

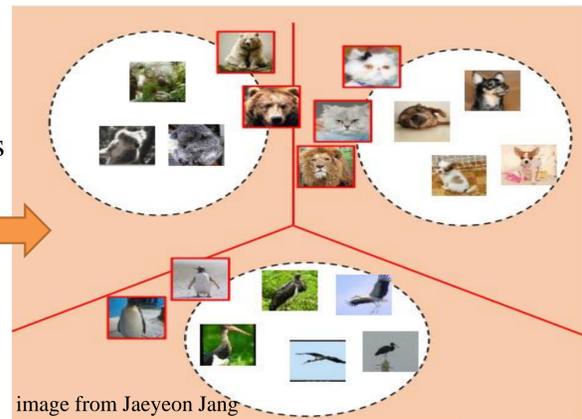
Motivation. Real-world machine learning systems need to analyze novel testing data that differs from the training data. Failing to recognize *unknown* objects causes serious safety concerns in autonomous vehicles (AVs).

A state-of-the-art semantic segmentation network has not been trained to recognize **strollers** or **street-market** (mid coln below). It misclassifies them as **motorcycle** and **building** (right coln below). Such misclassifications can be a critical mistake when fed into AVs because these objects require different plans for obstacle avoidance.



Problem formulation. Through the lens of K -way classification, a system should flag *unknown objects* not belonging to the pre-defined K classes, in addition to K -way classification. This is crisply formulated as *Open-Set Recognition*.

Open-Set Recognition requires recognizing examples from the pre-defined K classes and identifies *unknown examples* that belong to some other classes outside the K classes.



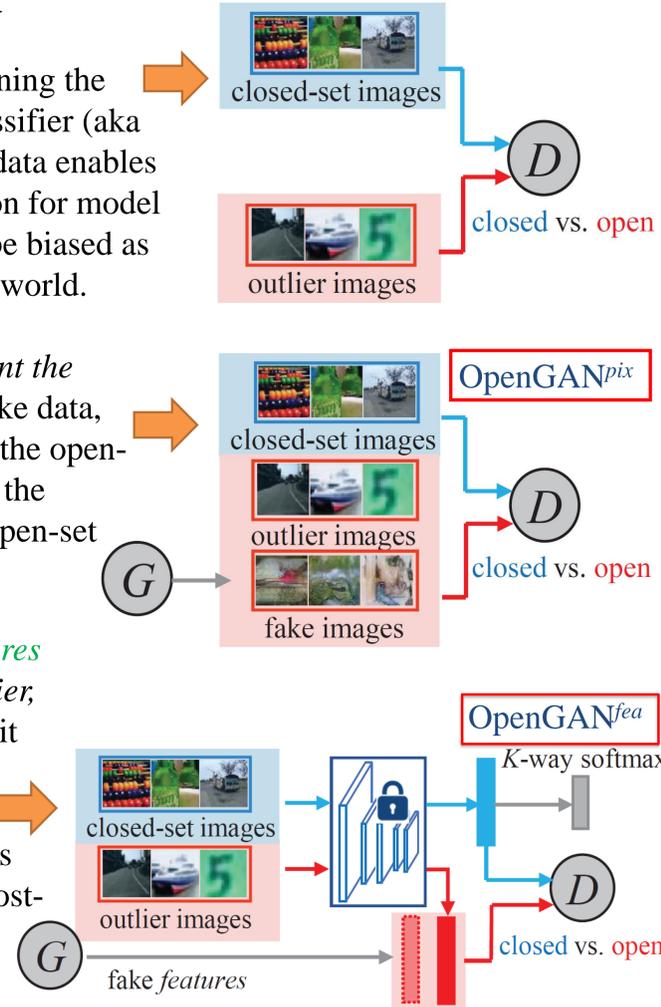
Our solution: OpenGAN trains a post-hoc open-set classifier to identify the open-set over **features** extracted from the off-the-shelf K -way network. The classifier is *adversarially* trained on real **outlier data** and **fake data**. To generate the **fake data**, we train a GAN by fooling the open-set classifier. That said, **open-set classifier \equiv GAN-discriminator!**

Key insights in OpenGAN

(a) Use **outlier data** for training the *discriminative* open-set classifier (aka Outlier Exposure). Outlier data enables stable training and validation for model selection. But outliers can be biased as they will not span the open world.

(b) Use **fake data** to augment the outlier data. To generate fake data, we train a GAN by fooling the open-set classifier. In this sense, the GAN-discriminator is the open-set classifier.

(c) Using **off-the-shelf features** to train the open-set classifier, rather than pixels. We find it much more effective to use features for open-set recognition than pixels. This leads to simply training a post-hoc lightweight model.



Experiment I: Cross-Dataset Open-Set Recognition

Metrics: Area Under ROC Curve and macro-F1 over $(K+1)$ classes

Setup: train a 200-way classification network on TinyImageNet train-set as the closed-set and another dataset (e.g., MNIST) as the outlier data, test on TinyImageNet test-set and a third dataset (e.g., CIFAR) as the open-set.

metric	MSP [24]	OpenMax [5]	NN ^{fea} [41]	GMM [26]	C2AE [35]	MSP _c [29]	MCdrop [17]	GDM [28]	CLS ^{pix} (K+1)	CLS ^{fea}	OpenGAN ^{pix}	OpenGAN ^{fea}
AUROC	.754	.686	.884	.945	.748	.834	.815	.857	.772	.936	.918	.969
F1	.560	.527	.552	.559	.569	.568	.567	.548	.568	.565	.576	.573

Conclusion

- Using features is better than pixels, ref. OpenGAN^{fea} vs OpenGAN^{pix}
- OpenGAN is better than binary classifiers, ref. OpenGAN^{fea} vs. CLS^{fea} which is a binary open-vs-closed classifier trained on features.
- OpenGAN is better than $(K+1)$ classifiers, ref. OpenGAN vs. $(K+1)$
- discriminative is better than generative, ref. OpenGAN vs. GMM

Visualization. Recall that the open-set classifier is the GAN-discriminator (a nonlinear MLP). It effectively groups closed- and open-set data in the off-the-shelf feature space. This intuitively shows why OpenGAN works.



Experiment II: Open-Set Discrimination (toyish but “standard”)

Setup: split a dataset (e.g., MNIST) into a closed-set (e.g., 0-5 digits) and an open-set (e.g., 6-9 digits) w.r.t class labels; train only on closed-set but test on both closed- and open-set.

Conclusion holds as in Experiment I.

Dataset	MSP [24]	MSP _c [29]	MCdrop [17]	GDM [28]	OpenMax [5]	GOpenMax [18]*	OSRCI [33]*	C2AE [35]*	CROS [54]*	RPL [10]*	Hybrid [57]*	GDFR [37]*	NN ^{pix} [41]	NN ^{fea} [41]	OpenGAN ^{-0^{pix}}	OpenGAN ^{-0^{fea}}
MNIST	.977	.985	.984	.989	.981	.984	.988	.989	.991	.996	.995	—	.931	.981	.987	.999
SVHN	.886	.891	.884	.866	.894	.896	.910	.922	.899	.968	.947	.935	.534	.888	.881	.988
CIFAR	.757	.808	.732	.752	.811	.675	.699	.895	.883	.901	.950	.807	.544	.801	.971	.973
TinyImageNet	.577	.713	.675	.712	.576	.580	.586	.748	.589	.809	.793	.608	.528	.692	.795	.907

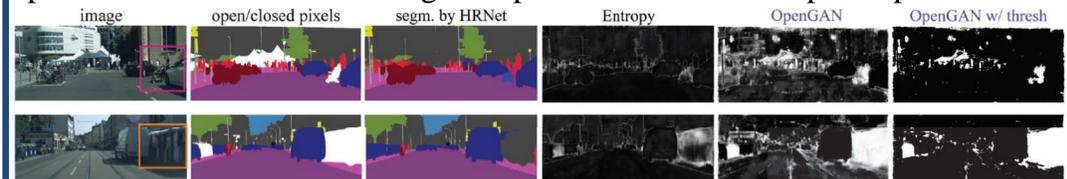
Experiment III: Open-Set Semantic Segmentation

Setup: recognize unknown object pixels in the context of semantic segmentation.

Conclusion holds as in Experiment I. Importantly, OpenGAN performs significantly better than existing open-set methods. Moreover, unlike OpenGAN which is a simple discriminative method, image-reconstruction based methods (not shown here) do not work well because of the difficulties in reconstructing high-resolution images.

MSP [24]	Entropy [49]	OpenMax [5]	C2AE [35]	MSP _c [29]	MCdrop [17]	GDM [28]	GMM [26]	HRNet-(K+1)	OpenGAN-0 ^{fea}	CLS ^{fea}	OpenGAN ^{fea}
.721	.697	.751	.722	.755	.767	.743	.765	.755	.709	.861	.885

Visualization. Second coln: white pixels are the “ground-truth” open-set pixels. Last coln: thresholding the open-set likelihood map of OpenGAN.



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