

$$\min_{x \in C} f(x)$$

$$\max_{x \in C} \tilde{f}(x)$$

$$\Leftrightarrow - \min_{x \in C} \tilde{f}(x)$$

primal LP

feasible then strong duality

dual LP

feasible then strong duality.

$f(x) - g(u, v)$  Duality gap.

$$f(x^*) \geq g(u, v) \quad \forall \text{ dual feasible } u, v$$

$$f(x) \geq g(u^*, v^*) \quad \forall \text{ primal feasible } x$$

$$\underbrace{f(x) - f^*}_{\leq} \leq \underbrace{f(x) - g(u, v)}_{\geq \epsilon}$$

$$x \in \mathbb{R}^n, \quad \|x\|_p = \left( \sum_{i=1}^n |x_i|^p \right)^{1/p}$$

$\|\cdot\|$ , dual  $\|\cdot\|_*$

$$\frac{|z^T x|}{\|z\|}$$

$$\|x\|_* = \max_{\|u\| \leq 1} u^T x \geq \frac{z^T x}{\|z\|}$$

$$z^T x \leq \|z\| \|x\|_*$$

$x^*$ ,  $u^*$ ,  $v^*$  optimal.

duality gap  $f(x^*) = g(u^*, v^*)$   
is zero

$$\begin{aligned} f(x^*) &= g(u^*, v^*) \\ &= \min_x f(x) + \sum u_i^* h_i(x) + \sum v_j^* l_j(x) \end{aligned}$$

$$\rightarrow = f(x^*) + \sum u_i^* h_i(x^*) + \sum v_j^* l_j(x^*)$$

$$\rightarrow = f(x^*)$$

$$0 \ni \partial f(x^*) + \sum u_i^* \partial h_i(x^*) + \sum v_j^* \partial l_j(x^*)$$

stationarity

$$\sum u_i^* h_i(x^*) = 0$$

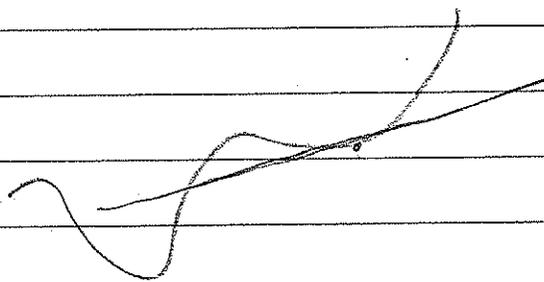
$$u_i^* h_i(x^*) = 0 \text{ for all } i$$

comp. slackness

$$\begin{aligned}
 g(u^*, v^*) &= f(x^*) + \sum u_i^* h_i(x^*) + \sum v_j^* l_j(x^*) \\
 &= L(x^*, u^*, v^*) \\
 &= f(x^*)
 \end{aligned}$$

$$g(u^*, v^*) = \min_x f(x) + \sum u_i^* h_i(x) + \sum v_j^* l_j(x)$$

$$\begin{aligned}
 &\text{stationarity} \\
 &= f(x^*) + \sum u_i^* h_i(x^*) + \sum v_j^* l_j(x^*) \\
 &\text{complementary slackness} \\
 &= f(x^*)
 \end{aligned}$$



$$\min \frac{1}{2} x^T Q x + c^T x$$

$$\text{s.t. } Ax = 0 \quad u$$

( E.g. Newton's step )

$$Ax^{(k)} = b \quad x^{(k+1)} = x^{(k)} + x$$

$$0 = Qx + c + A^T u$$

$$Ax = 0$$

$$\begin{bmatrix} Q & A^T \\ A & 0 \end{bmatrix} \begin{bmatrix} x \\ u \end{bmatrix} = \begin{bmatrix} -c \\ 0 \end{bmatrix}$$

$$\min \frac{1}{2} \|y - Ax\|^2 + \lambda \|x\|_1$$

$$-A^T(y - Ax) + \lambda s = 0, \quad s \in \partial \|x\|_1$$

$$A^T(y - Ax) = \lambda s$$

$$s \in \begin{cases} [-1, 1] & x_i < 0 \\ \{0\} & x_i = 0 \\ [1, 1] & x_i > 0 \end{cases}$$

$$|A_i^T(y - Ax)| < \lambda \implies x_i = 0.$$

$$|z_j^T(y - Ax)| < \lambda \quad [A z]$$

$$A = [A_{c1} \dots A_{cp}]$$

$$x = [x_{c1} \dots x_{cp}]$$

$$\min_x \frac{1}{2} \|y - Ax\|^2 + \lambda \sum \|x_{ci}\|_2 \sqrt{p_{ci}}$$

$$A_{ci}^T (y - Ax) = \lambda \sqrt{p_{ci}} s_{ci}$$

$$s_{ci} \in \partial \|x_{ci}\|_2$$

$$s_{ci} \in \begin{cases} \left\{ \frac{x_{ci}}{\|x_{ci}\|_2} \right\} & x_{ci} \neq 0 \\ \{z : \|z\|_2 \leq 1\} & x_{ci} = 0 \end{cases}$$

$$\|A_{ci}^T (y - Ax)\|_2 < \lambda \sqrt{p_{ci}} \Rightarrow x_{ci} = 0$$

$$A_{ci}^T (y - Ax) = \lambda \sqrt{p_{ci}} \frac{x_{ci}}{\|x_{ci}\|_2}$$

$$x_{ci} = \left( A_{ci}^T A_{ci} + \frac{\lambda \sqrt{p_{ci}} I}{\|x_{ci}\|_2} \right)^{-1} A_{ci}^T (y - c_i)$$

$$\min L(x, \lambda) = f(x) + \lambda(h(x) - t)$$

$$\Leftrightarrow \min f(x) + \lambda h(x)$$

$$\min f(x) + \lambda h(x)$$

$$\underline{t = h(x^*)}$$

$$\min f(x) \quad \text{st} \quad h(x) \leq t$$

$$\min f(x) + \lambda(h(x) - t)$$

$$\Leftrightarrow \min f(x) + \lambda h(x)$$

$$\lambda(h(x^*) - t) = 0$$

$$f(x) + \lambda(h(x) - t)$$

$$f(x) + \lambda h(x)$$

$$\frac{1}{2} \|y - Ax\|_2^2 + \lambda \|x\|_1$$

$x^*$  is unique

$$\# \text{ of nonzeros in } x^* \leq \min\{n, p\}$$

$$A^T \nabla f(Ax) + \lambda s = 0$$

$$-A^T \nabla f(Ax) = \lambda s$$

$$s \in \partial \|x\|_1$$

$$\begin{cases} \in \{\text{sign}(x_i)\} & x_i \neq 0 \\ [-1, 1] & = 0 \end{cases}$$

$$S = \{j : |A_j^T \nabla f(Ax)| = \lambda\}$$

$$x_i = 0 \text{ for all } i \notin S$$

$$\text{rank}(A_S) < |S|$$

$$A_i = \sum_{\substack{j \in S \\ j \neq i}} c_j A_j$$

$$1 = \sum_j c_j \underbrace{s_j s_i}_{a_j}$$

$$s_i A_i = \sum a_j s_j A_j \text{ where } a_j \text{ satisfy}$$

$S: A_i \in \text{aff} \{s_j A_j, j \in S \setminus \{i\}\}$

$\Rightarrow$   $A$  entries density over  $\mathbb{R}^{n \times p}$   
then this can't happen w.p. 1

$$\text{w.p. 1} \quad \text{rank}(A_S) = |S| \\ \leq \min\{n, p\}$$

Reduced problem

$$\min_x f(A_S x_S) + \lambda \|x_S\|_1$$

strictly  
convex

$$A_S^T \nabla^2 f(A_S x_S) A_S$$

$\Rightarrow$  unique solution