

# 10-301/601: Introduction to Machine Learning

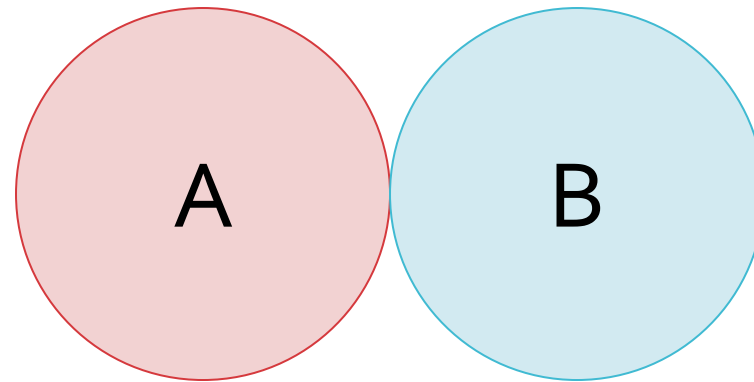
## Lecture 18 – Learning Theory (Infinite Case)

Henry Chai

5/28/25

## The Union Bound...

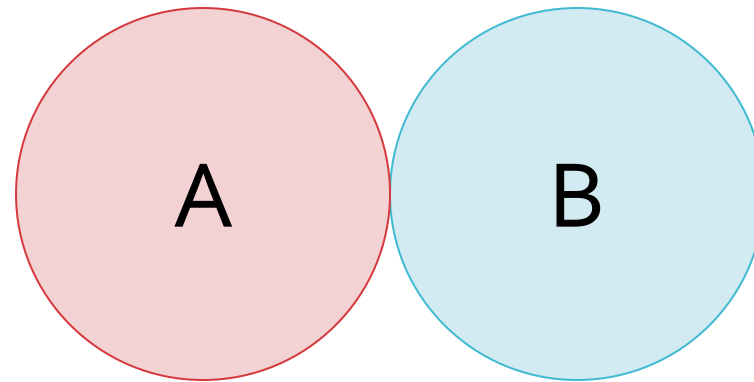
$$P\{A \cup B\} \leq P\{A\} + P\{B\}$$



# The Union Bound is Bad!

$$P\{A \cup B\} \leq P\{A\} + P\{B\}$$

$$P\{A \cup B\} = P\{A\} + P\{B\} - P\{A \cap B\}$$

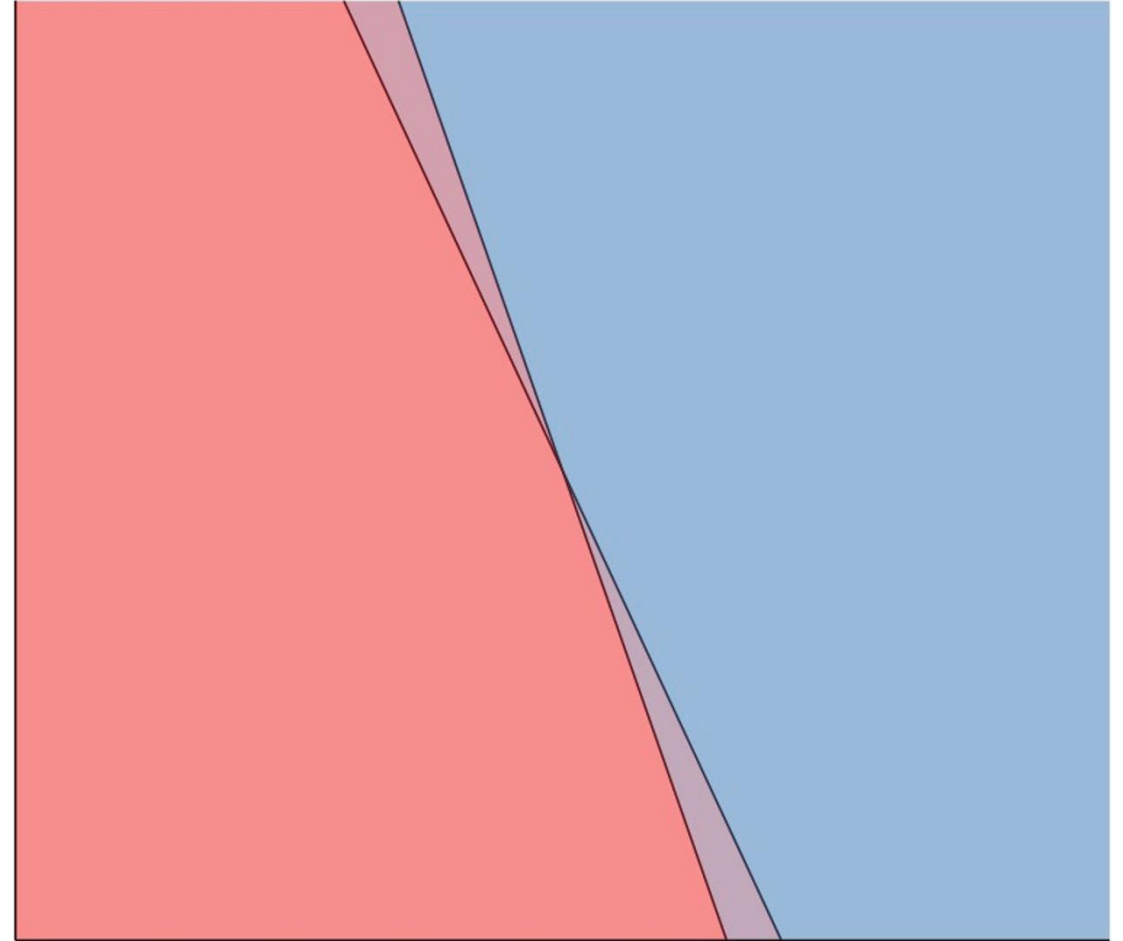


# Intuition

If two hypotheses  $h_1, h_2 \in \mathcal{H}$  are very similar, then the events

- “ $h_1$  is consistent with the first  $m$  training data points”
- “ $h_2$  is consistent with the first  $m$  training data points”

will overlap a lot!

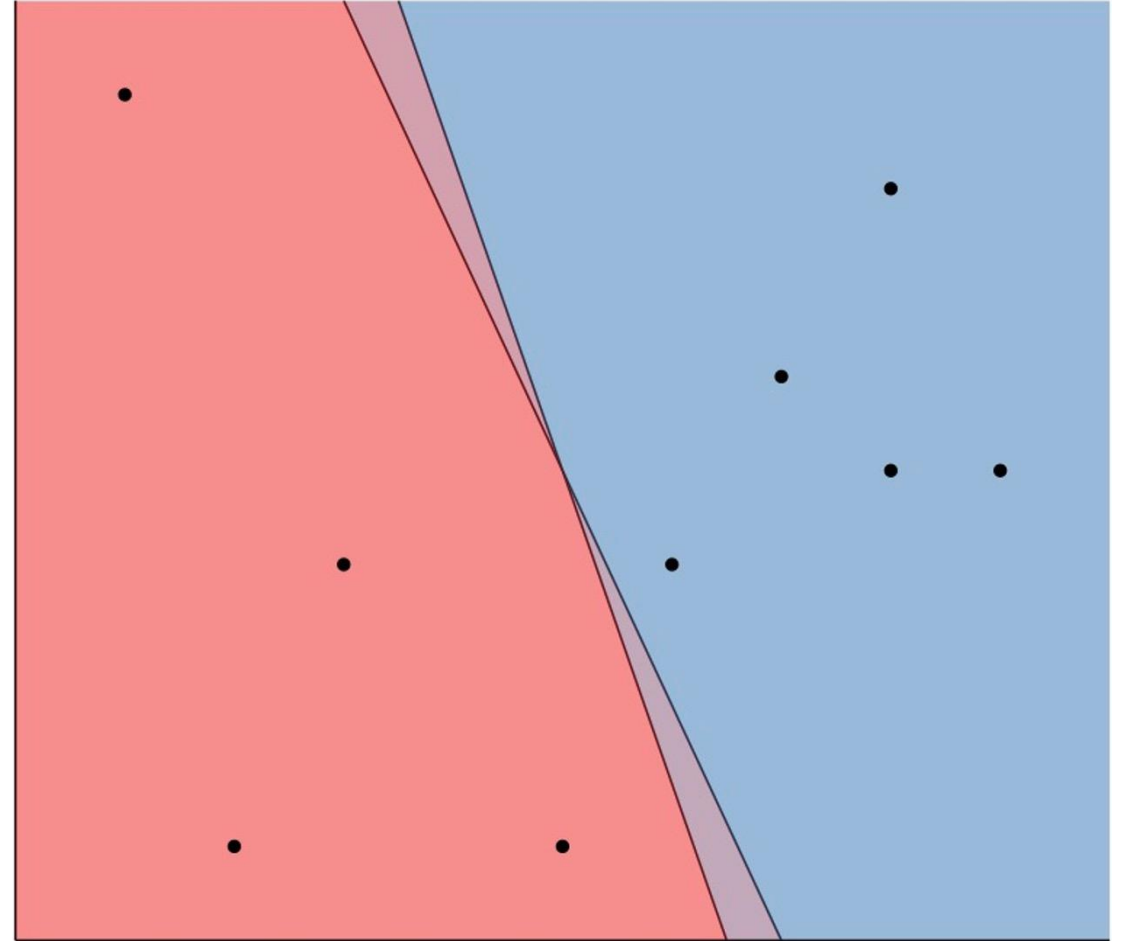


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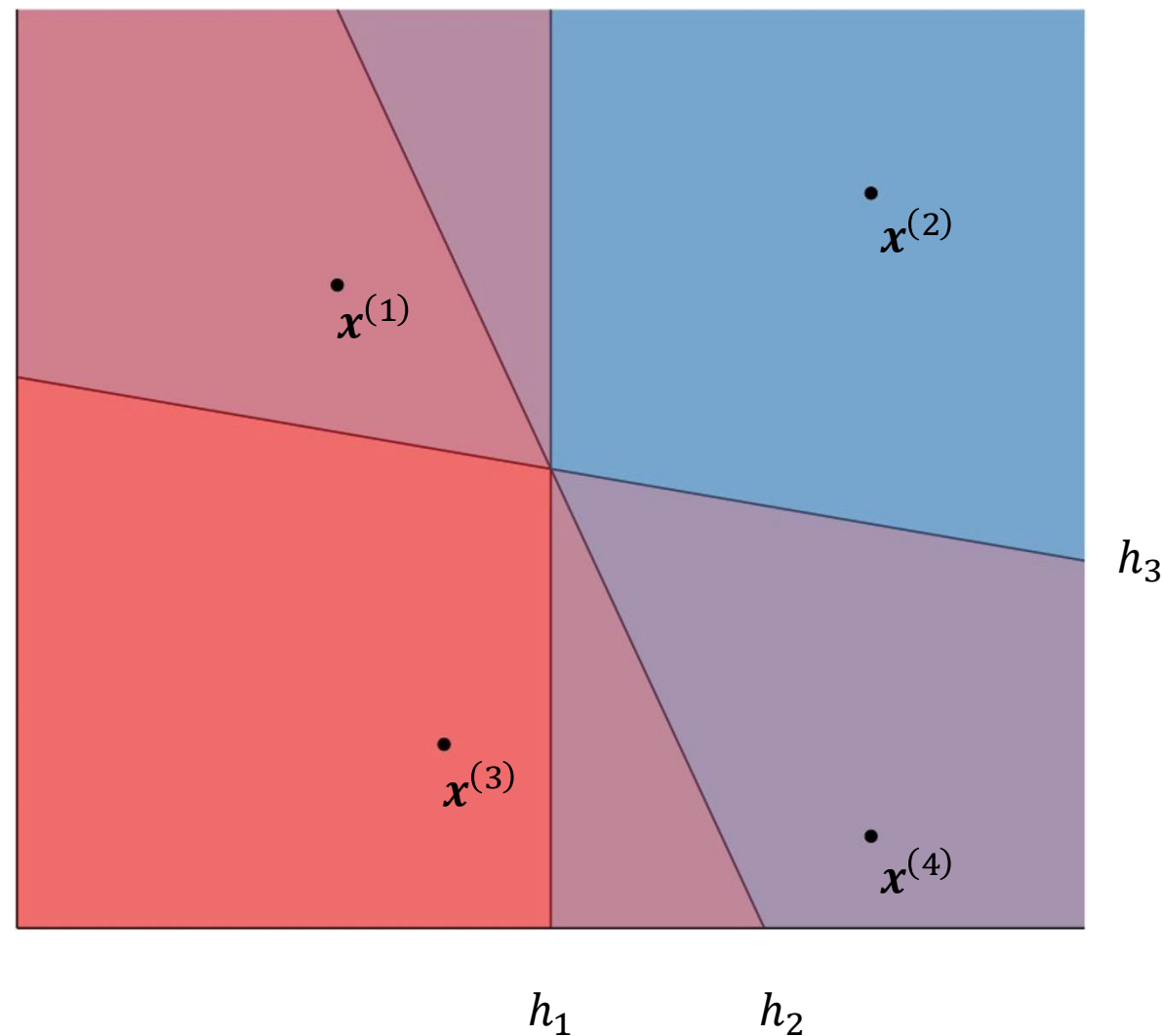


# Labellings

- Given some finite set of data points  $S = (\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(M)})$  and some hypothesis  $h \in \mathcal{H}$ , applying  $h$  to each point in  $S$  results in a labelling
  - $(h(\mathbf{x}^{(1)}), \dots, h(\mathbf{x}^{(M)}))$  is a vector of  $M$  +1's and -1's
- Given  $S = (\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(M)})$ , each hypothesis in  $\mathcal{H}$  induces a labelling but not necessarily a unique labelling
  - The set of labellings induced by  $\mathcal{H}$  on  $S$  is
$$\mathcal{H}(S) = \left\{ \left( h(\mathbf{x}^{(1)}), \dots, h(\mathbf{x}^{(M)}) \right) \mid h \in \mathcal{H} \right\}$$

# Example: Labellings

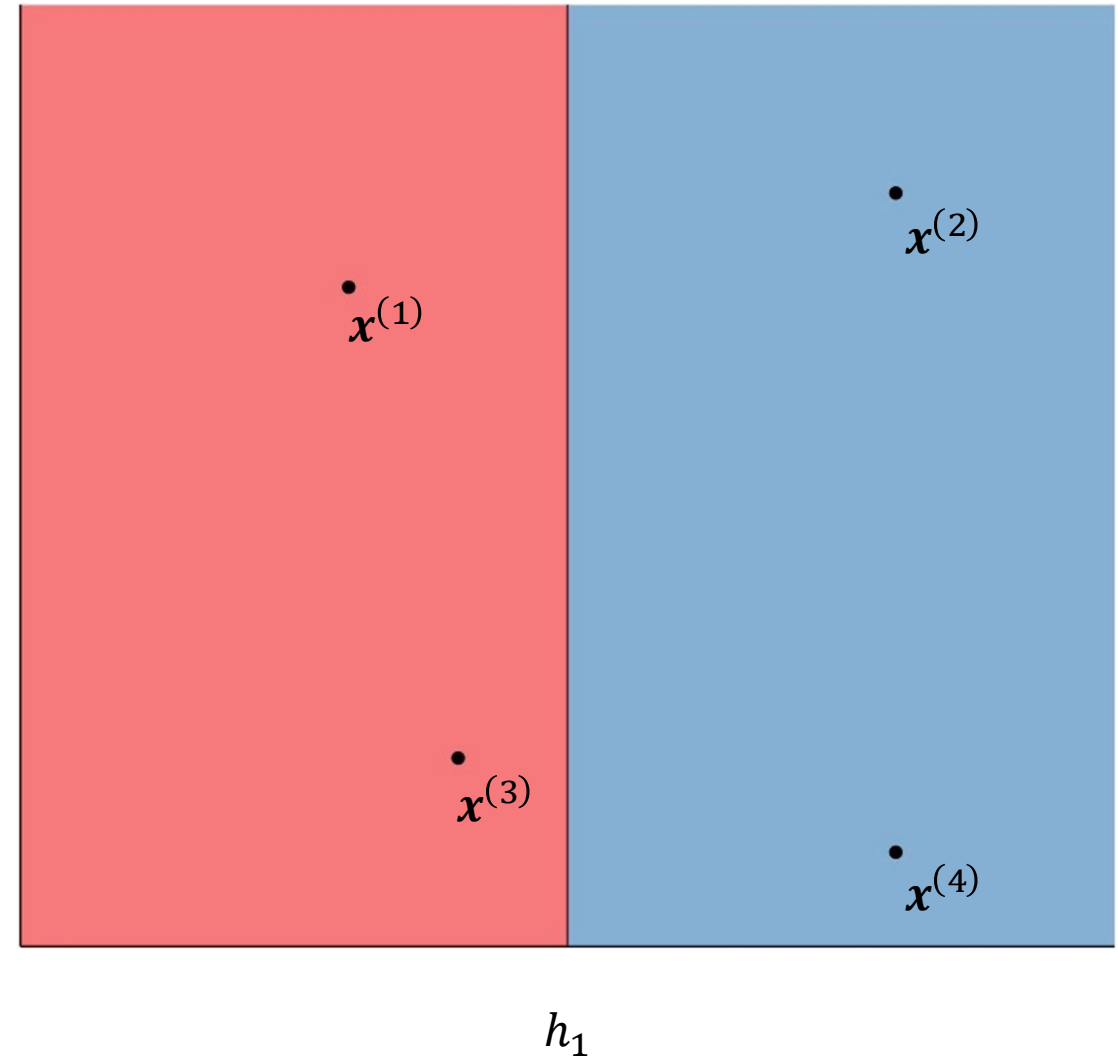
$$\mathcal{H} = \{h_1, h_2, h_3\}$$



# Example: Labellings

$$\mathcal{H} = \{h_1, h_2, h_3\}$$

$$\begin{aligned} & \left( h_1(\mathbf{x}^{(1)}), h_1(\mathbf{x}^{(2)}), h_1(\mathbf{x}^{(3)}), h_1(\mathbf{x}^{(4)}) \right) \\ &= (-1, +1, -1, +1) \end{aligned}$$

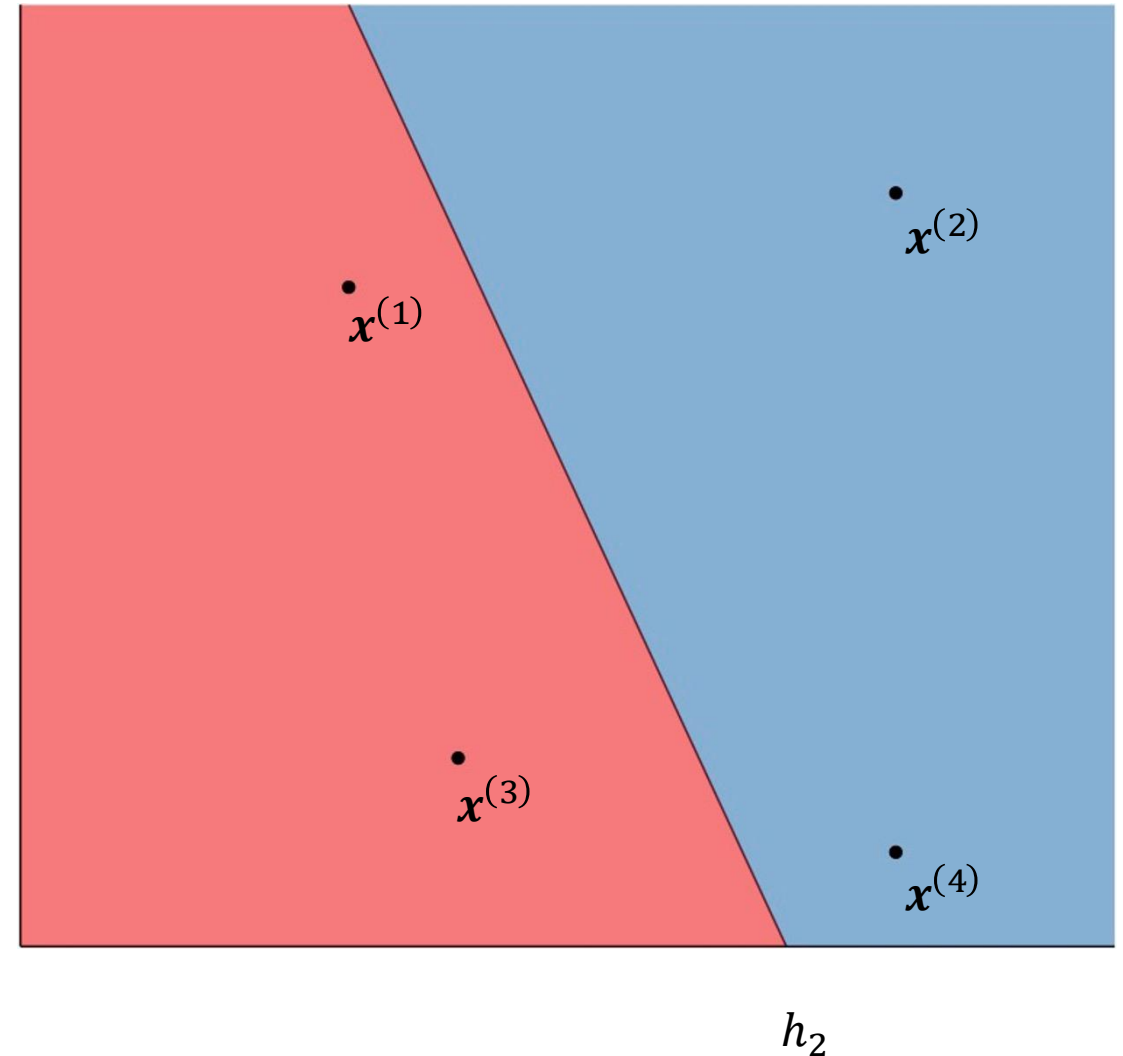




# Example: Labellings

$$\mathcal{H} = \{h_1, h_2, h_3\}$$

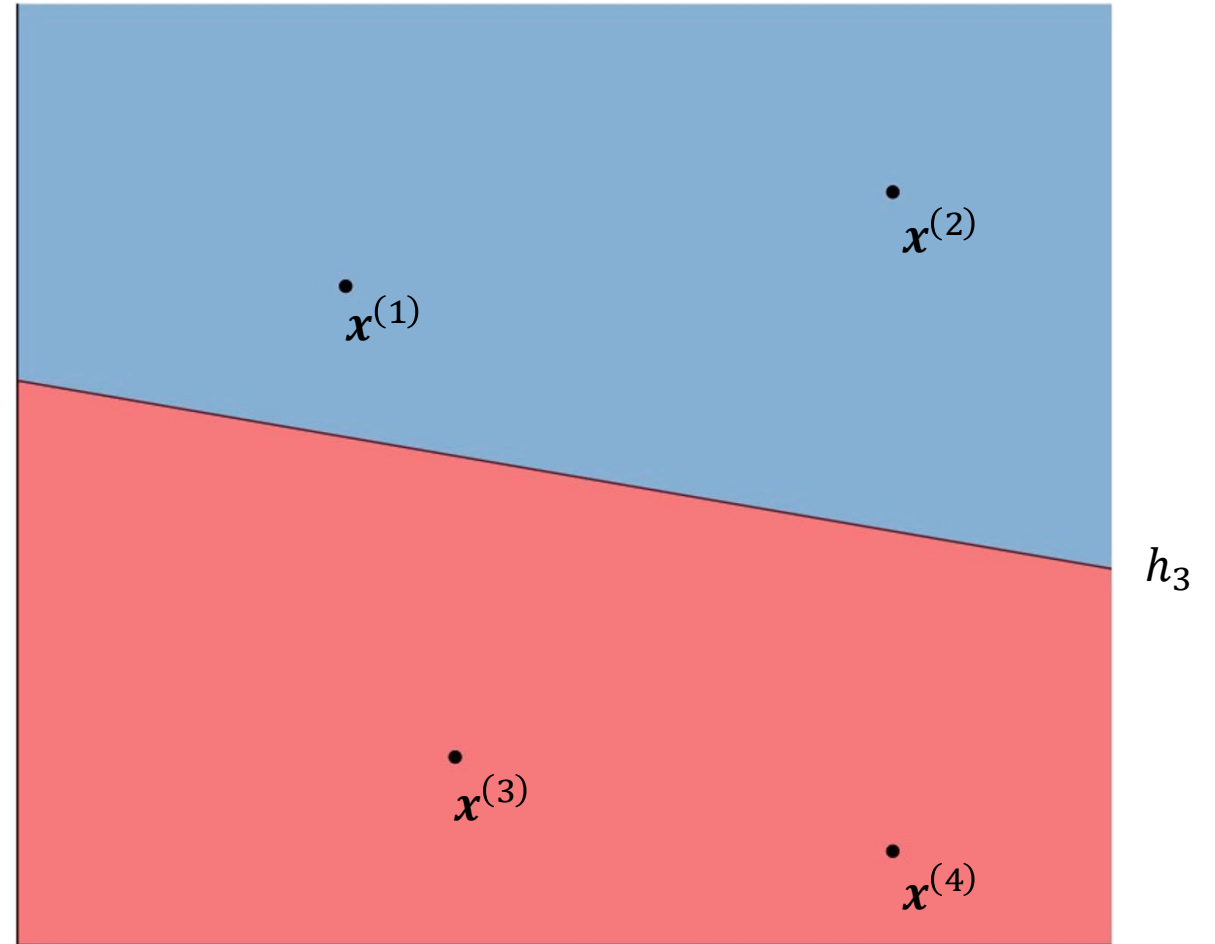
$$\begin{aligned} & \left( h_2(\mathbf{x}^{(1)}), h_2(\mathbf{x}^{(2)}), h_2(\mathbf{x}^{(3)}), h_2(\mathbf{x}^{(4)}) \right) \\ &= (-1, +1, -1, +1) \end{aligned}$$



# Example: Labellings

$$\mathcal{H} = \{h_1, h_2, h_3\}$$

$$\begin{aligned} & \left( h_3(\mathbf{x}^{(1)}), h_3(\mathbf{x}^{(2)}), h_3(\mathbf{x}^{(3)}), h_3(\mathbf{x}^{(4)}) \right) \\ &= (+1, +1, -1, -1) \end{aligned}$$

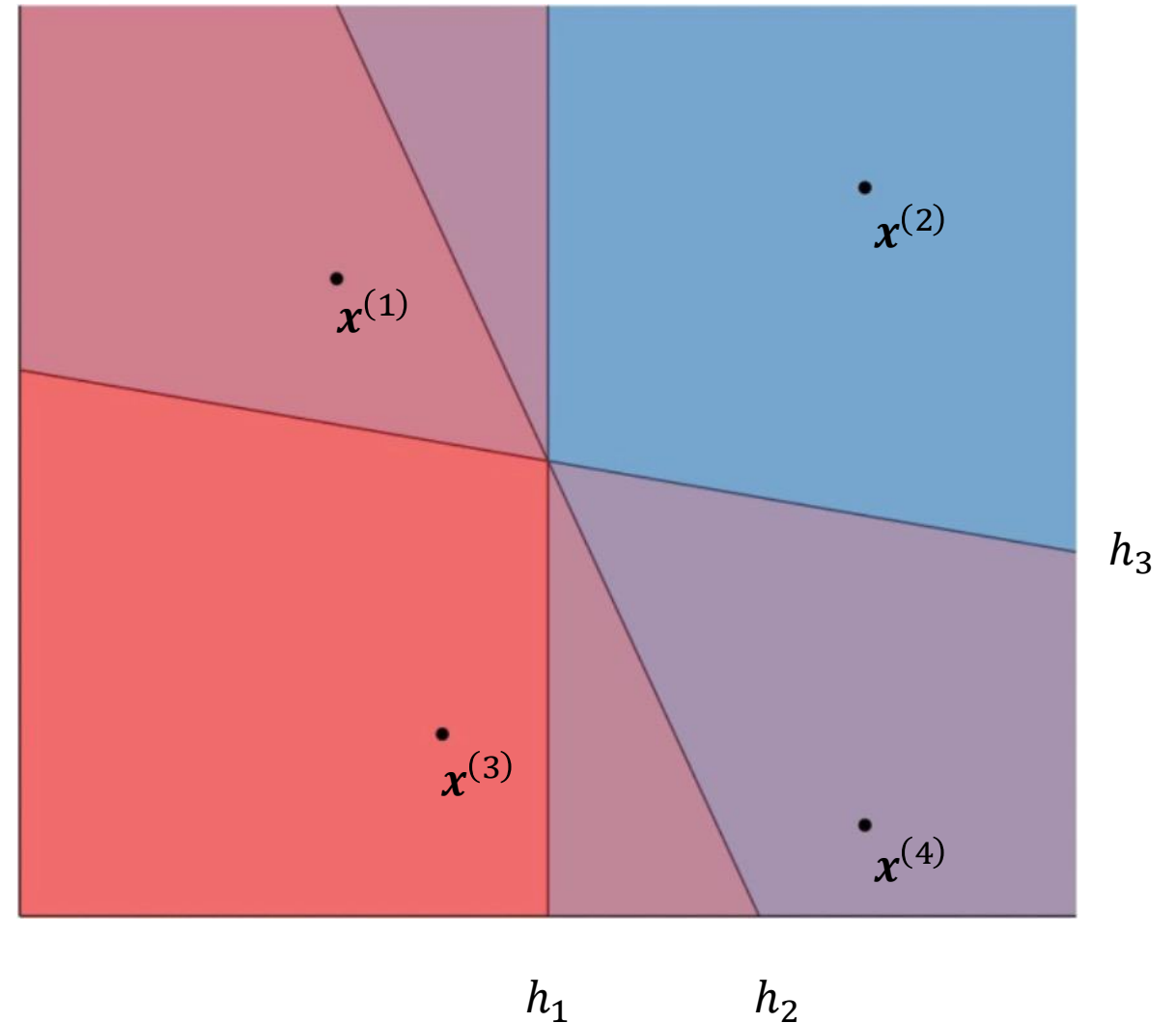


# Example: Labellings

$$\mathcal{H} = \{h_1, h_2, h_3\}$$

$$\mathcal{H}(S) = \{(+1, +1, -1, -1), (-1, +1, -1, +1)\}$$

$$|\mathcal{H}(S)| = 2$$

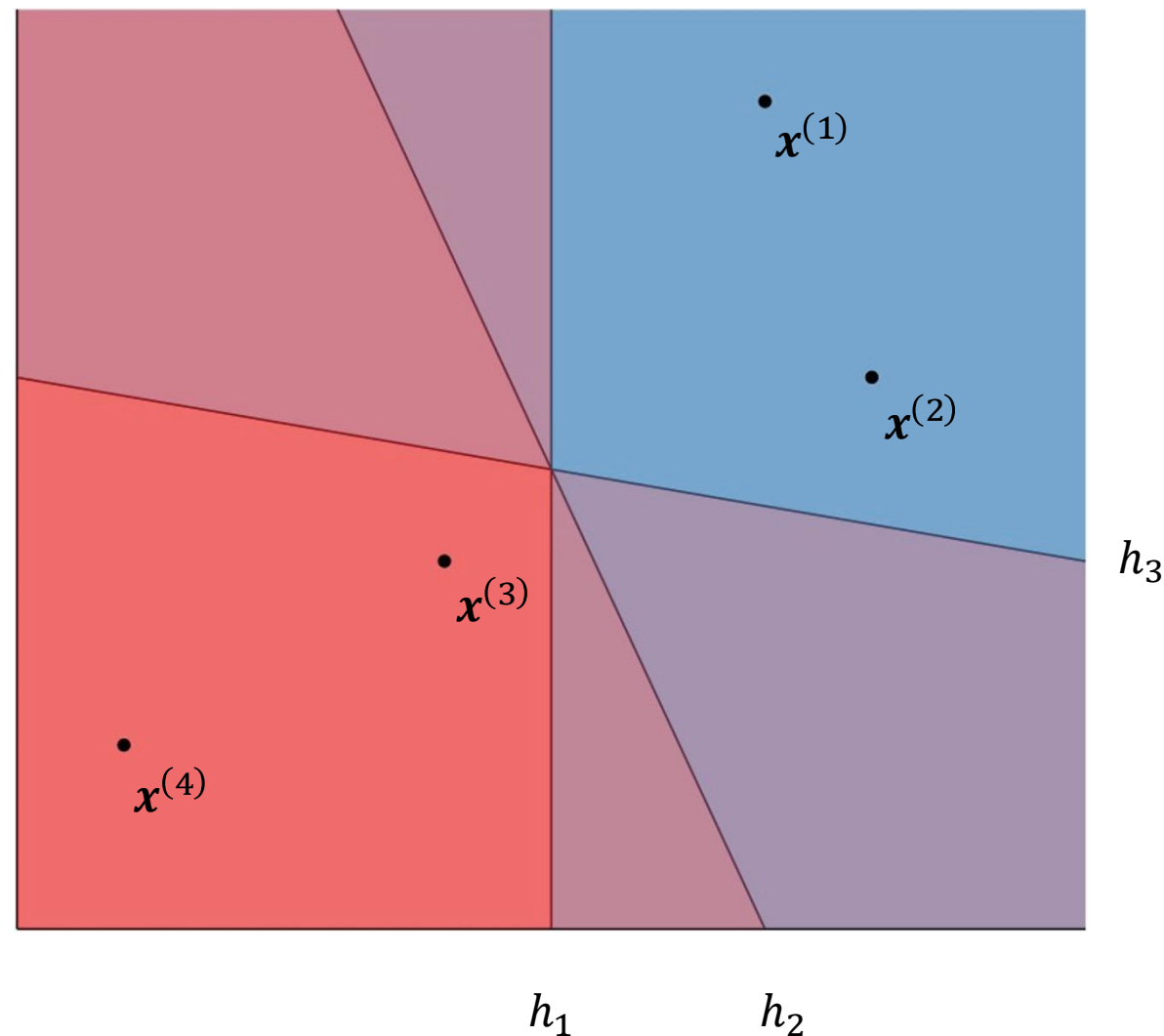


# Example: Labellings

$$\mathcal{H} = \{h_1, h_2, h_3\}$$

$$\mathcal{H}(S) = \{(+1, +1, -1, -1)\}$$

$$|\mathcal{H}(S)| = 1$$

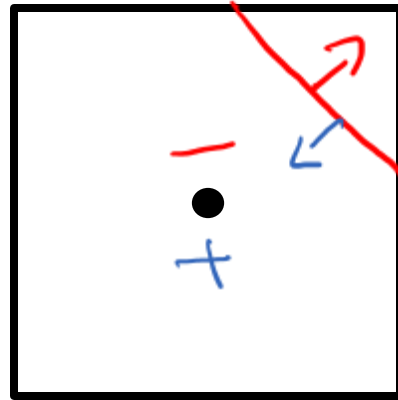


# VC-Dimension

- $\mathcal{H}(S)$  is the set of all labellings induced by  $\mathcal{H}$  on  $S$ 
  - If  $|S| = M$ , then  $|\mathcal{H}(S)| \leq 2^M$
  - $\mathcal{H}$  shatters  $S$  if  $|\mathcal{H}(S)| = 2^M$
- The VC-dimension of  $\mathcal{H}$ ,  $VC(\mathcal{H})$ , is the size of the largest set  $S$  that can be shattered by  $\mathcal{H}$ .
  - If  $\mathcal{H}$  can shatter arbitrarily large finite sets, then
$$VC(\mathcal{H}) = \infty$$
- To prove that  $VC(\mathcal{H}) = d$ , you need to show
  1.  $\exists$  some set of  $d$  data points that  $\mathcal{H}$  can shatter and
  2.  $\nexists$  a set of  $d + 1$  data points that  $\mathcal{H}$  can shatter

## VC-Dimension: Example

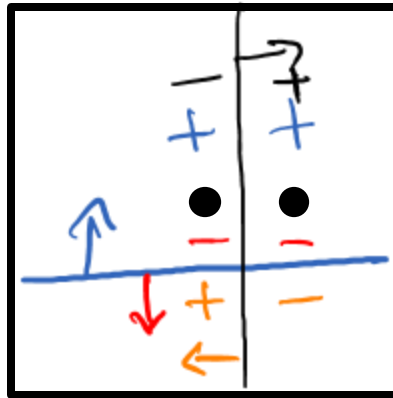
- $\mathbf{x} \in \mathbb{R}^2$  and  $\mathcal{H}$  = all 2-dimensional linear separators
- What is  $VC(\mathcal{H})$ ?
  - Can  $\mathcal{H}$  shatter some set of 1 point?



$S$

# VC-Dimension: Example

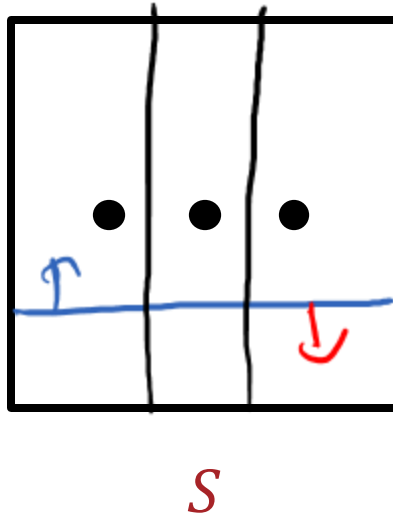
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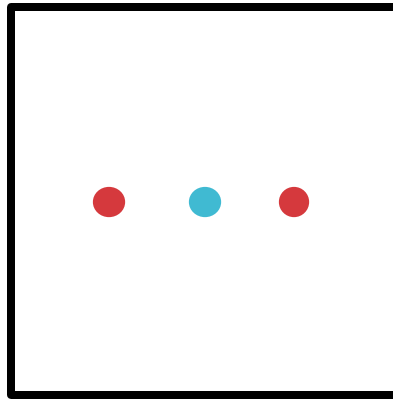
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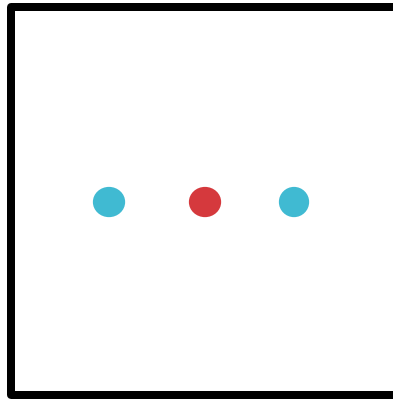
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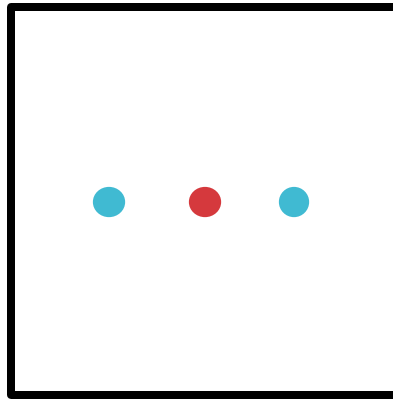
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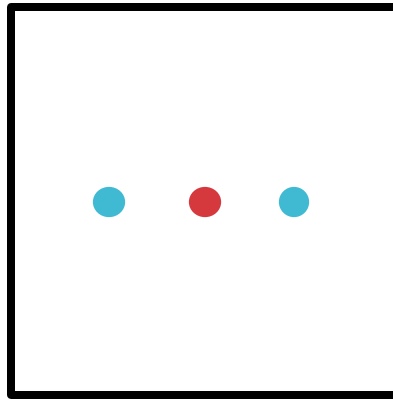
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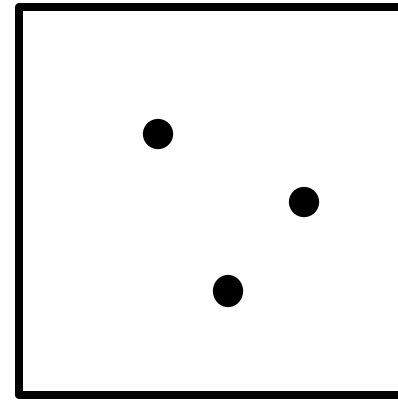
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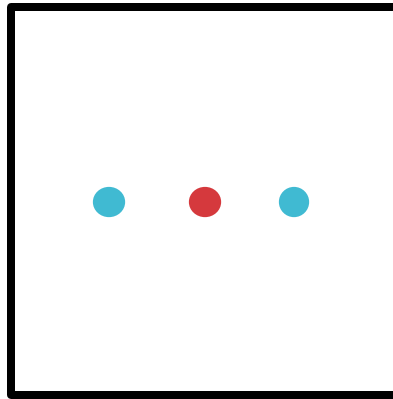
$S_1$



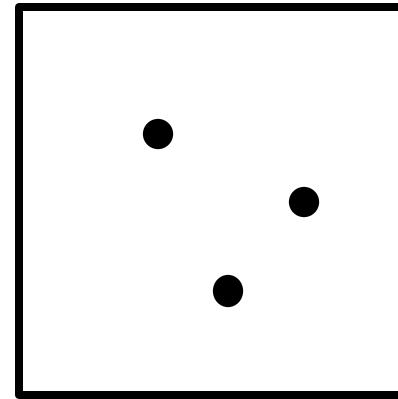
$S_2$

## VC-Dimension: Example

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- What is  $VC(\mathcal{H})$ ?
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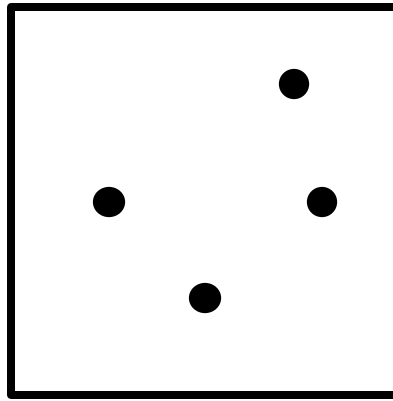
$$|\mathcal{H}(S_1)| = 6$$



$$|\mathcal{H}(S_2)| = 8$$

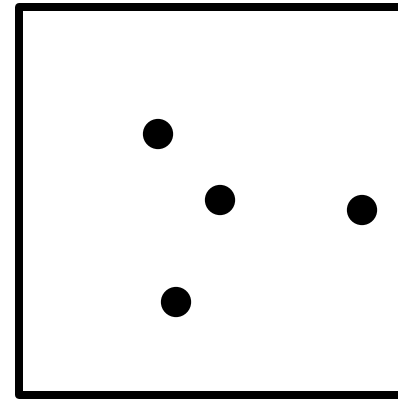
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$S_1$

All points on the  
convex hull

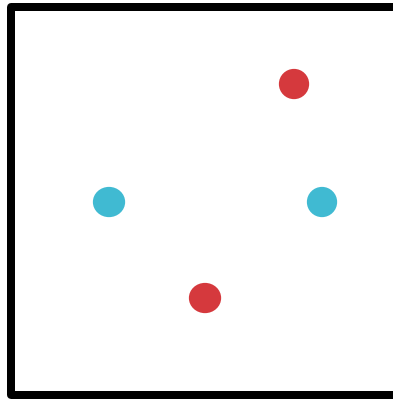


$S_2$

At least one point  
inside the convex hull

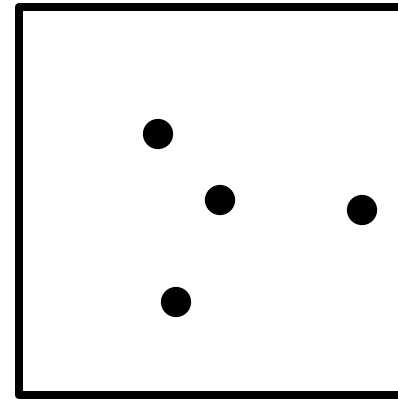
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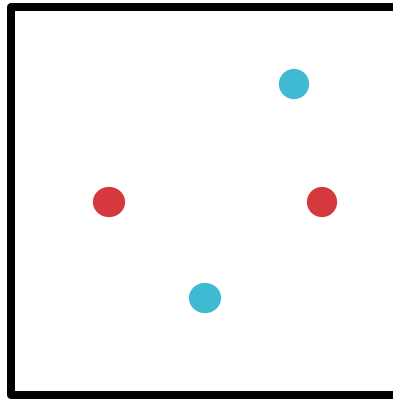


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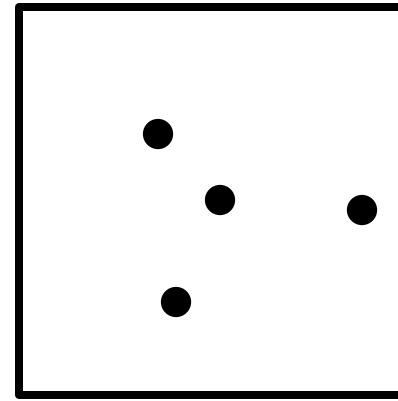
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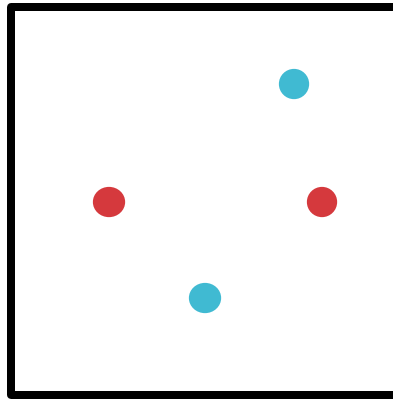
$S_2$

At least one point  
inside the convex hull



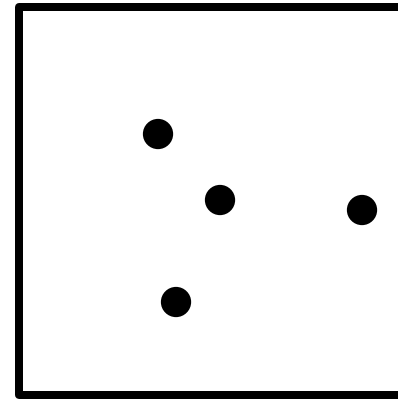
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$$|\mathcal{H}(S_1)| = 14$$

All points on the  
convex hull

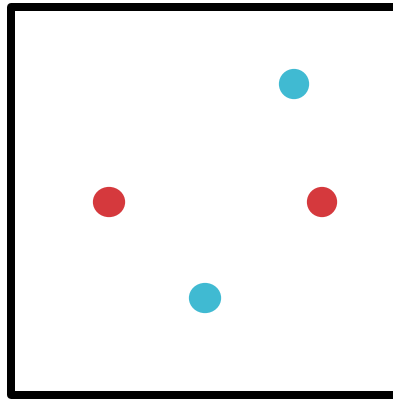


$S_2$

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inside the convex hull

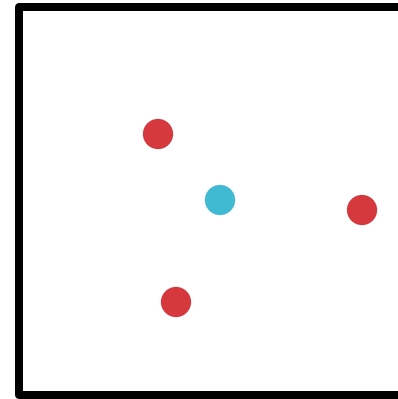
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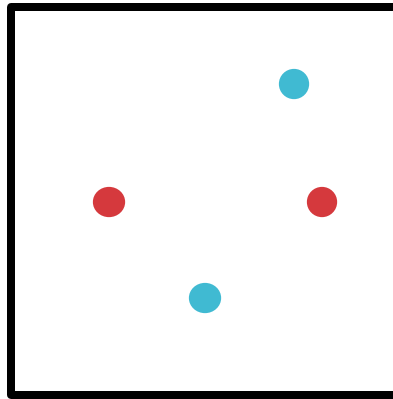


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At least one point  
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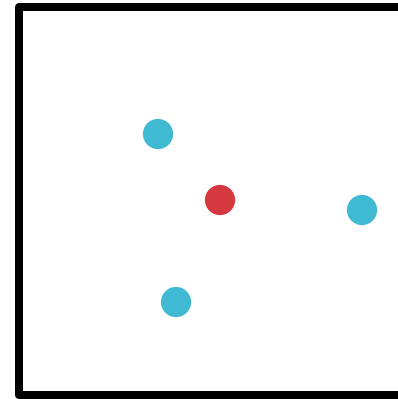
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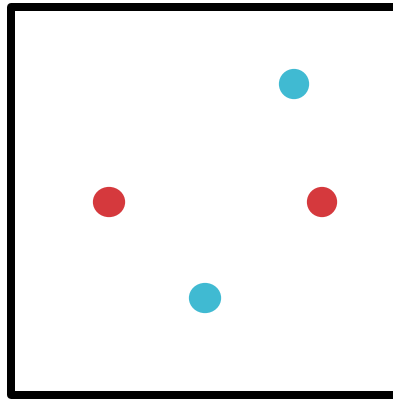


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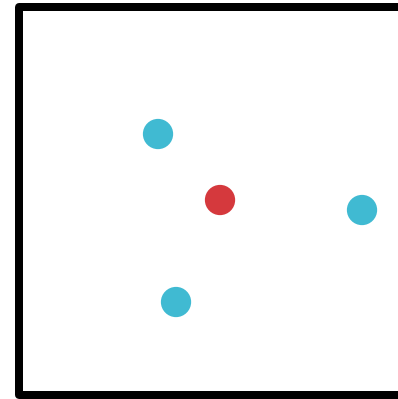
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$$|\mathcal{H}(S_1)| = 14$$

All points on the  
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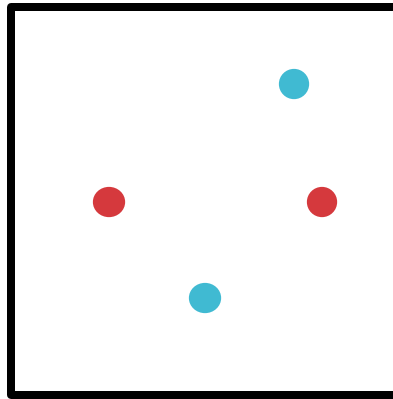


$$|\mathcal{H}(S_2)| = 14$$

At least one point  
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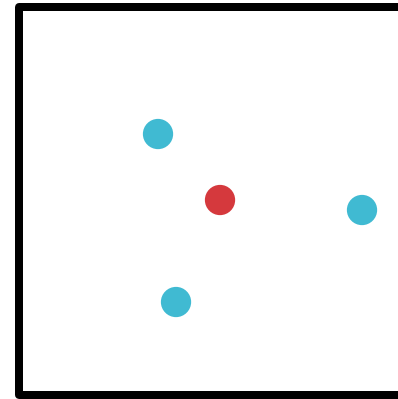
## VC-Dimension: Example

- $\mathbf{x} \in \mathbb{R}^2$  and  $\mathcal{H}$  = all 2-dimensional linear separators
- $VC(\mathcal{H}) = 3$ 
  - Can  $\mathcal{H}$  shatter some set of 1 point?
  - Can  $\mathcal{H}$  shatter some set of 2 points?
  - Can  $\mathcal{H}$  shatter some set of 3 points?
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$$|\mathcal{H}(S_1)| = 14$$

All points on the  
convex hull



$$|\mathcal{H}(S_2)| = 14$$

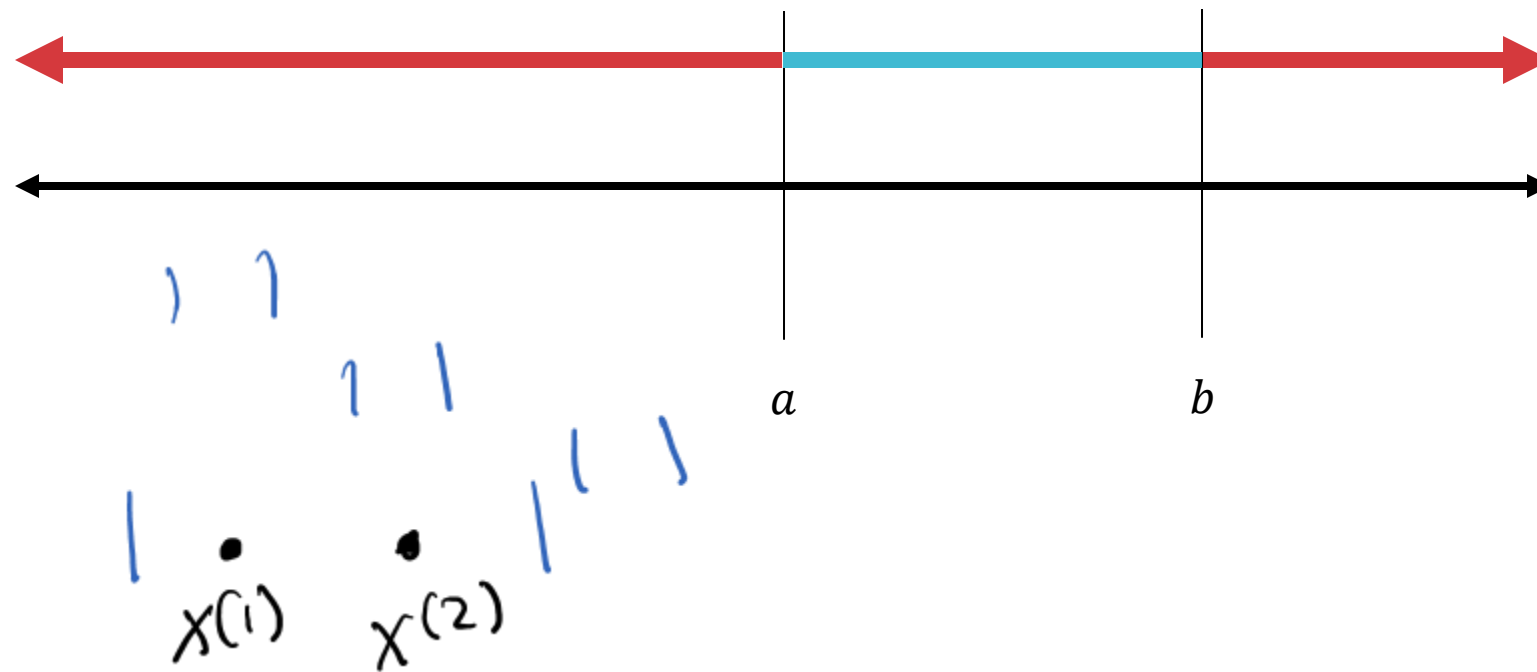
At least one point  
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## VC-Dimension: Example

- $x \in \mathbb{R}^d$  and  $\mathcal{H}$  = all  $d$ -dimensional linear separators
- $VC(\mathcal{H}) = d + 1$

## VC-Dimension: Example

- $x \in \mathbb{R}$  and  $\mathcal{H} =$  all 1-dimensional positive intervals



What is the VC-dimension of  $\mathcal{H} =$  all 1-dimensional positive intervals?

0

1

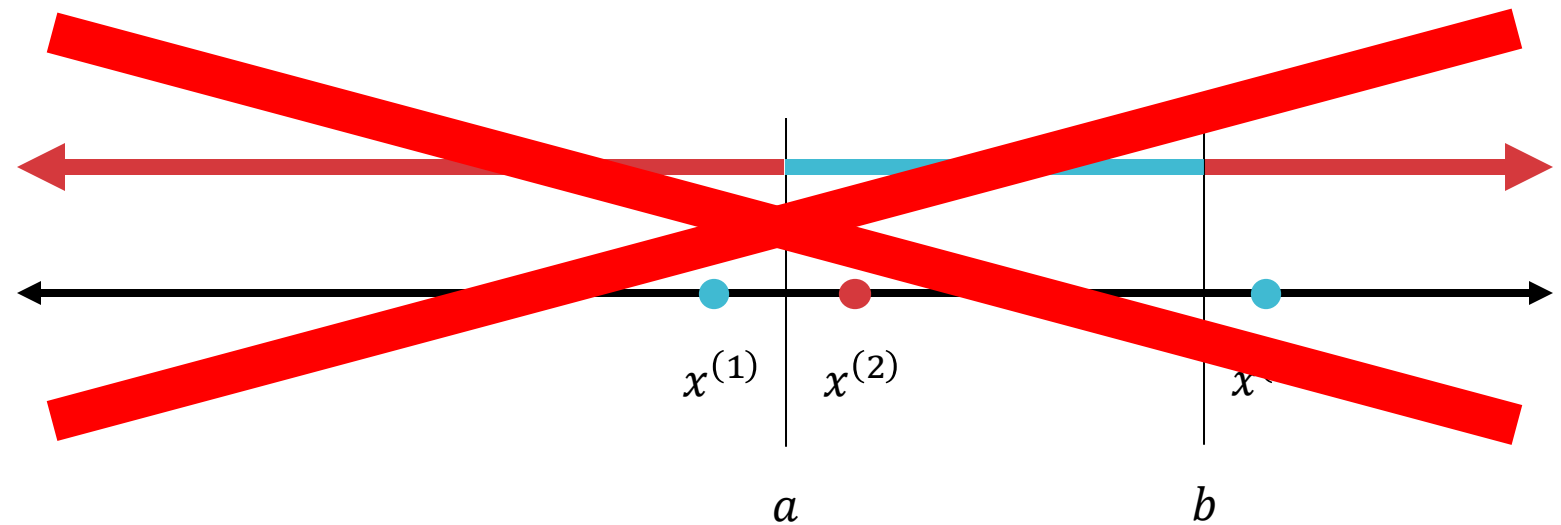
2

3



# VC-Dimension: Example

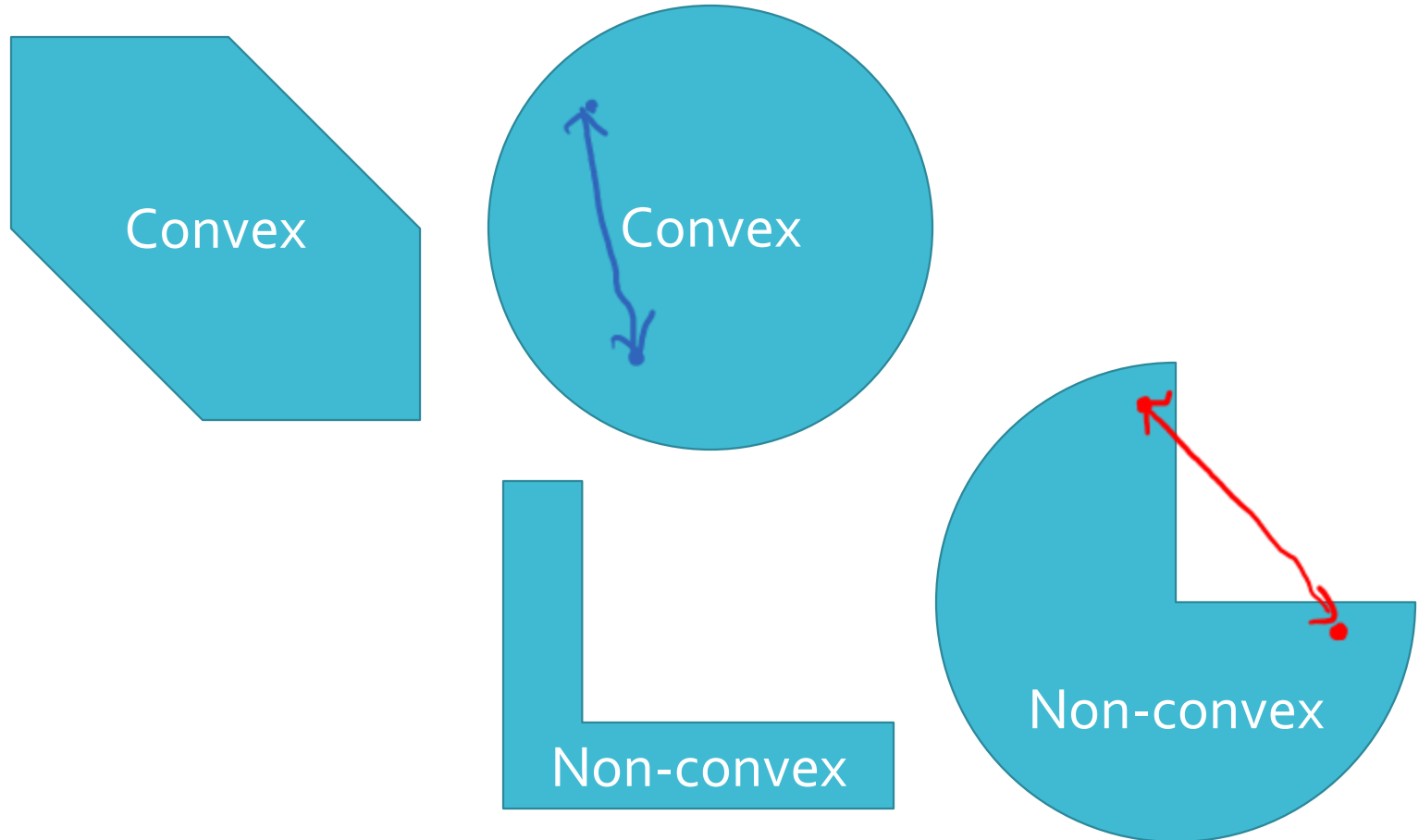
- $x \in \mathbb{R}$  and  $\mathcal{H} =$  all 1-dimensional positive intervals



- $VC(\mathcal{H}) = 2$

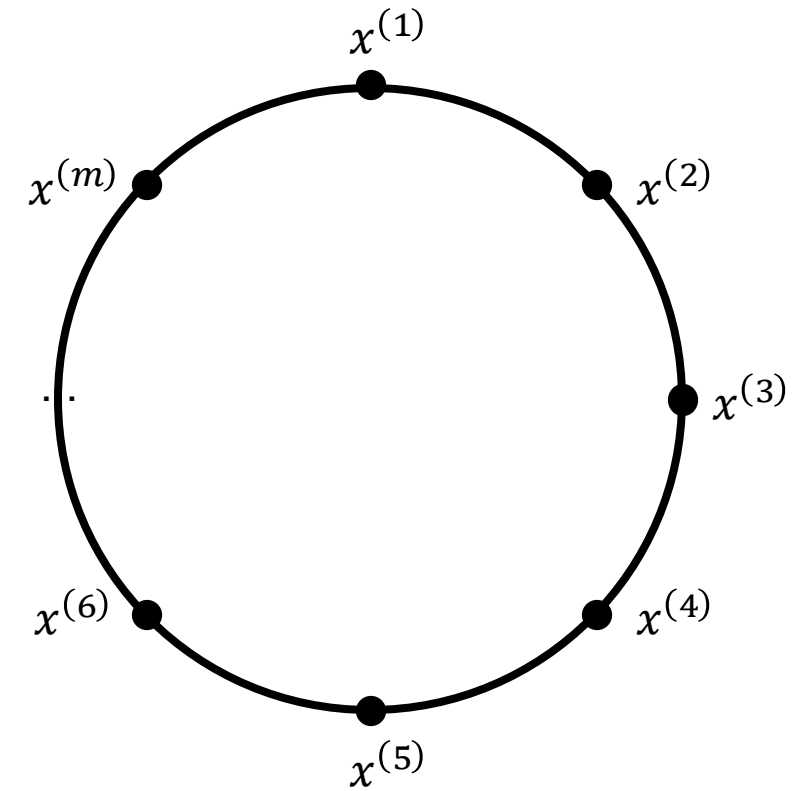
# VC-Dimension: Example

- $x^{(m)} \in \mathbb{R}^2$  and  $\mathcal{H} =$  all 2-dimensional positive convex sets



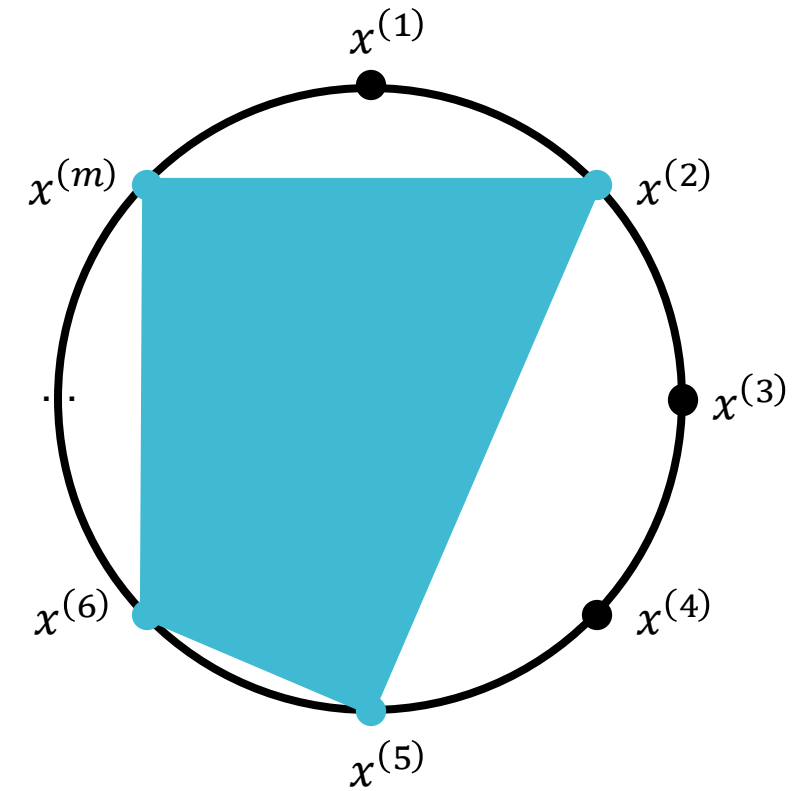
## VC-Dimension: Example

- $x^{(m)} \in \mathbb{R}^2$  and  $\mathcal{H} =$  all 2-dimensional positive convex sets
- What is  $d_{VC}(\mathcal{H})$ ?



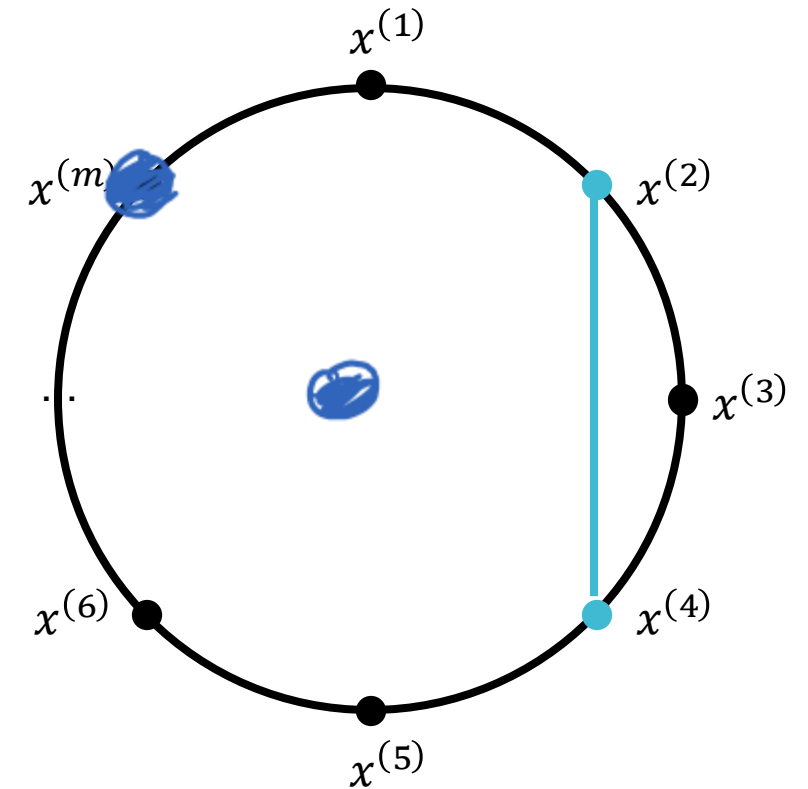
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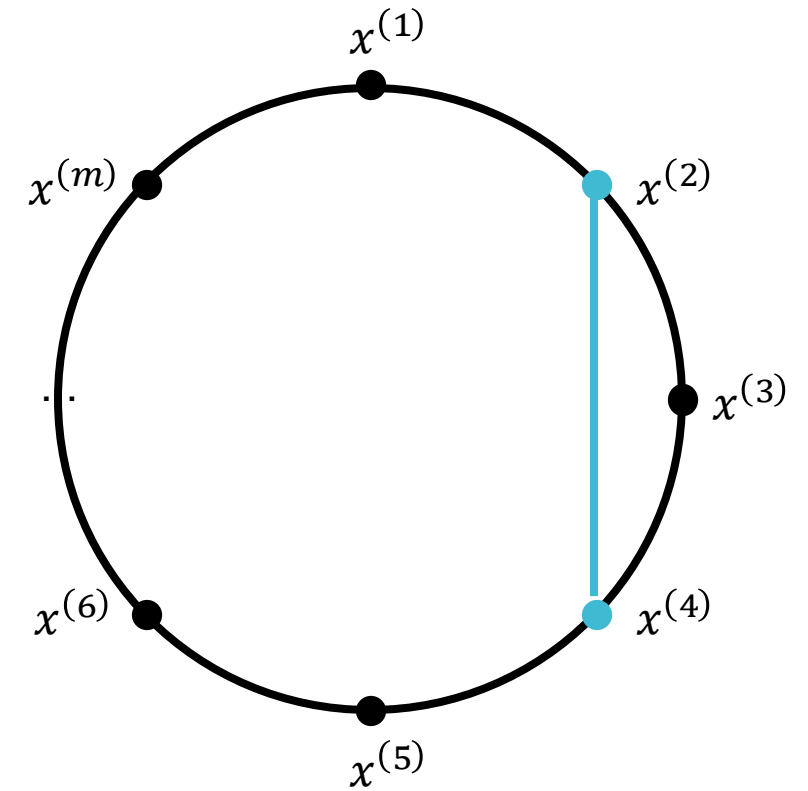
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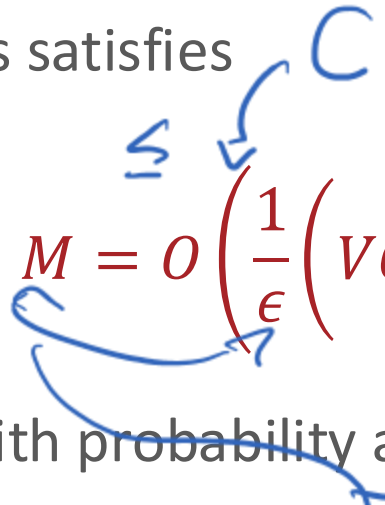
# VC-Dimension: Example

- $x^{(m)} \in \mathbb{R}^2$  and  $\mathcal{H} =$  all 2-dimensional positive convex sets
- $d_{VC}(\mathcal{H}) = \infty!$



## Theorem 3: Vapnik- Chervonenkis (VC)-Bound

- Infinite, realizable case: for any hypothesis set  $\mathcal{H}$  and distribution  $p^*$ , if the number of labelled training data points satisfies


$$M = O\left(\frac{1}{\epsilon}\left(VC(\mathcal{H})\log\left(\frac{1}{\epsilon}\right) + \log\left(\frac{1}{\delta}\right)\right)\right)$$

then with probability at least  $1 - \delta$ , all  $h \in \mathcal{H}$  with  $\hat{R}(h) = 0$  have  $R(h) \leq \epsilon$

# Statistical Learning Theory Corollary 3

- Infinite, realizable case: for any hypothesis set  $\mathcal{H}$  and distribution  $p^*$ , given a training data set  $S$  s.t.  $|S| = M$ , all  $h \in \mathcal{H}$  with  $\hat{R}(h) = 0$  have

$$R(h) \leq O\left(\frac{1}{M}\left(VC(\mathcal{H}) \log\left(\frac{M}{VC(\mathcal{H})}\right) + \log\left(\frac{1}{\delta}\right)\right)\right)$$

with probability at least  $1 - \delta$ .



## Theorem 4: Vapnik- Chervonenkis (VC)-Bound

- Infinite, agnostic case: for any hypothesis set  $\mathcal{H}$  and distribution  $p^*$ , if the number of labelled training data points satisfies

$$M = O\left(\frac{1}{\epsilon^2} \left(VC(\mathcal{H}) + \log\left(\frac{1}{\delta}\right)\right)\right)$$

then with probability at least  $1 - \delta$ , all  $h \in \mathcal{H}$  have

$$|R(h) - \hat{R}(h)| \leq \epsilon$$

$$|R(h) - \hat{R}(h)| \leq O\left(\sqrt{\frac{1}{M}(VC(\mathcal{H}) + \ln(1/\delta))}\right)$$
$$-O\left(\sqrt{\frac{1}{M}(VC(\mathcal{H}) + \ln(1/\delta))}\right) \leq R(h) - \hat{R}(h) \leq O\left(\sqrt{\frac{1}{M}(VC(\mathcal{H}) + \ln(1/\delta))}\right)$$

# Statistical Learning Theory Corollary 4

- Infinite, agnostic case: for any hypothesis set  $\mathcal{H}$  and distribution  $p^*$ , given a training data set  $S$  s.t.  $|S| = M$ , all  $h \in \mathcal{H}$  have

$$\leq R(h) \leq \hat{R}(h) + O\left(\sqrt{\frac{1}{M}\left(VC(\mathcal{H}) + \log\left(\frac{1}{\delta}\right)\right)}\right)$$

with probability at least  $1 - \delta$ .

# Approximation Generalization Tradeoff

How well does  
 $h$  generalize?

$$R(h) \leq \hat{R}(h) + O\left(\sqrt{\frac{1}{M} \left( VC(\mathcal{H}) + \log\left(\frac{1}{\delta}\right) \right)}\right)$$

How well does  $h$   
approximate  $c^*$ ?

# Approximation Generalization Tradeoff

$$R(h) \leq \underbrace{\hat{R}(h)}_{\substack{\text{Decreases as} \\ VC(\mathcal{H}) \text{ increases}}} + O\left(\underbrace{\sqrt{\frac{1}{M} \left( VC(\mathcal{H}) + \log\left(\frac{1}{\delta}\right) \right)}}_{\substack{\text{Increases as} \\ VC(\mathcal{H}) \text{ increases}}}\right)$$

# Key Takeaways

- For infinite hypothesis sets, use the VC-dimension (or the growth function) as a measure of complexity
  - Computing  $d_{VC}(\mathcal{H})$
  - Sample complexity and statistical learning theory style bounds using  $d_{VC}(\mathcal{H})$