# 10417/10617 Intermediate Deep Learning: Fall2019

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https://deeplearning-cmu-10417.github.io/

Midterm Review

## Midterm Review

- Polynomial curve fitting generalization, overfitting
- Loss functions for regression

$$\mathbb{E}[L] = \int \int (t - y(\mathbf{x}))^2 p(\mathbf{x}, t) d\mathbf{x} dt.$$

- Generalization / Overfitting
- Statistical Decision Theory

## Midterm Review

- Bernoulli, Multinomial random variables (mean, variances)
- Multivariate Gaussian distribution (form, mean, covariance)
- Maximum likelihood estimation for these distributions.
- Exponential family / Maximum likelihood estimation / sufficient statistics for exponential family.

$$p(\mathbf{x}|\boldsymbol{\eta}) = h(\mathbf{x})g(\boldsymbol{\eta}) \exp \left\{ \boldsymbol{\eta}^{\mathrm{T}} \mathbf{u}(\mathbf{x}) \right\}$$

• Linear basis function models / maximum likelihood and least squares:

$$\ln p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \beta) = \sum_{i=1}^{N} \ln \mathcal{N}(t_n | \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_n), \beta)$$

$$= -\frac{\beta}{2} \sum_{n=1}^{N} (t_n - \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_n))^2 + \frac{N}{2} \ln \beta - \frac{N}{2} \ln(2\pi).$$

$$\mathbf{w}_{\mathrm{ML}} = \left(\mathbf{\Phi}^{\mathrm{T}} \mathbf{\Phi}\right)^{-1} \mathbf{\Phi}^{\mathrm{T}} \mathbf{t}$$

## Midterm Review

Regularized least squares:

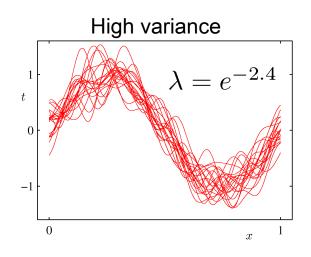
$$\frac{1}{2} \sum_{n=1}^{N} \{t_n - \mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}_n)\}^2 + \frac{\lambda}{2} \mathbf{w}^{\mathrm{T}} \mathbf{w} \qquad \mathbf{w} = \left(\lambda \mathbf{I} + \boldsymbol{\Phi}^{\mathrm{T}} \boldsymbol{\Phi}\right)^{-1} \boldsymbol{\Phi}^{\mathrm{T}} \mathbf{t}.$$

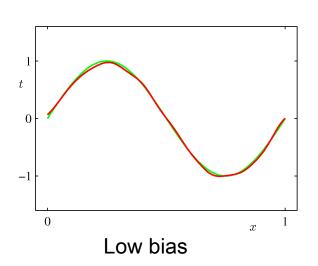
$$\mathbf{w} = \left(\lambda \mathbf{I} + \mathbf{\Phi}^{\mathrm{T}} \mathbf{\Phi}\right)^{-1} \mathbf{\Phi}^{\mathrm{T}} \mathbf{t}.$$

Ridge

regression

Bias-variance decomposition.

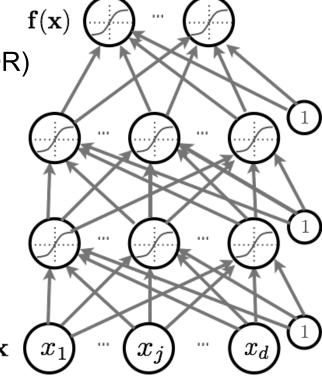




Gradient Descend, SGD, Parameter Update Rules

## **Neural Networks**

- How neural networks predict f(x) given an input x:
  - Forward propagation
  - Types of units
  - Capacity of neural networks (AND, OR, XOR)
- How to train neural nets:
  - Loss function
  - Backpropagation with gradient descent
- More recent techniques:
  - Dropout
  - Batch normalization
  - Unsupervised Pre-training



# Artificial Neuron: Logistic Regression

Neuron pre-activation (or input activation):

$$a(\mathbf{x}) = b + \sum_{i} w_i x_i = b + \mathbf{w}^{\top} \mathbf{x}$$

Neuron output activation:

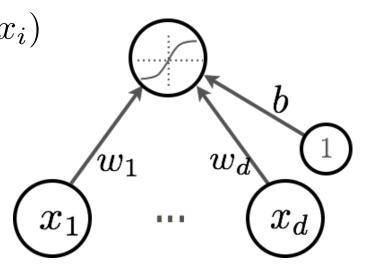
$$h(\mathbf{x}) = g(a(\mathbf{x})) = g(b + \sum_{i} w_i x_i)$$

where

**W** are the weights (parameters)

b is the bias term

 $g(\cdot)$  is called the activation function

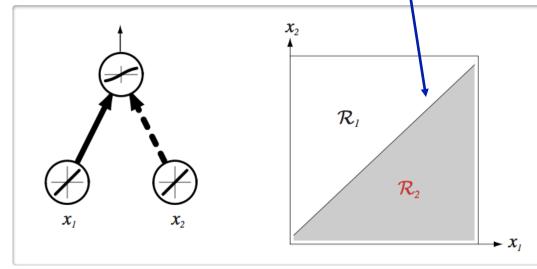


## Decision Boundary of a Neuron

- Binary classification:
  - With sigmoid, one can interpret neuron as estimating  $p(y=1|\mathbf{x})$
  - Interpret as a logistic classifier

**Decision boundary** 

- If activation is greater than 0.5, predict 1
- Otherwise predict 0

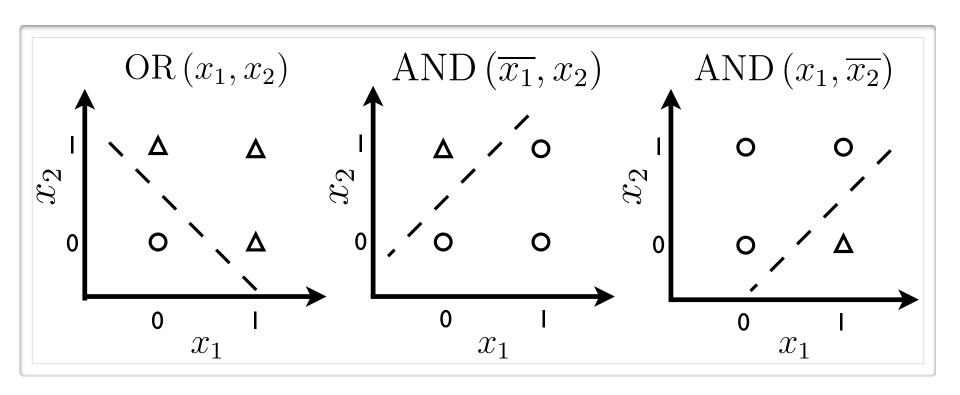


(from Pascal Vincent's slides)

Same idea can be applied to a tanh activation

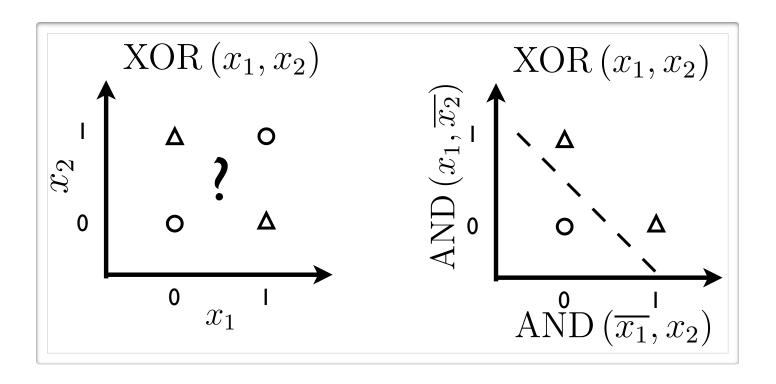
# Capacity of a Single Neuron

• Can solve linearly separable problems.



# Capacity of a Single Neuron

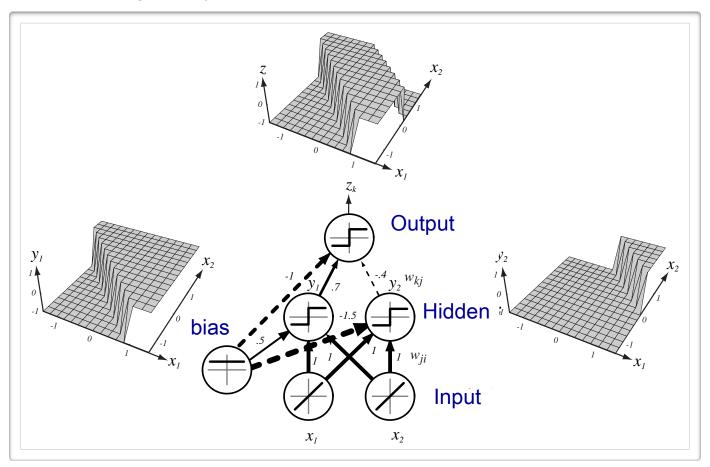
Can not solve non-linearly separable problems.



- Need to transform the input into a better representation.
- Remember basis functions!

## Capacity of Neural Nets

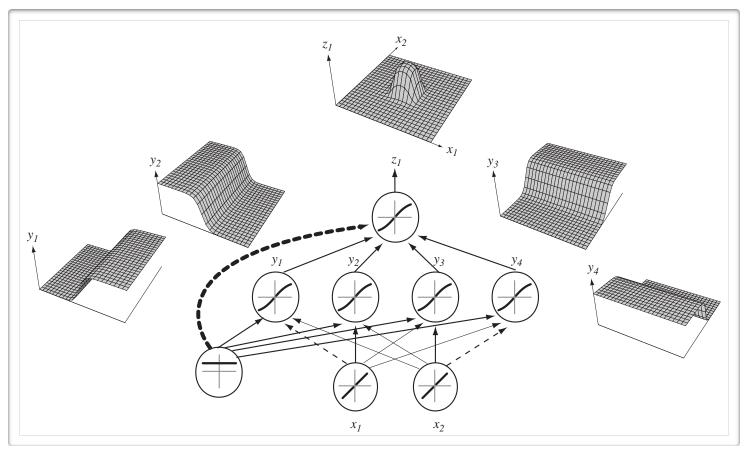
Consider a single layer neural network



(from Pascal Vincent's slides)

## Capacity of Neural Nets

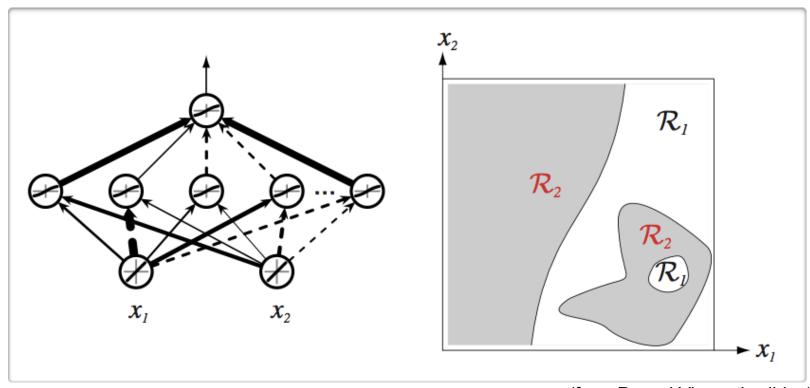
Consider a single layer neural network



(from Pascal Vincent's slides)

## Capacity of Neural Nets

Consider a single layer neural network



(from Pascal Vincent's slides)

#### **Neural Networks**

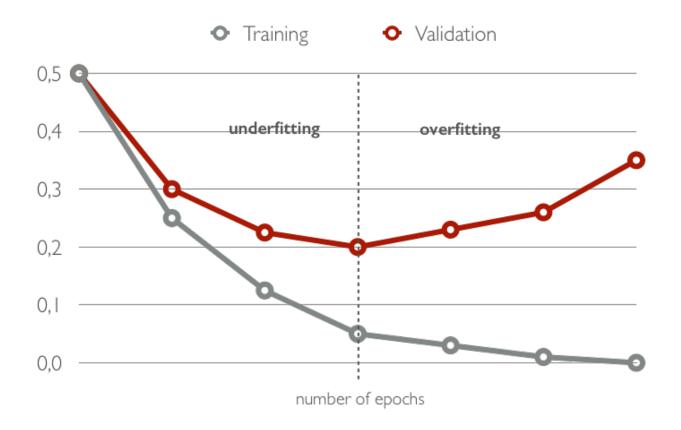
- SGD Training, cross entropy loss, ReLU activations
- Classification with neural networks
- Regularization, Dropout, Batchnorm
- Forward Propagation and Backprop (computing derivatives)

## Model Selection

- Training Protocol:
  - Train your model on the Training Set  $\mathcal{D}^{\mathrm{train}}$
  - For model selection, use Validation Set  $\mathcal{D}^{\mathrm{valid}}$ 
    - > Hyper-parameter search: hidden layer size, learning rate, number of iterations/epochs, etc.
  - Estimate generalization performance using the Test Set  $\mathcal{D}^{\mathrm{test}}$
- Remember: Generalization is the behavior of the model on unseen examples.

# **Early Stopping**

• To select the number of epochs, stop training when validation set error increases (with some look ahead).



#### Conv Nets

- Convolutional networks leverage these ideas
  - Local connectivity
  - Parameter sharing
  - Convolution
  - Pooling / subsampling hidden units
  - Understanding Receptive Fields

Local contrast normalization, rectification