

Linear programs



10-725 Optimization
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Review: LPs

- LPs: m constraints, n vars
 - ▶ $A: \mathbb{R}^{m \times n}$ $b: \mathbb{R}^m$ $c: \mathbb{R}^n$ $x: \mathbb{R}^n$
 - ▶ ineq form
 - ▶ [min or max] $c^T x$ s.t. $Ax \leq b$
 - ▶ $m \geq n$
 - ▶ std form
 - ▶ [min or max] $c^T x$ s.t. $Ax = b$ $x \geq 0$
 - ▶ $m \leq n$

$$\begin{aligned} \max \quad & 2x + 3y \text{ s.t.} \\ & x + y \leq 4 \\ & 2x + 5y \leq 12 \\ & x + 2y \leq 5 \\ & x, y \geq 0 \end{aligned}$$

Review: LPs

- Polyhedral feasible set
 - ▶ infeasible (unhappy ball)
 - ▶ unbounded (where's my ball?)
- Optimum at a vertex (= a 0-face)
- Transforming LPs
 - ▶ changing \geq to \leq to =
 - ▶ getting rid of free vars or bounded vars

Review: LPs

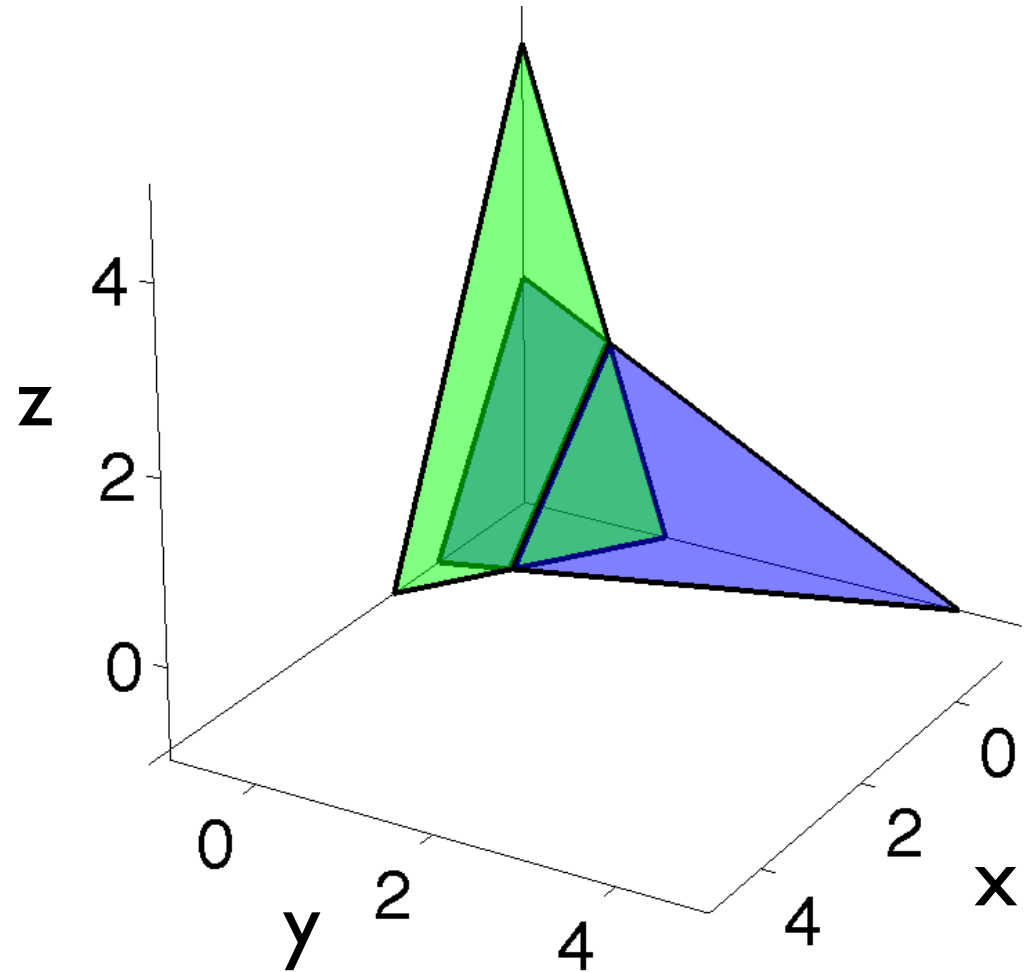
- Tableau:

<u>x</u>	<u>y</u>	u	v	w	z	RHS
1	1	1	0	0	0	4
2	5	0	1	0	0	12
1	2	0	0	1	0	5
-2	-3	0	0	0	1	0
- Row operations to get equivalent tableaux
- Basis (more or less corresponds to a corner)
 - ▶ use row ops to make $m \times m$ block of tableau = identity matrix
 - ▶ set nonbasic vars = 0: enough constraints to fully specify all other variables (so, a 0-face, if it's feasible)

Ineq form is projected std form

$$\begin{aligned} x, y, z &\geq 0 \\ A[x;y;z] &= b \end{aligned}$$

$$\begin{array}{ccc|c} 3 & 1 & 2 & 5 \\ 2 & 3 & 1 & 5 \end{array}$$



Three bases

$$\begin{array}{ccc|c} 1 & 0 & 5/7 & 10/7 \\ 0 & 1 & -1/7 & 5/7 \end{array}$$

$$-5 \leq z \leq 2$$

$$\begin{array}{ccc|c} 1 & 5 & 0 & 5 \\ 0 & -7 & 1 & -5 \end{array}$$

$$5/7 \leq y \leq 1$$

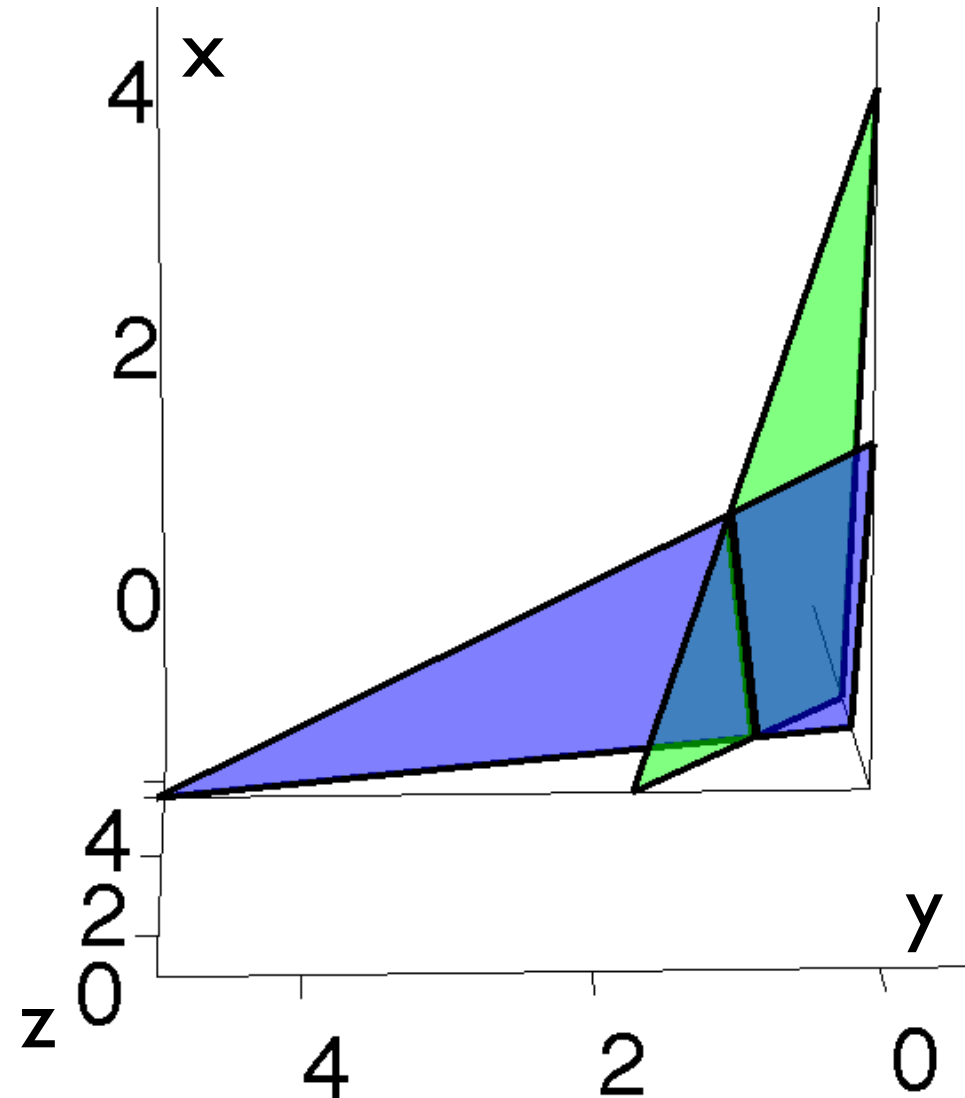
$$\begin{array}{ccc|c} 1/5 & 1 & 0 & 1 \\ 7/5 & 0 & 1 & 2 \end{array}$$

$$x \leq 5 \quad x \leq 10/7$$

$$\begin{array}{c} 10/7 \\ 5/7 \end{array}$$

$$\begin{array}{c} 5 \\ -5 \end{array}$$

$$\begin{array}{c} 1 \\ 2 \end{array}$$



What if we can't pick basis?

- E.g., suppose A doesn't have full row rank
 - ▶ can't pick m linearly independent cols
- Ex:
 - ▶ $3x + 2y + 1z = 3$
 - ▶ $6x + 4y + 2z = 6$

What if we can't pick basis?

- E.g., suppose fewer vars than constraints
 - ▶ A taller than it is wide, $m \geq n$
 - ▶ can't pick enough cols of A to make a square matrix
- Ex:

Nonsingular

- We can assume
 - ▶ $n \geq m$ (at least as many vars as constra)
 - ▶ A has full row rank
- Else, drop rows (maintaining rank) until it's true
- Called ***nonsingular*** standard form LP

Naive (sloooooow) algorithm

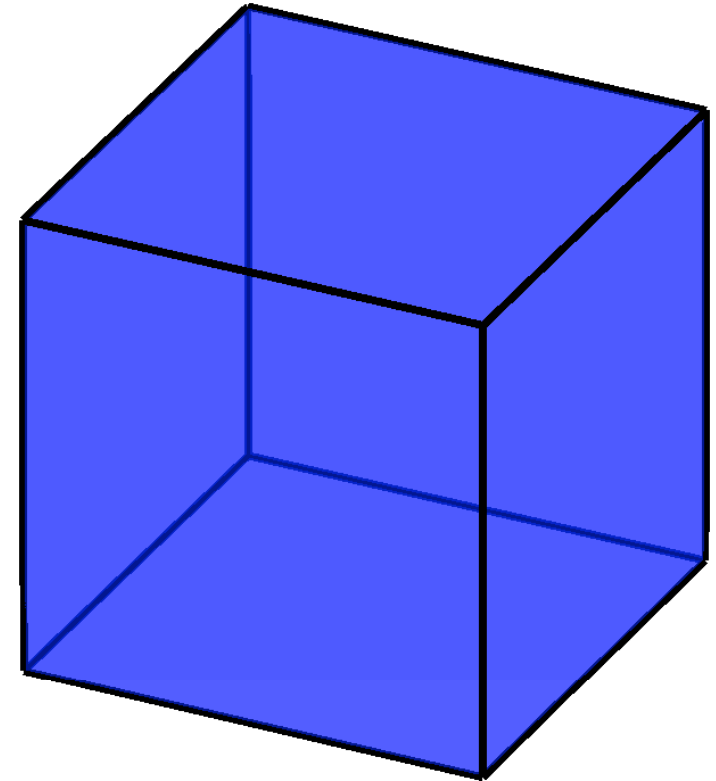
- Put in nonsingular standard form
- Iterate through all subsets of n vars
 - ▶ if m constraints, how many subsets?
- Check each for
 - ▶ full rank (“basis-ness”)
 - ▶ feasibility ($\text{RHS} \geq 0$)
- If pass both tests, compute objective
- Maintain running winner, return at end

Improving our search

- Naive: enumerate all possible bases
- Smarter: maybe neighbors of good bases are also good?
- Simplex algorithm: repeatedly move to a neighboring basis to improve objective
 - ▶ continue to assume nonsingular standard form LP

Neighboring bases

- Two bases are **neighbors** if they share $(m-1)$ variables
- Neighboring feasible bases correspond to vertices connected by an edge

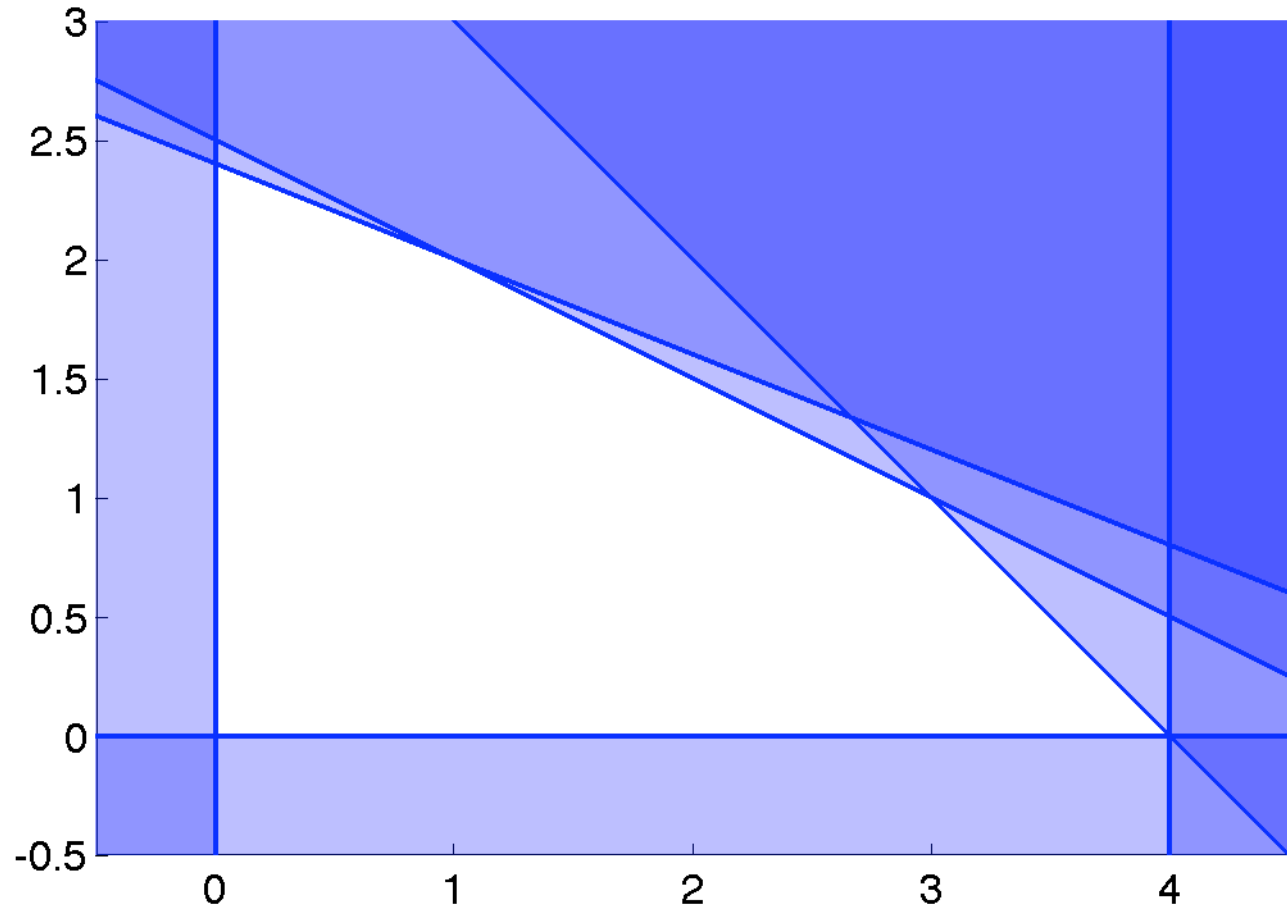


<u>x</u>	<u>y</u>	<u>z</u>	<u>u</u>	<u>v</u>	<u>w</u>	<u>RHS</u>
1	0	0	1	0	0	1
0	1	0	0	1	0	1
0	0	1	0	0	1	1

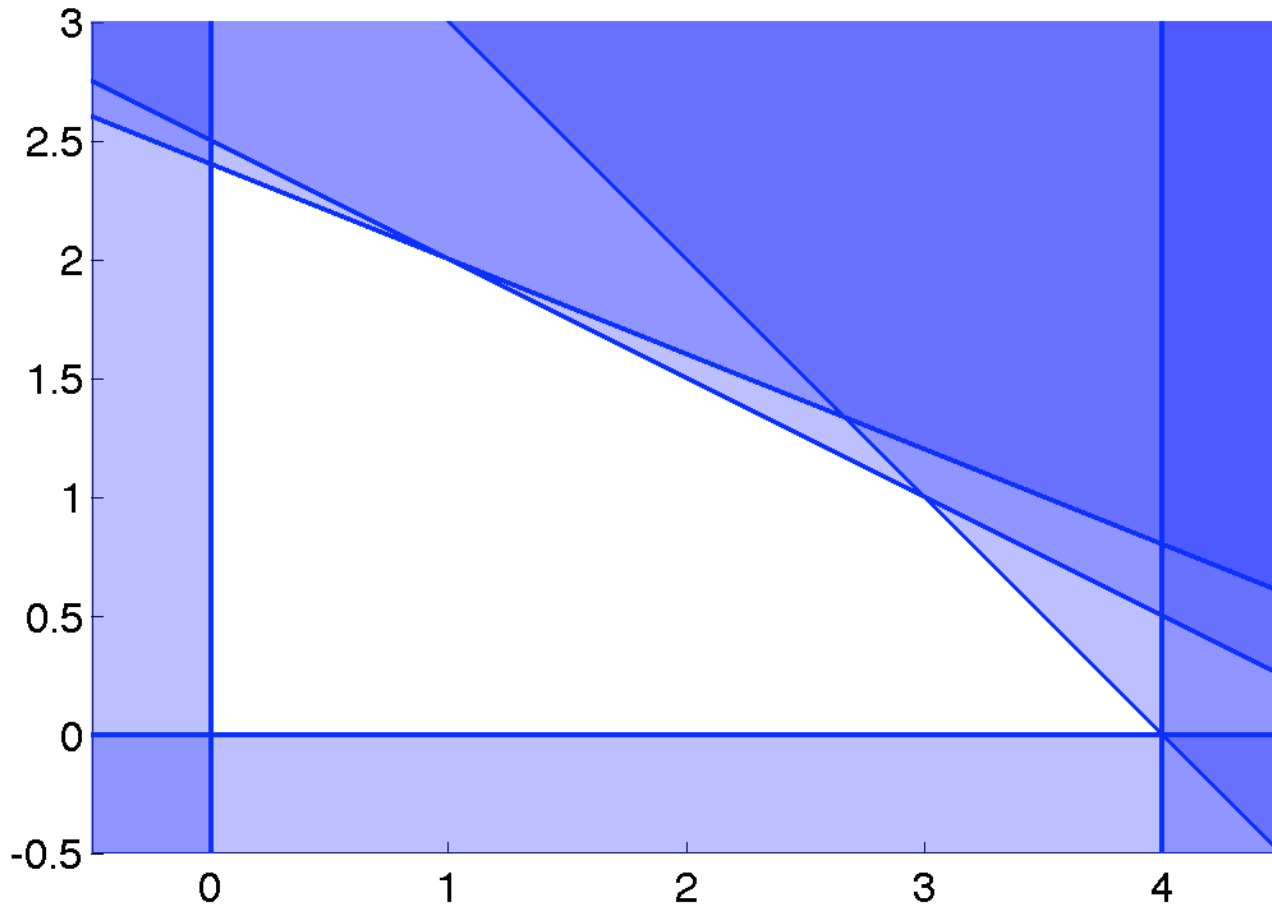
def'n: pivot, enter, exit

Example

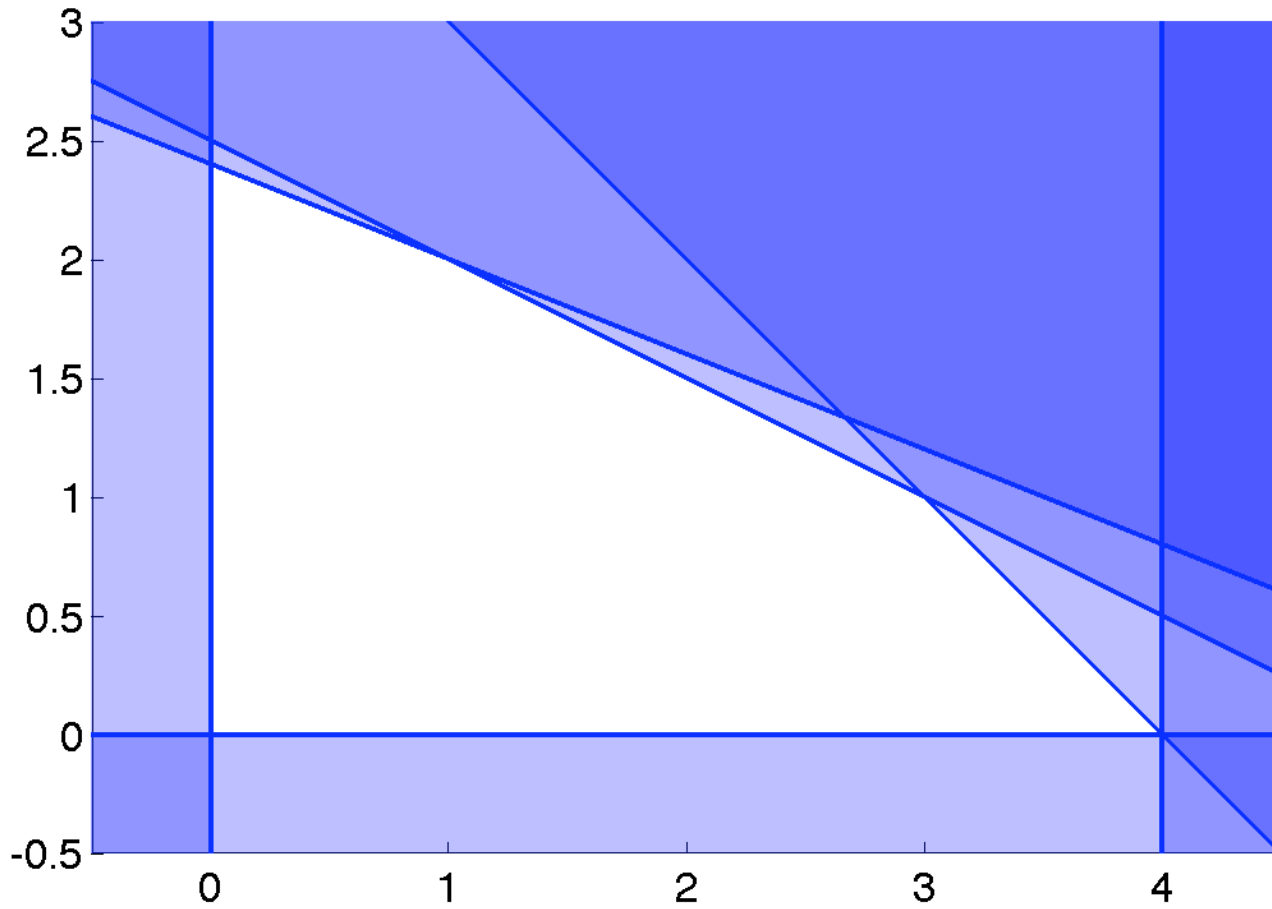
$$\begin{aligned} \max z &= 2x + 3y \text{ s.t.} \\ x + y &\leq 4 \\ 2x + 5y &\leq 12 \\ x + 2y &\leq 5 \\ x &\leq 4 \end{aligned}$$



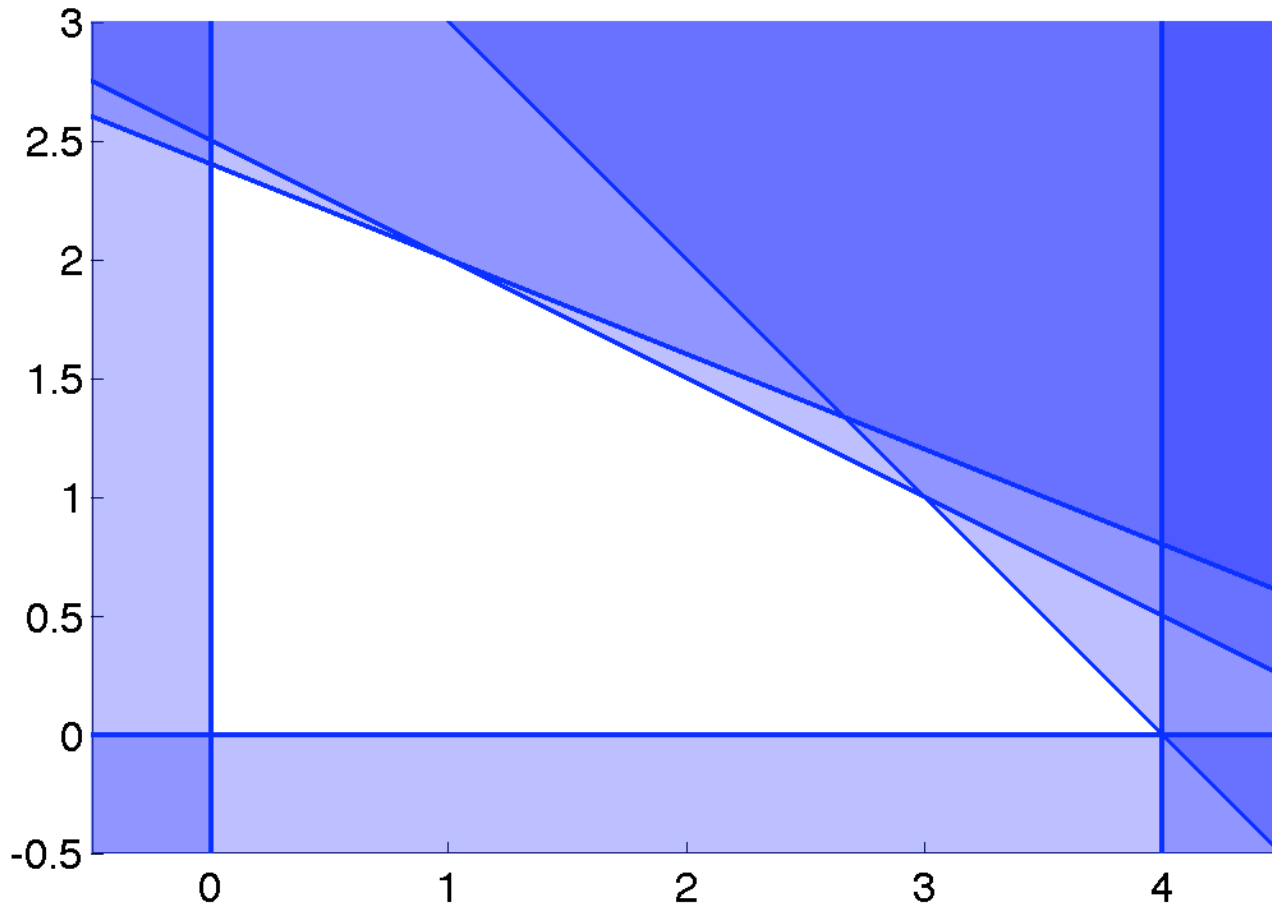
x	y	s	t	u	v	z	RHS
1	1	1	0	0	0	0	4
2	5	0	1	0	0	0	12
1	2	0	0	1	0	0	5
1	0	0	0	0	1	0	4
-2	-3	0	0	0	0	1	0



x	y	s	t	u	v	z	RHS
0.4	1	0	0.2	0	0	0	2.4
0.6	0	1	-0.2	0	0	0	1.6
0.2	0	0	-0.4	1	0	0	0.2
1	0	0	0	0	1	0	4
-0.8	0	0	0.6	0	0	1	7.2

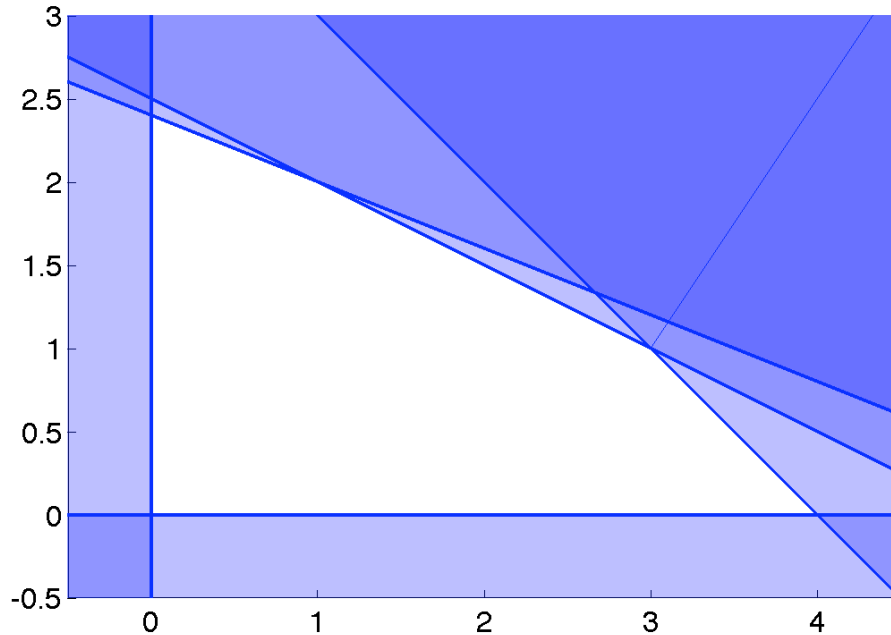


<u>x</u>	<u>y</u>	s	t	u	v	z	RHS
1	0	0	-2	5	0	0	1
0	1	0	1	-2	0	0	2
0	0	1	1	-3	0	0	1
0	0	0	2	-5	1	0	3
0	0	0	-1	4	0	1	8



<u>x</u>	<u>y</u>	s	t	u	v	z	RHS
1	0	2	0	-1	0	0	3
0	1	-1	0	1	0	0	1
0	0	1	1	-3	0	0	1
0	0	-2	0	1	1	0	1
0	0	1	0	1	0	1	9

Initial basis



<u>x</u>	<u>y</u>	<u>u</u>	<u>v</u>	<u>w</u>	<u>RHS</u>
1	1	1	0	0	4
2	5	0	1	0	12
1	2	0	0	1	5

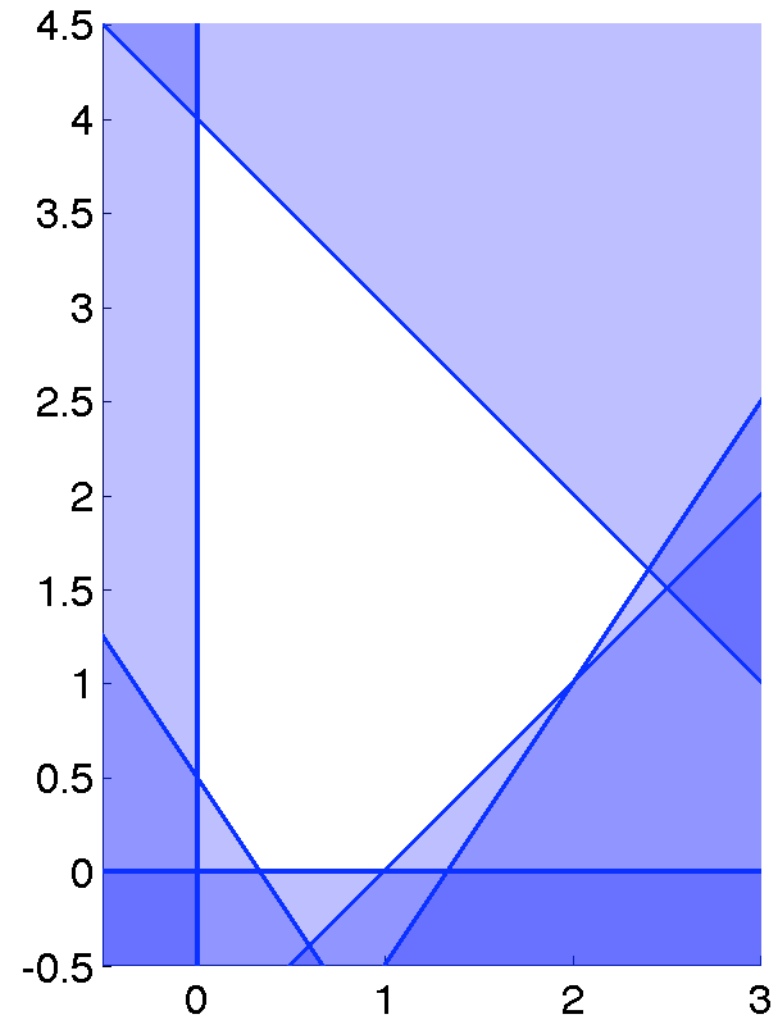
- So far, assumed we started w/ feasible basic solution—in fact, it was trivial to find one
- Not always so easy in general

Big M

$$0 \leq x, y, s_1 \dots s_6$$

$$\max x - 2y$$

<u>x</u>	<u>y</u>	<u>slacks</u>				<u>z</u>	<u>RHS</u>
1	1	1	0	0	0	0	4
3	-2	0	1	0	0	0	4
1	-1	0	0	1	0	0	1
-3	-2	0	0	0	1	0	-1
-1	2	0	0	0	0	1	0



- Can make it easy: variant of slack trick
 - ▶ For each violated constraint, add var w/ coeff -1
 - ▶ Penalize in objective; negate constraint

Simplex in one slide

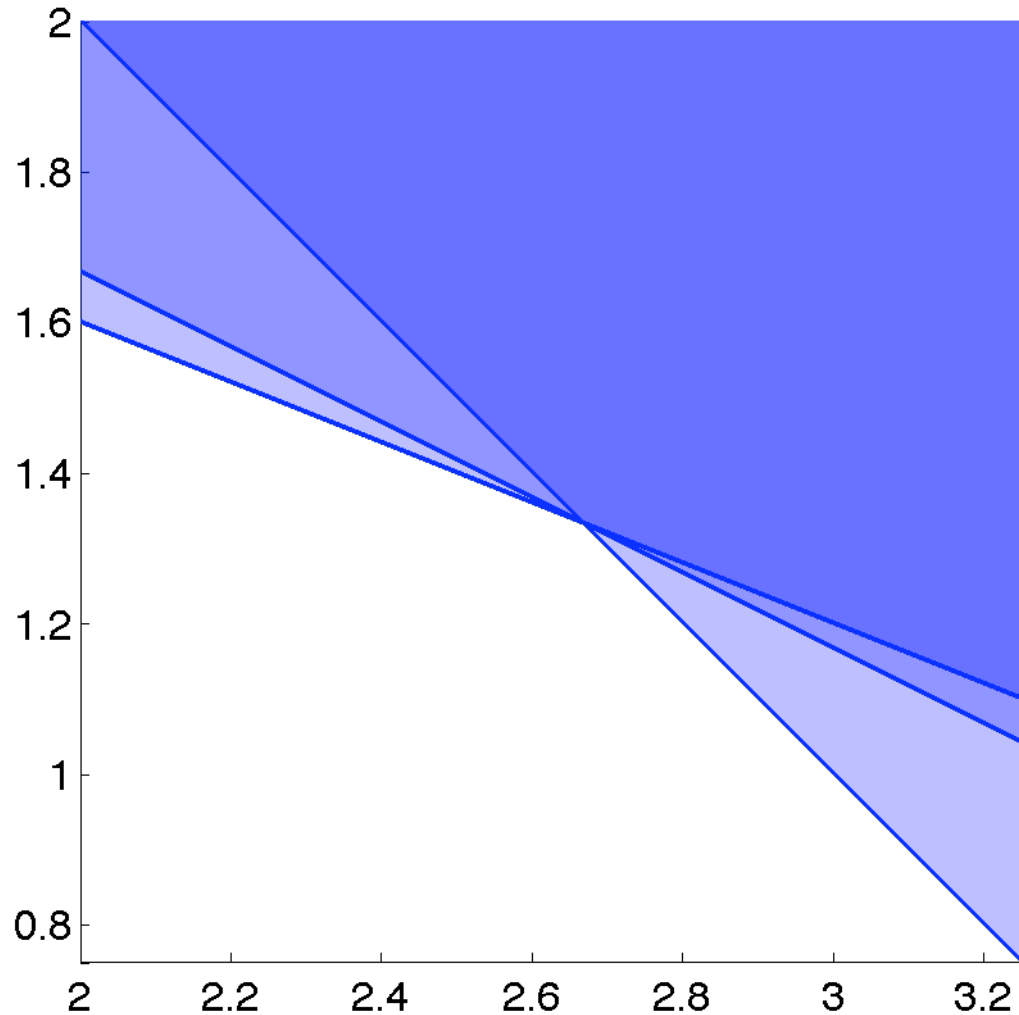
(skipping degeneracy handling)

- Given a nonsingular standard-form max LP
- Start from a feasible basis and its tableau
 - ▶ big-M if needed
- Pick non-basic variable w/ coeff in objective ≤ 0
- Pivot it into basis, getting neighboring basis
 - ▶ select exiting variable to keep feasibility
- Repeat until all non-basic variables have objective ≥ 0

Degeneracy

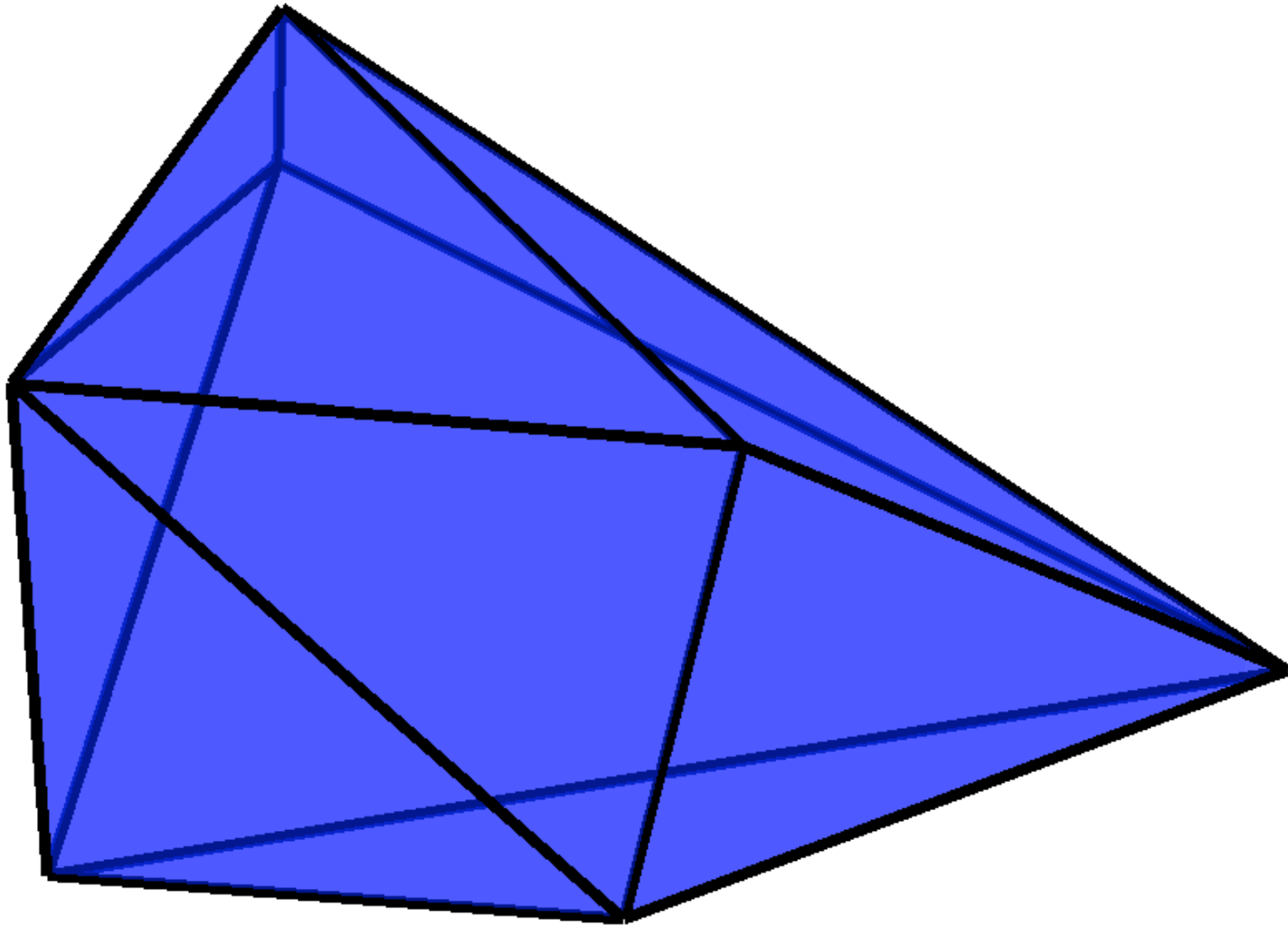
- Not every set of m variables yields a corner
 - ▶ some have rank $< m$ (not a basis)
 - ▶ some are infeasible
- Can the reverse be true? Can two bases yield the same corner?

Degeneracy



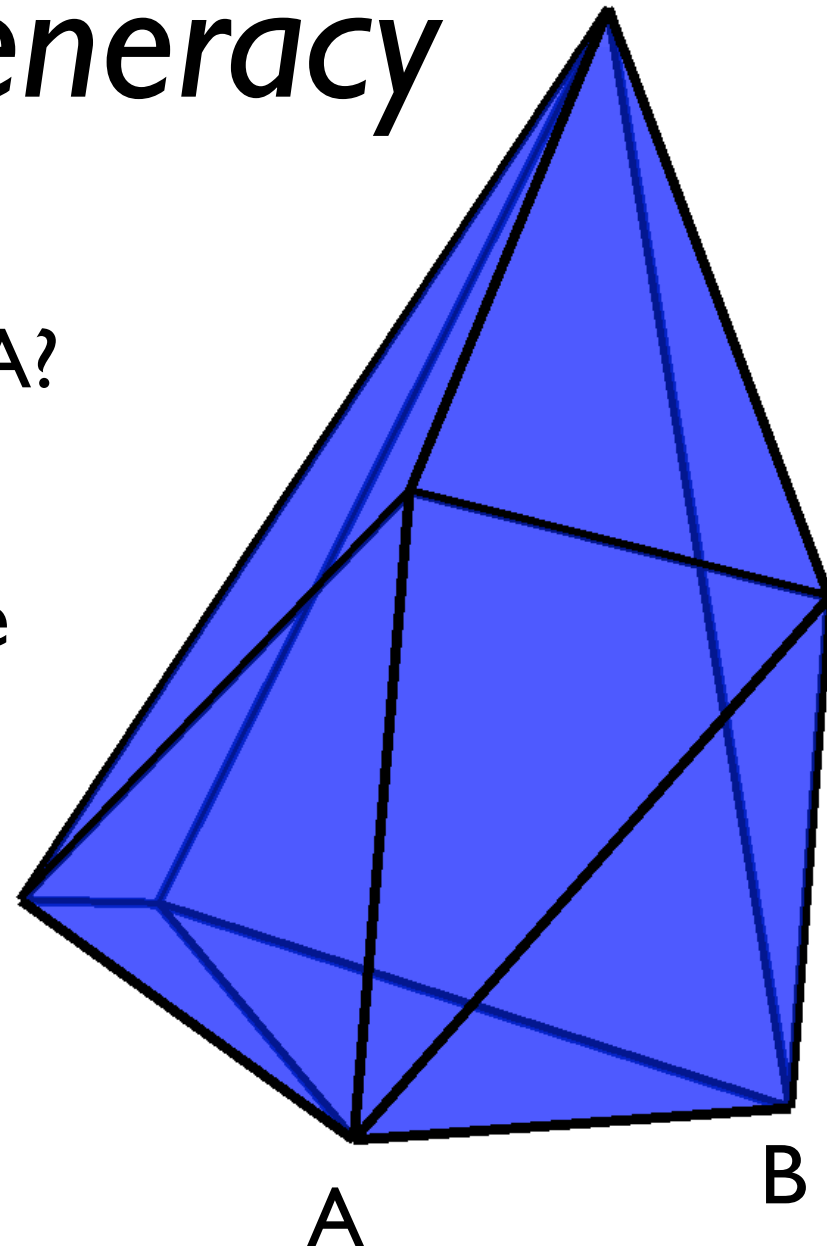
<u>x</u>	<u>y</u>	<u>u</u>	<u>v</u>	<u>w</u>	<u>RHS</u>
1	1	1	0	0	4
2	5	0	1	0	12
1	2	0	0	1	16/3
1	0	0	-2	5	8/3
0	1	0	1	-2	4/3
0	0	1	1	-3	0
1	0	2	0	-1	8/3
0	1	-1	0	1	4/3
0	0	1	1	-3	0

Degeneracy in 3D



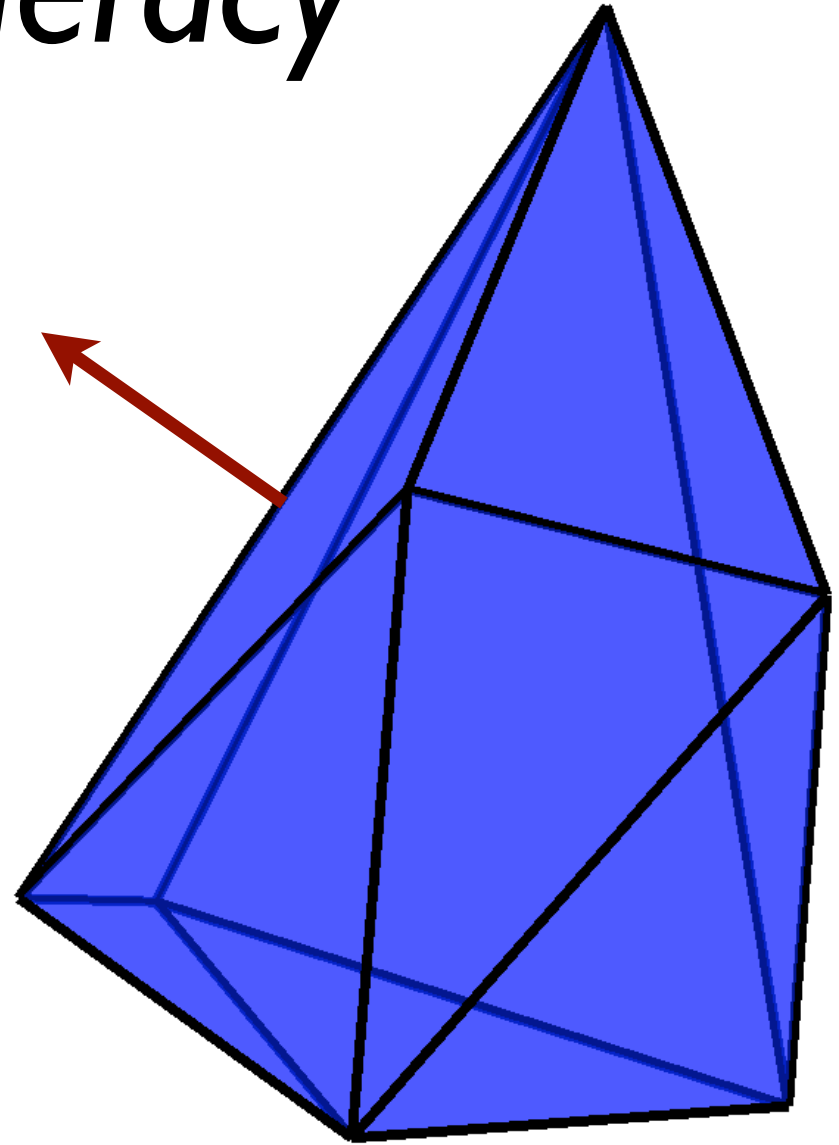
Bases & degeneracy

- How many bases for vertex A?
 - ▶
- Are they all neighbors of one another?
 - ▶
- Are they all neighbors of B?
 - ▶



Dual degeneracy

- More than m entries in objective row = 0
 - ▶ so, a nonbasic variable has reduced cost = 0
 - ▶ objective orthogonal to a d -face for $d \geq 1$



Handling degeneracy

- Sometimes have to make pivots that don't improve objective
 - ▶ stay at same corner (exiting variable was already 0)
 - ▶ move to another corner w/ same objective (coeff of entering variable in objective was 0)
- Problem of cycling
 - ▶ need an anti-cycling rule (there are many...)
 - ▶ e.g.: add tiny random numbers to obj, RHS