Supplementary Notes on Static and Dynamic Semantics

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In this lecture we illustrate the basic concepts underlying the static and dynamic semantics of a programming language on a very simple example: the language of arithmetic expression augmented by variables and definitions.

The static and dynamic semantics are properties of the abstract syntax (terms) rather than the concrete syntax (strings). Therefore we will deal exclusively with abstract syntax here.

The static semantics can further be decomposed into two parts: variable scope and rules of typing. They determine how to interpret variables, and discern the meaningful expressions. As we saw in the last lecture, variable scope is encoded directly into the terms representing the abstract syntax. In this lecture we further discuss the laws governing variable binding on terms. The second step will be to give the rules of typing in the form of an inductively defined judgment. This is not very interesting for arithmetic expressions, comprising only a single type, but it serve to illustrate the ideas.

The dynamic semantics varies more greatly between different languages and different levels of abstraction. We will only give a very brief introduction here and continue the topic in the next lecture.

The basic principle of variable binding called *lexical scoping* is that the name of a bound variable should not matter. In other words, consistently renaming a variable in a program should not affect its meaning. Everything below will follow from this principle.

We now make this idea of "consistent renaming of variables" more precise. The development in [Ch. 5.3] takes simultaneous substitution as a primitive; we avoid the rather heavy notation by only dealing with a single

substitution at a time. This goes hand in hand with the decision that binding prefixes such as x.t only ever bind a single variable, and not multiple ones. We use the notation $\{y/x/t\}$ to denote the result of substituting y for x in t, yet to be defined. With that we will define renaming of x to y with the equation

$$x.t \equiv y.\{y/x\}t$$

which can be applied multiple times, anywhere in a term. For this to preserve the meaning, y most not already occur free in x.t, because otherwise the free occurrence of y would be *captured* by the new binder.

As an example, consider the term

$$let(num(1), x.let(plus(x, num(1)), y.plus(y, x)))$$

which should evaluate to num(3). It should be clear that renaming y to x should be disallowed. The resulting term

$$let(num(1), x.let(plus(x, num(1)), x.plus(x, x)))$$

means something entirely different and would evaluate to num(4).

To make this side condition more formal, we define the set of free variables in a term.

$$FV(x) = \{x\}$$

$$FV(o(t_1,...,t_n)) = \bigcup_{1 \le i \le n} FV(t_i)$$

$$FV(x.t) = FV(t) \setminus \{x\}$$

So before defining the substitution $\{y/x\}t$ we restate the rule defining variable renaming, also called α -conversion, with the proper side condition:

$$x.t \equiv y.\{y/x\}t$$
 provided $y \notin FV(t)$

Now back to the definition of substitution of one variable y for another variable x in a term t, $\{y/x\}t$. The definition recurses over the structure of a term.¹

$$\begin{cases} y/x\}x &= y \\ \{y/x\}z &= z & \text{provided } x \neq z \\ \{y/x\}o(t_1,\ldots,t_n) &= o(\{y/x\}t_1,\ldots,\{y/x\}t_n) \\ \{y/x\}x.t &= x.t \\ \{y/x\}z.t &= x.\{y/x\}t & \text{provided } x \neq z \text{ and } y \neq z \\ \{y/x\}y.t & \text{undefined provided } x \neq z \end{cases}$$

¹It can in fact be seen as yet another form of inductive definition, but we will not formalize this here.

Note that substitution is a *partial* operation. The reason the last case must be undefined is because any occurrence of x in t would be replaced by y and thereby captured. As an example while this must be ruled out, reconsider

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let(num(1), x.let(plus(x, num(1)), y.plus(y, x)))
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which evaluates to num(3). If we were allowed to rename x to y we would obtain

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let(num(1), y.let(plus(y, num(1)), y.plus(y, y)))
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which once again means something entirely different and would evaluate to num(4).

In the operational semantics we need a more general substitution, because we need to substitute one term for a variable in another term. We generalize the definition above, taking care to rewrite the side condition on substitution in a slightly more general, but consistent form, in order to prohibit variable capture.

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\begin{array}{rcl} \{u/x\}x &=& u\\ \{u/x\}z &=& z & \operatorname{provided} x \neq z\\ \{u/x\}o(t_1,\ldots,t_n) &=& o(\{u/x\}t_1,\ldots,\{u/x\}t_n)\\ \{u/x\}x.t &=& x.t\\ \{y/x\}z.t &=& x.\{u/x\}t & \operatorname{provided} x \neq z \text{ and } y \notin \operatorname{FV}(u)\\ \{u/x\}z.t & \operatorname{undefined} & \operatorname{provided} x \neq z \text{ and } y \in \operatorname{FV}(u) \end{array}
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In practice we would like to treat substitution as a total operation. This cannot be justified on terms, but, surprisingly, it works on α -equivalence classes of terms! Since we want to identify terms that only differ in the names of their bound variables, this is sufficient for all purposes in the theory of programming languages. More formally, the following theorem (which we will not prove) justifies treating substitution as a total operation.

Theorem 1 (Substitution and α -Conversion)

- (i) If $u \equiv u'$, $t \equiv t'$, and $\{u/x\}t$ and $\{u'/x\}t'$ are both defined, then $\{u/x\}t \equiv \{u'/x\}t'$.
- (ii) Given u, x, and t, then there always exists a $t' \equiv t$ such that $\{u/x\}t'$ is defined.

We sketch the proof of part (ii), which proceeds by induction on the size of t. If $\{u/x\}t$ is defined we choose t' to be t. Otherwise, then somewhere the last clause in the definition of substitution applies and there is a binder

 $z.t_1$ in t such that $z \in FV(u)$. Then we can rename z to a new variable z' which occurs neither in free in u nor free in $z.t_1$ to obtain $z'.t_1'$. Now we can continue with $z'.\{u/x\}t_1'$ by an appeal to the induction hypothesis.

The algorithm described in this proof is in fact the definition of *capture-avoiding substitution* which makes sense whenever we are working modulo α -equivalence classes of terms. Fortunately, this will always be the case for the remainder of this course.

With the variable binding, renaming, and substitution understood, we can now formulate a first version of the typing rules for this language. Because there is only one type, nat, the rules are somewhat trivialized. Their only purpose for this small language is to verify that an expression e is closed, that is, $FV(e) = \{\}$. In order to specify this inductively, we use a new judgment form a so-called hypothetical judgment. We write it as

$$J_1,\ldots,J_n\vdash J$$

which means that J follows from assumptions J_1, \ldots, J_n . Its most basic property is that

$$J_1, \ldots, J_i, \ldots J_n \vdash J_i$$

always holds, which should be obvious: if an assumption is identical to the judgment we are trying to derive, we are done. We will nonetheless restate instances of this general principle for each case.

The particular form of hypothetical judgment we consider is

$$x_1$$
:nat,..., x_n :nat $\vdash e$: nat

which should be read:

Under the assumption that variables x_1, \ldots, x_n stand for natural numbers, e has the type of natural number.

We usually abbreviate a whole sequence of assumptions with the letter Γ .² We write '·' for an empty collection of assumptions, and we abbreviate \cdot , x:nat by x:nat.

²In [Ch. 6] this is written instead as $\Gamma \vdash e$ ok, where Γ is a set of variables. Since there is only one type, the two formulations are clearly equivalent.

The judgment is defined by the following rules.

$$\frac{x : \mathtt{nat} \in \Gamma}{\Gamma \vdash x : \mathtt{nat}} \qquad \overline{\Gamma \vdash \mathtt{num}(k) : \mathtt{nat}}$$

$$\frac{\Gamma \vdash e_1 : \mathtt{nat} \quad \Gamma \vdash e_2 : \mathtt{nat}}{\Gamma \vdash \mathtt{plus}(e_1, e_2) : \mathtt{nat}} \qquad \frac{\Gamma \vdash e_1 : \mathtt{nat} \quad \Gamma \vdash e_2 : \mathtt{nat}}{\Gamma \vdash \mathtt{times}(e_1, e_2) : \mathtt{nat}}$$

$$\frac{\Gamma \vdash e_1 : \mathtt{nat} \quad \Gamma, x : \mathtt{nat} \vdash e_2 : \mathtt{nat}}{\Gamma \vdash \mathtt{let}(e_1, x : e_2) : \mathtt{nat}}$$

The point of being interested in typing for this small language is only to guarantee that there are no free variables in a term to the evaluation will not get stuck. This property can easily be verified.

Theorem 2

If
$$\cdot \vdash e$$
: nat then $FV(e) = \{ \}$.

Proof: We cannot prove this directly by rule induction, since the second premise of the rule for let introduces an assumption. So we generalizing to

If
$$x_1$$
:nat,..., x_n :nat $\vdash e$: nat then $FV(e) \subseteq \{x_1,...,x_n\}$.

This generalized statement cabe proved easily by rule rule induction.

Next we would like to give the operational semantics, specifying the value of an expression. We represent values also as expressions, although they are restricted to have the form num(k). There are multiple ways to specify the operational semantics, for example as a structured operational semantics [Ch. 7.1] or as an evaluation semantics [Ch. 7.2]. We give two forms of evaluation semantics here, which directly relate an expression to its value although they do not specify how to compute the value precisely.

The first way³ employs a hypothetical judgment in which we make assumptions about the values of variables. It is written as

$$x_1 \Downarrow v_1, \ldots, x_n \Downarrow v_n \vdash e \Downarrow v.$$

We call $x_1 \Downarrow v_1, \ldots, x_n \Downarrow v_n$ an *environment* and denote an environment by η . It is important that all variables x_i in an environment are distinct so that

³suggested by a student in class

the value of a variable is uniquely determined.

$$\frac{x \!\!\!\! \Downarrow v \in \eta}{\eta \vdash x \!\!\!\! \Downarrow v} \qquad \overline{\eta \vdash \operatorname{num}(k) \Downarrow \operatorname{num}(k)}$$

$$\frac{\eta \vdash e_1 \Downarrow \operatorname{num}(k_1) \quad \eta \vdash e_2 \Downarrow \operatorname{num}(k_2)}{\eta \vdash \operatorname{plus}(e_1, e_2) \Downarrow \operatorname{num}(k_1 + k_2)} \qquad \frac{\eta \vdash e_1 \Downarrow \operatorname{num}(k_1) \quad \eta \vdash e_2 \Downarrow \operatorname{num}(k_2)}{\eta \vdash \operatorname{times}(e_1, e_2) \Downarrow \operatorname{num}(k_1 \times k_2)}$$

$$\frac{\eta \vdash e_1 \Downarrow v_1 \quad \eta, x \!\!\!\! \Downarrow v_1 \vdash e_2 \Downarrow v_2}{\eta \vdash \operatorname{let}(e_1, x. e_2) \Downarrow v_2} \text{ (x not declared in η)}$$

In the rule for let we make the assumption that the value of x is v_1 while evaluating e_2 . One may be concerned that this operational semantics is partial, in case bound variables with the same name occur nested in a term. However, since we working with α -equivalences classes of terms we can always rename the inner bound variable to that the rule for let applies. We will henceforth not make such a side condition explicit, using the general convention that we rename bound variables as necessary so that contexts or environment declare only distinct variables.

An alternative semantics uses substitution instead of environments. For this judgment we evaluate only closed terms, so no hypothetical judgment is needed.

$$\begin{array}{c|c} \textit{No rule for variables } x & \hline \mathsf{num}(k) \Downarrow \mathsf{num}(k) \\ \hline e_1 \Downarrow \mathsf{num}(k_1) & e_2 \Downarrow \mathsf{num}(k_2) \\ \mathsf{plus}(e_1, e_2) \Downarrow \mathsf{num}(k_1 + k_2) & \hline e_1 \Downarrow \mathsf{num}(k_1) & e_2 \Downarrow \mathsf{num}(k_2) \\ \hline & \mathsf{times}(e_1, e_2) \Downarrow \mathsf{num}(k_1 \times k_2) \\ \hline & \underbrace{e_1 \Downarrow v_1 \quad \{v_1/x\}e_2 \Downarrow v_2}_{\mathsf{let}(e_1, x. e_2) \Downarrow v_2} \end{array}$$

In the next lecture we discuss how these two alternatives for the operational semantics are related, and how they are related to the typing judgment.