

15-462 Computer Graphics I
Lecture 14

Clipping and Scan Conversion

Line Clipping
Polygon Clipping
Clipping in Three Dimensions
Scan Conversion (Rasterization)
[Angel 7.3-7.6, 7.8-7.9]

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Frank Pfenning
Carnegie Mellon University

<http://www.cs.cmu.edu/~fp/courses/graphics/>

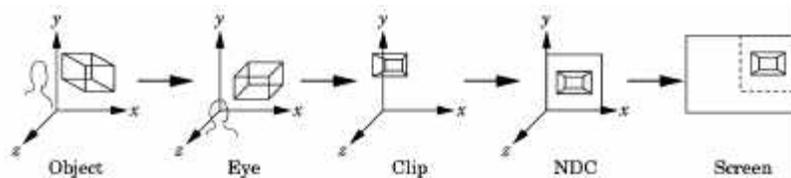
The Graphics Pipeline, Revisited



- Must eliminate objects outside viewing frustum
- Tied in with projections
 - Clipping: object space (eye coordinates)
 - Scissoring: image space (pixels in frame buffer)
- Introduce clipping in stages
 - 2D (for simplicity)
 - 3D (as in OpenGL)
- In a later lecture: scissoring

Transformations and Projections

- Sequence applied in many implementations
 1. Object coordinates to
 2. Eye coordinates to
 3. Clip coordinates to
 4. Normalized device coordinates to
 5. Screen coordinates



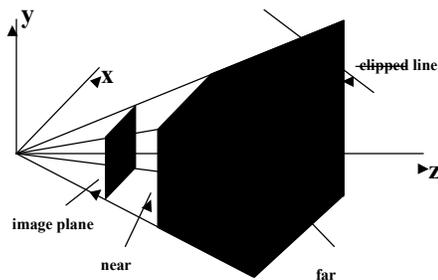
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Clipping Against a Frustum

- General case of frustum (truncated pyramid)



- Clipping is tricky because of frustum shape

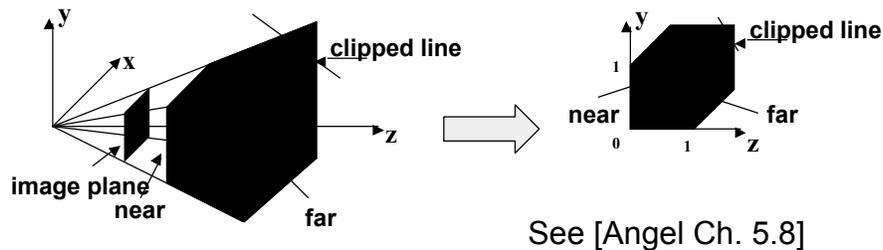
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Perspective Normalization

- Solution:
 - Implement perspective projection by perspective normalization and orthographic projection
 - Perspective normalization is a homogeneous tfm.



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The Normalized Frustum

- OpenGL uses $-1 \leq x,y,z \leq 1$ (others possible)
- Clip against resulting cube
- Clipping against programmer-specified planes is different and more expensive
- Often a useful programming device

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The Viewport Transformation

- Transformation sequence again:
 1. Camera: From object coordinates to eye coords
 2. Perspective normalization: to clip coordinates
 3. Clipping
 4. Perspective division: to normalized device coords.
 5. Orthographic projection (setting $z_p = 0$)
 6. Viewport transformation: to screen coordinates
- Viewport transformation can distort
- Often in OpenGL: resize callback

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Line-Segment Clipping

- General: 3D object against cube
- Simpler case:
 - In 2D: line against square or rectangle
 - Before scan conversion (rasterization)
 - Later: polygon clipping
- Several practical algorithms
 - Avoid expensive line-rectangle intersections
 - Cohen-Sutherland Clipping
 - Liang-Barsky Clipping
 - Many more [see Foley et al.]

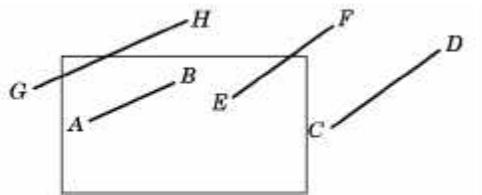
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Clipping Against Rectangle

- Line-segment clipping: modify endpoints of lines to lie within clipping rectangle
- Could calculate intersections of line (segments) with clipping rectangle (expensive)



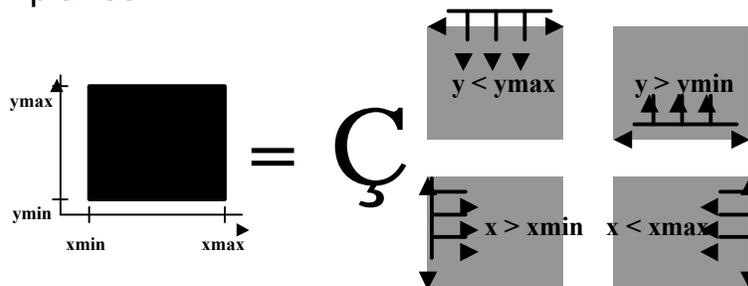
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Cohen-Sutherland Clipping

- Clipping rectangle as intersection of 4 half-planes



- Encode results of four half-plane tests
- Generalizes to 3 dimensions (6 half-planes)

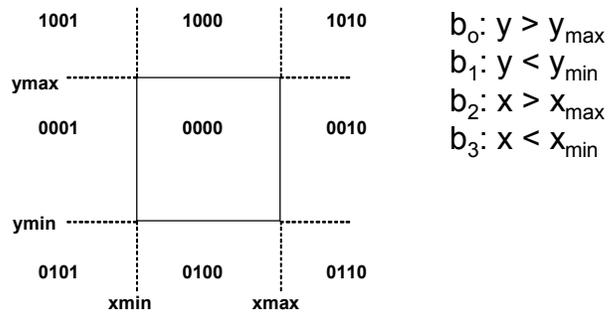
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Outcodes

- Divide space into 9 regions
- 4-bit outcode determined by comparisons



- $o_1 = \text{outcode}(x_1, y_1)$ and $o_2 = \text{outcode}(x_2, y_2)$

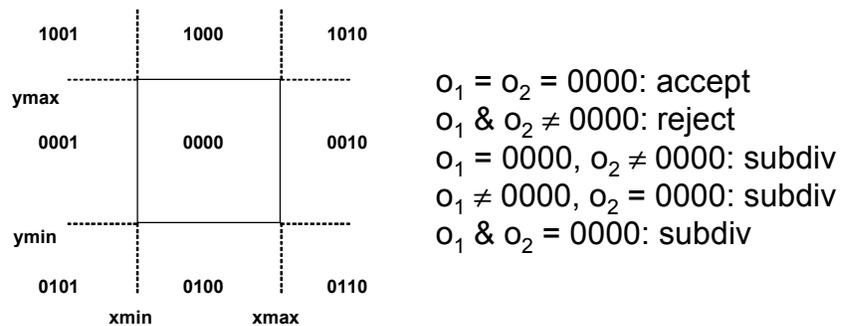
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Cases for Outcodes

- Outcomes: accept, reject, subdivide



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Cohen-Sutherland Subdivision

- Pick outside endpoint ($o \neq 0000$)
- Pick a crossed edge ($o = b_0b_1b_2b_3$ and $b_k \neq 0$)
- Compute intersection of this line and this edge
- Replace endpoint with intersection point
- Restart with new line segment
 - Outcodes of second point are unchanged
- Must converge (roundoff errors?)

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Liang-Barsky Clipping

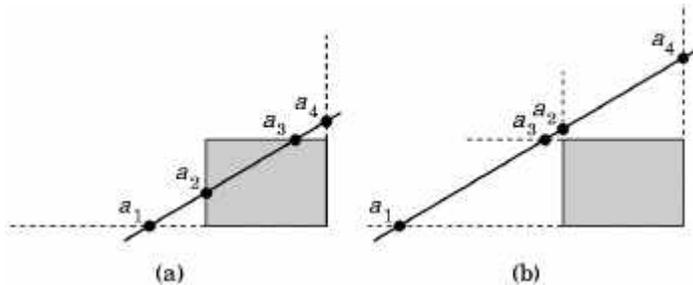
- Starting point is parametric form
$$\mathbf{p}(\alpha) = (1 - \alpha)\mathbf{p}_1 + \alpha\mathbf{p}_2, \quad 0 \leq \alpha \leq 1$$
$$x(\alpha) = (1 - \alpha)x_1 + \alpha x_2$$
$$y(\alpha) = (1 - \alpha)y_1 + \alpha y_2$$
- Compute four intersections with extended clipping rectangle
- Will see that this can be avoided

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Ordering of intersection points



- Order the intersection points
- Figure (a): $1 > \alpha_4 > \alpha_3 > \alpha_2 > \alpha_1 > 0$
- Figure (b): $1 > \alpha_4 > \alpha_2 > \alpha_3 > \alpha_1 > 0$

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Liang-Barsky Efficiency Improvements

- Efficiency improvement 1:
 - Compute intersections one by one
 - Often can reject before all four are computed
- Efficiency improvement 2:
 - Equations for α_3, α_2

$$y_{max} = (1 - \alpha_3)y_1 + \alpha_3y_2$$

$$x_{min} = (1 - \alpha_2)x_1 + \alpha_2x_2$$

$$\alpha_3 = \frac{y_{max} - y_1}{y_2 - y_1}, \quad \alpha_2 = \frac{x_{min} - x_1}{x_2 - x_1}$$
 - Compare α_3, α_2 without floating-point division

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Line-Segment Clipping Assessment

- Cohen-Sutherland
 - Works well if many lines can be rejected early
 - Recursive structure (multiple subdiv) a drawback
- Liang-Barsky
 - Avoids recursive calls (multiple subdiv)
 - Many cases to consider (tedious, but not expensive)
 - Used more often in practice (?)

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Outline

- Line-Segment Clipping
 - Cohen-Sutherland
 - Liang-Barsky
- Polygon Clipping
 - Sutherland-Hodgeman
- Clipping in Three Dimensions
- Scan Conversion
 - DDA algorithm
 - Bresenham's algorithm

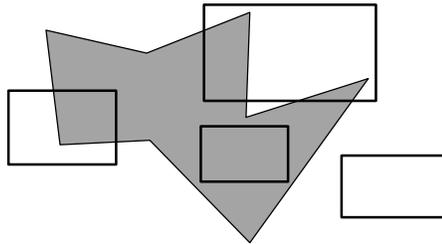
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Polygon Clipping

- Convert a polygon into one or more polygons
- Their union is intersection with clip window
- Alternatively, we can first tessellate concave polygons (OpenGL supported)



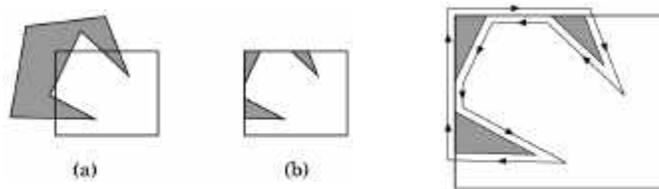
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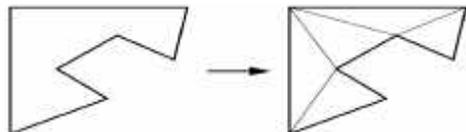
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Concave Polygons

- Approach 1: clip and join to a single polygon



- Approach 2: tessellate and clip triangles



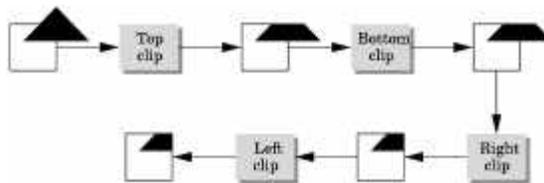
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Sutherland-Hodgeman I

- Subproblem:
 - Input: polygon (vertex list) and single clip plane
 - Output: new (clipped) polygon (vertex list)
- Apply once for each clip plane
 - 4 in two dimensions
 - 6 in three dimension
 - Can arrange in pipeline



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Sutherland-Hodgeman II

- To clip vertex list (polygon) against half-plane:
 - Test first vertex. Output if inside, otherwise skip.
 - Then loop through list, testing transitions
 - In-to-in: output vertex
 - In-to-out: output intersection
 - out-to-in: output intersection and vertex
 - out-to-out: no output
 - Will output clipped polygon as vertex list
- May need some cleanup in concave case
- Can combine with Liang-Barsky idea

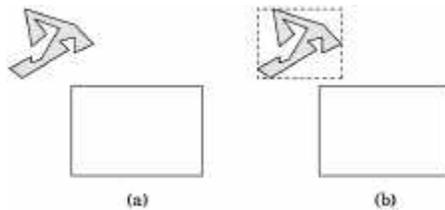
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Other Cases and Optimizations

- Curves and surfaces
 - Analytically if possible
 - Through approximating lines and polygons otherwise
- Bounding boxes
 - Easy to calculate and maintain
 - Sometimes big savings



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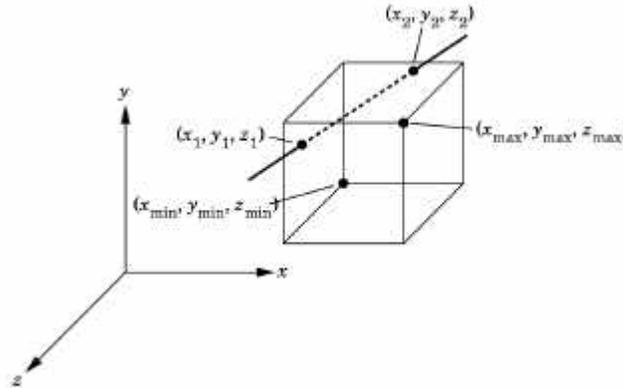
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Clipping Against Cube

- Derived from earlier algorithms
- Can allow right parallelepiped



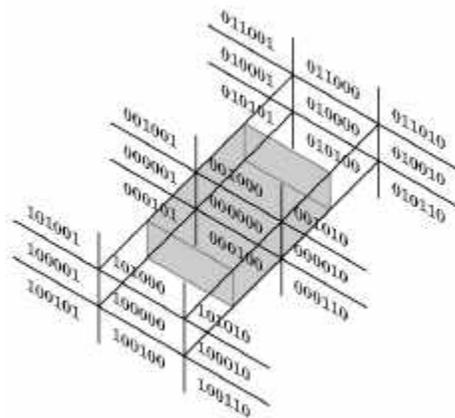
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Cohen-Sutherland in 3D

- Use 6 bits in outcode
 - b_4 : $z > z_{max}$
 - b_5 : $z < z_{min}$
- Other calculations as before



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Liang-Barsky in 3D

- Add equation $z(\alpha) = (1 - \alpha) z_1 + \alpha z_2$
- Solve, for \mathbf{p}_0 in plane and normal \mathbf{n} :

$$y_{max} = (1 - \alpha_3)y_1 + \alpha_3y_2$$

$$x_{min} = (1 - \alpha_2)x_1 + \alpha_2x_2$$

$$\alpha_3 = \frac{y_{max} - y_1}{y_2 - y_1}, \quad \alpha_2 = \frac{x_{min} - x_1}{x_2 - x_1}$$

- Yields

$$\alpha = \frac{\mathbf{n} \cdot (\mathbf{p}_0 - \mathbf{p}_1)}{\mathbf{n} \cdot (\mathbf{p}_2 - \mathbf{p}_1)}$$

- Optimizations as for Liang-Barsky in 2D

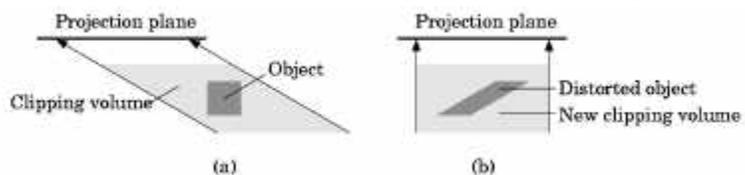
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Perspective Normalization

- Intersection simplifies for orthographic viewing
 - One division only (no multiplication)
 - Other Liang-Barsky optimizations also apply
- Otherwise, use perspective normalization
 - Reduces to orthographic case
 - Applies to oblique and perspective viewing



Normalization of oblique projections

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Summary: Clipping

- Clipping line segments to rectangle or cube
 - Avoid expensive multiplications and divisions
 - Cohen-Sutherland or Liang-Barsky
- Clipping to viewing frustum
 - Perspective normalization to orthographic projection
 - Apply clipping to cube from above
- Client-specific clipping
 - Use more general, more expensive form
- Polygon clipping
 - Sutherland-Hodgeman pipeline

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Rasterization

- Final step in pipeline: rasterization (scan conv.)
- From screen coordinates (float) to pixels (int)
- Writing pixels into frame buffer
- Separate z-buffer, display, shading, blending
- Concentrate on primitives:
 - Lines
 - Polygons (Thursday)

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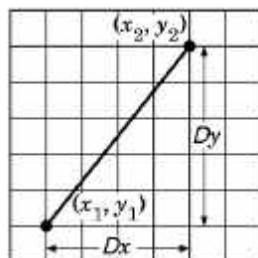
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DDA Algorithm

- DDA (“Digital Differential Analyzer”)
- Represent

$$y = mx + h \quad \text{where} \quad m = \frac{y_2 - y_1}{x_2 - x_1} = \frac{\Delta y}{\Delta x}$$

- Assume $0 \leq m \leq 1$
- Exploit symmetry
- Distinguish special cases



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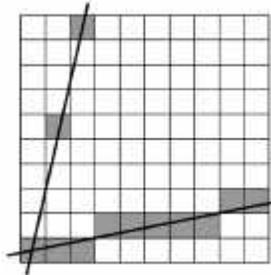
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DDA Loop

- Assume `write_pixel(int x, int y, int value)`

```
For (ix = x1; ix <= x2; ix++)  
{  
    y += m;  
    write_pixel(ix, round(y), color);  
}
```

- Slope restriction needed
- Easy to interpolate colors



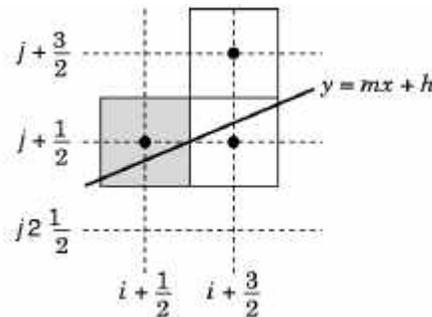
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Bresenham's Algorithm I

- Eliminate floating point addition from DDA
- Assume again $0 \leq m \leq 1$
- Assume pixel centers halfway between ints



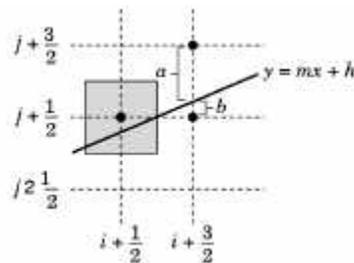
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Bresenham's Algorithm II

- Decision variable $a - b$
 - If $a - b > 0$ choose lower pixel
 - If $a - b \leq 0$ choose higher pixel
- Goal: avoid explicit computation of $a - b$
- Step 1: re-scale $d = (x_2 - x_1)(a - b) = \Delta x(a - b)$
- d is always integer



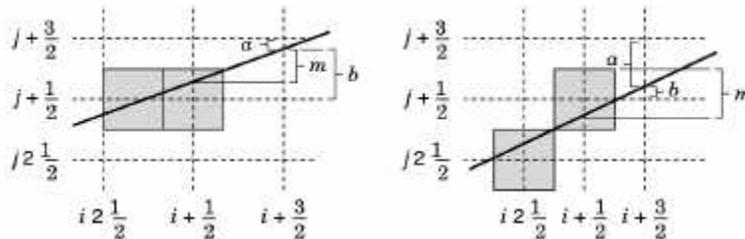
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Bresenham's Algorithm III

- Compute d at step $k + 1$ from d at step k !
- Case: j did not change ($d_k > 0$)
 - a decreases by m , b increases by m
 - $(a - b)$ decreases by $2m = 2(\Delta y / \Delta x)$
 - $\Delta x(a - b)$ decreases by $2\Delta y$



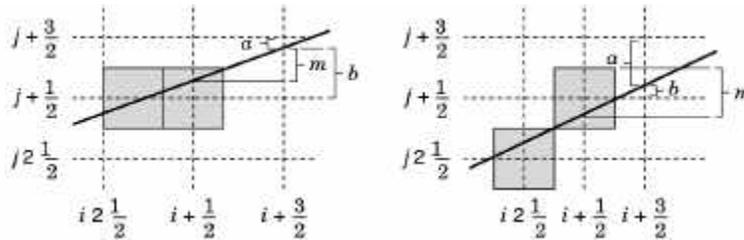
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Bresenham's Algorithm IV

- Case: j did change ($d_k \leq 0$)
 - a decreases by $m-1$, b increases by $m-1$
 - $(a-b)$ decreases by $2m-2 = 2(\Delta y/\Delta x - 1)$
 - $\Delta x(a-b)$ decreases by $2(\Delta y - \Delta x)$



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Bresenham's Algorithm V

- So $d_{k+1} = d_k - 2\Delta y$ if $d_k > 0$
- And $d_{k+1} = d_k - 2(\Delta y - \Delta x)$ if $d_k \leq 0$
- Final (efficient) implementation:

```
void draw_line(int x1, int y1, int x2, int y2) {
    int x, y = y1;
    int dx = 2*(x2-x1), dy = 2*(y2-y1);
    int dydx = dy-dx, D = (dy-dx)/2;

    for (x = x1; x <= x2; x++) {
        write_pixel(x, y, color);
        if (D > 0) D -= dy;
        else {y++; D -= dydx;}
    }
}
```

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Bresenham's Algorithm VI

- Need different cases to handle other m
- Highly efficient
- Easy to implement in hardware and software
- Widely used

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Preview

- Scan conversion of polygons
- Anti-aliasing
- Other pixel-level operations
- Assignment 5 due Thursday
- Assignment 6 (written) out Thursday