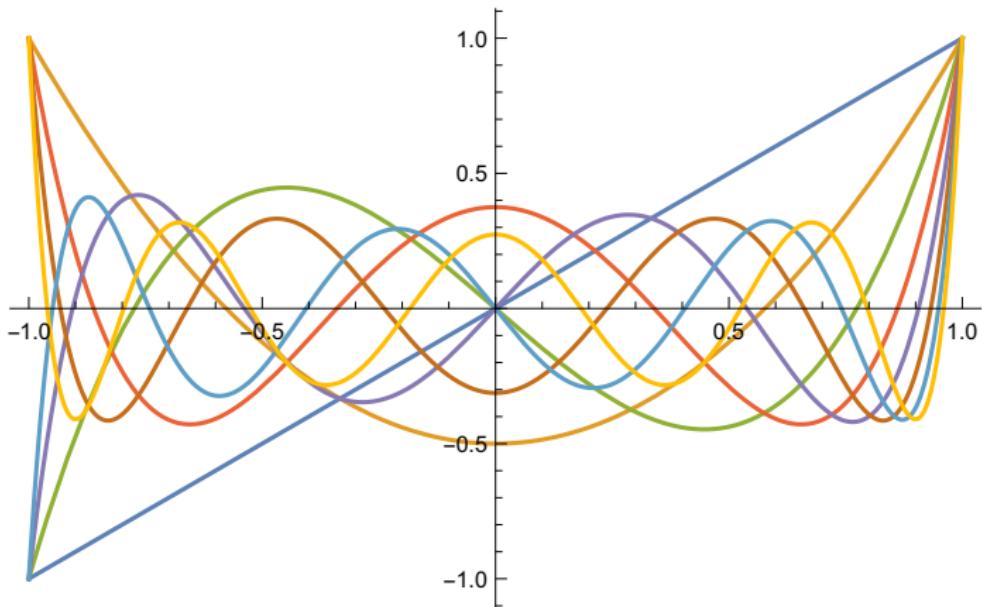
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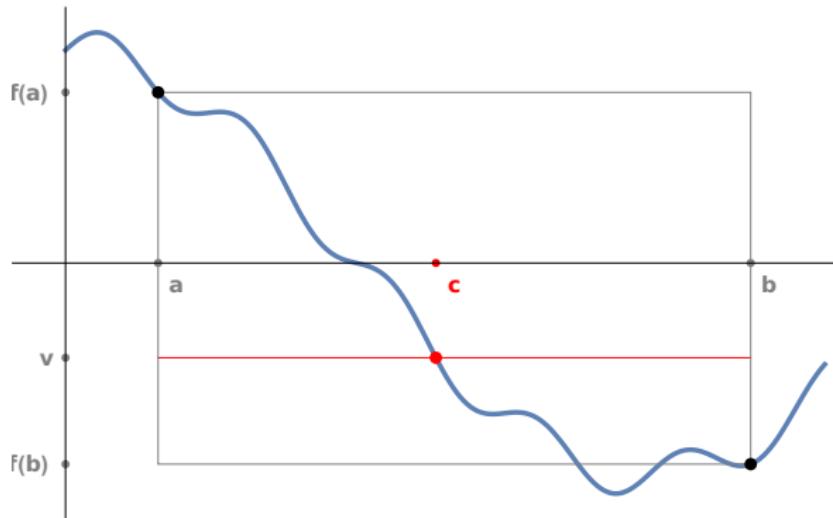
## **1 Functions Defined**

## **2 Composition and Iteration**

# Pretty Pictures



Legendre polynomials you might know from calculus.



A beautiful picture of some rando continuous function. Supposedly this picture is useful to understand why the *intermediate value theorem* holds.

Unfortunately, this concept of a function familiar from calculus is far too narrow for our purposes. We need to work a bit harder and figure out what the essential ideas behind the concept of a function really are.

First off, we can take inspiration from **computable functions**, functions that can be described by an algorithm.

To specify such a function, we need three pieces of information:

- the type of the allowed inputs,
- the type of the corresponding outputs,
- a mechanical method to get from input to output.

Input/output types are a perfectly good general idea, that we will steal. Alas, requiring all functions to be defined by an algorithm is not terribly useful.

For us, the “method” can be as general as imaginable: it can be just a collection of input/output pairs.

More precisely, suppose  $A$  and  $B$  are two sets. We want to define **functions from  $A$  to  $B$** . To this end, consider some input/output pairs:

$$F \subseteq A \times B$$

When would  $F$  make sense as a function?

We need two key properties.

Totality For every  $x \in A$ , there is a  $y \in B$  such that  $(x, y) \in F$ .

Single-Valuedness If  $(x, y), (x, z) \in F$ , then  $y = z$ .

In other words, we want the function to be defined on all of  $A^{\dagger}$ , and we want the output to be unique.

That's all, folks.

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<sup>†</sup>Actually, it does make sense to consider so-called **partial functions** that may not be defined on all of  $A$ , but not right now.

## Definition

A **function** (or **map**, **mapping**) from  $A$  to  $B$  is a triple  $(F, A, B)$  where  $F \subseteq A \times B$  is total and single-valued.

We write  $f : A \rightarrow B$  for a function from  $A$  to  $B$  and call  $A$  the **domain** of  $f$ , and  $B$  its **codomain**.  $F = \text{grf } f$  is called the **graph** of the function<sup>†</sup>.

$f$  is an **endofunction** if  $\text{dom } f = \text{cod } f$ .

We write  $f(a) = b$  instead of  $(a, b) \in F$ .

We write  $A \rightarrow B$  or  $B^A$  for the collection of all functions from  $A$  to  $B$ .

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<sup>†</sup>In set theory, a function is often defined to be its graph. That won't work for us.

## Example: Legendre Polynomial #5

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For  $P_5$  we have:

- the domain is  $\mathbb{R}$
- the codomain is  $\mathbb{R}$
- the graph is

$$\{ (x, (15x - 70x^3 + 63x^5)/8) \mid x \in \mathbb{R} \}$$

So this function is “computable” in a way (once you have figured out what it means to compute with reals, currently more or less an open problem).

Usually we do not utilize the triple notation for functions, it's a bit too fusty. Instead we write things like

$$f : A \rightarrow B \quad f(x) = \text{blahblahblah}$$

If domain and codomain are completely obvious from context, we may get lazy and write

$$f(x) = \text{blahblahblah}$$

It's best to avoid this for a while, though, to get used to specifying domain and codomain precisely.

When  $b = f(a)$ , one often calls  $b$  the **image** of  $a$  under  $f$ .

## Definition

Consider a function  $f : A \rightarrow B$ . The **image** of  $X \subseteq A$  under  $f$  is

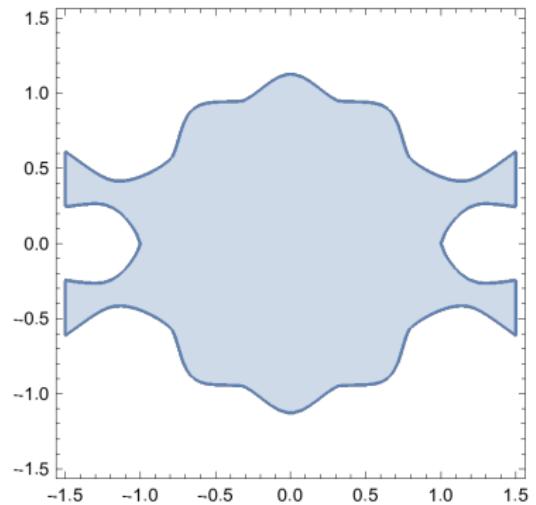
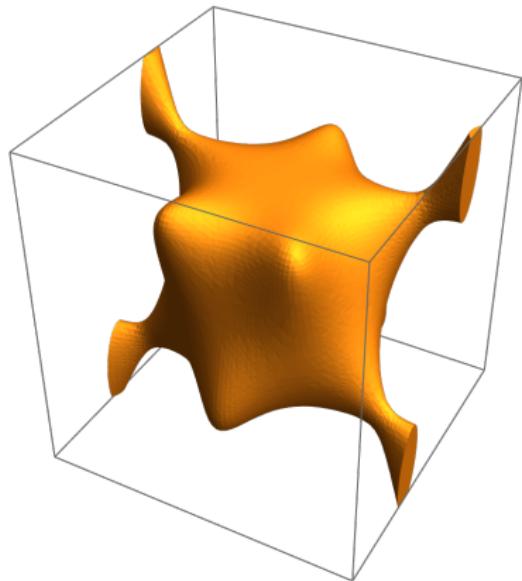
$$f(X) = \{ f(x) \mid x \in X \}$$

The **range** or **image** of  $f$  is  $\text{rng } f = f(\text{dom } f)$ .

For example,  $\sin : \mathbb{R} \rightarrow \mathbb{R}$  has range  $[-1, 1]$ ,  $\exp : \mathbb{R} \rightarrow \mathbb{R}$  has range  $\mathbb{R}_+$  and  $\log : \mathbb{R}_+ \rightarrow \mathbb{R}$  has range  $\mathbb{R}$ .

# What is $f$ ?

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If you want to be very precise, you can introduce a new function

$$\hat{f} : \mathfrak{P}(A) \rightarrow \mathfrak{P}(B) \quad \hat{f}(X) = \{ f(x) \mid x \in X \}$$

In other words, we could keep track of the change in domain and codomain and change the symbol for the function accordingly.

In programming this is critical, code expecting input of type  $A$  will not accept input of type  $\mathfrak{P}(A)$ .

But in math and TCS it's up to the reader to figure out what exactly is meant by  $f^\dagger$ . You are supposed to adjust the types depending on context.

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<sup>†</sup>This tends to drive beginners nuts, but in the end it is the only feasible approach. Otherwise you drown in symbols

## Definition

Consider a function  $f : A \rightarrow B$ .

The **preimage** or **fiber** of  $b \in B$  under  $f$  is

$$f^{-1}(b) = \{ a \in A \mid f(a) = b \}$$

The **preimage** of  $X \subseteq B$  under  $f$  is  $f^{-1}(X) = \bigcup_{b \in X} f^{-1}(b)$ .

Warning:  $f^{-1}$  is **not** a function  $B \rightarrow A$ , it has the type  $B \rightarrow \mathfrak{P}(A)$  or  $\mathfrak{P}(B) \rightarrow \mathfrak{P}(A)$ <sup>†</sup>.

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<sup>†</sup>But see bijections below.

Consider  $\sin : \mathbb{R} \rightarrow \mathbb{R}$ .

For  $|x| > 1$ , the fibers  $\sin^{-1}(x)$  are all empty.

The fiber  $\sin^{-1}(0)$  is  $\mathbb{Z}\pi$ .

And  $\sin^{-1}(\mathbb{R}_{\geq 0})$  is  $[0, \pi] + 2\mathbb{Z}\pi$ .

Suppose we have some ambient set  $\mathcal{U}$  and we need to deal with subsets  $A \subseteq \mathcal{U}$ . We can express these subsets in terms of functions.

## Definition

The **characteristic function** of  $A \subseteq \mathcal{U}$  is defined by  $\chi_A : \mathcal{U} \rightarrow \mathbf{2}$  where

$$\chi_A(x) = \begin{cases} 1 & \text{if } x \in A \\ 0 & \text{otherwise.} \end{cases}$$

Here we write  $\mathbf{2} = \{0, 1\}$ .

We will shamelessly identify 0 with False, and 1 with True, whenever convenient. Or we think of them as integers, it all depends<sup>†</sup>.

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<sup>†</sup>This kind of skulduggery drives type theory purists nuts.

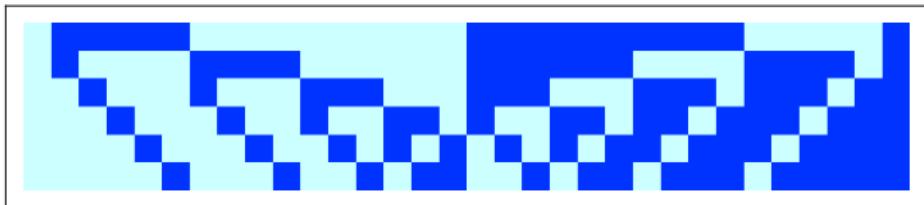
So  $\chi_A$  is just a bitvector that answers membership questions.

In particular when  $\mathcal{U} = [n]$  and  $n$  is reasonably small, this provides an excellent implementation for subsets.

Consider the universe  $\mathcal{U} = [10]$  and  $A = \{2, 3, 6, 8\}$ , then

```
bool A[] = {0,0,1,1,0,0,1,0,1,0}
```

For  $n = 64$  this means we can perform some operations in one step.



Bitvectors for all even-cardinality subsets of  $[6]$ .

Characteristic functions translate set operations into logical connectives:

$$\chi_{A \cup B} = \chi_A \vee \chi_B$$

$$\chi_{A \cap B} = \chi_A \wedge \chi_B$$

$$\chi_{A \oplus B} = \chi_A \oplus \chi_B$$

$$\chi_{A^c} = \neg \chi_A$$

Here all the logical operations are supposed by applied pointwise:

$$\chi_{A \cup B}(x) = \chi_A(x) \vee \chi_B(x).$$

## 1 Functions Defined

## 2 Composition and Iteration

The most important property of functions is that they can be composed, we can execute one after the other. Given

$$f : A \rightarrow B \quad g : B \rightarrow C$$

## Definition

The **composition** of  $f$  and  $g$ , in symbols  $g \circ f$ , is given by

$$h : A \rightarrow C \quad h(x) = g(f(x))$$

Note that the codomain of  $f$  and the domain of  $g$  has to match, otherwise composition is undefined.

In 1976, the category theorist [Charles Wells](#) wrote<sup>†</sup>.

Observe that I write functions on the right and functional composition from left to right. This is undoubtedly the *Wave of the Future*. It makes functional diagrams easier to read and corresponds to the natural order of doing things on a pocket calculator.

Hewlett-Packard was no doubt pleased with Wells's comments: their calculators used postfix notation: argument 1, argument 2, operator. Works much better than infix.

Alas, nothing happened, zilch, nada, null.

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<sup>†</sup>In a paper titled "Some Applications of the Wreath Product Construction," no less.

There is a clash between composition of functions and diagrams

$$A \xrightarrow{f} B \xrightarrow{g} C$$

Reading from left-to-right we get  $f \circ g$ , but according to our definition this is  $g \circ f^\dagger$ .

Also, the standard convention for sequential composition of programs is  $F;G$ : first run  $F$ , then run  $G$ .

Alas, the composition convention is firmly entrenched, we won't fight.

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<sup>†</sup>Worse, it clashes with relational composition, see there.

## Definition

Let  $f : A \rightarrow A$  be an endofunction. The ***kth power*** of  $f$  (or ***kth iterate*** of  $f$ ) is defined by induction as follows:

$$f^0 = I_A$$

$$f^k = f \circ f^{k-1}$$

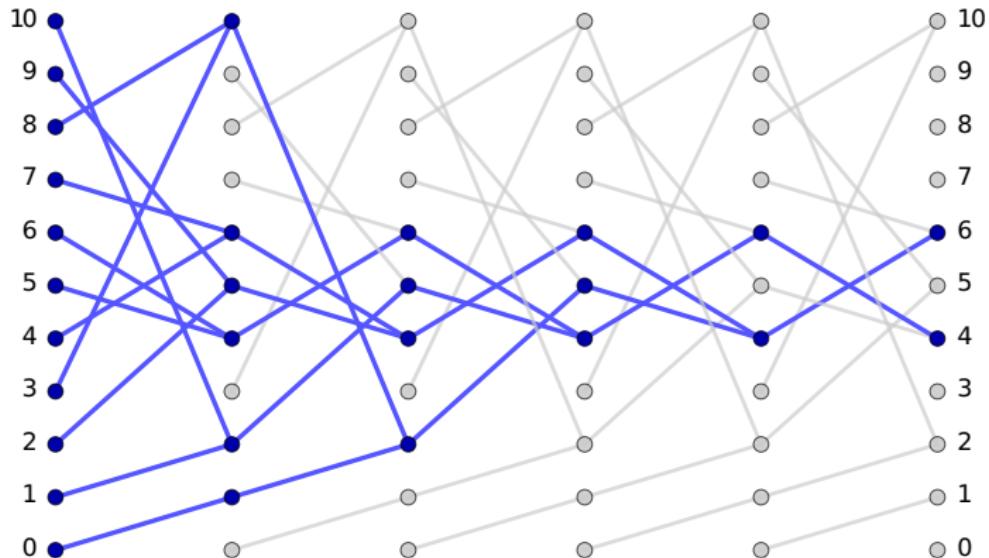
Here  $I_A$  denotes the identity function on  $A$ .

Informally, this just means: compose function  $f$   $(k-1)$ -times with itself.

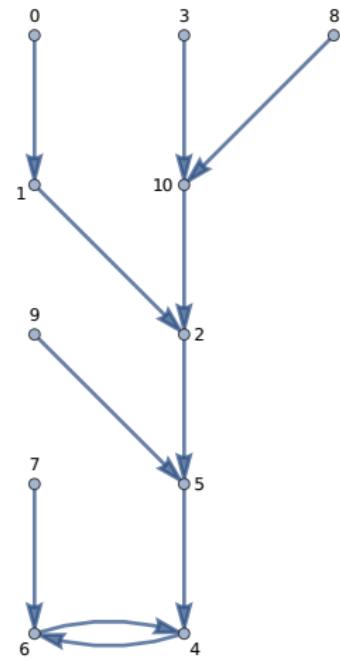
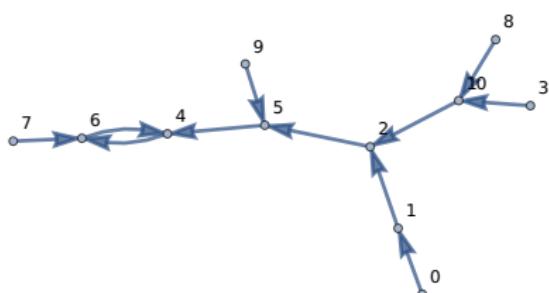
$$f^k = \underbrace{f \circ f \circ f \circ \dots \circ f}_{k \text{ terms}}$$

# Example 1

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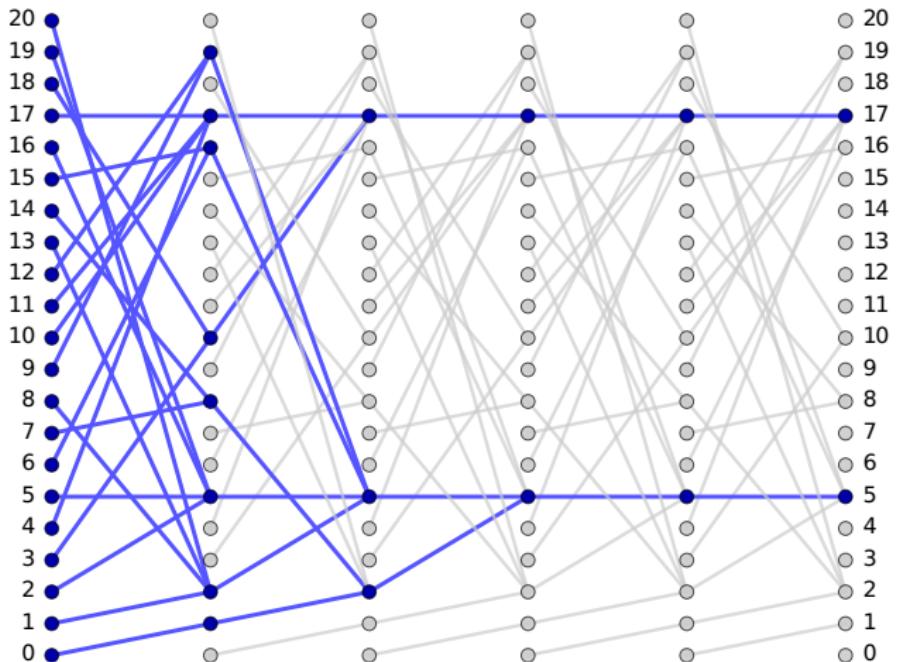


Iterating the map  $x \mapsto x^2 + 1 \pmod{11}$ .

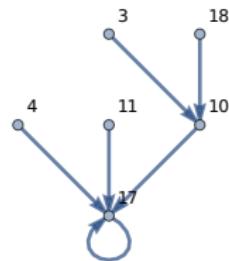
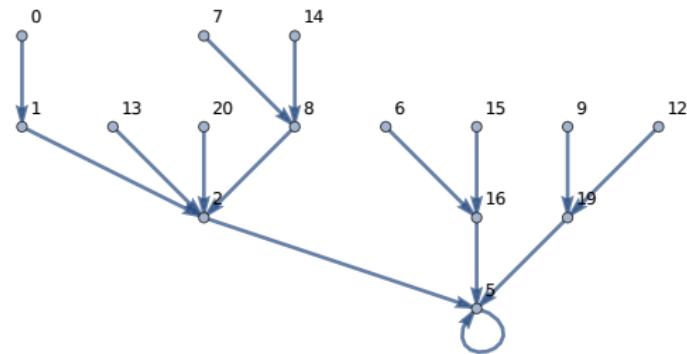


## Example 2

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Iterating the map  $x \mapsto x^2 + 1 \pmod{21}$ .



Without any further knowledge about  $f$ , there is not much one can say about the iterates  $f^k$ . But the following always holds.

## Lemma (Laws of Iteration)

- $f^n \circ f = f^{n+1}$
- $f^n \circ f^m = f^{n+m}$
- $(f^n)^m = f^{n \cdot m}$

This should look very familiar ...

A point  $a \in A$  is a **fixed point** of  $f$  if  $f(a) = a$ .

Here is an example. Write  $a :: L$  for the list  $L$  with element  $a$  prepended and define the following operation on numbers and binary lists.

$$\beta : \mathbb{N} \times \text{List}(2) \rightarrow \mathbb{N} \times \text{List}(2)$$

$$\beta(0, L) = (0, L)$$

$$\beta(x, L) = (x \text{ div } 2, (x \text{ mod } 2) :: L)$$

Now suppose we have an operator  $\text{FP}$  that, given  $\beta$  and  $a$ , looks for a fixed point among the iterates  $a, \beta(a), \beta(\beta(a)), \dots$

Of course, there may be none, just think about the first example from above.

In our situation, a fixed point always exists (why?) and we have

$$\text{FP}(\beta, (x, \text{nil})) = (0, \text{bin}(x))$$

where  $\text{bin}(x)$  is the binary expansion of  $x$ .

Thinking in terms of fixed point often produces very elegant descriptions of computations, often **one-liners**:

$$\text{tobin}(x) = \text{last}(\text{FP}(\beta, (x, \text{nil})))$$

## Exercise

*In your favorite programming language, implement a fixed point operation. Make sure to handle non-existent fixed points intelligently. Then implement the conversion to binary.*

## Exercise

*Fixed points are quite important in calculus, for example in Newton's method. Typical application: to compute  $1/a$  where  $0 \neq a \in \mathbb{R}$  we can find a fixed point of  $g(x) = 2x - ax^2$ .*

*How does one have to modify the fixed point operator for this to make sense in an actual computation?*