

Powerful Tools for Data Mining Fractals, power laws, SVD

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Part I: Singular Value Decomposition (SVD) = Eigenvalue decomposition

www.cs.cmu.edu/~christos/

SVD - outline

- ➡ • Motivation
- Definition - properties
- Interpretation; more properties
- Complexity
- Applications - success stories
- Conclusions

SVD - Motivation

- problem #1: text - LSI: find 'concepts'
- problem #2: compression / dim. reduction

SVD - Motivation

- problem #1: text - LSI: find 'concepts'

term	data	information	retrieval	brain	lung
document					
CS-TR1	1	1	1	0	0
CS-TR2	2	2	2	0	0
CS-TR3	1	1	1	0	0
CS-TR4	5	5	5	0	0
MED-TR1	0	0	0	2	2
MED-TR2	0	0	0	3	3
MED-TR3	0	0	0	1	1

SVD - Motivation

- problem #2: compress / reduce dimensionality

Problem - specs

- ~10**6 rows; ~10**3 columns; no updates;
- Compress / extract features

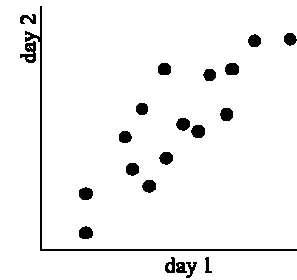
customer	day	We	Th	Fr	Sa	Su
		7/10/06	7/11/06	7/12/06	7/13/06	7/14/06
ABC Inc.	1	1	1	0	0	0
DEF Ltd.	2	2	2	0	0	0
GHI Inc.	1	1	1	0	0	0
KLM Co.	5	5	5	0	0	0
Smith	0	0	0	2	2	2
Johnson	0	0	0	3	3	3
Thompson	0	0	0	1	1	1

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SVD - Motivation

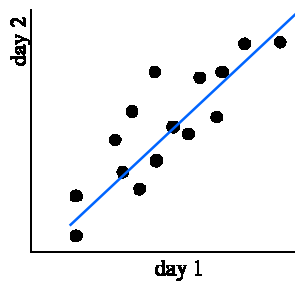


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SVD - Motivation



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SVD - outline

- Motivation
- ➔ • Definition - properties
- Interpretation; more properties
- Complexity
- Applications - success stories
- Conclusions

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SVD - Definition

(reminder: matrix multiplication)

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix} \times \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} \\ \\ \end{bmatrix}$$

$3 \times 2 \qquad 2 \times 1$

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SVD - Definition

(reminder: matrix multiplication)

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix} \times \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} \\ \\ \end{bmatrix}$$

$\begin{matrix} \xleftrightarrow{3 \times 2} & \xleftrightarrow{2 \times 1} & \xleftrightarrow{3 \times 1} \end{matrix}$

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skip

SVD - Definition

(reminder: matrix multiplication)

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix} \times \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \\ -1 \end{bmatrix}$$

$\begin{matrix} \xleftarrow{3 \times 2} & & \xrightarrow{2 \times 1} & & \xrightarrow{3 \times 1} \end{matrix}$

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skip

SVD - Definition

(reminder: matrix multiplication)

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix} \times \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \\ -1 \end{bmatrix}$$

$\begin{matrix} \xleftarrow{3 \times 2} & & \xrightarrow{2 \times 1} & & \xrightarrow{3 \times 1} \end{matrix}$

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skip

SVD - Definition

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SVD - notation

Conventions:

- bold capitals -> matrix (eg. **A**, **U**, **Λ** , **V**)
- bold lower-case -> column vector (eg., **x**, **v**₁, **u**₃)
- regular lower-case -> scalars (eg., λ_1 , λ_r)

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SVD - Definition

$$\mathbf{A}_{[n \times m]} = \mathbf{U}_{[n \times r]} \mathbf{\Lambda}_{[r \times r]} (\mathbf{V}_{[m \times r]})^T$$

- **A**: n x m matrix (eg., n documents, m terms)
- **U**: n x r matrix (n documents, r concepts)
- **Λ** : r x r diagonal matrix (strength of each 'concept') (r : rank of the matrix)
- **V**: m x r matrix (m terms, r concepts)

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SVD - Definition

- **A** = **U** **Λ** **V**^T - example:

A	U	Λ	V
n × m	n × r	r × r	m × r

$$\begin{array}{c} \boxed{} \\ \boxed{} \\ \boxed{} \end{array} = \begin{array}{c} \boxed{} \\ \boxed{} \end{array} \times \begin{array}{c} \boxed{} \\ \boxed{} \\ \boxed{} \end{array} \times \begin{array}{c} \boxed{} \\ \boxed{} \end{array}$$

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SVD - Properties

THEOREM [Press+92]: always possible to decompose matrix A into $A = U \Lambda V^T$, where

- U, Λ, V : unique (*)
- U, V : column orthonormal (ie., columns are unit vectors, orthogonal to each other)
 - $U^T U = I; V^T V = I$ (I : identity matrix)
- Λ : eigenvalues are positive, and sorted in decreasing order

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SVD - Example

- $A = U \Lambda V^T$ - example:

$$\begin{array}{c} \text{retrieval} \\ \text{data} \downarrow \text{inf.} \text{ brain lung} \\ \begin{array}{c} \uparrow \text{CS} \\ \downarrow \text{MD} \end{array} \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}
 \end{array}$$

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SVD - Example

- $A = U \Lambda V^T$ - example:

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SVD - Example

- $A = U \Lambda V^T$ - example:

$$\begin{array}{c} \text{retrieval} \\ \text{data} \downarrow \text{inf.} \text{ brain lung} \\ \begin{array}{c} \uparrow \text{CS} \\ \downarrow \text{MD} \end{array} \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}
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SVD - Example

- $A = U \Lambda V^T$ - example:

$$\begin{array}{c} \text{retrieval} \\ \text{data} \downarrow \text{inf.} \text{ brain lung} \\ \begin{array}{c} \uparrow \text{CS} \\ \downarrow \text{MD} \end{array} \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}
 \end{array}$$

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SVD - Example

- $A = U \Lambda V^T$ - example:

$$\begin{array}{c} \text{retrieval} \\ \text{data} \downarrow \text{inf.} \text{ brain lung} \\ \begin{array}{c} \uparrow \text{CS} \\ \downarrow \text{MD} \end{array} \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}
 \end{array}$$

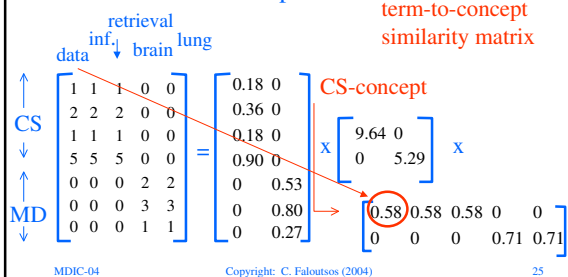
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SVD - Example

- $A = U \Lambda V^T$ - example:



SVD - outline

- Motivation
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SVD - Interpretation #1

'documents', 'terms' and 'concepts':
[Foltz+92]

- U : document-to-concept similarity matrix
- V : term-to-concept sim. matrix
- Λ : its diagonal elements: 'strength' of each concept

SVD - Interpretation #1

'documents', 'terms' and 'concepts':

Q: if A is the document-to-term matrix, what is $A^T A$?

Q: $A A^T$?

SVD - Interpretation #1

'documents', 'terms' and 'concepts':

Q: if A is the document-to-term matrix, what is $A^T A$?

A: term-to-term ($[m \times m]$) similarity matrix

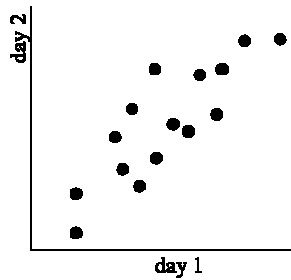
Q: $A A^T$?

A: document-to-document ($[n \times n]$) similarity matrix

SVD - Interpretation #2

- best axis to project on: ('best' = min sum of squares of projection errors)

SVD - Motivation



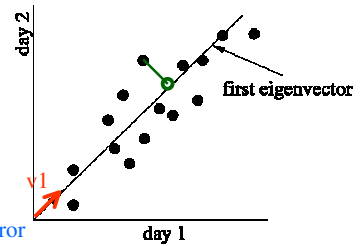
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SVD - interpretation #2

SVD: gives
best axis to project



- minimum RMS error

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SVD - Interpretation #2

customer	day	We 7/10/96	Th 7/11/96	Fr 7/12/96	Sa 7/13/96	Su 7/14/96
ABC Inc.		1	1	1	0	0
DEF Ltd.		2	2	2	0	0
GHI Inc.		1	1	1	0	0
KLM Co.		5	5	5	0	0
Smith		0	0	0	2	2
Johnson		0	0	0	3	3
Thompson		0	0	0	1	1

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SVD - Interpretation #2

- $A = U \Lambda V^T$ - example:

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}$$

v1

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SVD - Interpretation #2

- $A = U \Lambda V^T$ - example:

variance ('spread') on the v1 axis

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}$$

(9.64 is circled in red)

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SVD - Interpretation #2

- $A = U \Lambda V^T$ - example:
 - $U \Lambda$ gives the coordinates of the points in the projection axis

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}$$

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SVD - Interpretation #2

- More details
- Q: how exactly is dim. reduction done?

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}$$

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SVD - Interpretation #2

- More details
- Q: how exactly is dim. reduction done?
- A: set the smallest eigenvalues to zero:

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & \cancel{5.99} \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}$$

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SVD - Interpretation #2

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}$$

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SVD - Interpretation #2

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}$$

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SVD - Interpretation #2

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 0.18 \\ 0.36 \\ 0.18 \\ 0.90 \\ 0 \\ 0 \\ 0 \end{bmatrix} \times \begin{bmatrix} 9.64 \\ 0.58 & 0.58 & 0.58 & 0 & 0 \end{bmatrix} \times$$

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SVD - Interpretation #2

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

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SVD - Interpretation #2

Exactly equivalent:

'spectral decomposition' of the matrix:

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}$$

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SVD - Interpretation #2

Exactly equivalent:

'spectral decomposition' of the matrix:

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} | & | \\ u_1 & u_2 \\ | & | \end{bmatrix} \times \begin{bmatrix} \lambda_1 & \emptyset \\ \emptyset & \lambda_2 \end{bmatrix} \times \begin{bmatrix} \text{---} v_1 \text{---} \\ \text{---} v_2 \text{---} \end{bmatrix}$$

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SVD - Interpretation #2

Exactly equivalent:

'spectral decomposition' of the matrix:

$$\begin{matrix} \xleftarrow{m} \xrightarrow{m} \\ \uparrow n \downarrow \end{matrix} \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \lambda_1 \mathbf{u}_1 \mathbf{v}_1^T + \lambda_2 \mathbf{u}_2 \mathbf{v}_2^T + \dots$$

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SVD - Interpretation #2

Exactly equivalent:

'spectral decomposition' of the matrix:

$$\begin{matrix} \xleftarrow{m} \xrightarrow{m} \\ \uparrow n \downarrow \end{matrix} \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \lambda_1 \mathbf{u}_1 \mathbf{v}_1^T + \lambda_2 \mathbf{u}_2 \mathbf{v}_2^T + \dots$$

← r terms →

$\mathbf{u}_1$ $\mathbf{v}_1^T$
 $n \times 1$ $1 \times m$

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SVD - Interpretation #2

approximation / dim. reduction:

by keeping the first few terms (Q: how many?)

$$\begin{matrix} \xleftarrow{m} \xrightarrow{m} \\ \uparrow n \downarrow \end{matrix} \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \lambda_1 \mathbf{u}_1 \mathbf{v}_1^T + \lambda_2 \mathbf{u}_2 \mathbf{v}_2^T + \dots$$

assume: $\lambda_1 \geq \lambda_2 \geq \dots$

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SVD - Interpretation #2

A heuristic - [Fukunaga]: keep 80-90% of 'energy' (= sum of squares of λ_i 's)

$$\begin{matrix} \xleftarrow{m} \xrightarrow{m} \\ \uparrow n \downarrow \end{matrix} \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \lambda_1 \mathbf{u}_1 \mathbf{v}_1^T + \lambda_2 \mathbf{u}_2 \mathbf{v}_2^T + \dots$$

assume: $\lambda_1 \geq \lambda_2 \geq \dots$

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SVD - outline

- Motivation
- Definition - properties
- Interpretation
 - #1: documents/terms/concepts
 - #2: dim. reduction
 - #3: picking non-zero, rectangular 'blobs'
 - #4: fixed points - graph interpretation
- Complexity
- ...



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SVD - Interpretation #3

- finds non-zero 'blobs' in a data matrix

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}$$

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SVD - Interpretation #3

- finds non-zero 'blobs' in a data matrix

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}$$

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SVD - Interpretation #3

- finds non-zero 'blobs' in a data matrix

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}$$

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SVD - Interpretation #3

- finds non-zero 'blobs' in a data matrix

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}$$

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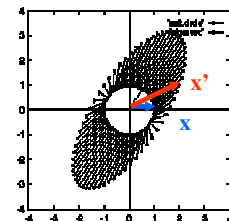
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SVD - Interpretation #4

- A as vector transformation

$$\begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$



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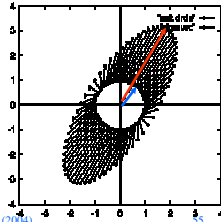
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SVD - Interpretation #4

- if A is symmetric, then, by defn., its eigenvectors remain parallel to themselves ('fixed points')

$$\lambda_1 \mathbf{v}_1 = A \mathbf{v}_1$$

$$3.62 * \begin{bmatrix} 0.52 \\ 0.85 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 0.52 \\ 0.85 \end{bmatrix}$$


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SVD - Interpretation #4

- fixed point operation ($A^T A$ is symmetric)
 - $A^T A \mathbf{v}_i = \lambda_i^2 \mathbf{v}_i$ ($i=1, \dots, r$) [Property 1]
 - eg., A : transition matrix of a Markov Chain; then $\mathbf{v}_1$ is related to the steady state probability distribution (= a particle, doing a random walk on the graph)
- convergence: for (almost) any $\mathbf{v}'$:
 - $(A^T A)^k \mathbf{v}' \sim (\text{constant}) \mathbf{v}_1$ [Property 2]
 - where $\mathbf{v}_1$: strongest 'right' eigenvector

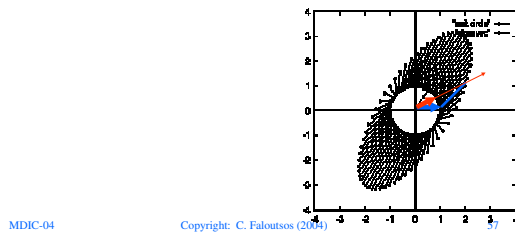
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SVD - Interpretation #4

- convergence - illustration:



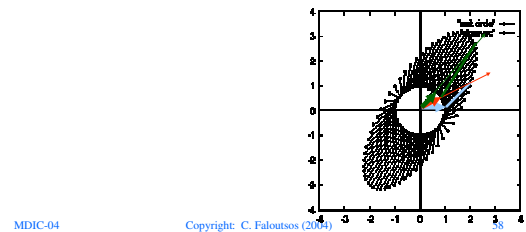
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SVD - Interpretation #4

- convergence - illustration:



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SVD - Interpretation #4

- $\mathbf{v}_1 \dots \mathbf{v}_r$: 'right' eigenvectors
- symmetrically: $\mathbf{u}_1 \dots \mathbf{u}_r$: 'left' eigenvectors for matrix $A (= U \Lambda V^T)$:

$$A \mathbf{v}_i = \lambda_i \mathbf{u}_i$$

$$\mathbf{u}_i^T A = \lambda_i \mathbf{v}_i^T$$

(right eigenvectors -> 'authority' scores in Kleinberg's algo;
left ones -> 'hub' scores)

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SVD - outline

- Motivation
- Definition - properties
- Interpretation
- ➔ Complexity
- Applications - success stories
- Conclusions

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SVD - Complexity

- $O(n * m * m)$ or $O(n * n * m)$ (whichever is less)
- less work, if we just want eigenvalues
- ... or if we want first k eigenvectors
- ... or if the matrix is sparse [Berry]
- Implemented: in *any* linear algebra package (LINPACK, matlab, Splus, mathematica ...)

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SVD - conclusions so far

- SVD: $A = U \Lambda V^T$: unique (*)
- U : document-to-concept similarities
- V : term-to-concept similarities
- Λ : strength of each concept

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SVD - conclusions so far

- dim. reduction: keep the first few strongest eigenvalues (80-90% of 'energy')
- SVD: picks up linear correlations
- SVD: picks up non-zero 'blobs'
- v_1 : fixed point (-> steady-state prob.)

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SVD - outline

- Motivation
- Definition - properties
- Interpretation
- Complexity
- ➔ Applications - success stories
- Conclusions

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SVD - Case studies

- ...
- ➔ Applications - success stories
 - multi-lingual IR, LSI queries
 - compression
 - PCA - 'ratio rules'
 - Karhunen-Lowe transform
 - Kleinberg/google algorithm

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Case study - LSI



- Q1: How to do queries with LSI?
- Q2: multi-lingual IR (english query, on spanish text?)

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Case study - LSI

Q1: How to do queries with LSI?
Problem: Eg., find documents with 'data'

$\begin{matrix} \uparrow \\ \text{CS} \\ \downarrow \\ \text{MD} \end{matrix}$

$$\begin{matrix} & \text{retrieval} & & & \\ & \text{data} & \text{inf} \downarrow & \text{brain} & \text{lung} \\ \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} & = & \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix} \end{matrix}$$

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Case study - LSI

Q1: How to do queries with LSI?
A: map query vectors into 'concept space' – how?

$\begin{matrix} \uparrow \\ \text{CS} \\ \downarrow \\ \text{MD} \end{matrix}$

$$\begin{matrix} & \text{retrieval} & & & \\ & \text{data} & \text{inf} \downarrow & \text{brain} & \text{lung} \\ \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} & = & \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix} \end{matrix}$$

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Case study - LSI

Q1: How to do queries with LSI?
A: map query vectors into 'concept space' – how?

$\begin{matrix} & \text{retrieval} & & & \\ & \text{data} & \text{inf} \downarrow & \text{brain} & \text{lung} \\ q^T = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \end{bmatrix} \end{matrix}$

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Case study - LSI

Q1: How to do queries with LSI?
A: map query vectors into 'concept space' – how?

$\begin{matrix} & \text{retrieval} & & & \\ & \text{data} & \text{inf} \downarrow & \text{brain} & \text{lung} \\ q^T = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \end{bmatrix} \end{matrix}$

A: inner product (cosine similarity) with each 'concept' vector v_i

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Case study - LSI

Q1: How to do queries with LSI?
A: map query vectors into 'concept space' – how?

$\begin{matrix} & \text{retrieval} & & & \\ & \text{data} & \text{inf} \downarrow & \text{brain} & \text{lung} \\ q^T = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \end{bmatrix} \end{matrix}$

A: inner product (cosine similarity) with each 'concept' vector v_i

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Case study - LSI

compactly, we have:
 $q^T_{\text{concept}} = q^T V$
Eg:

$\begin{matrix} & \text{retrieval} & & & \\ & \text{data} & \text{inf} \downarrow & \text{brain} & \text{lung} \\ q^T = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \end{bmatrix} \end{matrix}$

$$\begin{bmatrix} 0.58 & 0 \\ 0.58 & 0 \\ 0.58 & 0 \\ 0 & 0.71 \\ 0 & 0.71 \end{bmatrix} \begin{matrix} \text{CS-concept} \\ \downarrow \\ \begin{bmatrix} 0.58 & 0 \end{bmatrix} \end{matrix}$$

term-to-concept similarities

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Case study - LSI

Drill: how would the document ('information', 'retrieval') handled by LSI?

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Case study - LSI

Drill: how would the document ('information', 'retrieval') handled by LSI? A: SAME:

$$\mathbf{d}_{\text{concept}}^T = \mathbf{d}^T \mathbf{V}$$

Eg: $\mathbf{d}^T = \begin{bmatrix} \text{data} & \text{inf} & \text{retrieval} & \text{brain} & \text{lung} \\ 0 & 1 & 1 & 0 & 0 \end{bmatrix}$

$$\mathbf{V} = \begin{bmatrix} 0.58 & 0 \\ 0.58 & 0 \\ 0.58 & 0 \\ 0 & 0.71 \\ 0 & 0.71 \end{bmatrix}$$

CS-concept $\downarrow$ $= \begin{bmatrix} 1.16 & 0 \end{bmatrix}$

term-to-concept similarities

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Case study - LSI

Observation: document ('information', 'retrieval') will be retrieved by query ('data'), although it does not contain 'data'!!

$$\mathbf{d}^T = \begin{bmatrix} \text{data} & \text{inf} & \text{retrieval} & \text{brain} & \text{lung} \\ 0 & 1 & 1 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1.16 & 0 \end{bmatrix}$$

$$\mathbf{q}^T = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 0.58 & 0 \end{bmatrix}$$

CS-concept $\downarrow$

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Case study - LSI

Q1: How to do queries with LSI?

→ Q2: multi-lingual IR (english query, on spanish text?)

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Case study - LSI

- Problem:
 - given many documents, translated to both languages (eg., English and Spanish)
 - answer queries across languages

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Case study - LSI

- Solution: ~ LSI

$$\begin{bmatrix} \text{data} & \text{inf} & \text{retrieval} & \text{brain} & \text{lung} \\ 1 & 1 & 1 & 0 & 0 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} \text{informacion} & \text{datos} \\ 1 & 1 & 1 & 0 & 0 \\ 1 & 2 & 2 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 5 & 5 & 4 & 0 & 0 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 2 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix}$$

CS $\updownarrow$ MD

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Case study - LSI

- Solution: ~ LSI

$\begin{matrix} \uparrow \\ \text{CS} \\ \downarrow \\ \uparrow \\ \text{MD} \\ \downarrow \end{matrix}$

	data	retrieval	inf.	brain	lung
1	1	1	0	0	
2	2	2	0	0	
1	1	1	0	0	
5	5	5	0	0	
0	0	0	2	2	
0	0	0	3	3	
0	0	0	1	1	

	information	datos
1	1	1
2	2	2
1	1	1
5	5	4
0	0	0
0	0	2
0	0	2
0	0	1

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SVD - outline - Case studies

- ...
- Applications - success stories
 - multi-lingual IR; LSI queries
 - compression
 - PCA - 'ratio rules'
 - Karhunen-Lowe transform
 - Kleinberg/google algorithm

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Case study: compression

[Korn+97]

Problem:

- given a matrix
- compress it, but maintain 'random access'

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Problem - specs

- ~10**6 rows; ~10**3 columns; no updates;
- random access to any cell(s) ; small error: OK

customer	day	Wa	Th	Fr	Sa	Su
	7/10/96	7/11/96	7/12/96	7/13/96	7/14/96	
ABC Inc.	1	1	1	0	0	
DEF Ltd.	2	2	2	0	0	
GHI Inc.	1	1	1	0	0	
KLM Co.	5	5	5	0	0	
Smith	0	0	0	2	2	
Johanson	0	0	0	3	3	
Thompson	0	0	0	1	1	

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Idea

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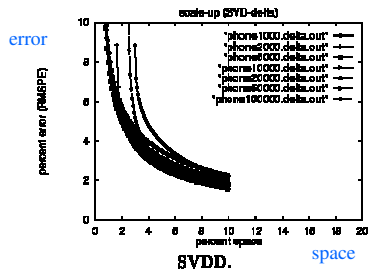
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SVD - reminder

- space savings: 2:1
- minimum RMS error

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Performance - scaleup



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SVD - outline - Case studies

- ...
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 - compression
 - ➔ PCA - 'ratio rules'
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 - Kleinberg/google algorithm

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PCA - 'Ratio Rules'

[Korn+00]

Typically: 'Association Rules' (eg.,
 $\{\text{bread, milk}\} \rightarrow \{\text{butter}\}$)

But:

- which set of rules is 'better'?
- how to reconstruct missing/corrupted values?

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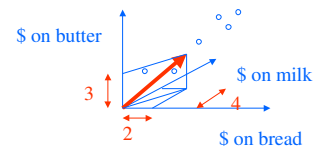
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PCA - 'Ratio Rules'

Idea: try to find 'concepts':

- Eigenvectors dictate rules about ratios:

$$\text{bread:milk:butter} = 2:4:3$$



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PCA - 'Ratio Rules'

[Korn+00]

Typically: 'Association Rules' (eg.,
 $\{\text{bread, milk}\} \rightarrow \{\text{butter}\}$)

But:

- ✓ – how to reconstruct missing/corrupted values?
- ✓ – which set of rules is 'better'?

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PCA - 'Ratio Rules'

Moreover: visual data mining, for free:

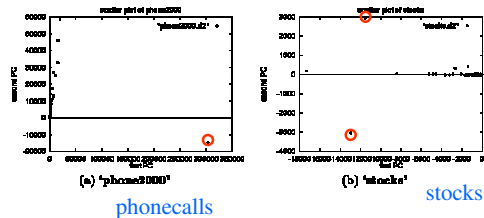
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PCA - Ratio Rules

- no Gaussian clusters; Zipf-like distribution



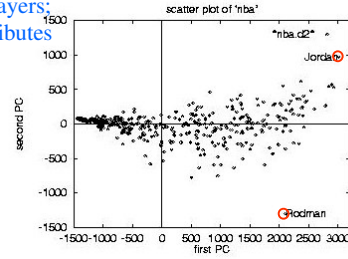
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PCA - Ratio Rules

NBA dataset
~500 players;
~30 attributes



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PCA - Ratio Rules

- PCA: get eigenvectors $v_1, v_2, \dots$
- ignore entries with small abs. value
- try to interpret the rest

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PCA - Ratio Rules

NBA dataset - V matrix (term to 'concept' similarities)

field	RR_1	RR_2	RR_3
minutes played	.808	-.4	
field goals			
goal attempts			
points	.406	.199	
total rebounds		-.489	.602
assists			-.486
steals			-.07

 v_1

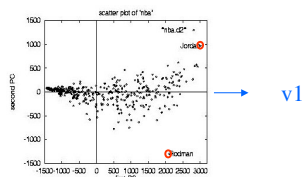
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Ratio Rules - example

- RR1: minutes:points = 2:1
- corresponding concept?



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Ratio Rules - example

- RR1: minutes:points = 2:1
- corresponding concept?
- A: 'goodness' of player

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Ratio Rules - example

- RR2: points: rebounds negatively correlated(!)

field	RR ₁	RR ₂	RR ₃
minutes played	.808	-.4	
field goals			
goal attempts			
points	.406	.199	
total rebounds		-.489	.602
assists			-.486
steals			-.07

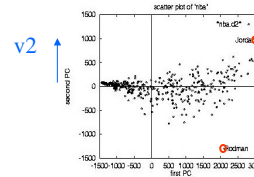
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Ratio Rules - example

- RR2: points: rebounds negatively correlated(!) - concept?



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Ratio Rules - example

- RR2: points: rebounds negatively correlated(!) - concept?
- A: position: offensive/defensive

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SVD - Case studies

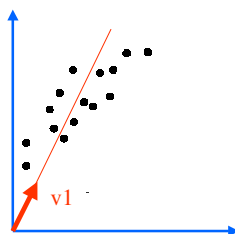
- ...
- Applications - success stories
 - multi-lingual IR; LSI queries
 - compression
 - PCA - 'ratio rules'
 - Karhunen-Lowe transform
 - Kleinberg/google algorithm

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K-L transform



[Duda & Hart]; [Fukunaga]

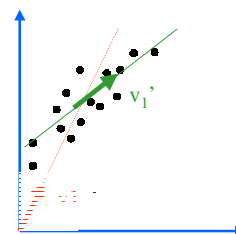
A subtle point:
SVD will give vectors that
go through the origin

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K-L transform



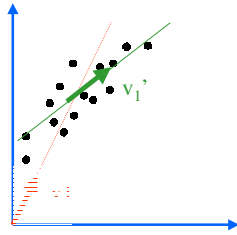
A subtle point:
SVD will give vectors that
go through the origin
Q: how to find v_1 ?

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K-L transform



A subtle point:
SVD will give vectors that
go through the origin
Q: how to find v_1' ?

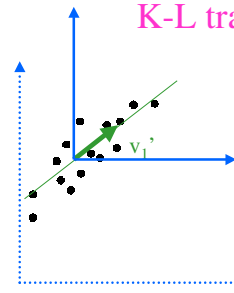
A: 'centered' PCA, ie.,
move the origin to center
of gravity

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K-L transform



A subtle point:
SVD will give vectors that
go through the origin
Q: how to find v_1' ?

A: 'centered' PCA, ie.,
move the origin to center
of gravity
and THEN do SVD

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SVD - outline

- Motivation
- Definition - properties
- Interpretation
- Complexity
- ➡ • Applications - success stories
- Conclusions

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SVD - Case studies

- ...
- Applications - success stories
 - multi-lingual IR; LSI queries
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 - Karhunen-Lowe transform
 - ➡ – Kleinberg/google algorithm

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Kleinberg's algorithm

- Problem dfn: given the web and a query
- find the most 'authoritative' web pages for this query

Step 0: find all pages containing the query terms

Step 1: expand by one move forward and backward

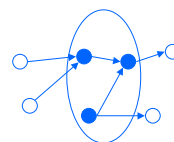
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Kleinberg's algorithm

- Step 1: expand by one move forward and backward



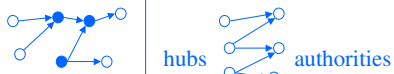
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Kleinberg's algorithm

- on the resulting graph, give high score (= 'authorities') to nodes that many important nodes point to
- give high importance score ('hubs') to nodes that point to good 'authorities'



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Kleinberg's algorithm

observations

- recursive definition!
- each node (say, ' i '-th node) has both an authoritativeness score a_i and a hubness score h_i

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Kleinberg's algorithm

Let $\mathbf{A}$ be the adjacency matrix:

the (i,j) entry is 1 if the edge from i to j exists

Let $\mathbf{h}$ and $\mathbf{a}$ be $[n \times 1]$ vectors with the 'hubness' and 'authoritativeness' scores.

Then:

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Kleinberg's algorithm

Then:

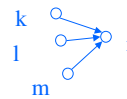
$$a_i = h_k + h_l + h_m$$

that is

$$a_i = \text{Sum}(h_j) \text{ over all } j \text{ that } (j,i) \text{ edge exists}$$

or

$$\mathbf{a} = \mathbf{A}^T \mathbf{h}$$

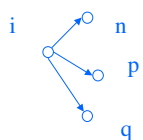


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Kleinberg's algorithm



symmetrically, for the 'hubness':

$$h_i = a_n + a_p + a_q$$

that is

$$h_i = \text{Sum}(a_j) \text{ over all } j \text{ that } (i,j) \text{ edge exists}$$

or

$$\mathbf{h} = \mathbf{A} \mathbf{a}$$

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Kleinberg's algorithm

In conclusion, we want vectors $\mathbf{h}$ and $\mathbf{a}$ such that:

$$\mathbf{h} = \mathbf{A} \mathbf{a}$$

$$\mathbf{a} = \mathbf{A}^T \mathbf{h}$$

That is:

$$\mathbf{a} = \mathbf{A}^T \mathbf{A} \mathbf{a}$$

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Kleinberg's algorithm

$\mathbf{a}$ is a right-eigenvector of the adjacency matrix $\mathbf{A}$ (by dfn!)

Starting from random $\mathbf{a}'$ and iterating, we'll eventually converge

(Q: to which of all the eigenvectors? why?)

Kleinberg's algorithm

(Q: to which of all the eigenvectors? why?)

A: to the one of the strongest eigenvalue, because of [Property 2]:

$$(\mathbf{A}^T \mathbf{A})^k \mathbf{v}' \sim (\text{constant}) \mathbf{v}_1$$

Kleinberg's algorithm - results

Eg., for the query 'java':

0.328 www.gamelan.com

0.251 java.sun.com

0.190 www.digitalfocus.com ("the java developer")

Kleinberg's algorithm - discussion

- 'authority' score can be used to find 'similar pages' (how?)
- closely related to 'citation analysis', social networks / 'small world' phenomena

google/page-rank algorithm

- closely related: imagine a particle randomly moving along the edges (*)
- compute its steady-state probabilities

(*) with occasional random jumps

SVD - outline

- Motivation
- Definition - properties
- Interpretation
- Complexity
- Applications - success stories
- ➡ • Conclusions

SVD - conclusions

SVD: a **valuable** tool - two major properties:

- (A) it gives the *optimal* low-rank approximation (= least squares best hyper-plane)
 - it finds ‘concepts’ = principal components = features; (linear) correlations
 - dim. reduction; visualization
 - (solves over- and under-constraint problems)

SVD - conclusions - cont'd

- (B) eigenvectors: fixed points

$$\mathbf{A}^T \mathbf{A} \mathbf{v}_i = \lambda_i \mathbf{v}_i$$

- steady-state prob. in Markov Chains / graphs
- hubs/authorities

Conclusions - in detail:

- given a (document-term) matrix, it finds ‘concepts’ (LSI)
- ... and can reduce dimensionality (KL)
- ... and can find rules (PCA; RatioRules)

Conclusions cont'd

- ... and can find fixed-points or steady-state probabilities (Kleinberg / google/ Markov Chains)
- (... and can solve optimally over- and under-constraint linear systems - see Appendix, (Eq. C1) - Moore/Penrose pseudo-inverse)

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Appendix: SVD properties

- (A): obvious
- (B): less obvious
- (C): least obvious (and most powerful!)

Properties - by defn.:

$$A(0): \mathbf{A}_{[n \times m]} = \mathbf{U}_{[n \times r]} \mathbf{\Lambda}_{[r \times r]} \mathbf{V}^T_{[r \times m]}$$

$$A(1): \mathbf{U}^T_{[r \times n]} \mathbf{U}_{[n \times r]} = \mathbf{I}_{[r \times r]} \text{ (identity matrix)}$$

$$A(2): \mathbf{V}^T_{[r \times n]} \mathbf{V}_{[n \times r]} = \mathbf{I}_{[r \times r]}$$

$$A(3): \mathbf{\Lambda}^k = \text{diag}(\lambda_1^k, \lambda_2^k, \dots, \lambda_r^k) \text{ (k: ANY real number)}$$

$$A(4): \mathbf{A}^T = \mathbf{V} \mathbf{\Lambda} \mathbf{U}^T$$

Less obvious properties

$$A(0): \mathbf{A}_{[n \times m]} = \mathbf{U}_{[n \times r]} \mathbf{\Lambda}_{[r \times r]} \mathbf{V}^T_{[r \times m]}$$

$$B(1): \mathbf{A}_{[n \times m]} (\mathbf{A}^T)_{[m \times n]} = ??$$

Less obvious properties

$$A(0): \mathbf{A}_{[n \times m]} = \mathbf{U}_{[n \times r]} \mathbf{\Lambda}_{[r \times r]} \mathbf{V}_{[r \times m]}^T$$

$$B(1): \mathbf{A}_{[n \times m]} (\mathbf{A}^T)_{[m \times n]} = \mathbf{U} \mathbf{\Lambda}^2 \mathbf{U}^T$$

symmetric; Intuition?

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Less obvious properties

$$A(0): \mathbf{A}_{[n \times m]} = \mathbf{U}_{[n \times r]} \mathbf{\Lambda}_{[r \times r]} \mathbf{V}_{[r \times m]}^T$$

$$B(1): \mathbf{A}_{[n \times m]} (\mathbf{A}^T)_{[m \times n]} = \mathbf{U} \mathbf{\Lambda}^2 \mathbf{U}^T$$

symmetric; Intuition?

'document-to-document' similarity matrix

$$B(2): \text{symmetrically, for 'V'}$$

$$(\mathbf{A}^T)_{[m \times n]} \mathbf{A}_{[n \times m]} = \mathbf{V} \mathbf{\Lambda}^2 \mathbf{V}^T$$

Intuition?

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Less obvious properties

A: term-to-term similarity matrix

$$B(3): ((\mathbf{A}^T)_{[m \times n]} \mathbf{A}_{[n \times m]})^k = \mathbf{V} \mathbf{\Lambda}^{2k} \mathbf{V}^T$$

and

$$B(4): (\mathbf{A}^T \mathbf{A})^k \sim \mathbf{v}_1 \lambda_1^{2k} \mathbf{v}_1^T \text{ for } k \gg 1$$

where

$\mathbf{v}_1$: $[m \times 1]$ first column (eigenvector) of $\mathbf{V}$

λ_1 : strongest eigenvalue

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Less obvious properties

$$B(4): (\mathbf{A}^T \mathbf{A})^k \sim \mathbf{v}_1 \lambda_1^{2k} \mathbf{v}_1^T \text{ for } k \gg 1$$

$$B(5): (\mathbf{A}^T \mathbf{A})^k \mathbf{v}' \sim (\text{constant}) \mathbf{v}_1$$

ie., for (almost) any $\mathbf{v}'$, it converges to a vector parallel to $\mathbf{v}_1$

Thus, useful to compute first eigenvector/value (as well as the next ones, too...)

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Less obvious properties - repeated:

$$A(0): \mathbf{A}_{[n \times m]} = \mathbf{U}_{[n \times r]} \mathbf{\Lambda}_{[r \times r]} \mathbf{V}_{[r \times m]}^T$$

$$B(1): \mathbf{A}_{[n \times m]} (\mathbf{A}^T)_{[m \times n]} = \mathbf{U} \mathbf{\Lambda}^2 \mathbf{U}^T$$

$$B(2): (\mathbf{A}^T)_{[m \times n]} \mathbf{A}_{[n \times m]} = \mathbf{V} \mathbf{\Lambda}^2 \mathbf{V}^T$$

$$B(3): ((\mathbf{A}^T)_{[m \times n]} \mathbf{A}_{[n \times m]})^k = \mathbf{V} \mathbf{\Lambda}^{2k} \mathbf{V}^T$$

$$B(4): (\mathbf{A}^T \mathbf{A})^k \sim \mathbf{v}_1 \lambda_1^{2k} \mathbf{v}_1^T$$

$$B(5): (\mathbf{A}^T \mathbf{A})^k \mathbf{v}' \sim (\text{constant}) \mathbf{v}_1$$

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Least obvious properties

$$A(0): \mathbf{A}_{[n \times m]} = \mathbf{U}_{[n \times r]} \mathbf{\Lambda}_{[r \times r]} \mathbf{V}_{[r \times m]}^T$$

$$C(1): \mathbf{A}_{[n \times m]} \mathbf{x}_{[m \times 1]} = \mathbf{b}_{[n \times 1]}$$

let $\mathbf{x}_0 = \mathbf{V} \mathbf{\Lambda}^{(-1)} \mathbf{U}^T \mathbf{b}$

if under-specified, $\mathbf{x}_0$ gives 'shortest' solution

if over-specified, it gives the 'solution' with the smallest least squares error

(see Num. Recipes, p. 62)

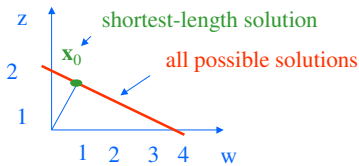
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Least obvious properties

Illustration: under-specified, eg
 $[1 \ 2] [w \ z]^T = 4$ (ie, $1w + 2z = 4$)



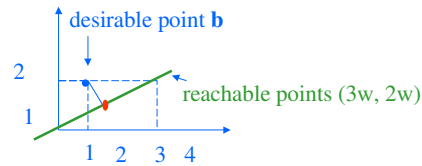
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Least obvious properties

Illustration: over-specified, eg
 $[3 \ 2]^T [w] = [1 \ 2]^T$ (ie, $3w = 1; 2w = 2$)



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Least obvious properties - cont'd

$$A(0): \mathbf{A}_{[n \times m]} = \mathbf{U}_{[n \times r]} \mathbf{\Lambda}_{[r \times r]} \mathbf{V}^T_{[r \times m]}$$

$$C(2): \mathbf{A}_{[n \times m]} \mathbf{v}_1_{[m \times 1]} = \lambda_1 \mathbf{u}_1_{[n \times 1]}$$

where $\mathbf{v}_1, \mathbf{u}_1$ the first (column) vectors of $\mathbf{V}, \mathbf{U}$. ($\mathbf{v}_1$ == right-eigenvector)

$$C(3): \text{symmetrically: } \mathbf{u}_1^T \mathbf{A} = \lambda_1 \mathbf{v}_1^T$$

$\mathbf{u}_1$ == left-eigenvector

Therefore:

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Least obvious properties - cont'd

$$A(0): \mathbf{A}_{[n \times m]} = \mathbf{U}_{[n \times r]} \mathbf{\Lambda}_{[r \times r]} \mathbf{V}^T_{[r \times m]}$$

$$C(4): \mathbf{A}^T \mathbf{A} \mathbf{v}_1 = \lambda_1^2 \mathbf{v}_1$$

(fixed point - the usual defn of eigenvector for a symmetric matrix)

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Least obvious properties -
altogether

$$A(0): \mathbf{A}_{[n \times m]} = \mathbf{U}_{[n \times r]} \mathbf{\Lambda}_{[r \times r]} \mathbf{V}^T_{[r \times m]}$$

$$C(1): \mathbf{A}_{[n \times m]} \mathbf{x}_{[m \times 1]} = \mathbf{b}_{[n \times 1]}$$

then, $\mathbf{x}_0 = \mathbf{V} \mathbf{\Lambda}^{(-1)} \mathbf{U}^T \mathbf{b}$: shortest, actual or least-squares solution

$$C(2): \mathbf{A}_{[n \times m]} \mathbf{v}_1_{[m \times 1]} = \lambda_1 \mathbf{u}_1_{[n \times 1]}$$

$$C(3): \mathbf{u}_1^T \mathbf{A} = \lambda_1 \mathbf{v}_1^T$$

$$C(4): \mathbf{A}^T \mathbf{A} \mathbf{v}_1 = \lambda_1^2 \mathbf{v}_1$$

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Properties - conclusions

$$A(0): \mathbf{A}_{[n \times m]} = \mathbf{U}_{[n \times r]} \mathbf{\Lambda}_{[r \times r]} \mathbf{V}^T_{[r \times m]}$$

$$B(5): (\mathbf{A}^T \mathbf{A})^k \mathbf{v}' \sim (\text{constant}) \mathbf{v}_1$$

$$C(1): \mathbf{A}_{[n \times m]} \mathbf{x}_{[m \times 1]} = \mathbf{b}_{[n \times 1]}$$

then, $\mathbf{x}_0 = \mathbf{V} \mathbf{\Lambda}^{(-1)} \mathbf{U}^T \mathbf{b}$: shortest, actual or least-squares solution

$$C(4): \mathbf{A}^T \mathbf{A} \mathbf{v}_1 = \lambda_1^2 \mathbf{v}_1$$

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