

Designing Robot Behavior in Human-Robot Interactions

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Human-robot interactions have been recognized to be a key element of future robots in many application domains such as manufacturing and transportation. It is challenging to design the behavior of those robots as they need to operate in highly unstructured and stochastic environments. The focus of this book is to set up a unified analytical framework for various human-robot systems; to establish a methodology to design the robot behaviors through control, decision and learning so that they can interact safely and efficiently with humans in dynamic uncertain environments; and to demonstrate the effectiveness of the method through a variety of realistic applications.

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