Machine Learning, Function Approximation and Version Spaces

Recommended reading: Mitchell, Chapter 2

Machine Learning 10-701

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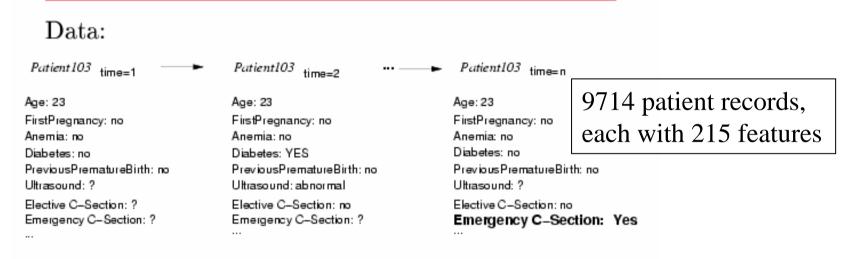
Machine Learning:

Study of algorithms that

- improve their <u>performance</u>
- at some task
- with <u>experience</u>

Learning to Predict Emergency C-Sections

[Sims et al., 2000]



One of 18 learned rules:

If No previous vaginal delivery, and
Abnormal 2nd Trimester Ultrasound, and
Malpresentation at admission
Then Probability of Emergency C-Section is 0.6

Over training data: 26/41 = .63,

Over test data: 12/20 = .60

Object Detection

(Prof. H. Schneiderman)

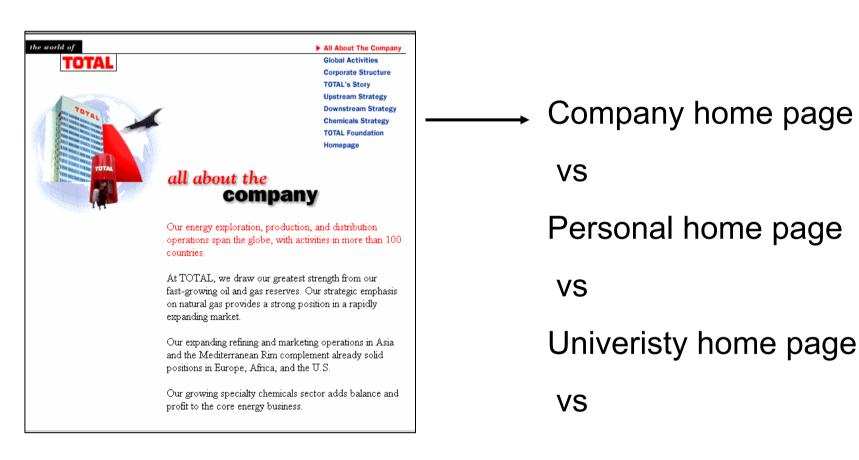




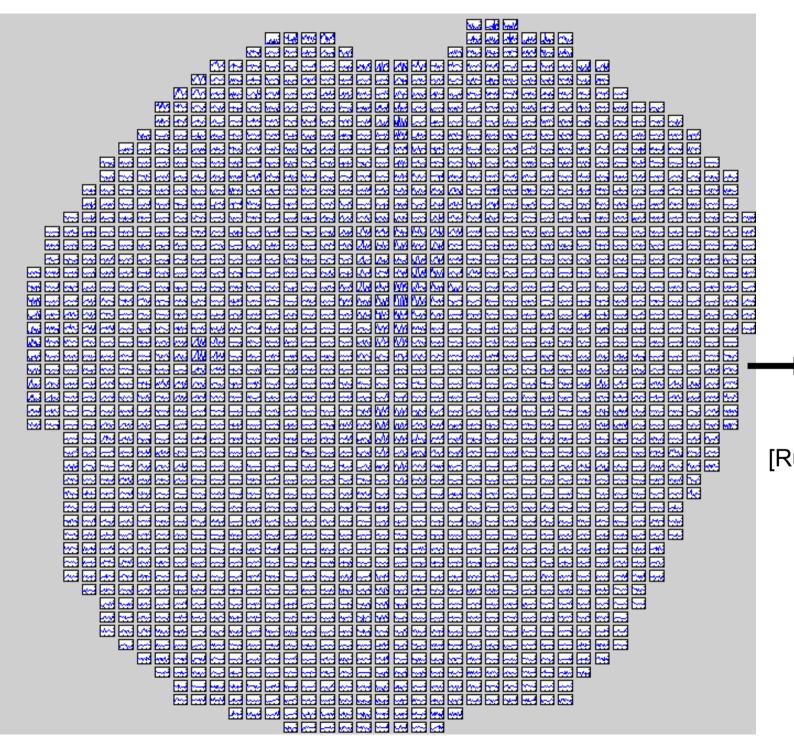
Example training images for each orientation



Text Classification



. . .



Reading a noun (vs verb)

[Rustandi et al., 2005]

Growth of Machine Learning

- Machine learning is preferred approach to
 - Speech recognition, Natural language processing
 - Computer vision
 - Medical outcomes analysis
 - Robot control
 - **—** ...
- This trend is accelerating
 - Improved machine learning algorithms
 - Improved data capture, networking, faster computers
 - Software too complex to write by hand
 - New sensors / IO devices
 - Demand for self-customization to user, environment

Training Examples for EnjoySport

C: < Sky, Temp, Humid, Wind, Water, Forecst > → EnjoySpt

Sky	Temp	Humid	Wind	Water	Forecst	EnjoySpt
Sunny	Warm	Normal	Strong	Warm	Same	Yes
Sunny	Warm	High	Strong	Warm	\mathbf{Same}	Yes
Rainy	Cold	High	Strong	Warm	Change	No
Sunny	${\rm Warm}$	High	Strong	Cool	Change	Yes

What is the general concept?

Function Approximation

Given:

- Instances X:
 - e.g. x = <0,1,1,0,0,1>
- Hypotheses H: set of functions h: X → {0,1}
 - e.g., H is the set of all boolean functions defined by conjunctions of constraints on the features of x. (such as $<0,1,?,?,1>\rightarrow 1$)
- Training Examples D: sequence of positive and negative examples of an unknown target function c: $X \rightarrow \{0,1\}$

$$- < x_1, c(x_1) >, ... < x_m, c(x_m) >$$

Determine:

A hypothesis h in H such that h(x)=c(x) for all x in X

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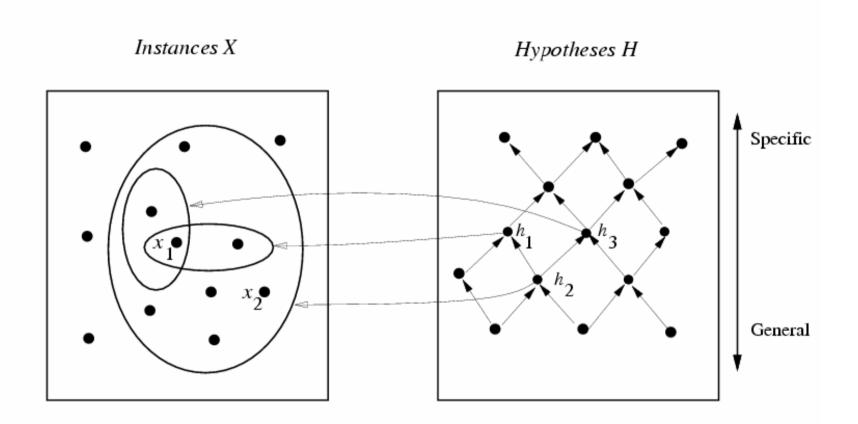
What we want

Determine:

- A hypothesis h in H such that h(x)=c(x) for all x in X
- A hypothesis h in H such that h(x)=c(x) for all x in D what we can observe

Here draw instance space, hypothesis space figure

Instances, Hypotheses, and More-General-Than



$$x_1$$
= x_2 =

$$h_1 = \langle Sunny, ?, ?, Strong, ?, ? \rangle$$

 $h_2 = \langle Sunny, ?, ?, ?, ?, ? \rangle$
 $h_3 = \langle Sunny, ?, ?, ?, Cool, ? \rangle$

Simplifying Assumptions for today (only)

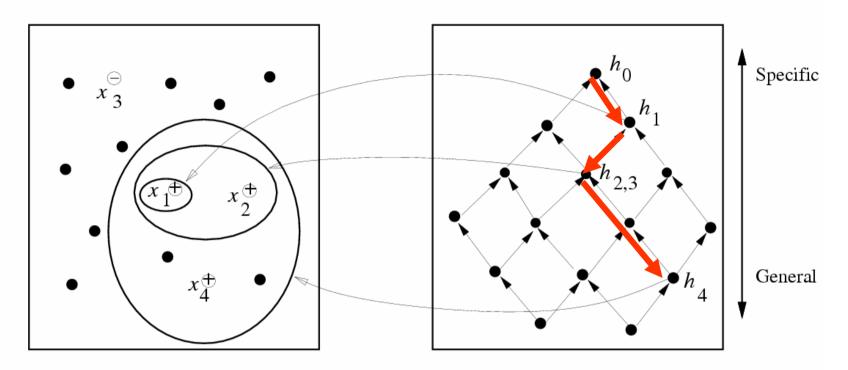
- Target function c is deterministic
- Target function c is contained in hypotheses H
- Training data is error-free, noise-free

Find-S **Algorithm**

- 1. Initialize h to the most specific hypothesis in H
- 2. For each positive training instance x
 - For each attribute constraint a_i in hIf the constraint a_i in h is satisfied by xThen do nothing Else replace a_i in h by the next more general constraint that is satisfied by x
- 3. Output hypothesis h

Instances X

Hypotheses H



 $x_1 = \langle Sunny\ Warm\ Normal\ Strong\ Warm\ Same \rangle, +$ $x_2 = \langle Sunny\ Warm\ High\ Strong\ Warm\ Same \rangle, +$ $x_3 = \langle Rainy\ Cold\ High\ Strong\ Warm\ Change \rangle, x_4 = \langle Sunny\ Warm\ High\ Strong\ Cool\ Change \rangle, +$

$$h_0 = \langle \phi, \phi, \phi, \phi, \phi, \phi \rangle$$

 $h_1 = \langle Sunny \ Warm \ Normal \ Strong \ Warm \ Same \rangle$

 $h_2 = \langle Sunny \ Warm \ ? \ Strong \ Warm \ Same \rangle$

 $h_3 = \langle Sunny \ Warm \ ? \ Strong \ Warm \ Same \rangle$

 $h_4 = \langle Sunny \ Warm \ ? \ Strong \ ? \ ? \rangle$

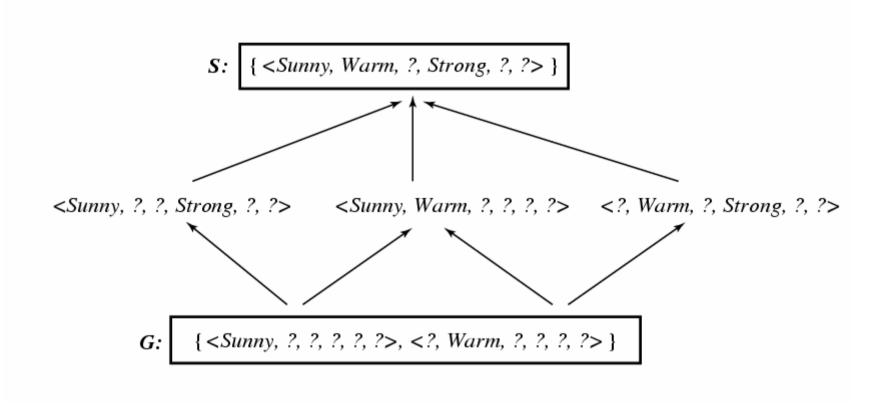
Problems with Find-S

- Finds just one of the many h's in H that fit the training data
 - the most specific one
- Can't determine when learning has converged to the final h

The List-Then-Eliminate Algorithm:

- 1. $VersionSpace \leftarrow$ a list containing every hypothesis in H
- 2. For each training example, $\langle x, c(x) \rangle$ remove from VersionSpace any hypothesis h for which $h(x) \neq c(x)$
- 3. Output the list of hypotheses in VersionSpace

Version Space for our EnjoySport problem



Representing Version Spaces

The **General boundary**, G, of version space $VS_{H,D}$ is the set of its maximally general members

The **Specific boundary**, S, of version space $VS_{H,D}$ is the set of its maximally specific members

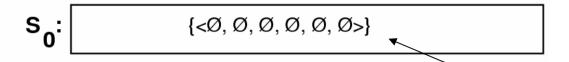
Every member of the version space lies between these boundaries

$$VS_{H,D} = \{ h \in H | (\exists s \in S)(\exists g \in G)(g \ge h \ge s) \}$$

where $x \ge y$ means x is more general or equal to y

Version Space Candidate Elimination Algorithm

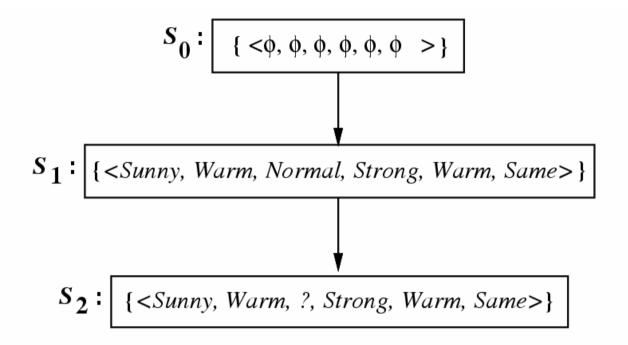
- Initialize S (G) to maximally specific (general) h's in H
- For each training example <x,c(x)>
 - if positive example <x,1>
 - Generalize S as much as needed to cover x, in all possible ways
 - Remove any h ∈ G, for which h(x)≠1
 - if negative example <x,0>
 - Specialize G as much as needed to exclude x, in all possible ways
 - Remove any h ∈ S for which h(x)=1
 - Retain only members of G that are more general than some member of S
 - Retain only members of S that are more general than some member of G



Matches NO instances

$$G_0$$
:

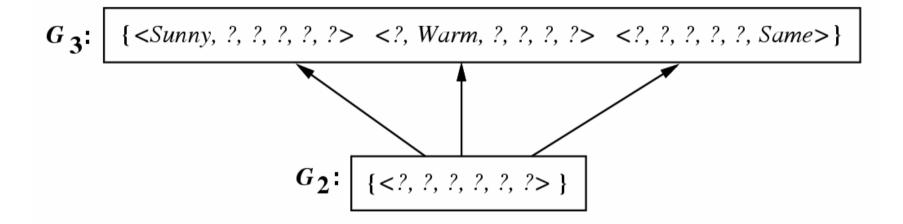
{<?, ?, ?, ?, ?, ?>}



$$G_0$$
, G_1 , G_2 : {, ?, ?, ?, ?, ?}

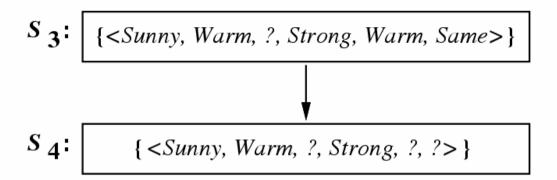
Training examples:

- 1. <Sunny, Warm, Normal, Strong, Warm, Same>, Enjoy Sport = Yes
- 2. <Sunny, Warm, High, Strong, Warm, Same>, Enjoy Sport = Yes



Training Example:

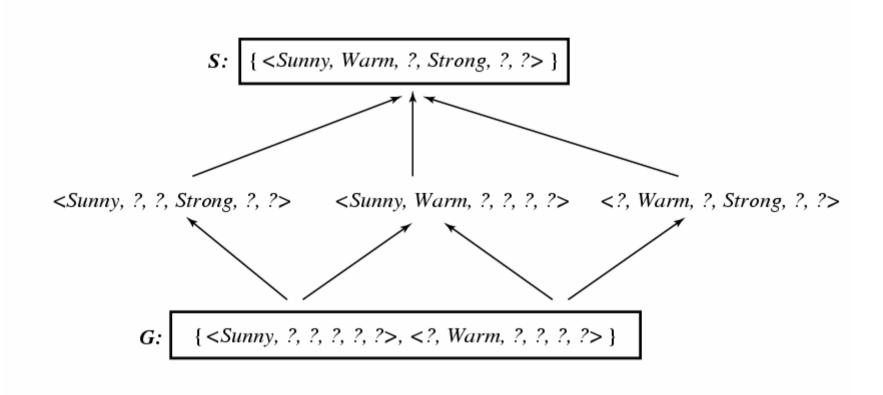
3. <Rainy, Cold, High, Strong, Warm, Change>, EnjoySport=No



Training Example:

4. <Sunny, Warm, High, Strong, Cool, Change>, EnjoySport = Yes

Version Space after all four examples



Machine Translation Example [Probst et al., 2003]

```
;; Hebrew Transfer Rule Example
English: the big boy
Hebrew: ha yeled ha gadol
NP::NP: [DET ADJ N] -> [DET N DET ADJ]
;;X-Y Alignment
(X1::Y1)
(X1::Y3)
(X2::Y4)
(X3::Y2)
::X-side constraints
((X1 \text{ NUMBER}) = (X3 \text{ NUMBER}))
((X1 DEFINITENESS) = +)
;;Y-side constraints
((Y2 \text{ NUMBER}) = (Y4 \text{ NUMBER}))
((Y2 \text{ GENDER}) = (Y4 \text{ GENDER}))
::X-Y constraints
((X0 \text{ NUMBER}) = (Y0 \text{ NUMBER}))
((X0 DEFINITENESS) = (Y0 DEFINITENESS))
```

Figure 1: Sample transfer rule for English to Hebrew.

Seeded VS Learning [Probst et al., 2003]:

Construct VS around a seed positive example.

Include only
hypotheses at a
predetermined level
of generalization, ± *k*levels in the partial
order.

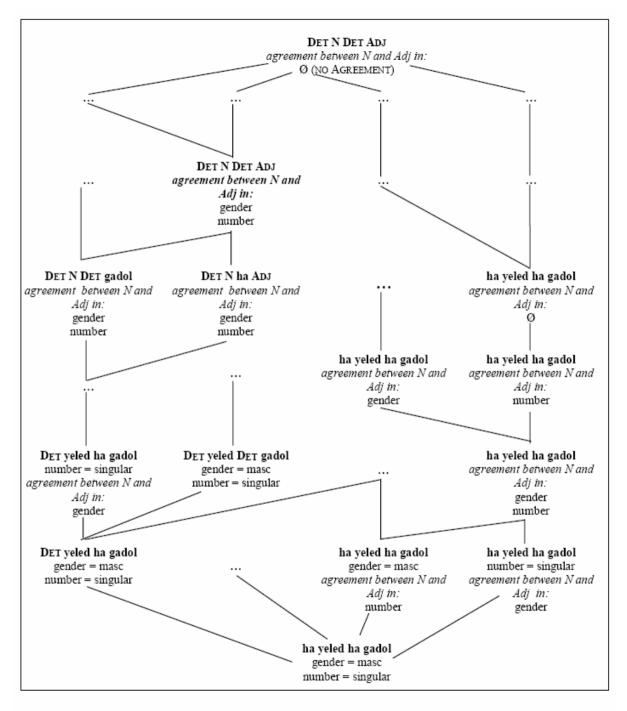
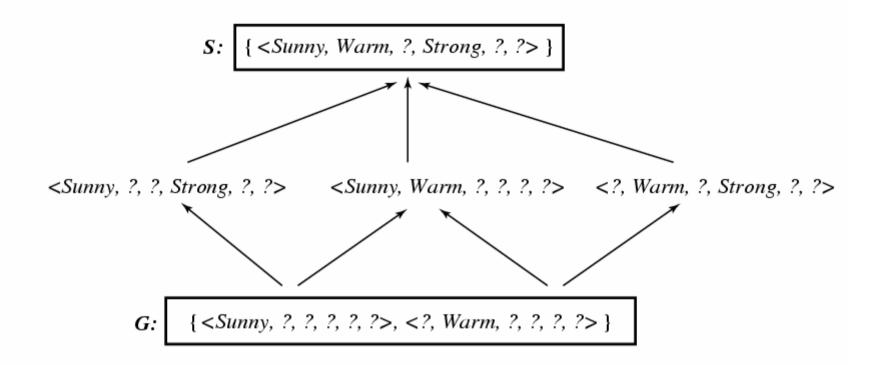
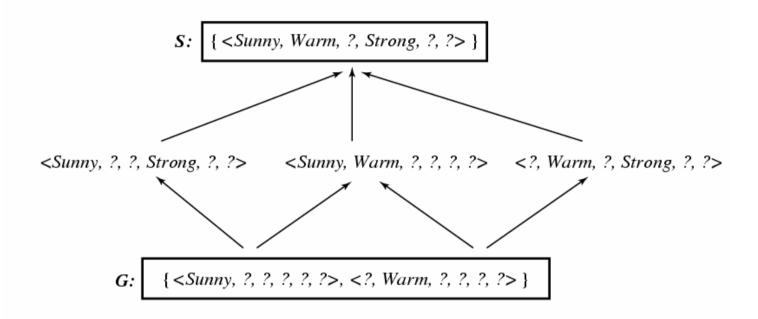


Figure 2: Partial representation of the version space for the example given in figure 1.

What Next Training Example?



How Should These Be Classified?



(Sunny Warm Normal Strong Cool Change)

 $\langle Rainy\ Cool\ Normal\ Light\ Warm\ Same \rangle$

⟨Sunny Warm Normal Light Warm Same⟩

What Justifies this Inductive Leap?

- + \(\langle Sunny Warm Normal Strong Cool Change \rangle \)
- + $\langle Sunny Warm Normal Light Warm Same \rangle$

 $S: \langle Sunny \ Warm \ Normal ? ? ? \rangle$

Why believe we can classify the unseen?

 $\langle Sunny \ Warm \ Normal \ Strong \ Warm \ Same \rangle$

An UNBiased Learner

Idea: Choose H that expresses every teachable concept (i.e., H is the power set of X)

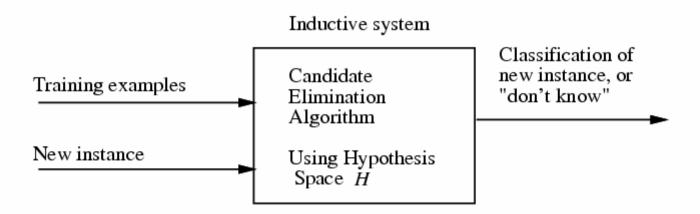
Consider H' = disjunctions, conjunctions, negations over previous H. E.g.,

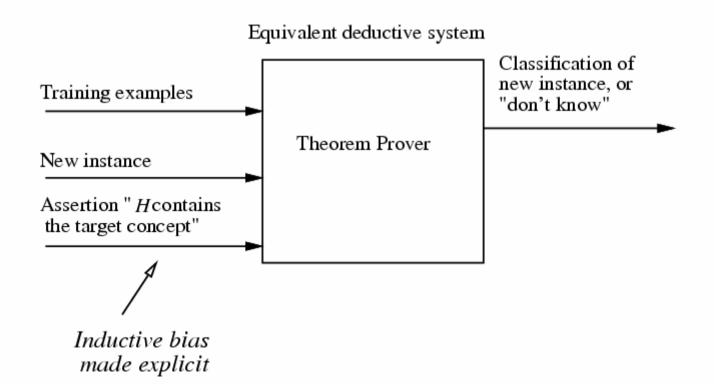
 $\langle Sunny Warm Normal??? \rangle \lor \neg \langle ??????Change \rangle$

What are S, G in this case?

$$S \leftarrow$$

$$G \leftarrow$$





What you should know:

- Well posed function approximation problem:
 - Instance space, X
 - Hypothesis space, H
 - Sample of training data, D
- Learning as search/optimization over H
 - Various objective functions
- Sample complexity of learning
 - How many examples needed to converge?
 - Depends on H, how examples generated, notion of convergence
- Biased and unbiased learners
 - Futility of unbiased learning