



# Sets, Data Types, and Functions

Matt Gormley  
Lecture 2  
August 29, 2018

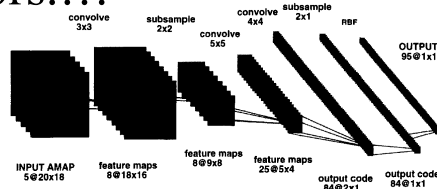
# Computer Vision

Correction...

## 4. Learning to recognize images

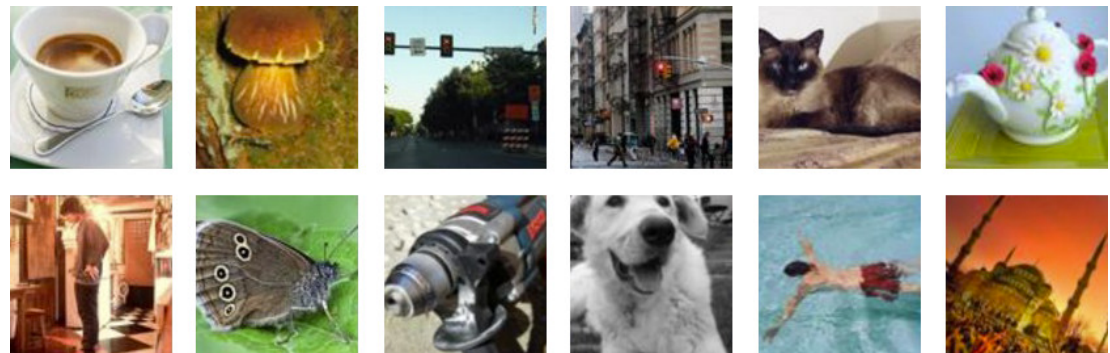
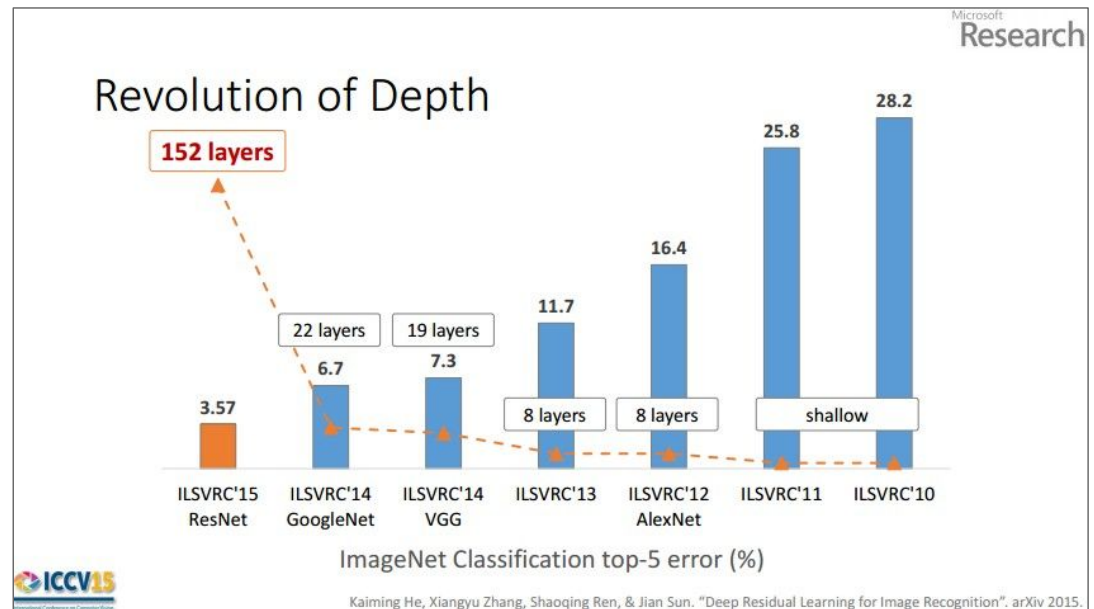
THEN

“...The recognizer is a convolution network that can be spatially replicated. From the network output, a hidden Markov model produces word scores. The entire system is globally trained to minimize word-level errors....”



(LeCun et al., 1995)

NOW



# **SYLLABUS HIGHLIGHTS**

# Syllabus Highlights

The syllabus is located on the course webpage:

<http://www.cs.cmu.edu/~mgormley/courses/606-607-f18>

The **course policies** are **required** reading.

# 606/607 Syllabus Highlights

- **Grading:** 55% homework, 10% in-class quizzes, 30% final exam, 5% participation
- **Final Exam:**
  - 606: Mini-I final exam week, date TBD
  - 607: Mini-II final exam week, date TBD
- **In-Class Quizzes:** always announced ahead of time
- **Homework:** 4 assignments with written / programming portions
  - 2 grace days for the unexpected
  - Late submissions: 80% day 1, 60% day 2, 40% day 3, 20% day 4
  - No submissions accepted after 4 days w/o extension
  - Extension requests: see syllabus
- **Recitations:** Fridays, same time/place as lecture (optional, interactive sessions)
- **Readings:** required, online, recommended for after lecture
- **Technologies:** Piazza (discussion), Gradescope (homework), Canvas (gradebook only)
- **Academic Integrity:**
  - Collaboration encouraged, but must be documented
  - Solutions must always be written independently
  - No re-use of found code / past assignments
  - Severe penalties (i.e. failure)
- **Office Hours:** posted on Google Calendar on “People” page

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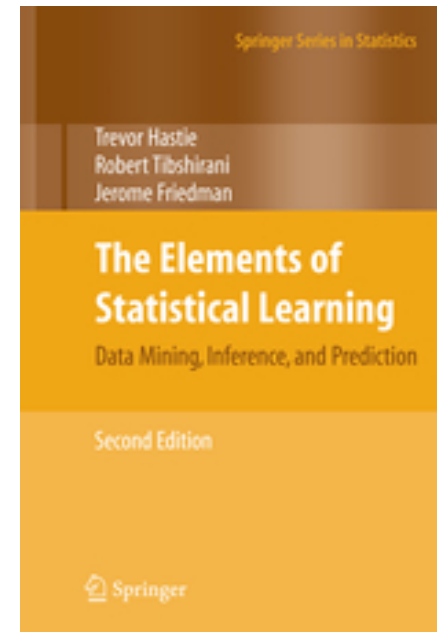
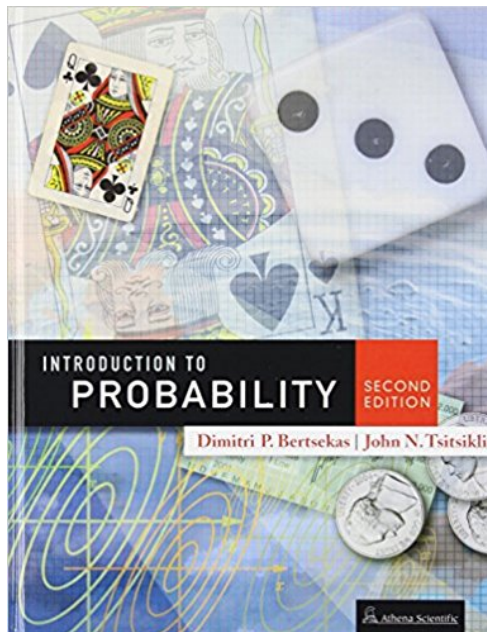
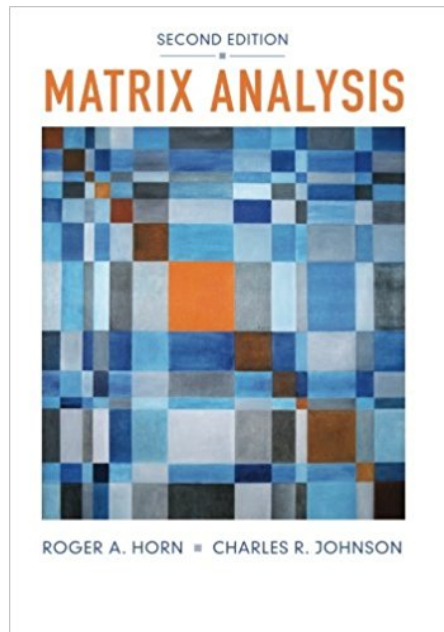
# Lectures

- You should ask lots of questions
  - Interrupting (by raising a hand) to ask your question is strongly encouraged
  - Asking questions later on Piazza is also great
- When I ask a question...
  - I want you to answer
  - Even if you don't answer, think it through as though I'm about to call on you
- Interaction improves learning (both in-class and at my office hours)



# Textbooks

These are optional, but highly recommended as an alternate presentation of the material



# Expected Background

## 10-606 (Math Background 4 ML)

You should be familiar with some of the following...

- Calculus:
  - can take scalar derivatives
  - can solve scalar integrals
- Linear Algebra:
  - know basic vector operations
  - seen matrix multiplication
- Probability:
  - seen the basics: conditioning, Bayes Rule, etc.
- Programming:
  - know some Python

**OR**

have sufficient programming background to pick up the basics of Python

But we'll offer practice to make sure you can catch up on your weaker areas

## 10-607 (CS Background 4 ML)

You should...

- be comfortable with all the topics listed for 10-606
- ideally, have the mathematical maturity of someone who completed 10-606 **because it will aide in understanding the motivating examples from machine learning**

That said, the content of 10-607 is designed stand alone

# Q&A

**Q:** Is this course right for me?

**A:**

- If you're a Master's or PhD and you lack some of the prerequisite material for 10-601/701, this is definitely the right course for you!
- If you're a Master's or PhD and you studied the prerequisite material for 10-601/701... but it was a long time ago, this is certainly the right course for you.
- If you're an undergrad, I would recommend the usual prereq sequence required for 10-601/701.
- For ugrad/MS/PhD: If you tried taken an Intro ML course here and felt a bit lost in all the math/CS, this is a great place to start.

**Q:** What calculus textbook would you recommend?

**A:** Good question... I'm still working on that one.

# Q&A

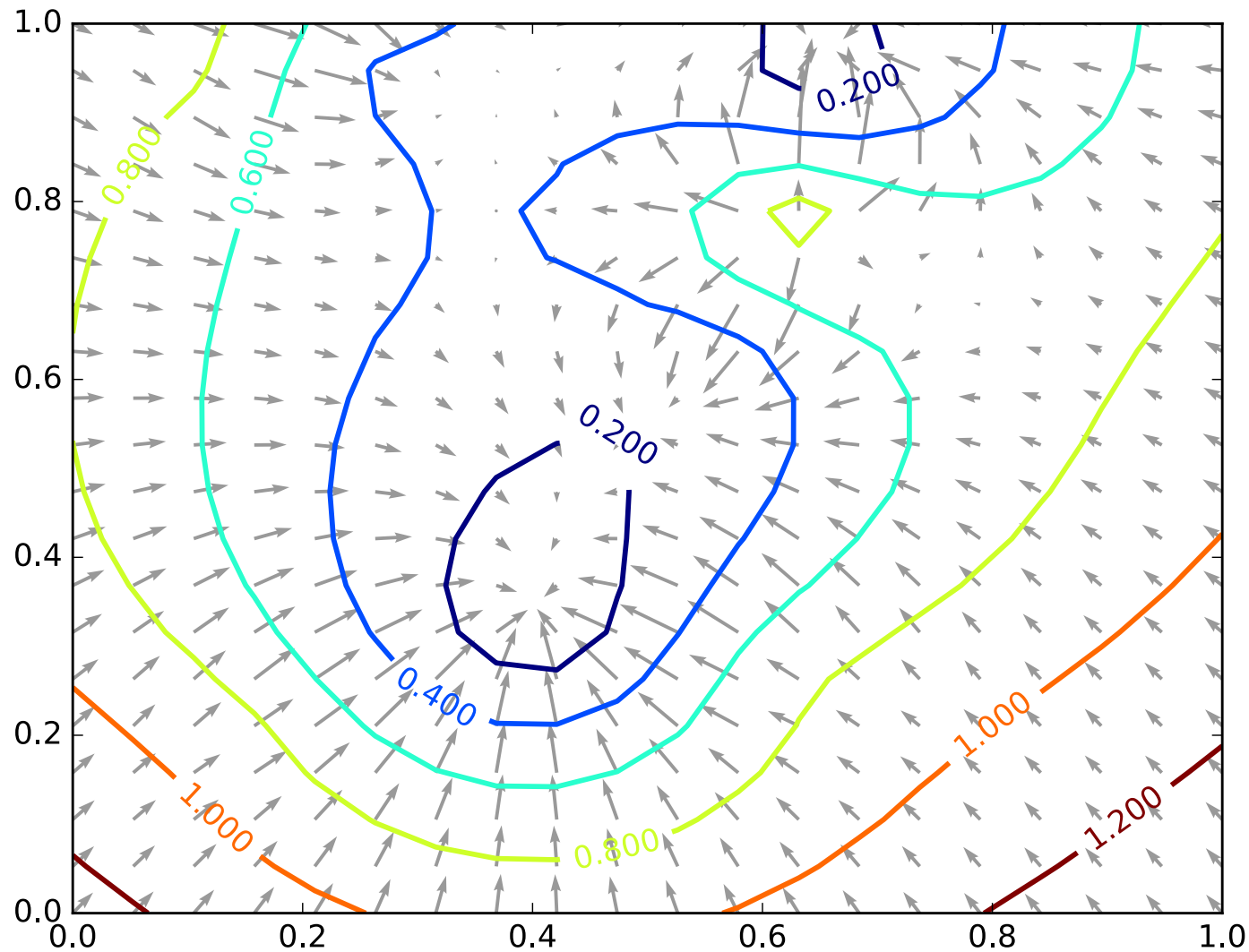
**Q:** What do I do if I'm feeling a bit lost in the math and CS in 10-606/607?

**A:** Let me know ASAP! (Do so in office hours, Piazza note, the middle of class, etc.) Our goal is to provide you with a learning environment in which you thrive. We'll certainly make adjustments if we need to.

# **MOTIVATION: SETS & TYPES**

# Sets, Types, and Functions show up **everywhere** in Machine Learning

# (Negative) Gradients

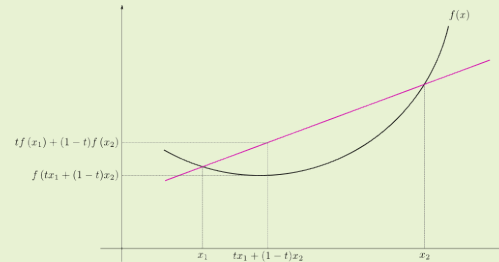


These are the **negative** gradients that Gradient **D**escent would follow.

# Convexity

Suppose we wish to define convexity of a function...

We could draw a picture.



...but that's a bit informal.

So instead, we could offer a mathematical definition.

Function  $f : \mathbb{R}^M \rightarrow \mathbb{R}$  is **convex**  
if  $\forall \mathbf{x}_1 \in \mathbb{R}^M, \mathbf{x}_2 \in \mathbb{R}^M, 0 \leq t \leq 1$ :

$$f(t\mathbf{x}_1 + (1-t)\mathbf{x}_2) \leq tf(\mathbf{x}_1) + (1-t)f(\mathbf{x}_2)$$

...but even this definition requires some carefully defined objects (the vectors, a function, the set of reals, the set of real-valued vectors of length  $M$ , etc.)




# Data for ML

What is the object we talk about more in Machine Learning than anything else?

Our data!



$$\mathcal{D} = \{(\mathbf{x}^{(n)}, y^{(n)})\}_{n=1}^N$$



The data consists of a set of tuples

$$\mathcal{D} = \{(\mathbf{x}^{(1)}, y^{(1)}), (\mathbf{x}^{(2)}, y^{(2)}), \dots, (\mathbf{x}^{(N)}, y^{(N)})\}$$

# The importance of sets...

- Gaussian Discriminant Analysis and Gaussian Mixture Models are almost identical
- There's really only one practical difference
- Can you spot it?

See next two slides...

# Gaussian Discriminant Analysis

**Data:**  $\mathcal{D} = \{(\mathbf{x}^{(i)}, z^{(i)})\}_{i=1}^N$  where  $\mathbf{x}^{(i)} \in \mathbb{R}^M$  and  $z^{(i)} \in \{1, \dots, K\}$

**Generative Story:**  $z \sim \text{Categorical}(\phi)$   
 $\mathbf{x} \sim \text{Gaussian}(\boldsymbol{\mu}_z, \boldsymbol{\Sigma}_z)$

**Model:** Joint:  $p(\mathbf{x}, z; \phi, \boldsymbol{\mu}, \boldsymbol{\Sigma}) = p(\mathbf{x}|z; \boldsymbol{\mu}, \boldsymbol{\Sigma})p(z; \phi)$

**Log-likelihood:**

$$\begin{aligned}\ell(\phi, \boldsymbol{\mu}, \boldsymbol{\Sigma}) &= \log \prod_{i=1}^N p(\mathbf{x}^{(i)}, z^{(i)}; \phi, \boldsymbol{\mu}, \boldsymbol{\Sigma}) \\ &= \sum_{i=1}^N \log p(\mathbf{x}^{(i)} | z^{(i)}; \boldsymbol{\mu}, \boldsymbol{\Sigma}) + \log p(z^{(i)}; \phi)\end{aligned}$$

# Gaussian Mixture-Model

**Data:**  $\mathcal{D} = \{\mathbf{x}^{(i)}\}_{i=1}^N$  where  $\mathbf{x}^{(i)} \in \mathbb{R}^M$

**Generative Story:**  $z \sim \text{Categorical}(\phi)$   
 $\mathbf{x} \sim \text{Gaussian}(\boldsymbol{\mu}_z, \boldsymbol{\Sigma}_z)$

**Model:** Joint:  $p(\mathbf{x}, z; \phi, \boldsymbol{\mu}, \boldsymbol{\Sigma}) = p(\mathbf{x}|z; \boldsymbol{\mu}, \boldsymbol{\Sigma})p(z; \phi)$   
Marginal:  $p(\mathbf{x}; \phi, \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \sum_{z=1}^K p(\mathbf{x}|z; \boldsymbol{\mu}, \boldsymbol{\Sigma})p(z; \phi)$

**(Marginal) Log-likelihood:**

$$\begin{aligned}\ell(\phi, \boldsymbol{\mu}, \boldsymbol{\Sigma}) &= \log \prod_{i=1}^N p(\mathbf{x}^{(i)}; \phi, \boldsymbol{\mu}, \boldsymbol{\Sigma}) \\ &= \sum_{i=1}^N \log \sum_{z=1}^K p(\mathbf{x}^{(i)}|z; \boldsymbol{\mu}, \boldsymbol{\Sigma})p(z; \phi)\end{aligned}$$

# Notation for ML

Machine Learning is notorious for requiring lots of notation... and not always being terribly consistent about it!

## 10601 Notation Crib Sheet

Matthew R. Gormley

February 26, 2018

### 1 Scalars, Vectors, Matrices

**Scalars** are either lowercase letters  $x, y, z, \alpha, \beta, \gamma$  or uppercase Latin letters  $N, M, T$ . The latter are typically used to indicate a **count** (e.g. number of examples, features, timesteps) and are often accompanied by a corresponding **index**  $n, m, t$  (e.g. current example, feature, timestep). **Vectors** are bold lowercase letters  $\mathbf{x} = [x_1, x_2, \dots, x_M]^T$  and are typically assumed to be column vectors—hence the transposed row vector in this example. When handwritten, a vector is indicated by an over-arrow  $\vec{x} = [x_1, x_2, \dots, x_M]^T$ . **Matrices** are bold uppercase letters:

$$\mathbf{U} = \begin{bmatrix} U_{11} & U_{12} & \dots & U_{1m} \\ U_{21} & U_{22} & & \\ \vdots & & \ddots & \\ U_{n1} & & & U_{nm} \end{bmatrix}$$

As in the examples above, subscripts are used as **indices** into structured objects such as vectors or matrices.

### 2 Sets

**Sets** are represented by calligraphic uppercase letters  $\mathcal{X}, \mathcal{Y}, \mathcal{D}$ . We often index a set by **labels** in parenthesized superscripts  $\mathcal{S} = \{s^{(1)}, s^{(2)}, \dots, s^{(S)}\}$ , where  $S = |\mathcal{S}|$ . A shorthand for this equivalently defines  $\mathcal{S} = \{s^{(i)}\}_{i=1}^S$ . This shorthand is convenient when defining a set of **training examples**:  $\mathcal{D} = \{(\mathbf{x}^{(1)}, y^{(1)}), (\mathbf{x}^{(2)}, y^{(2)}), \dots, (\mathbf{x}^{(N)}, y^{(N)})\}$  is equivalent to  $\mathcal{D} = \{(\mathbf{x}^{(i)}, y^{(i)})\}_{i=1}^N$ .

### 3 Random Variables

**Random variables** are also uppercase Latin letters  $X, Y, Z$ , but their use is typically apparent from context. When a random variable  $X_i$  and a scalar  $x_i$  are upper/lower-case versions of each other, we typically mean that the scalar is a **value** taken by the random variable.

When possible, we try to reserve Greek letters for **parameters**  $\theta, \phi$  or **hyperparameters**  $\alpha, \beta, \gamma$ .

For a random variable  $X$ , we write  $X \sim \text{Gaussian}(\mu, \sigma^2)$  to indicate that  $X$  follows a 1D Gaussian distribution with mean  $\mu$  and variance  $\sigma^2$ . We write  $\mathbf{x} \sim \text{Gaussian}(\mu, \sigma^2)$  to say that  $\mathbf{x}$  is a value sampled from the same distribution.

1

A **conditional probability distribution** over random variable  $X$  given  $Y$  and  $Z$  is written  $P(X|Y, Z)$  and its **probability mass function** (pmf) or **probability density function** (pdf) is  $p(x|y, z)$ . If the probability distribution has parameters  $\alpha, \beta$ , we can write its pmf/pdf in at least three equivalent ways: A statistician might prefer  $p(x|y, z; \alpha, \beta)$  to clearly demarcate the parameters. A graphical models expert prefer  $p(x|y, z, \alpha, \beta)$  since said parameters are really just additional random variables. A typographer might prefer to save ink by writing  $p_{\alpha, \beta}(x|y, z)$ . To refer to this pmf/pdf as a function over possible values of  $\alpha$  we would write it as  $p_{\alpha, \beta}(y, z)$ . Using our  $\sim$  notation from above, we could then write that  $X$  follows the distribution  $X \sim p_{\alpha, \beta}(y, z)$  and  $\mathbf{x}$  is a sample from it  $\mathbf{x} \sim p_{\alpha, \beta}(y, z)$ .

The **expectation** of a random variable  $X$  is  $\mathbb{E}[X]$ . When dealing with random quantities for which the generating distribution might not be clear, we can denote it in the expectation. For example,  $\mathbb{E}_{\mathbf{x} \sim p_{\alpha, \beta}(y, z)}[f(\mathbf{x}, y, z)]$  is the expectation of  $f(\mathbf{x}, y, z)$  for some function  $f$  where  $\mathbf{x}$  is sampled from the distribution  $p_{\alpha, \beta}(y, z)$  and  $y$  and  $z$  are constant for the evaluation of this expectation.

### 4 Functions and Derivatives

Suppose we have a function  $f(x)$ . We write its partial derivative with respect to  $x$  as  $\frac{\partial f(x)}{\partial x}$  or  $\frac{df(x)}{dx}$ . We also denote its first derivative as  $f'(x)$ , its second derivative as  $f''(x)$ , and so on. For a multivariate function  $f(\mathbf{x}) = f(x_1, \dots, x_M)$ , we write its gradient with respect to  $\mathbf{x}$  as  $\nabla_{\mathbf{x}} f(\mathbf{x})$  and frequently omit the subscript, i.e.  $\nabla f(\mathbf{x})$ , when it is clear from context—it might not be for a gradient such as  $\nabla_{\mathbf{x}} g(\mathbf{x}, \mathbf{y})$ .

### 5 Common Conventions

The table below lists additional common conventions we follow:

Notation	Description
$N$	number of training examples
$M$	number of feature types
$K$	number of classes
$n$ or $i$	current training example
$m$	current feature type
$k$	current class
$\mathbb{Z}$	set of integers
$\mathbb{R}$	set of reals
$\mathbb{R}^M$	set of real-valued vectors of length $M$
$\{0, 1\}^M$	set of binary vectors of length $M$
$\mathbf{x}$	feature vector (input) where $\mathbf{x} = [x_1, x_2, \dots, x_M]^T$ ; typically $\mathbf{x} \in \mathbb{R}^M$ or $\mathbf{x} \in \{0, 1\}^M$

<sup>1</sup>Note that a more careful notation system would always use  $\frac{\partial f(\mathbf{x})}{\partial x_i}$  for partial derivatives, since  $\frac{df(\mathbf{x})}{d\mathbf{x}}$  is typically reserved for total derivatives. However, only partial derivatives make as appropriate sense.

2

$y$  label / regressand (output); for classification  $y \in \{1, 2, \dots, K\}$ ; for binary classification  $y \in \{0, 1\}$  or  $y \in \{+1, -1\}$ ; for regression,  $y \in \mathbb{R}$

$\mathbf{X}$  input space, i.e.  $\mathbf{x} \in \mathcal{X}$

$\mathcal{Y}$  output space, i.e.  $y \in \mathcal{Y}$

$\mathbf{x}^{(i)}$  the  $i$ th feature vector in the training data

$y^{(i)}$  the  $i$ th true output in the training data

$x_m^{(i)}$  the  $m$ th feature of the  $i$ th feature vector

$(\mathbf{x}^{(i)}, y^{(i)})$  the  $i$ th training example (feature vector, true output)

$\mathcal{D}$  set of training examples; for supervised learning  $\mathcal{D} = \{(\mathbf{x}^{(i)}, y^{(i)})\}_{i=1}^N$ ; for unsupervised learning  $\mathcal{D} = \{\mathbf{x}^{(i)}\}_{i=1}^N$

$\mathbf{X}$  design matrix; the  $i$ th row contains the features of the  $i$ th training example  $\mathbf{x}^{(i)}$ ; i.e. the  $i$ th row contains  $x_1^{(i)}, \dots, x_M^{(i)}$

$X_1, \dots, X_M$  random variables corresponding to feature vector  $\mathbf{x}$  (note: we generally avoid defining a vector-valued random variable  $\mathbf{X} = [X_1, X_2, \dots, X_M]^T$  so that  $\mathbf{X}$  is not overloaded with the design matrix)

$Y$  random variable corresponding to predicted class  $y$

$P(Y = y|\mathbf{X} = \mathbf{x})$  probability of random variable  $Y$  taking value  $y$  given that random variable  $\mathbf{X}$  takes value  $\mathbf{x}$

$p(y|\mathbf{x})$  shorthand for  $P(Y = y|\mathbf{X} = \mathbf{x})$

$\theta$  model parameters

$\mathbf{w}$  model parameters (weights of linear model)

$b$  model parameter (bias term of linear model)

$\ell(\theta)$  log-likelihood of the data, depending on context, this might alternatively be the log-conditional likelihood or log-marginal likelihood

$J(\theta)$  objective function

$J^{(i)}(\theta)$  example  $i$ 's contribution to the objective function; typically  $J(\theta) = \frac{1}{N} \sum_{i=1}^N J^{(i)}(\theta)$

$\nabla J(\theta)$  gradient of the objective function with respect to model parameters  $\theta$

$\nabla J^{(i)}(\theta)$  gradient of  $J^{(i)}(\theta)$  with respect to model parameters  $\theta$

$\theta^T \mathbf{x}$  or  $\mathbf{x}^T \theta$  or  $\theta \cdot \mathbf{x}$  stepsize in numerical optimization

$\theta^T \mathbf{x}$  or  $\mathbf{x}^T \theta$  or  $\theta \cdot \mathbf{x}$  dot product of model parameters and features

$h_{\theta}(\mathbf{x})$  decision function / decision rule / hypothesis

$\mathcal{H}$  hypothesis space; we say that  $h \in \mathcal{H}$

$\hat{y}$  prediction of a decision function, e.g.  $\hat{y} = h_{\theta}(\mathbf{x})$

$\hat{\theta}$  model parameters that result from learning

$\ell(y, y)$  loss function

$p^*(\mathbf{x}, y)$  unknown data generating distribution of labeled examples

$p^*(\mathbf{x})$  unknown data generating distribution of feature vectors only

$c^*(\mathbf{x})$  true unknown hypothesis (i.e. oracle labeling function), e.g.  $y = c^*(\mathbf{x})$

$\mathbf{z}$  Values of unknown variables (latent)

$Z_1, \dots, Z_C$  random variables (latent) corresponding to  $\mathbf{z}$

3

$\mathbf{y}_1, \dots, \mathbf{y}_C$  predicted structure (output) for structured prediction

$Y_1, \dots, Y_C$  random variables corresponding to predicted structure  $\mathbf{y}$

$\mathbb{I}(a = b)$  indicator function which returns 1 when  $a$  equals  $b$  and 0 otherwise—other notations are also possible  $\mathbb{I}(a = b) = \mathbb{I}(a = b) = \mathbb{I}_{a=b}$

4

# **PRELIMINARIES: SETS AND TYPES**

# Sets

## *Chalkboard*

- Definitions: Set, element of, equality, subset
- Example: Sets of sets
- Set builder notation
- Python list/set comprehensions
- Exercise: Set builder notation
- Definitions: Union, intersection, difference, complement
- Exercise: Set complement
- Tuples and set product
- Exercise: Set product

# Data Types and Functions

## *Chalkboard*

- Data types, structs, unions
- Tagged unions
- Exercise: Tagged unions
- Functions
- Anonymous functions
- Exercises: Functions