

18544: Network Design and Evaluation

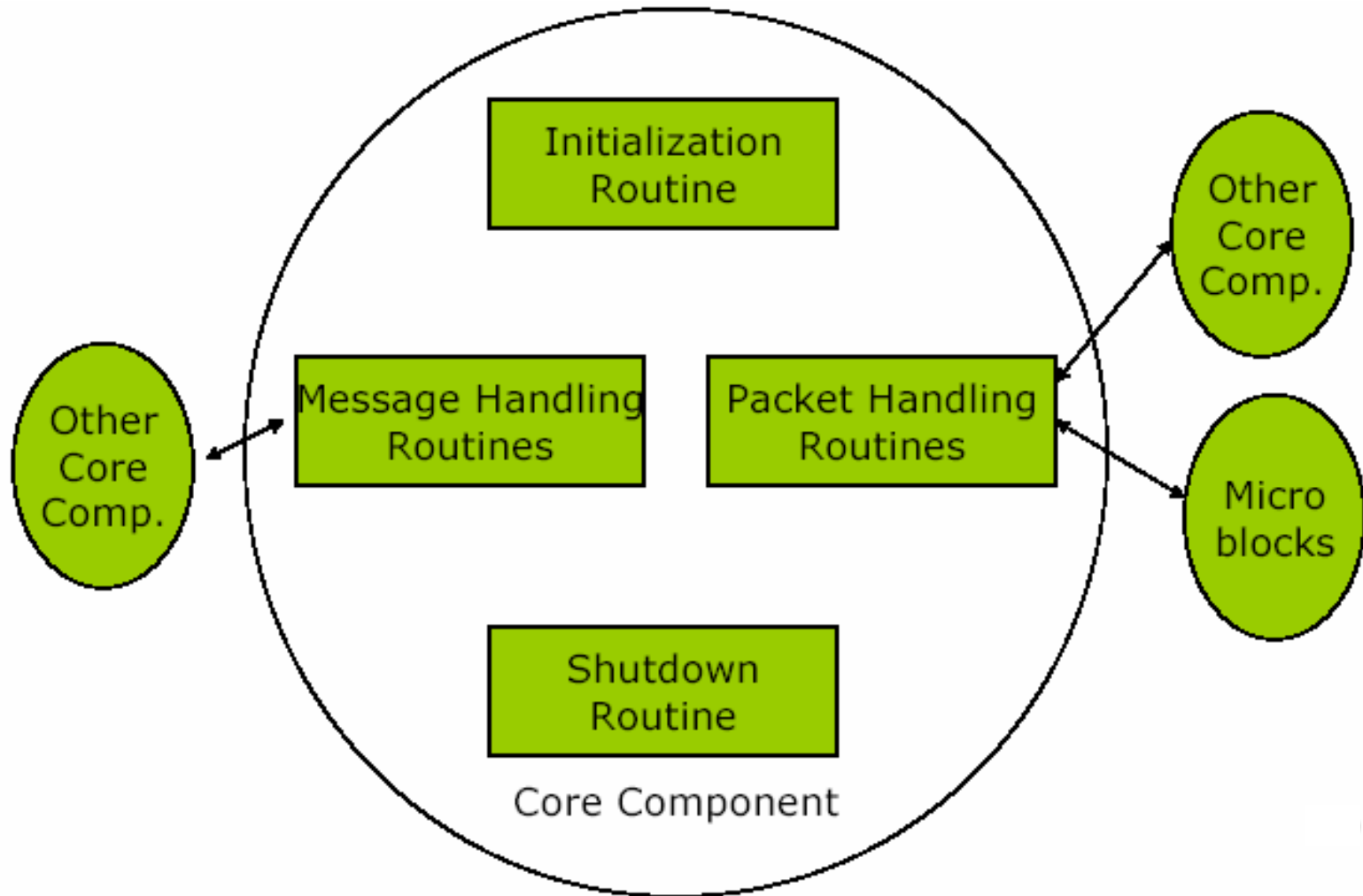


Core Components Review
and Using Hardware
Sept 19, 2006

Agenda

- ❑ Core Component Programming
 - Memory management
 - Patching symbols
 - Exchanging Packets
- ❑ Using Hardware
 - Building the core
 - Booting up the application

Structure of a Core Component



Memory Management [1]

- ❑ Memory used by core components managed using malloc and free
- ❑ Resource Manager manages memory accessed by the microengines
- ❑ To allocate memory from the Intel XScale core using Resource Manager

```
IX_EXPORT_FUNCTION ix_error  
    ix_rm_mem_alloc(  
        ix_memory_type arg_MemType,  
        ix_uint32 arg_MemChannel,  
        ix_uint32 arg_Size,  
        void** arg_pMemoryAddr);
```

Memory Management [2]

- ❑ Address microengines use may be different than Intel XScale core
- ❑ For example, if you want to give an address returned by `ix_rm_mem_alloc` to the microengines, convert it to an address which can be used by microengines using `ix_rm_get_phys_offset` function
- ❑ Also tells the memory type and channel if required

Patching Load-time Constants [1]

- ❑ A way of communication between the XScale core and microengines
- ❑ Used in patching memory locations determined when the core component is initialized
 - The values of these constants are not known at compile time, but rather are determined at the code loading time
 - The values cannot be changed once they are set (can be only changed by stopping and reloading the microengines)

Patching Load-time Constants [2]

▣ Signature of load-time constants:

```
IX_EXPORT_FUNCTION ix_error  
    ix_rm_ueng_patch_symbols(  
        ix_uint32 arg_MENumber,  
        ix_uint32 arg_SymbolsNumber,  
        const ix_imported_symbol  
        arg_aSymbols[]);
```

▣ In microengine assembly code:

```
.import_var ETHERNET_SYMBOL_NAME
```

or in microengine C:

```
int ETHERNET_DATA =  
    LoadTimeConstant ("ETHERNET_SYMBOL_NAME");
```

Example

//Allocate shared memory for the control block

```
err = ix_rm_mem_alloc(IX_MEMORY_TYPE SRAM,  
    channel, sizeof(ethernet_control_block),  
    (void**)eth_context->control_block);
```

```
if (err != IX_SUCCESS)  
    // error handling
```

```
err = ix_rm_get_phys_offset( eth_context->  
    control_block, NULL, NULL, NULL,  
    &control_block_phys );
```

```
if (err != IX_SUCCESS)  
    // error handling
```


Example (Cont.)

```
//Now patch the control block symbol for all
//of the microengines on which Ethernet
//microblocks will run
for (i = 0; i < sizeof(me_numbers); i++) {
    ix_imported_symbol symbol;
    symbol.m_value = (ix_uint32)
        control_block_phys;
    symbol.m_name = ETHERNET_SYMBOL_NAME;
    err = ix_rm_ueng_patch_symbols(i, 1, &symbol);
    if (err != IX_SUCCESS)
        //error handling
}
```

Packet Handling

- ❑ The XScale Core handles infrequently - arriving packet types that require more complicated processing
 - Control and configuration packets
 - ❑ Routing update packets
 - Packets requiring lengthy processing
 - ❑ IP packets with options
 - Correcting erroneous conditions
 - ❑ Sending ICMP packets
 - Other packets not handled by microblocks

Packet Handling: MB \Rightarrow CC [1]

- ❑ The core component needs to register the packet handler routines
- ❑ The signature of the handler function:

```
ix_error (* ix_pkt_handler) (  
    ix_buffer_handle arg_hDataToken,  
    ix_uint32 arg_ExceptionCode,  
    void* arg_pComponentContext)
```

Packet Handling: MB \Rightarrow CC [2]

- Use `ix_cci_cc_add_packet_handler` to register the handler in the core:

```
ix_error  
    ix_cci_cc_add_packet_handler(  
        ix_cc_handle arg_hComponent,  
        ix_uint32 arg_InputID,  
        ix_pkt_handler arg_Handler,  
        ix_input_type arg_SourceType );
```

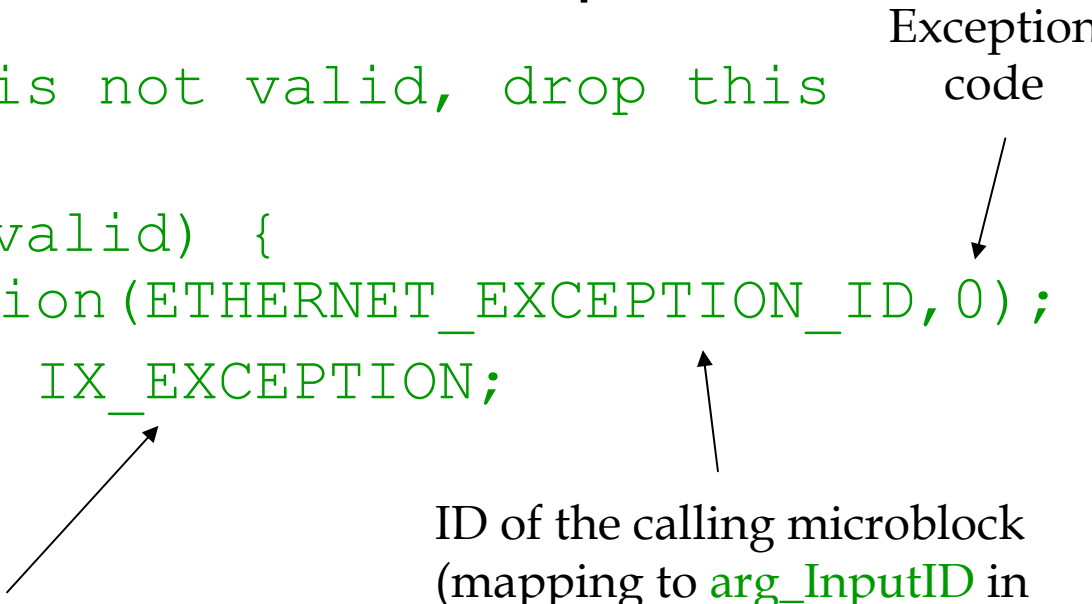
Packet Handling: MB \Rightarrow CC [3]

- When microblock wants to send packets to its core component:
 - it sets the next block value to the unique packet handler identifier (i.e. Input ID)
 - The microblock can also set a 32-bit exception code

Packet Handling: MB \Rightarrow CC [4]

- ▣ The following microengine C code sends packet to the Ethernet core component:

```
// If the entry is not valid, drop this packet
if(!table_entry.valid) {
    dl_set_exception(ETHERNET_EXCEPTION_ID, 0);
    dlNextBlock = IX_EXCEPTION;
    return;
}
```



Dispatch loop will catch this packet and notify the core


ID of the calling microblock
(mapping to `arg_InputID` in
`ix_cci_cc_add_packet_handler`)

Packet Handling: CC \Rightarrow MB [1]

- Core components can send packets to microblocks or other core components using the following API:

```
ix_error ix_rm_packet_send(  
    ix_communication_id  
        arg_CommunicationId,  
    ix_buffer_handle arg_MessageBuffer,  
    ix_uint32 arg_UserData );
```

Destination
Microblock ID

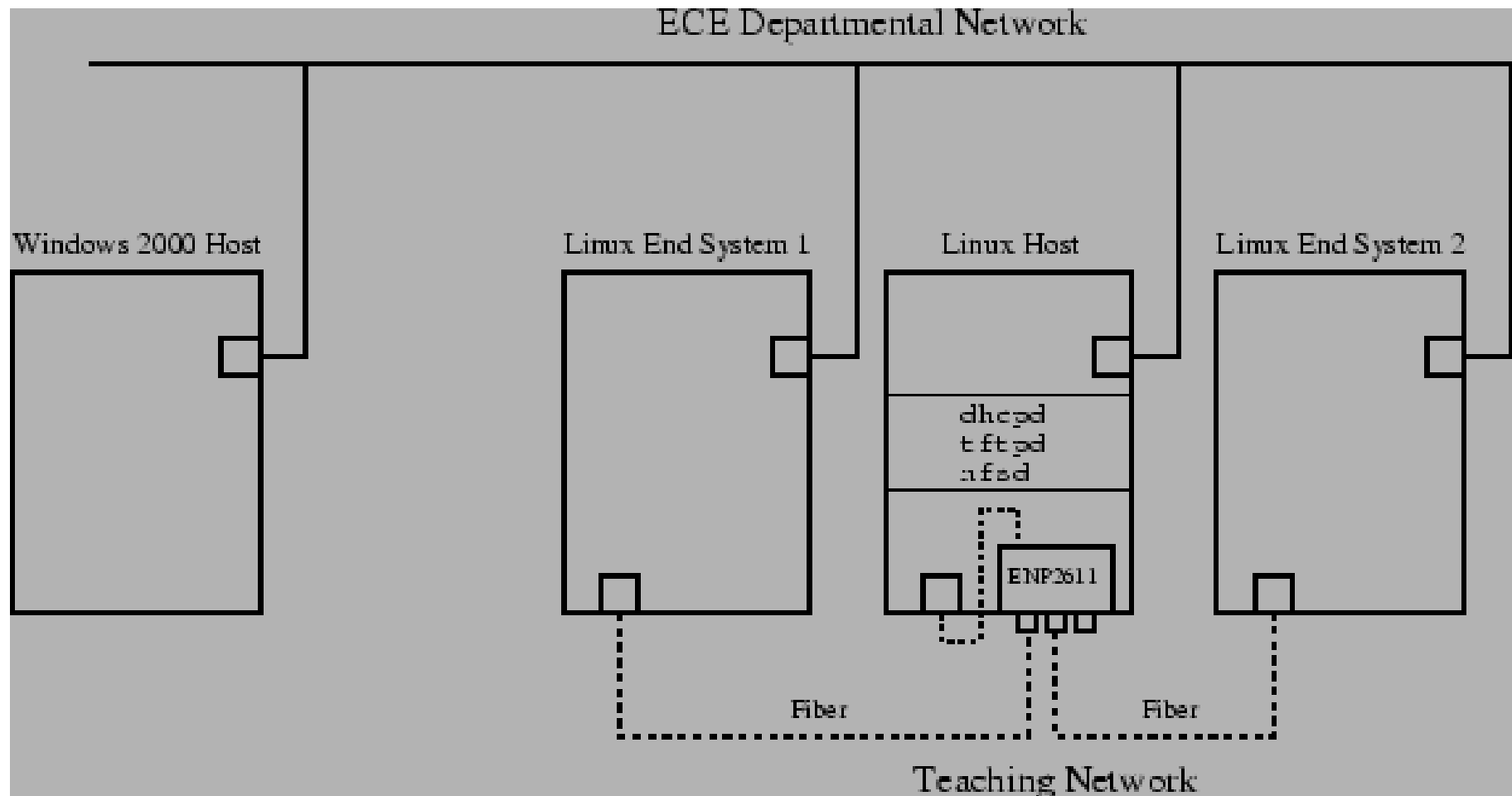


- The dl_source macro polls the scratch ring to retrieve the packet.

Using the Hardware



Network Setup: Physical Layout



Network Setup (Cont.)

- ❑ Linux hosts (the black boxes) connected to the ENP-2611 board to form a teaching Network
- ❑ Radisys ENP-2611 board
 - Hosted by one of the Linux machines
 - Carries the Intel IXP 2400 Network Processor
 - 3 fiber ports to connect to the hosts (see the back of the black box hosting the board)
 - Runs embedded Linux on XScale processor
- ❑ Windows machine connected to the ENP-2611 board via RS-232

Building the Core [1]

- ❑ Download [proj_544fall04_core.tar.gz](#) from the course site to `/opt/ixa_sdk_3.5/src` on the Linux host. Untar the file using the command

```
tar xzvf proj_544fall04_core.tar.gz
```

Note: the code is already copied to the Linux host by TAs so you can simply skip this step if no change is made on the code.

- ❑ Make sure that `/opt/hardhat/previewkit/arm/xscale_be/bin` is in your PATH. (Use `echo $PATH` in Bash Shell)

Build the Core [2]

- ❑ On the Linux host, cd to the directory

```
/opt/ixa_sdk_3.5/src/applications/proj_544  
fall04/ipv4_enp2611
```

- ❑ Issue the command

```
make -f Makefile.linux_kernel
```

Note: to rebuild the code, issue the following command before the above one:

```
make -f Makefile.linux_kernel clean
```

- ❑ cd to the directory

```
/opt/hardhat/previewkit/arm/xscale_be/target/opt/proj_544fall04/ipv4_enp2611
```

- ❑ Issue the command

```
cp linux_kernel/xscale_be/ixp2400/debug/*
```

Linux Host Configuration

- ❑ Runs DHCP daemon
 - Allows auto configuration of the board via crossover cable
- ❑ Provides NFS service to give storage access – board have no onboard disk

Getting things to work!

□ Run the script

`/opt/ixp_scripts/host_startup.sh`

- This will bring up the DHCP daemon, TFTP daemon, and the NFS service
- Setup a HyperTerminal Session (Baud Rate: 57600, Flow Control: None) on the Windows machine
- Reset the ENP-2611 board (press “red” button on the board)
- Login as root through the HyperTerminal session (no password required)

Running ipv4_enp2611 on the hardware

- ❑ Compile the microengine code on the Windows machine (set the preprocessor symbol to `USE_IMPORT_VAR` and not `SIMULATION`)
 - Must use IXA SDK 3.5 for compilation
 - Can use IXA SDK 4.2 for simulation to utilize new features
- ❑ Copy the microengine image `ipv4_enp2611.uof` to the Linux host at

```
/opt/hardhat/previewkit/arm/xscale_be/target  
/opt/proj_544fall04/ipv4_enp2611
```

Note: the `ipv4_enp2611.uof` file is already copied to the Linux host by TAs so you can simply skip this step if no change is made on the code.

Running ipv4_enp2611 on the hardware

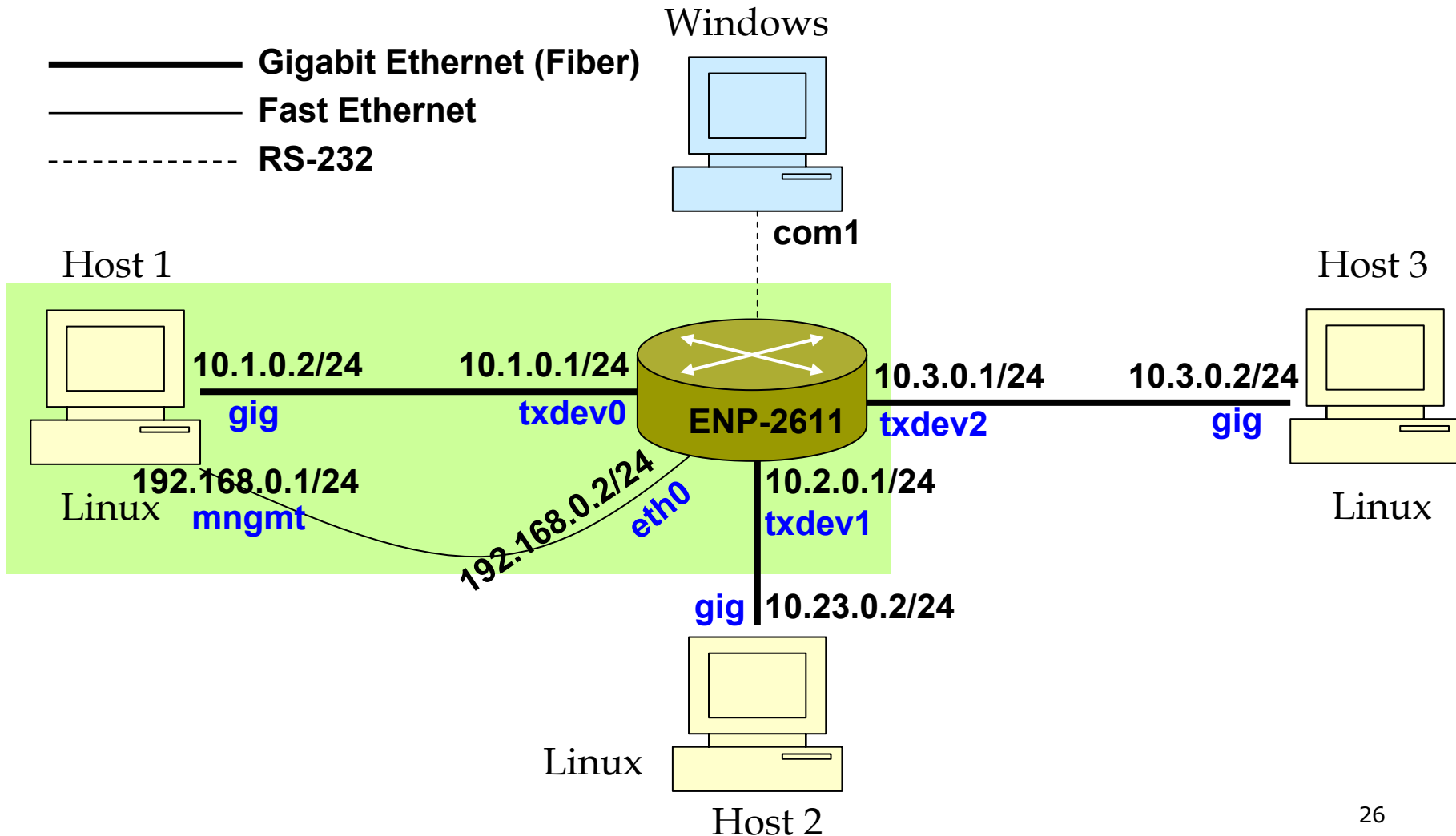
- ❑ On the ENP-2611 board, run the script
`/root/init_script.sh`
- ❑ On each Linux machine, run
`/opt/ixp_scripts/endsys_startup_X.sh` (X=1 if
machine hosting ENP-2611 or X=2 otherwise)

PINGing the hosts

- Now we should be able to PING across the board

e.g. ping 10.x.0.1 (x=1,2,3 are the fiber ports on the ENP-2611) ping 10.x.0.2 (x=1,2,3 are the host machines)

Lab Setup: Logical Layout



Quick Summary

Action (in sequence)	Description
Host: /opt/ixp_scripts/host_startup.sh	Start DHCP/TFTP/NFS services on the host
Host & ENP-2611: Doing DHCP	ENP-2611 gets IP, image filename, and NFS mount directory
Host & ENP-2611: Doing TFTP	ENP-2611 downloads the kernel image. Start running the kernel.
ENP-2611: /root/init_script.sh	Install loadable kernel modules (CCs) Initialize IP address and ARP/route tables on the board
Host: /opt/ixp_scripts/endsys_startup_X.sh	Set IP addresses for the gigabit Eth I/F. Initialize ARP/route tables on the hosts

Where to Obtain the Code Base...

- Microengine (WorkBench):

http://www.cs.cmu.edu/afs/andrew.cmu.edu/course/18/544/dl/proj_544fall04.zip

- Core Code Base (Linux):

http://www.cs.cmu.edu/afs/andrew.cmu.edu/course/18/544/dl/proj_544fall04_core.tar.gz

Questions?



It is recommended to use online instructions posted on the course website for setting up the hardware.