

10-601 Introduction to Machine Learning

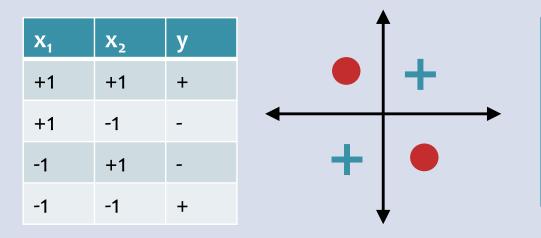
Machine Learning Department School of Computer Science Carnegie Mellon University

Logistic Regression

Matt Gormley Lecture 9 Feb. 13, 2019

Q&A

- **Q:** In recitation, we only covered the Perceptron mistake bound for **linearly separable data**. Isn't that an unrealistic setting?
- A: Not at all! Even if your data isn't linearly separable to begin with, we can often add features to make it so.



Exercise: Add another feature to transform this nonlinearly separable data into linearly separable data.

Reminders

- Homework 3: KNN, Perceptron, Lin.Reg.
 - Out: Wed, Feb 6
 - Due: Fri, Feb 15 at 11:59pm
- Homework 4: Logistic Regression
 - Out: Fri, Feb 15
 - Due: Fri, Mar 1 at 11:59pm
- Midterm Exam 1
 - Thu, Feb 21, 6:30pm 8:00pm
- Today's In-Class Poll
 - http://p9.mlcourse.org

PROBABILISTIC LEARNING

Probabilistic Learning

Function Approximation

Previously, we assumed that our output was generated using a **deterministic target function**:

$$\mathbf{x}^{(i)} \sim p^*(\cdot)$$
$$y^{(i)} = c^*(\mathbf{x}^{(i)})$$

Our goal was to learn a hypothesis h(x) that best approximates c^{*}(x)

Probabilistic Learning

Today, we assume that our output is **sampled** from a conditional **probability distribution**:

$$\begin{aligned} \mathbf{x}^{(i)} &\sim p^*(\cdot) \\ y^{(i)} &\sim p^*(\cdot | \mathbf{x}^{(i)}) \end{aligned}$$

Our goal is to learn a probability distribution $p(y|\mathbf{x})$ that best approximates $p^*(y|\mathbf{x})$

Robotic Farming

	Deterministic	Probabilistic
Classification (binary output)	Is this a picture of a wheat kernel?	Is this plant drought resistant?
Regression (continuous output)	How many wheat kernels are in this picture?	What will the yield of this plant be?





Bayes Optimal Classifier

Whiteboard

- Bayes Optimal Classifier
- Reducible / irreducible error
- Ex: Bayes Optimal Classifier for 0/1 Loss

Learning from Data (Frequentist)

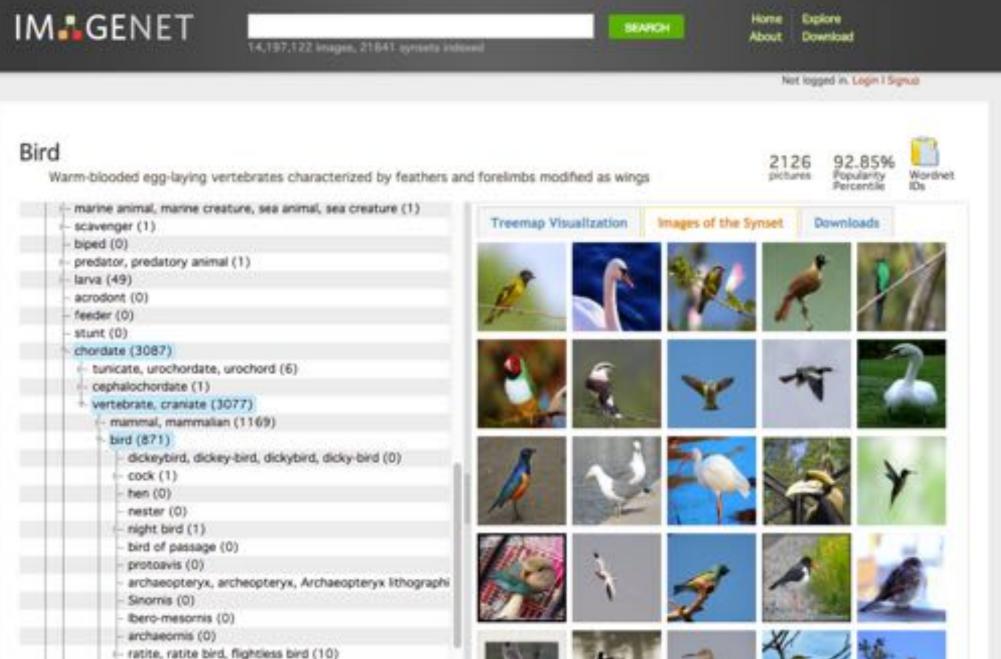
Whiteboard

- Principle of Maximum Likelihood Estimation (MLE)
- Strawmen:
 - Example: Bernoulli
 - Example: Gaussian
 - Example: Conditional #1 (Bernoulli conditioned on Gaussian)
 - Example: Conditional #2 (Gaussians conditioned on Bernoulli)

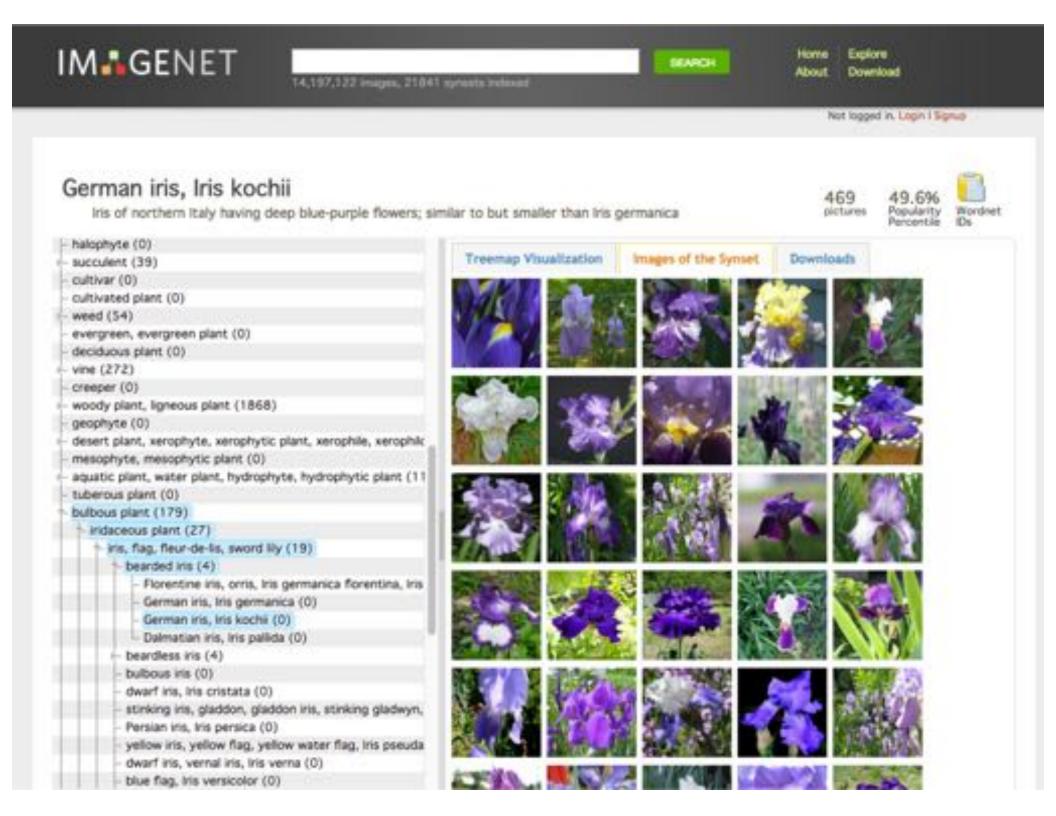
MOTIVATION: LOGISTIC REGRESSION

Example: Image Classification

- ImageNet LSVRC-2010 contest:
 - Dataset: 1.2 million labeled images, 1000 classes
 - Task: Given a new image, label it with the correct class
 - **Multiclass** classification problem
- Examples from http://image-net.org/



- carinate, carinate bird, flying bird (0)
- passerine, passenform bird (279)
- nonpasserine bird (0)
- bird of prey, raptor, raptorial bird (80)
- gallinaceous bird, gallinacean (114)



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Example: Image Classification

CNN for Image Classification (Krizhevsky, Sutskever & Hinton, 2011) 17.5% error on ImageNet LSVRC-2010 contest

Input

image

(pixels)

- Five convolutional layers (w/max-pooling)
- Three fully connected layers

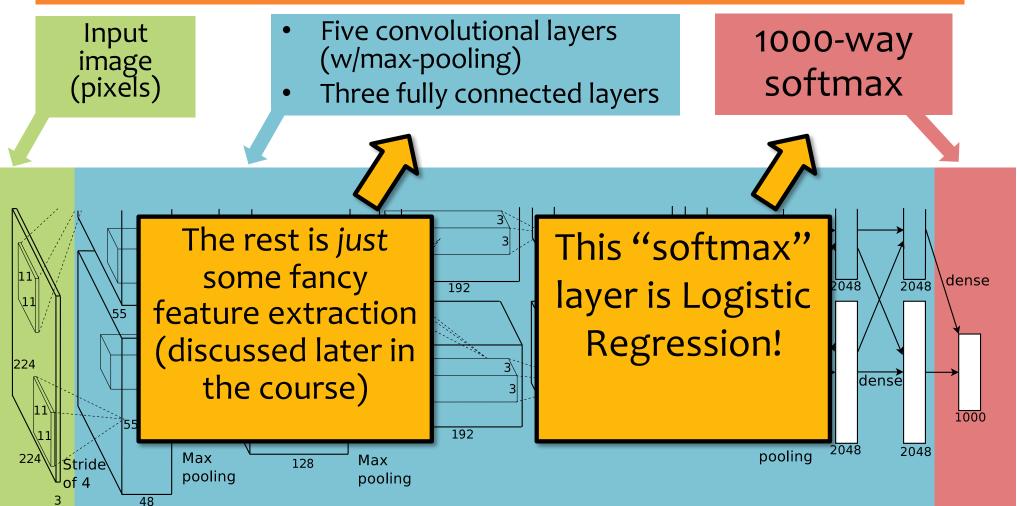
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1000-way

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Example: Image Classification

CNN for Image Classification (Krizhevsky, Sutskever & Hinton, 2011) 17.5% error on ImageNet LSVRC-2010 contest



LOGISTIC REGRESSION

Data: Inputs are continuous vectors of length M. Outputs are discrete.

 $\mathcal{D} = \{\mathbf{x}^{(i)}, y^{(i)}\}_{i=1}^N$ where $\mathbf{x} \in \mathbb{R}^M$ and $y \in \{0, 1\}$

We are back to classification.

Despite the name logistic **regression**.

Linear Models for Classification

Looking ahead:

- We'll see a number of commonly used Linear Classifiers
- These include:
 - Perceptron
 - Logistic Regression
 - Naïve Bayes (under certain conditions)
 - Support Vector Machines

Key idea: Try to learn this hyperplane directly

Directly modeling the hyperplane would use a decision function:

 $h(\mathbf{x}) = \operatorname{sign}(\boldsymbol{\theta}^T \mathbf{x})$

 $y \in \{-1, +1\}$

for:



Background: Hyperplanes

Notation Trick: fold the bias b and the weights w into a single vector $\boldsymbol{\theta}$ by prepending a constant to x and increasing dimensionality by one! Hyperplane (Definition 1): $\mathcal{H} = \{\mathbf{x} : \mathbf{w}^T \mathbf{x} = b\}$

Hyperplane (Definition 2): $\mathcal{H} = \{\mathbf{x} : \boldsymbol{\theta}^T \mathbf{x} = 0\}$

and $x_0 = 1$

$$\boldsymbol{\theta} = [b, w_1, \dots, w_M]^T$$

Half-spaces: $\mathcal{H}^+ = \{\mathbf{x} : \boldsymbol{\theta}^T \mathbf{x} > 0 \text{ and } x_0 = 1\}$ $\mathcal{H}^- = \{\mathbf{x} : \boldsymbol{\theta}^T \mathbf{x} < 0 \text{ and } x_0 = 1\}$

Using gradient ascent for linear classifiers

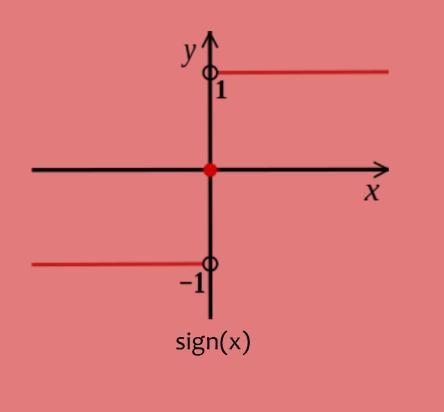
Key idea behind today's lecture:

- 1. Define a linear classifier (logistic regression)
- 2. Define an objective function (likelihood)
- 3. Optimize it with gradient descent to learn parameters
- 4. Predict the class with highest probability under the model

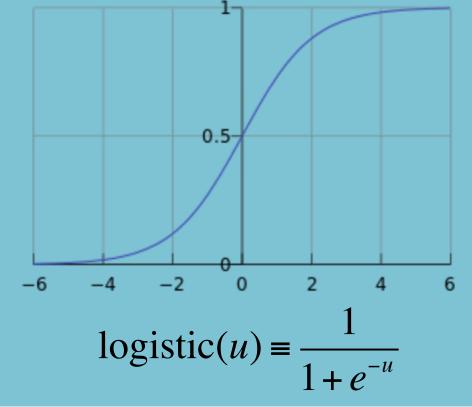
Using gradient ascent for linear classifiers

This decision function isn't differentiable:

 $h(\mathbf{x}) = \operatorname{sign}(\boldsymbol{\theta}^T \mathbf{x})$



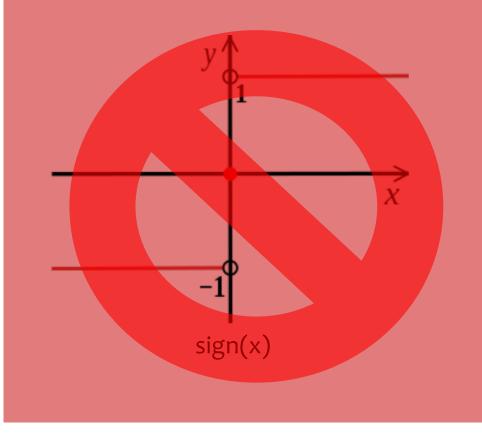
Use a differentiable function instead: $p_{\theta}(y = 1 | \mathbf{x}) = \frac{1}{1 + \exp(-\theta^T \mathbf{x})}$



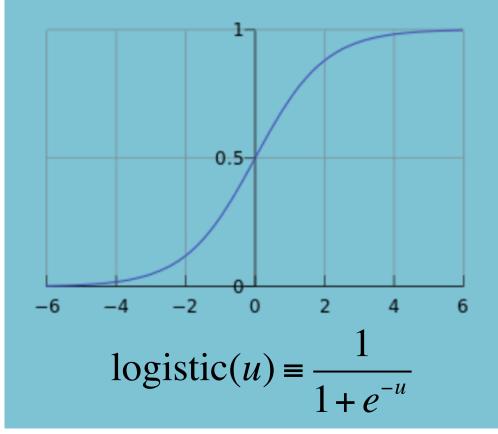
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 $\mathcal{D} = \{\mathbf{x}^{(i)}, y^{(i)}\}_{i=1}^N$ where $\mathbf{x} \in \mathbb{R}^M$ and $y \in \{0, 1\}$

Model: Logistic function applied to dot product of parameters with input vector. $p_{\theta}(y = 1 | \mathbf{x}) = \frac{1}{1 + \exp(-\theta^T \mathbf{x})}$

Learning: finds the parameters that minimize some objective function. $\theta^* = \operatorname*{argmin}_{\theta} J(\theta)$

Prediction: Output is the most probable class. $\hat{y} = \operatorname*{argmax}_{y \in \{0,1\}} p_{\theta}(y|\mathbf{x})$

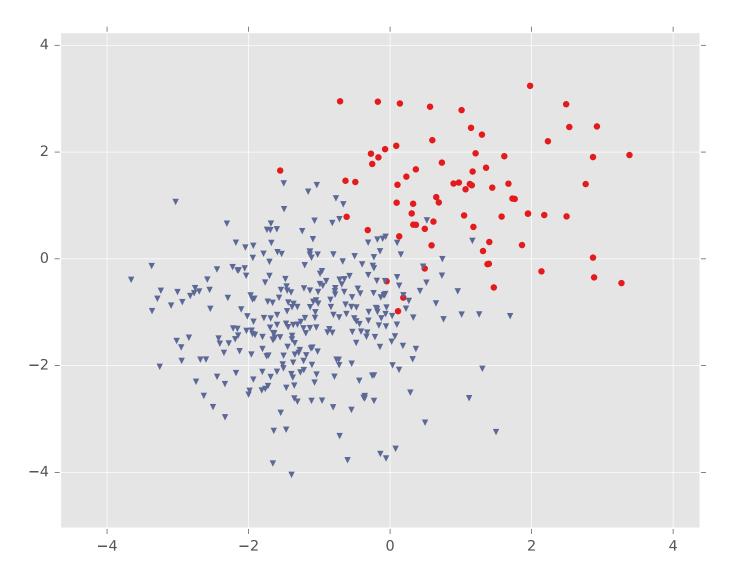
Whiteboard

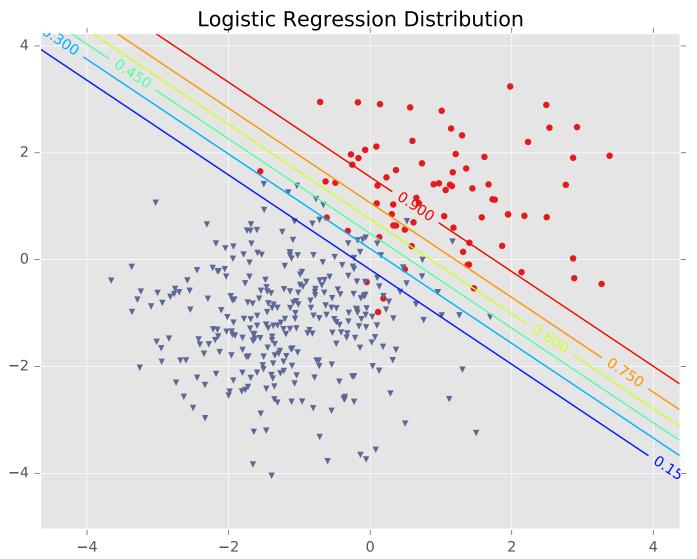
- Bernoulli interpretation
- Logistic Regression Model
- Decision boundary

Learning for Logistic Regression

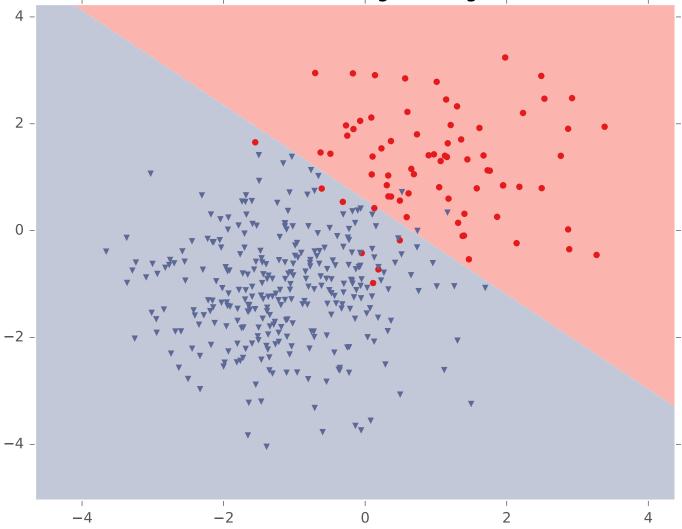
Whiteboard

- Partial derivative for Logistic Regression
- Gradient for Logistic Regression





Classification with Logistic Regression



LEARNING LOGISTIC REGRESSION

Maximum **Conditional** Likelihood Estimation

Learning: finds the parameters that minimize some objective function.

 $\boldsymbol{\theta}^* = \operatorname*{argmin}_{\boldsymbol{\theta}} J(\boldsymbol{\theta})$

We minimize the *negative* log conditional likelihood:

$$J(\boldsymbol{\theta}) = -\log \prod_{i=1}^{N} p_{\boldsymbol{\theta}}(y^{(i)} | \mathbf{x}^{(i)})$$

Why?

- 1. We can't maximize likelihood (as in Naïve Bayes) because we don't have a joint model p(x,y)
- 2. It worked well for Linear Regression (least squares is MCLE)

Maximum **Conditional** Likelihood Estimation

Learning: Four approaches to solving $\theta^* = \operatorname{argmin}_{\theta} J(\theta)$

Approach 1: Gradient Descent (take larger – more certain – steps opposite the gradient)

Approach 2: Stochastic Gradient Descent (SGD) (take many small steps opposite the gradient)

Approach 3: Newton's Method (use second derivatives to better follow curvature)

Approach 4: Closed Form??? (set derivatives equal to zero and solve for parameters)

Maximum **Conditional** Likelihood Estimation

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(set derivatives equal to zero and solve for parameters)

Logistic Regression does not have a closed form solution for MLE parameters.

SGD for Logistic Regression

Question:

Which of the following is a correct description of SGD for Logistic Regression?

Answer:

At each step (i.e. iteration) of SGD for Logistic Regression we...

- A. (1) compute the gradient of the log-likelihood for all examples (2) update all the parameters using the gradient
- B. (1) ask Matt for a description of SGD for Logistic Regression, (2) write it down, (3) report that answer
- C. (1) compute the gradient of the log-likelihood for all examples (2) randomly pick an example (3) update only the parameters for that example
- D. (1) randomly pick a parameter, (2) compute the partial derivative of the loglikelihood with respect to that parameter, (3) update that parameter for all examples
- E. (1) randomly pick an example, (2) compute the gradient of the log-likelihood for that example, (3) update all the parameters using that gradient
- F. (1) randomly pick a parameter and an example, (2) compute the gradient of the log-likelihood for that example with respect to that parameter, (3) update that parameter using that gradient



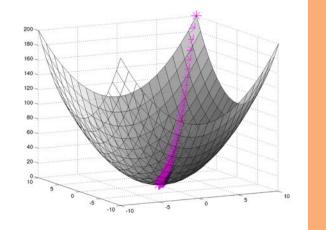
Gradient Descent

Algorithm 1 Gradient Descent

1: procedure
$$GD(\mathcal{D}, \boldsymbol{\theta}^{(0)})$$

2:
$$\boldsymbol{ heta} \leftarrow \boldsymbol{ heta}^{(0)}$$

3: while not converged do 4: $\boldsymbol{\theta} \leftarrow \boldsymbol{\theta} - \lambda \nabla_{\boldsymbol{\theta}} J(\boldsymbol{\theta})$



In order to apply GD to Logistic Regression all we need is the **gradient** of the objective $\nabla_{\theta} J(\theta) =$ function (i.e. vector of partial derivatives).

$$\begin{bmatrix} \frac{\overline{d}}{d\theta_1} J(\boldsymbol{\theta}) \\ \frac{\overline{d}}{d\theta_2} J(\boldsymbol{\theta}) \\ \vdots \\ \frac{\overline{d}}{d\theta_M} J(\boldsymbol{\theta}) \end{bmatrix}$$

Stochastic Gradient Descent (SGD)

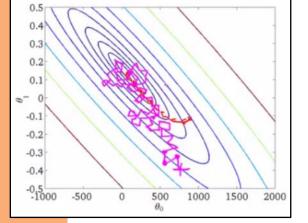
Algorithm 1 Stochastic Gradient Descent (SGD)

1: procedure SGD(
$$\mathcal{D}, \boldsymbol{\theta}^{(0)}$$
)

$$: \quad oldsymbol{ heta} \leftarrow oldsymbol{ heta}^{(0)}$$

3: while not converged do 4: for $i \in \text{shuffle}(\{1, 2, \dots, N\})$

$$\boldsymbol{\theta} \leftarrow \boldsymbol{\theta} - \lambda \nabla_{\boldsymbol{\theta}} J^{(i)}(\boldsymbol{\theta})$$



6: return θ

5

We can also apply SGD to solve the MCLE problem for Logistic Regression.

We need a per-example objective:

Let
$$J(\boldsymbol{\theta}) = \sum_{i=1}^{N} J^{(i)}(\boldsymbol{\theta})$$

where $J^{(i)}(\boldsymbol{\theta}) = -\log p_{\boldsymbol{\theta}}(y^{i}|\mathbf{x}^{i})$.

Mini-Batch SGD

• Gradient Descent:

Compute true gradient exactly from all N examples

• Mini-Batch SGD:

Approximate true gradient by the average gradient of K randomly chosen examples

• Stochastic Gradient Descent (SGD): Approximate true gradient by the gradient of one randomly chosen example

Mini-Batch SGD

while not converged:
$$oldsymbol{ heta} \leftarrow oldsymbol{ heta} - \lambda \mathbf{g}$$

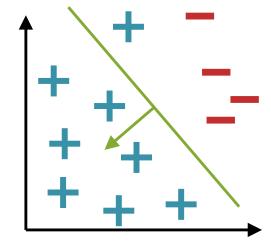
Three variants of first-order optimization:

Gradient Descent: $\mathbf{g} = \nabla J(\boldsymbol{\theta}) = \frac{1}{N} \sum_{i=1}^{N} \nabla J^{(i)}(\boldsymbol{\theta})$ SGD: $\mathbf{g} = \nabla J^{(i)}(\boldsymbol{\theta})$ where i sampled uniformly Mini-batch SGD: $\mathbf{g} = \frac{1}{S} \sum_{s=1}^{S} \nabla J^{(i_s)}(\boldsymbol{\theta})$ where i_s sampled uniformly $\forall s$

Logistic Regression vs. Perceptron

Question:

True or False: Just like Perceptron, one step (i.e. iteration) of SGD for Logistic Regression will result in a change to the parameters only if the current example is incorrectly classified.



Answer:

Summary

- Discriminative classifiers directly model the conditional, p(y|x)
- Logistic regression is a simple linear classifier, that retains a probabilistic semantics
- 3. Parameters in LR are learned by **iterative optimization** (e.g. SGD)

Logistic Regression Objectives

You should be able to...

- Apply the principle of maximum likelihood estimation (MLE) to learn the parameters of a probabilistic model
- Given a discriminative probabilistic model, derive the conditional log-likelihood, its gradient, and the corresponding Bayes Classifier
- Explain the practical reasons why we work with the log of the likelihood
- Implement logistic regression for binary or multiclass classification
- Prove that the decision boundary of binary logistic regression is linear
- For linear regression, show that the parameters which minimize squared error are equivalent to those that maximize conditional likelihood