

Cutting Planes

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Convex Optimization 10-725/36-725

Dual Derivatives

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Then for all $\tilde{\mu} \in \Re^r$,

$$\begin{aligned} q(\tilde{\mu}) &= \inf_{x \in X} \left\{ f(x) + \tilde{\mu}' g(x) \right\} \\ &\leq f(x_\mu) + \tilde{\mu}' g(x_\mu) \\ &= f(x_\mu) + \mu' g(x_\mu) + (\tilde{\mu} - \mu)' g(x_\mu) \\ &= q(\mu) + (\tilde{\mu} - \mu)' g(x_\mu). \end{aligned}$$

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- Thus $g(x_\mu)$ is a subgradient of q at μ .

Example: Polyhedral, Non-differentiable Dual

$$q(\mu) = \min_{i \in I} \{ a'_i \mu + b_i \},$$

where I is a finite index set, and $a_i \in \Re^r$ and b_i are given (arises when X is a discrete set, as in integer programming).

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• **Proposition:** Let q be polyhedral as above, and let I_μ be the set of indices attaining the minimum

$$I_\mu = \{ i \in I \mid a_i' \mu + b_i = q(\mu) \}.$$

The set of all subgradients of q at μ is

$$\partial q(\mu) = \left\{ g \mid g = \sum_{i \in I_\mu} \xi_i a_i, \xi_i \geq 0, \sum_{i \in I_\mu} \xi_i = 1 \right\}.$$

Primal Problem

minimize $f(x)$

subject to $x \in X, \quad g_j(x) \leq 0, \quad j = 1, \dots, r,$

assuming $-\infty < f^* < \infty$.

Dual Problem

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- Dual problem: Maximize

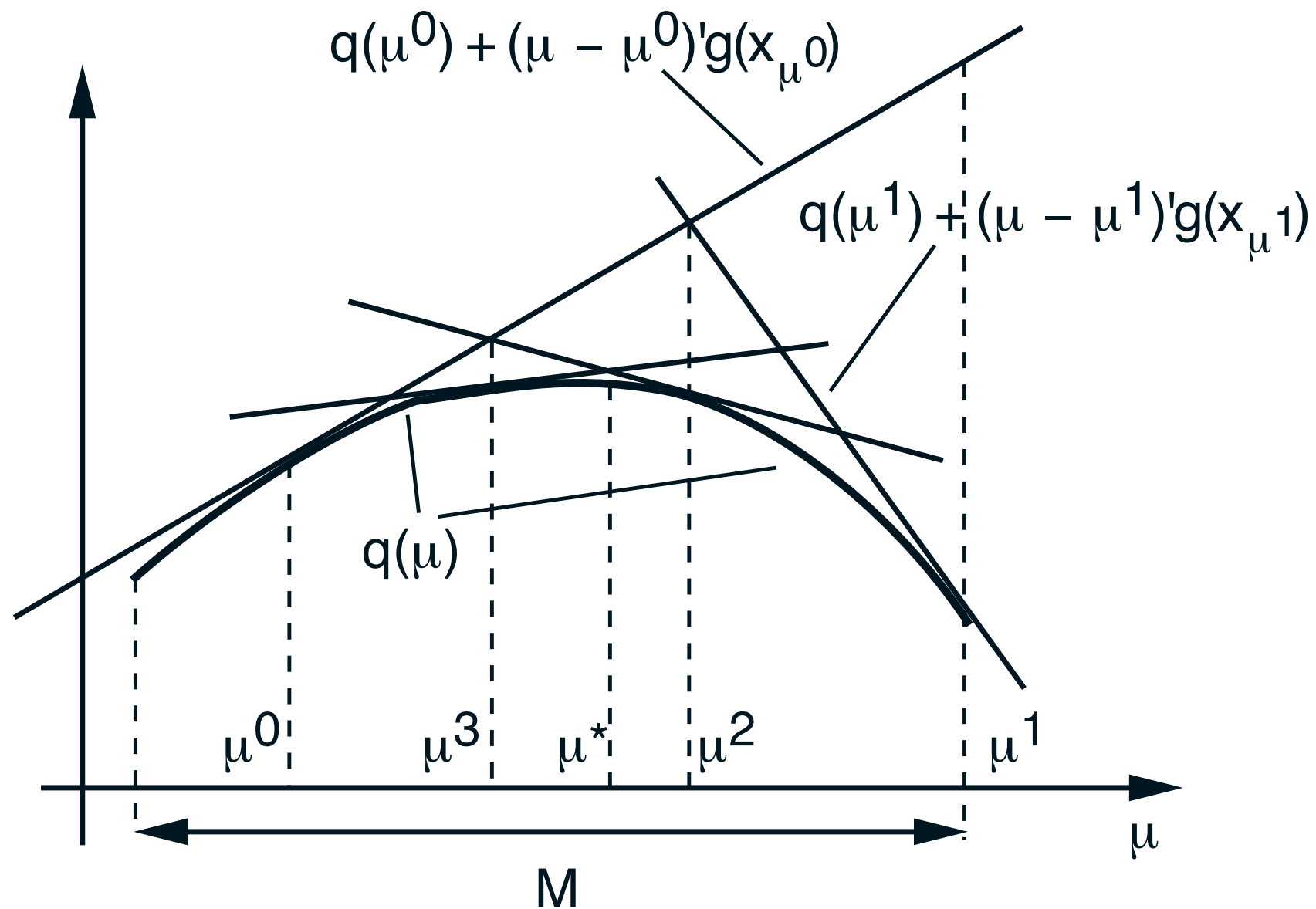
$$q(\mu) = \inf_{x \in X} L(x, \mu) = \inf_{x \in X} \{f(x) + \mu' g(x)\}$$

subject to $\mu \in M = \{\mu \mid \mu \geq 0, q(\mu) > -\infty\}$.

Cutting Plane Algorithms

- Cutting Plane Algorithms: iteratively refine the constraint set, or objective function by means of linear inequalities
- **Constraint Set:** For integer linear programs, iterate: if LP relaxation optimal point is not integral, refine the LP constraint set by a linear inequality separating non-integral point from integer constraint set
- **Objective Function:** Useful for convex, but non-differentiable programs
 - Iteratively approximate objective via piece-wise linear function
 - Popular use: for solving non-differentiable dual programs
 - We will be focusing on this class of cutting plane algorithms

Cutting Plane Method



- Solve piece-wise linear approximation to dual

Piece-wise Linear Approx.

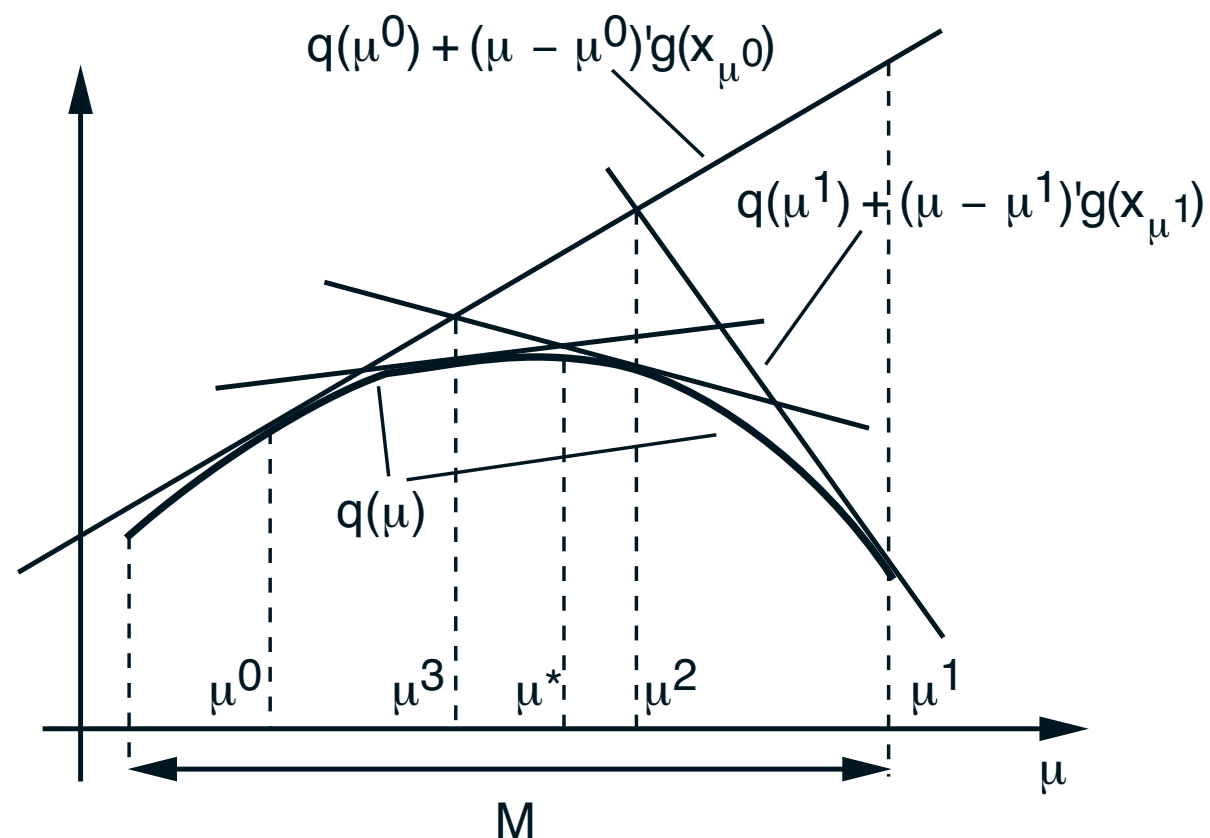
- k th iteration, after μ^i and $g^i = g(x_{\mu^i})$ have been generated for $i = 0, \dots, k - 1$:

$$Q^k(\mu) = \min_{i=0, \dots, k-1} \left\{ q(\mu^i) + (\mu - \mu^i)' g^i \right\}.$$

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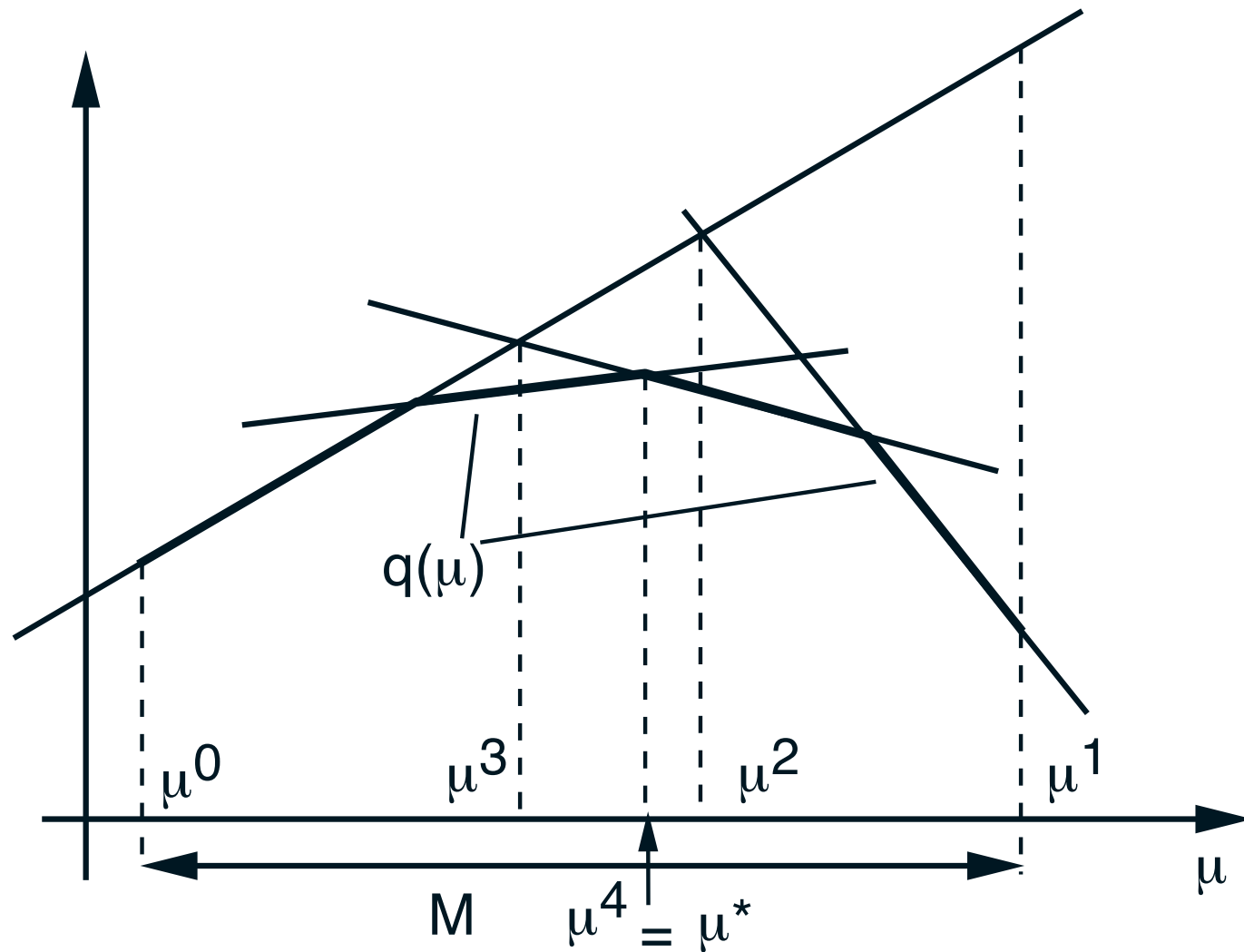


Cutting Plane Method

- k th iteration, after μ^i and $g^i = g(x_{\mu^i})$ have been generated for $i = 0, \dots, k - 1$: Solve

$$\max_{\mu \in M} Q^k(\mu)$$

Polyhedral Case



- Where dual objective is already a piece-wise linear function

Polyhedral Case

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- Then subgradient g^k in the cutting plane method is a vector a_{i^k} for which the minimum is attained.
- Finite termination expected.

Convergence

- **Proposition:** Assume that the max of Q_k over M is attained and that q is real-valued. Then every limit point of a sequence $\{\mu^k\}$ generated by the cutting plane method is a dual optimal solution.

Proof of Convergence

Proof: g^i is a subgradient of q at μ^i , so

$$q(\mu^i) + (\mu - \mu^i)' g^i \geq q(\mu), \quad \forall \mu \in M,$$
$$Q^k(\mu^k) \geq Q^k(\mu) \geq q(\mu), \quad \forall \mu \in M. \quad (1)$$

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- Suppose $\{\mu^k\}_K$ converges to $\bar{\mu}$. Then, $\bar{\mu} \in M$, and by Eq. (1) and continuity of Q^k and q (real-valued assumption), $Q^k(\bar{\mu}) \geq q(\bar{\mu})$. Using this and Eq. (1), we obtain for all k and $i < k$,

$$q(\mu^i) + (\mu^k - \mu^i)' g^i \geq Q^k(\mu^k) \geq Q^k(\bar{\mu}) \geq q(\bar{\mu}).$$

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$$\lim_{k \rightarrow \infty, k \in K} Q^k(\mu^k) = q(\bar{\mu}).$$

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Combining with (1), $q(\bar{\mu}) = \max_{\mu \in M} q(\mu)$.

Separable Problem

$$\text{minimize } \sum_{j=1}^J f_j(x_j)$$

$$\text{subject to } x_j \in X_j, \quad j = 1, \dots, J, \quad \sum_{j=1}^J A_j x_j = b.$$

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- Solving for its dual:

$$\begin{aligned} q(\lambda) &= \sum_{j=1}^J \min_{x_j \in X_j} \{ f_j(x_j) + \lambda' A_j x_j \} - \lambda' b \\ &= \sum_{j=1}^J \{ f_j(x_j(\lambda)) + \lambda' A_j x_j(\lambda) \} - \lambda' b \end{aligned}$$

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$$\text{subgradient at } \lambda: \quad g_\lambda = \sum_{j=1}^J A_j x_j(\lambda) - b.$$

Dantzig-Wolfe Decomposition

- D-W decomposition method is just the cutting plane applied to the dual problem $\max_{\lambda} q(\lambda)$.
- At the k th iteration, we solve the “approximate dual”

$$\lambda^k = \arg \max_{\lambda \in \mathbb{R}^r} Q^k(\lambda) \equiv \min_{i=0, \dots, k-1} \left\{ q(\lambda^i) + (\lambda - \lambda^i)' g^i \right\}.$$

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The dual of this (called *master problem*) is

$$\begin{aligned} &\text{minimize} && \sum_{i=0}^{k-1} \xi^i (q(\lambda^i) - \lambda^{i'} g^i) \\ &\text{subject to} && \sum_{i=0}^{k-1} \xi^i = 1, && \sum_{i=0}^{k-1} \xi^i g^i = 0, \\ &&& \xi^i \geq 0, \quad i = 0, \dots, k-1, \end{aligned}$$

- The master problem is written as

$$\begin{aligned}
 &\text{minimize} && \sum_{j=1}^J \left(\sum_{i=0}^{k-1} \xi^i f_j(x_j(\lambda^i)) \right) \\
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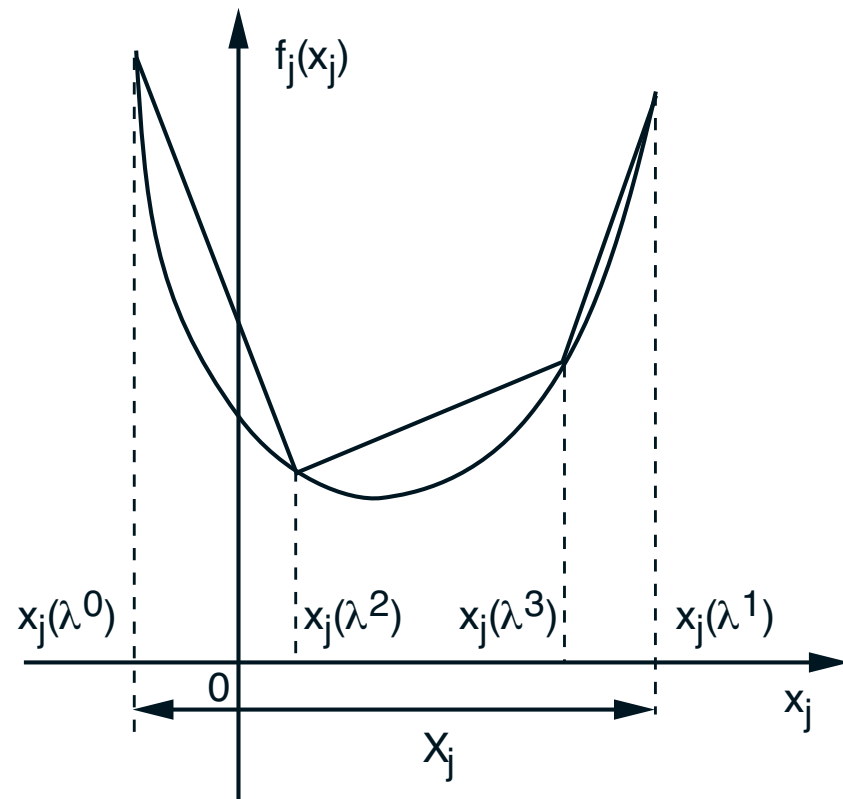
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- Vectors x_j are expressed as

$$\sum_{i=0}^{k-1} \xi^i x_j(\lambda^i)$$

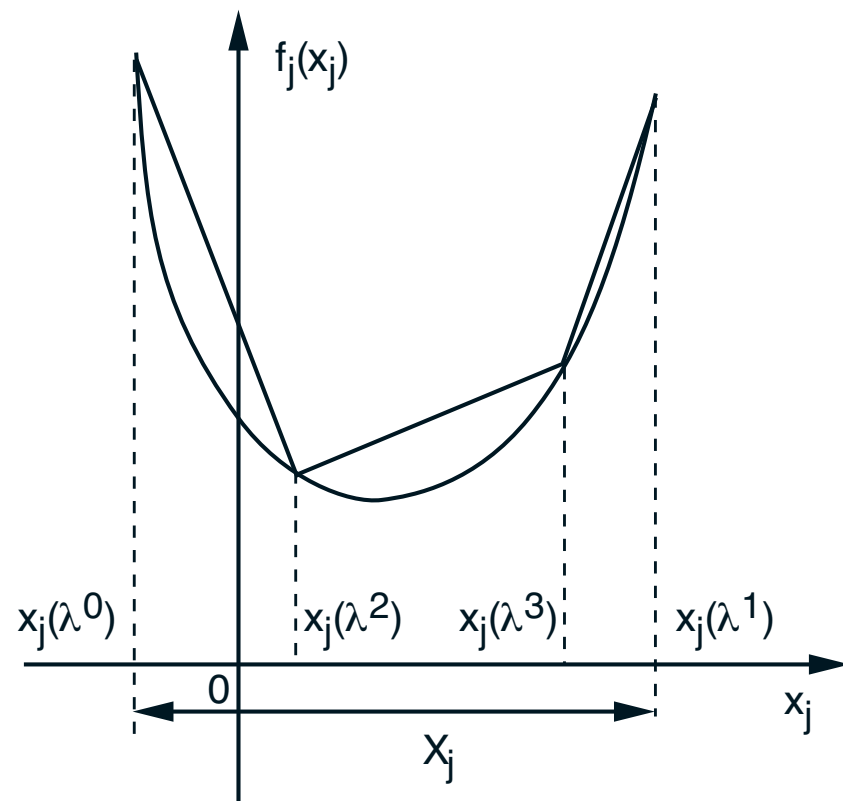
Dantzig-Wolfe Decomposition: Geometric Intuition

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- This is a “dual” operation to the one involved in the cutting plane approximation, which can be viewed as *outer linearization*.