Linear Regression (Matrix-vector form)

$$\widehat{\beta} = \arg\min_{\beta} \frac{1}{n} \sum_{i=1}^{n} (X_i \beta - Y_i)^2$$

$$= \arg\min_{\beta} \frac{1}{n} (\mathbf{A}\beta - \mathbf{Y})^T (\mathbf{A}\beta - \mathbf{Y})$$

$$\begin{bmatrix} X_1 \end{bmatrix} \begin{bmatrix} X_1^{(1)} & \dots & X_1^{(p)} \end{bmatrix}$$

$$\mathbf{A} = \begin{bmatrix} X_1 \\ \vdots \\ X_n \end{bmatrix} = \begin{bmatrix} X_1^{(1)} & \dots & X_1^{(p)} \\ \vdots & \ddots & \vdots \\ X_n^{(1)} & \dots & X_n^{(p)} \end{bmatrix}$$

$$\widehat{f}_n^L(X) = X\widehat{\beta}$$

$$\mathbf{Y} = \left[egin{array}{c} \mathbf{Y}_1 \ dots \ \mathbf{Y}_n \end{array}
ight]$$

Normal equations:
$$(\mathbf{A}^T \mathbf{A}) \hat{\beta} = \mathbf{A}^T \mathbf{Y}$$

If invertible, closed form expression or gradient descent

Linear regression solution satisfies **Normal Equations**

$$(\mathbf{A}^T \mathbf{A})\widehat{\beta} = \mathbf{A}^T \mathbf{Y}$$

$$\mathbf{p} \times \mathbf{p} \quad \mathbf{p} \times \mathbf{1} \qquad \mathbf{p} \times \mathbf{1}$$



When is $(\mathbf{A}^T \mathbf{A})$ invertible?

Recall: Full rank matrices are invertible. What is rank of (A^TA) ?

If
$$\mathbf{A} = \mathbf{U}\mathbf{S}\mathbf{V}^ op$$
, then

If
$$\mathbf{A} = \mathbf{U}\mathbf{S}\mathbf{V}^{\top}$$
, then
$$\begin{bmatrix} \mathbf{V}^{\top} & \mathbf{V}$$

r equations in p unknowns. Under-determined if r < p, hence no n<p high-dim setting unique solution.

Regularized Linear Regression

Aarti Singh & Geoff Gordon

Machine Learning 10-701 Feb 22, 2021



Regularized Least Squares

What if $(\mathbf{A}^T \mathbf{A})$ is not invertible ?

r equations , p unknowns – underdetermined system of linear equations many feasible solutions

Need to constrain solution further

e.g. bias solution to "small" values of β (small changes in input don't translate to large changes in output)

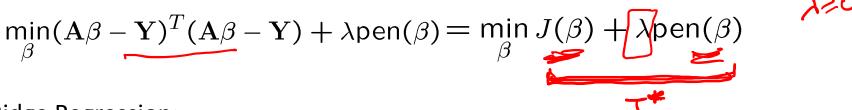
$$\widehat{\beta}_{\mathsf{MAP}} = \arg\min_{\beta} \sum_{i=1}^{n} (Y_i - X_i \beta)^2 + \lambda \|\beta\|_2^2$$

Ridge Regression (12 penalty)

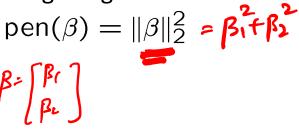
$$= \underset{\beta}{\text{arg min}} \quad (\mathbf{A}\beta - \mathbf{Y})^T (\mathbf{A}\beta - \mathbf{Y}) + \lambda \|\beta\|_2^2 \qquad \lambda \ge 0$$

$$\Rightarrow \beta^T (\mathbf{A}A + \lambda \mathbf{I})^{\beta} \qquad \beta^T \mathbf{A}^T \mathbf{A}^T \mathbf{Y} \qquad (\mathbf{A}^T \mathbf{A} + \lambda \mathbf{I})^{-1} \mathbf{A}^T \mathbf{Y} \qquad (\mathbf{A}^T \mathbf{A} + \lambda \mathbf{I}) \text{ invertible ?}$$

Understanding regularized Least Squares



Ridge Regression:



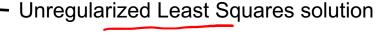
 β s with constant $J(\beta)$

(level sets of $J(\beta)$)

 β s with constant |2 norm (level sets of pen(β))

 β_2

(level sets of pen(β))



Regularized Least Squares

What if $(\mathbf{A}^T \mathbf{A})$ is not invertible ?

r equations , p unknowns – underdetermined system of linear equations many feasible solutions

Need to constrain solution further

e.g. bias solution to "small" values of β (small changes in input don't translate to large changes in output)

$$\widehat{\beta}_{\text{MAP}} = \arg\min_{\beta} \sum_{i=1}^{n} (Y_i - X_i \beta)^2 + \lambda \|\beta\|_2^2 \qquad \text{Ridge Regression (I2 penalty)}$$

$$= \sum_{\beta \text{MAP}} \widehat{\beta}_{\text{MAP}} = \arg\min_{\beta} \sum_{i=1}^{n} (Y_i - X_i \beta)^2 + \lambda \|\beta\|_1 \qquad \text{Lasso (I1 penalty)}$$

Many β can be zero – many inputs are irrelevant to prediction in high-dimensional settings (typically intercept term not penalized)

Regularized Least Squares

What if $(\mathbf{A}^T \mathbf{A})$ is not invertible ?

r equations , p unknowns – underdetermined system of linear equations many feasible solutions

Need to constrain solution further

e.g. bias solution to "small" values of β (small changes in input don't translate to large changes in output)

$$\widehat{\beta}_{\mathsf{MAP}} = \arg\min_{\beta} \sum_{i=1}^{n} (Y_i - X_i \beta)^2 + \lambda \|\beta\|_2^2 \qquad \begin{array}{c} \mathsf{Ridge Regression} \\ \mathsf{(l2 penalty)} \end{array}$$

$$\widehat{\beta}_{\mathsf{MAP}} = \arg\min_{\beta} \sum_{i=1}^{n} (Y_i - X_i \beta)^2 + \lambda \|\beta\|_1 \qquad \qquad \mathsf{Lasso} \\ \mathsf{||k||} \qquad \mathsf{||k||} \qquad \mathsf{(l1 penalty)} \end{array}$$

No closed form solution, but can optimize using sub-gradient descent (packages available)

Ridge Regression vs Lasso

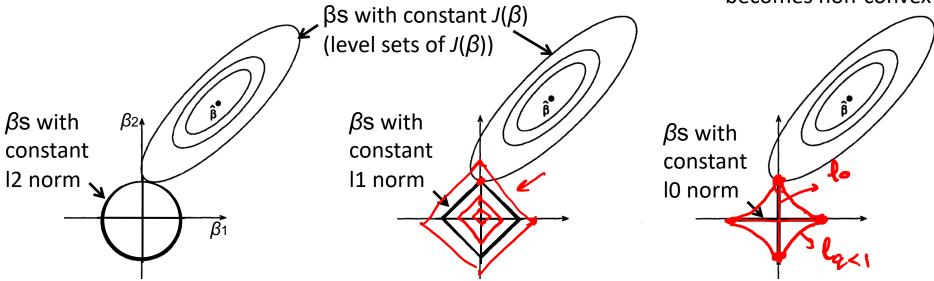
$$\min_{\beta} (\mathbf{A}\beta - \mathbf{Y})^T (\mathbf{A}\beta - \mathbf{Y}) + \lambda \mathrm{pen}(\beta) = \min_{\beta} J(\beta) + \lambda \mathrm{pen}(\beta)$$

$$\parallel \beta \parallel_{\mathbf{b}} = \sum_{\mathbf{Y}} \mathbf{1}_{\beta} \mathbf{I}_{\mathbf{b}} \mathbf{I}_{\mathbf{b}} \mathbf{I}_{\mathbf{b}}$$
Ridge Regression:
Lasso:

pen(β) = $\|\beta\|_2^2$

pen(β) = $\|\beta\|_1$ = $\mathbb{Z}[\beta]$

Ideally IO penalty, but optimization becomes non-convex



Lasso (I1 penalty) results in sparse solutions – vector with more zero coordinates Good for high-dimensional problems – don't have to store all coordinates, interpretable solution!

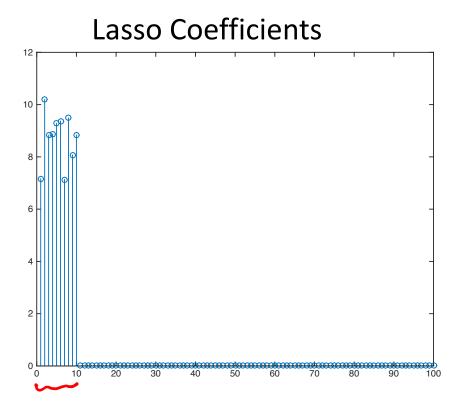
Matlab example

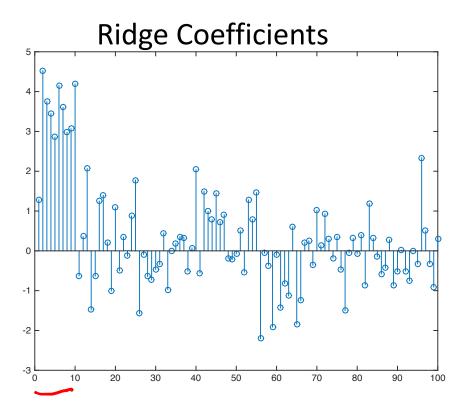
```
clear all
                                            lassoWeights = lasso(X,Y,'Lambda',1,
                                            'Alpha', 1.0);
    close all
                                            Ylasso = Xtest*lassoWeights;
\rightarrow n = 80; % datapoints
                                            norm(Ytest-Ylasso)
\rightarrow p = 100; % features
    k = 10; % non-zero features
                                            ridgeWeights = lasso(X,Y,'Lambda',1,
                                            'Alpha', 0.0001);
    rng(20);
                                            Yridge = Xtest*ridgeWeights;
                                            norm(Ytest-Yridge)
    X = randn(n,p);
    weights = zeros(p,1);
    weights(1:k) = randn(k,1)+10;
                                            stem(lassoWeights)
    noise = randn(n,1) * 0.5;
                                            pause
    Y = X*weights + noise;
                                            stem(ridgeWeights)
    Xtest = randn(n,p);
    noise = randn(n,1) * 0.5;
    Ytest = Xtest*weights + noise;
```

Matlab example

Test MSE = 33.7997

Test MSE = 185.9948





Least Squares and M(C)LE

Intuition: Signal plus (zero-mean) Noise model
$$Y = f^*(X) + \epsilon = X\beta^* + \epsilon$$

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$$Y = f^*(X) + \epsilon$$

Least Square Estimate is same as Maximum Conditional Likelihood Estimate under a Gaussian model!

Regularized Least Squares and M(C)AP

 $P(\theta|D) \propto P(\theta) P(D|\theta)$

 $\mathsf{constant}(\sigma^2, \tau^2)$

What if
$$(\mathbf{A}^T\mathbf{A})$$
 is not invertible ?
$$(\mathbf{B}^T\mathbf{A}) = \arg\max_{\beta} \log p(\{Y_i\}_{i=1}^n | \beta, \sigma^2, \{X_i\}_{i=1}^n + \log p(\beta))$$
 Conditional log likelihood log prior

I) Gaussian Prior
$$\beta \sim \mathcal{N}(\mathbf{0}, \tau^2\mathbf{I}) \qquad p(\beta) \propto e^{-\beta^T\beta/2\tau^2} \qquad p(\beta) \sim e$$

Prior belief that β is Gaussian with zero-mean biases solution to "small" β

Regularized Least Squares and M(C)AP

$$\widehat{\beta}_{\text{MAP}} = \arg\max_{\beta} \log p(\{Y_i\}_{i=1}^n | \beta, \sigma^2, \{X_i\}_{i=}^n + \log p(\beta) \}$$
 Conditional log likelihood log prior
$$\beta_i \overset{iid}{\sim} \text{ Laplace}(0,t) \qquad p(\beta_i) \propto e^{-|\beta_i|/t}$$

$$p(\beta) = \prod_{\beta \in \mathcal{A}} p(\beta_i) = \prod_{\beta \in \mathcal{A}} p(\beta_i)$$
 Conditional log likelihood log prior
$$\beta_i \overset{iid}{\sim} \text{ Laplace}(0,t) \qquad p(\beta_i) \propto e^{-|\beta_i|/t}$$
 Conditional log likelihood log prior
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 Conditional log likelihood log prior
$$\beta_i \overset{iid}{\sim} \text{ Laplace}(0,t) \qquad p(\beta_i) \propto e^{-|\beta_i|/t}$$
 Conditional log likelihood log prior log prior
$$\beta_i \overset{iid}{\sim} \text{ Laplace}(0,t) \qquad p(\beta_i) \propto e^{-|\beta_i|/t}$$
 Conditional log likelihood log prior log

Prior belief that β is Laplace with zero-mean biases solution to "sparse" β

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Polynomial Regression

degree m

Univariate (1-dim) $f(X) = \beta_0 + \beta_1 X + \beta_2 X^2 + \dots + \beta_m X^m = X\beta$ case:

where
$$\mathbf{X} = [1 \ X \ X^2 \dots X^m]$$
 , $\beta = [\beta_1 \dots \beta_m]^T$

$$\hat{\beta} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \mathbf{Y}$$

$$\widehat{f}_n(X) = \mathbf{X}\widehat{\beta}$$

where
$$\mathbf{A}=\left[\begin{array}{ccccc} 1 & X_1 & X_1^2 & \dots & X_1^m \\ \vdots & & \ddots & \vdots \\ 1 & X_n & X_n^2 & \dots & X_n^m \end{array}\right]$$

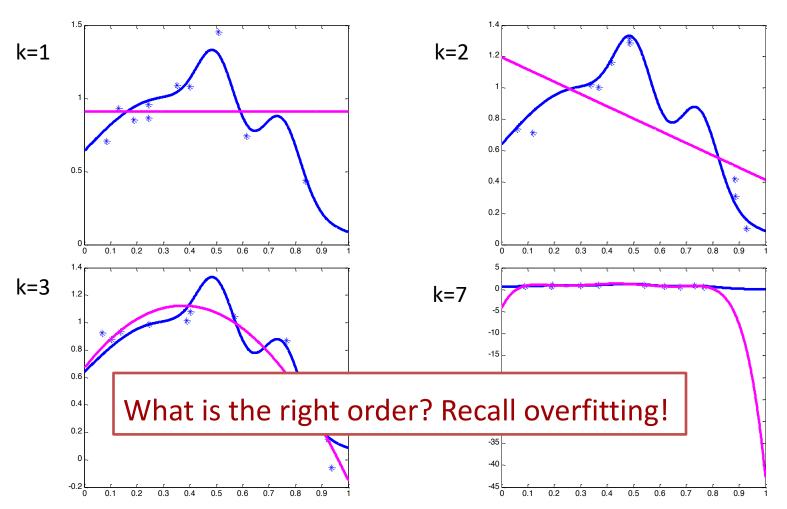
Multivariate (p-dim)
$$f(X)$$
 case:

Multivariate (p-dim)
$$f(X) = \beta_0 + \beta_1 X^{(1)} + \beta_2 X^{(2)} + \dots + \beta_p X^{(p)}$$
 case:
$$+ \sum_{i=1}^p \sum_{j=1}^p \beta_{ij} X^{(i)} X^{(j)} + \sum_{i=1}^p \sum_{j=1}^p \sum_{k=1}^p X^{(i)} X^{(j)} X^{(k)}$$

+...terms up to degree m

Polynomial Regression

Polynomial of order k, equivalently of degree up to k-1



Regression with nonlinear features

$$f(X) = \sum_{j=0}^{m} \beta_j X^j = \sum_{j=0}^{m} \beta_j \phi_j(X)$$
Weight of each feature features
$$\phi_0(X)$$

$$\phi_1(X)$$

In general, use any nonlinear features

e.g. e^X, log X, 1/X, sin(X), ...

$$\widehat{\beta} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \mathbf{Y} \qquad \mathbf{A} = \begin{bmatrix} \phi_0(X_1) \ \phi_1(X_1) \ \dots \ \phi_m(X_1) \\ \vdots \ \phi_0(X_n) \ \phi_1(X_n) \ \dots \ \phi_m(X_n) \end{bmatrix}$$

$$\widehat{f}_n(X) = \mathbf{X}\widehat{\beta}$$
 $\mathbf{X} = [\phi_0(X) \ \phi_1(X) \ \dots \ \phi_m(X)]$