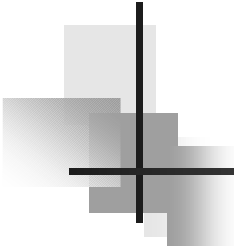


Domain Separation by Construction

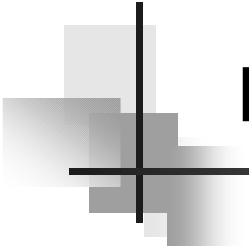
Bill Harrison, Mark Tullsen, & James Hook

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OGI School of Science & Engineering
Oregon Health & Science University



Domain Separation by Construction

- Approach to language-based security based on monads:
 - Provide a modular algebra of effects,
 - Allow precise control of interaction of threads
 - Expressible in any higher-order functional programming language
- Outline development of a operating system kernel
 - Kernel obeys non-interference style property
 - Called “take separation”
 - Security property follows directly from well-understood (aka, *by construction*) properties of monads aid in its verification



Foundations of our approach

trace
based
security
models

- Goguen/Meseguer 82,84
- McCullough 88
- McClean 94
- Zakathinos, et al., 95,97
- ...

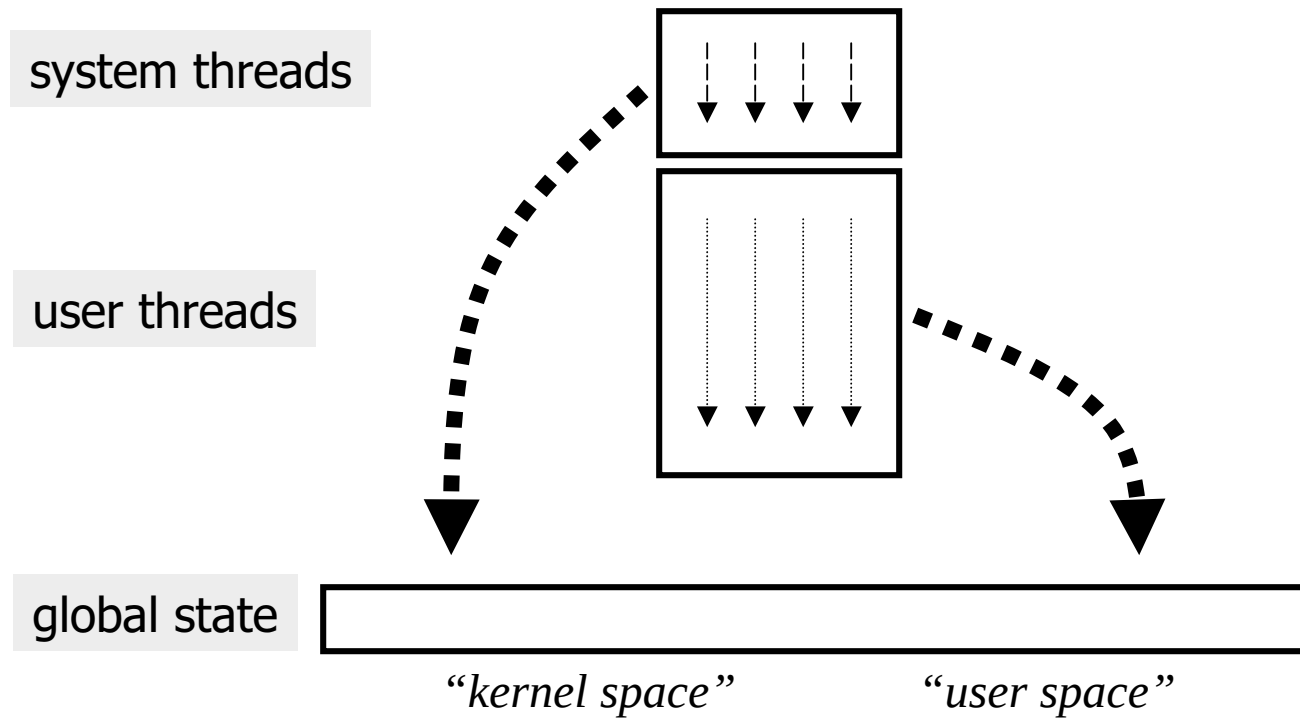
security
by
design

- Separability & Separation
Kernels [Rushby]
- Java Sandboxing
- KSOS 79
- Fox Project 98
- White, et al., 00
- ...

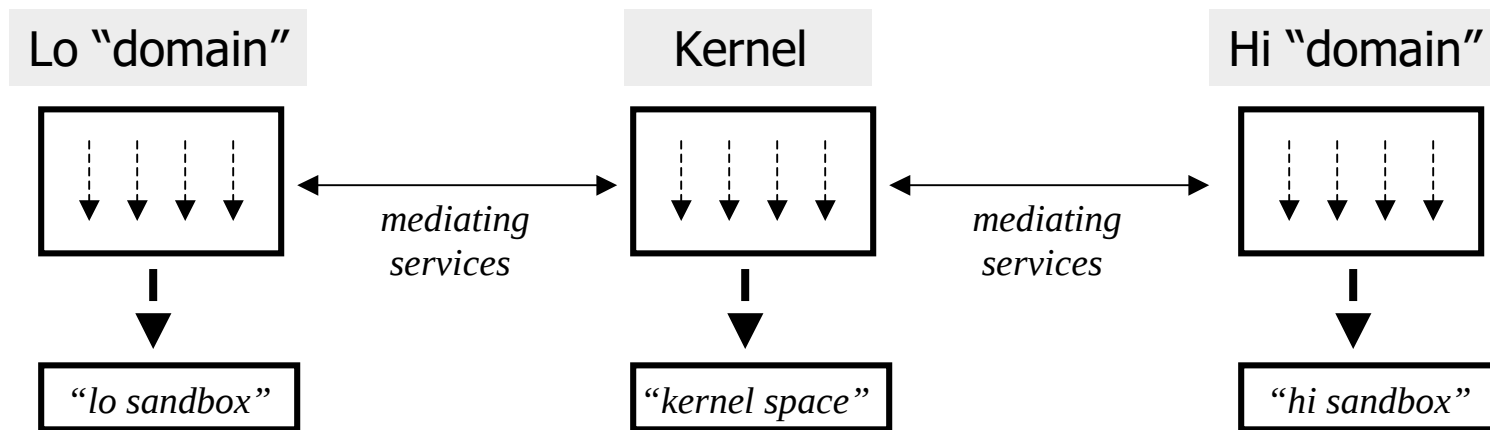
monadic
semantics

- LiangHudakJones 95
- Moggi 89
- Harrison 01
- Papaspyrou 00
- ...

Shared-state concurrency with global state

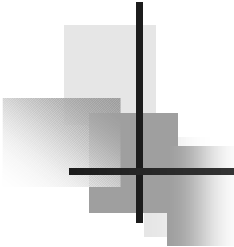


Separation Kernel Approach [Rushby82,81,...]



Security through separation:

- relies on tamed effects via state partitioning
AND controlling interactions through trusted kernel services
- supports a "divide & conquer" approach to verification



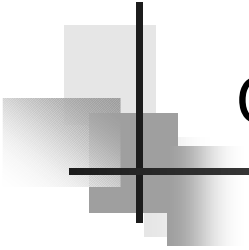
Trace-based models

An **event system** S is a tuple $\langle E, T, I, O \rangle$ where

$$\begin{array}{ll} T \subseteq E^* & (\mathcal{T} \text{ is the set of permissible traces}) \\ I \cup O \subseteq E & \\ I \cap O = \phi & (\text{I/O events are distinct}) \\ X \downarrow_Y = \text{subseq of } X \text{ with no } y \in Y & (\text{"view" from } Y) \\ E = L_o \cup H_i \text{ \& } L_o \cap H_i = \phi & \end{array}$$

Ex: Generalized Non-interference [GoguenMeseguer]

“Changes in high-level inputs only result in changes to high-level outputs”



Our approach to language based semantics

Instead of traces of abstract Lo and Hi events:

$$h_0, l_0, \dots, h_n, l_n$$

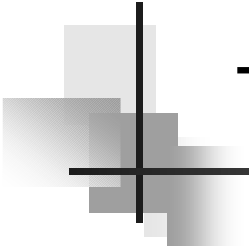
consider the imperative *program*:

$$h_0 ; l_0 ; \dots ; h_n ; l_n$$

with (monadic) denotational semantics:

$$\llbracket - \rrbracket : (Beh_{Lo} + Beh_{Hi}) \rightarrow R()$$

Monad R encapsulates imperative effects and a notion of concurrency called *resumptions* [Plotkin76, Schmidt86, Moggi89].



Take separation (first cut)

For any initial sequence of interleaved H_i and L_O operations, the L_O operations should be “oblivious” to the high security operations:

$$\begin{aligned} \llbracket h_0 ; l_0 ; \dots ; h_n ; l_n \rrbracket &\gg \text{mask} H_i \\ &= \llbracket l_0 ; \dots ; l_n \rrbracket \gg \text{mask} H_i \end{aligned}$$

What is a monad?

A **monad** is an algebra of *effects* (state, exceptions, concurrency,...)

M	(type constructor)
$\eta_M : a \rightarrow M a$	(unit)
$\star_M : M a \rightarrow (a \rightarrow M b) \rightarrow M b$	(bind)
$\gg_M : M () \rightarrow M () \rightarrow M ()$	(sequence)

Additionally, a state monad, St , has the **effects**:

$u : (Sto \rightarrow Sto) \rightarrow St ()$	(update)
$g : St ()$	(get)

Properties “by construction” of state monads

$u f \star \lambda_.u g$	$=$	$u (g \circ f)$	(sequencing)
$g \star \lambda\sigma_0.u (\lambda_.\sigma_0)$	$=$	$\eta()$	(cancellation)



Monad transformers are constructors for monads

Monad transformer, $(\text{StateT } Sto)$, adds effects to existing monad M

$$St = \text{StateT } Sto \ M$$

Monad $St2$ with two states H, L

$$St2 = \text{StateT } L \ (\text{StateT } H \ M)$$

$$u_L : (L \rightarrow L) \rightarrow St2 \ ()$$

$$g_L : St2 \ L$$

$$u_H : (H \rightarrow H) \rightarrow St2 \ ()$$

$$g_H : St2 \ H$$

Another by-construction property: “atomic non-interference”

$$(u_L \ f) \gg_{St2} (u_H \ g) = (u_H \ g) \gg_{St2} (u_L \ f)$$

Primer on resumption-based concurrency

- Consider two simple threads: $a = [a_0; a_1]$ and $b = [b_0]$
- *Concurrency as interleaving*: $(a \parallel b)$ means:

$$\{[a_0; a_1; b_0], [a_0; b_0; a_1], [b_0; a_0; a_1]\}$$

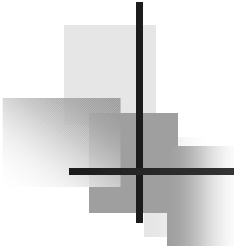
- Resumption monad transformer:

$$\begin{aligned} \text{ResT } M a &= \mu R. D a + P(M(R a)) \\ \text{step} &: M a \rightarrow \text{ResT } M a \\ \text{step } \varphi &= P(\varphi \star_M \lambda v. \eta_M(Dv)) \end{aligned}$$

D = "done"
 P = "pause"

- Now, $(a \parallel b)$ means the set of:

$$\begin{aligned} &(\text{step } a_0) \gg (\text{step } a_1) \gg (\text{step } b_0) \\ &(\text{step } a_0) \gg (\text{step } b_0) \gg (\text{step } a_1) \\ &(\text{step } b_0) \gg (\text{step } a_0) \gg (\text{step } a_1) \end{aligned}$$



Monadic event systems

- **Events** are effects in state monads
 - Update operation. $u : (\text{Sto} \rightarrow \text{Sto}) \rightarrow M ()$
 - Get operation. $g : M \text{ Sto}$
 - Monad transformers give us “interaction rules” by construction
- **Traces** represented by “resumption threads”
- **Domain separation** by associating different domains with different state monad transformers
- This approach unifies “security by design” with formal trace-based security models
 - Implementations directly in higher-order typed functional languages
 - Reason about system specs at the level of denotational semantics
 - Promise of the approach: Scalability/Modularity through monads & monad transformers

Monadic Event Systems

(a) *Multi-threading*

$R = \text{ResT } K$

$\xrightarrow{\text{scheduler, step}}$

$\xrightarrow{\text{run}}$

(b) *Kernel*

$K = \text{StateT } L (\text{StateT } H M)$

$\xrightarrow{\text{liftL}}$

$\xrightarrow{\text{liftH}}$

(c) *Separate Domains*

$Lo = \text{StateT } L M$

$Hi = \text{StateT } H M$

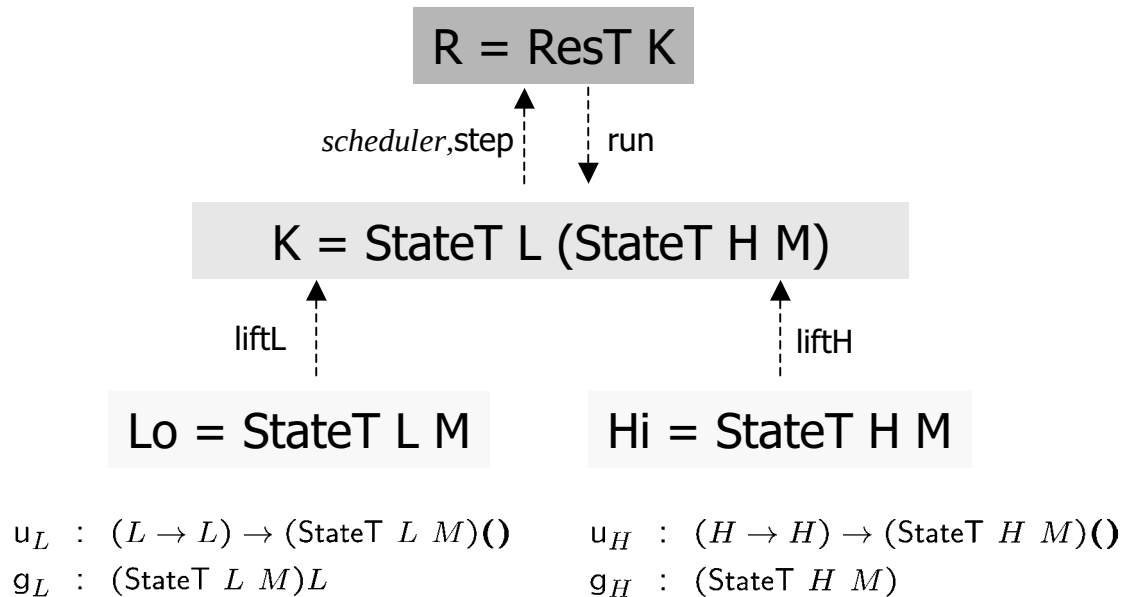
$u_L : (L \rightarrow L) \rightarrow (\text{StateT } L M)()$

$u_H : (H \rightarrow H) \rightarrow (\text{StateT } H M)()$

$g_L : (\text{StateT } L M)L$

$g_H : (\text{StateT } H M)$

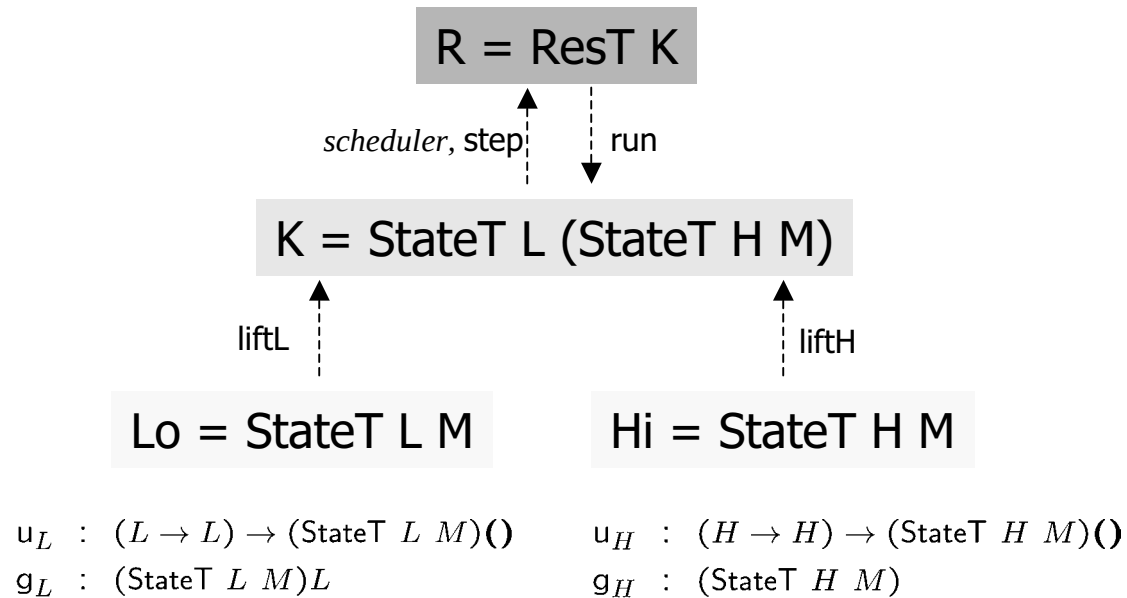
Monadic Event Systems



Properties "by construction"

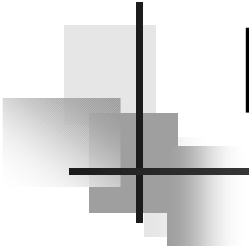
$$\begin{aligned} u f \star \lambda_. u g &= u (g \circ f) && \text{(sequencing)} \\ g \star \lambda\sigma_0. u (\lambda_. \sigma_0) &= \eta() && \text{(cancellation)} \end{aligned}$$

Monadic Event Systems (more “by construction” properties)



Interaction rules (aka “atomic non-interference”)

$$\text{liftL } (u_L \ f) \gg_K \text{liftH } (u_H \ g) = \text{liftH } (u_H \ g) \gg_K \text{liftL } (u_L \ f)$$



Language of behaviors *Beh*

Abstract Syntax for the Behavior Language.

$$\begin{aligned} Beh \quad ::= \quad & Var := Exp \mid \\ & skip \mid \\ & Beh; Beh \mid \\ & ite \ Exp \ Beh \ Beh \mid \\ & while \ Exp \ do \ Beh \end{aligned}$$
$$Exp \quad ::= \quad Var \mid Integer$$

Basic Separation

- Refine monad transformer to reflect separation:

$$\begin{aligned}\text{ResT } M a &= \mu R. D a + P_{\text{Lo}}(M(R a)) + P_{\text{Hi}}(M(R a)) \\ \text{stepL} &: M a \rightarrow \text{ResT } M a \\ \text{stepH} &: M a \rightarrow \text{ResT } M a \\ \text{stepL } \varphi &= P_{\text{Lo}}(\varphi \star_M \lambda v. \eta_M(Dv)) \\ \text{stepH } \varphi &= P_{\text{Hi}}(\varphi \star_M \lambda v. \eta_M(Dv))\end{aligned}$$

- Create “security conscious” semantics

$$\text{evL} : \text{Beh} \rightarrow R ()$$

$$\text{evH} : \text{Beh} \rightarrow R ()$$

$$\text{evL } (x:=1) = \text{stepL } ((\text{liftL} \circ u_L)[x \mapsto 1])$$

$$\text{evH } (x:=1) = \text{stepH } ((\text{liftH} \circ u_H)[x \mapsto 1])$$

Create two schedulers

Schedule **with**
Hi & Lo events

$withHi : Beh \rightarrow Beh \rightarrow R()$
 $withHi\ lo\ hi = weave\ (evL\ lo)\ (evH\ hi)$

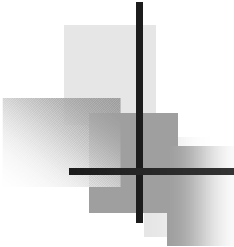
$weave : R() \rightarrow R() \rightarrow R()$
 $weave\ [l_0, l_1, \dots]\ [h_0, h_1, \dots] = [l_0, h_0, l_1, h_1, \dots]$

Schedule **without**
Hi & Lo events

$withoutHi : Beh \rightarrow R()$
 $withoutHi\ lo = evL\ lo$

$takeLo : Integer \rightarrow R() \rightarrow R()$
 $takeLo\ n\ [l_0, h_0, \dots, l_n, \dots] = [l_0, \dots, l_n]$

$run : Ra \rightarrow Ka$
 $run\ [e_0, e_1, \dots] = e_0 \gg_K e_1 \gg_K \dots$



Security property

Theorem 5 (Take Separation)

Let $lo, hi \in Beh$, then for all natural numbers n ,

$$\begin{aligned} run (takeLo\ n\ (withoutHi\ (evL\ lo))) &\gg_K maskHi \\ &= run (takeLo\ n\ (withHi\ (evL\ lo)\ (evH\ hi))) \gg_K maskHi \end{aligned}$$

where

$$maskHi = liftHi(u_H\ (\lambda_.h_0))$$

for fixed $h_0 \in H$.

Proof Sketch

To show:

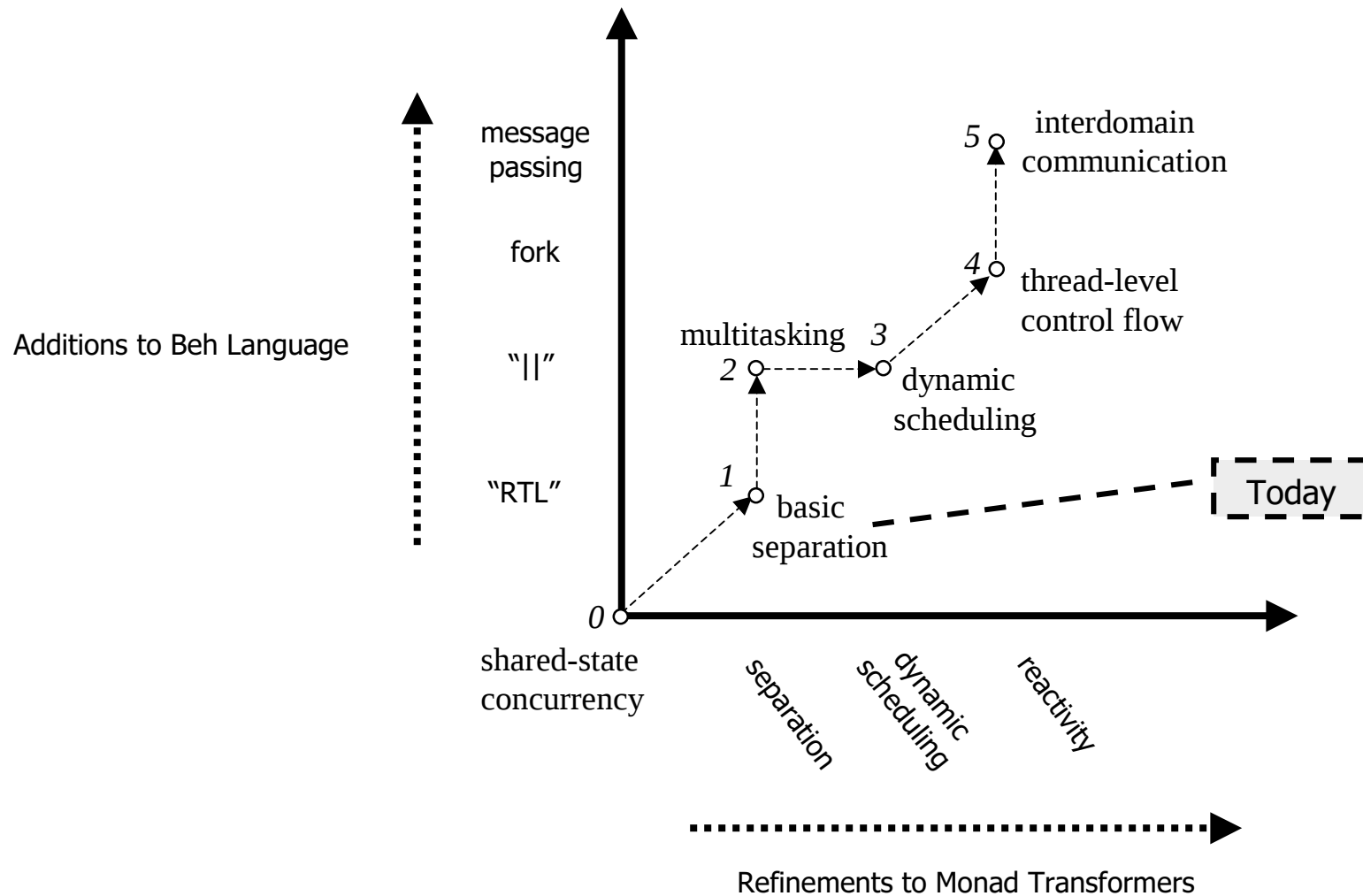
$$\begin{aligned} & \text{run } (\text{takeLo } n \text{ } (\text{withoutHi } (\text{evL } lo))) \gg_K \text{ maskHi} \\ &= \text{run } (\text{takeLo } n \text{ } (\text{withHi } (\text{evL } lo) \text{ } (\text{evH } hi)))) \gg_K \text{ maskHi} \end{aligned}$$

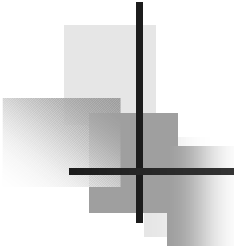
Follows from sequencing, atomic non-inter., and monad laws

$$\begin{aligned} & (l_1 \gg h_1 \gg \dots \gg l_{(k+1)} \gg h_{(k+1)} \gg \eta()) \gg \text{maskHi} \\ & \quad \{\text{sequencing}\} \quad = l_1 \gg h_1 \gg \dots \gg l_{(k+1)} \gg \text{maskHi} \\ & \quad \{l_{(k+1)} \# \text{maskHi}\} \quad = l_1 \gg h_1 \gg \dots \gg \text{maskHi} \gg l_{(k+1)} \\ & \quad \{\text{ind. hyp.}\} \quad = \underbrace{l_1 \gg \dots}_{h_i \text{ excised}} \gg \text{maskHi} \gg l_{(k+1)} \\ & \quad \{l_i \# \text{maskHi}\} \quad = l_1 \gg \dots \gg l_{(k+1)} \gg \text{maskHi} \end{aligned}$$

* (x # y) means x,y are atomically non-interfering.

Enhancing system by refining the underlying monads





Domain Separation by Construction

- Our approach unifies “security by design” with formal trace-based security models
 - Implementations directly in higher-order typed functional languages
 - Reason about systems at the level of denotational semantics
- Promise of the approach: Scalability/Modularity of systems & their verifications through monads
 - Monads provide an algebraic theory of effects useful in formal specification & verification
 - Verification promoted via “by construction” properties of monads
 - System development through refinement to underlying monads
 - Cost of re-verification of a refined system can be minimal