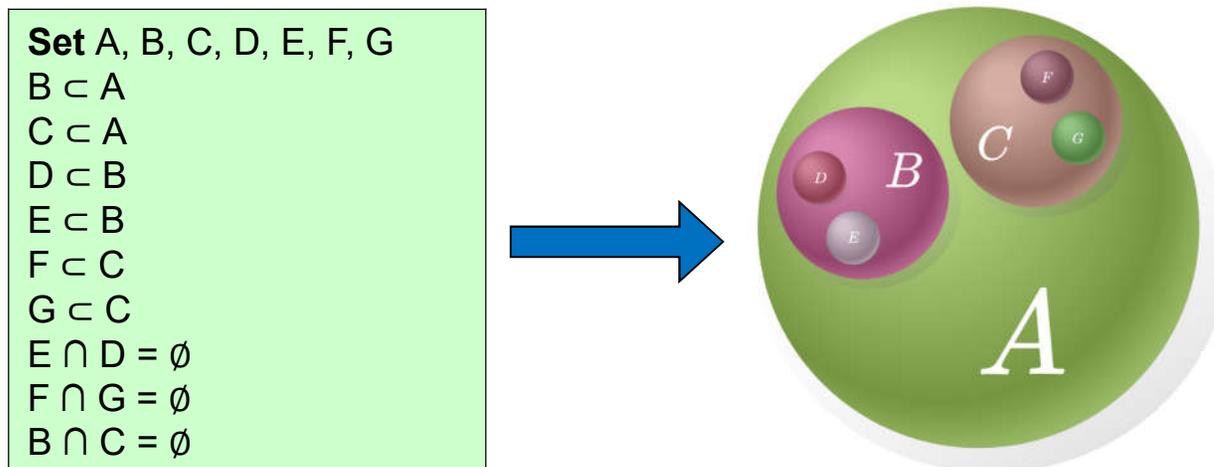


# Penrose: From Mathematical Notation to Beautiful Diagrams

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Joint work with Katherine Ye, Wode Ni, Max Krieger, Dor Ma'ayan, Jenna Wise, Yumeng Du, Lily Shellhammer, Joshua Sunshine, and Keenan Crane



# Diagrams are useful, but too rare

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- Diagrams are useful...
  - Diagrams help in solving math problems [Larkin&Simon]
  - High-impact papers have many figures [Lee et al.]
- But rare: just 39% of arXiv math papers contain diagrams
  - And even those contain only 1 figure for every 10 pages

“People have very powerful facilities for taking in information visually... On the other hand, they do not have a good built-in facility for turning an internal spatial understanding back into a two-dimensional image. [So] mathematicians usually have fewer and poorer figures in their papers and books than in their heads.”

- Fields medalist William Thurston

# The Penrose Vision

You write this:

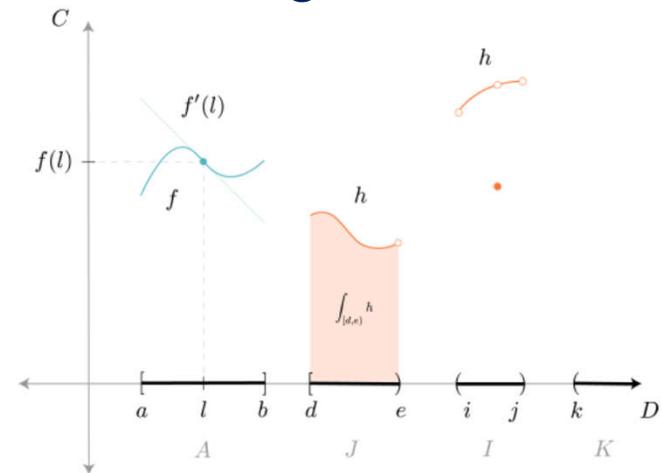
$a, b, d, e, i, j, k, \text{inf} \in \mathbb{R}$   
 $b$  **IsLessThan**  $k$   
 $A := [a, b] \subseteq \mathbb{R}$   
 $J := [d, e) \subseteq \mathbb{R}$   
 $I := (i, j) \subseteq \mathbb{R}$   
 $K := (k, \text{inf}) \subseteq \mathbb{R}$

$f : A \rightarrow \mathbb{R}$   
 $f$  **IsDifferentiable**

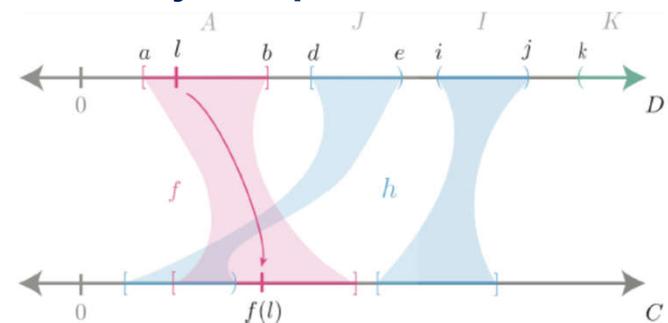
$U := (J \cup I) \subseteq \mathbb{R}$   
 $h : U \rightarrow \mathbb{R}$   
 $h$  **IsDiscontinuous**

$l \in A$   
 $p2 := \mathbf{Pt}(l, f(l))$   
 $df1 := f'(l)$   
 $ih := \int_J h$

Penrose generates this:



Or, if you prefer, this:



# Penrose in Action

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- Linear algebra – simple intro
- Linear algebra – sugar and direct manipulation
- SIGGRAPH teaser video

# Can we create a LaTeX for Diagrams?

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## LaTeX

- Describe document content (.tex) separate from layout
- Extensible formatting styles (.sty)
- Extensible with new document structuring concepts (macros)
- Optimizes (mostly textual) layout of documents

## Penrose

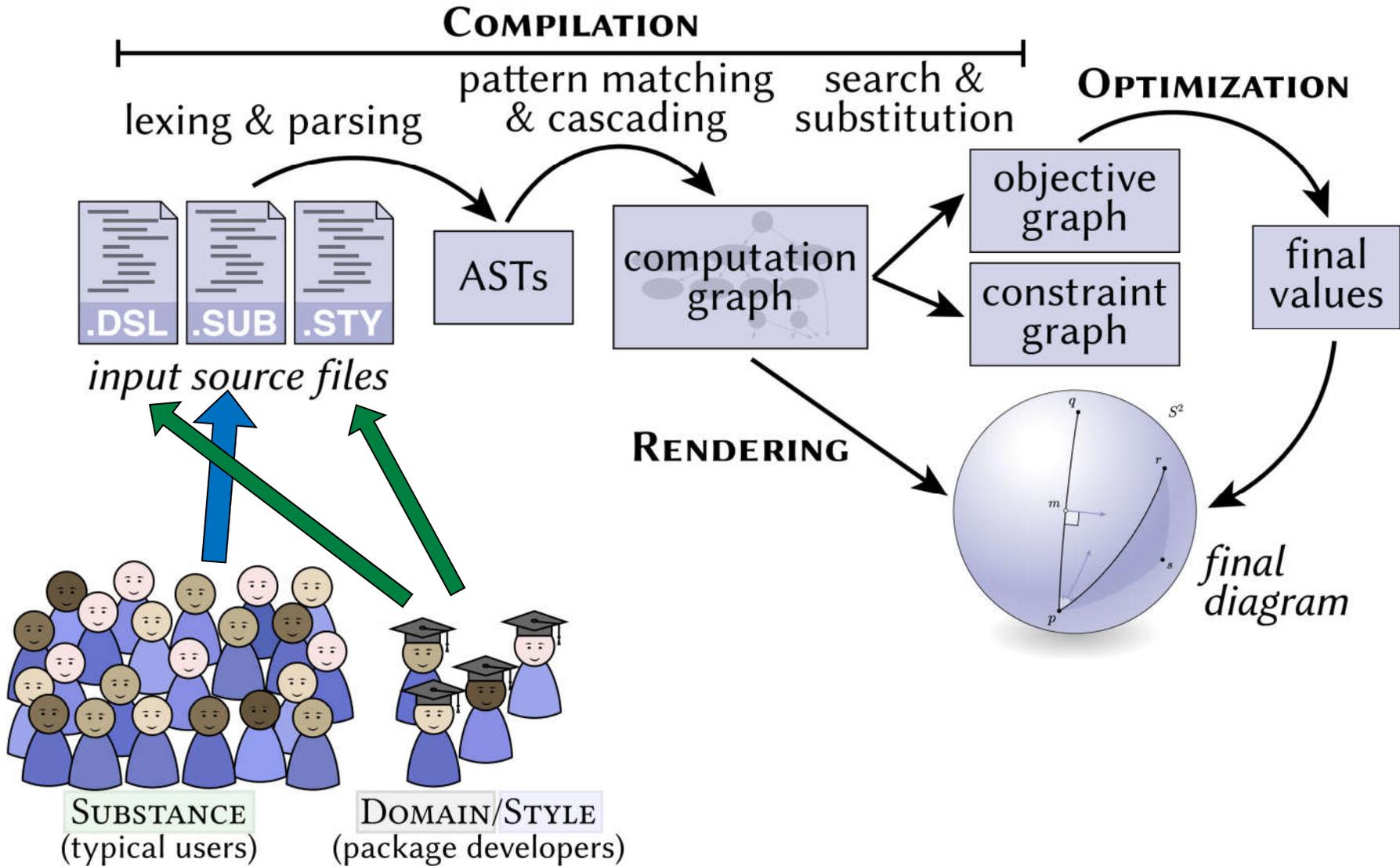
- Describe mathematical content (Substance) separate from visual representation
- Extensible rendering (Style)
- Extensible with new math domains (Domain)
- Optimizes (graphical) layout of diagrams

# Existing tools are inadequate

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- Graphing calculators (e.g. Wolfram Alpha)
  - Visualize concrete data or functions
  - Don't understand, can't visualize mathematical abstractions
- Drawing tools (e.g. Adobe Illustrator, TikZ)
  - Require laborious specification of low-level details
  - Don't understand semantics
- Domain-specific visualizations (e.g. Group Explorer)
  - Work well for a particular domain, but are not extensible

# The Penrose Architecture and Users



# Anatomy of a Substance Program

Object  $U$  of type  
`VectorSpace`

`VectorSpace`  $U$

`Vector`  $u_1, u_2, u_3, u_4, u_5 \in U$

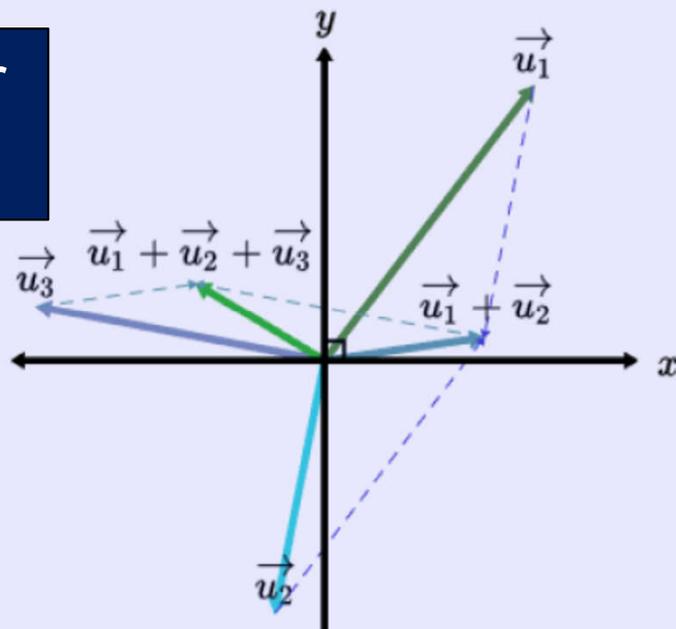
$u_3 := u_1 + u_2$

$u_5 := u_3 + u_4$

Syntactic sugar  
declares variables  
and relationships  
 $In(u_i, U)$  for each  $u_i$

Syntactic sugar for  
 $AddV(u_3, u_4)$

Declares that  $u_5$  is  
equal to  $AddV(u_3, u_4)$



# The Domain Language

type Vector

Declares type VectorSpace. Constructors may eventually have arguments.

type VectorSpace

Declares a predicate and its type

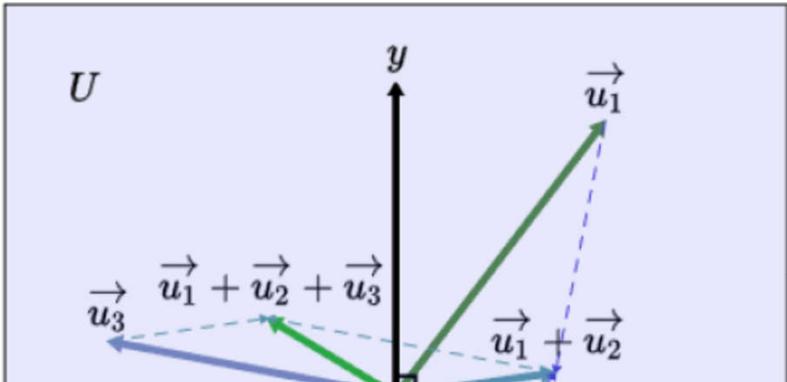
predicate In: Vector \* VectorSpace V

function addV: Vector \* Vector -> Vector

Declares an operator and its type

notation " $v1 + v2$ " ~ " $addV(v1, v2)$ "

notation " $Vector\ a \in U$ " ~ " $Vector\ a; In(a, U)$ "



Declares syntactic sugar

# Substance and Domain Design Features

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- Separate, reusable domain extensions
  - New types, predicates, operators
  - New domain-specific notation
    - Similar to Coq notation extension
- Generic, typed object model
  - Check that substance programs are well-formed
  - Match on types in style programs

# The Style Language

```
Vector v
with VectorSpace U
where v ∈ U {
  v.shape = Arrow {
    start = U.shape.center
  }

  encourage nearHead(v.shape, v.text)
  ensure contains(U.shape, v.shape)
}
```

Match once per Vector; call it v

For each v there must be at least one U

And  $\text{In}(v, U)$  must hold

```
Vector u
with Vector v, w; VectorSpace U
where u := v + w; u, v, w ∈ U {
  u.shape.end = v.shape.end + w.shape.end

  u.slider_v = Arrow {
    start = w.shape.end
    end = u.shape.end
    style = "dashed"
  }

  u.slider_w = Arrow { ... }
}
```

# The Style Language

```
Vector v
with VectorSpace U
where v ∈ U {
  v.shape = Arrow {
    start = U.shape.center
  }

  encourage nearHead(v.shape, v.text)
  ensure contains(U.shape, v.shape)
}
```

For each match create an Arrow graphical object. Attach it to the shape field of v.

Set a feature of v.shape  
The runtime can optimize other features

```
Vector u
with Vector v, w; VectorSpace U
where u := v + w; u, v, w ∈ U {
  u.shape.end = v.shape.end + w.shape.end
```

**encourage** contributes to objective function. **ensure** is a constraint.

```
  u.slider_v = Arrow {
    start = w.shape.end
    end = u.shape.end
    style = "dashed"
  }
```

Refines a shape created earlier

```
  u.slider_w = Arrow { ... }
}
```

Creates more shapes for vectors when there is predicate relating them to other vectors

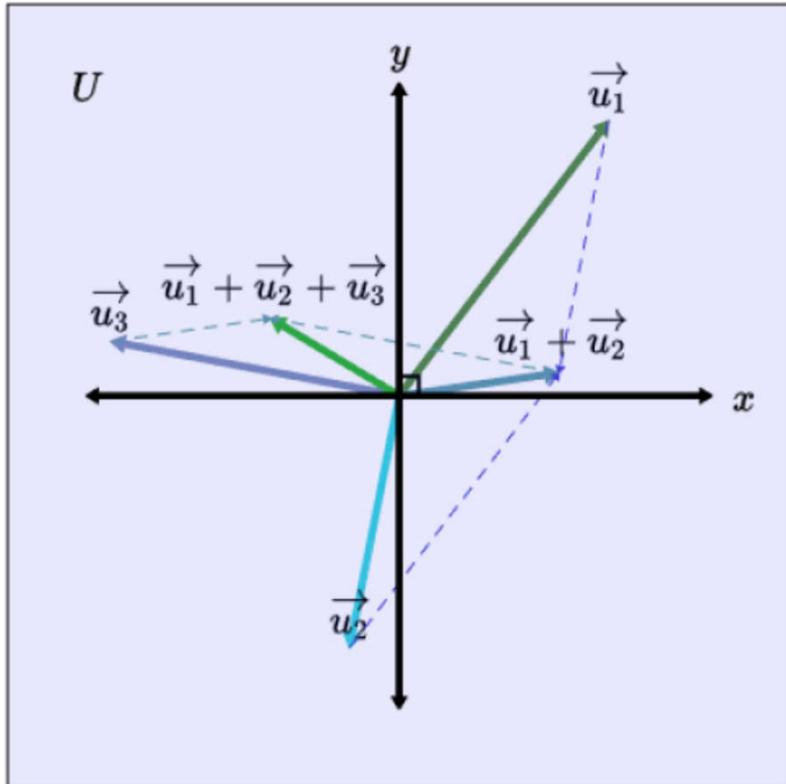
# Substance, Style, and Output

**VectorSpace**  $U$

**Vector**  $u_1, u_2, u_3, u_4, u_5 \in U$

$u_4 := u_1 + u_2$

$u_5 := u_4 + u_3$



**Vector**  $v$

**with** **VectorSpace**  $U$

**where**  $v \in U$  {

```
v.shape = Arrow {  
  start = U.shape.center  
}
```

```
encourage nearHead(v.shape, v.text)  
ensure contains(U.shape, v.shape)
```

}

**Vector**  $u$

**with** **Vector**  $v, w$ ; **VectorSpace**  $U$

**where**  $u := v + w$ ;  $u, v, w \in U$  {

```
u.shape.end = v.shape.end + w.shape.end
```

```
u.slider_v = Arrow {  
  start = w.shape.end  
  end = u.shape.end  
  style = "dashed"  
}
```

}

```
u.slider_w = Arrow { ... }
```

}

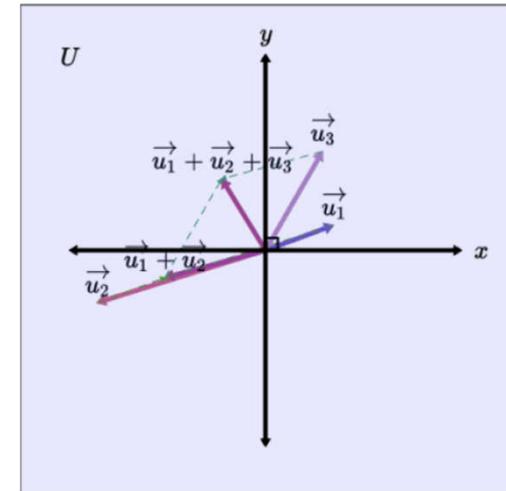
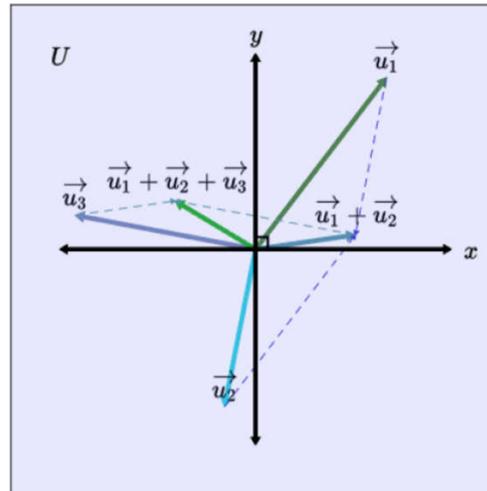
# Style Design Characteristics

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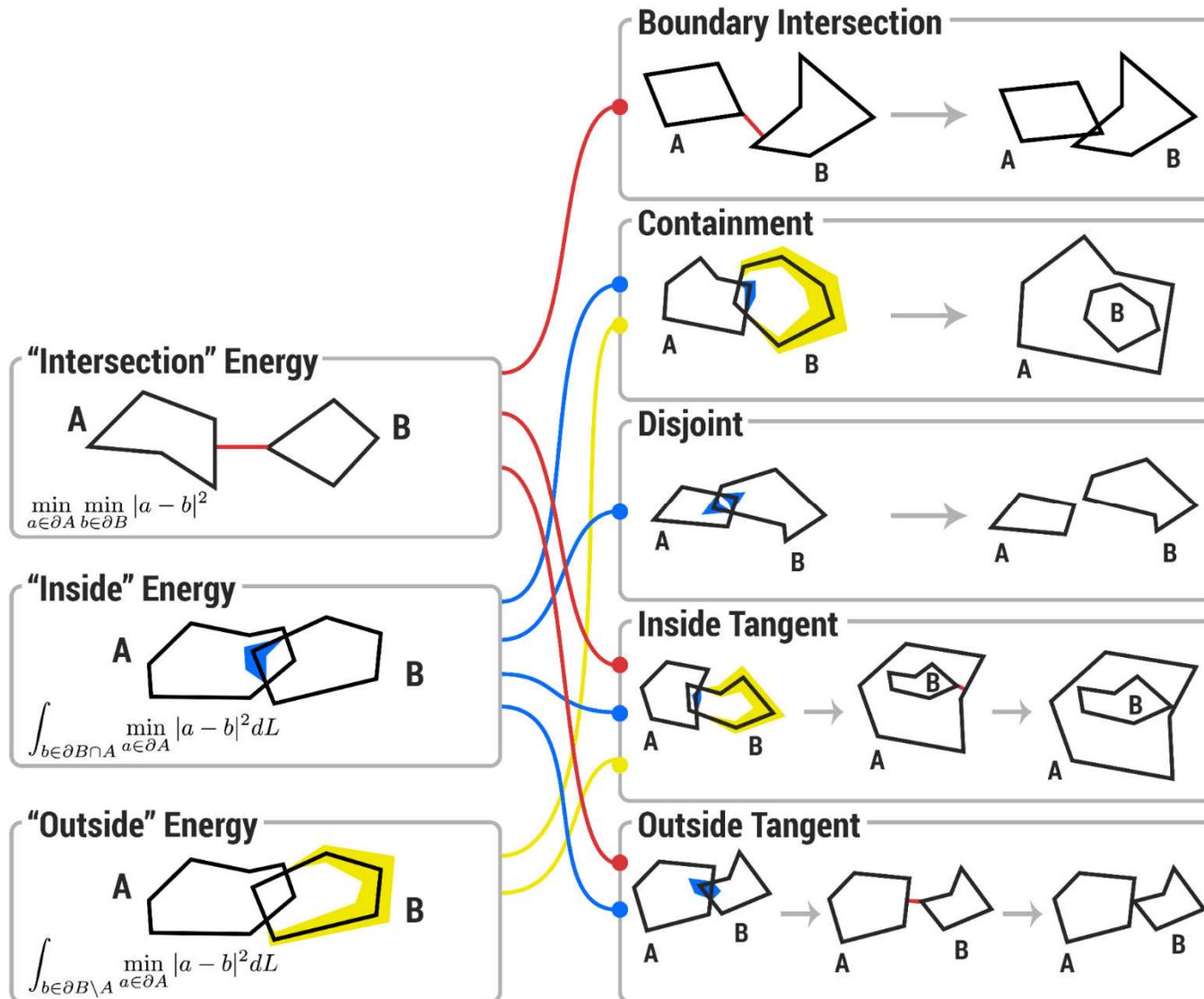
- Extensible and reusable
  - Many styles per domain
  - Use different styles with the same substance program
  - Typical end-users need not understand style programs
    - But expert users can edit them or write new ones if they want to
- Provides a *visual semantics* for substance programs
  - Pattern matches over logical objects, generates graphical objects
  - Generates objectives and constraints for later optimization
  - Later matches can refine the semantics provided by earlier ones

# Optimization

- Basically hill-climbing to solve constraints and maximize objectives
- All Penrose functions are end-to-end differentiable
  - Can take the derivative and modify the input(s) in the direction(s) that improve the composite objective function
- Can run multiple times  
→ multiple diagrams



# Mathematics Underlying the Constraints



# Euclidean Geometry

---

**Point** p, q, r, s

**Segment** a := p, q

**Segment** b := p, r

**Point** m := **Midpoint**(a)

**Angle** theta :=  $\angle(q, p, r)$

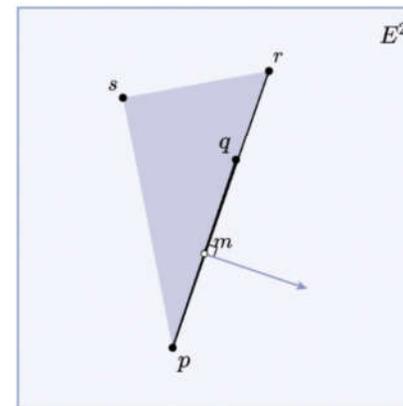
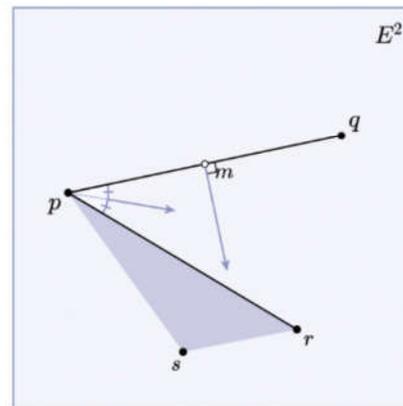
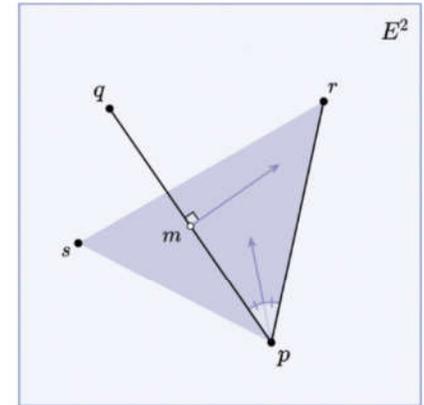
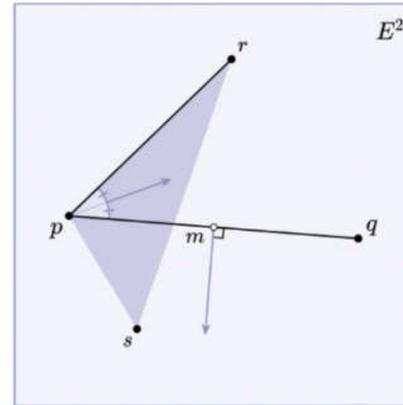
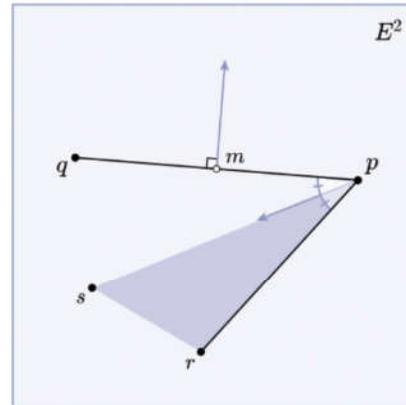
**Triangle** t := p, r, s

**Ray** w := **Bisector**(theta)

**Ray** h := **PerpendicularBisector**(a)

How do these relationships look if we assume that two parallel lines never meet?

# Euclidean Geometry



**Point**  $p, q, r, s$   
**Segment**  $a := p, q$   
**Segment**  $b := p, r$   
**Point**  $m := \text{Midpoint}(a)$   
**Angle**  $\theta := \angle(q, p, r)$   
**Triangle**  $t := p, r, s$   
**Ray**  $w := \text{Bisector}(\theta)$   
**Ray**  $h := \text{PerpendicularBisector}(a)$

drawn in euclidean geometry  
(assuming parallel postulate)

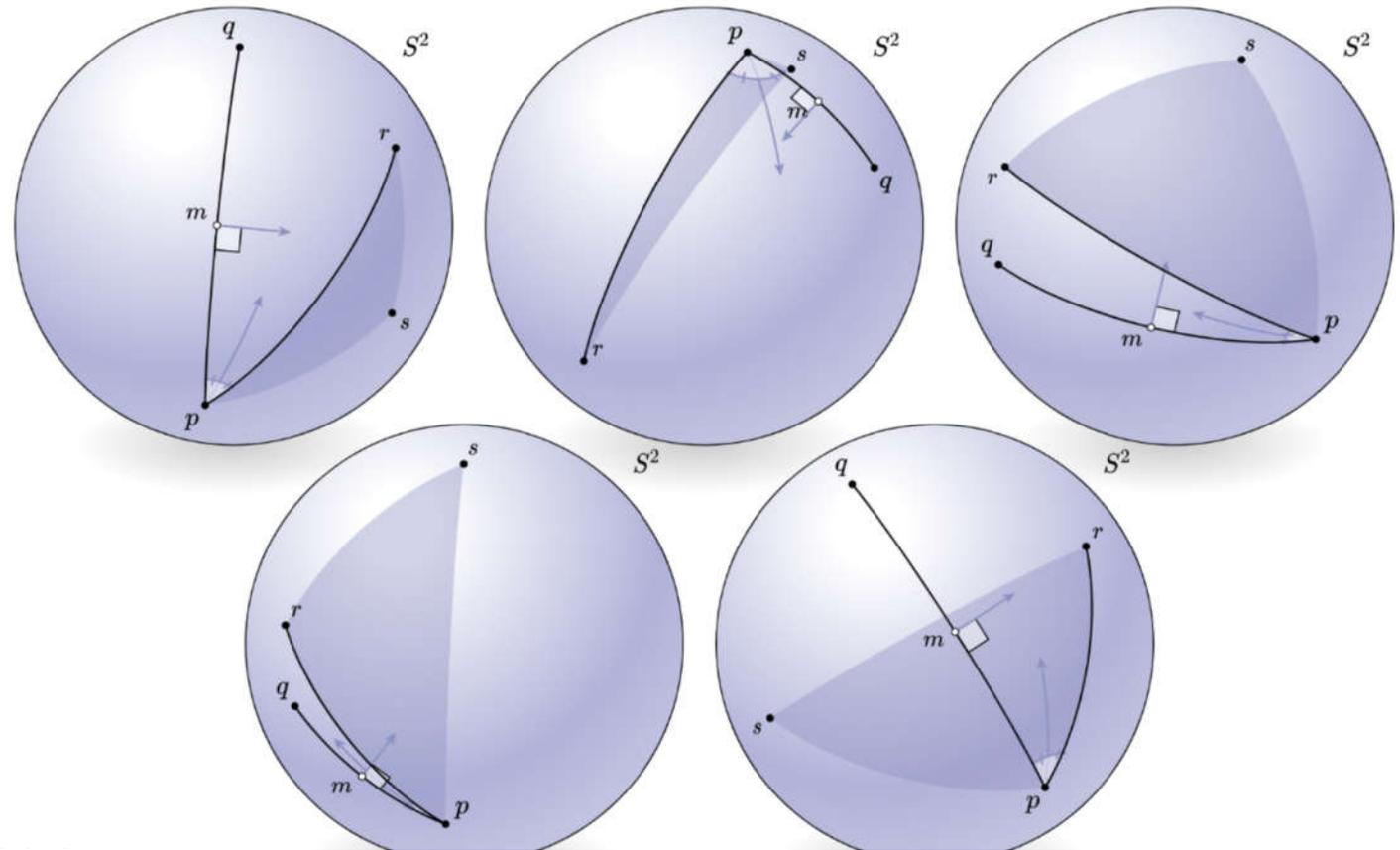
# Non-Euclidean Geometry

---

**Point** p, q, r, s  
**Segment** a := p, q  
**Segment** b := p, r  
**Point** m := **Midpoint**(a)  
**Angle** theta :=  $\angle(q, p, r)$   
**Triangle** t := p, r, s  
**Ray** w := **Bisector**(theta)  
**Ray** h := **PerpendicularBisector**(a)

What if the parallel postulate  
doesn't hold?  
How would we visualize these  
relationships on, say, a sphere?

# Non-Euclidean Geometry

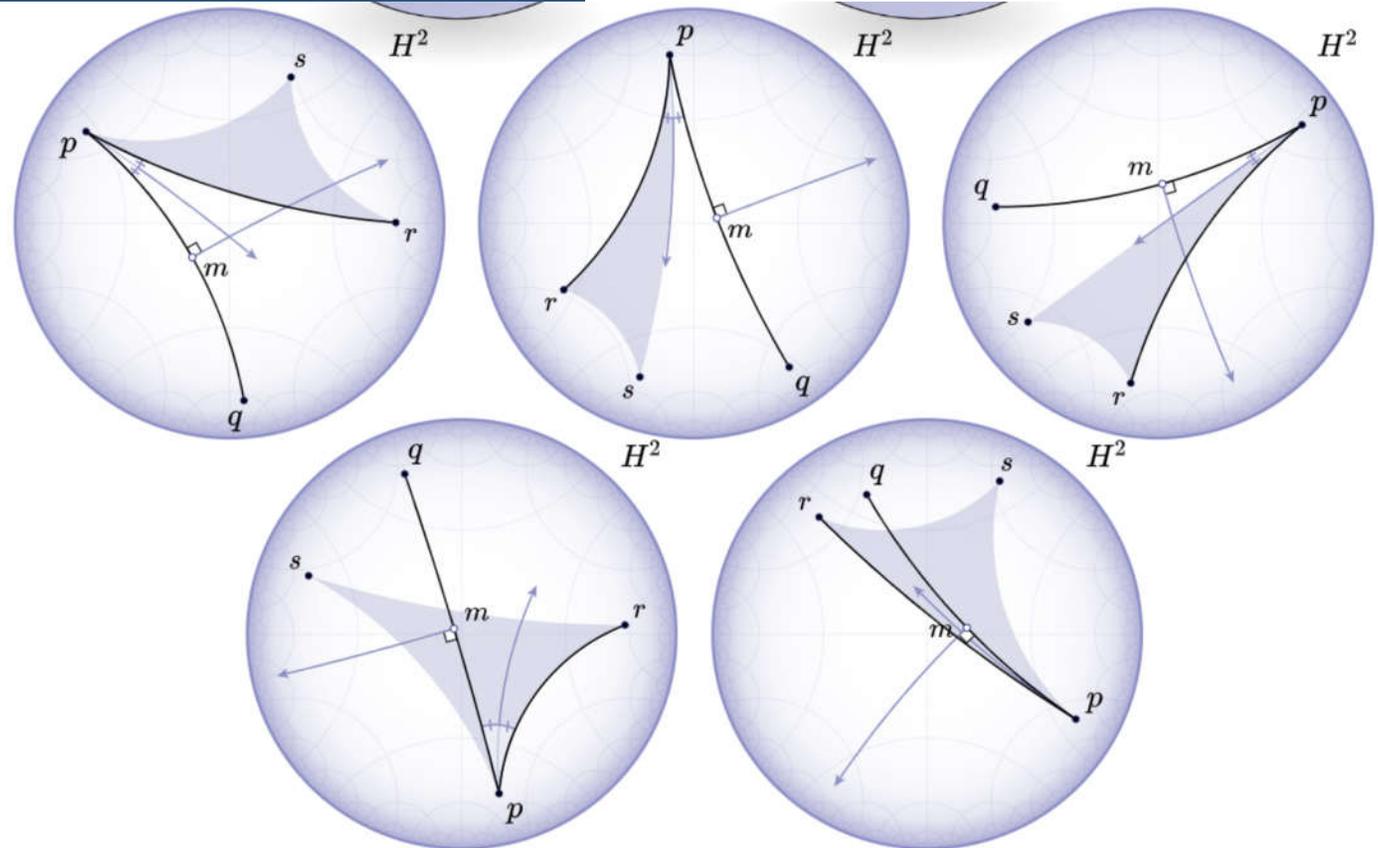


Point  $p, q, r, s$   
Segment  $a := p, q$   
Segment  $b := p, r$   
Point  $m := \text{Midpoint}(a)$   
Angle  $\theta := \angle(q, p, r)$   
Triangle  $t := p, r, s$   
Ray  $w := \text{Bisector}(\theta)$   
Ray  $h := \text{PerpendicularBisector}(a)$

(different samples of the same Substance program, not a rotated sphere of the same diagram)

here's the [style program](#)

# Non-Euclidean Geometry



Point  $p, q, r, s$   
Segment  $a := p, q$   
Segment  $b := p, r$   
Point  $m := \text{Midpoint}(a)$   
Angle  $\theta := \angle(q, p, r)$   
Triangle  $t := p, r, s$   
Ray  $w := \text{Bisector}(\theta)$   
Ray  $h := \text{PerpendicularBisector}(a)$

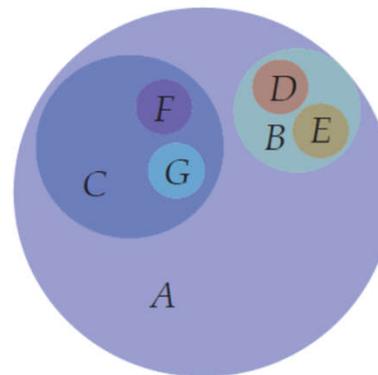
(different samples of the same Substance program)

# More Penrose Demonstrations

- Set theory
  - tree style
  - Venn style
- Real analysis
  - parallel axis style
  - perpendicular axis style
- Any live requests?
  - Set theory
  - Linear algebra
  - Real analysis

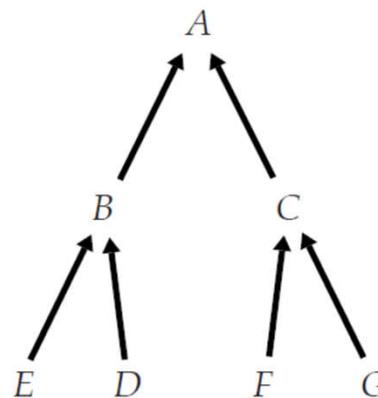
```

Set A, B, C, D, E, F, G
Subset B A
Subset C A
Subset D B
Subset E B
Subset F C
Subset G C
NoIntersect E D
NoIntersect F G
NoIntersect B C
    
```



```

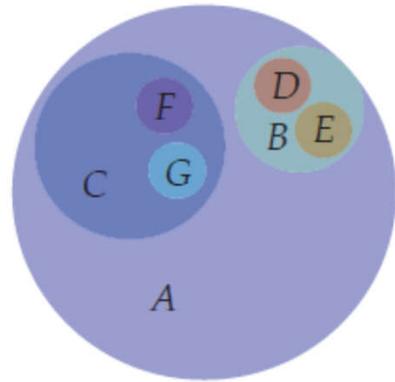
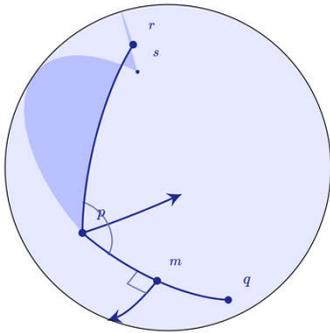
Set x {
  shape = Circle { }
  ensure x contains x.label
}
NoIntersect x y {
  ensure x notOverlap y
}
Subset x y {
  ensure y contains x
  ensure x smallerThan y
  ensure y.label outside x
}
    
```



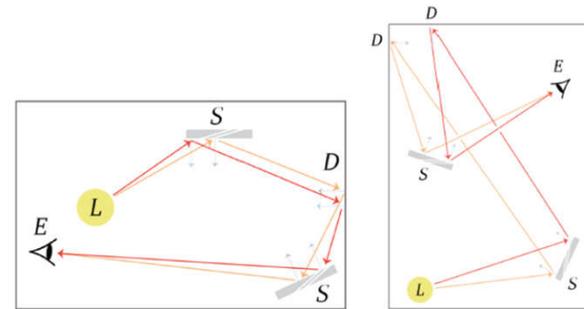
```

Set x { shape = Text{ } }
Subset x y {
  encourage y above x
  encourage x sameX y
  shape = Arrow {
    start = x.shape
    end = y.shape
  }
}
Set x, Set y {
  encourage x repel y
}
    
```

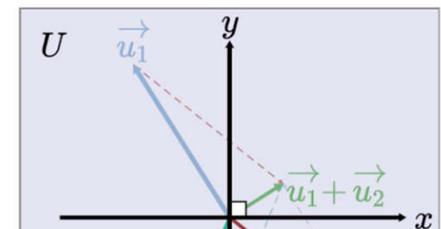
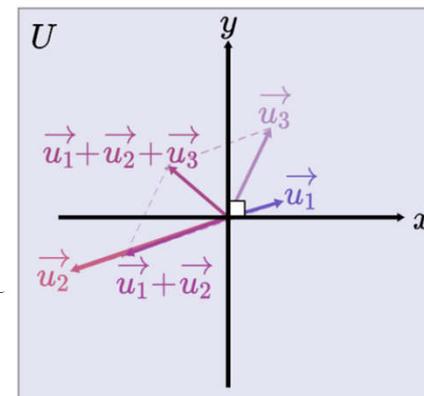
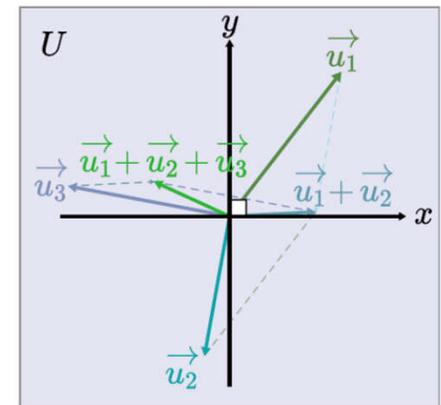
# Penrose: customizable visual semantics for concept-level expressions in an extensible set of domains



```
-- regex for a caustic
pathType = [L, S, D, S, E]
path1 = sample(pathType)
path2 = sample(pathType)
```

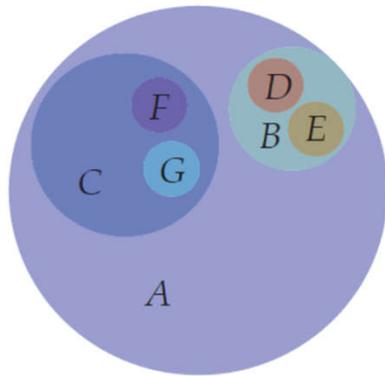


**VectorSpace**  $U$   
**Vector**  $u_1, u_2, u_3,$   
 $u_4, u_5 \in U$   
 $u_3 := u_1 + u_2$   
 $u_5 := u_3 + u_4$

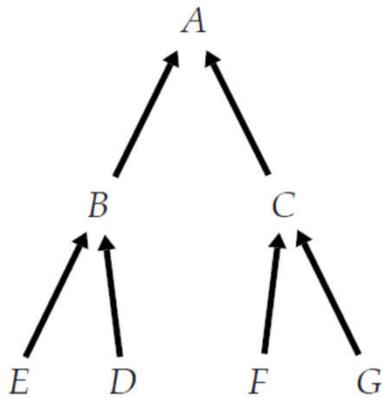


# More examples

```
Set A, B, C, D, E, F, G
Subset B A
Subset C A
Subset D B
Subset E B
Subset F C
Subset G C
NoIntersect E D
NoIntersect F G
NoIntersect B C
```



```
Set x {
  shape = Circle { }
  ensure x contains x.label
}
NoIntersect x y {
  ensure x notOverlap y
}
Subset x y {
  ensure y contains x
  ensure x smallerThan y
  ensure y.label outside x
}
```



```
Set x { shape = Text{ } }
Subset x y {
  encourage y above x
  encourage x sameX y
  shape = Arrow {
    start = x.shape
    end = y.shape
  }
}
Set x, Set y {
  encourage x repel y
}
```