

RECITATION HOMEWORK 3

10-418/618: MACHINE LEARNING FOR STRUCTURED DATA

09/28/2022

Directed Graphical Models

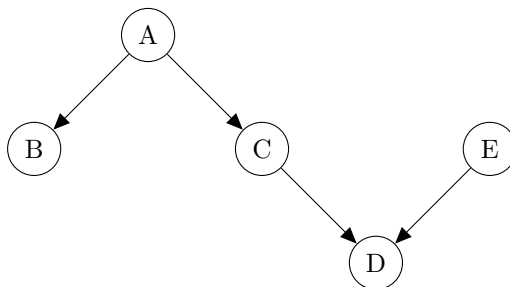


Figure 1: Directed Graphical Model

1. Consider the graph \mathcal{G} given in Figure 1. Suppose you are given a joint distribution $P(A, B, C, D, E)$ and you are informed that P factorizes according to \mathcal{G} . Write down a factorization of P based on the definition of a directed graphical model.
2. Draw the moralized graph of \mathcal{G}

Undirected Graphical Models

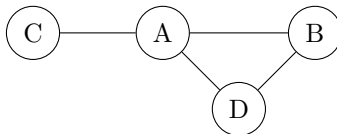
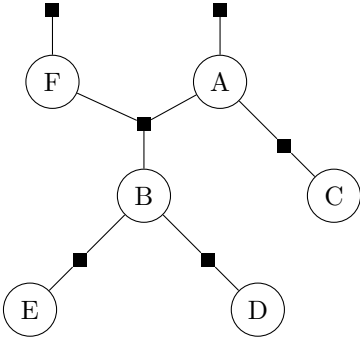


Figure 2: Undirected Graphical Model

3. Identify the cliques in Fig. 2.
4. What is the Markov boundary of A? of D?

Factor Graphs

5. Convert the following factor graph to a directed graphical model and an undirected graphical model:



Variable Elimination

6. When Querying $P(A|h = \tilde{h})$, Perform variable elimination on the following directed graph G in the order: H,G,F,E,D,C,B

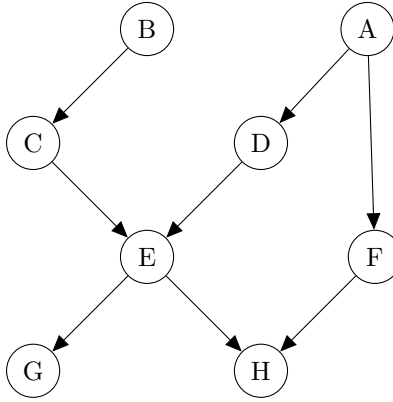


Figure 3: Initial graph for variable elimination

Variable Eliminated	Factor Computed
H	
G	
F	
E	
D	
C	
B	

7. Perform variable elimination on undirected graph G' :

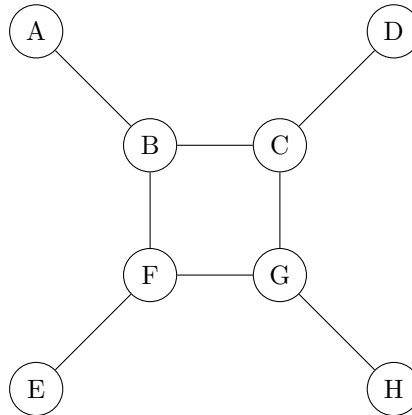


Figure 4: Initial graph for variable elimination

Order F, B, C, G, A, D, H, E:

Variable Eliminated	Elimination Clique
F	
B	
C	
G	
A	
D	
H	
E	

Order A, D, E, H, B, C, F, G:

Variable Eliminated	Elimination Clique
A	
D	
E	
H	
B	
C	
F	
G	

8. How does the size of the elimination cliques relate to the computational complexity of variable elimination?

Belief Propagation

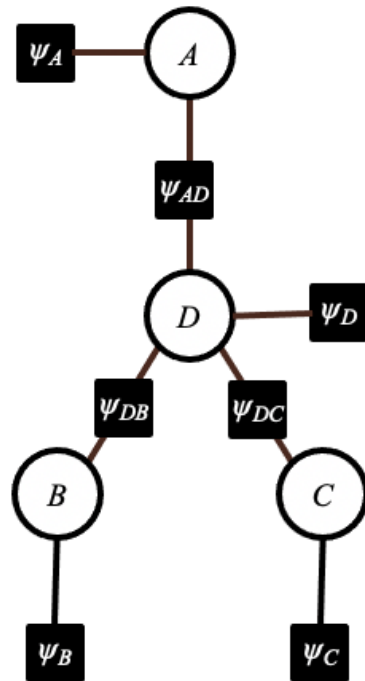


Figure 5

a	$\psi_A(a)$
0	3
1	2

b	$\psi_B(b)$
0	1
1	2

c	$\psi_C(c)$
0	3
1	1

d	$\psi_D(d)$
0	1
1	1

a	d	$\psi_{AD}(a, d)$
0	0	2
0	1	2
1	0	2
1	1	3

b	d	$\psi_{DB}(b, d)$
0	0	1
0	1	2
1	0	1
1	1	1

c	d	$\psi_{DC}(c, d)$
0	0	1
0	1	1
1	0	1
1	1	3

9. Consider the factor graph in Figure 5. On paper, carry out a run of belief propagation by sending messages first from the leaves ψ_B, ψ_C to the root ψ_A , and then from the root back to the leaves. Assume all messages are un-normalized. Then find the beliefs at nodes A, B, C , and D along with the beliefs for ψ_{DB}, ψ_{DC} , and ψ_{AD} .

Constituency Parsing

First we'll consider an extremely ambiguous sentence and see how we could disambiguate the meaning.

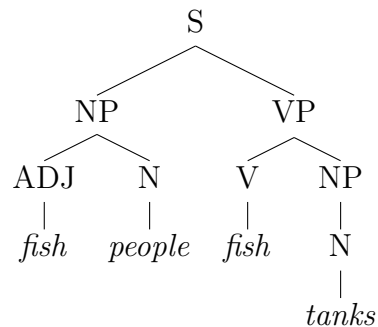
Fish people fish tanks. (1)

This sentence could be interpreted two ways.

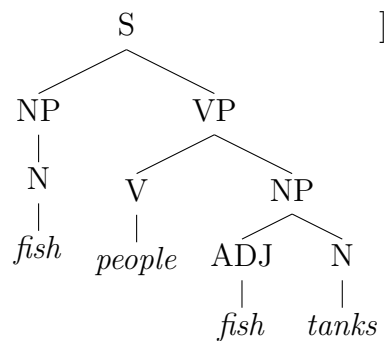
1. Fish-People hybrids fish in tanks.
2. Fish populate fish tanks. (This uses a less common meaning of people meaning "to populate".)

How could we build in structure to distinguish between these two meanings? One way is to build and label a parse tree.

1. Fish-People hybrids fish in tanks.



2. Fish populate fish tanks.



Both of these options can be summarized by a simple set of rules called a *grammar*. If you've taken a compiler course, you'll know and hate this term.

$$\begin{aligned} \mathbf{S} &\rightarrow \mathbf{NP VP} \\ \mathbf{NP} &\rightarrow \mathbf{ADJ N} \mid \mathbf{N} \\ \mathbf{VP} &\rightarrow \mathbf{V NP} \end{aligned}$$

The takeaway from this is that if we could somehow generate these tree-labelings, we would be much closer to pulling *meaning* from a sequence of words before further processing. For example, this can be a useful first step in a dialogue system where disambiguating meaning is crucial.

So now that we've established the context for our problem of interest, let's set it aside for a little while.

Message Passing Review

Remember that for belief propagation on factor graphs, we have two types of messages we can pass.

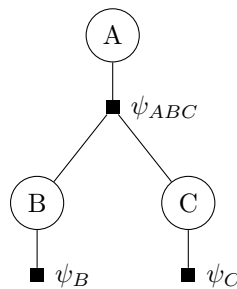
Variable to Factor:

$$\mu_{x \rightarrow f}(x) = \prod_{g \in \text{Ne}(x)/f} \mu_{g \rightarrow x}(x)$$

Factor to Variable:

$$\mu_{f \rightarrow x}(x) = \sum_{\mathcal{X}_f/x} \psi_f(\mathcal{X}_f) \prod_{y \in \{\text{Ne}(f)/x\}} \mu_{y \rightarrow f}(y)$$

We'll consider applying these rules to the following undirected graphical model.



Representation

First, let's consider the case where each potential function is tabular, variables B and C are binary, and variable A has N possible settings.

Q: How would we represent this as a NumPy array?

A: Use an array where each axis i represents all the values variable i can take.

Q: What would be the size of ψ_b ?

A: $(2,)$

Q: What would be the size of ψ_{abc} ?

A: $(N, 2, 2)$

Q: How would we marginalize out a variable in a potential function in this scenario?

A: Sum over the axis that represents the variable you want to marginalize.

Q: How would we express each of the types of messages in code?

A: This is a straightforward combination of element wise multiplication and summing over your axis of interest.