

10-301/601: Introduction to Machine Learning

Lecture 10 – Logistic Regression

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6/4/24

Front Matter

- Announcements:
 - HW3 released 5/23, due 6/4 (today!) at 11:59 PM
 - HW4 released 6/4 (today!), due 6/11 at 11:59 PM
- Recommended Readings:
 - Murphy, [Chapters 8.1-8.3](#)

Recall: Probabilistic Learning

- Previously:
 - (Unknown) Target function, $c^*: \mathcal{X} \rightarrow \mathcal{Y}$
 - Classifier, $h: \mathcal{X} \rightarrow \mathcal{Y}$
 - Goal: find a classifier, h , that best approximates c^*
- Now:
 - (Unknown) Target *distribution*, $y \sim P^*(Y|\mathbf{x})$
 - Distribution, $P(Y|\mathbf{x})$
 - Goal: find a distribution, P , that best approximates P^*

Building a Probabilistic Classifier

- Define a decision rule
 - Given a test data point \mathbf{x}' , predict its label \hat{y} using the *posterior distribution* $P(Y = y|X = \mathbf{x}')$
 - Common choice: $\hat{y} = \underset{y}{\operatorname{argmax}} P(Y = y|X = \mathbf{x}')$
- Model the posterior distribution
 - Option 1 - Model $P(Y|X)$ directly as some function of X (today!)
 - Option 2 - Use Bayes' rule (later):

$$P(Y|X) = \frac{P(X|Y) P(Y)}{P(X)} \propto P(X|Y) P(Y)$$

Modelling the Posterior

- Suppose we have binary labels $y \in \{0,1\}$ and D -dimensional inputs $\mathbf{x} = [1, x_1, \dots, x_D]^T \in \mathbb{R}^{D+1}$

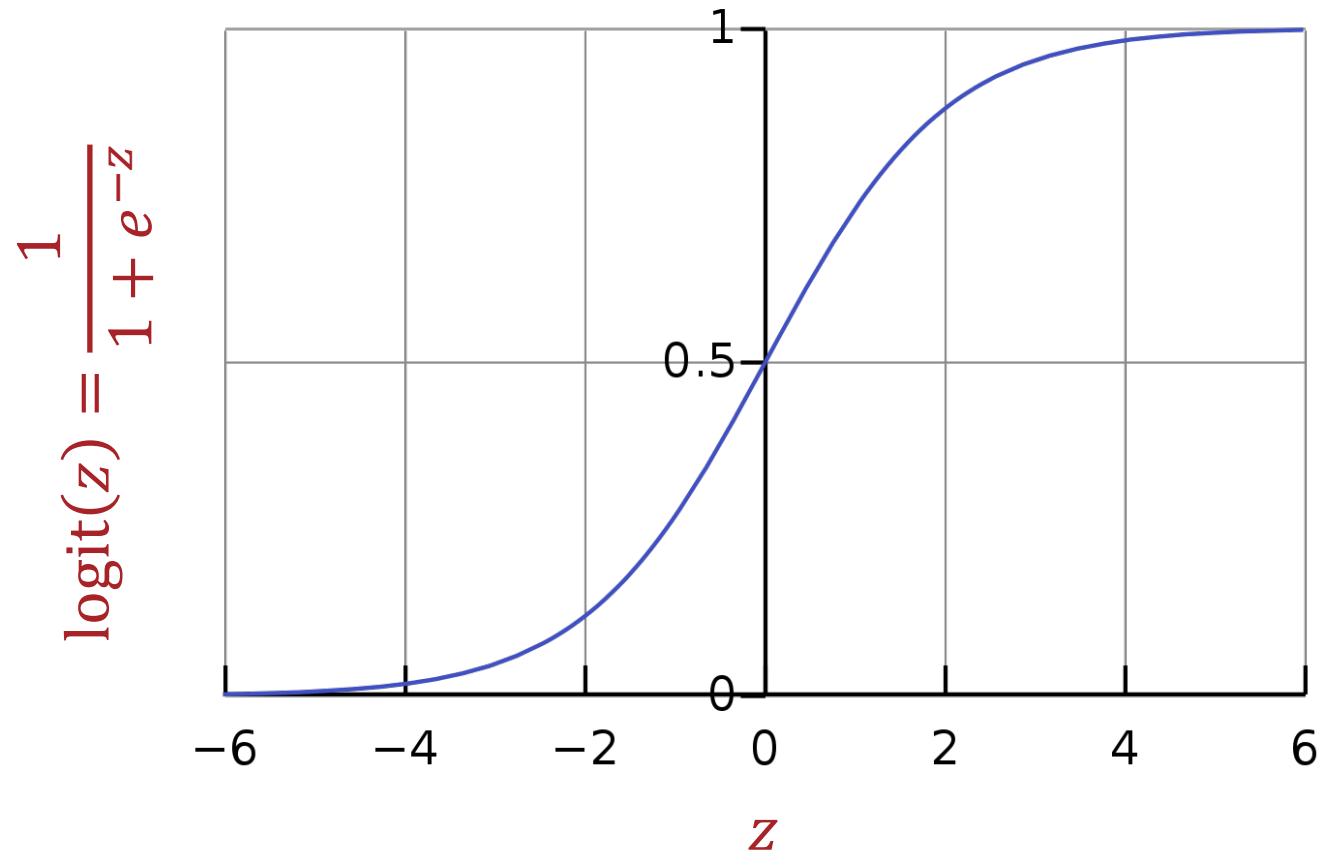
- **Assume**

$$\begin{aligned} P(Y = 1|\mathbf{x}) &= \text{logit}(\mathbf{w}^T \mathbf{x}) = \frac{1}{1 + \exp(-\mathbf{w}^T \mathbf{x})} \\ &= \frac{\exp(\mathbf{w}^T \mathbf{x})}{\exp(\mathbf{w}^T \mathbf{x}) + 1} \end{aligned}$$

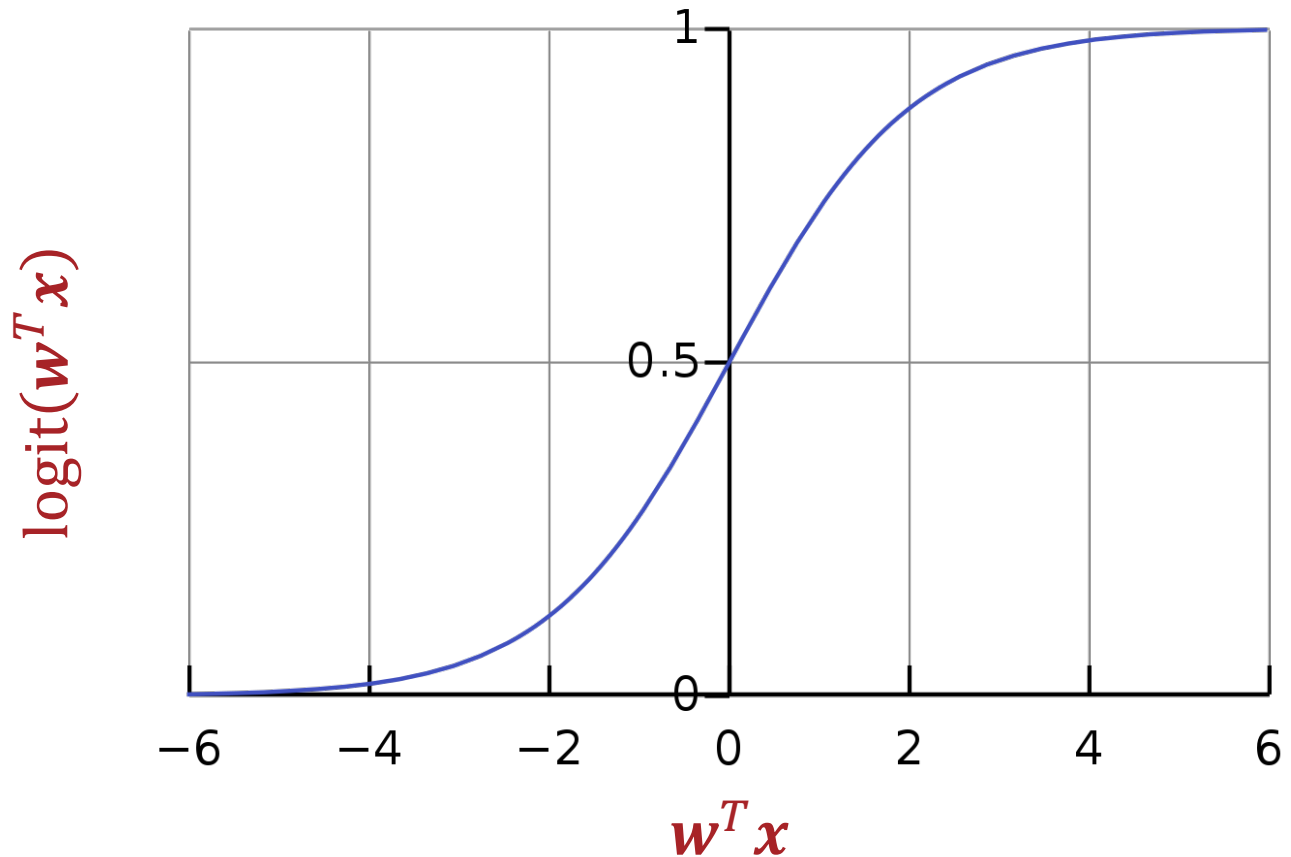
- This implies two useful facts:

1. $P(Y = 0|\mathbf{x}) = 1 - P(Y = 1|\mathbf{x}) = \frac{1}{\exp(\mathbf{w}^T \mathbf{x}) + 1}$
2. $\frac{P(Y = 1|\mathbf{x})}{P(Y = 0|\mathbf{x})} = \exp(\mathbf{w}^T \mathbf{x}) \rightarrow \log \frac{P(Y = 1|\mathbf{x})}{P(Y = 0|\mathbf{x})} = \mathbf{w}^T \mathbf{x}$

Logistic Function



Why use the Logistic Function?



- Differentiable everywhere
- $\text{logit}: \mathbb{R} \rightarrow [0, 1]$
- The decision boundary is linear in \mathbf{x} !

Logistic Regression Decision Boundary

$$\hat{y} = \begin{cases} 1 & \text{if } P(Y = 1|\mathbf{x}) \geq \frac{1}{2} \\ 0 & \text{otherwise} \end{cases}$$

$$P(Y = 1|\mathbf{x}) = \text{logit}(\mathbf{w}^T \mathbf{x}) = \frac{1}{1 + \exp(-\mathbf{w}^T \mathbf{x})} \geq \frac{1}{2}$$

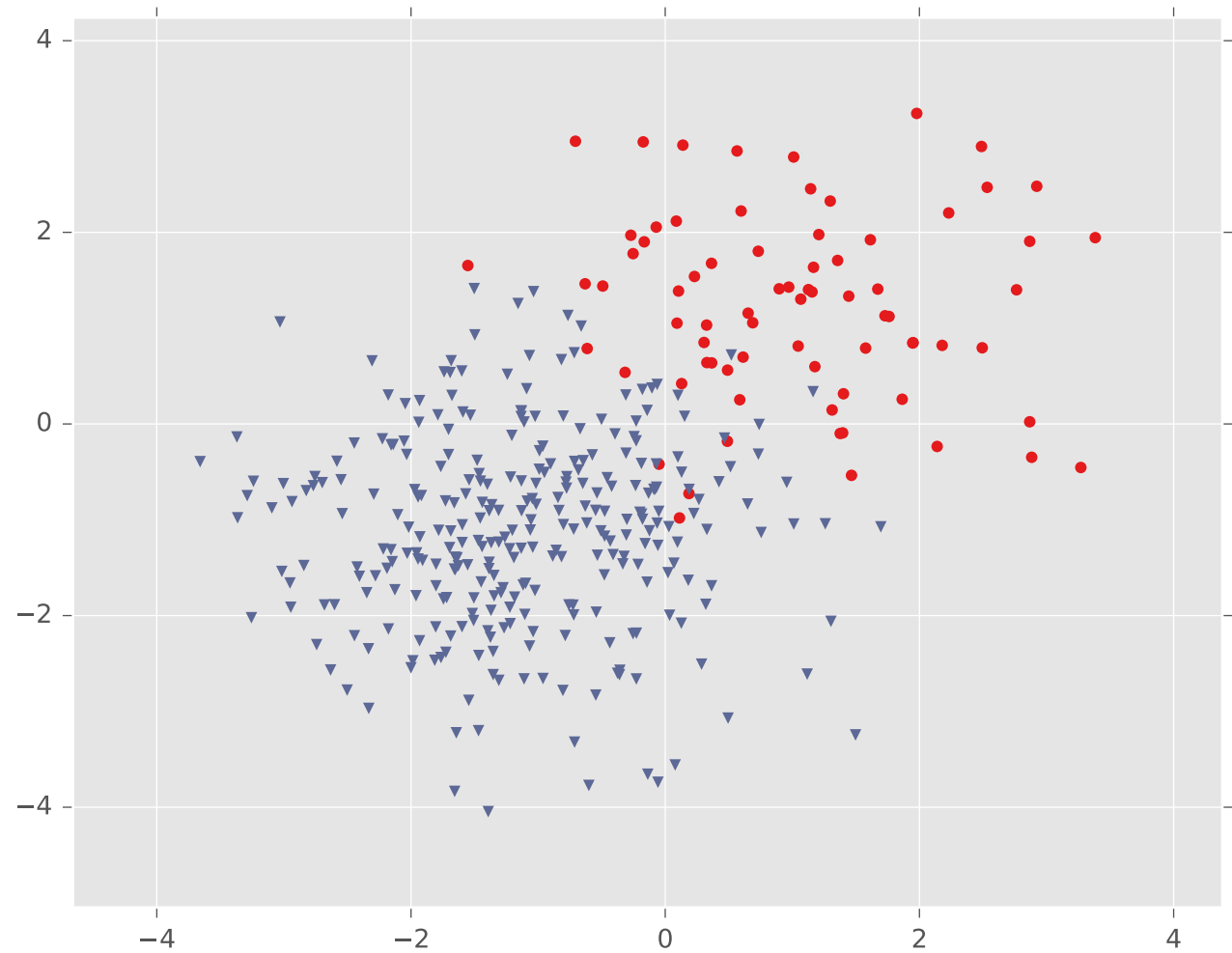
$$2 \geq 1 + \exp(-\mathbf{w}^T \mathbf{x})$$

$$1 \geq \exp(-\mathbf{w}^T \mathbf{x})$$

$$\log(1) \geq -\mathbf{w}^T \mathbf{x}$$

$$0 \leq \mathbf{w}^T \mathbf{x}$$

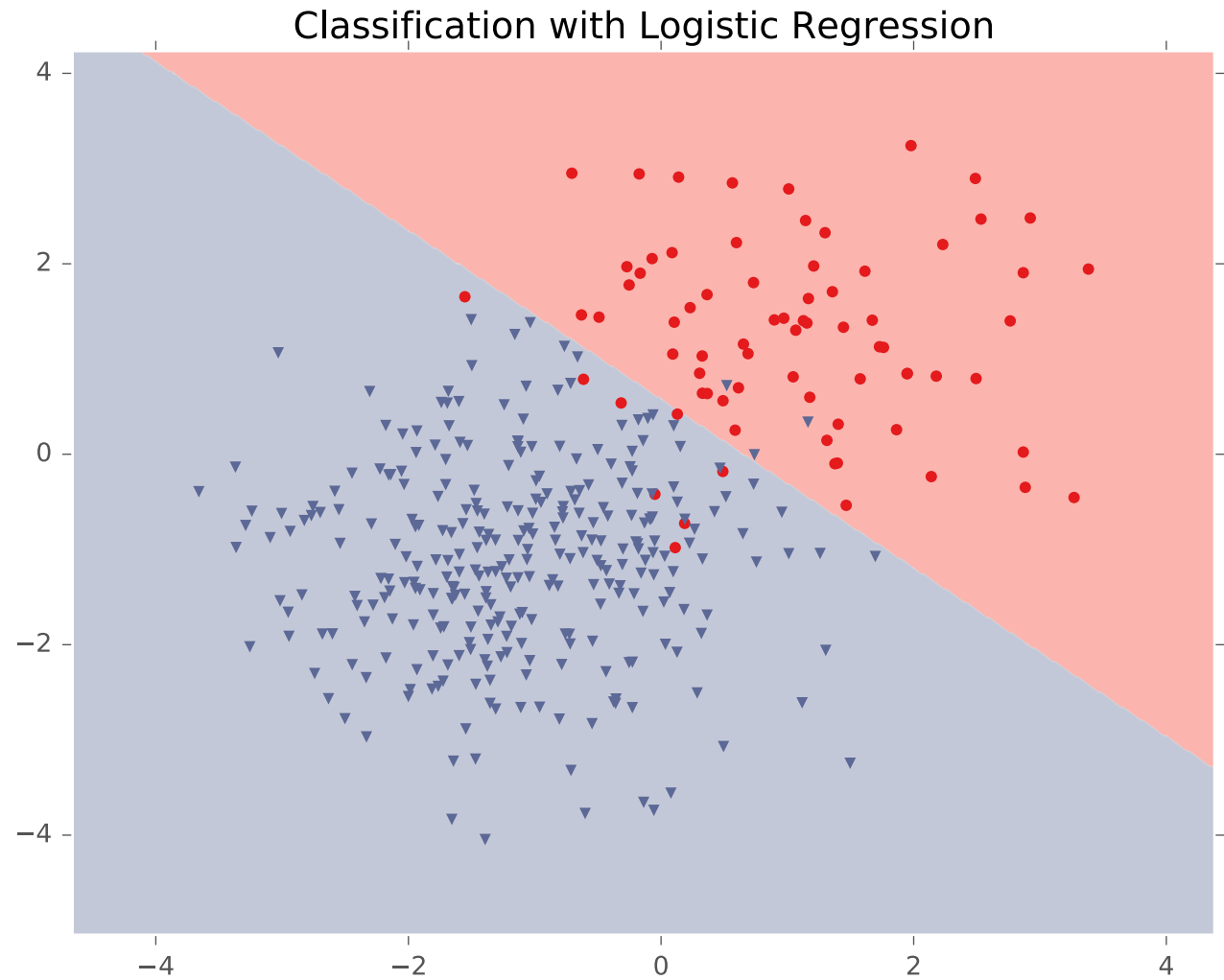
Logistic Regression Decision Boundary



Logistic Regression Decision Boundary



Logistic Regression Decision Boundary



General Recipe for Machine Learning

- Define a model and model parameters
- Write down an objective function
- Optimize the objective w.r.t. the model parameters

Recipe for Logistic Regression

- Define a model and model parameters
 - Assume independent, identically distributed (iid) data
 - Assume $P(Y = 1|X) = \text{logit}(\mathbf{w}^T \mathbf{x})$
 - Parameters: $\boldsymbol{\theta} = [w_0, w_1, \dots, w_D]$
- Write down an objective function
 - ~~Maximize the *conditional* log-likelihood~~
 - Minimize the negative conditional log-likelihood
- Optimize the objective w.r.t. the model parameters
 - ???

Setting the Parameters via Minimum Negative Conditional (log-)Likelihood Estimation (MCLE)

Find $\boldsymbol{\theta}$ that minimizes

$$\begin{aligned}\ell_{\mathcal{D}}(\boldsymbol{\theta}) &= -\log P(y^{(1)}, \dots, y^{(N)} | \mathbf{x}^{(1)}, \dots, \mathbf{x}^{(N)}, \boldsymbol{\theta}) = -\log \prod_{n=1}^N P(y^{(n)} | \mathbf{x}^{(n)}, \boldsymbol{\theta}) \\ &= -\log \prod_{n=1}^N P(Y = 1 | \mathbf{x}^{(n)}, \boldsymbol{\theta})^{y^{(n)}} \left(P(Y = 0 | \mathbf{x}^{(n)}, \boldsymbol{\theta}) \right)^{1-y^{(n)}} \\ &= -\sum_{i=1}^N y^{(i)} \log P(Y = 1 | \mathbf{x}^{(i)}, \boldsymbol{\theta}) + (1 - y^{(i)}) \log P(Y = 0 | \mathbf{x}^{(i)}, \boldsymbol{\theta}) \\ &= -\sum_{i=1}^N y^{(i)} \log \frac{P(Y = 1 | \mathbf{x}^{(i)}, \boldsymbol{\theta})}{P(Y = 0 | \mathbf{x}^{(i)}, \boldsymbol{\theta})} + \log P(Y = 0 | \mathbf{x}^{(i)}, \boldsymbol{\theta}) \\ &= -\sum_{i=1}^N y^{(i)} \boldsymbol{\theta}^T \mathbf{x}^{(i)} - \log \left(1 + \exp(\boldsymbol{\theta}^T \mathbf{x}^{(i)}) \right)\end{aligned}$$

Setting the Parameters via MAP?

(stay tuned for regularization, tomorrow!)

Find $\boldsymbol{\theta}$ that minimizes

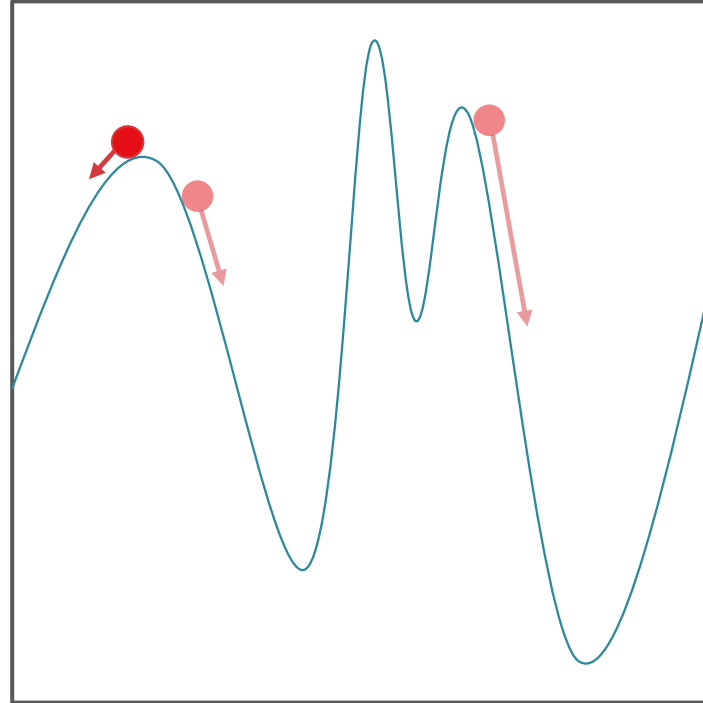
$$\begin{aligned}\ell_{\mathcal{D}}(\boldsymbol{\theta}) &= -\log P(y^{(1)}, \dots, y^{(N)} | \mathbf{x}^{(1)}, \dots, \mathbf{x}^{(N)}, \boldsymbol{\theta}) = -\log \prod_{n=1}^N P(y^{(n)} | \mathbf{x}^{(n)}, \boldsymbol{\theta}) \\ &= -\log \prod_{n=1}^N P(Y = 1 | \mathbf{x}^{(n)}, \boldsymbol{\theta})^{y^{(n)}} \left(P(Y = 0 | \mathbf{x}^{(n)}, \boldsymbol{\theta}) \right)^{1-y^{(n)}} \\ &= -\sum_{i=1}^N y^{(i)} \log P(Y = 1 | \mathbf{x}^{(i)}, \boldsymbol{\theta}) + (1 - y^{(i)}) \log P(Y = 0 | \mathbf{x}^{(i)}, \boldsymbol{\theta}) \\ &= -\sum_{i=1}^N y^{(i)} \log \frac{P(Y = 1 | \mathbf{x}^{(i)}, \boldsymbol{\theta})}{P(Y = 0 | \mathbf{x}^{(i)}, \boldsymbol{\theta})} + \log P(Y = 0 | \mathbf{x}^{(i)}, \boldsymbol{\theta}) \\ &= -\sum_{i=1}^N y^{(i)} \boldsymbol{\theta}^T \mathbf{x}^{(i)} - \log \left(1 + \exp(\boldsymbol{\theta}^T \mathbf{x}^{(i)}) \right)\end{aligned}$$

Minimizing the Negative Conditional (log-)Likelihood

$$\begin{aligned}\ell_{\mathcal{D}}(\boldsymbol{\theta}) &= -\sum_{n=1}^N y^{(n)} \boldsymbol{\theta}^T \mathbf{x}^{(n)} - \log\left(1 + \exp(\boldsymbol{\theta}^T \mathbf{x}^{(n)})\right) \\ \nabla_{\boldsymbol{\theta}} \ell_{\mathcal{D}}(\boldsymbol{\theta}) &= -\sum_{n=1}^N y^{(n)} \nabla_{\boldsymbol{\theta}} \boldsymbol{\theta}^T \mathbf{x}^{(n)} - \nabla_{\boldsymbol{\theta}} \log\left(1 + \exp(\boldsymbol{\theta}^T \mathbf{x}^{(n)})\right) \\ &= -\sum_{n=1}^N y^{(n)} \mathbf{x}^{(n)} - \frac{\exp(\boldsymbol{\theta}^T \mathbf{x}^{(n)})}{1 + \exp(\boldsymbol{\theta}^T \mathbf{x}^{(n)})} \mathbf{x}^{(n)} \\ &= \sum_{n=1}^N \mathbf{x}^{(n)} (P(Y = 1 | \mathbf{x}^{(n)}, \boldsymbol{\theta}) - y^{(n)})\end{aligned}$$

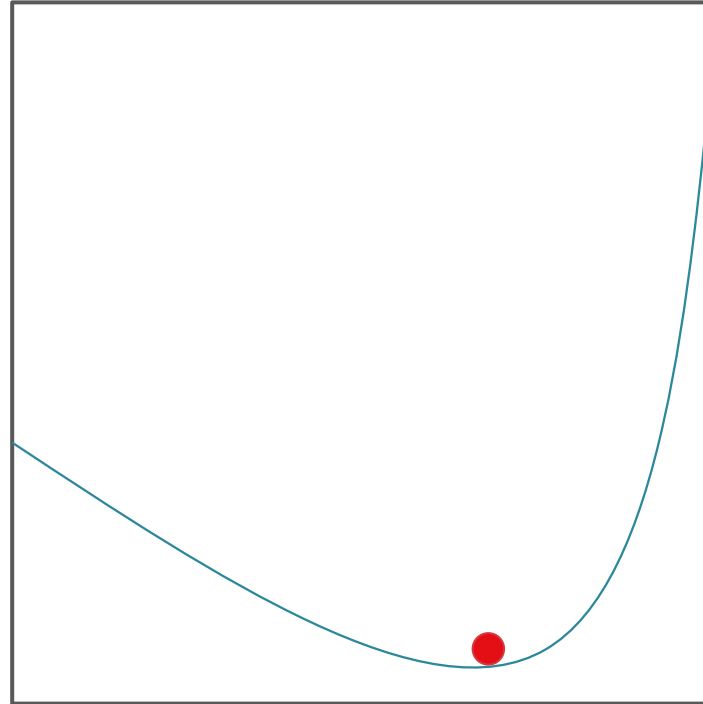
Recall: Gradient Descent

- An iterative method for minimizing functions
- Requires the gradient to exist everywhere



Recall: Gradient Descent

- An iterative method for minimizing functions
- Requires the gradient to exist everywhere



- Good news: the negative conditional log-likelihood, like the squared error, is also convex!

Gradient Descent

- Input: $\mathcal{D} = \{(\mathbf{x}^{(n)}, y^{(n)})\}_{n=1}^N, \eta^{(0)}$

1. Initialize $\boldsymbol{\theta}^{(0)}$ to all zeros and set $t = 0$

2. While TERMINATION CRITERION is not satisfied

- a. Compute the gradient:

$$\nabla_{\boldsymbol{\theta}} \ell_{\mathcal{D}}(\boldsymbol{\theta}^{(t)}) = \sum_{n=1}^N \mathbf{x}^{(n)} (P(Y = 1 | \mathbf{x}^{(n)}, \boldsymbol{\theta}^{(t)}) - y^{(n)})$$

- b. Update $\boldsymbol{\theta}$: $\boldsymbol{\theta}^{(t+1)} \leftarrow \boldsymbol{\theta}^{(t)} - \eta^{(0)} \nabla_{\boldsymbol{\theta}} \ell_{\mathcal{D}}(\boldsymbol{\theta}^{(t)})$

- c. Increment t : $t \leftarrow t + 1$

- Output: $\boldsymbol{\theta}^{(t)}$

What is the computational cost of one iteration of gradient descent for logistic regression?

$O(D)$

0%

$O(N)$

0%

$O(D^2)$

0%

$O(ND)$

0%

$O(N^2)$

0%

Stochastic Gradient Descent

- Input: $\mathcal{D} = \{(\mathbf{x}^{(n)}, y^{(n)})\}_{n=1}^N, \eta_{SGD}^{(0)}$
 1. Initialize $\boldsymbol{\theta}^{(0)}$ to all zeros and set $t = 0$
 2. While TERMINATION CRITERION is not satisfied
 - a. Randomly sample a data point from \mathcal{D} , $(\mathbf{x}^{(n)}, y^{(n)})$
 - b. Compute the pointwise gradient:
$$\nabla_{\boldsymbol{\theta}} \ell^{(n)}(\boldsymbol{\theta}^{(t)}) = \mathbf{x}^{(n)} (P(Y = 1 | \mathbf{x}^{(n)}, \boldsymbol{\theta}^{(t)}) - y^{(n)})$$
 - c. Update $\boldsymbol{\theta}$: $\boldsymbol{\theta}^{(t+1)} \leftarrow \boldsymbol{\theta}^{(t)} - \eta_{SGD}^{(0)} \nabla_{\boldsymbol{\theta}} \ell^{(n)}(\boldsymbol{\theta}^{(t)})$
 - d. Increment t : $t \leftarrow t + 1$
- Output: $\boldsymbol{\theta}^{(t)}$

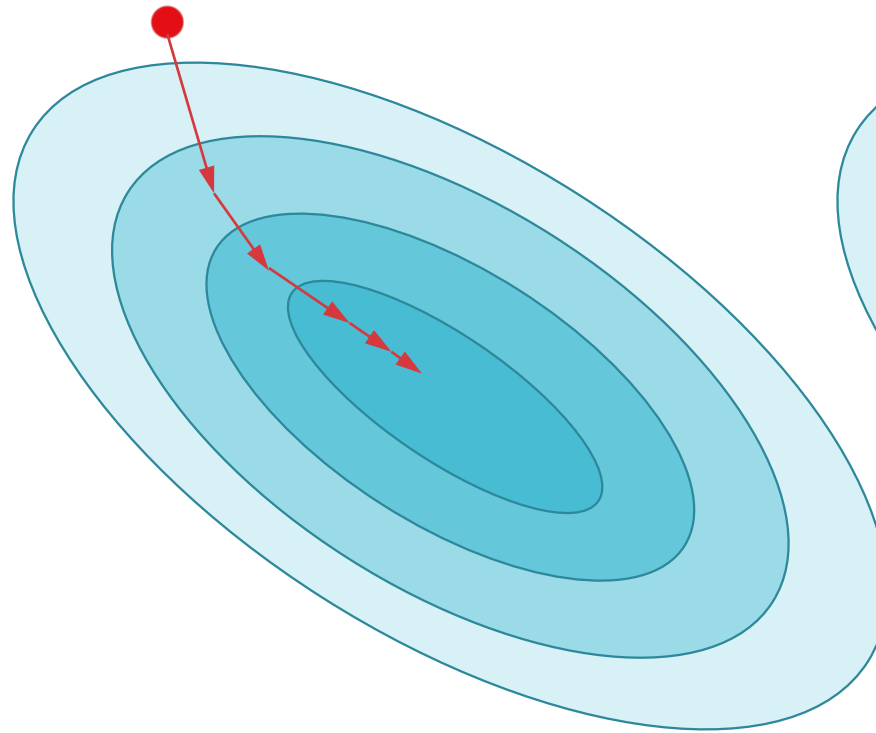
Stochastic Gradient Descent

- If the data point is sampled uniformly at random, then the expected value of the pointwise gradient is proportional to the full gradient:

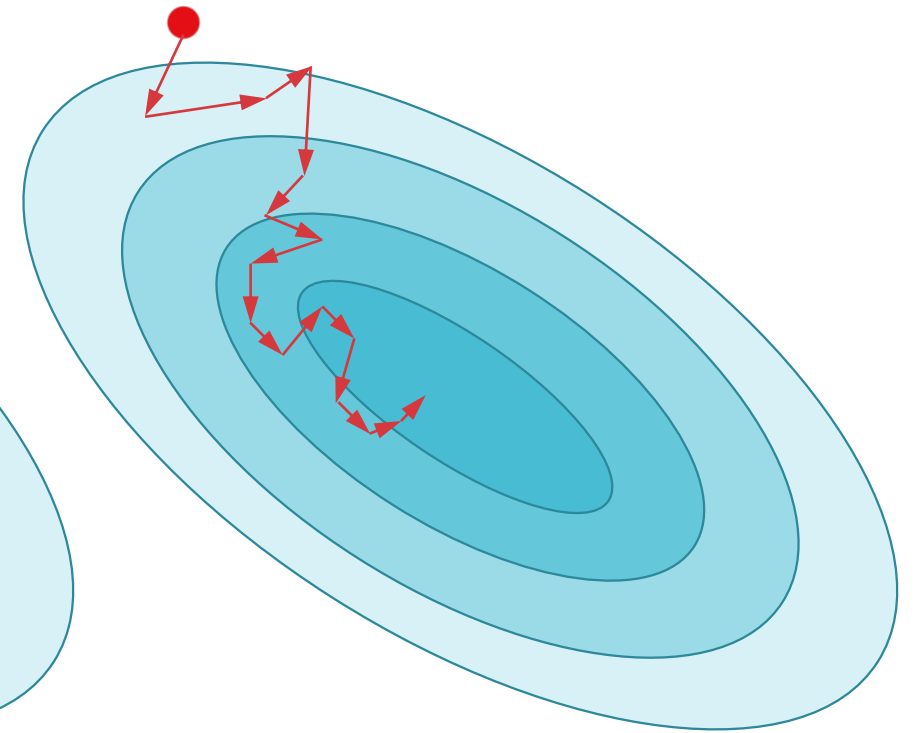
$$\begin{aligned} E \left[\nabla_{\boldsymbol{\theta}} \ell_{\mathbf{x}^{(n)}, \mathbf{y}^{(n)}}(\boldsymbol{\theta}^{(t)}) \right] &= \frac{1}{N} \sum_{n=1}^N \nabla_{\boldsymbol{\theta}} \ell^{(n)}(\boldsymbol{\theta}^{(t)}) \\ &= \frac{1}{N} \sum_{n=1}^N \mathbf{x}^{(n)} (P(Y = 1 | \mathbf{x}^{(n)}, \boldsymbol{\theta}^{(t)}) - y^{(n)}) \\ &= \frac{1}{N} \nabla_{\boldsymbol{\theta}} \ell_{\mathcal{D}}(\boldsymbol{\theta}^{(t)}) \end{aligned}$$

- In practice, the data set is randomly shuffled then looped through so that each data point is used equally often

Stochastic Gradient Descent vs. Gradient Descent



Gradient Descent



Stochastic Gradient Descent

Mini-batch Stochastic Gradient Descent

• Input: $\mathcal{D} = \{(\mathbf{x}^{(n)}, y^{(n)})\}_{n=1}^N, \eta_{MB}^{(0)}, B$

1. Initialize $\boldsymbol{\theta}^{(0)}$ to all zeros and set $t = 0$
2. While TERMINATION CRITERION is not satisfied

a. Randomly sample B data points from \mathcal{D} :

$$\mathcal{D}_{batch} \{(\mathbf{x}^{(b)}, y^{(b)})\}_{b=1}^B$$

b. Compute the gradient w.r.t. the sampled *batch*:

$$\nabla_{\boldsymbol{\theta}} \ell_{\mathcal{D}_{batch}}(\boldsymbol{\theta}^{(t)}) = \sum_{b=1}^B \mathbf{x}^{(b)} (P(Y = 1 | \mathbf{x}^{(b)}, \boldsymbol{\theta}^{(t)}) - y^{(b)})$$

c. Update $\boldsymbol{\theta}$: $\boldsymbol{\theta}^{(t+1)} \leftarrow \boldsymbol{\theta}^{(t)} - \eta_{MB}^{(0)} \nabla_{\boldsymbol{\theta}} \ell_{\mathcal{D}_{batch}}(\boldsymbol{\theta}^{(t)})$

d. Increment t : $t \leftarrow t + 1$

• Output: $\boldsymbol{\theta}^{(t)}$

Key Takeaways

- Logistic regression
 - Logistic function induces a linear decision boundary
 - Conditional likelihood maximization
- Gradient descent vs. stochastic gradient descent tradeoffs