## 10-606 Mathematical Foundations for Machine Learning

Machine Learning Department
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## Deriving Principal Component Analysis (PCA)

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Lecture 11
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## Reminders

- Quiz 1: Linear Algebra (today)
- Homework 3: Matrix Calculus + Probability
- Out: Wed, Oct. 3
- Due: Wed, Oct. 10 at 11:59pm
- Quiz 2: Matrix Calculus + Probability
- In-class, Wed, Oct. 10


## $Q \& A$

## DIMENSIONALITY REDUCTION

## PCA Outline

- Dimensionality Reduction
- High-dimensional data
- Learning (low dimensional) representations
- Principal Component Analysis (PCA)
- Examples:2D and 3D
- Data for PCA
- PCA Definition
- Objective functions for PCA
- PCA, Eigenvectors, and Eigenvalues
- Algorithms for finding Eigenvectors / Eigenvalues
- PCA Examples
- Face Recognition
- Image Compression


## High Dimension Data

## Examples of high dimensional data:

- High resolution images (millions of pixels)



## High Dimension Data

## Examples of high dimensional data:

- Multilingual News Stories
(vocabulary of hundreds of thousands of words)



## High Dimension Data

## Examples of high dimensional data:

- Brain Imaging Data (100s of MBs per scan)



## High Dimension Data

## Examples of high dimensional data:

- Customer Purchase Data


Recommended for you, Matt



Buy if Again in Baby Products


Engineering Books
astives

## Learning Representations

PCA, Kernel PCA, ICA: Powerful unsupervised learning techniques for extracting hidden (potentially lower dimensional) structure from high dimensional datasets.

Useful for:

- Visualization
- More efficient use of resources (e.g., time, memory, communication)
- Statistical: fewer dimensions $\rightarrow$ better generalization
- Noise removal (improving data quality)
- Further processing by machine learning algorithms


## PRINCIPAL COMPONENT ANALYSIS (PCA)

## PCA Outline

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## Principal Component Analysis (PCA)



In case where data lies on or near a low d-dimensional linear subspace, axes of this subspace are an effective representation of the data.

Identifying the axes is known as Principal Components Analysis, and can be obtained by using classic matrix computation tools (Eigen or Singular Value Decomposition).

## 2D Gaussian dataset



Slide from Barnabas Poczos

## $1^{\text {st }}$ PCA axis



## $2^{\text {nd }}$ PCA axis



Slide from Barnabas Poczos

## Principal Component Analysis (PCA)

Whiteboard

- Data for PCA
- PCA Definition
- Objective functions for PCA

$$
\begin{array}{ll} 
& \text { Data for PCA } \\
\mathcal{D}=\left\{\mathbf{x}^{(i)}\right\}_{i=1}^{N} & \mathbf{X}=\left[\begin{array}{c}
\left(\mathbf{x}^{(1)}\right)^{T} \\
\left(\mathbf{x}^{(2)}\right)^{T} \\
\vdots \\
\left(\mathbf{x}^{(N)}\right)^{T}
\end{array}\right]
\end{array}
$$

We assume the data is centered, and that each axis has sample variance equal to one.

$$
\begin{aligned}
\mu & =\frac{1}{N} \sum_{i=1}^{N} \mathbf{x}^{(i)}=\mathbf{0} \\
\sigma_{j}^{2} & =\frac{1}{N} \sum_{i=1}^{N}\left(x_{j}^{(i)}\right)^{2}=1
\end{aligned}
$$

## Sample Covariance Matrix

The sample covariance matrix is given by:

$$
\Sigma_{j k}=\frac{1}{N} \sum_{i=1}^{N}\left(x_{j}^{(i)}-\mu_{j}\right)\left(x_{k}^{(i)}-\mu_{k}\right)
$$

Since the data matrix is centered, we rewrite as:

$$
\boldsymbol{\Sigma}=\frac{1}{N} \mathbf{X}^{T} \mathbf{X}
$$

## Maximizing the Variance

Quiz: Consider the two projections below

1. Which maximizes the variance?
2. Which minimizes the reconstruction error?

Option A


Option B


## PCA

## Equivalence of Maximizing Variance and Minimizing Reconstruction Error

Claim: Minimizing the reconstruction error is equivalent to maximizing the variance.
Proof: First, note that:

$$
\begin{equation*}
\left\|\mathbf{x}^{(i)}-\left(\mathbf{v}^{T} \mathbf{x}^{(i)}\right) \mathbf{v}\right\|^{2}=\left\|\mathbf{x}^{(i)}\right\|^{2}-\left(\mathbf{v}^{T} \mathbf{x}^{(i)}\right)^{2} \tag{1}
\end{equation*}
$$

since $\mathbf{v}^{T} \mathbf{v}=\|\mathbf{v}\|^{2}=1$.
Substituting into the minimization problem, and removing the extraneous terms, we obtain the maximization problem.

$$
\begin{align*}
\mathbf{v}^{*} & =\underset{\mathbf{v}:\|\mathbf{v}\|^{2}=1}{\operatorname{argmin}} \frac{1}{N} \sum_{i=1}^{N}\left\|\mathbf{x}^{(i)}-\left(\mathbf{v}^{T} \mathbf{x}^{(i)}\right) \mathbf{v}\right\|^{2}  \tag{2}\\
& =\underset{\mathbf{v}:\|\mathbf{v}\|^{2}=1}{\operatorname{argmin}} \frac{1}{N} \sum_{i=1}^{N}\left\|\mathbf{x}^{(i)}\right\|^{2}-\left(\mathbf{v}^{T} \mathbf{x}^{(i)}\right)^{2}  \tag{3}\\
& =\underset{\mathbf{v}:\|\mathbf{v}\|^{2}=1}{\operatorname{argmax}} \frac{1}{N} \sum_{i=1}^{N}\left(\mathbf{v}^{T} \mathbf{x}^{(i)}\right)^{2} \tag{4}
\end{align*}
$$

## Principal Component Analysis (PCA)

Whiteboard

- PCA, Eigenvectors, and Eigenvalues
- Algorithms for finding Eigenvectors /

Eigenvalues

- SVD: Relation of Singular Vectors to

Eigenvectors

## SVD for PCA

For any arbitrary matrix A, SVD gives a decomposition:

$$
\begin{equation*}
\mathbf{A}=\mathbf{U} \boldsymbol{\Lambda} \mathbf{V}^{T} \tag{1}
\end{equation*}
$$

where $\boldsymbol{\Lambda}$ is a diagonal matrix, and $\mathbf{U}$ and $\mathbf{V}$ are orthogonal matrices. Suppose we obtain an SVD of our data matrix $\mathbf{X}$, so that:

$$
\begin{equation*}
\mathbf{X}=\mathbf{U} \boldsymbol{\Lambda} \mathbf{V}^{T} \tag{1}
\end{equation*}
$$

Now consider what happens when we rewrite $\mathbf{\Sigma}=\frac{1}{N} \mathbf{X}^{T} \mathbf{X}$ terms of this SVD.

$$
\begin{align*}
\boldsymbol{\Sigma} & =\frac{1}{N} \mathbf{X}^{T} \mathbf{X}  \tag{2}\\
& =\frac{1}{N}\left(\mathbf{U} \boldsymbol{\Lambda} \mathbf{V}^{T}\right)^{T}\left(\mathbf{U} \boldsymbol{\Lambda} \mathbf{V}^{T}\right)  \tag{3}\\
& =\frac{1}{N}\left(\mathbf{V} \boldsymbol{\Lambda}^{T} \mathbf{U}^{T}\right)\left(\mathbf{U} \boldsymbol{\Lambda} \mathbf{V}^{T}\right)  \tag{4}\\
& =\frac{1}{N} \mathbf{V} \boldsymbol{\Lambda}^{T} \boldsymbol{\Lambda} \mathbf{V}^{T}  \tag{5}\\
& =\frac{1}{N} \mathbf{V}(\boldsymbol{\Lambda})^{2} \mathbf{V}^{T} \tag{6}
\end{align*}
$$

Above we used the fact that $\mathbf{U}^{T} \mathbf{U}=\mathbf{I}$ since $\mathbf{U}$ is orthogonal by definition.

## SVD for PCA

For any arbitrary matrix A, SVD gives a decomposition:

$$
\begin{equation*}
\mathbf{A}=\mathbf{U} \boldsymbol{\Lambda} \mathbf{V}^{T} \tag{1}
\end{equation*}
$$

where $\boldsymbol{\Lambda}$ is a diag We find that $(\boldsymbol{\Lambda})^{2}$ is a diagonal matrix whose entries are $\Lambda_{i i}=\lambda_{i}^{2}$ Suppose we obtc the squares of the eigenvalues of the SVD of $\mathbf{X}$. Further, both $\mathbf{X}$ and $\mathbf{X}^{T} \mathbf{X}$ share the same eigenvectors in their SVD.
Now consider wr Thus, we can run SVD on $\mathbf{X}$ without ever instantiating the large $\mathbf{X}^{T} \mathbf{X}$ of this SVD. to obtain the necessary principal components more efficiently.

$$
\begin{align*}
\boldsymbol{\Sigma} & =\frac{1}{N} \mathbf{X}^{T} \mathbf{X}  \tag{2}\\
& =\frac{1}{N}\left(\mathbf{U} \boldsymbol{\Lambda} \mathbf{V}^{T}\right)^{T}\left(\mathbf{U} \boldsymbol{\Lambda} \mathbf{V}^{T}\right)  \tag{3}\\
& =\frac{1}{N}\left(\mathbf{V} \boldsymbol{\Lambda}^{T} \mathbf{U}^{T}\right)\left(\mathbf{U} \boldsymbol{\Lambda} \mathbf{V}^{T}\right)  \tag{4}\\
& =\frac{1}{N} \mathbf{V} \boldsymbol{\Lambda}^{T} \boldsymbol{\Lambda} \mathbf{V}^{T}  \tag{5}\\
& =\frac{1}{N} \mathbf{V}(\boldsymbol{\Lambda})^{2} \mathbf{V}^{T} \tag{6}
\end{align*}
$$

Above we used the fact that $\mathbf{U}^{T} \mathbf{U}=\mathbf{I}$ since $\mathbf{U}$ is orthogonal by definition.

## Principal Component Analysis (PCA)

$\left(X X^{T}\right) v=\lambda v$, so $v$ (the first $P C$ ) is the eigenvector of sample correlation/covariance matrix $X X^{T}$
Sample variance of projection $\mathrm{v}^{T} X X^{T} \mathrm{v}=\lambda \mathrm{v}^{T} \mathrm{v}=\lambda$
Thus, the eigenvalue $\lambda$ denotes the amount of variability captured along that dimension (aka amount of energy along that
 dimension).

Eigenvalues $\lambda_{1} \geq \lambda_{2} \geq \lambda_{3} \geq \cdots$

- The $1^{\text {st }} \mathrm{PC} v_{1}$ is the the eigenvector of the sample covariance matrix $X X^{T}$ associated with the largest eigenvalue
- The 2nd PC $v_{2}$ is the the eigenvector of the sample covariance matrix $X X^{T}$ associated with the second largest eigenvalue
- And so on ...


## How Many PCs?

- For M original dimensions, sample covariance matrix is MxM, and has up to M eigenvectors. So M PCs.
- Where does dimensionality reduction come from?

Can ignore the components of lesser significance.


- You do lose some information, but if the eigenvalues are small, you don't lose much
- M dimensions in original data
- calculate $M$ eigenvectors and eigenvalues
- choose only the first D eigenvectors, based on their eigenvalues
- final data set has only $D$ dimensions

Slides from Barnabas Poczos

Original sources include:

- Karl Booksh Research group
- Tom Mitchell
- Ron Parr


## PCA EXAMPLES

## Face recognition

## Challenge: Facial Recognition

- Want to identify specific person, based on facial image
- Robust to glasses, lighting,...
$\Rightarrow$ Can't just use the given $256 \times 256$ pixels



## Applying PCA: Eigenfaces

Method: Build one PCA database for the whole dataset and then classify based on the weights.

- Example data set: Images of faces
- Famous Eigenface approach [Turk \& Pentland], [Sirovich \& Kirby]
- Each face $\mathbf{x}$ is ...
- $256 \times 256$ values (luminance at location)
$-\mathbf{X}$ in $\mathfrak{R}^{256 \times 256}$ (view as 64 K dim vector)

m faces


## Principle Components



## Reconstructing...



- ... faster if train with...
- only people w/out glasses
- same lighting conditions


## Shortcomings

- Requires carefully controlled data:
- All faces centered in frame
- Same size
- Some sensitivity to angle
- Alternative:
- "Learn" one set of PCA vectors for each angle
- Use the one with lowest error
- Method is completely knowledge free
- (sometimes this is good!)
- Doesn't know that faces are wrapped around 3D objects (heads)
- Makes no effort to preserve class distinctions


## Image Compression

## Oriainal Imaae



- Divide the original $372 \times 492$ image into patches:
- Each patch is an instance that contains $12 \times 12$ pixels on a grid
- View each as a 144-D vector


## $\mathrm{L}_{2}$ error and PCA dim



Slide from Barnabas Poczos

## PCA compression: 144D $\rightarrow$ 60D



## PCA compression: 144D $\rightarrow$ 16D



Slide from Barnabas Poczos

## 16 most important eigenvectors















## PCA compression: 144D $\rightarrow$ 6D



## 6 most important eigenvectors








## PCA compression: 144D $\rightarrow$ 3D



## 3 most important eigenvectors





Slide from Barnabas Poczos

## PCA compression: 144D $\rightarrow$ 1D



## 60 most important eigenvectors <br> 

Looks like the discrete cosine bases of JPG!...

## 2D Discrete Cosine Basis


http://en.wikipedia.org/wiki/Discrete_cosine_transform

