Andrea Bajcsy

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I am an Assistant Professor in the Robotics Institute at Carnegie Mellon University. I work at the intersection of robotics, machine learning, control theory, and human-AI interaction. I'm particularly interested in developing theory and algorithms towards "open world" robot safety, leveraging both decision-theoretic (e.g., robust control) and statistical (e.g., uncertainty quantification) methods. I ground my work through systems such as robotic manipulators, aerial vehicles, quadrupeds, and autonomous cars.

Current Position

Assistant Professor **September 2023 - *present***
Robotics Institute, Carnegie Mellon University
Director, Interactive and Trustworthy Robotics Laboratory

Education

University of California, Berkeley **2022**
Ph.D. in Electrical Engineering and Computer Science
Advisors: Anca D. Dragan & Claire J. Tomlin
Thesis: *Bridging Safety and Learning in Human-Robot Interaction*

University of Maryland, College Park **2016**
B.S. in Computer Science, Minor in Mathematics

Past Positions

Postdoctoral Scholar **August 2022 - July 2023**
with Jitendra Malik, University of California, Berkeley

Research Intern **Spring 2021**
NVIDIA Research, Autonomous Vehicles Research Group

Research Intern **Summer 2016**
Max Planck Institute for Intelligent Systems, Autonomous Motion Group

Awards & Honors

DARPA Young Faculty Award 2025
For *"Unifying Uncertainty & Safety for Embodied AI Agents"*

NSF CAREER Award 2025
For *"Formalizing Open World Safety for Interactive Robotics"*

Google Research Scholar Award 2024
For *"In-the-Wild Robot Behavior Alignment from Human Preferences"*

Rising Stars Academic Career Workshop in EECS 2021
Awarded to 40 EECS graduate and postdoctoral women.

Honorable Mention for the 2020 IEEE T-RO Best Paper Award 2020

Robotics: Science and Systems (RSS) Pioneers 2020
Awarded to 30 early career researchers around the world in robotics.

National Science Foundation Graduate Research Fellowship 2016

Berkeley EECS Excellence Award 2016

Student Researchers of the Year Award 2016
Awarded to 5 undergraduates, University of Maryland.

CRA Undergraduate Research Award Honorable Mention 2016
Recognizes undergraduates in North American universities who show outstanding research potential in an area of computing research.

Brendan Iribe Scholar 2015
Awarded yearly to 1 computer science undergraduate, University of Maryland.

Pre-Prints

[P6] **Reimagination with Test-time Observation Interventions: Distractor-Robust World Model Predictions**.
Y. Chen, J. Wei, C. Xu, B. Li, M. Tomizuka, A. Bajcsy, R. Tian.
International Conference on Robotics and Automation (ICRA), 2025
(in preparation).

[P5] **Vision-Language Guided Safe Dynamic Manipulation via Object-Centric Transformers**.
S. Saxena, O. Kroemer, A. Bajcsy.
International Conference on Robotics and Automation (ICRA), 2025
(in preparation).

[P4] **A Unified Framework for Robots that Influence Humans over Long-Term Interaction**.
S. Sagheb, S. Parekh, R. Pandya, Y. Mun, K. Driggs-Campbell, A. Bajcsy, D.P. Losey.
International Journal of Robotics Research (IJRR), 2025
(under review).

[P3] **Maximizing Alignment with Minimal Feedback: Efficiently Learning Rewards for Visuomotor Robot Policy Alignment**.
R. Tian, Y. Wu. C. Xu, M. Tomizuka, J. Malik, A. Bajcsy.
International Journal of Robotics Research (IJRR), 2025
(under review).

[P2] **Human–AI Safety: A Descendant of Generative AI and Control Systems Safety**.
A. Bajcsy and J. Fisac
arXiv, 2024.

[P1] **Towards the Unification and Data-Driven Synthesis of Autonomous Vehicle Safety Concepts**.
K. Leung*, A. Bajcsy*, E. Schmerling, M. Pavone.
arXiv, 2022.

Conference Publications

[C31] **Uncertainty-aware Latent Safety Filters for Avoiding Out-of-Distribution Failures**.
J. Seo, K. Nakamura, A. Bajcsy.
Conference on Robot Learning (CoRL), 2025.

[C30] **Adapting by Analogy: OOD Generalization of Visuomotor Policies via Functional Correspondence**.
P. Gupta, H. Admoni, A. Bajcsy.
Conference on Robot Learning (CoRL), 2025.

[C29] **Robots that Suggest Safe Alternatives**.
H.J. Jeong, R. Chen, and A. Bajcsy.
International Conference on Intelligent Robots and Systems (IROS), 2025.

[C28] **Your Learned Constraint is Secretly a Backwards Reachable Tube**.
M. Qadri, G. Swamy, J. Francis, M. Kaess, A. Bajcsy.
Reinforcement Learning Conference (RLC), 2025.

[C27] **Generalizing Safety Beyond Collision-Avoidance via Latent-Space Reachability Analysis**.
K. Nakamura, L. Peters, A. Bajcsy.
Robotics: Science and Systems (RSS), 2025.

[C26] **From Foresight to Forethought: VLM-In-the-Loop Policy Steering via Latent Alignment**.
Y. Wu, R. Tian, G. Swamy, A. Bajcsy.
Robotics: Science and Systems (RSS), 2025.
(Outstanding paper award at ICLR 2025 Workshop on World Models)

[C25] **Updating Robot Safety Representations Online from Natural Language Feedback**.
L. Santos*, Z. Li*, L. Peters, S. Bansal†, A. Bajcsy†.
International Conference on Robotics and Automation (ICRA), 2025.

[C24] **Robots that Learn to Safely Influence via Prediction-Informed Reach-Avoid Dynamic Games**.
R. Pandya, C. Liu, A. Bajcsy.
International Conference on Robotics and Automation (ICRA), 2025.

[C23] **Conformalized Interactive Imitation Learning: Handling Expert Shift & Intermittent Feedback**.
M. Zhao, R. Simmons, H. Admoni, A. Ramdas*, A. Bajcsy*.
International Conference on Learning Representations (ICLR), 2025.

[C22] **Agent-to-Sim: Learning Interactive Behavior Models from Casual Longitudinal Videos**.
G. Yang, A. Bajcsy, S. Saito*, A. Kanazawa*.
International Conference on Learning Representations (ICLR), 2025.

[C21] **Not All Errors Are Made Equal: A Regret Metric for Detecting System-Level Trajectory Prediction Failures**.
K. Nakamura, R. Tian, A. Bajcsy.
Conference on Robot Learning (CoRL), 2024.

[C20] **Adaptive Human Trajectory Prediction via Latent Corridors**.
N. Thakkar, K. Mangalam, A. Bajcsy, J. Malik
European Conference on Computer Vision (ECCV), 2024.

[C19] **Conformalized Teleoperation: Confidently Mapping Human Inputs to High-Dimensional Robot Actions**.
M. Zhao, R. Simmons, H. Admoni, A. Bajcsy.
Robotics: Science & Systems (RSS), 2024.

[C18] **Conformal Decision Theory: Safe Autonomous Decisions Without Distributions**.
J. Lekeufack*, A.N. Angelopoulos*, A. Bajcsy*, M.I. Jordan, J. Malik.
International Conference on Robotics and Automation (ICRA), 2024.

[C17] **Learning Vision-Based Pursuit-Evasion Robot Policies.**
A. Bajcsy*, A. Loquercio*, A. Kumar, J. Malik.
International Conference on Robotics and Automation (ICRA), 2024.

[C16] **What Matters to *You*? Towards Visual Representation Alignment for Robot Learning**.
R. Tian, C. Xu, M. Tomizuka, J. Malik, A. Bajcsy.
International Conference on Learning Representations (ICLR), 2024.

[C15] **Deception Game: Closing the Safety-Learning Loop in Interactive Robot Autonomy.**
H. Hu*, Z. Zhang*, K. Nakamura, A. Bajcsy, J.F. Fisac.
Conference on Robot Learning (CoRL), 2023.

[C14] **Towards Modeling and Influencing the Dynamics of Human Learning.**
R. Tian, M. Tomizuka, A.D. Dragan, A. Bajcsy.
International Conference on Human-Robot Interaction (HRI), 2023.

[C13] **Towards Robots that Influence Humans over Long-Term Interaction**.
S. Sagheb, Y. Mun, N. Ahmadian, B.A. Christie, A. Bajcsy, K. Driggs-Campbell, D.P. Losey.
International Conference on Robotics and Automation (ICRA), 2023.

[C12] **Safety Assurances for Human-Robot Interaction via Confidence-aware Game-theoretic Human Models.**
R. Tian*, L. Sun*, A. Bajcsy*, M. Tomizuka, A.D. Dragan.
International Conference on Robotics and Automation (ICRA), 2022.

[C11] **Analyzing Human Models that Adapt Online.**
A. Bajcsy, A. Siththaranjan, C.J. Tomlin, A.D. Dragan.
International Conference on Robotics and Automation (ICRA), 2021.

[C10] **A Hamilton-Jacobi Reachability-Based Framework for Predicting and Analyzing Human Motion for Safe Planning**.
S. Bansal*, A. Bajcsy*, E. Ratner*, A.D. Dragan, C.J. Tomlin.
International Conference on Robotics and Automation (ICRA), 2020.

[C9] **An Efficient Reachability-Based Framework for Provably Safe Autonomous Navigation in Unknown Environments**.
A. Bajcsy*, S. Bansal*, E. Bronstein, V. Tolani, C.J. Tomlin.
Conference on Decision and Control (CDC), 2019.

[C8] **A Scalable Framework For Real-Time Multi-Robot, Multi-Human Collision Avoidance**.
A. Bajcsy*, S.L. Herbert*, D. Fridovich-Keil, J.F. Fisac, S. Deglurkar, A.D. Dragan, C.J. Tomlin.
International Conference on Robotics and Automation (ICRA), 2019.

[C7] **Learning Under Misspecified Objective Spaces**.
A. Bobu, A. Bajcsy, J.F. Fisac, A.D. Dragan.
Conference on Robot Learning (CoRL), 2018.
(invited to special issue)

[C6] **Probabilistically Safe Robot Planning with Confidence-Based Human Predictions**.
J.F. Fisac*, A. Bajcsy*, S.L. Herbert, D. Fridovich-Keil, S. Wang, C.J. Tomlin, A.D. Dragan.
Robotics: Science and Systems (RSS), 2018.
(invited to special issue)

[C5] **Learning from Physical Human Corrections, One Feature at a Time**.
A. Bajcsy, D.P. Losey, M.K. O'Malley, A.D. Dragan.
International Conference on Human-Robot Interaction (HRI), 2018.

[C4] **Learning Robot Objectives from Physical Human Robot Interaction**.
A. Bajcsy*, D.P. Losey*, M.K. O'Malley, A.D. Dragan.
Conference on Robot Learning (CoRL), 2017.
(oral, acceptance rate 10%)

[C3] **A Review of Principles in Design and Usability Testing of Tactile Technology for Individuals with Visual Impairments**.
E.L. Horton, R. Renganathan, B.N. Toth, A.J. Cohen, A.V. Bajcsy, A. Bateman, M.C. Jennings, A. Khattar, R.S. Kuo, F.A. Lee, M.K. Lim, L.W, Migasiuk, A. Zhang, O.K. Zhao, M.A. Oliveira.
Assistive Technology, 2016.

[C2] **Systematic Measurement of Marginal Mark Types on Voting Ballots**.
A. Bajcsy, Y.S. Li-Baboud, M. Brady.
NIST IR 8069, 2015.

[C1] **Depicting Web Images for the Blind and Visually Impaired**.
A. Bajcsy, Y.S. Li-Baboud, M. Brady.
SPIE Newsroom, 2013.

Journal Articles

[J9] **Intent Demonstration in General-Sum Dynamic Games via Iterative Linear-Quadratic Approximations**.
J. Li, A. Siththaranjan, S. Sojoudi, C. Tomlin, A. Bajcsy.
IEEE Transactions on Control Systems Technology (TCST), 2025.

[J8] **Contingency Games for Multi-Agent Interaction**.
L. Peters, A. Bajcsy, C.Y Chiu, D. Fridovich-Keil, F. Laine, L. Ferranti, J. Alonso-Mora.
Robotics and Automation Letters (RA-L), 2024.
(Finalist for the 2024 Best Paper Award of the IEEE RAS Technical Committee on Robot Control)

[J7] **StROL: Stabilized and Robust Online Learning from Humans.**
S.A. Mehta, F. Meng, A. Bajcsy, D.P. Losey
Robotics and Automation Letters (RA-L), 2024.

[J6] **Physical Interaction as Communication: Learning Robot Objectives Online from Human Corrections**.
D.P. Losey, A. Bajcsy, M.K. O'Malley, A.D. Dragan.
International Journal of Robotics Research (IJRR), 2021.

[J5] **Efficient Dynamics Estimation with Adaptive Model Sets**.
E. Ratner, A. Bajcsy, C.J. Tomlin, A.D. Dragan.
IEEE Robotics and Automation Letters (RA-L), 2021.

[J4] **A Robust Control Framework for Human Motion Prediction**.
A. Bajcsy, S. Bansal, E. Ratner, C.J. Tomlin, A.D. Dragan.
IEEE Robotics and Automation Letters (RA-L), 2020.

[J3] **Quantifying Hypothesis Space Misspecification in Learning from Human-Robot Demonstrations and Physical Corrections.**
A. Bobu, A. Bajcsy, J.F. Fisac, S. Deglurkar, A.D. Dragan.
IEEE Transactions on Robotics (T-RO), 2020.
(Honorable Mention for the 2020 IEEE T-RO Best Paper Award)

[J2] **Confidence-Aware Motion Prediction for Real-Time Collision Avoidance.**
D. Fridovich-Keil*, A. Bajcsy*, J.F. Fisac, S.L. Herbert, S. Wang, A.D. Dragan, C.J. Tomlin.
International Journal of Robotics Research (IJRR), 2019.

[J1] **A User-Centered Design and Analysis of an Electrostatic Haptic Touchscreen System for Students with Visual Impairments.**
A. Bateman, O. Zhao, A. Bajcsy, M. Jennings, B. Toth, A. Cohen, E. Horton, A. Khattar, R. Kuo, F. Lee, M.K. Lim, L. Migasiuk, R. Renganathan, A. Zhang, M.A. Oliveira.
International Journal of Human-Computer Studies, 2017.

Teaching

Embodied AI Safety Spring 2025
Instructor, Carnegie Mellon University.

Human–Robot Interaction Fall 2024, Fall 2025
Instructor, Carnegie Mellon University.

Models & Algorithms for Interactive Robotics Spring 2024
Instructor, Carnegie Mellon University.

Intro to Artificial Intelligence Fall 2020
Teaching Assistant, UC Berkeley.

Linear Systems Theory Fall 2019
Teaching Assistant, UC Berkeley.

Selected Invited Talks

Samsung Research America: Silicon Valley Road Trip

* equal contribution. † equal advising

Scaling Robot Safety 2025

RSS Workshop: Out-of-Distribution in Robotics
Controlling Away from OOD Failures 2025

RSS Workshop: Evaluating Robots for the Real World.
What Can Robot Safety Learn from LLM Safety? 2025

ICRA Workshop: Robot safety under "intangible" specifications.
Towards Open World Robot Safety 2025

ICRA Workshop: Human-Centered Robot Learning in the Era of Big Data and Large Models.
What Can Robot Safety Learn from LLM Safety? 2025

ICRA Workshop: Long Term Human Motion Prediction.
System-level Failures in Human Trajectory Prediction 2025

Stanford Robotics Seminar.
Towards Open World Robot Safety 2025

UC Berkeley CITRIS Autonomy Series. –""— 2025

Toyota Research Institute (TRI): Deep Dive. –""— 2025

Cornell Robotics Seminar. –""— 2025

Princeton Robotics Seminar. –""— 2024

Keynote: Brazilian Symposium on Robotics. –""— 2024

CoRL Workshop: CoRoboLearn.
Towards Human–AI Safety: Unifying Gen. AI & Control Systems Safety 2024

RSS Workshop: Semantics for Robotics. –""— 2024

RSS Workshop: Generative Modeling Meets HRI. –""— 2024

RSS Workshop: Safety & Normative Behaviors in HRI. –""– 2024

University of Utah, Robotics Seminar.
Towards Human–AI Safety 2024

Google, Deepmind. –""– 2024

Nuro, Mountain View.
Practical Safety Assurances for Dynamic Human-Robot Interactions 2022

ICML Workshop: Safe Learning for Autonomous Driving. –""– 2022

University of Illinois Champaign-Urbana, Robotics Seminar.
Bridging Safety and Learning in Human-Robot Interaction 2023

University of Wisconsin-Madison, Robotics Seminar. –""– 2023

Carnegie Mellon University, Department Seminar. –""– 2022

Northwestern University, Department Seminar. –""– 2022

Brown University, Department Seminar. –""– 2022

Georgia Tech, Department Seminar. –“”– 2022

University of Washington, Department Seminar. –“”– 2022

University of Pennsylvania, Department Seminar. –“”– 2022

Harvard University, Department Seminar. –“”– 2022

MIT, Department Seminar. –“”– 2022

UC Santa Barbara, Department Seminar. –“”– 2022

University of Michigan, Department Seminar. –“”– 2022

Cornell, Department Seminar. –“”– 2022

UC Los Angeles, Department Seminar. –“”– 2022

Caltech, Department Seminar. –“”– 2022

Berkeley Seminar on Multi-Agent Reinforcement Learning Seminar.
–“”– 2022

University of Washington, Robotics Colloquium. –“”– 2021

Stanford University, Robotics Seminar.
Introspective Human Motion Prediction for Safe Robot Autonomy 2020

ETH Zurich, Autonomy Talks.
–“”– 2020

University of Chicago Laboratory School, Innovative Robotics Symposium.
Safe Robots Which Learn From (and About) Humans 2020

Berkeley DeepDrive.
A Robust Control Framework for Human Motion Prediction 2020

Northwestern University, Robotics Seminar.
Confidence-Aware Motion Prediction for Real-time Collision Avoidance 2019

National Institute of Standards and Technology. –“”– 2019

ICRA Workshop: Long-Term Human Motion Prediction. –“”– 2019

Advising

Current Ph.D. Students

Hyun Joe Jeong	2025 - *present*
Junwon Seo	2024 - *present*
Yilin Wu	2024 - *present*
Kensuke Nakamura	2023 - *present*
Ravi Pandya (co-advised with Changliu Liu)	2023 - *present*

Current Masters Students

Rosy Chen (MSCS)	2024 - *present*
Tiffany Han (MSR, co-advised with Zeynep Temel)	2025 - *present*
Surgan Jandial (MSR, co-advised with Fernando De la Torre)	2024 - *present*

Current Undergraduate Students

Matthew Kim	2025 - *present*
Sunny Agarwal	2025 - *present*
Jessie Yuan	2025 - *present*
Eric Hu	2025 - *present*

Past Ph.D. Students

Ran Tian (co-advised with Masayoshi Tomizuka) 2022 - 2025
Thesis: *Towards Safe & Aligned Embodied AI in the Era of Robotics Foundation Models*

Past Masters Students

Evolone Layne (→ PhD University of Washington)	2024-2025
Vibhakar Mohta (→ ML Engineer at Plus)	2023-2024
Dylan Goetting (→ Skild.ai)	2023
Charles Tang (→ Software engineer at Mosaic ML)	2020

Past Undergraduate Students

Hyun Joe Jeong (→ PhD at CMU)	2024 - 2025
Leonardo Santos (→ PhD at KTH)	2024 - 2025
Abigail Defranco (→ MSR at CMU)	2024 - 2025
Zirui Li	2024
Regina Wang (→ MS at Stanford)	2022
Anand Siththaranjan (→ PhD at Berkeley)	2021
Sampada Deglurkar (→ PhD at Berkeley)	2020
Eli Bronstein (→ PhD at Berkeley)	2019

PhD Thesis Committees

Tiago Almeida (Örebro University, Sweden)	Achim J. Lilienthal, 2025
Saumya Saxena (CMU RI)	Oliver Kroemer, 2025
Ingrid Navarro (CMU RI)	Jean Oh, 2025
Rebecca Martin (CMU RI)	Sebastian Scherer, 2025
Neerja Thakkar (UC Berkeley EECS)	Jitendra Malik, 2024
Shaunak Mehta (Virgina Tech ME)	Dylan Losey, 2024
Jay Patrikar (CMU RI)	Sebastian Scherer, 2024
Michelle Zhao (CMU RI)	Henny Admoni & Reid Simmons, 2024
Tianhao Wei (CMU RI)	Changliu Liu, 2024
Yiwei Lyu (CMU ECE)	John Dolan, 2024
Benjamin Newman (CMU RI)	Henny Admoni & Kris Kitani, 2023
Ananya Rao (CMU RI)	David Wettergreen & Howie Choset, 2023
Katherine Shih (CMU RI)	Aaron Steinfeld, 2023

PhD Qualifer Committees

Andrew Jong (CMU RI)	Sebastian Scherer, 2025
Arthur Bucker (CMU RI)	Jean Oh, 2025
Yuyao Shi (CMU RI)	Jessica Hodgins, 2025
Itamar Mishani (CMU RI)	Maxim Lichachev, 2025

MSR Thesis Committees

Yishu Li (CMU RI)	Dave Held, 2025
Pranay Gupta (CMU RI)	Henny Admoni & Dave Held, 2024
Zhanyi Sun (CMU RI)	Zackory Erickson & Dave Held, 2024
Weihao Zeng (CMU RI)	Katia Sycara, 2024

Outreach

CMU Robotics Institute Pathways Fellowship (mentor) 2024 - 2025
Immersive program crafted to empower entrepreneurs within the domains of robotics, manufacturing, and automation.

Robotics Institute Summer Scholars (RISS) (mentor) 2024, 2025
Mentored undergraduates from around the world in summer research.

Inclusion@RSS, Pathways@RSS (mentor, speaker) 2024, 2025
Early career graduate students who belong to traditionally underrepresented groups in robotics.

SCS Female Professor Breakfast (mentor) 2023 - 2024
Mentored undergraduate women in the school of computer science.

AI Scholars (invited talk) 2024
Residential summer program for high-schoolers who have been historically excluded and/or under-resourced in STEM, both in academia and industry.

ML@Berkeley (invited talk) 2021
Spoke to undergraduate club focused on machine learning and its applications.

creAItivity (invited talk) 2021
Taught students interested in AI about safe robot interaction.

Tranfer-To-Excellence REU (mentoring and invited talks) 2021 - 2022
Competitive summer internship for California community college students.

AI4ALL (mentor and speaker) 2020 - 2022
Program for current 9th and 10th grade students from underrepresented communities in the Bay Area to learn about computing and AI.

Girls in Engineering Camp (instructor) 2018 - 2019
Taught at a week-long summer camp for middle school students who learn about engineering.

Professional Activities

Associate Editor (AE) / Area Chair (AC) / Program Committee (PC)

CoRL: Conference on Robot Learning (AC) 2025
L4DC: Learning for Dynamics & Control Conference (PC) 2023, 2025

ICLR: International Conference on Learning Representations (AC) 2024
IROS: International Conference on Intelligent Robots and Systems (AE) 2024
ICRA: International Conference on Robotics and Automation (AE) 2023

Organizing Committee

RSS: Robotics: Science and Systems (Presentation Chair) 2023

External Reviewer

Conferences
CoRL: Conference on Robot Learning
RSS: Robotics: Science and Systems
IROS: International Conference on Intelligent Robots and Systems
ICRA: International Conference on Robotics and Automation
HRI: Human-Robot Interaction
ICCPS: International Conference on Cyber-Physical Systems
ACC: American Control Conference
AAAI: Association for the Advancement of Artificial Intelligence

Journals
IJRR: International Journal of Robotics Research
RA-L: Robotics and Automation Letters
T-RO: Transactions on Robotics
AURO: Autonomous Robots
PNAS Nexus: Proceedings of the National Academy of Sciences

Career Workshops
RSS Pioneers 2025, 2024
HRI Pioneers 2025

Grants
NSF: National Science Foundation 2024

Conference Session Chair

RSS: Robotics: Science and Systems (Control & Dynamics) 2025
ICRA: International Conference on Robotics & Automation (Safe Control 2) 2025

Workshops Organized

ICRA: Safely Leveraging Vision-Language Foundation Models in Robotics 2025

ICRA: Public Trust in Autonomy 2025

NESCW: Northeast Systems and Control Workshop 2024, 2025

ICRA: Long-term Human Motion Prediction 2021, 2022

RSS: Robotics for People 2021

Robotics: Science and Systems (RSS) Pioneers 2021

RSS: 2nd Workshop on Robust Autonomy 2020

RSS: Safe Robot Learning and Control in Real-World Environments 2019

Department & School Service

Robotics Institute Seminar Organizer	Fall 2024 - *present*
Robotics Institute Faculty Hiring Committee	2025
ACM/SCS Dissertation Award Committee	2024
Women@SCS Faculty Breakfast Mentor	2024
SCS Junior Faculty Orientation Panel	2024
SCS Faculty Job Market Panel	2023

Press & Media

CMU News *"The NSF CAREER Awardees Supercharging STEM"*	2025
NBC News *"Robots at UC Berkeley Take a Step Forward"*	2018
WIRED *"How to Interact With Robots Without Embarrassing Yourself"*	2018
Robohub *"Learning Robot Objectives from Physical Human Interaction"*	2018