

Lecture 6: 2/6/17

Naive Bayes Model

$$D = \{(x^{(i)}, y^{(i)})\}_{i=1}^N$$

Bernoulli Naive Model:

$$\begin{aligned}
 p(\vec{x}, y | \phi, \theta) &= p(x_1, \dots, x_M, y | \phi, \theta) \\
 &= p(y | \phi) \prod_{m=1}^M p(x_m | y, \theta) \\
 &= \left[\phi^y (1-\phi)^{(1-y)} \right] \prod_{m=1}^M (\theta_{my})^{x_m} (1-\theta_{my})^{(1-x_m)}
 \end{aligned}$$

$\theta = \begin{bmatrix} \theta_{10} & \theta_{11} \\ \vdots & \vdots \\ \theta_{M0} & \theta_{M1} \end{bmatrix}$

Naive Bayes Assumption:

$$\text{Recall: } p(\vec{x}, y) = p(\vec{x} | y) p(y)$$

$$p(\vec{x} | y) = \prod_{m=1}^M p(x_m | y)$$

each x_q is conditionally independent of x_r given $y \forall q, r$

Def: two r.v.s X, Y are cond. indep. given r.v. Z
 written $X \perp Y | Z$
 iff $P(X, Y | Z) = P(X | Z) P(Y | Z)$

Q: Why is this "naive"?

A: in real data.

Q: Why is it useful?

A: Count parameters:

Case #1: w/o NB assumption:

$$p(x_1, \dots, x_M | y) =$$

x_1	x_2	...	x_M	y	$p(\vec{x} y)$
0	0	...	0	0	.
0	0	...	0	1	.
0	0	...	1	0	.
0	0	...	1	1	.

2^{M+1} rows

$2^{M+1} - 2$ params

Case #2 w/ NBD

$$\begin{aligned}
 p(x_1=1 | y=0) &= \theta_{10} \\
 p(x_1=0 | y=0) &= 1 - \theta_{10}
 \end{aligned}$$

$4M$ rows

$2M$ params

$$p(x_1 | y) =$$

x_1	y	$p(x_1 y)$
0	0	.
0	1	.
1	0	.
1	1	.

$$p(x_2 | y) =$$

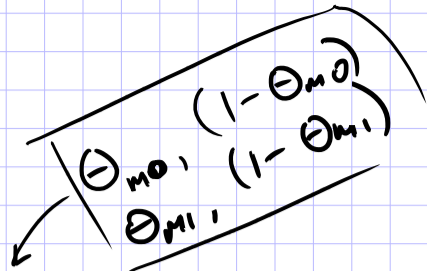
$$\dots p(x_M | y) =$$

MLE for Naive Bayes

① Data Likelihood

$$l(\phi, \theta) = \log \prod_{i=1}^N p(x^{(i)}, y^{(i)} | \phi, \theta)$$

$$= \sum_{i=1}^N \left[\log p(y^{(i)} | \phi) + \sum_{m=1}^M \log p(x_m^{(i)} | y^{(i)}, \theta) \right]$$



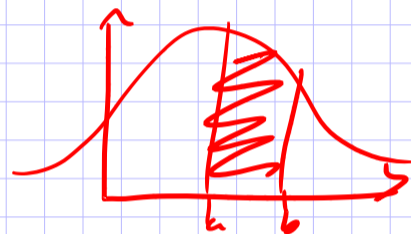
times $y^{(i)}$ is 1 in D

$$= N_{y=1} \log \phi + N_{y=0} \log(1 - \phi)$$

$$+ \sum_{m=1}^M \left[N_{x_m=1, y=1} \log \theta_{m1} + N_{x_m=0, y=1} \log(1 - \theta_{m1}) \right]$$

times that $x_m^{(i)}=1$ and $y^{(i)}=0$

$$+ \sum_{m=1}^M \left[N_{x_m=1, y=0} \log \theta_{m0} + N_{x_m=0, y=0} \log(1 - \theta_{m0}) \right]$$



MLE for ϕ and θ :

$$(\hat{\phi}, \hat{\theta}) = \underset{\phi, \theta}{\operatorname{argmax}} l(\phi, \theta)$$

② Take partials wrt ϕ :

$$\frac{d l(\phi, \theta)}{d \phi} = \frac{N_{y=1}}{\phi} + \frac{N_{y=0}}{\phi - 1}$$

we already know the MLE!
set equal to zero, solve for ϕ ...

$$\phi^{MLE} = \frac{N_{y=1}}{N_{y=1} + N_{y=0}} = \frac{N_{y=1}}{N}$$

③ Take partials wrt θ_{my} :

Case where $y=0, \theta_{m0}$

$$\frac{d l(\phi, \theta)}{d \theta_{m0}} = \frac{N_{x_m=1, y=0}}{\theta_{m0}} + \frac{N_{x_m=0, y=0}}{\theta_{m0} - 1}$$

$$\Rightarrow \theta_{m0}^{MLE} = \frac{N_{x_m=1, y=0}}{N_{x_m=1, y=0} + N_{x_m=0, y=0}} = \frac{N_{x_m=1, y=0}}{N_{y=0}}$$

MAP Estimation for NB

The Problem w/ MLE:

Suppose we never observe "Brexit" in Onion article

$$\forall i \text{ where } y^{(i)} = \text{Onion}, X_{\text{Brexit}}^{(i)} = 0$$

Q: What is the MLE $\Theta_{\text{Brexit, Onion}} = ?$

$$p(y = \text{Onion} | \vec{x}^{(\text{new})}) = 0$$

↑ contains Brexit

Beta Priors:

$$\phi \sim \text{Beta}(\alpha, \beta)$$

$$\Theta_{m,y} \sim \text{Beta}(\alpha, \beta) \quad \forall y \in \{0,1\} \quad \forall m \in \{1, \dots, M\}$$

for i in $1 \dots N$

$$y^{(i)} \sim \text{Bern}(\phi)$$

$$x_1^{(i)} \sim \text{Bern}(\Theta_{1,y})$$

$$\vdots$$
$$x_m^{(i)} \sim \text{Bern}(\Theta_{m,y})$$

$$l_{\text{MAP}}(\phi, \Theta) = \log \left[p(\phi, \Theta | \alpha, \beta) p(D | \phi, \Theta) \right]$$

$$= \log \left[p(\phi | \alpha, \beta) \prod_{m=1}^M p(\Theta_{m,0} | \alpha, \beta) p(\Theta_{m,1} | \alpha, \beta) \left[\prod_{i=1}^N p(x^{(i)}, y^{(i)} | \phi, \Theta) \right] \right]$$

MAP Estimates:

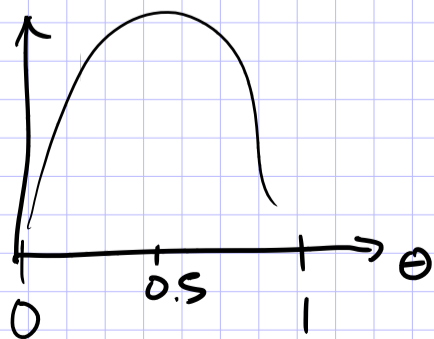
$$(\hat{\phi}, \hat{\Theta}) = \underset{\phi, \Theta}{\text{argmax}} l_{\text{MAP}}(\phi, \Theta)$$

Take partials, set equal to zero, and solve.

$$\Theta_{m,0} = \frac{N_{x_m=1, y=0} + (\alpha - 1)}{N_{y=0} + (\alpha - 1) + (\beta - 1)}$$

$$1 - \Theta_{m,0} = \frac{N_{x_m=0, y=0} + (\beta - 1)}{N_{y=0} + (\alpha - 1) + (\beta - 1)}$$

$$1 - \Theta_{m,0} = \frac{N_{x_m=0, y=0} + (\beta - 1)}{N_{y=0} + (\alpha - 1) + (\beta - 1)}$$



Hyperparameters α, β :

- Special case: where $\alpha = 2, \beta = 2$ called "Add-1 Smoothing"
- Chosen by hand, with world knowledge ~~with~~ about the model.
- Can learn them (Beyond Scope)

Gaussian Naive Bayes

Gaussian NB Model:

$$y \sim \text{Bern}(\theta) = p(y)$$
$$x_1 \sim \text{Gaussian}(\mu_{1y}, \sigma_{1y}^2) = p(x_1 | y)$$
$$\vdots$$
$$x_M \sim \text{Gaussian}(\mu_{My}, \sigma_{My}^2) = p(x_M | y)$$

$$\text{Data: } y \in \{0, 1\}$$
$$\vec{x} \in \mathbb{R}^M$$

$$p(\vec{x}, y) = p(y) \prod_{m=1}^M p(x_m | y)$$

event model

Recall:

Bernoulli NB Model:

$$y \sim \text{Bern}(\theta)$$
$$x_1 \sim \text{Bern}(\theta_{1y})$$
$$\vdots$$
$$x_M \sim \text{Bern}(\theta_{My})$$

$$y \in \{0, 1\}$$
$$\vec{x} \in \{0, 1\}^M$$

Gaussian NB Parameters

$$\theta \in \mathbb{R}$$

$$\mu = \begin{bmatrix} \mu_{10} & \mu_{11} \\ \vdots & \vdots \\ \mu_{M0} & \mu_{M1} \end{bmatrix} \begin{array}{l} \leftarrow \text{for } x_1 \\ \\ \leftarrow \text{for } x_M \end{array}$$

\uparrow if $y=0$ \uparrow if $y=1$

$$\mu_{my} \in \mathbb{R} \quad \forall y, m$$

$$\sigma^2 = \begin{bmatrix} \sigma_{10}^2 & \sigma_{11}^2 \\ \vdots & \vdots \\ \sigma_{M0}^2 & \sigma_{M1}^2 \end{bmatrix}$$

$$\sigma_{my}^2 > 0 \quad \forall y, m$$

Details:

① Data likelihood:

② Learning (MLE or MAP)

③ Prediction:

$$\hat{y} = h(\vec{x}) = \underset{y \in \{0,1\}}{\operatorname{argmax}} p(y | \vec{x}, \phi, \mu, \sigma^2)$$

Everything just works like "Bernoulli" NB!