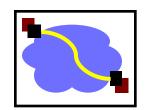


15-440 Distributed Systems

Lecture 14 – RAID

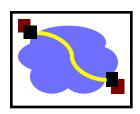
Thanks to Greg Ganger and Remzi Arapaci-Dusseau for slides





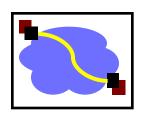
HPC1		COM1		COM2	_
Component	%	Component	%	Component	%
Hard drive	30.6	Power supply	34.8	Hard drive	49.1
Memory	28.5	Memory	20.1	Motherboard	23.4
Misc/Unk	14.4	Hard drive	18.1	Power supply	10.1
CPU	12.4	Case	11.4	RAID card	4.1
motherboard	4.9	Fan	8	Memory	3.4
Controller	2.9	CPU	2	SCSI cable	2.2
QSW	1.7	SCSI Board	0.6	Fan	2.2
Power supply	1.6	NIC Card	1.2	CPU	2.2
MLB	1	LV Pwr Board	0.6	CD-ROM	0.6
SCSI BP	0.3	CPU heatsink	0.6	Raid Controller	0.6

Outline



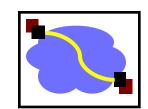
- Using multiple disks
 - Why have multiple disks?
 - problem and approaches
- RAID levels and performance
- Estimating availability

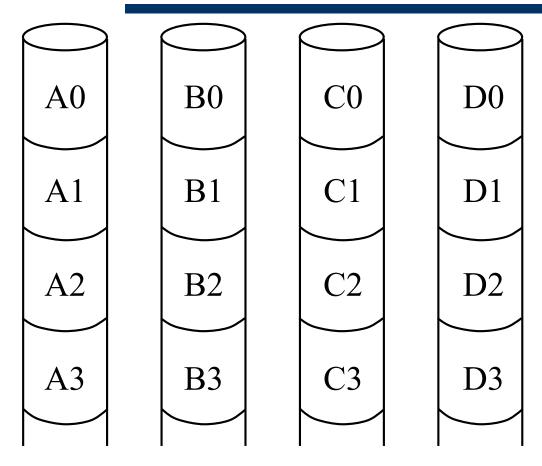
Motivation: Why use multiple disks?



- Capacity
 - More disks allows us to store more data
- Performance
 - Access multiple disks in parallel
 - Each disk can be working on independent read or write
 - Overlap seek and rotational positioning time for all
- Reliability
 - Recover from disk (or single sector) failures
 - Will need to store multiple copies of data to recover
 - So, what is the simplest arrangement?

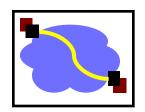
Just a bunch of disks (JBOD)



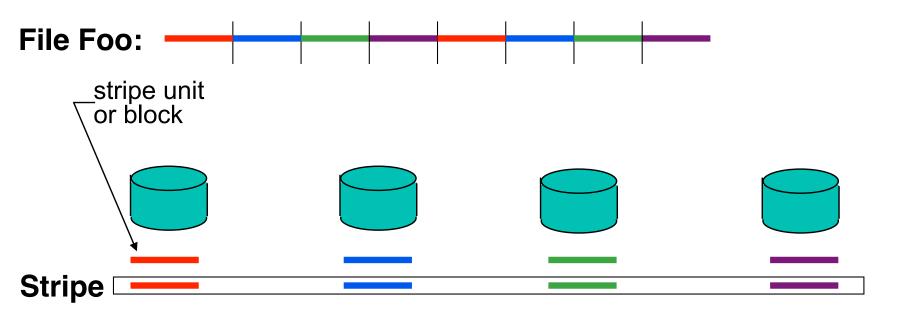


- Yes, it's a goofy name
 - industry really does sell "JBOD enclosures"

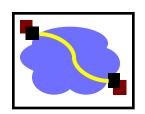
Disk Striping



- Interleave data across multiple disks
 - Large file streaming can enjoy parallel transfers
 - High throughput requests can enjoy thorough load balancing
 - If blocks of hot files equally likely on all disks (really?)



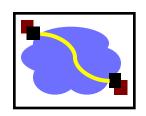
Now, What If A Disk Fails?



- In a JBOD (independent disk) system
 - one or more file systems lost
- In a striped system
 - a part of each file system lost
- Backups can help, but

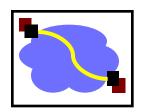
- backing up takes time and effort
- backup doesn't help recover data lost during that day
 - Any data loss is a big deal to a bank or stock exchange

Tolerating and masking disk failures

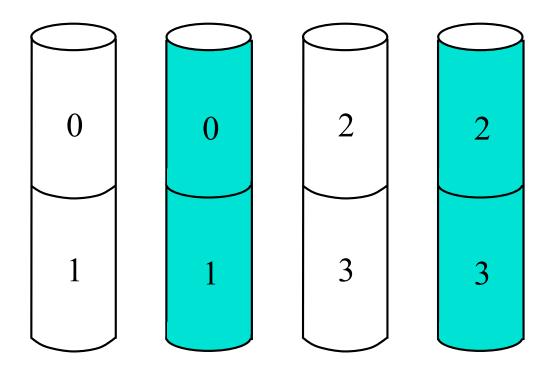


- If a disk fails, it's data is gone
 - may be recoverable, but may not be
- To keep operating in face of failure
 - must have some kind of data redundancy
- Common forms of data redundancy
 - replication
 - erasure-correcting codes
 - error-correcting codes

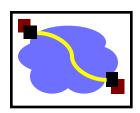
Redundancy via replicas



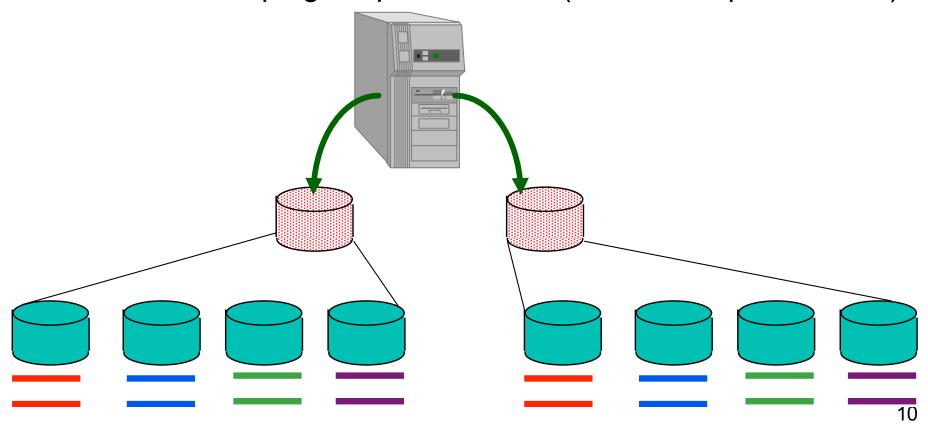
- Two (or more) copies
 - mirroring, shadowing, duplexing, etc.
- Write both, read either



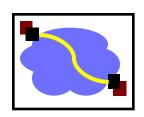
Mirroring & Striping



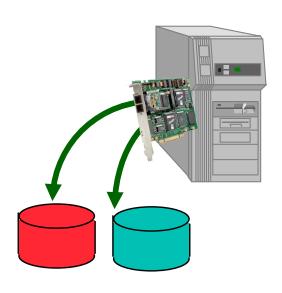
- Mirror to 2 virtual drives, where each virtual drive is really a set of striped drives
 - Provides reliability of mirroring
 - Provides striping for performance (with write update costs)

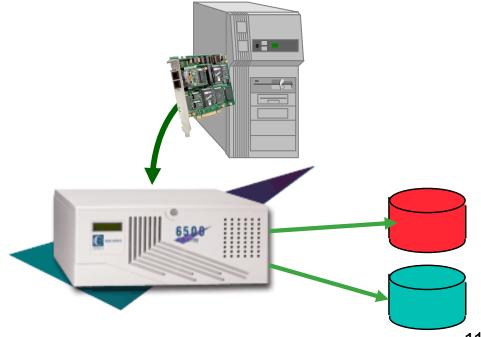


Implementing Disk Mirroring

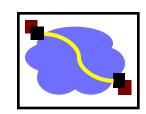


- Mirroring can be done in either software or hardware
- Software solutions are available in most OS's
 - Windows2000, Linux, Solaris
- Hardware solutions
 - Could be done in Host Bus Adaptor(s)
 - Could be done in Disk Array Controller



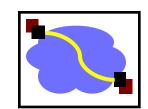


Lower Cost Data Redundancy

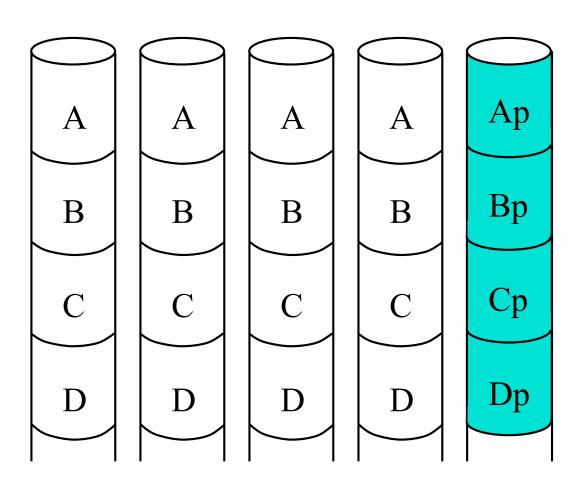


- Single failure protecting codes
 - general single-error-correcting code is overkill
 - General code finds error and fixes it
- Disk failures are self-identifying (a.k.a. erasures)
 - Don't have to find the error
- Fact: N-error-detecting code is also N-erasurecorrecting
 - Error-detecting codes can't find an error, just know its there
 - But if you independently know where error is, allows repair
 - Parity is single-disk-failure-correcting code
 - recall that parity is computed via XOR
 - it's like the low bit of the sum

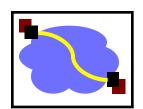
Simplest approach: Parity Disk

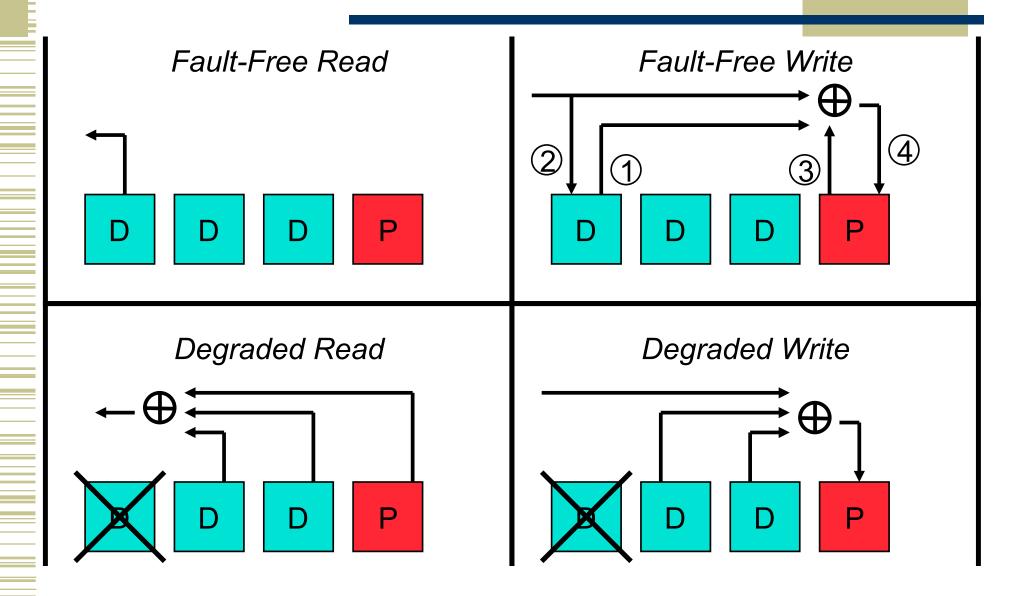


 Capacity: one extra disk needed per stripe

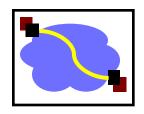


Updating and using the parity



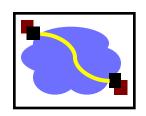


Performance



- Suppose 1 drive gives bandwidth B
- Fault-Free Read = 3B
- Degraded Read = 1B
- Fault-Free Write = 0.5 B
 - But can do 2B Fault-Free Read at the same time
- Degraded Write = 1 B

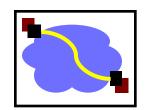
The parity disk bottleneck



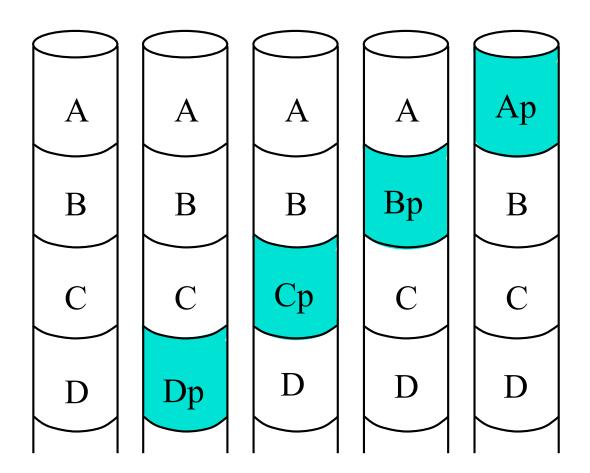
- Reads go only to the data disks
 - But, hopefully load balanced across the disks
- All writes go to the parity disk

- And, worse, usually result in Read-Modify-Write sequence
- So, parity disk can easily be a bottleneck

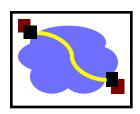
Solution: Striping the Parity



Removes parity disk bottleneck

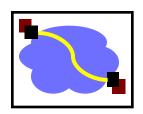


Outline



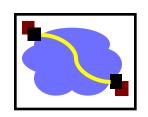
- Using multiple disks
 - Why have multiple disks?
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- Estimating availability

RAID Taxonomy

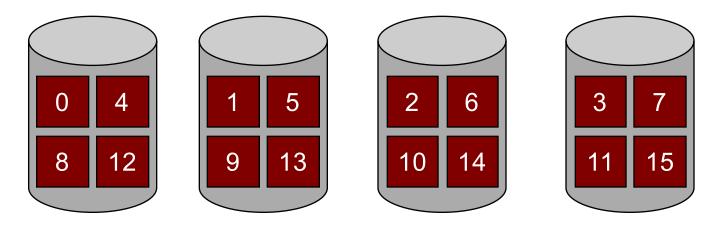


- Redundant Array of Inexpensive Independent Disks
 - Constructed by UC-Berkeley researchers in late 80s (Garth)
- RAID 0 Coarse-grained Striping with no redundancy
- RAID 1 Mirroring of independent disks
- RAID 2 Fine-grained data striping plus Hamming code disks
 - Uses Hamming codes to detect and correct multiple errors
 - Originally implemented when drives didn't always detect errors
 - Not used in real systems
- RAID 3 Fine-grained data striping plus parity disk
- RAID 4 Coarse-grained data striping plus parity disk
- RAID 5 Coarse-grained data striping plus striped parity

RAID-0: Striping



- Stripe blocks across disks in a "chunk" size
 - How to pick a reasonable chunk size?

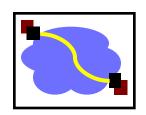


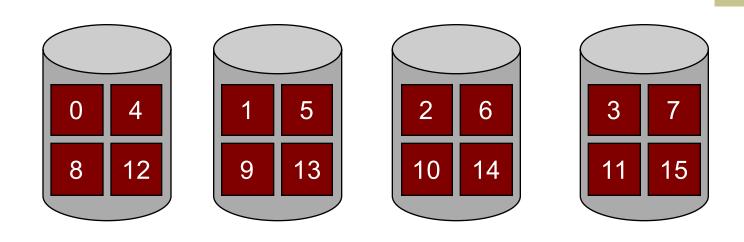
How to calculate where chunk # lives?

Disk:

Offset within disk:

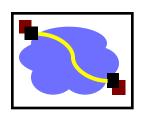
RAID-0: Striping



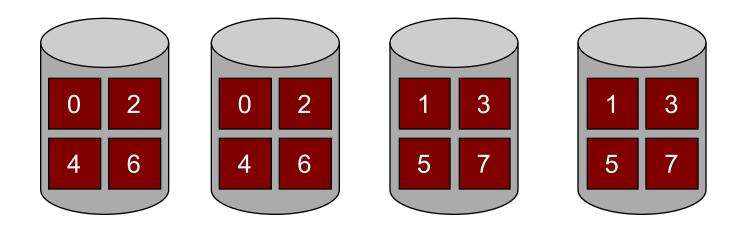


- Evaluate for D disks
- Capacity: How much space is wasted?
- Performance: How much faster than 1 disk?
- Reliability: More or less reliable than 1 disk?

RAID-1: Mirroring



- Motivation: Handle disk failures
- Put copy (mirror or replica) of each chunk on another disk

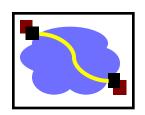


Capacity:

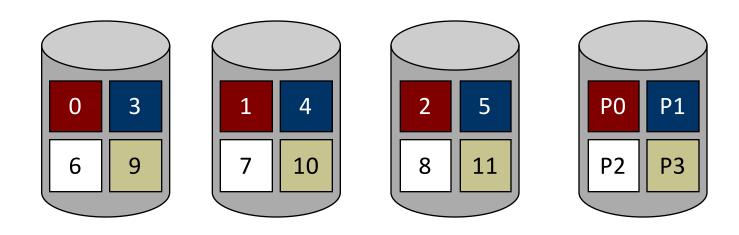
Reliability:

Performance:

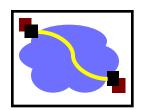
RAID-4: Parity

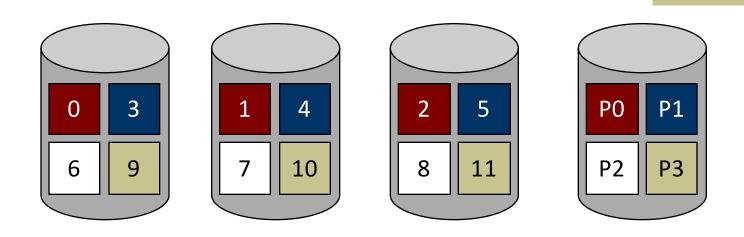


- Motivation: Improve capacity
- Idea: Allocate parity block to encode info about blocks
 - Parity checks all other blocks in stripe across other disks
- Parity block = XOR over others (gives "even" parity)
 - Example: 0 1 0 → Parity value?
- How do you recover from a failed disk?
 - Example: x 0 0 and parity of 1
 - What is the failed value?



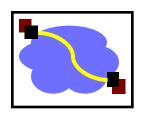
RAID-4: Parity



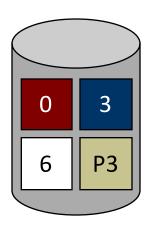


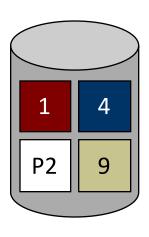
- Capacity:
- Reliability:
 - Performance:
 - Reads
 - Writes: How to update parity block?
 - Two different approaches
 - Small number of disks (or large write):
 - Large number of disks (or small write):
 - Parity disk is the bottleneck

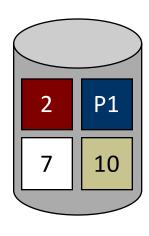
RAID-5: Rotated Parity

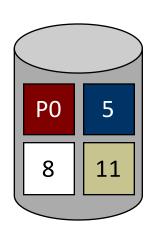


Rotate location of parity across all disks



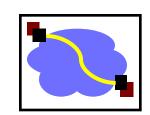






- Capacity:
- Reliability:
- Performance:
 - Reads:
 - Writes:
 - Still requires 4 I/Os per write, but not always to same parity disk

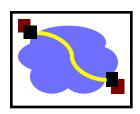
Comparison



	RAID-0	RAID-1	RAID-4	RAID-5
Capacity	N	N/2	N-1	N-1
Reliability	0	1 (for sure)	1	1
		$\frac{N}{2}$ (if lucky)		
Throughput				
Sequential Read	$N \cdot S$	$(N/2) \cdot S$	$(N-1)\cdot S$	$(N-1)\cdot S$
Sequential Write Random Read	$N \cdot S$	$(N/2) \cdot S$	$(N-1)\cdot S$	$(N-1)\cdot S$
Random Read	$N \cdot R$	$N \cdot R$	$(N-1)\cdot R$	$N \cdot R$
Random Write	$N \cdot R$	$(N/2) \cdot R$	$\frac{1}{2} \cdot R$	$\frac{N}{4}R$
Latency			_	1
Read	D	D	D	D
Write	D	D	2D	2D

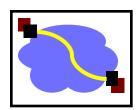
Table 38.7: RAID Capacity, Reliability, and Performance

Outline



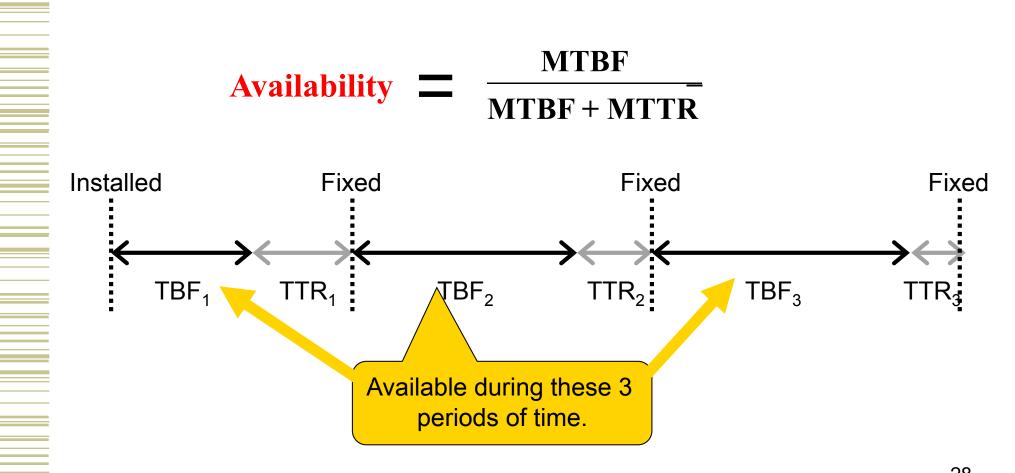
- Using multiple disks
 - Why have multiple disks?
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Sidebar: Availability metric

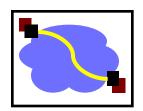


- Fraction of time that server is able to handle requests
 - Computed from MTBF and MTTR (Mean Time To Repair)

Availability
$$= \frac{\text{MTBF}}{\text{MTBF} + \text{MTTR}}$$

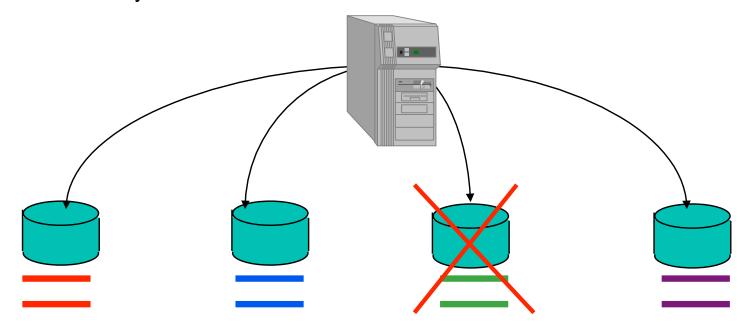


How often are failures?

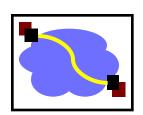


- MTBF (Mean Time Between Failures)
 - MTBF_{disk} ~ 1,200,00 hours (~136 years, <1% per year)
- MTBF_{mutli-disk system} = mean time to first disk failure
 - which is MTBF_{disk} / (number of disks)
 - For a striped array of 200 drives

• $MTBF_{array} = 136 \text{ years} / 200 \text{ drives} = 0.65 \text{ years}$

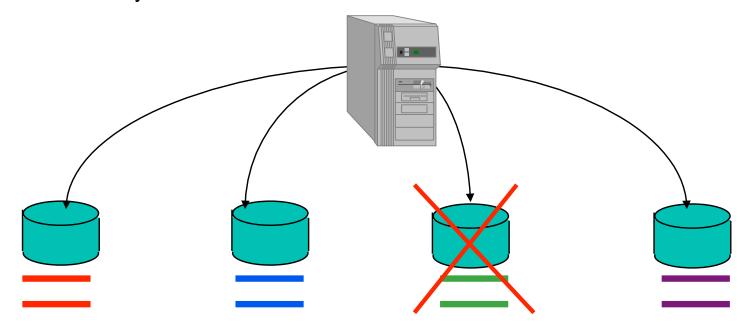


Back to Mean Time To Data Loss (MTTDL)

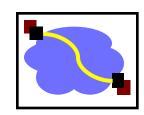


- MTBF (Mean Time Between Failures)
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• $MTBF_{array} = 136 \text{ years} / 200 \text{ drives} = 0.65 \text{ years}$

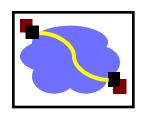


Reliability without rebuild



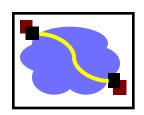
- 200 data drives with MTBFdrive
 - $MTTDL_{array} = MTBF_{drive} / 200$
- Add 200 drives and do mirroring
 - MTBF_{pair} = (MTBF_{drive} / 2) + MTBF_{drive} = 1.5 * MTBF_{drive}
 - MTTDL_{array} = MTBF_{pair} / 200 = MTBF_{drive} / 133
- Add 50 drives, each with parity across 4 data disks
 - MTBF_{set} = (MTBF_{drive} / 5) + (MTBF_{drive} / 4) = $0.45 * MTBF_{drive}$
 - MTTDL_{array} = MTBF_{set} / 50 = MTBF_{drive} / 111

Rebuild: restoring redundancy after failure



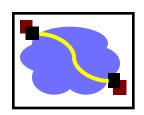
- After a drive failure
 - data is still available for access
 - but, a second failure is BAD
- So, should reconstruct the data onto a new drive
 - on-line spares are common features of high-end disk arrays
 - reduce time to start rebuild
 - must balance rebuild rate with foreground performance impact
 - a performance vs. reliability trade-offs
- How data is reconstructed
 - Mirroring: just read good copy
 - Parity: read all remaining drives (including parity) and compute

Reliability consequences of adding rebuild



- No data loss, if fast enough
 - That is, if first failure fixed before second one happens
- New math is...
 - MTTDL_{array} = MTBF_{firstdrive} * (1 / prob of 2nd failure before repair)
 - ... which is MTTR_{drive} / MTBF_{seconddrive}
- For mirroring
 - MTBF_{pair} = (MTBF_{drive} / 2) * (MTBF_{drive} / MTTR_{drive})
 - For 5-disk parity-protected arrays
 - MTBF_{set} = (MTBF_{drive} / 5) * ((MTBF_{drive} / 4)/ MTTR_{drive})

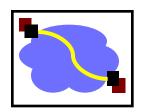
Three modes of operation



- Normal mode
 - everything working; maximum efficiency
- Degraded mode
 - some disk unavailable
 - must use degraded mode operations
- Rebuild mode

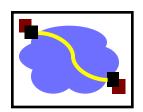
- reconstructing lost disk's contents onto spare
- degraded mode operations plus competition with rebuild

Mechanics of rebuild



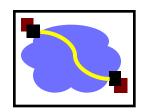
- Background process
 - use degraded mode read to reconstruct data
 - then, write it to replacement disk
- Implementation issues
 - Interference with foreground activity and controlling rate
 - Rebuild is important for reliability
 - Foreground activity is important for performance
 - Using the rebuilt disk
 - For rebuilt part, reads can use replacement disk
 - Must balance performance benefit with rebuild interference

Conclusions



- RAID turns multiple disks into a larger, faster, more reliable disk
- RAID-0: Striping Good when performance and capacity really matter, but reliability doesn't
- RAID-1: Mirroring Good when reliability and write performance matter, but capacity (cost) doesn't
 - RAID-5: Rotating Parity Good when capacity and cost matter or workload is read-mostly
 - Good compromise choice

Exam Details



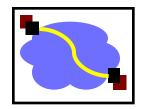
- Look at past exams (http://www.cs.cmu.edu/~srini/15-440/exams.html)
- Coverage C.
 Closed book
 No calculation
 Style

 short
 long

 Revi
 ' Coverage – up to and including RAID lecture

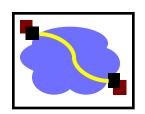
 - No calculator all calculations will be simple
 - - short answer questions
 - long, multi-part questions
 - Review session
 - Monday @ 4:30 in Rashid Auditorium in GHC

Disk Subsystem Load Balancing



- I/O requests are almost never evenly distributed
 - Some data is requested more than other data
 - Depends on the apps, usage, time, ...
- What is the right data-to-disk assignment policy?
 - Common approach: Fixed data placement
 - Your data is on disk X, period!
 - For good reasons too: you bought it or you're paying more...
 - Fancy: Dynamic data placement
 - If some of your files are accessed a lot, the admin(or even system) may separate the "hot" files across multiple disks
 - · In this scenario, entire files systems (or even files) are manually moved by the system admin to specific disks
 - Alternative: Disk striping
 - Stripe all of the data across all of the disks

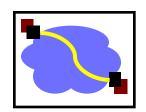
Disk striping details



How disk striping works

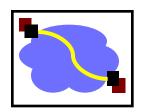
- Break up total space into fixed-size stripe units
- Distribute the stripe units among disks in round-robin
- Compute location of block #B as follows
 - disk# = B%N (%=modulo,N = #ofdisks)
 - LBN# = B / N (computes the LBN on given disk)

Hardware vs. Software RAID



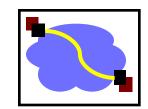
- Hardware RAID
 - Storage box you attach to computer
 - Same interface as single disk, but internally much more
 - Multiple disks
 - More complex controller
 - NVRAM (holding parity blocks)
- Software RAID
 - OS (device driver layer) treats multiple disks like a single disk
 - Software does all extra work
- Interface for both
 - Linear array of bytes, just like a single disk (but larger)

RAID 6



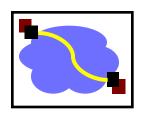
- P+Q Redundancy
 - Protects against multiple failures using Reed-Solomon codes
 - Uses 2 "parity" disks
 - P is parity
 - Q is a second code
 - It's two equations with two unknowns, just make "biggerbits"
 - Group bits into "nibbles" and add different coefficients to each equation (two independent equations in two unknowns)
- Similar to parity striping
 - De-clusters both sets of parity across all drives
 - For small writes, requires 6 I/Os
 - Read old data, old parity1, old parity2
 - Write new data, new parity1, new parity2

The Disk Array Matrix



	Independent	Fine Striping	Course Striping	
None	JBOD		RAID0	
Replication	Mirroring RAID1		RAID0+1	
Parity Disk		RAID3	RAID4	
Striped Parity	Gray90		RAID5	

Advanced Issues



- What happens if more than one fault?
 - Example: One disk fails plus "latent sector error" on another
 - RAID-5 cannot handle two faults
 - Solution: RAID-6 (e.g., RDP) Add multiple parity blocks
- Why is NVRAM useful?

- Example: What if update 2, don't update P0 before power failure (or crash), and then disk 1 fails?
- NVRAM solution: Use to store blocks updated in same stripe
 - If power failure, can replay all writes in NVRAM
- Software RAID solution: Perform parity scrub over entire disk

