# Techniques for Speeding Up CFR (some of these apply to other algorithms also)

**Tuomas Sandholm** 

### Focus of this lecture

- Theoretically sound techniques that are
- game-independent
- …although game-specific techniques also exist
  - Johanson et al. *IJCAI*-11 faster traversal; applies at least to poker
  - Farina & Sandholm 2021 sequence form LP sparsification; applies well at least to poker

# TECHNIQUE FAMILY 1: "PREDICTIVITY AKA. OPTIMISM"

**ALREADY COVERED IN AN EARLIER LECTURE** 

## **TECHNIQUE 2: "ALTERNATION"**

### Alternation

 In CFR, perform update for P1, then update for P2, and so on, instead of interleaving them

#### **Simultaneous iterates:**

#### for t = 1, ..., T:

- $x^t \leftarrow \text{request strategy from P1's RM}$
- $y^t \leftarrow$  request strategy from P2's RM
- Pass utility  $Ay^t$  to P1's RM
- Pass utility  $-\mathbf{A}^{\mathsf{T}}\mathbf{x}^{t}$  to P2's RM

#### **Alternating iterates:**

for t = 1, ..., T:

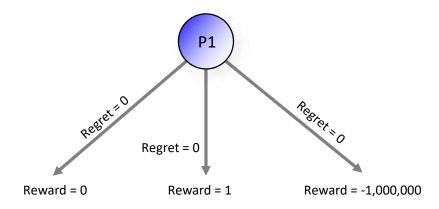
- $y^t \leftarrow \text{request strategy from P2's RM}$
- Pass utility  $Ay^t$  to P1's RM
- $x^t \leftarrow$  request strategy from P1's RM
- Pass utility  $-A^{T}x^{t}$  to P2's RM
- Motivation: updates each agent based on the newest strategy of the opponent
- Converges faster in practice
- Still provable  $O(\sqrt{T})$  cumulative regret [Burch et al. JAIR-19]
- Wibisono-Tao-Piliouras (2022) showed that alternating mirror descent has T<sup>1</sup>(1/3) regret in zero-sum games, and Katona-Wang-Wibisono (2025) improved this to T<sup>1</sup>(1/5)
- <u>Farina et al. (2023)</u> gave a lower bound of (roughly) T^{1/2} for alternating RM+

### **TECHNIQUE FAMILY 3: "RE-WEIGHTING"**

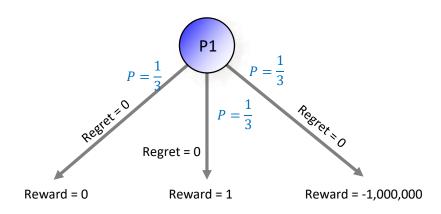
[BROWN & SANDHOLM AAAI-19 DISTINGUISHED PAPER HONORABLE MENTION]

THIS WAS THE FASTEST ALGORITHM FOR 0-SUM GAMES (NORMAL- AND EXTENSIVE-FORM) AT THE TIME

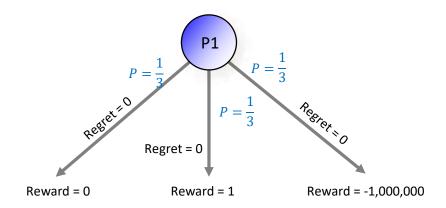
i.e., the previously fastest algorithm in practice



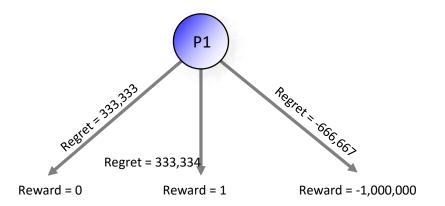
 On first iteration, pick all actions with equal probability



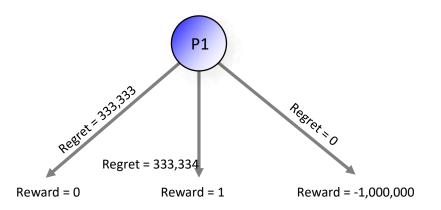
- On first iteration, pick all actions with equal probability
- Expected reward is -333,333



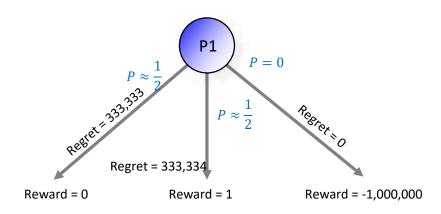
- On first iteration, pick all actions with equal probability
- Expected reward is -333,333
- Update regret as
   Action EV Achieved EV



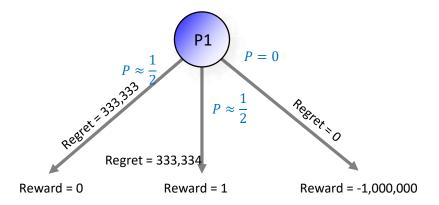
- On first iteration, pick all actions with equal probability
- Expected reward is -333,333
- Update regret as
   Action EV Achieved EV
- CFR+ floors regret at zero



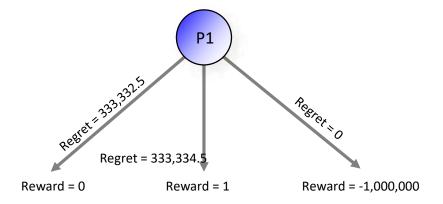
 On second iteration, pick actions
 proportional to their regret

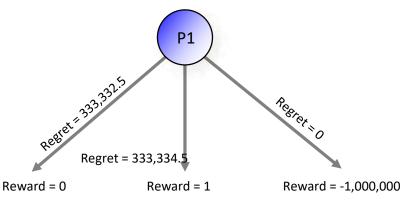


- On second iteration, pick actions
   proportional to their regret
- Expected reward  $\approx 0.5$



- On second iteration, pick actions
   proportional to their regret
- Expected reward  $\approx 0.5$
- Update regret





- Problem:
   Takes CFR+ 471,407 iterations to learn to pick the middle action with 100% probability!
- Solution:
   Discount early "bad" iterations' regrets and average strategy by weighing iteration t by t
  - We coin this Linear CFR
  - Takes only 970 iterations to learn to pick the middle action
  - Worst-case convergence bound increases by only a factor  $\frac{2}{\sqrt{3}}$  ...

## Weighted Averaging Schemes for CFR+

Works for any sequence of nondecreasing weights:

**Theorem 1.** Suppose T iterations of RM+ are played in a two-player zero-sum game. Then the weighted average strategy profile, where iteration t is weighed proportional to  $w_t > 0$  and  $w_i \leq w_j$  for all i < j, is a  $\frac{w_T}{\sum_{t=1}^T w_t} \Delta |\mathcal{I}| \sqrt{|A|} \sqrt{T}$ -Nash equilibrium.

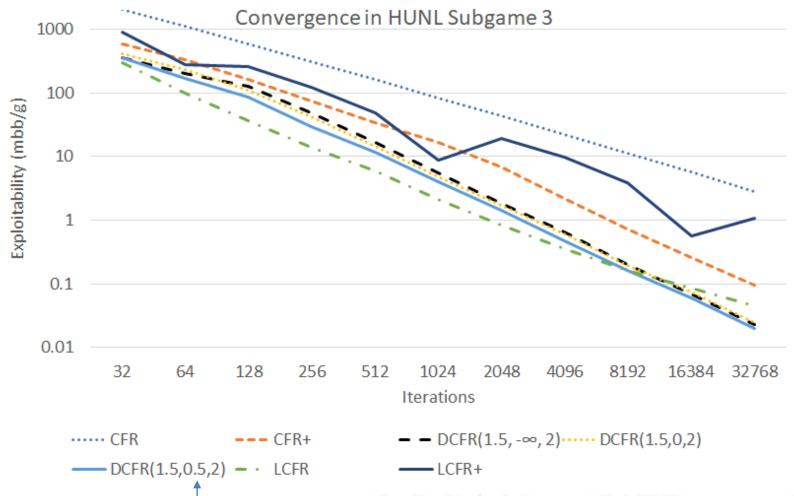


Bound is never lower than with uniform weights.

### Discounted CFR

- Linear CFR: Weigh iteration t by t (in regrets and in averaging)
- CFR+: Floor regrets at zero (and weigh iteration t by t in averaging)
- Can we combine both into Linear CFR+?
  - Theory: Yes!
  - Practice: No! Does very poorly
- But less-aggressive combinations do well: Discounted CFR (DCFR)
  - On each iteration, multiply positive regrets by  $\frac{t^{\alpha}}{t^{\alpha}+1}$
  - On each iteration, multiply negative regrets by  $\frac{t^{\beta}}{t^{\beta}+1}$
  - Weight contributions toward average strategy by  $(\frac{t}{t+1})^{\gamma}$
  - Worst-case convergence bound only a small constant worse than CFR
  - For  $\alpha=1.5$ ,  $\beta=0$ ,  $\gamma=2$ , consistently outperforms CFR+ in practice

#### Experiment on heads-up no-limit Texas hold'em endgames used by *Libratus*



 $\beta$  > 0 facilitates regret-based pruning (to be discussed next in this lecture) because regrets can get negative, so we also show results for  $\beta$  =1/2.

Empirically we observed that CFR+ converges faster when assigning iteration t a weight of  $t^2$  rather than a weight of t when calculating the average strategy. We therefore use this weight for CFR+ and its variants throughout this paper when calculating the average strategy.

### Further improvements in this paper

- In Discounted CFR, can discount contributions to the average strategy in different ways
  - CFR+ does this in a specific way: linear
  - We show that many other ways are theoretically valid: any nondecreasing weight sequence where final weight/sum of weights -> 0 works
    - E.g.,  $t^x$  for any x > 0
    - Many choices in the valid space are empirically faster
- Monte Carlo Linear CFR
  - CFR+ and Discounted CFR do poorly with sampling, but Linear CFR does very well

• ...

# Conclusions on this paper

- Superior performance is achieved by discounting early CFR iterations
- Discounted CFR (DCFR) matches or exceeds CFR+ in all domains tested and was the state-of-the-art equilibrium-finding algorithm in large imperfectinformation games
- Linear CFR (LCFR) does even better in games with extremely suboptimal action, but is inferior to DCFR otherwise
  - Also works well with sampling, unlike CFR+ and DCFR

### Hyperparameter Schedules

["Faster Game Solving via Hyperparameter Schedules", N. Zhang, S. McAleer & T. Sandholm, 2024]

### Discounted CFR (DCFR)

- On each iteration, multiply positive regrets by  $\frac{t^{\alpha}}{t^{\alpha}+1}$
- On each iteration, multiply negative regrets by  $\frac{t^{\beta}}{t^{\beta}+1}$
- Weight contributions toward average strategy by  $(\frac{t}{t+1})^{\gamma}$
- For any t,  $\alpha = 1.5$ ,  $\beta = 0$ ,  $\gamma = 2$ , that is, uses a fixed weighting scheme using a constant Hyperparameter Schedule (HS)

### Hyperparameter Schedule-Powered DCFR

#### HS-DCFR

- On each iteration, multiply positive regrets by  $\frac{t^{HS}\alpha}{t^{HS}\alpha+1}$
- On each iteration, multiply negative regrets by  $\frac{t^{HS}\beta}{t^{HS}\beta+1}$
- Weight contributions toward average strategy by  $(\frac{t}{t+1})^{HS\gamma}$
- $HS_{\alpha}: \alpha = 1 + \frac{3}{n}t, HS_{\beta}: \beta = -1 \frac{2}{n}t$
- $HS_{\gamma 30}$ :  $\gamma_{30} = \frac{30}{n} \frac{5}{n}t$ ,  $HS_{\gamma 15}$ :  $\gamma_{15} = \frac{15}{n} \frac{5}{n}t$ 
  - Performs experimentally better than just setting weights of first 1/3 of iterations to 0
- -n is, say, the total number of iterations that will be run

### Hyperparameter Schedule-powered DCFR

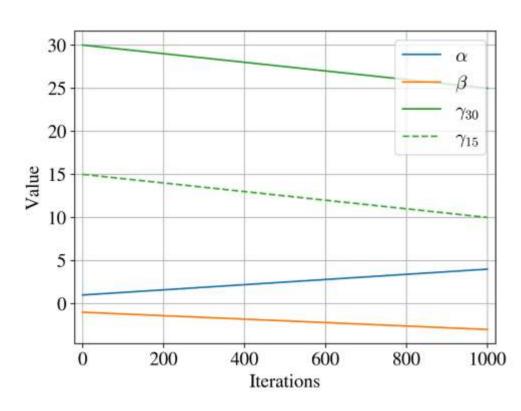
### HS-DCFR(30) & HS-DCFR(15)

$$- HS_{\alpha}: \alpha = 1 + \frac{3}{n}t$$

$$- HS_{\beta}: \beta = -1 - \frac{2}{n}t$$

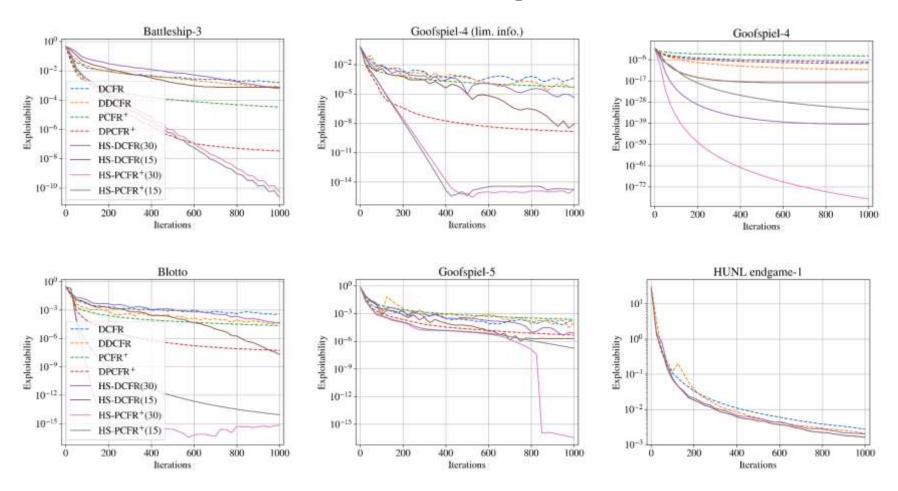
$$- HS_{\gamma 30}: \gamma_{30} = 30 - \frac{5}{n}t$$

$$- HS_{\gamma 15}: \gamma_{15} = 15 - \frac{5}{n}t$$



- In our experiments, we set n to 1000

### **HS-Powered Algorithms**



Orders of magnitude speed improvements over prior state-of-the-art algorithms on both extensive-form and normal-form games!

State of the art

# TECHNIQUE FAMILY 4: "DYNAMIC PRUNING TECHNIQUES"

Why not permanent pruning like  $\alpha\beta$ -pruning in perfect-information games?

# Early idea: "Partial Pruning"

[Lanctot et al. ICML-09]

 If on some path, the opponent's reach (i.e., probability of playing there) is 0, then that path can be pruned because it will not affect the regrets

 This is a no-brainer to use, but one can prune more ...

#### Next idea: "Interval Regret-Based Pruning (Interval RBP)"

#### [Brown & Sandholm NeurIPS-15]

- While partial pruning allows one to prune paths that an opponent reaches with zero probability, Interval RBP allows one to also prune paths that the agent reaches with zero probability
- Such pruning is necessarily temporary. Consider an action  $a \in A(I)$  such that  $\sigma^t(I, a) = 0$ , and assume that it is known action a will not be played with positive probability until some far-future iteration t' (in RM, this would be the case if  $R^t(I, a) << 0$ )
  - To determine t', the condition on when regret might turn positive can be projected conservatively or checked dynamically
- Since action a is played with zero probability on iteration t, the strategy played and reward received following action a (that is, in D(I, a)) will not contribute to the regret for any information set preceding action a on iteration t. In fact, what happens in D(I, a) has no bearing on the rest of the game tree until iteration t'. So one can **procrastinate** in deciding what happened beyond action a on iterations t, ..., t'-1
- Upon reaching iteration t', rather than individually making up the t'-t iterations over D(I, a), one can do a single iteration, playing against the average of the opponents' strategies in those iterations that were missed, and declare that we played that strategy on all the missed iterations
- Moreover, since player i never plays action a with positive probability between iterations t and t',
  every other player can apply partial pruning on that part of the game tree for those iterations, i.e.,
  skip it completely
- This, in turn, means that player i has free rein to play whatever she wants in D(I, a) without affecting the regrets of the other players. In light of that, and of the fact that player i gets to decide what is played in D(I, a) after knowing what the other players have played, player i might as well play a strategy that ensures zero regret for all information sets I'∈D(I, a) in the iterations t...t'. A CBR to the average of the opponent strategies on iterations t...t' would qualify as such a zero-regret strategy
  - Definition. A counterfactual best response (CBR) is a strategy similar to a best response, except that it
    maximizes counterfactual value even at information sets that it does not reach due to its earlier actions

### Next idea: "Total Regret-Based Pruning (Total RBP)"

[Brown & Sandholm ICML-17]

- When pruning ends and regret must be updated in the pruned branch:
  - Interval RBP calculates a CBR to the average opponent strategy over the skipped iterations t...t', and updates regret in the pruned branch as if that CBR strategy were played in those iterations
  - Total RBP calculates a CBR in the pruned branch against the opponent's average strategy over all iterations 1...t' played so far, and sets regret as if that CBR strategy were played in all those iterations
    - Instead of CBR, an approximate CBR can be used. The paper shows how approximate it can be to still get the theoretical convergence guarantee
      - In practice CFR converges much faster than the theoretical bound, so the potential function (used in the convergence proof) is typically far lower than the theoretical bound. Thus, while choosing a near-CBR rather than an exact CBR may allow for slightly longer pruning according to the theory, it may actually result in worse performance. Clever heuristics for deciding on a near-CBR may lead to even better performance in practice
- Again, to determine t', the condition on when regret might turn positive can be projected conservatively or checked dynamically (formula is in the paper)

### Total RBP Has a Space Advantage

- Storing regrets:
  - Pruned subtrees need not be stored because their regrets are computed from scratch at iteration t'
    - **Theorem.** For any information set I and action  $a \in A(I)$  that is not part of a best response to a Nash equilibrium, there is an iteration  $T_{l,a}$  such that for all  $T \ge T_{l,a}$ , action a in information set I (and its descendants) could be pruned forever
      - The algorithm won't know whether T has met the condition, so every once in a while a (near) best response computation in D(I, a) needs to be done, but that doesn't require storing regrets
- Storing average strategies: Fortunately, if action a in information set I is pruned for long enough, the stored cumulative strategy in D(I, a) can be discarded at the cost of a small increase in the distance of the final average strategy from a Nash equilibrium (by saying we never play a in I)
- Corollary. In a zero-sum game (with some threshold on the average strategy C/sqrt(T) for C>0), after a finite number of iterations, CFR with Total RBP requires only
  - $O(|\#infosets\ not\ pruned\ by\ above\ theorem||A|)\ space$
  - Can be useful, e.g., if the abstraction is grown dynamically

#### Total RBP Is Faster than CFR

- Same number of iterations
- Iterations are faster
  - Intuitively, as both players converge to a Nash equilibrium, actions that are not a CBR will eventually do worse than actions that are, so those suboptimal actions will accumulate increasing amounts of negative regret. This allows those action to be pruned for increasingly long periods
  - **Theorem.** In a zero-sum game, if both players choose strategies according to CFR with Total RBP, conducting T iterations traverses only  $O(|S|T + |H| \ln(T))$  nodes

Game paths that are part of some All game paths (i.e., infosets) CBR to some equilibrium

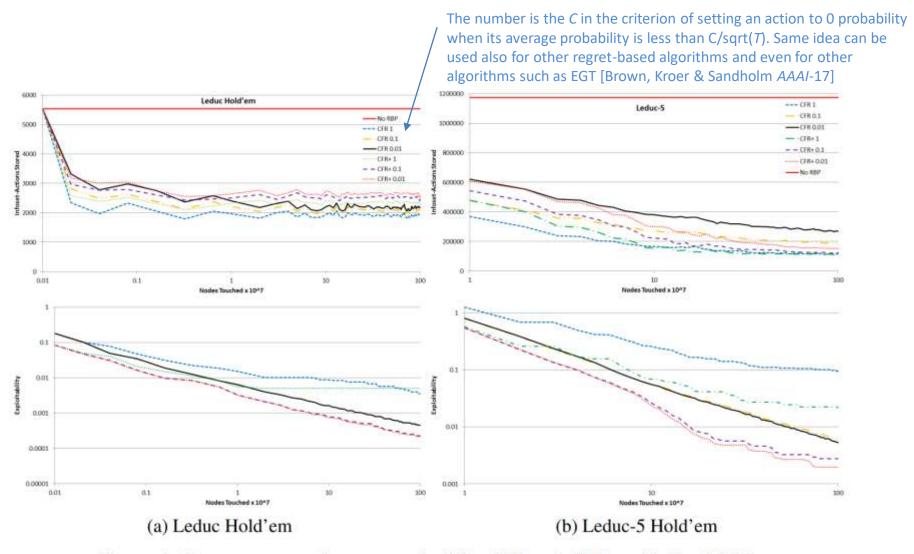


Figure 1: Convergence and space required for CFR and CFR+ with Total RBP.

**Detail about CFR+:** Since Interval RBP can only prune negative-regret actions, Interval RBP modifies the definition of CFR+ so that regret can be negative, but immediately jumps up to zero as soon as regret increases. Total RBP does not require this modification. Both forms of RBP modify the behavior of CFR+ because without pruning, CFR+ would put positive probability on an action as soon as its regret increases, while RBP waits until pruning is over. CFR+'s linear weighting of the average strategy is only guaranteed to converge to a Nash equilibrium if pruning does not occur. While pruning does well empirically with CFR+, the convergence is noisy. This noise can be reduced by using the lowest-exploitability average strategy profile found so far. We did that in this experiment

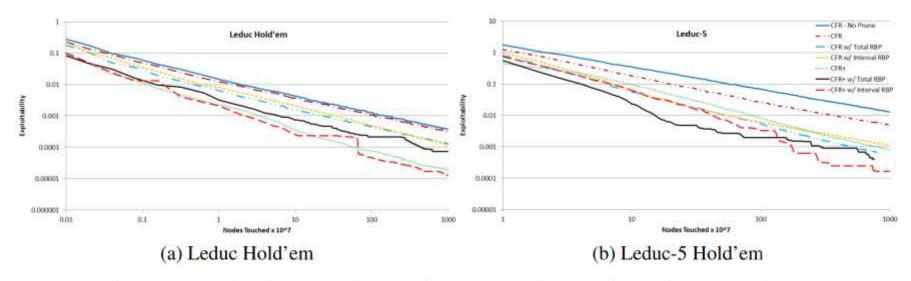


Figure 2: Convergence for CFR and CFR+ with only partial pruning, with Interval RBP, and with Total RBP. "CFR - No Prune" is CFR without any pruning.

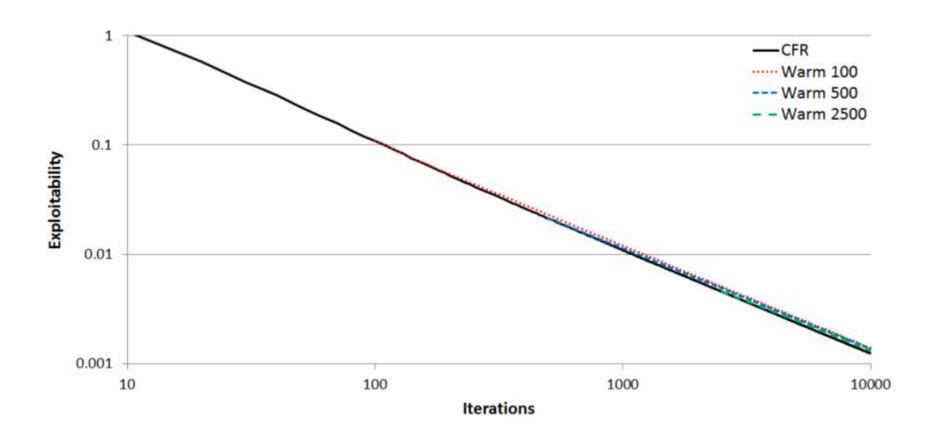
# TECHNIQUE FAMILY 5: "WARM STARTING"

## Warm starting CFR from any strategies

[Brown & Sandholm AAAI-16]

- Just starting CFR from given strategies naively doesn't help (and often hurts) compared to starting CFR from uniform strategies
  - Thus it was believed that CFR can't be warm started, but we showed it can
- The input strategies can come from any source: hand crafted, a different algorithm, CFR run on a coarser abstraction, etc.
- Enables simultaneous abstraction and equilibrium finding
  - See also earlier paper on that [Brown & Sandholm IJCAI-15]
- Idea: Pretend that the input strategies came from CFR by not just setting the average strategies but also setting the number of iterations so far T and the regrets appropriately
  - The paper shows the constraints that need to be satisfied to make the CFR proof go through, and suggests practically well-performing choices within those constraints

## Experiment on Flop Texas hold'em



### Another experiment on Flop Texas hold'em

