Multiclass Perception

Key Iden: If the prediction is incorrect (g + yt) then increase the score of yt and decrease the score of g

Algo: (Multiclass Perception)

O = 0

while not conveyed:

For (x,y) in D:

$$\hat{y} = \underset{j \in \{1, \dots, K3\}}{\operatorname{argmax}} \quad \Theta^{T} f(\hat{x}, j)$$

$$: \hat{y} \neq y^{*}: \quad \Theta = \Theta + f(\hat{x}, y^{*}) - f(\hat{x}, \hat{y})$$

 Θ 1. fill in the blank $(\Theta + f(x,y^*))^T f(x,y^*) \ge \Theta^T f(x,y^*)$

Algo. (Structual box.) $\hat{y} = argmax \quad \partial^T f(\hat{x}, y)$ $y \in y(\hat{x})$

Structured Perception

· Alyo:

· Same as Multicless Receptor w/each possible output structure yey(x) as a "class"

. Truling examples are (\vec{x}, \vec{y}) where $\vec{x} \in \mathcal{X}$ and $\vec{y} \in \mathcal{Y}(\vec{x})$

· Feature Fractions $f(\vec{x}, \vec{y}) \in \mathbb{R}^M$ repr. of (\vec{x}, \vec{y}) poir

• Predict $\hat{y} = a_{5} m_{x} \Theta^{T} f(\vec{x}, \vec{y})$

Key Questin: How to compute?

If $\exp(\Theta^T f(\vec{x}, \vec{y}))$ decomposes multiplicatively according to some factor graph, then some this "MAP inference problem" W/MILP, e.g., $\exp(\Theta^T f(\vec{x}, \vec{y})) = \exp(E \Theta^T f_c(\vec{x}, \vec{y}_c))$ $= T \exp(\Theta^T f_c(\vec{x}, \vec{y}_c))$

=
$$\prod_{c} \exp(\Theta^{T}f_{c}(\vec{x}, y_{c}))$$

= $\prod_{c} \psi_{c}(\vec{x}, y_{c})$

Structured SVM

Model: Linear
$$\hat{y} = h(\hat{x}) = agmex$$
 $\vec{y} \in \mathcal{Y}(\hat{x})$
 $\vec{y} \in \mathcal{Y}(\hat{x})$

$$\underline{Q.P.:} \quad \min_{\omega,e} \quad \frac{1}{2} \left(||\omega||_2 \right)^2 + C \underbrace{\sum_{i=1}^{N} \sum_{\hat{\gamma} \in \mathcal{Y}(\hat{x}^{(i)})}^{e_i,\hat{\gamma}}}_{e_i,\hat{\gamma}}$$

s.t.
$$S_{\omega}(x^{(i)}, y^{(i)}) - S_{\omega}(x^{(i)}, \hat{y}) \ge |(y^{(i)}, \hat{y}) - e_{i}, \hat{y}|$$
 $\forall i$

$$e_{i,\hat{\gamma}} \ge 0$$

Key Idea:

Q: How very constructs are in this Q.P.?

Key Idea: fold a maximization problem into constraint

s.t.
$$S_{\omega}(\vec{x}^{(i)}, \vec{y}^{(i)}) \ge \left[\max_{\hat{x} \in \mathcal{M}(\hat{x})} S_{\omega}(\vec{x}^{(i)}, \hat{y}) + l(y^{(i)}, q)\right] - e$$
:

s.t.
$$S_{\omega}(\vec{x}^{(i)}, \vec{y}^{(i)}) \ge \left[\max_{\hat{y} \in \mathcal{Y}(\vec{x})} S_{\omega}(\vec{x}^{(i)}, \hat{y}) + l(y^{(i)}, q)\right] - e$$
:

 $e_i \ge 0$

thuse N constraints and Nslack vars replaced

the $O(N, \max_{i} |\mathcal{Y}(\vec{x}^{(i)})|)$ constants and shake vars above

Q.P. W/ Hinge Loss

$$\min_{\omega} \frac{1}{2} ||\omega||_{2}^{2} + C \underbrace{\sum_{i=1}^{N} \left[\max_{\omega} \left(0, \left[\max_{\hat{y} \in \mathcal{Y}(\hat{x})} S_{\omega}(\hat{x}^{(i)}, \hat{y}) + l(y^{(i)}, \hat{y}) \right] - S_{\omega}(\hat{x}^{(i)}, y^{(i)}) \right]}_{\Xi}$$

Sul-Gradient

$$\nabla l_{w}^{s.H.}(\vec{x}^{(i)}, y^{(i)}) = \begin{cases} 0 & \text{if } l_{w}^{s.H.}(\vec{x}^{(i)}, \vec{y}^{(i)}) \\ f(\vec{x}^{(i)}, y^{(i)}) - f(\vec{x}^{(i)}, \hat{y}) & \text{otherwise} \end{cases}$$

$$f(\dot{x}^{(i)}, y^{(i)}) - f(\dot{x}^{(i)}, \hat{y})$$
 otherwise

where
$$\hat{y} = \operatorname{argmax} S_{\omega}(\vec{x}^{(i)}, \hat{y}) + \mathcal{L}(y^{(i)}, \hat{y})$$

$$\hat{y} \in \mathcal{Y}(\vec{x}^{(i)})$$

not your standard

MAP Informe problem

Train of Stochastra Subgradunt Gradient

$$p(z) = \emptyset_z$$

$$P(z) = \emptyset_{z}$$

$$= 0.2 | 0.1 | 0.6 | 0.1 |$$

$$= p(z) = 1$$

$$= 2 | dsorete$$

$$= 2 | P(z) | dz = 1$$

$$= 2 | eR$$

 $\int_{\mathbb{R}^{n}} \left(z | x \right) dz = 1$