#### Recap

Bayes classifier – assumes P<sub>XY</sub> known, optimal for 0/1 loss

- Gaussian Bayes classifier assumes
  - Class distribution is Bernoulli/Multinomial (1997) Class conditional distribution of features is Gaussian
- Decision boundary (binary classification)

P(X14) ~

## How many parameters do we need to learn (continuous features)?

Class distribution:

$$P(Y = y) = p_y \text{ for all y in H, M, L}$$

K-1 if K labels

$$p_H$$
,  $p_M$ ,  $p_L$  (sum to 1)

→ Class conditional distribution of features:

$$P(X=x|Y=y) \sim N(\mu_y, \Sigma_y)$$
 for each y

$$\mu_y$$
 – d-dim vector

$$\Sigma_{v}$$
 - dxd matrix

Kd + Kd(d+1)/2 = O(Kd<sup>2</sup>) if d features 
$$O(K(d+d^2))$$
  $\Sigma_y(i,j) = \Sigma_y(j,i)$ 

Quadratic in dimension d! If 
$$d = 256x256$$
 (  $d + d(d+1)$ ) pixels, ~ 13 billion parameters!

# How many parameters do we need to learn (discrete features)?

#### Class distribution:

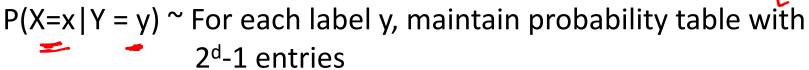
$$P(Y = y) = p_y \text{ for all y in } 0, 1, 2, ..., 9$$

$$p_0, p_1, ..., p_9$$
 (sum to 1)

K-1

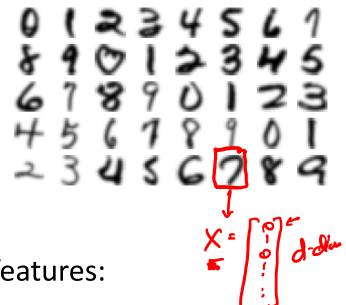
#### K-1 if K labels

Class conditional distribution of (binary) features:



K(2<sup>d</sup> − 1) if d binary features

**Exponential in dimension d!** 



### Naïve Bayes Classifier

- Bayes Classifier with additional "naïve" assumption:
  - Features are independent given class:

$$X = \begin{bmatrix} X_1 \\ X_2 \end{bmatrix}$$

$$P(X_1, X_2|Y) = P(X_1|X_2, Y)P(X_2|Y)$$

$$= P(X_1|Y)P(X_2|Y)$$

– More generally:

- More generally: 
$$P(X|Y) = P(X_1...X_d|Y) = \prod_{i=1}^d P(X_i|Y)$$
 
$$X = \begin{bmatrix} X_1 \\ X_2 \\ \cdots \\ X_d \end{bmatrix}$$

 If conditional independence assumption holds, NB is optimal classifier! But worse otherwise.

### **Conditional Independence**

X is conditionally independent of Y given Z:

probability distribution governing X is independent of the value of Y, given the value of Z

$$(\forall x, y, z) P(X = x | Y = y, Z = z) = P(X = x | Z = z)$$

Equivalent to:

$$P(X, Y \mid Z) = P(X \mid Z)P(Y \mid Z)$$

• e.g., P(Thunder|Rain, Lightning) = P(Thunder|Lightning)

Note: does NOT mean Thunder is independent of Rain

### Naïve Bayes Classifier

- Bayes Classifier with additional "naïve" assumption:
  - Features are independent given class:

$$P(X_1...X_d|Y) = \prod_{i=1}^d P(X_i|Y)$$
 
$$f_{NB}(\mathbf{x}) = \arg\max_y P(x_1, \dots, x_d \mid y) P(y)$$
 
$$= \arg\max_y \prod_{i=1}^d P(x_i|y) P(y)$$
 
$$= \arg\max_y \prod_{i=1}^d P(y) \prod_{x_i \in X_d} P(y) \prod_{x_$$

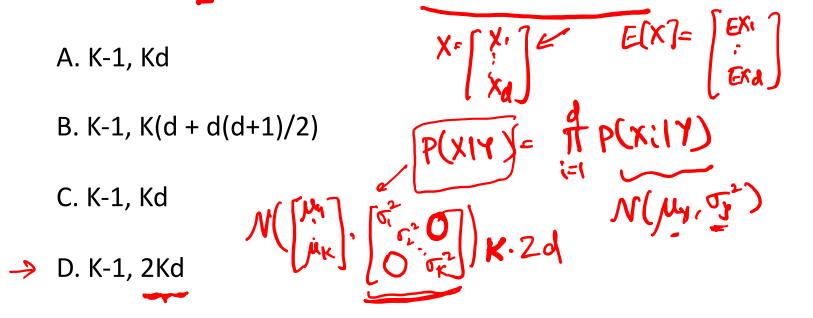
How many parameters now?

# How many parameters do we need to learn (continuous features)?



Number of parameters for class distribution P(Y=y) for K classes?

Number of parameters for Class conditional distribution of features P(X = x | Y = y) for d features (using Gaussian Naïve Bayes assumption)?



# How many parameters do we need to learn (discrete features)?

#### > Poll

D. K-1, 2Kd

Number of parameters for class distribution P(Y=y) for K classes?

Number of parameters for Class conditional distribution of features P(X = x | Y = y) for d binary features (using Naïve Bayes assumption)?

A. K-1, K2<sup>d</sup> 
$$P(x|y) = \prod_{i} P(x_i|y)$$
  $X_i \in \{0_i\}^3$   
B. K-1, K(d-1)  
C. K-1, Kd  $X_2^{d}$ 

### Naïve Bayes Classifier

- Bayes Classifier with additional "naïve" assumption:
  - Features are independent given class:

$$P(X_1...X_d|Y) = \prod_{i=1}^d P(X_i|Y)$$

$$f_{NB}(\mathbf{x}) = \arg \max_{y} P(x_1, \dots, x_d \mid y) P(y)$$

$$= \arg \max_{y} \prod_{i=1}^{d} P(x_i \mid y) P(y)$$

 Has fewer parameters, and hence requires fewer training data, even though assumption may be violated in practice

### Learned Gaussian Naïve Bayes Model Means for P(BrainActivity | WordCategory)

Pairwise classification accuracy: 85%

[Mitchell et al.03]

People words

Animal words Mariad

