Design and Human Factors Illah Nourbakhsh CMU/Robotics Institute

Mid-term surveys, grades and what they mean...

Functionally Adaptive Robotics

Cooking

Eyesight

Communication

Story-creation

Piano!

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Manipulate the World

Externalize Memory

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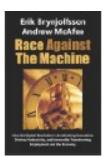
Forlizzi, DiSalvo, Gemperle

Balanced and imbalanced ecologies reminding family to call; communication social networking social Al agent

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Sheridan

Automation and underemployment history facts of life: must get along supervisory roles RABA-RABA



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What is Intelligence?

Levels of Deception (Mitchell 1988)

Camouflage

Programmed but active

Tailored responses

Awareness of other mental processes

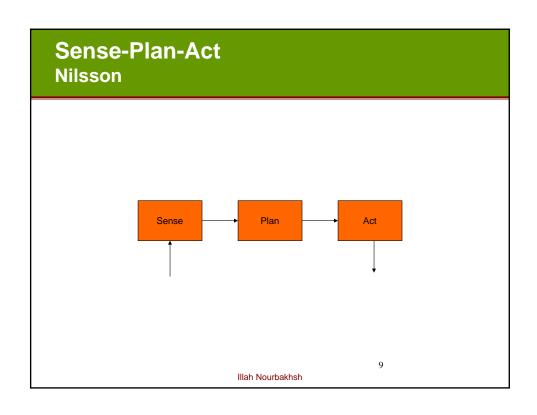
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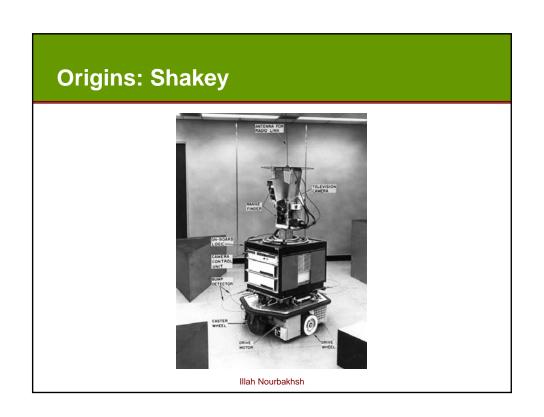
The Goal

Given initial conditions and goal constraints, design a robot automata such that the robotenvironment system satisfies the goal constraints.

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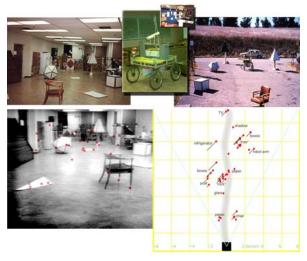


Origins: The Stanford Cart



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Origins: The Stanford Cart



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