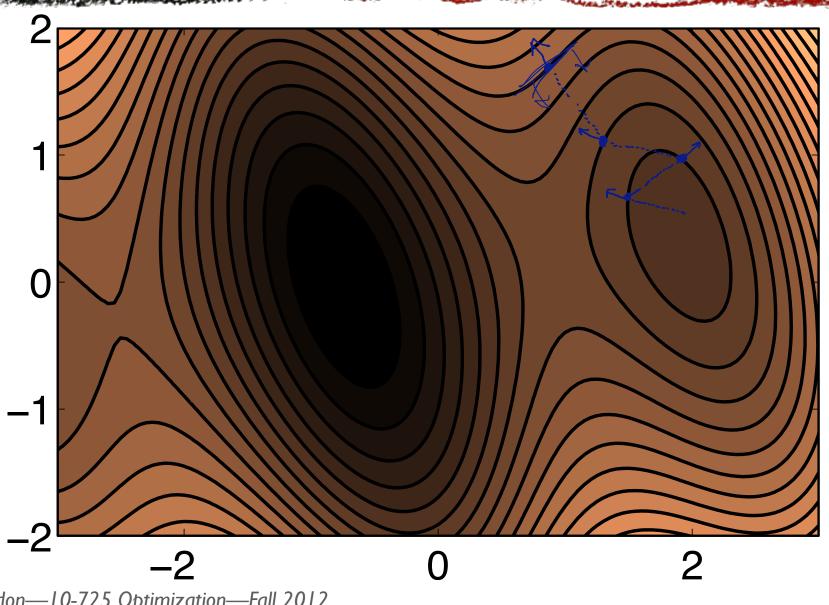
### First-order methods Convexity

10-725 Optimization Geoff Gordon Ryan Tibshirani

#### Gradient descent

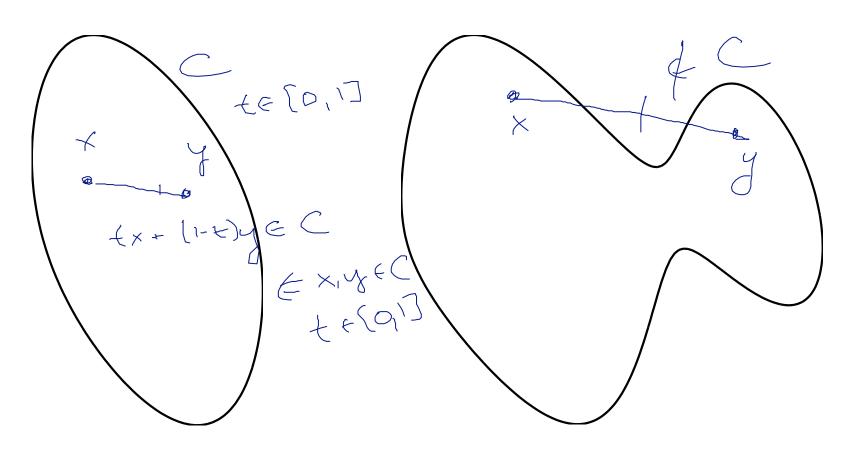


### When do we stop?

• Using holdout set, if  $f(x) = E(f_i(x) | i \sim P)$ 

- Using convergence bounds (later)
  - usual form is:
    - $ightharpoonup K_f(f(x_0) f(x^*))$  [some fn of  $1/\epsilon$ ]
  - need estimates of first two terms
- For  $f(x^*)$ , duality (later); for  $K_f$ , properties of f:
  - convex? strongly convex? Lipschitz?

### Convex sets



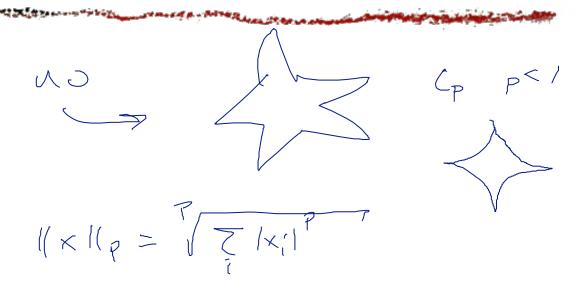
For all  $x, y \in C$ , for all  $t \in [0, 1]$ :  $tx + (I-t)y \in C$   $P(x) \in C$   $E_{x \sim P}(x) \in C$ 

### Examples

point

yes

rive  $||x||_p \leq ||$ 



• x on boundary of C ( $\partial$ C) if:

 $B_{p}(x, \epsilon) \wedge C \neq \emptyset$   $B_{p}(x, \epsilon) \wedge C \neq \emptyset$ 

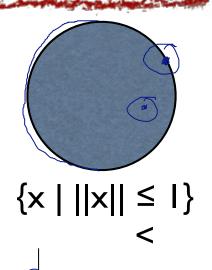
• x in interior of C if:

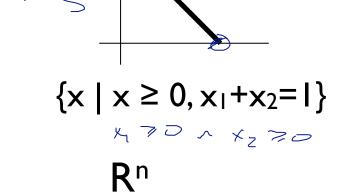
Bp (x, e) = C for small E

• x in *relative* interior (rel int C) if:

subspace SDC restrict to 5

- C closed if: gc ⊆ C
- Copen if:  $3 \subset \land C = 4$
- C compact if: closed bounded





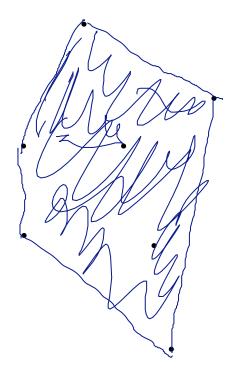
#### Convex hull

{ Za; x! | x; e (, a; ≥0, 29;=1)}

Any closed, convex C

= hill (X)

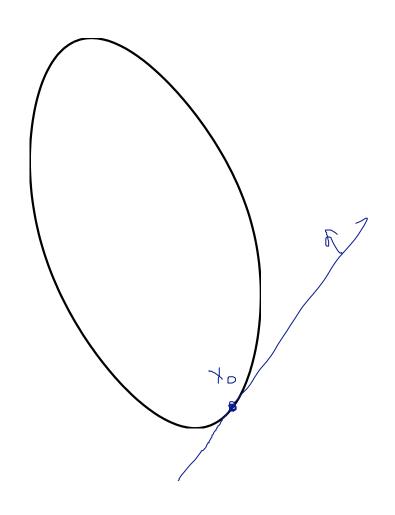
| X | = 00



### Dual representation

C= 1 {x | q-x++ <0} ~ 97,5; Any closed conex C
= this

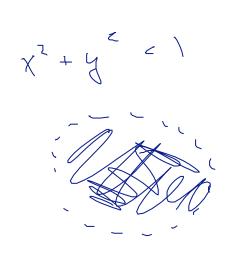
### Supporting hyperplane thm

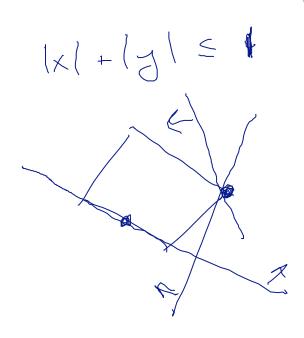


- For any point x<sub>0</sub> on boundary of convex C:
  - exist (w, b) with

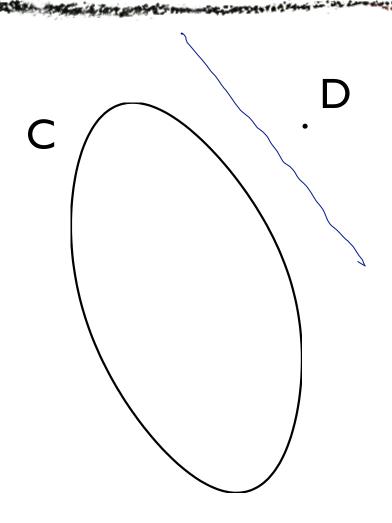
  - $x_0. \omega = 5$   $x. \omega \leq 5$   $\forall x \in C$

## Supporting hyperplane exs





### Separating hyperplane thm



- For any convex C and D with  $C \cap D = \emptyset$ 
  - ▶ exist (w, b) with
  - W·x ≥ b
     W-x ≥ b
     X ∈ T
- If both C, D are closed,
   and at least one compact:

Strict W.X < b

# Separating hyperplane exs

halfspace à complement

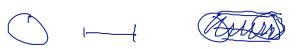
J= 1/x

MM

Y = 0

## Proving a set convex

- Use definition directly  $t \times + (1-t)y$
- Represent as convex hull or ∩ of halfspaces
- Supporting hyperplane partial converse
  - C closed, nonempty interior, has supporting hyperplane at all boundary points ⇒ C convex
- Build C up from simpler sets using convexitypreserving operations

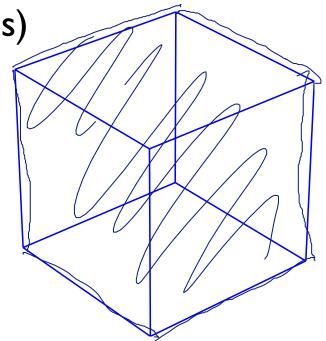


### Convexity-preserving set ops

• Translation 
$$\{x + b \mid x \in C\}$$



- projection (e.g., dropping coords)
- Intersection < ∩ </li>
- Set sum C+D= {x+y | xeC yeD}
- Perspective (x,y,z) EC 270 (x/2 \\ \/ 2)

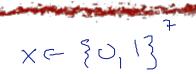


### Ex: symmetric PSD matrices

$$\times^{T}A \times \geq 0 \quad \forall \times$$

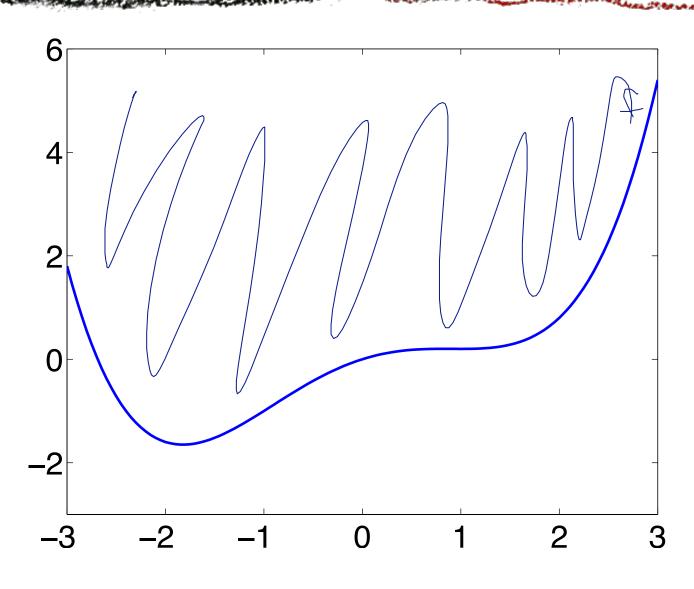
• Two proofs that  $\{A \mid A = A^T, A \ge 0\}$  is convex

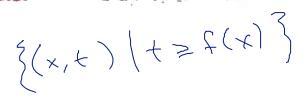
#### Ex: conditionals



- Given a convex set of dist'ns  $P(x_{1:7})$ ,
  - $P(x_{1:5} \mid x_{6:7}) = P(x_{1:7}) / P(x_{6:7})$
  - numerator:
  - denominator:
- Convex?

## Epigraph





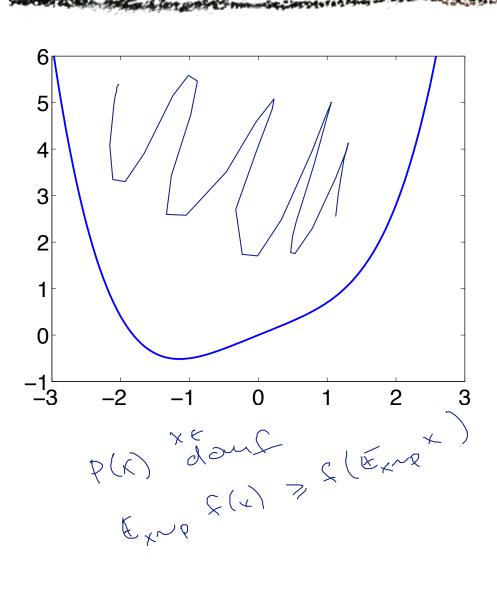
#### Domain

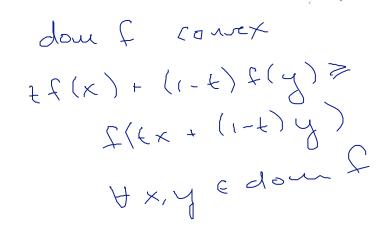
• dom 
$$f = \begin{cases} x \mid f(x) \in xists & f(x) < m \end{cases}$$

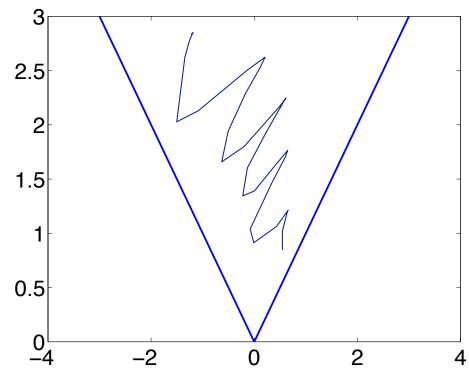
- dom  $1/x = \mathbb{R} \{0\}$
- dom ln(x) =

#### froncex epif ronnex

### Convex functions



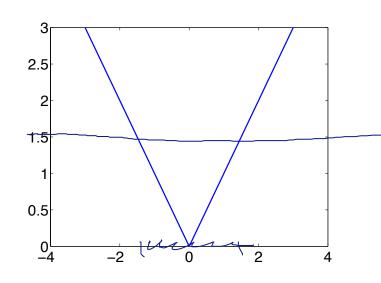




### Relating convex sets and fns

Sublevel sef

- $f(x) convex \Rightarrow \{x \mid \mathcal{L}(x) \in \mathcal{L} \} convex$
- Converse?



## Proving a function convex

- Use definition directly
- Prove that epigraph is convex via set methods
  - e.g., supporting hyperplanes: for all x, y,  $f(x) = f(y) + (x-y)^{\frac{1}{2}}$
  - this is first-order convexity condition for fns
- 2nd order:  $\frac{d^2}{dx^2} \mathcal{L}(x) \ge 0$
- Construct f from simpler convex fns using convexity-preserving ops

### Convexity-preserving fn ops

- Nonnegative weighted sum ( + + 5) (x) = 4 (x)

  + 6 q (x)
- Pointwise max/sup g(x) = S P G(x)
- Composition w/ affine \$\(\mathcal{L}(\mathcal{L} \times \delta)\)
- Composition w/ monotone convex
- Perspective f(x,t) = f(x/t)t

g monotore convex g(f(x))

epij

- f(x, y) convex in (x, y), set C convex:
  - ▶  $g(y) = \min_{x \in C} f(x,y)$  is convex if  $g(y) > -\infty$

epi 5 = 3(x,y,t) \ > 5(x,y)}

# Example: f(x) = |x|

$$|x| \ge x$$

$$|x| \ge x$$

$$|x| \ge -x$$

#### In 2 or more dimensions

 $f(x) > f(x) + (x-y) \cdot \nabla f(y)$ 

All the above, but for 2nd order:

$$H = \frac{d^2}{dx^2} f(x)$$

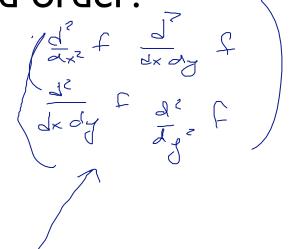
$$H \ge 0$$
eig(H)

reduce to ID

Or: reduce to ID

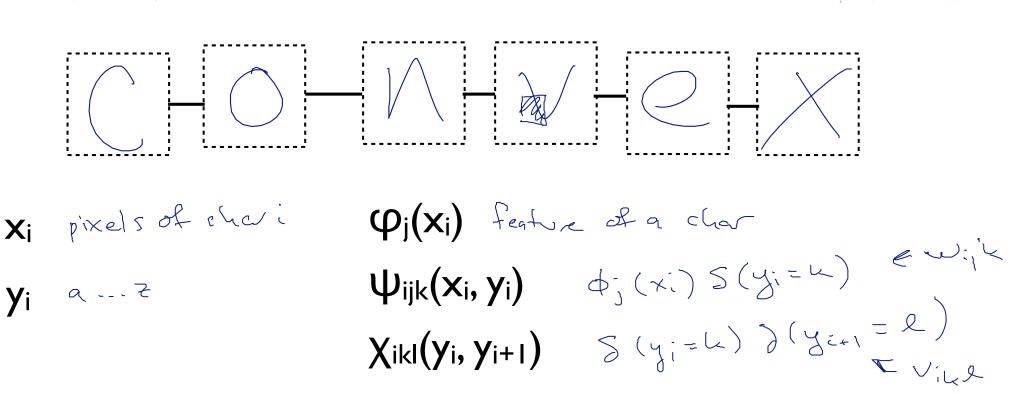
$$Xo + td$$

$$f(Xo + td)$$



### Ex: structured classifier

### Ex: structured classifier



$$L(x,y;v,w) = \sum_{j \in \mathcal{X}} \psi_{ijk} \omega_{ijk} + \sum_{ike} \chi_{ike} (y_{i}, y_{ik})^{\vee} ike$$

Classifier: y = arg max L(x,y,v,w)

Geoff Gordon—10-725 Optimization—Fall 2012

## Learning structured classifier

- Get it right if: (<, y; v, w) > (<, y', v, w')
- So, want: L(x,y;y,ω) ≥ max(((κ,y';y,ω) + π(y,y'))

- RHS LHS: convex