

# RL with continuous action spaces

## General function approximation continued...

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**MACHINE LEARNING** DEPARTMENT



# Average Bellman error – Q version

Weaker notion of Bellman error:

Evaluate  $g$ -approximation of  $Q$  using a policy  $\pi_f$

$$\mathcal{E}(g; f, h) = \mathbb{E}_{s_h, a_h \sim d_h^{\pi_f}} \left[ g(s_h, a_h) - r(s_h, a_h) - \mathbb{E}_{s_{h+1} \sim P(\cdot | s_h, a_h)} \left[ \max_{a \in \mathcal{A}} g(s_{h+1}, a) \right] \right]$$

$f$ : defines roll-in distribution over  $s_h, a_h$

We know that  $\mathcal{E}(Q^\star; f, h) = 0, \forall f$

Hence, any  $g$  such that  $\mathcal{E}(g; f, h) \neq 0$ , is an incorrect  $Q^\star$  approximator

# Average Bellman error – V version

Evaluate average Bellman wrt  $V$  function induced by  $g$  as well:

$$\mathcal{E}(g; f, h) = \mathbb{E}_{s_h \sim d_h^{\pi_f}} \left[ V_g(s_h) - r(s_h, \pi_g(s_h)) - \mathbb{E}_{s_{h+1} \sim P(\cdot | s_h, \pi_g(s_h))} \left[ V_g(s_{h+1}) \right] \right]$$

$f$ : defines roll-in distribution over  $s_h, a_h$

and  $V_g(s) = \max_a g(s, a)$ .

Again we have  $\mathcal{E}(Q^\star; f, h) = 0, \forall f$

( because:  $V_{Q^\star}(s) - r(s, \pi_{Q^\star}(s)) - \mathbb{E}_{s' \sim P_h(\cdot | s, \pi_{Q^\star}(s))} V_{Q^\star}(s') = 0$  )

Hence, any  $g$  such that  $\mathcal{E}(g; f, h) \neq 0$ , is an incorrect  $Q^\star$  approximator

# Estimating Q-Bellman error (generative setting)

Recall our hypothesis class  $\mathcal{F}$ , where each  $g \in \mathcal{F}$  is in the form of  $g(s, a)$

For  $Q$ -Bellman rank, we define Bellman error loss as:

$$\ell(s_h, a_h, s'_{h+1}, g) = g(s_h, a_h) - r(s_h, a_h) - \max_{a'} g(s_{h+1}, a')$$

If we had a dataset  $\mathcal{D} := \{s_h, a_h, s_{h+1}\}$  where  $s_h, a_h \sim d_h^{\pi_f}, s_{h+1} \sim P_h(\cdot | s_h, a_h)$

then  $\forall g : \mathbb{E}_{\mathcal{D}}[\ell(s_h, a_h, s_{h+1}, g)]$  is an unbiased est of  $\mathcal{E}(g; f, h)$

# Estimating V-Bellman error (generative setting)

Recall our hypothesis class  $\mathcal{F}$ , where each  $g \in \mathcal{F}$  is in the form of  $g(s, a)$

For V-Bellman rank, we define Bellman error loss as:

$$\ell(s_h, a_h, s'_{h+1}, g) = \frac{\mathbf{1}\{a_h = \pi_g(s_h)\}}{1/A} \left( g(s_h, a_h) - r(s_h, a_h) - \max_{a'} g(s_{h+1}, a') \right)$$

If we had a dataset  $\mathcal{D} := \{s_h, a_h, s_{h+1}\}$  where  $s_h \sim d_h^{u_f}, a_h \sim U(\mathcal{A})$ ,  
 $s_{h+1} \sim P_h(\cdot | s_h, a_h)$

then  $\forall g : \mathbb{E}_{\mathcal{D}}[\ell(s_h, a_h, s_{h+1}, g)]$  is an unbiased est of  $\mathcal{E}(g; f, h)$

# Estimating Bellman rank

Uniform convergence style assumption on our hypothesis class  $\mathcal{F}$ :

Given any distribution  $\nu \in \Delta(S \times A \times S)$ , and  $m$  i.i.d samples  $\{s_i, a_i, s'_i\}$  from  $\nu$ ,  
w/ probability at least  $1 - \delta$ ,

$$\forall g : \left| \mathbb{E}_{\nu} \ell(s, a, s', g) - \mathbb{E}_{\mathcal{D}} \ell(s, a, s', g) \right| \leq \varepsilon_{gen}(m, \mathcal{F}, \delta)$$

Example: when  $\mathcal{F}$  is discrete (for B-rank loss), Hoeffding + union bound over  $\mathcal{F}$  implies:

$$\varepsilon_{gen}(m, \mathcal{F}, \delta) := 2H \sqrt{\frac{\ln(|\mathcal{F}|/\delta)}{m}}$$

# Bellman rank

$\exists$  two mappings  $W_h : \mathcal{F} \mapsto \mathbb{R}^d$ ,  $X_h : \mathcal{F} \mapsto \mathbb{R}^d$  ( $d = \text{Bellman-rank}$ )

s.t.  $\forall f, g \in \mathcal{F} : \mathcal{E}(g; f, h) = \langle W_h(g), X_h(f) \rangle$

$\forall h : \mathcal{E}_h \in \mathbb{R}^{|\mathcal{F}| \times |\mathcal{F}|}$

	$g \quad f$					
$\pi_f$		$\mathcal{E}_{g;f,h}$	$\mathcal{E}_{f;f,h}$			

Rank of this matrix = Bellman rank

Note: we just assume the existence of  $W$ ,  $X$ , but they are unknown

# Algorithm under Bellman rank

- Works for general function approximation with low Bellman rank
- Gives optimism without adding (nonlinear) bonus



# Bilinear-UCB

A general algorithm under Bellman rank that can learn an  $\epsilon$  near optimal policy with number of samples

e.g.,  $\text{poly}(H, \text{b-rank}, \ln(|\mathcal{F}|), 1/\epsilon^2)$

# Bilinear-UCB

At iteration  $t$  :

Select  $f_t = \arg \max_{g \in \mathcal{F}} V_g(s_0)$

$$\text{s.t., } \forall h : \sum_{i=0}^{t-1} \left( \mathbb{E}_{\mathcal{D}_{h,i}} [\ell(s_h, a_h, s_{h+1}, g)] \right)^2 \leq R^2$$

# Bilinear-UCB

At iteration  $t$  :

Select  $f_t = \arg \max_{g \in \mathcal{F}} V_g(s_0)$

$$\text{s.t., } \forall h : \sum_{i=0}^{t-1} \left( \mathbb{E}_{\mathcal{D}_{h,i}} [\ell(s_h, a_h, s_{h+1}, g)] \right)^2 \leq R^2$$

For all  $h$ , create  $\mathcal{D}_{h,t} = \{s_h, a_h, s_{h+1}\}$  w/  $m$  triples, where:

- For Q-B rank case:  $s_h, a_h \sim d_h^{\pi_{f_t}}, s_{h+1} \sim P_h(\cdot | s_h, a_h)$
- For V-B rank case:  $s_h \sim d_h^{\pi_{f_t}}, a_h \sim U(A), s_{h+1} \sim P_h(\cdot | s_h, a_h)$

# Bilinear-UCB

$$\text{Select } f_t = \arg \max_{g \in \mathcal{F}} V_g(s_0) \quad \text{s.t., } \forall h : \sum_{i=0}^{t-1} \left( \mathbb{E}_{\mathcal{D}_{h,i}} [\ell(s_h, a_h, s_{h+1}, g)] \right)^2 \leq R^2$$

1. When the batch size ( $|\mathcal{D}_{h,i}|$ ) is large,

$$\mathbb{E}_{\mathcal{D}_{h,i}} \ell(s_h, a_h, s_{h+1}, g) \rightarrow \mathcal{E}(g; f_i, h)$$

2. We know that  $\sum_{i=1}^{t-1} \mathcal{E}(f^\star; f_i, h) = 0$

3. By properly setting batch size and  $R$ , we eliminate wrong hypothesis, but keep  $f^\star$

4. This gives optimism:  $V_{f_t}(s_0) \geq V_{f^\star}(s_0) := V^\star(s_0)$

Optimism allows explore and exploit tradeoff!

# Analysis of Bilinear-UCB

Step 1: proving optimism via showing  $f^\star$  is always a feasible solution (whp)

$$\text{Recall constraint: } \forall h : \sum_{i=0}^{t-1} \left( \mathbb{E}_{\mathcal{D}_{h,i}} [\ell(s_h, a_h, s_{h+1}, g)] \right)^2 \leq R^2$$

**Lemma:** set  $R = \sqrt{T} \cdot \varepsilon_{\text{gen}}(m, \mathcal{F}, \delta/TH)$ ,

W/ prob  $1 - \delta$ , we have  $f^\star$  being a feasible solution for all the  $T$  iterations;

Proof: Consider any iteration  $i < t$ :

$$|\mathbb{E}_{\mathcal{D}_{i,h}} \ell(s_h, a_h, s_{h+1}, f^\star) - \mathcal{E}(f^\star; f_i, h)| \leq \varepsilon_{\text{gen}}$$

$$(\mathbb{E}_{\mathcal{D}_{i,h}} \ell(s_h, a_h, s_{h+1}, f^\star))^2 \leq \varepsilon_{\text{gen}}^2 \quad \text{since } \mathcal{E}(f^\star; f_i, h) = 0$$

$$\sum_{i=0}^{t-1} \left( \mathbb{E}_{\mathcal{D}_{i,h}} \ell(s_h, a_h, s_{h+1}, f^\star) \right)^2 \leq t \varepsilon_{\text{gen}}^2 \leq T \varepsilon_{\text{gen}}^2 := R^2$$

# Analysis of Bilinear-UCB

Step 1: proving optimism via showing  $f^\star$  is always a feasible solution (whp)

The fact that  $f^\star$  being feasible  $\Rightarrow$  optimism, i.e.,  $\forall t, V_{f_t}(s_0) \geq V_{f^\star}(s_0) := V^\star(s_0)$

Proof:

Recall the objective function:

$$\text{Select } f_t = \arg \max_{g \in \mathcal{F}} V_g(s_0) \quad \text{s.t., } \forall h : \sum_{i=0}^{t-1} \left( \mathbb{E}_{\mathcal{D}_{h,i}} [\ell(s_h, a_h, s_{h+1}, g)] \right)^2 \leq R^2$$

# Analysis of Bilinear-UCB

Step 2: Using optimism to upper bound per-episode regret:

$$\text{Optimism} \Rightarrow V^\star(s_0) - V^{\pi_{f_t}}(s_0) \leq V_{f_t}(s_0) - V^{\pi_{f_t}}(s_0)$$

**Lemma:**

$$\begin{aligned} V_{f_t}(s_0) - V^{\pi_{f_t}}(s_0) &= \sum_{h=0}^{H-1} \mathbb{E}_{s_h, a_h \sim d_h^{\pi_{f_t}}} \left[ f_t(s_h, a_h) - r(s_h, a_h) - \mathbb{E}_{s_{h+1} \sim P_h(s_h, a_h)} \max_{a'} f_t(s_{h+1}, a') \right] \\ &= \sum_{h=0}^{H-1} \mathcal{E}(f_t; f_t, h) = \sum_{h=0}^{H-1} W_h(f_t)^\top X_h(f_t) \end{aligned}$$

Proof:

$$\begin{aligned} V_{f_t}(s_0) - V^{\pi_{f_t}}(s_0) &= \mathbb{E}_{a_0 \sim \pi_{f_t}(s_0)} [f_t(s_0, a_0)] - \mathbb{E}_{a_h \sim \pi_{f_t}(s_h), s_{h+1} \sim P(\cdot | s_h, a_h)} [\sum_{h=0}^{H-1} r(s_h, a_h)] \\ &= \mathbb{E}_{a_h \sim \pi_{f_t}(s_h), s_{h+1} \sim P(\cdot | s_h, a_h)} [\sum_{h=0}^{H-1} (f_t(s_h, a_h) - r(s_h, a_h) - f_t(s_{h+1}, a_{h+1}))] \\ &\quad \text{telescoping sum since } f_t(s_H, a_H) = 0 \\ &= \sum_{h=0}^{H-1} \mathbb{E}_{a_h, s_h \sim d^{\pi_{f_t}}} [f_t(s_h, a_h) - r(s_h, a_h) - \mathbb{E}_{s_{h+1} \sim P(\cdot | s_h, a_h)} [\max_{a'} f_t(s_{h+1}, a')]] \\ &\quad \text{since } a_{h+1} = \arg \max_{a'} f_t(s_{h+1}, a') \end{aligned}$$

# Analysis of Bilinear-UCB

Step 2: Using optimism to upper bound per-episode regret:

$$\begin{aligned} V^\star(s_0) - V^{\pi_{f_t}}(s_0) &= \sum_{h=0}^{H-1} \mathbb{E}_{s_h, a_h \sim d_h^{\pi_{f_t}}} \left[ f_t(s_h, a_h) - r(s_h, a_h) - \mathbb{E}_{s_{h+1} \sim P_h(s_h, a_h)} \max_{a'} f_t(s_{h+1}, a') \right] \\ &= \sum_{h=0}^{H-1} \mathcal{E}(f_t; f_t, h) = \sum_{h=0}^{H-1} W_h(f_t)^\top X_h(f_t) \end{aligned}$$

Define “feature” covariance matrix  $\Sigma_{t,h} = \sum_{i=0}^{t-1} X_h(f_i)X_h(f_i)^\top + \lambda I$

Cauchy-Schwartz implies 
$$V^\star(s_0) - V^{\pi_{f_t}}(s_0) \leq \sum_{h=0}^{H-1} \|W_h(f_t)\|_{\Sigma_{t,h}} \|X_h(f_t)\|_{\Sigma_{t,h}^{-1}}$$



# Analysis of Bilinear-UCB

Summary so far, after optimism + per-episode regret decomposition, we get:

Define “feature” covariance matrix  $\Sigma_{t,h} = \sum_{i=0}^{t-1} X_h(f_i)X_h(f_i)^\top + \lambda I$

$$\forall t : V^\star(s_0) - V^{\pi_{f_t}}(s_0) \leq \sum_{h=0}^{H-1} \|W_h(f_t)\|_{\Sigma_{t,h}} \|X_h(f_t)\|_{\Sigma_{t,h}^{-1}}$$

Similar to linUCB, using elliptical potential lemma:

$$\|X_h(f_t)\|_{\Sigma_{t,h}^{-1}}^2 \leq \exp\left(\frac{Hd}{T} \ln\left(1 + \frac{TB_X^2}{d\lambda}\right)\right) - 1,$$

$$\text{where } \|X_h(f)\|_2 \leq B_X \quad \forall f \in \mathcal{F}$$

$$\text{Similarly, let } \|W_h(f)\|_2 \leq B_W \quad \forall f \in \mathcal{F}$$

# Analysis of Bilinear-UCB

Summary so far, after optimism + per-episode regret decomposition, we get:

Define “feature” covariance matrix  $\Sigma_{t,h} = \sum_{i=0}^{t-1} X_h(f_i)X_h(f_i)^\top + \lambda I$

$$\forall t : V^\star(s_0) - V^{\pi_{f_t}}(s_0) \leq \sum_{h=0}^{H-1} \|W_h(f_t)\|_{\Sigma_{t,h}} \|X_h(f_t)\|_{\Sigma_{t,h}^{-1}}$$

$$\forall h : \sum_{i=0}^{t-1} \left( \mathbb{E}_{\mathcal{D}_{h,i}}[\ell(s_h, a_h, s_{h+1}, f_t)] \right)^2 \leq R^2$$

$$\Rightarrow \forall h : \sum_{i=0}^{t-1} \mathcal{E}(f_t; f_i, h)^2 \leq \sum_{i=0}^{t-1} 2 \left( \mathcal{E}(f_t; f_i, h) - \mathbb{E}_{\mathcal{D}_{i,h}} \ell(s_h, a_h, s_{h+1}, f_t) \right)^2 + \sum_{i=0}^{t-1} 2 \left( \mathbb{E}_{\mathcal{D}_{i,h}} \ell(s_h, a_h, s_{h+1}, f_t) \right)^2$$

$$\Rightarrow \forall h : \sum_{i=0}^{t-1} \mathcal{E}(f_t; f_i, h)^2 \leq 4T\epsilon_{gen}^2 \Rightarrow \forall h : \sum_{i=0}^{t-1} (W_h(f_t)^\top X_h(f_i))^2 \leq 4T\epsilon_{gen}^2$$

$$\Rightarrow \forall h : \|W_h(f_t)\|_{\Sigma_{t,h}}^2 \leq 4T\epsilon_{gen}^2 + \lambda B_W^2$$

# Analysis of Bilinear-UCB

$$\begin{aligned} \forall t : V^\star(s_0) - V^{\pi_{f_t}}(s_0) &\leq \sum_{h=0}^{H-1} \left\| W_h(f_t) \right\|_{\Sigma_{t,h}} \|X_h(f_t)\|_{\Sigma_{t,h}^{-1}} \\ &\leq H \sqrt{4\lambda B_W^2 + 4T \varepsilon_{gen}^2} \sqrt{\exp\left(\frac{Hd}{T} \ln\left(1 + \frac{TB_X^2}{d\lambda}\right)\right) - 1} \end{aligned}$$

Set  $1/\lambda = B_W^2/\varepsilon_{gen}^2 + 1/B_X^2$  And  $T = \left\lceil 2Hd \ln\left(4Hd \left(\frac{B_X^2 B_W^2}{\varepsilon_{gen}^2} + 1\right)\right) \right\rceil$

$$\begin{aligned} &\leq H \sqrt{2(4\lambda B_W^2 + 4T \varepsilon_{gen}^2)} \\ &\leq 5\varepsilon_{gen} \sqrt{dH^3 \ln\left(4Hd \left(\frac{B_X^2 B_W^2}{\varepsilon_{gen}^2} + 1\right)\right)}. \end{aligned}$$

# Analysis of Bilinear-UCB

$$\forall t : V^\star(s_0) - V^{\pi_{f_t}}(s_0) \leq \sum_{h=0}^{H-1} \left\| W_h(f_t) \right\|_{\Sigma_{t,h}} \|X_h(f_t)\|_{\Sigma_{t,h}^{-1}}$$

Regret bound

$$\leq 5\varepsilon_{gen} \sqrt{dH^3 \ln \left( 4Hd \left( \frac{B_X^2 B_W^2}{\varepsilon_{gen}^2} + 1 \right) \right)}.$$

Example: when  $\mathcal{F}$  is discrete (for B-rank loss), Hoeffding + union bound over  $\mathcal{F}$  implies:

$$\varepsilon_{gen}(m, \mathcal{F}, \delta) := 2H \sqrt{\frac{\ln(|\mathcal{F}|/\delta)}{m}}$$

eps-optimal with sample complexity ,  $m \sim \text{poly}(H, d, \ln(|\mathcal{F}|), 1/\text{eps}^2)$

# General function approximation

Summary:

- General non-linear function approximation
- Hardness - Exponential complexity with continuous arms
- Poly sample complexity under Bellman rank, low-rank MDP, Bellman completeness **Towards model-free RL**
- Bilinear-UCB algorithm

Open questions:

- Computational complexity
- Online setting (needs additional assumptions)

**Instead of parametrizing model/value functions,  
can we parametrize policies directly?**