

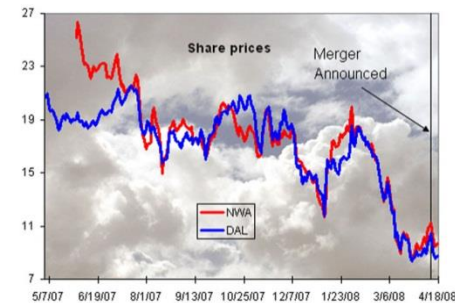
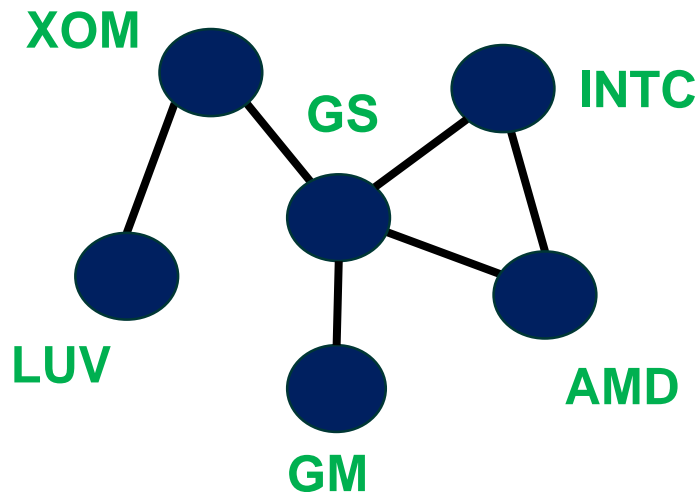


# A Spectral Algorithm for Latent Tree Graphical Models

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Carnegie Mellon University

# Probabilistic Graphical Models

Ubiquitous in many applications, where it is necessary to model structure and dependencies among a set of variables.

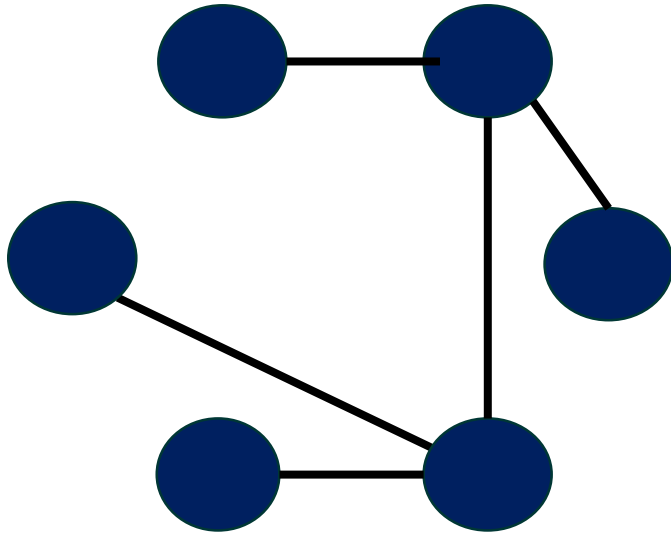


## Return on Investment



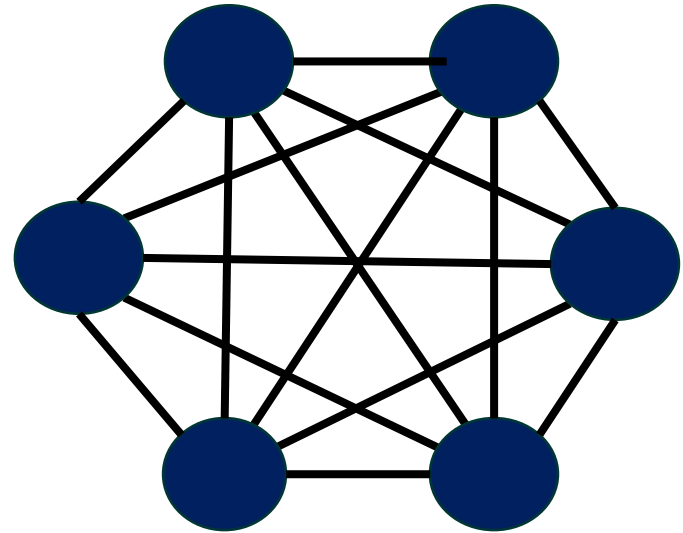
Source: MSN Money.com, Case Shiller

## Tree Graphical Models



- **Very restrictive model**
- Structure Learning – **Easy**
- Parameter learning – **Easy**
- Inference – **Easy**

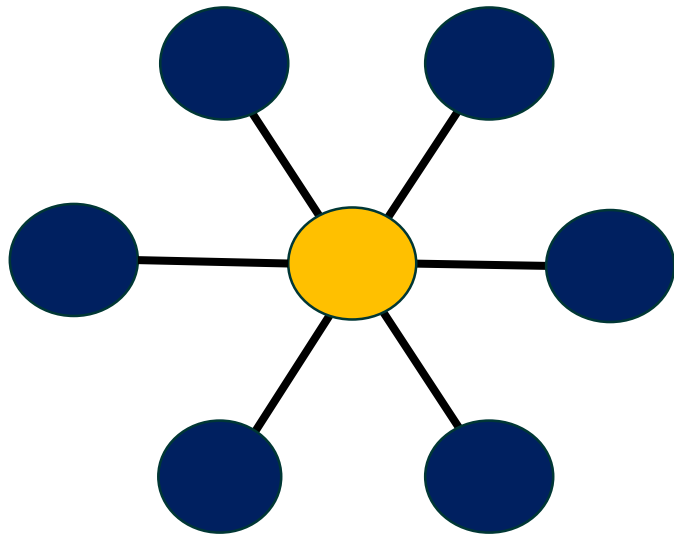
## Loopy Graphical Models



- **Very rich model**
- Structure Learning – **Hard**
- Parameter learning – **Hard**
- Inference – **Hard**

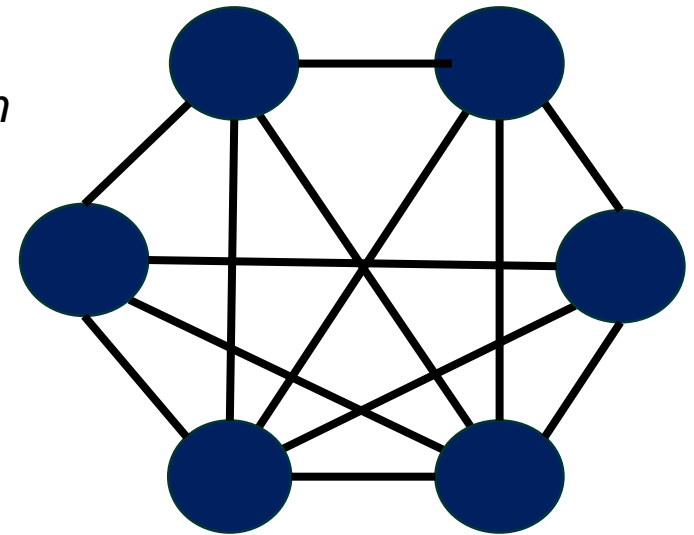
# Latent Tree Graphical Models

Add additional unobserved variables to enrich flexibility of model



Latent tree

*Integrating hidden variable out*



Loopy model

- Reasonably rich model
- Structure Learning – Tractable (Choi et al. 2010)
- Parameter learning/Inference – ???

## Expectation Maximization

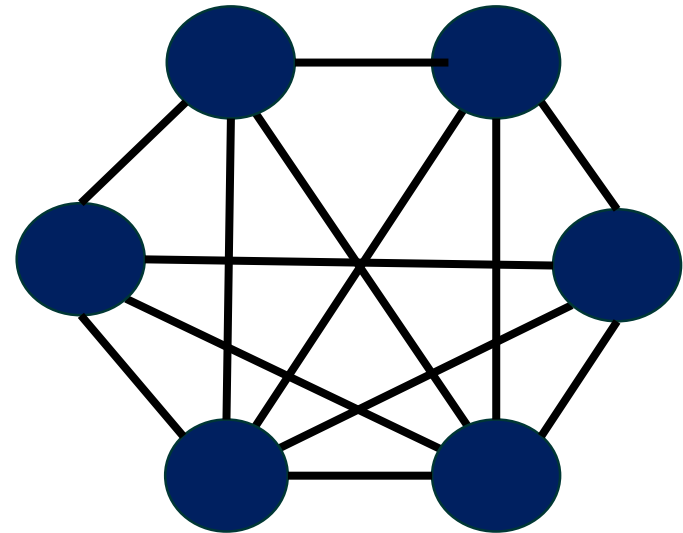
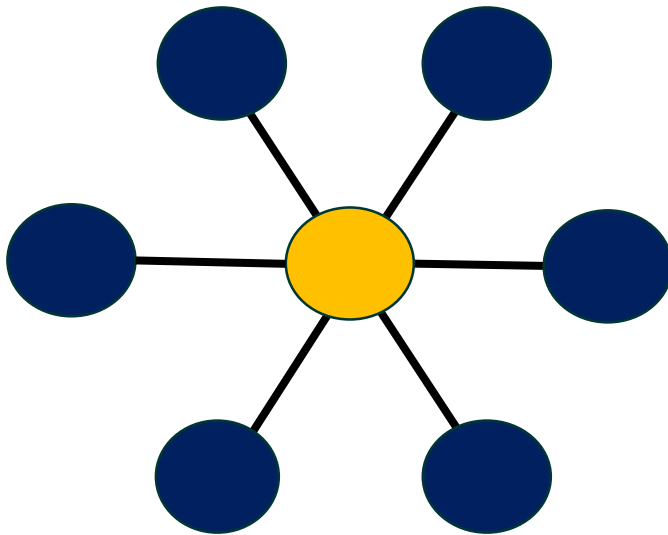
- Recovers parameters explicitly and therefore can recover hidden states
- Slow – First Order Optimization Method
- Local Minima
- Lack of Theoretical Guarantees

## Spectral Algorithm

- Does not explicitly recover parameters, so cannot recover hidden states (We can only compute observed marginals).
- (Very) Fast – No optimization needed
- Local Minima Free
- Consistent

# Focusing on Inference

- Explicitly recovering the hidden states makes the problem fundamentally non-convex.
- But in many applications the goal is to simply do prediction (i.e. compute marginals among observed variables)



# Spectral Algorithm

- Do **NOT** explicitly learn latent parameters
- Instead learn “transformed” version of parameters.

$$P = AB$$



A and B depend on hidden variables

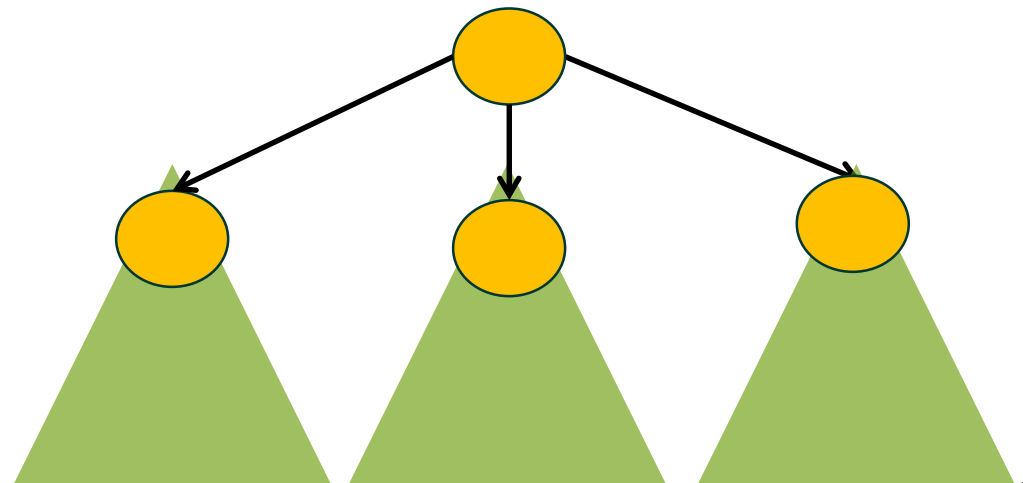
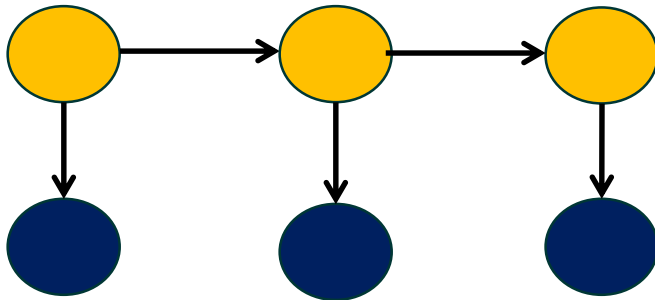
$$P = ASS^{-1}B$$

**Key:** Construct **S** such that **AS** and **S<sup>-1</sup> B** only depend on observed variables. Then we can easily compute **P** (without ever learning **A**, **B**, or **S** individually)

Underlying dependence on spectral properties is what gives the method the name spectral algorithm.

# Related Work

- Hsu et al. – Spectral Algorithm for HMMs
- Boots et al. - Reduced Rank HMMs
- Song et al. - Kernelized Spectral Method for nonparametric HMMs
- **Challenges** for Latent Trees
  - Topology significantly more complex
  - Not every hidden variable has an observed neighbor

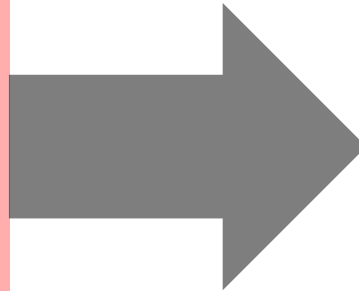




# Algorithm Overview

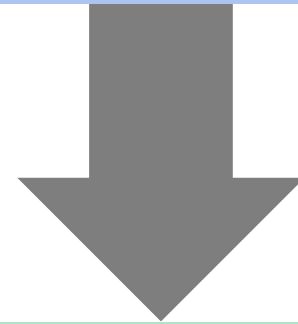
## *Latent Tree Representation*

**Compute joint probability as  
sequence of matrix  
multiplications**



## *Transformed Representation*

**Insert transform matrices  
so that we can estimate  
transformed quantities  
instead of actual quantities**



## *Observable Representation*

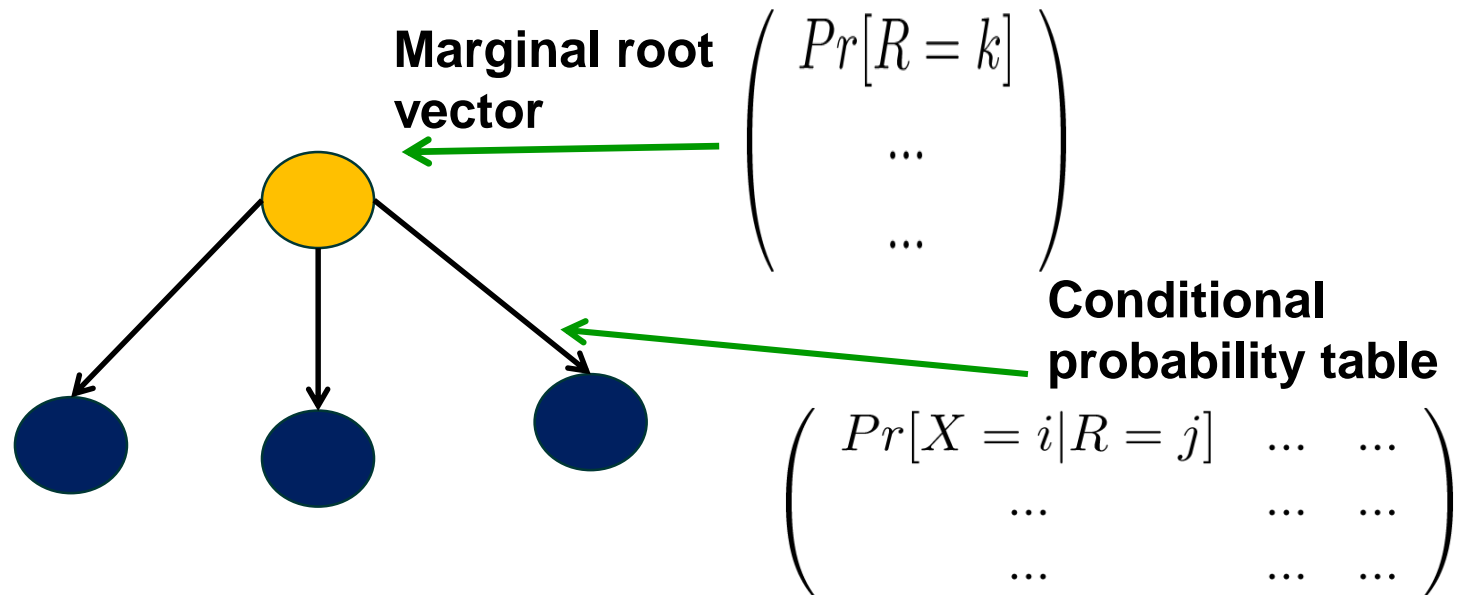
**Prove that these  
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of observed variables.**

# Algorithm Overview

## *Latent Tree Representation*

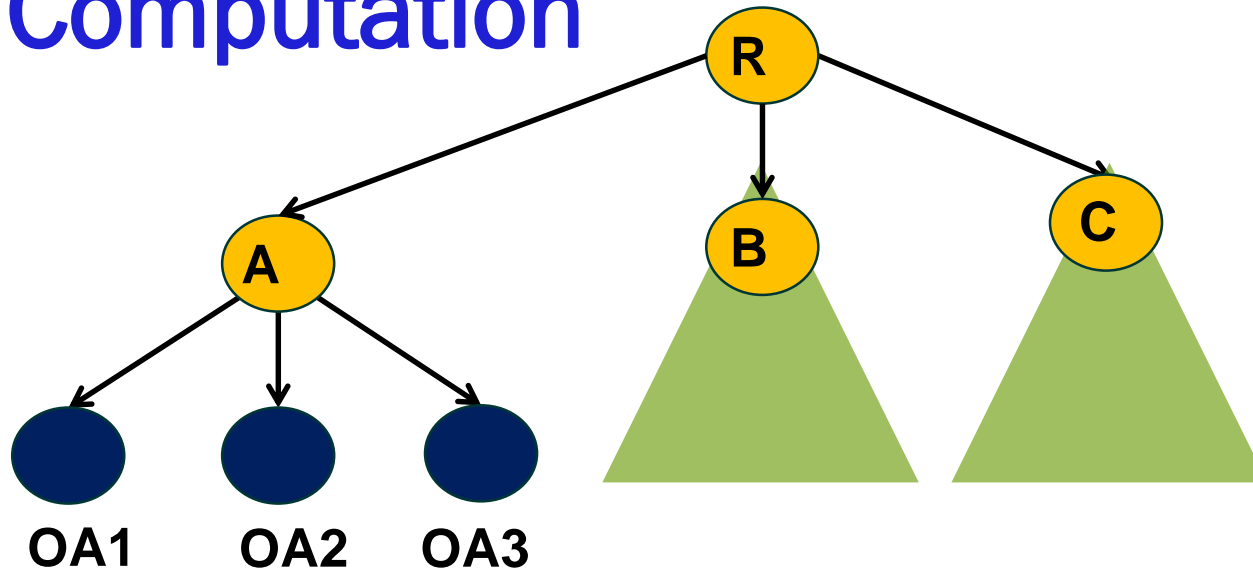
**Compute joint probability as  
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multiplications**

# Parametrizing Latent Trees



- All hidden nodes are internal
- Conditional Probability Tables (CPTs) **cannot be directly estimated from data**

# Representing Joint Probability Computation

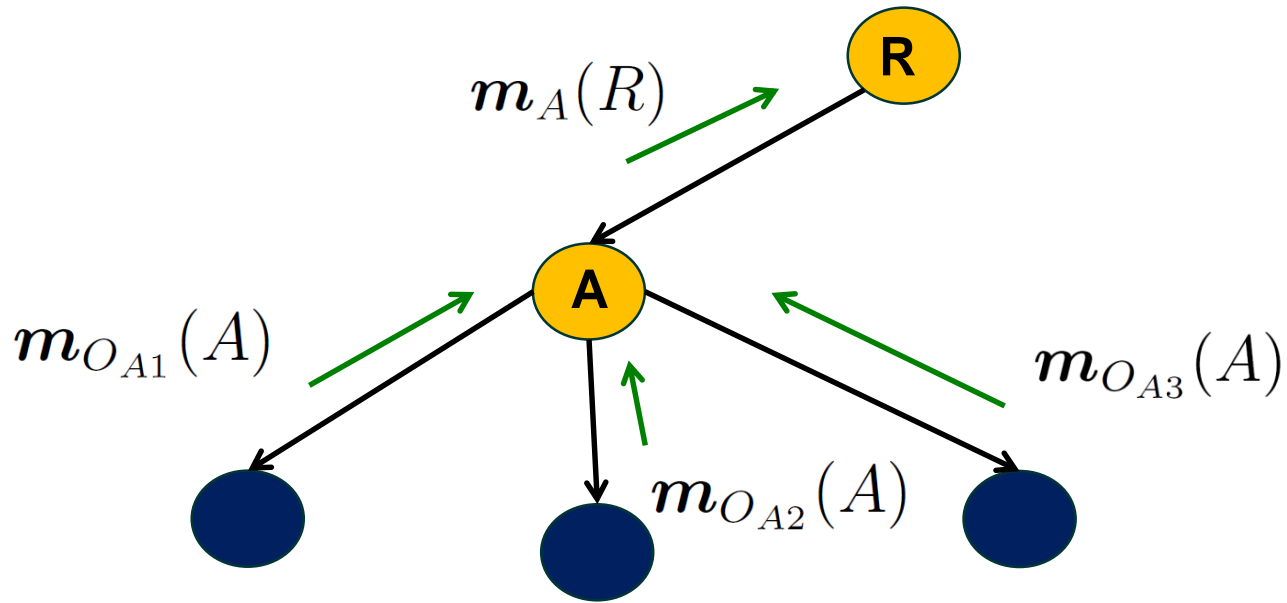


We would like to compute the following joint probability of all observed variables:

$$\mathbb{P}[O_{A1} = o_{A1}, O_{A2} = o_{A2}, O_{A3} = o_{A3}, \dots\dots\dots]$$

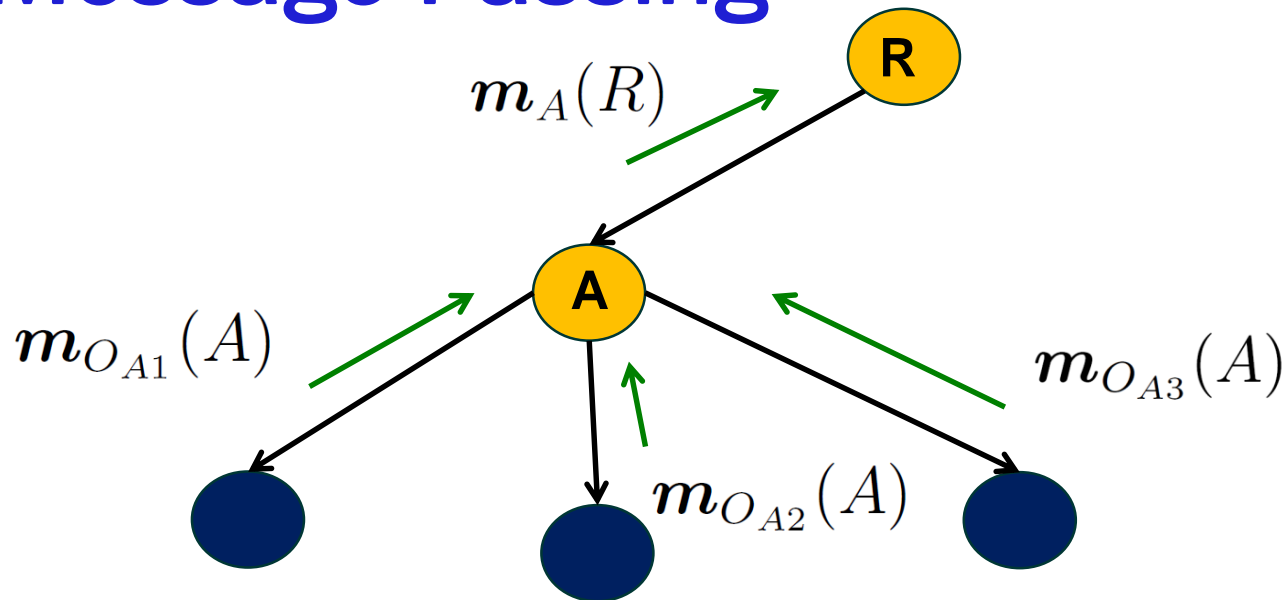
Compute this using message passing

# Message Passing



$$m_A(R) = \sum_A \mathbb{P}[A|R] m_{O_{A1}}(A) m_{O_{A2}}(A) m_{O_{A3}}(A)$$

# Message Passing



a vector

$$m_{o_{A1}}(A) = \mathbb{P}[O_{A1} = o_{A1} | A] =$$

(remember we don't know how to explicitly compute this since it depends on A...)

# Representing the Product

$$m_{o_{A1}, o_{A2}, o_{A3}}(A)$$

$$m_A(R) = \sum_A \mathbb{P}[A|R] m_{O_{A1}}(A) m_{O_{A2}}(A) m_{O_{A3}}(A)$$

$$m_{o_{A1}, o_{A2}, o_{A3}}(A) = \mathbb{P}[O_{A1} = o_{A1}|A] \cdot \mathbb{P}[O_{A2} = o_{A2}|A] \cdot \mathbb{P}[O_{A3} = o_{A3}|A]$$



# Instead let Message be Diagonal Matrix

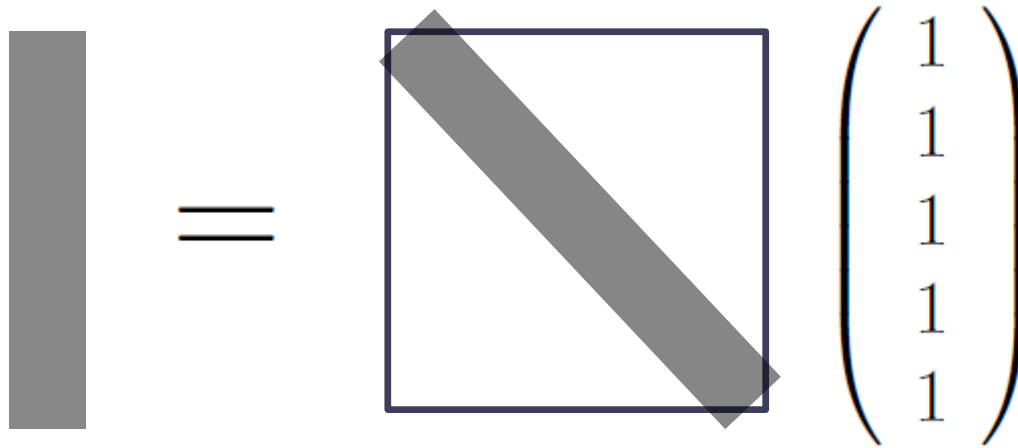
$$\mathbb{P}[O_{A1} = o_{A1}|A] \cdot \mathbb{P}[O_{A2} = o_{A2}|A] \cdot \mathbb{P}[O_{A3} = o_{A3}|A]$$



$$\mathbf{M}_A(R) = \mathbf{M}_{A1}(A) \quad \mathbf{M}_{A2}(A) \quad \mathbf{M}_{A3}(A)$$



# Equivalence with Original Message



The diagram illustrates the equivalence between a vertical gray bar, an equals sign, a square with a gray diagonal bar, and a column vector of five ones. This represents the equation  $\mathbf{1}_A = \mathbf{M}_{A1}(A) \mathbf{1}_A$ .

$$\mathbf{m}_A(R) = \mathbf{M}_{A1}(A) \mathbf{1}_A$$

# Representing the Sum

- Represent conditional probability table with a cube

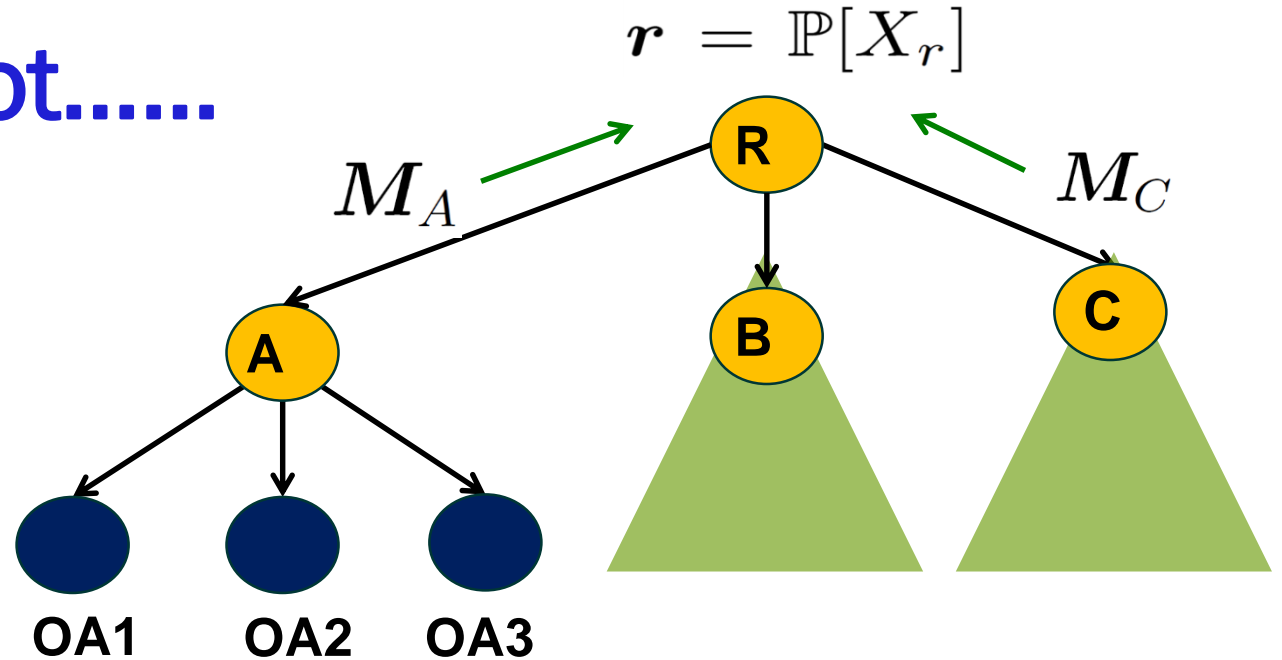
Representation of  $\Pr[R | A]$   
as a cube

$$\begin{array}{c}
 \begin{array}{|c|} \hline \text{ } \\ \hline \end{array}
 \end{array}
 M_A(R) = \begin{array}{c} \text{Cube} \\ \mathcal{T}_{A|R} \end{array} \bar{\times}_1 \begin{array}{|c|} \hline \text{ } \\ \hline \end{array}$$

$$\begin{array}{|c|} \hline \text{ } \\ \hline \end{array}
 m_A(R) = \sum_A \mathbb{P}[A|R] m_{O_{A1}}(A) m_{O_{A2}}(A) m_{O_{A3}}(A)$$

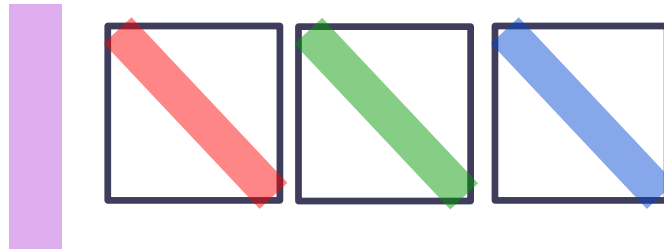
$$M_{o_{A1}}(A) M_{o_{A2}}(A) M_{o_{A3}}(A) \mathbf{1}_A$$

# At the root.....



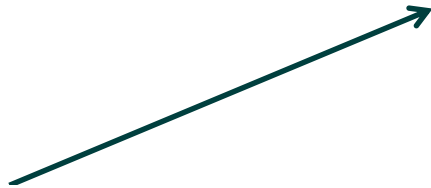
$$\mathbb{P}[O_{A1} = o_{A1}, O_{A2} = o_{A2}, O_{A3} = o_{A3}, \dots] =$$

$$\mathbf{r}^\top \mathbf{M}_A \mathbf{M}_B \mathbf{M}_C \mathbf{1}_r$$



# Computation of Joint Probability

$$\mathbb{P}[O_{A1} = o_{A1}, O_{A2} = o_{A2}, O_{A3} = o_{A3}, \dots] = \mathbf{r}^\top \mathbf{M}_A \mathbf{M}_B \mathbf{M}_C \mathbf{1}_r$$



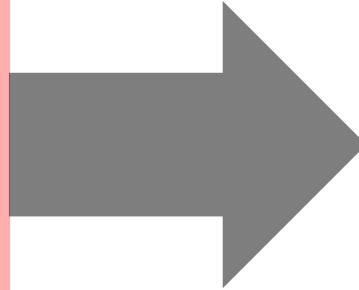
$$\mathbf{M}_A = \mathcal{T}_{A|R} \bar{\times} \mathbf{1} \mathbf{M}_{o_{A1}} \mathbf{M}_{o_{A2}} \mathbf{M}_{o_{A3}} \mathbf{1}_A$$

**Sequence of matrix multiplications**

# Algorithm Overview

## *Latent Tree Representation*

**Compute joint probability as  
sequence of matrix  
multiplications**



## *Transformed Representation*

**Insert transform matrices  
so that we can estimate  
transformed quantities  
instead of actual quantities**

# Transformed Representation

Transform matrices  $RL^{-1} = I$

$$\mathbb{P}[O = o] = r^\top M_A M_B M_C \mathbf{1}_r = r^\top M_A \overline{RL^{-1}} M_B M_C \mathbf{1}_r$$

$$M_A = \mathcal{T}_{A|R} \bar{\times}_1 L_{o_{A1}} \overline{L_{o_{A1}}^{-1} M_{o_{A1}} R_{o_{A1}}} L_{o_{A2}}^{-1} M_{o_{A2}} R_{o_{A2}} L_{o_{A3}}^{-1} M_{o_{A3}} R_{o_{A3}} \mathbf{1}_A$$

$$\tilde{M}_{o_{A1}}$$

# Transformed Representation

Original Quantity:  $M_{o_{A1}}$  

Transformed Quantity:  $\tilde{M}_{o_{A1}} = L_{o_{A1}}^{-1} M_{o_{A1}} R_{o_{A1}}$

**Estimate this instead!**

Original Quantity:  $r^\top$  

Transformed Quantity:  $\tilde{r}^\top = r^\top L_A$

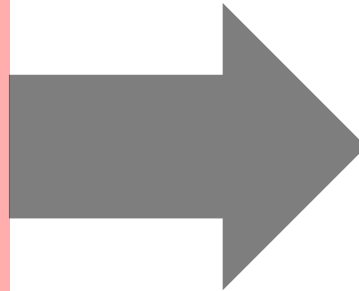
**Estimate this instead!**

**And similarly for the cube and one vector.....**

# Algorithm Outline

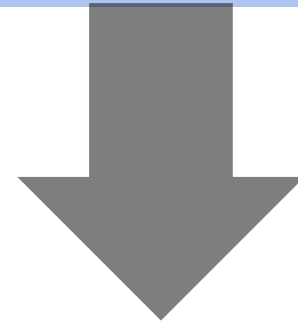
## *Latent Tree Representation*

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## *Observable Representation*

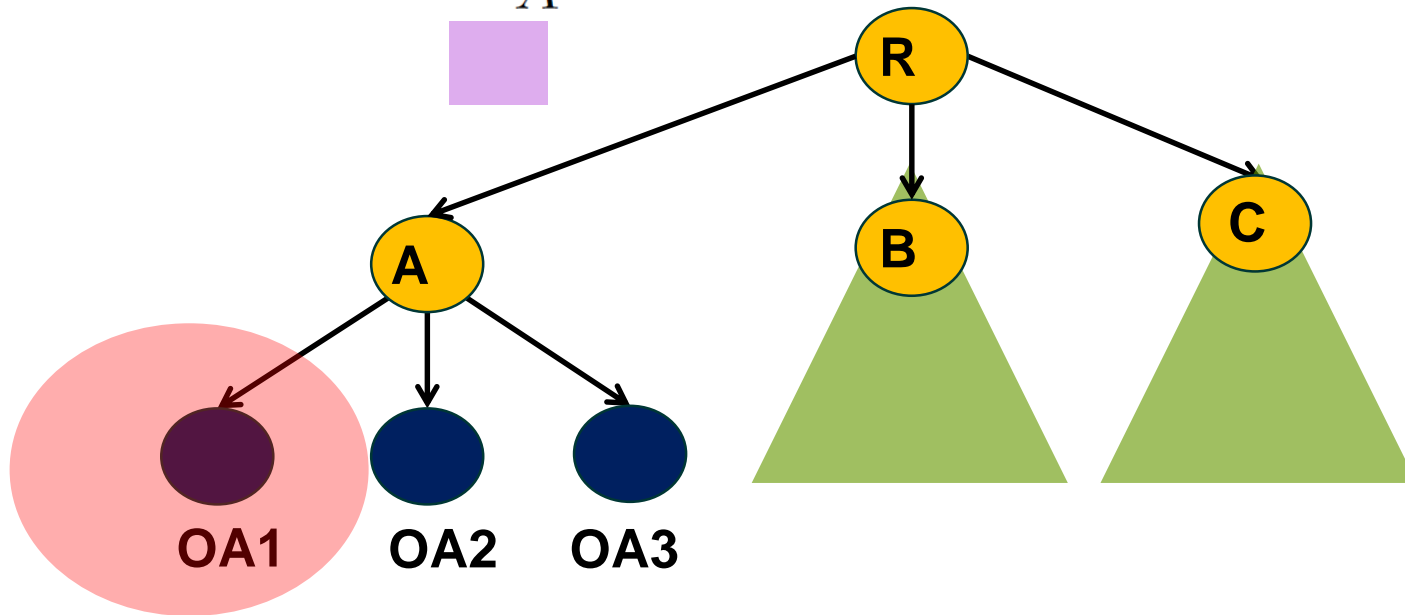
**Prove that these  
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# Observable Representation

Consider the root:

$$\tilde{\mathbf{r}}^\top = \mathbf{r}^\top \mathbf{L}_A$$



Consider the following  
choice for  $\mathbf{L}$ :

$$\mathbf{Z}(k, l) = \mathbb{P}[O_{A1} = k | R = l]$$

# Observable Representation

$$\mathbf{r}^\top = \text{[blue box]}$$

**Not a function of observed variables**

$$\tilde{\mathbf{r}}^\top = \text{[blue box]} \quad \mathbf{r}^\top = \mathbb{P}[R]^\top$$

**function of observed variables**

$$\begin{array}{c} \mathbb{P}[O_{A1} = k | R = l] \\ \text{[red box with vertical brown bar and } \mathbf{L} \text{]} \end{array} = \begin{array}{c} \mathbb{P}[O_{A1}]^\top \\ \text{[purple box with green circle]} \end{array}$$

$$\tilde{r}[o] = \sum_R \mathbb{P}[O_{A1} = o | R] \mathbb{P}[R] = \mathbb{P}[O_{A1} = o]$$

**R integrated out by the matrix multiplication!**

# Observable Representation

- If  $\mathbf{L} = \mathbf{Z}^\top$  then  $\mathbf{L}^{-1}$  does not exist since  $\mathbf{Z}$  is not square!

$$\mathbf{Z}(k, l) = \mathbb{P}[O_{A1} = k | R = l]$$

- **Solution:** Project  $\mathbf{Z}$  down to the subspace of hidden variables with a matrix  $\mathbf{U}$

$$\mathbf{L} = \mathbf{Z}^\top \mathbf{U} \quad \mathbf{L}^{-1} = (\mathbf{Z}^\top \mathbf{U})^{-1}$$

$$\tilde{\mathbf{r}}^\top = \mathbf{r}^\top \mathbf{L}_A \quad \longrightarrow \quad \mathbf{r}^\top = \mathbb{P}[O_{A1}]^\top \mathbf{U}_{O_{A1}}$$

# Observable Representation (Message)

$$M_A = \square$$

Not a function of observed variables

$$\tilde{M}_{o_{A1}}$$

=

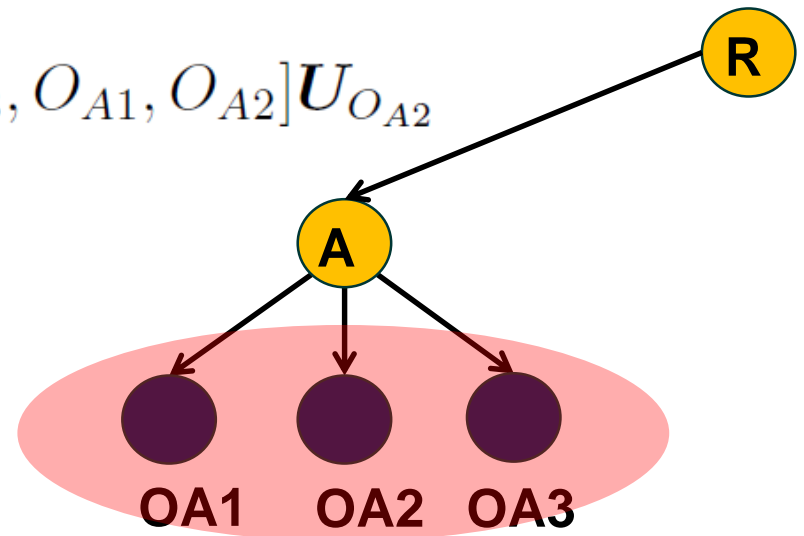
$$L_{o_{A1}}^{-1}$$

$$M_A$$

$$R_{o_{A1}}$$

function of observed variables

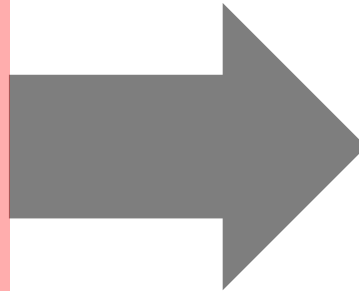
$$\begin{aligned}
 \tilde{M}_{o_{A1}} &= f(O_{A1}, O_{A2}, O_{A3}) \\
 &= (\mathbb{P}[O_{A3}, O_{A1}] U_{O_{A1}})^\dagger \mathbb{P}[O_{A3}, O_{A1}, O_{A2}] U_{O_{A2}}
 \end{aligned}$$



# Algorithm Overview

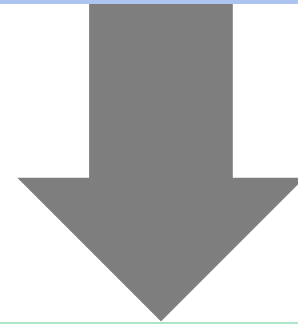
## *Latent Tree Representation*

**Compute joint probability as  
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## *Transformed Representation*

**Add transform matrices to  
estimate transformed  
quantities instead of actual  
quantities**



## *Observable Representation*

**Prove that these  
transformed quantities are  
functions  
of observed variables.**

# Sample Complexity

- When empirical estimate of transformed quantities equals true transformed quantities, joint probability estimate is equal to the true joint probability.
- Aggregate the errors across the quantities to get a bound.

*With high probability,*

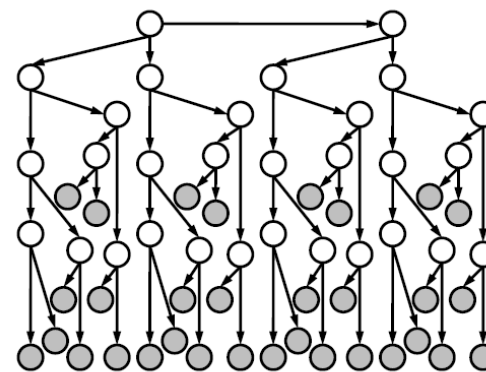
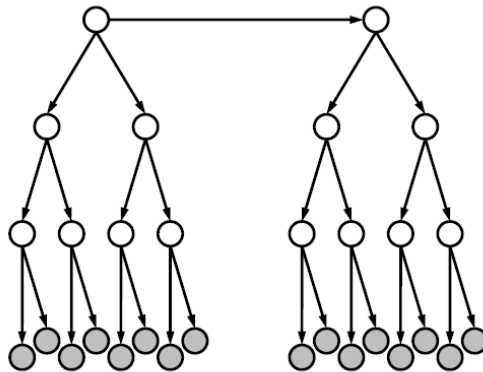
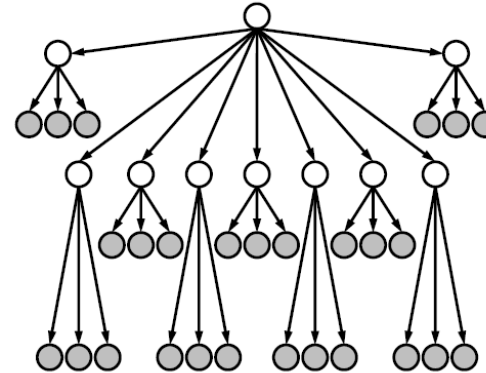
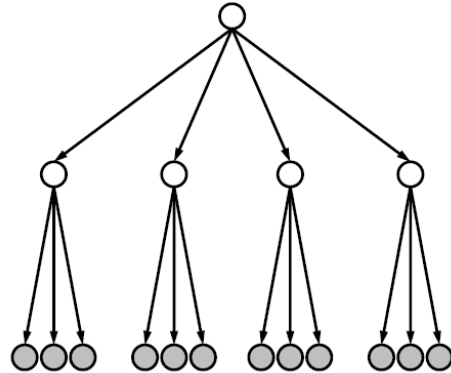
$$\sum_{x_1, \dots, x_O} \left| \hat{\mathbb{P}}[x_1, \dots, x_O] - \mathbb{P}[x_1, \dots, x_O] \right| \leq O \left( \sqrt{\frac{(d_{\max} S_H)^{2\ell+1} S_O}{N}} \right)$$

The equation is annotated with arrows indicating the meaning of its components:
 

- Max degree** (green arrow) points to  $d_{\max}$ .
- Number of hidden states** (purple arrow) points to  $S_H$ .
- depth** (green arrow) points to the exponent  $2\ell+1$ .
- Number of samples** (red arrow) points to  $N$ .
- Number of observed states** (purple arrow) points to  $S_O$ .

# Simulations

- 4 types of trees:

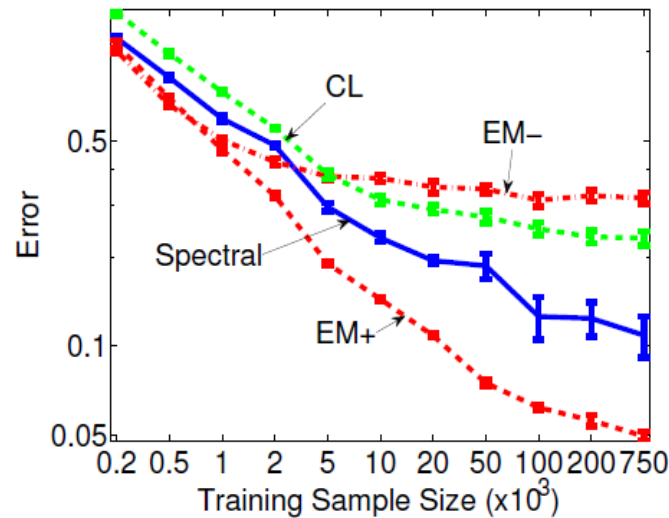
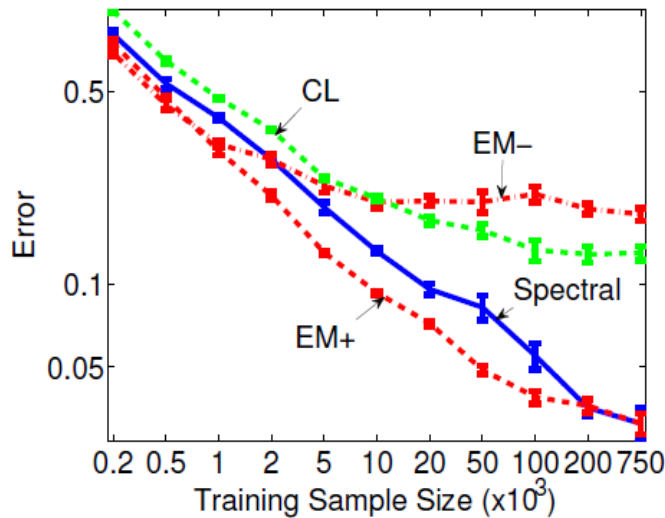


Compare with:

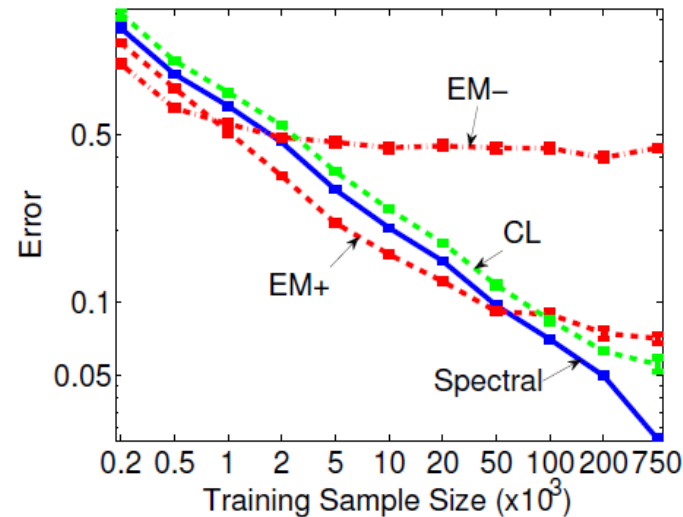
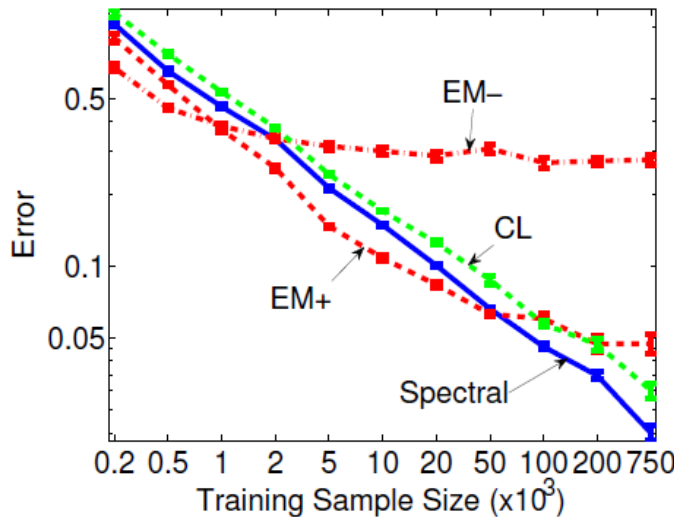
- **EM** (high precision), **EM** (low precision) on latent tree
- **Chow liu tree** on best fully observable tree – more restricted model.

# Simulations-Error

Spectral  
 EM  
 Chow Liu

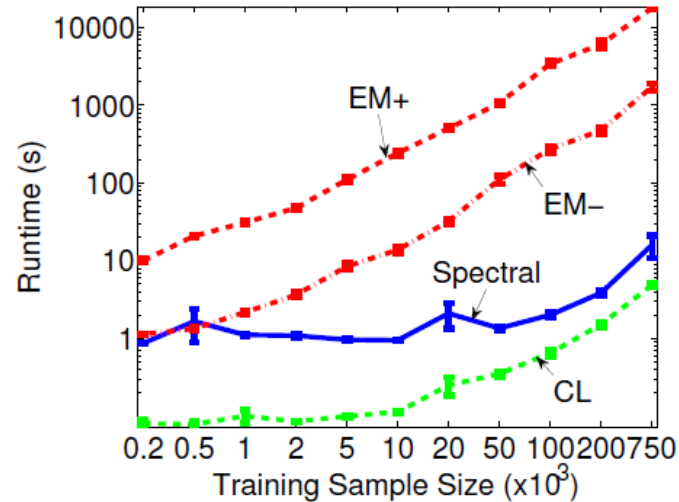
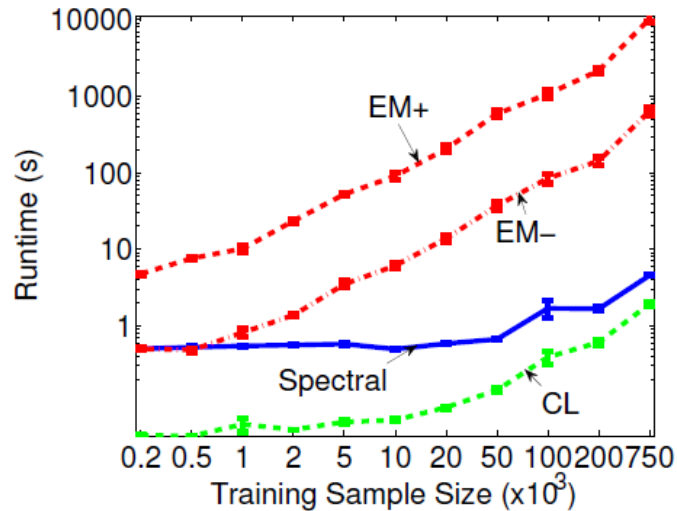


Spectral  
 EM  
 Chow Liu

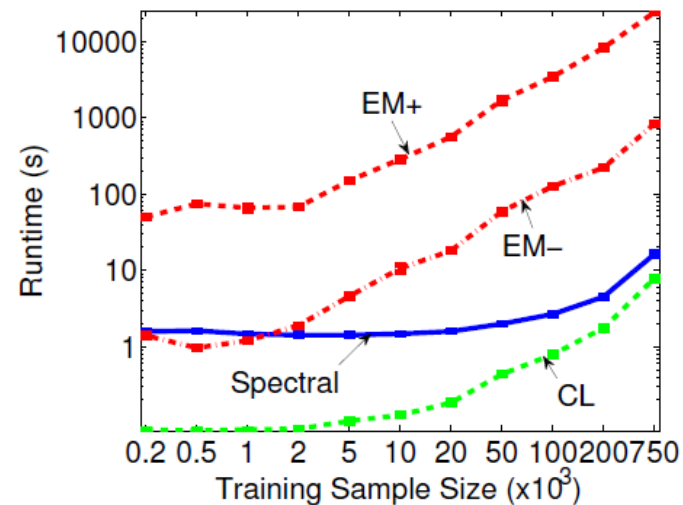
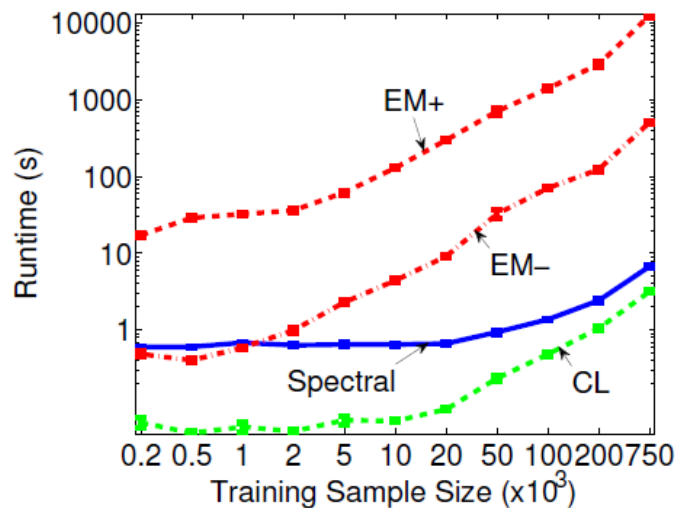




# Simulations-Speed



**Spectral**  
**EM**  
**Chow Liu**

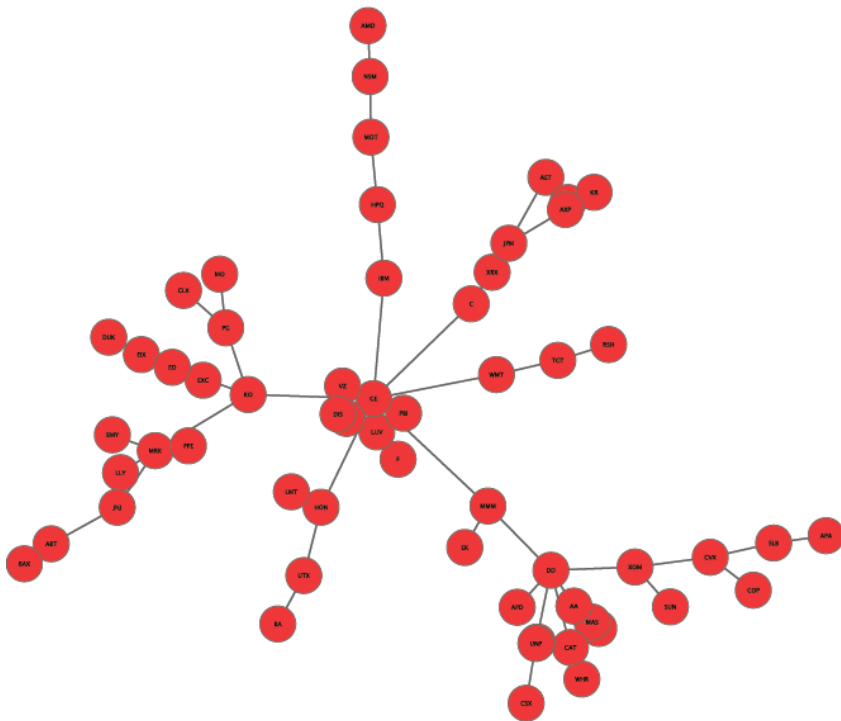


**Spectral**  
**EM**  
**Chow Liu**

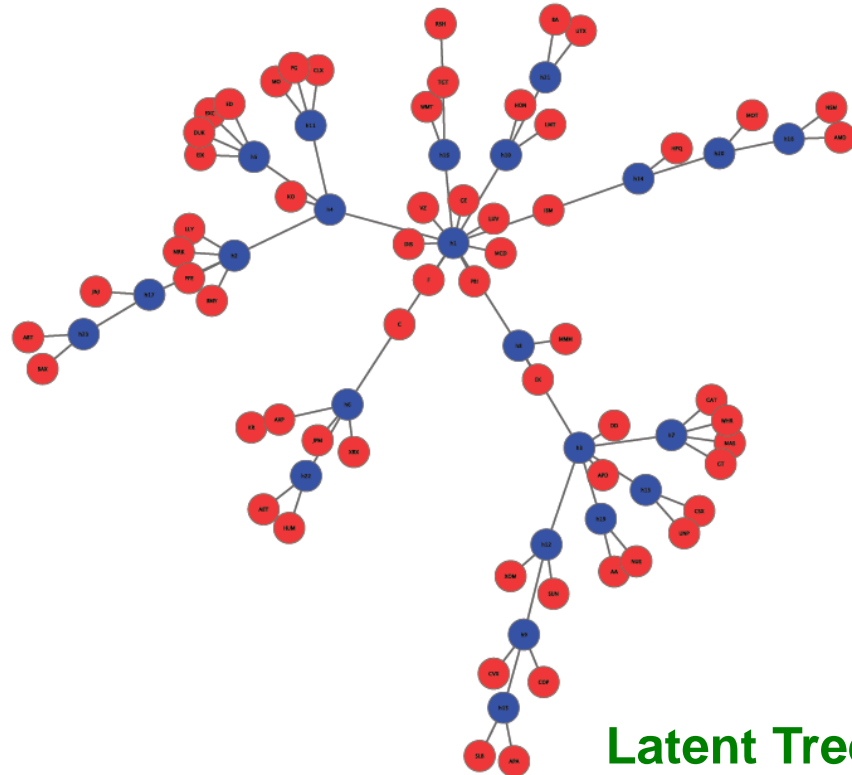
# Stock Data Experiment

Acquired closing prices for 59 stocks from 1984 to 2011. Goal is to condition on a few stocks and see how well they predict another stock.

Latent tree structure learned using algorithm of Choi et al. 2010

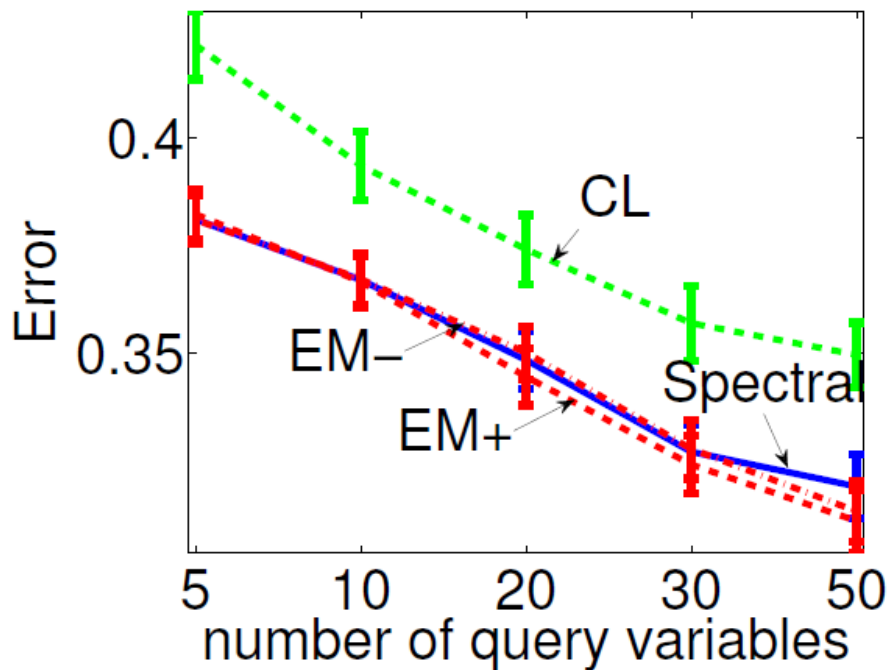


# Chow Liu Tree



# Latent Tree

# Stock Data Results



**Spectral**

**EM**

**Chow Liu**

All the approaches that use the estimated latent tree perform better than message passing on the fully observable estimated Chow Liu tree.

# Conclusion

- Latent trees are a **powerful** as well as **tractable** way to model relationships among variables
- Our spectral algorithm presents a fast, consistent, and local-minima-free approach for parameter learning/inference in latent trees.
- Future directions include spectral algorithms for loopy graphs and kernelized spectral algorithms.