Shortest Paths with Negative Weights

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Based in part on Section 6.8

Shortest Path Problem

Shortest Path with Negative Weights. Given directed graph G with weighted edges d(u, v) that may be positive or negative, find the shortest path from s to t.

Complication of Negative Weights

Negative cycles: If some cycle has a negative total cost, we can make the s-t path as low cost as we want:

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Negative cycles: If some cycle has a negative total cost, we can make the s-t path as low cost as we want:

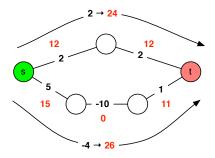
Go from s to some node on the cycle, and then travel around the cycle many times, eventually leaving to go to t.



Assume, therefore, that G has no negative cycles.

Let's just add a big number!

- ▶ Adding a large number *M* to each edge doesn't work!
- ▶ The cost of a path P will become $M \times \text{length}(P) + \text{cost}(P)$.
- ▶ If *M* is big, the number of hops (length) will dominate.



Bellman-Ford

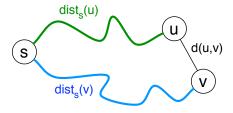
Let $dist_s(v)$ be the current estimated distance from s to v.

At the start, $dist_s(s) = 0$ and $dist_s(v) = \infty$ for all other v.

Ford step. Find an edge (u, v) such that

$$dist_s(u) + d(u, v) < dist_s(v)$$

and set $dist_s(v) = dist_s(u) + d(u, v)$.



Repeatedly Applying Ford Step

Theorem. After applying the Ford step until

$$dist_s(u) + d(u, v) \ge dist_s(v)$$

for all edges, $dist_s(u)$ will equal the shortest-path distance from s to u for all u.

Proof. We show that, for every v:

▶ There is a path of length $dist_s(v)$

(next two slide)

No path is shorter

(in three slides)

So $dist_s(v)$ must be the length of the shortest path.

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A path of length $dist_s(v)$ exists

Theorem. After any number i of applications of the Ford step, either $dist_s(v) = \infty$ or there is a s - v path of length $dist_s(v)$.

Proof. Let v be a vertex such that $dist_s(v) < \infty$. We proceed by induction on i.

Base case: When i = 0, only $dist_s(s) = 0 < \infty$ and there is a path of length 0 from s to s.

Induction hypothesis: Assume true for all applications < i.

A path of length $dist_s(v)$ exists, II

Proof, continued.

Induction step: Let $dist_s(v)$ be the distance updated during the ith application. It is updated using some edge (u, v) using the rule:

$$dist_s(v) = dist_s(u) + d(u, v)$$

 $dist_s(u)$ must be $\leq \infty$ and thus must have been updated by some application of the Ford rule at a step before i.

Therefore, by the induction hypothesis, there is a path P_{su} of length $dist_s(u)$.

Now, on the *i*th application $P_{su} + (u, v)$ is a path of length $dist_s(u) + d(u, v) = dist_s(v)$

No paths are shorter

Theorem. Let P_{sv} be any path from s to v. When the Ford step can no longer be applied, length $(P_{sv}) \ge dist_s(v)$.

Proof. By induction on # edges in P_{sv} .

Base case: When $|P_{sv}| = 1$, it consists of a single edge (s, v) and because the Ford step can't be applied $d(s, v) \ge dist_s(v)$.

Induction hypothesis: Assume true for all P_{sv} of k or fewer edges.

Induction step: Let P_{sv} be an s - v path of k + 1 edges. $P_{sv} = P_{su} + (u, v)$ for some u.

$$length(P_{sv}) = length(P_{su}) + d(u, v) \ge dist_s(u) + d(u, v) \ge dist_s(v)$$

Otherwise, the Ford step could be applied.

Which edges are candidates for the Ford rule?

Ford rule:

$$dist_s(u) + d(u, v) < dist_s(v)$$

This can only become true if $dist_s(u)$ has gotten smaller since the last time we checked.

- ▶ Whenever we change $dist_s(u)$ we add u to a queue.
- To look for an edge to apply the Ford rule to we take a node of the queue and look at all its edges.

Implementation

```
ShortestPath(G, s, t):
   Initialize dist[u] = \infty for all u
   dist[s] = 0
   # queue tracks nodes that are candidates for Ford rule
   queue = [s]
   while queue is not empty:
      v = front of queue (and remove v)
      for u \in neighbors(v):
         # Apply Ford rule if we can
         if dist[v] + d(v,u) < dist[u]:
            dist[u] = dist[v] + d(v,u)
            parent[u] = v
            if u \notin queue: put w at end of queue
```

Running time

- \triangleright n = number of nodes
- ightharpoonup m = number of edges

After $dist_s(v)$ has been updated k times, it corresponds to a simple path of k edges.

A path can contain at most n-1 edges (before nodes start to repeat), so each $dist_s(v)$ can be updated at most n-1 times.

Updating all vertices once takes time O(m) since we look at each edge twice.

Total running time = O(mn).

Note that this is slower than Dijkstra's algorithm in general.

A dynamic programming view of Bellman-Ford

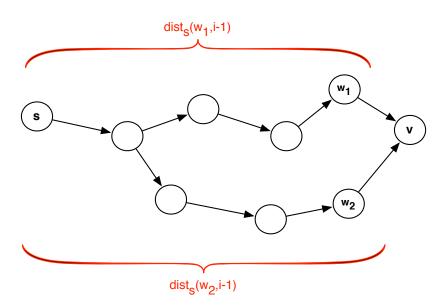
Another view

Definition. Let $dist_s(v, i)$ be minimum cost of a path from s to v that uses at most i edges.

Can recursively define $dist_s(v, i)$:

- 1. If best s v path uses at most i 1 edges, then $dist_s(v, i) = dist_s(v, i 1)$.
- 2. If best s v uses i edges, and the last edge is (w, v), then $dist_s(v, i) = d(w, v) + dist_s(w, i 1)$.

Subproblems, picture



Recurrence

Let N(w) be the neighbors of w.

 $dist_s(v, i) = cost of best path from s to v using at most i edges.$

Recurrence:

$$dist_s(v, i) = \min \begin{cases} dist_s(v, i - 1) \\ \min_{w \in N(v)} dist_s(w, i - 1) + d(w, v) \end{cases}$$

Base case: $dist_s(v, 1) = d(s, v)$ or ∞ if (s, v) does not exist

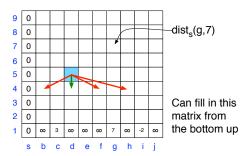
Goal: Compute $dist_s(t, n-1)$.

Important Facts About This Recurrence

Recurrence:

$$dist_s(v,i) = \min \begin{cases} dist_s(v,i-1) \\ \min_{w \in N(v)} dist_s(w,i-1) + d(w,v) \end{cases}$$

- $ightharpoonup dist_s(v,x)$ depends only on $dist_s(w,y)$ for which y is smaller than x.
- ▶ There are only $|V| \times (|V| 1)$ possible arguments for $dist_s(\cdot, \cdot)$.



Code

```
BellmanFord(G=(V.E), s, t):
 Initialize dist_s[x, 1] to d(s,x) for all x
For i = 1, ..., |V|-1:
  For v in V:
     // find the best w on which to apply the Ford rule
     best_w = None
     for w in N(v): // N(v) are neighbors of v
        best_w = min(best_w, dist_s[w, i-1] + d[w,v])
     dist s[v,i] = min(best w. dist s[v. i-1])
   EndFor
 EndFor
 Return dist s[t, n-1]
```

Running Time

Simple Analysis:

- ➤ O(n²) subproblems
- O(n) time to compute each entry in the table (have to search over all possible neighbors w).
- ▶ Therefore, runs in $O(n^3)$ time.

A better analysis:

- ▶ Let n_v be the number of edges entering v.
- ▶ Filling in each entry actually only takes $O(n_v)$ time.
- ► Total time = $O(n \sum_{v \in V} n_v) = O(nm)$.