

# Lecture 19

## ITK's Path Framework

(Bio)Medical Image Analysis - Spring 2025  
16-725 (CMU RI) : BioE 2630 (Pitt)  
Dr. John Galeotti



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# Preface



- This is based on the slides I presented at MICCAI 05's ITK workshop.
- They discuss the motivation and usage for the unified path framework I added to ITK.
- You can see the related Insight Journal article at <http://hdl.handle.net/1926/40>
  - (Note: It used to be one of the top-rated journal articles until I.J. was redone, and all the old reviews were scrapped.)



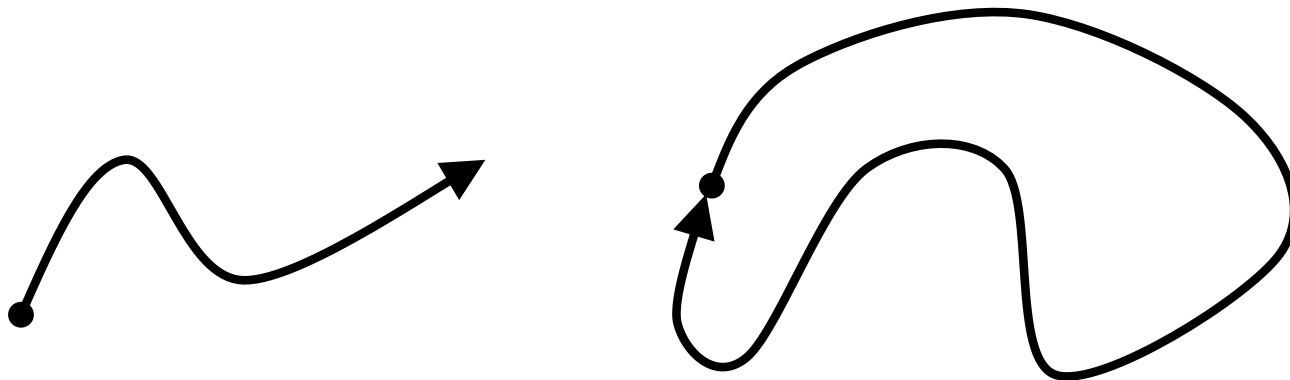
# Introduction



- The need for paths in ITK
- Basic concepts and path types
- Implementation details
- Example usage

# The Need for Paths in ITK

- A path is a curve that maps a scalar value to a point in n-dimensional space





# The Need for Paths in ITK



- Paths are useful for:
  - Segmentation algorithms
    - Active contours, snakes, LiveWire
  - Ridge tracking
  - Path planning
  - User interaction
- Implementation of the above in ITK can be simplified by having a common, existing path framework.



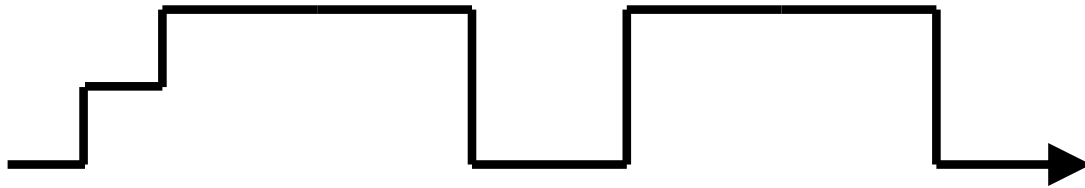
# The Need for Paths in ITK



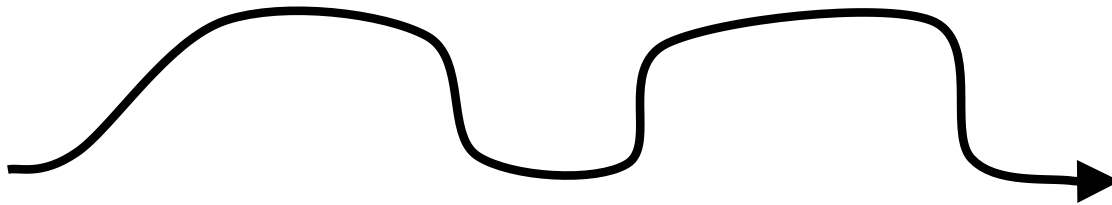
- Unfortunately, the ITK pipeline was originally designed to operate on image and mesh data types
  - Neither images nor meshes are well suited for path representation

# Basic Concepts and Path Types

- Two common types of paths:
- Chain codes are a type of discrete curve

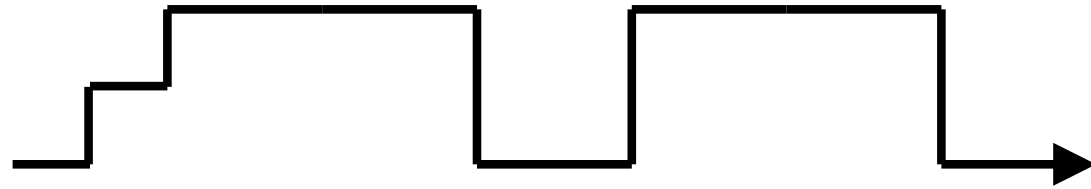


- Parametric curves are continuous



- Other types of paths are also possible

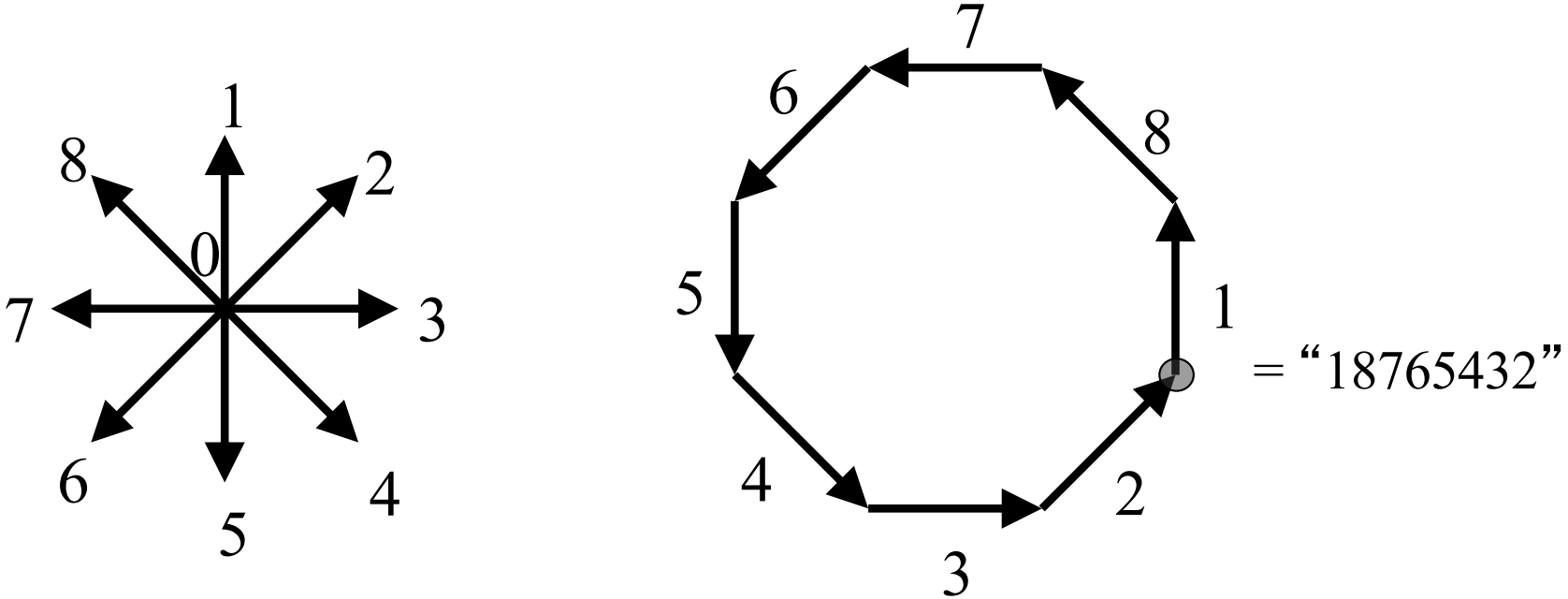
# Chain Codes



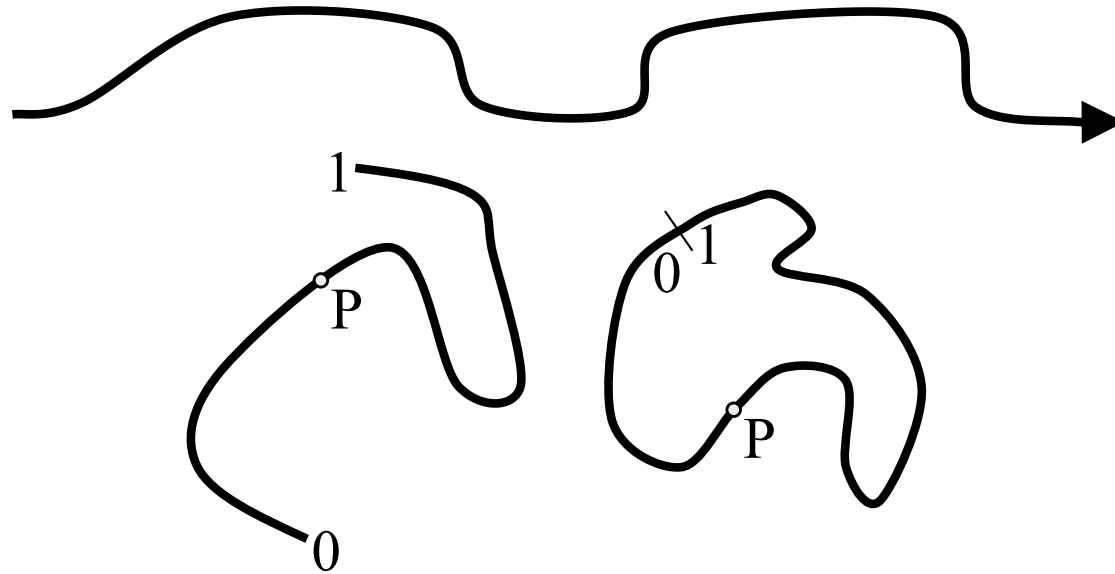
- Represent a path as a sequence of offsets between adjoining voxels
- Provide efficient incremental access and comparatively poor random index access



# 2D Chain Code Example: Freeman Code



# Parametric Curves



- Represent a path as an algebraically defined curve parameterized over a scalar input
- Provide efficient random access and comparatively poor incremental index access
  - Difficult to know how much to increment the parameterized input to reach the next voxel



# Implementation Details



- Necessary Functionality
- Path class hierarchy
- Path iterators
- Path filter hierarchy



# Necessary Functionality



- Efficiency
- Handle open, closed, & self-crossing paths
- Iterate along a path through an image
- Examine image data in an arbitrarily defined neighborhood surrounding any given point along a path

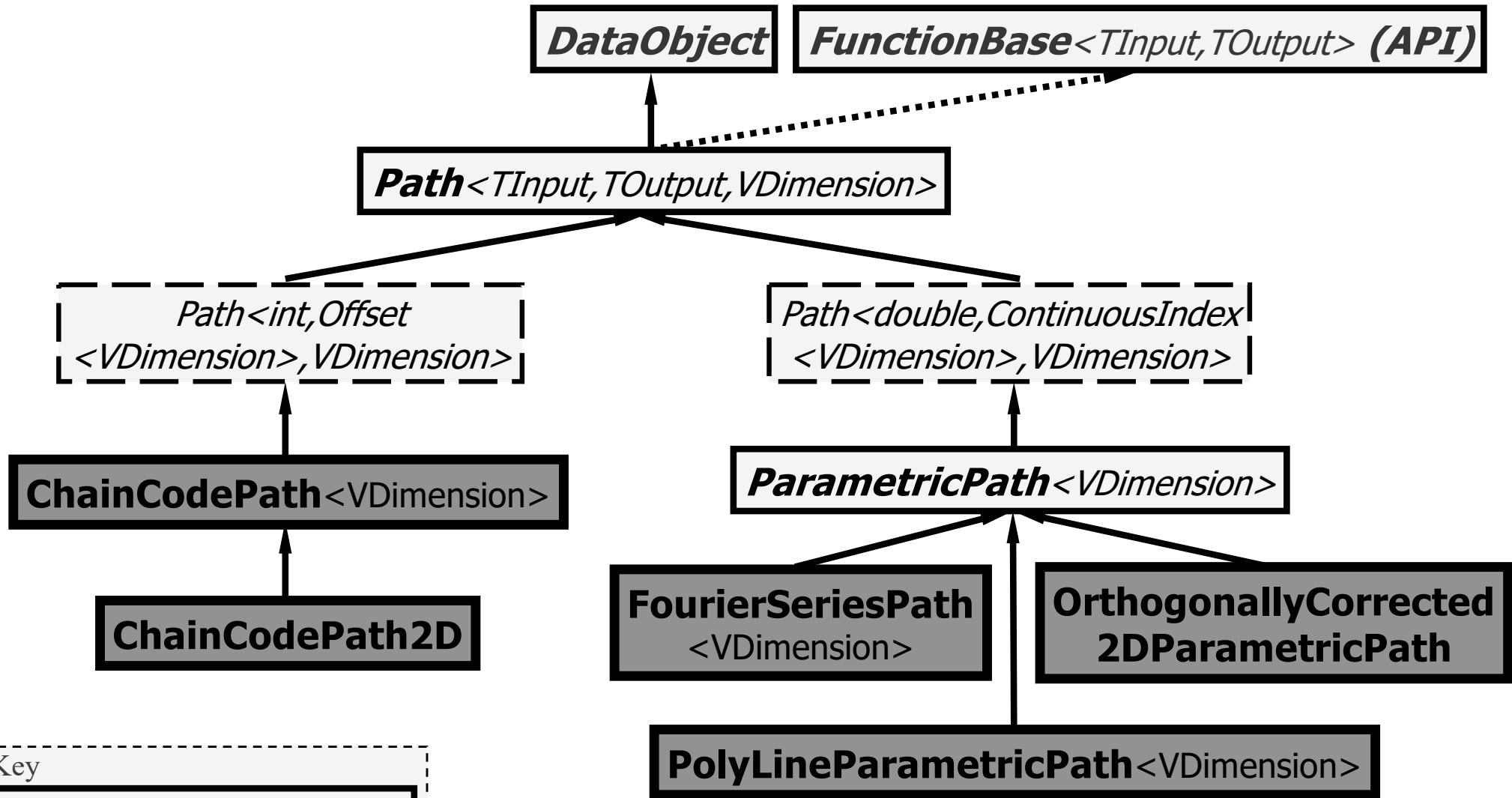


# Necessary Functionality



- Create and modify arbitrary chain codes
- Smooth paths in continuous index space
- Find exact normals to smooth paths
- Distort paths by orthogonal offsets at regular spacing
- Support user interaction

# Path Class Hierarchy



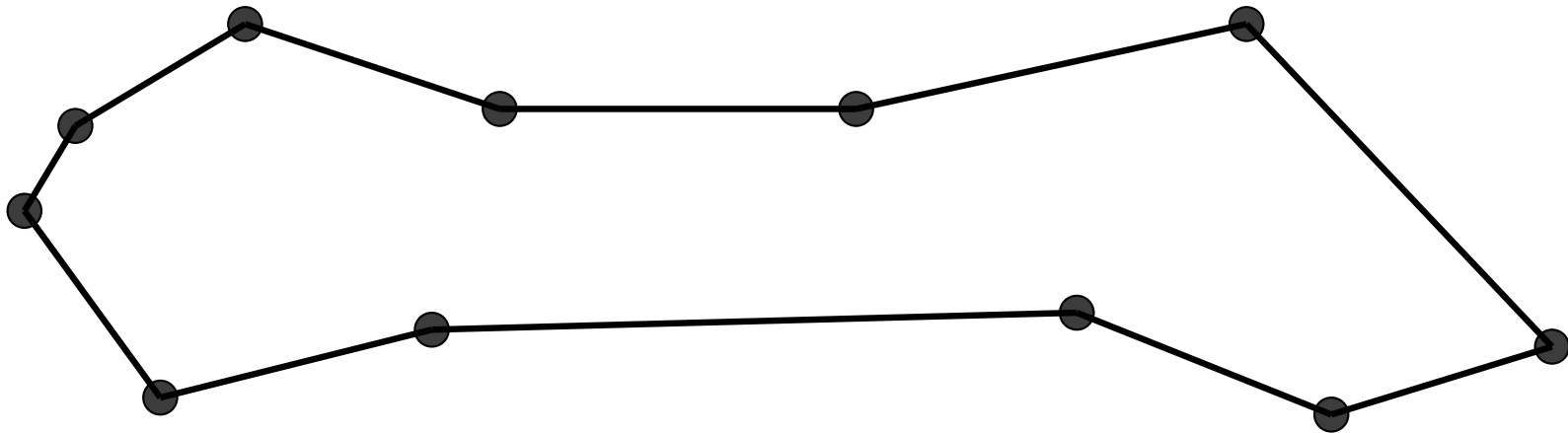
Key

***Abstract Base Class***

**Instantiatable Class**

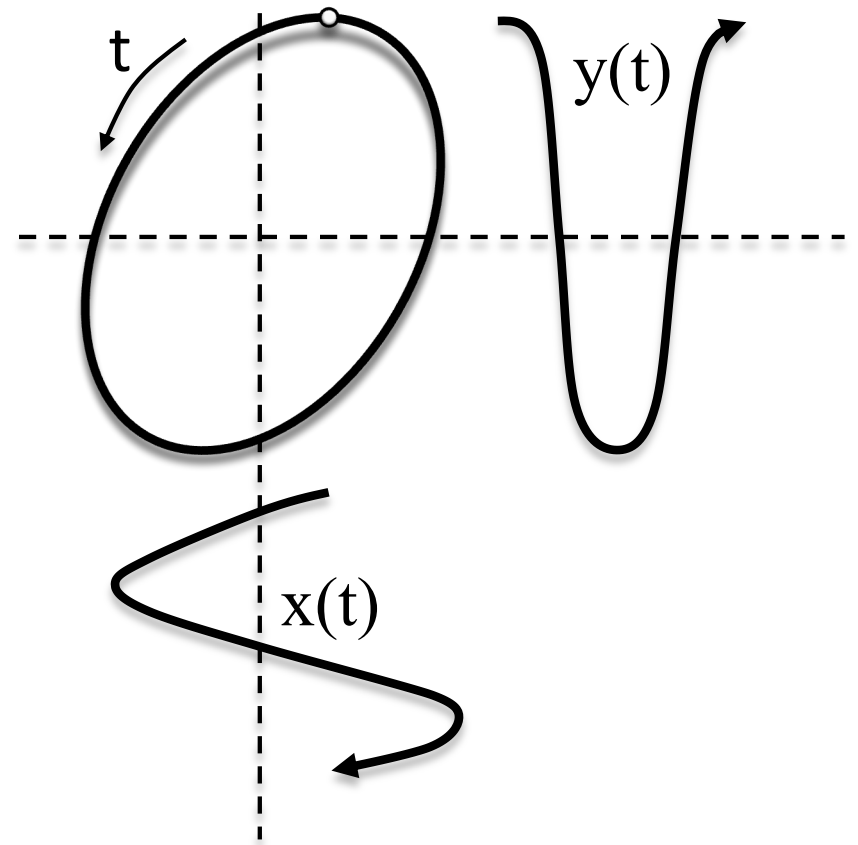
# PolyLineParametricPath

- Represents a path as a series of vertices connected by line segments
- Provides a simple means of creating a path that can then be converted to other path types



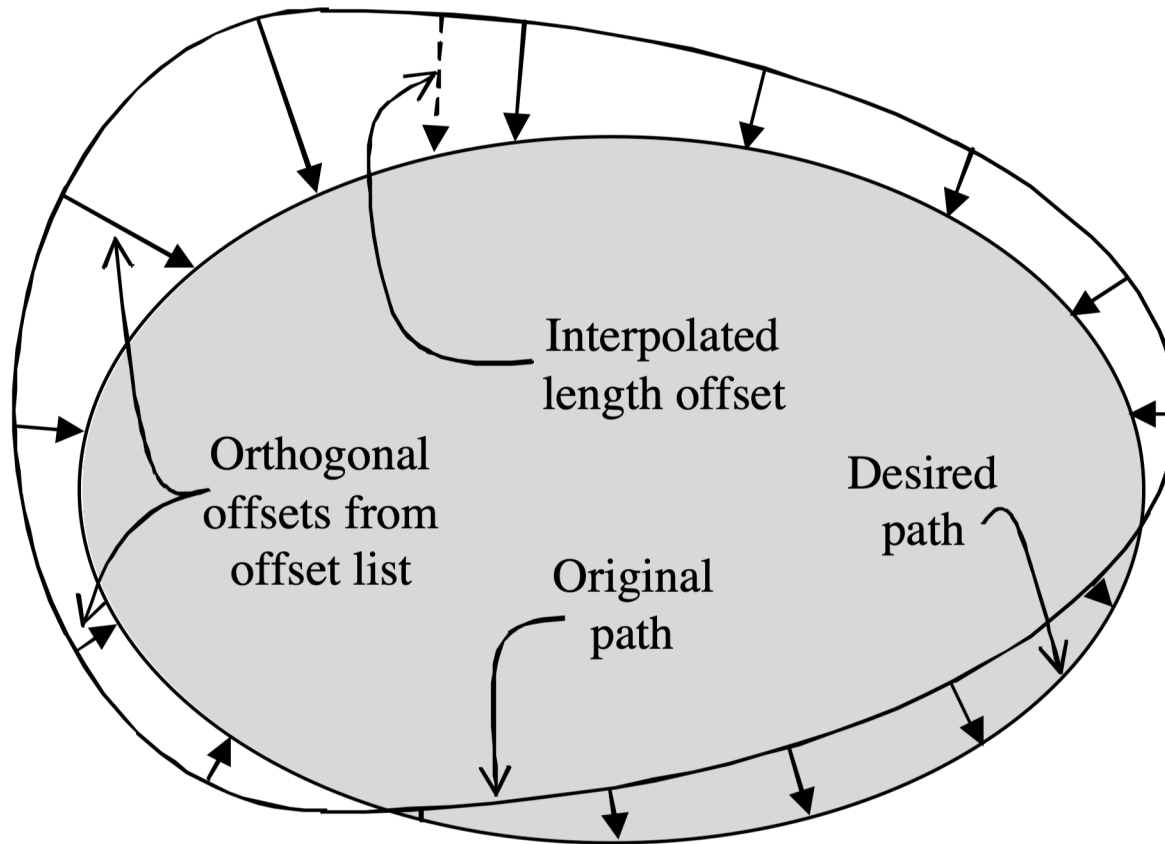
# FourierSeriesPath

- Represents a closed path by its Fourier coefficients in each dimension
- Has continuous well-defined derivatives with respect to its input
  - At all points along the curve, the normal direction is well-defined and easy to compute.



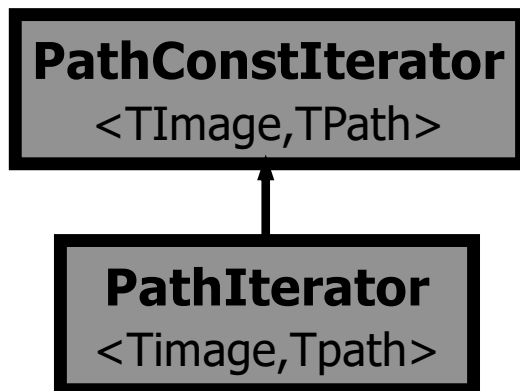


# Orthogonally Corrected Path



# Path Iterators

- Iterators traverse paths through images
  - Allows const paths
  - Necessary for path inputs in pipeline
- Implemented a universal path iterator



# Path Iterators: Implementation

- Iterators traverse paths through images
  - Paths do not store a current position; iterators do
  - Allows const paths with many concurrent positions
  - The path iterator is able to traverse any type of path
- Path iterators are supported by the **Path::IncrementInput (InputType & Input)** function
  - All paths must know how much to increment a given path input to advance the path output to the next neighboring voxel along the path
  - For efficiency, **IncrementInput ()** returns the offset resulting from its modification of Input

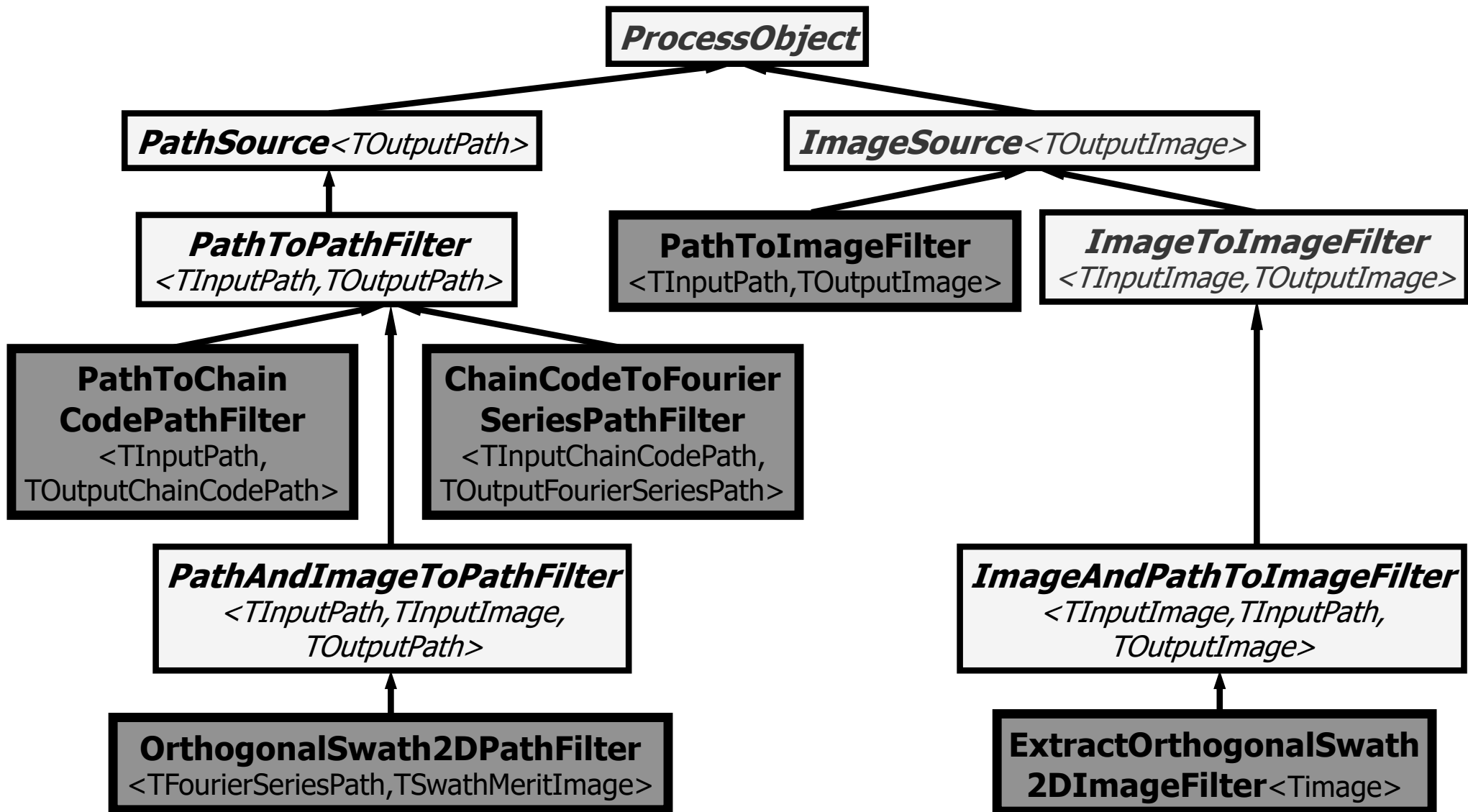
# Current Base Class API

- **Path<TInput, TOutput, VDimension>**
  - **virtual InputType StartOfInput() const**
  - **virtual InputType EndOfInput() const**
  - **virtual OutputType Evaluate(InputType) const =0**
  - **virtual IndexType EvaluateToIndex(InputType) const =0**
  - **virtual OffsetType IncrementInput(InputType) const =0**
- **PathConstIterator<TImage, TPath>**
  - **GoToBegin()**
  - **bool IsAtEnd()**
  - **operator++()**
  - **IndexType GetIndex()**
  - **PathInputType GetPathPosition()**

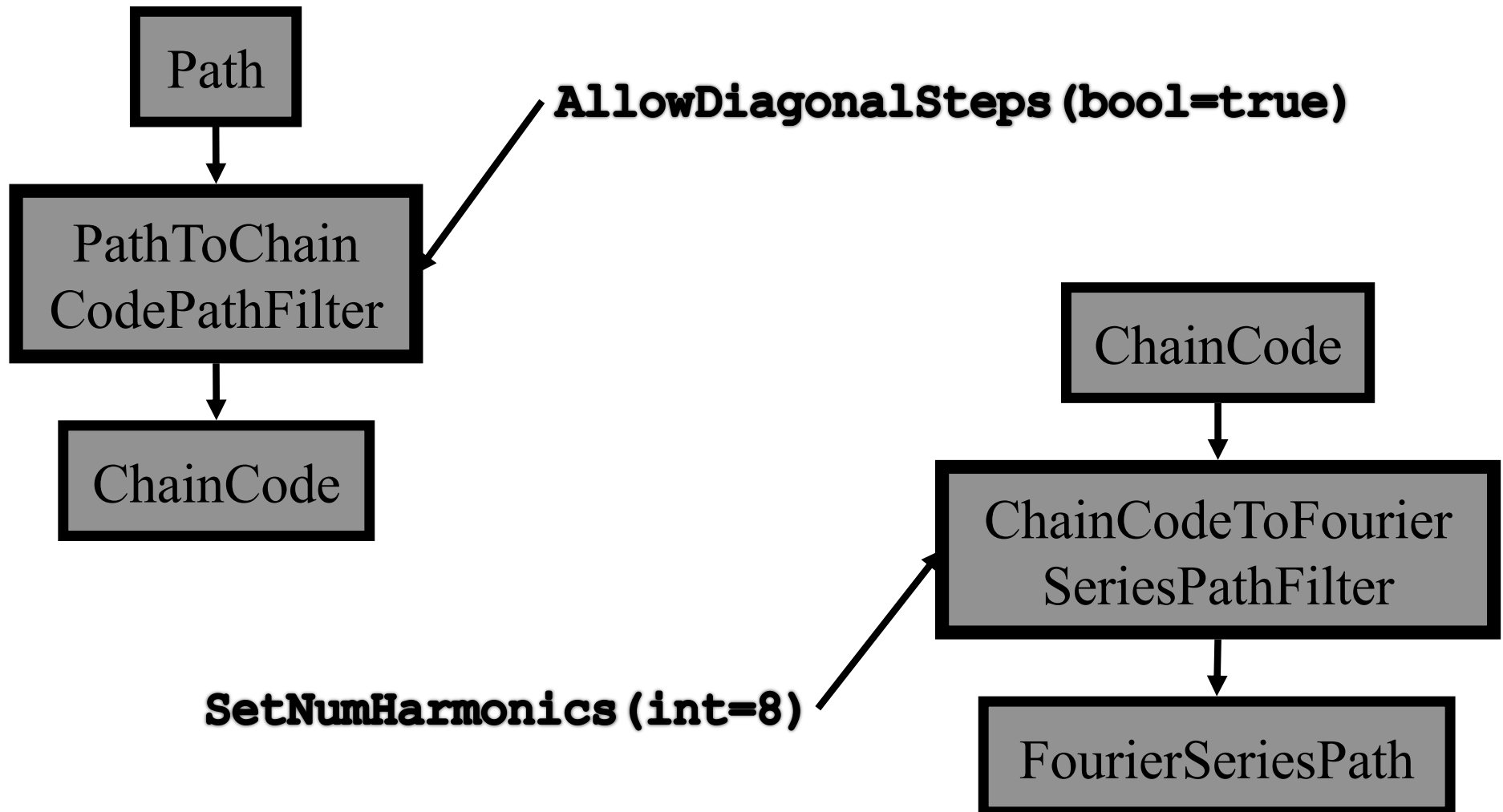
# Subclass API Extensions

- **ChainCodePath<VDimension>**
  - **SetStart (IndexType)**
  - **IndexType GetStart () const**
  - **unsigned NumberOfSteps () const**
  - **InsertStep (InputType position, OffsetType step)**
  - **ChangeStep (InputType position, OffsetType step)**
  - **Clear ()**
- **ParametricPath<VDimension>**
  - **VectorType EvaluateDerivative (InputType) const**
- **FourierSeriesPath<VDimension>**
  - **AddHarmonic (VectorType CosCoef, VectorType SinCoef)**
  - **Clear ()**

# Path Filter Hierarchy



# Conversion Filters





# Philosophical Comparison with Spatial Objects



- Spatial Objects represent geometric shapes (and therefore their associated boundaries)
  - A Spatial Object's interior is well defined
- Paths represent sequences of connected indices
  - A path may not be closed (no interior defined)
  - A closed path's interior is difficult to compute





# Empirical Comparison with Spatial Objects

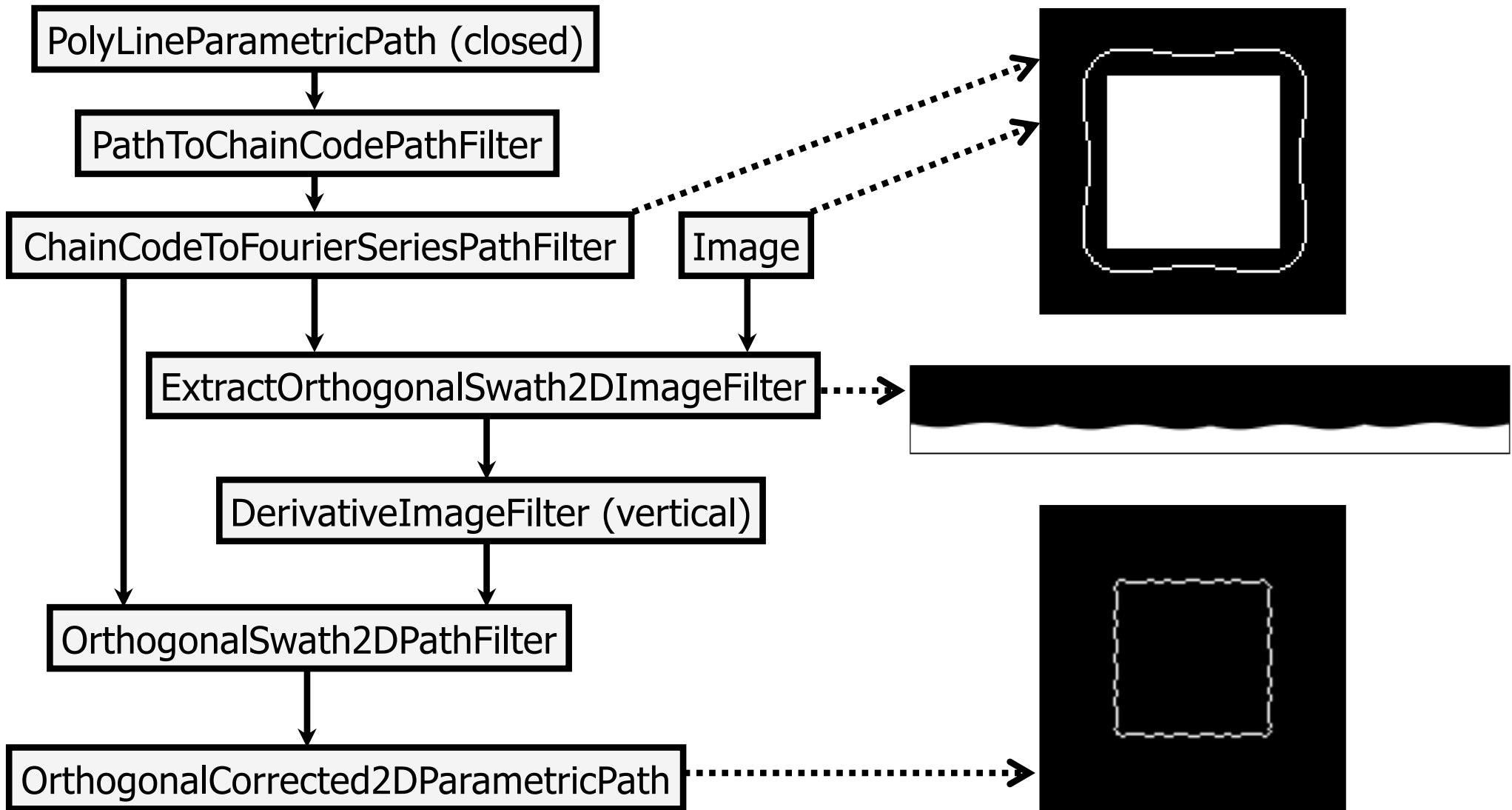


- Spatial Objects are well suited to rendering, analysis, and data interchange
- Paths are well suited to computation, optimization, and iterator direction control
- ITK could be extended to enable simple conversion by:
  - Making a Spatial Object that uses one or more paths as an internal representation
  - Making a Path that uses one or more intersecting spatial objects as an internal representation

# Example Usage

- Implementation of a published 2D active contour algorithm
  - Finds optimal orthogonal offsets at evenly spaced points along an initial path
  - Requires that neighboring offsets differ in value by at most one
- Added to ITK, including demonstration test code
  - **Modules/Filtering/Path/test/itkOrthogonalSwath2DPathFilterTest.cxx**

# OrthogonalSwath2DPathFilter





# Conclusion



- Added user-extensible path support to ITK
  - Data type hierarchy
  - Iterators
  - Filter hierarchy
  - Example implementation in test code
- New core data types *can* be added to ITK!