

# Bayes classifier, Decision boundary

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Machine Learning 10-315

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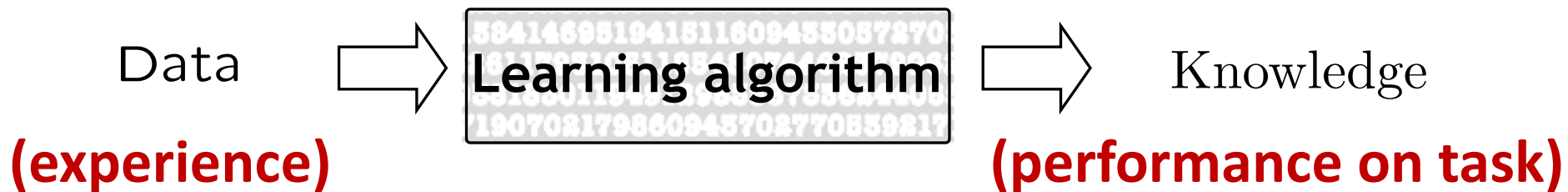
**MACHINE LEARNING** DEPARTMENT



# What is Machine Learning?

Design and Analysis of algorithms that

- improve their performance
- at some task
- with experience



# Tasks

Broad categories -

- **Supervised learning**

$$X \rightarrow Y$$

Classification, Regression

- **Unsupervised learning**

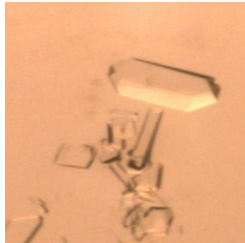
$X$

Density estimation, Clustering, Dimensionality reduction

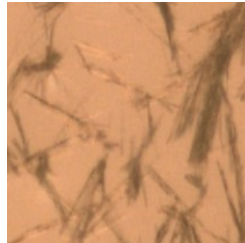
- Graphical models
- Semi-supervised learning
- Active learning
- Bayesian optimization
- Reinforcement learning
- Many more ...

# Experience

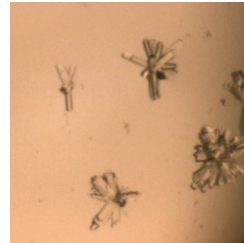
## Training data



Crystal



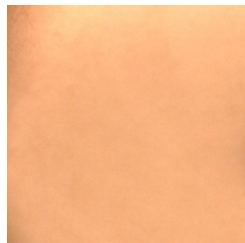
Needle



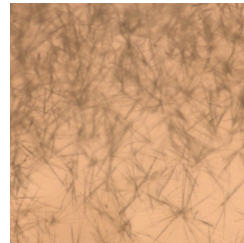
Tree



Tree

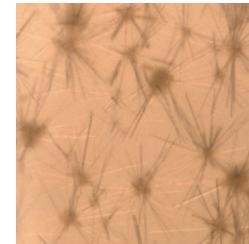


Empty



Needle

## Test data



?

A good ML algorithm

should: **generalize** <sup>↖</sup> aka perform well on test data

should not: **overfit** the training data

*gap between test & training performance*

# Performance

For test data  $X$ , measure of closeness between label  $Y$  and prediction  $f(X)$

$$f: X \rightarrow Y$$

Binary Classification  $\text{loss}(Y, \underline{f(X)}) = 1_{\{f(X) \neq Y\}}$  0/1 loss

Regression  $\text{loss}(Y, f(X)) = (f(X) - Y)^2$  squared loss  
 $|f(X) - Y|$  abs loss

We will talk about more performance measures including for unsupervised learning later in course.

Training data  $(X_i, Y_i)_{i=1}^n$

$$\frac{1}{n} \sum_{i=1}^n 1_{f(X_i) \neq Y_i}$$

## Poll

- A classifier with 100% accuracy on training data and 70% accuracy on test data is better than a classifier with 80% accuracy on training data and 80% accuracy on test data.  
A. True                      B. False
- Which classifier is better, given following statistics on test accuracy?

	Mean	Best run	<u>Std</u>
Classifier A	92%	97%	15%
Classifier B	87%	100%	5%

# Design of ML algorithms

Minimize loss in expectation (over random test data)

$$\min_f E_{X,Y}[\text{loss}(f(X), Y)]$$

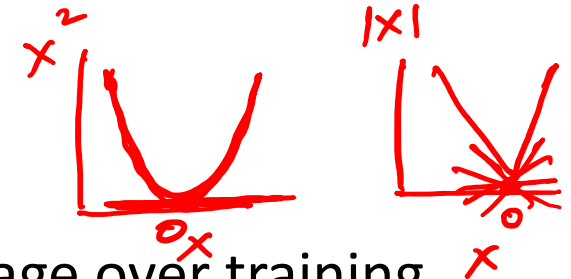
$x, y$

$$(f(x) - y)^2$$

$$\frac{\partial}{\partial f}$$

- Different methods use
  - different loss, e.g. 0/1 loss, squared loss, etc.
  - different model  $f$ , e.g. linear, neural network, decision tree etc.

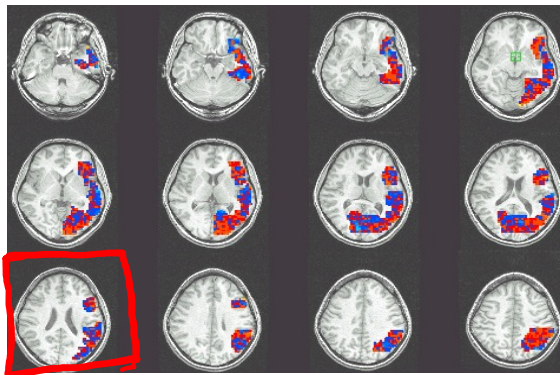
➤ Why prefer squared loss over abs loss?



- For training, replace expectation with average over training data

# Classification

Goal: Construct **prediction rule**  $f : \mathcal{X} \rightarrow \mathcal{Y}$



**Input, X**



High Stress  
Moderate Stress  
Low Stress

**Label, Y**

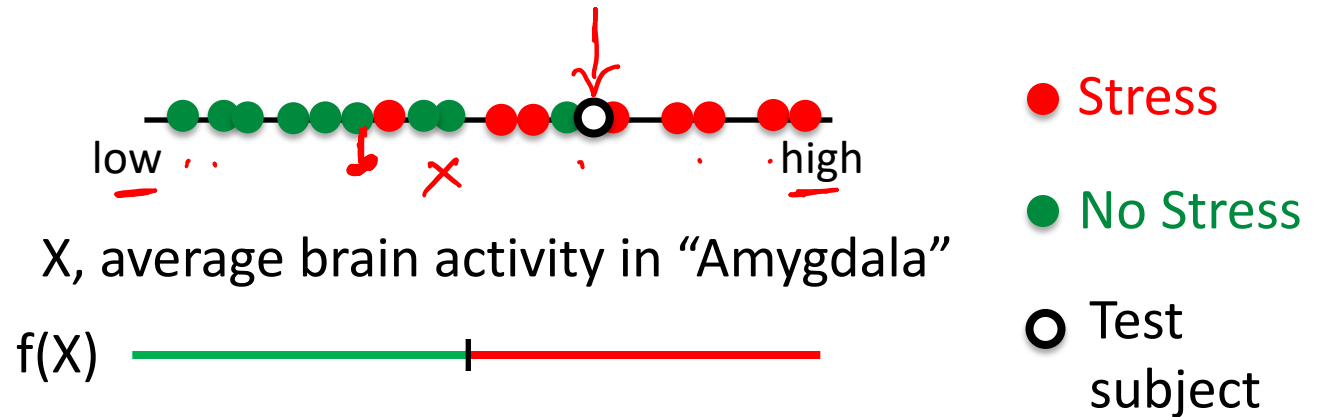
In general: label Y can belong to more than two classes  
X is multi-dimensional (brain activity in all regions)

But let's start with a simple case:

label Y is binary (either "Stress" or "No Stress")  
X is average brain activity in the "Amygdala"



# Binary Classification



Model X and Y as random variables with joint distribution  $P_{XY}$  *unknown*

Training data  $\{X_i, Y_i\}_{i=1}^n \sim \text{iid}$  (independent and identically distributed)  
samples from  $P_{XY}$

→ Test data  $\{X, Y\} \sim \text{iid}$  sample from  $P_{XY}$

Training and test data are independent draws from same distribution

# Optimal classifier

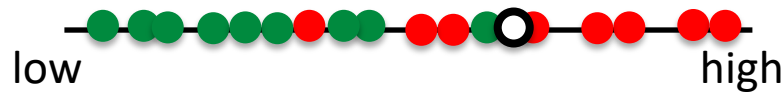
Minimize loss in expectation (over random test data)

$$\min_f E_{XY}[\text{loss}(f(X), Y)]$$

- Which classifier  $f$  is optimal for 0/1 loss, assuming we know data-generating distribution  $P(X, Y)$ ?

$$\{X_i, Y_i\}_{i=1}^n$$

# Bayes Classifier



X, average brain activity in "Amygdala"

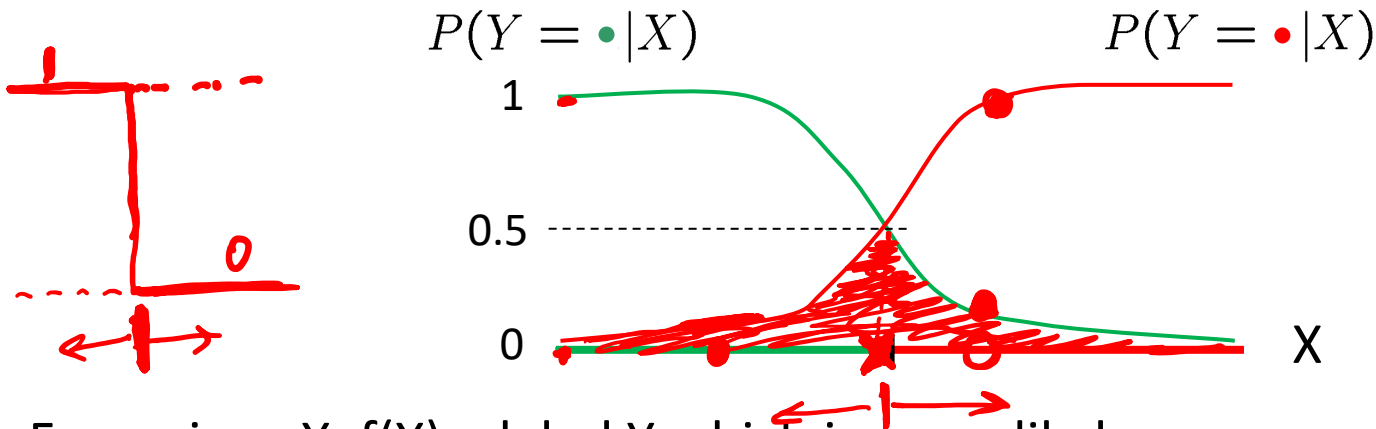


● Stress

● No Stress

○ Test subject

Model X and Y as random variables



For a given X,  $f(X)$  = label Y which is more likely

$$\underline{f(X)} = \arg \max_{Y=y} P(Y = y | X = \underline{x})$$

$$\arg \max_y \underline{P(Y=y|X=x)}$$

# Bayes Rule

**Bayes Rule:**  $\underline{P(Y|X)} = \frac{\underline{P(X|Y)P(Y)}}{P(X)}$  ←

$$P(Y = y|X = x) = \frac{P(X = x|Y = y)P(Y = y)}{P(X = x)}$$

To see this, recall:

$$\rightarrow P(X,Y) = P(X|Y) \underline{P(Y)} \quad \text{chain rule}$$

$$\rightarrow P(Y,X) = P(Y|X) P(X)$$



Thomas Bayes

# Bayes Classifier – equivalent form

**Bayes Rule:**  $P(Y|X) = \frac{P(X|Y)P(Y)}{P(X)}$

$$P(Y = y|X = x) = \frac{P(X = x|Y = y)P(Y = y)}{P(X = x)}$$

**Bayes classifier:**

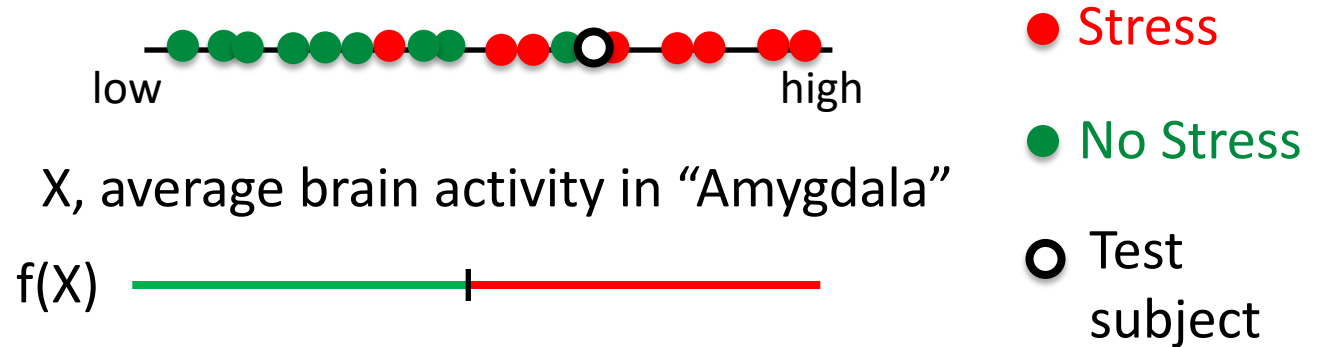
$$f(X) = \arg \max_{Y=y} P(Y = y|X = x)$$

$$= \arg \max_{Y=y} \underbrace{P(X = x|Y = y)}_{\text{Class conditional Distribution of inputs}} \underbrace{P(Y = y)}_{\text{Distribution of class}}$$

Class conditional  
Distribution of inputs

Distribution of class

# Bayes Classifier



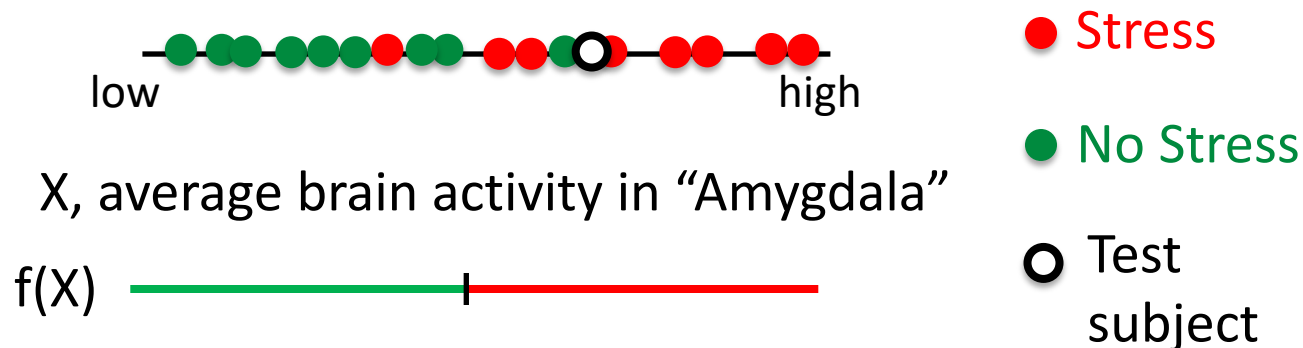
$$f(X) = \arg \max_{Y=y} \underbrace{P(X = x|Y = y)}_{\text{Class conditional Distribution of inputs}} \underbrace{P(Y = y)}_{\text{Class distribution}}$$

We can now consider appropriate models for the two terms:

→ Class distribution  $P(Y=y)$

→ Class conditional distribution of inputs  $P(X=x|Y=y)$

# Modeling class distribution



Modeling Class distribution  $P(Y=y) = \text{Bernoulli}(\theta)$

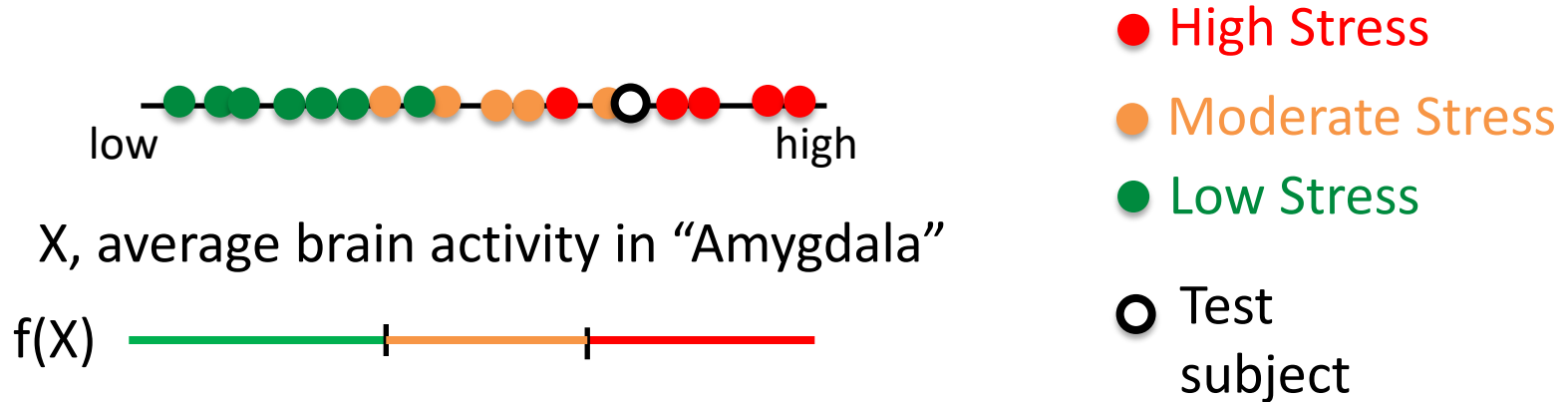
$$P(Y = \bullet) = \theta$$

$$P(Y = \bullet) = 1 - \theta$$

Like a coin flip



# Modeling class distribution



➤ How do we model multiple (>2) classes?

Modeling Class distribution  $P(Y) = \text{Categorical}(p_H, p_M, p_L)$

$$P(Y = \text{red}) = p_H \quad P(Y = \text{orange}) = p_M \quad P(Y = \text{green}) = p_L$$

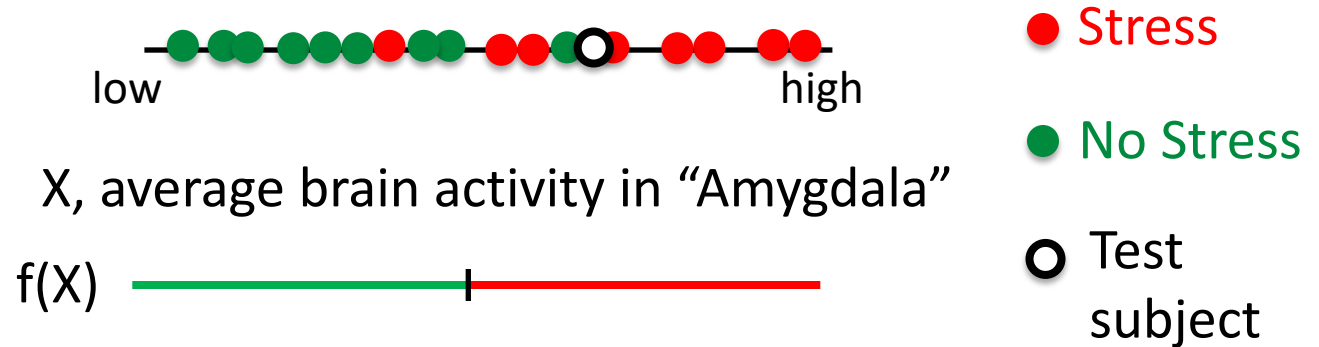
Like a dice roll



$$\underline{p_H + p_M + p_L = 1}$$



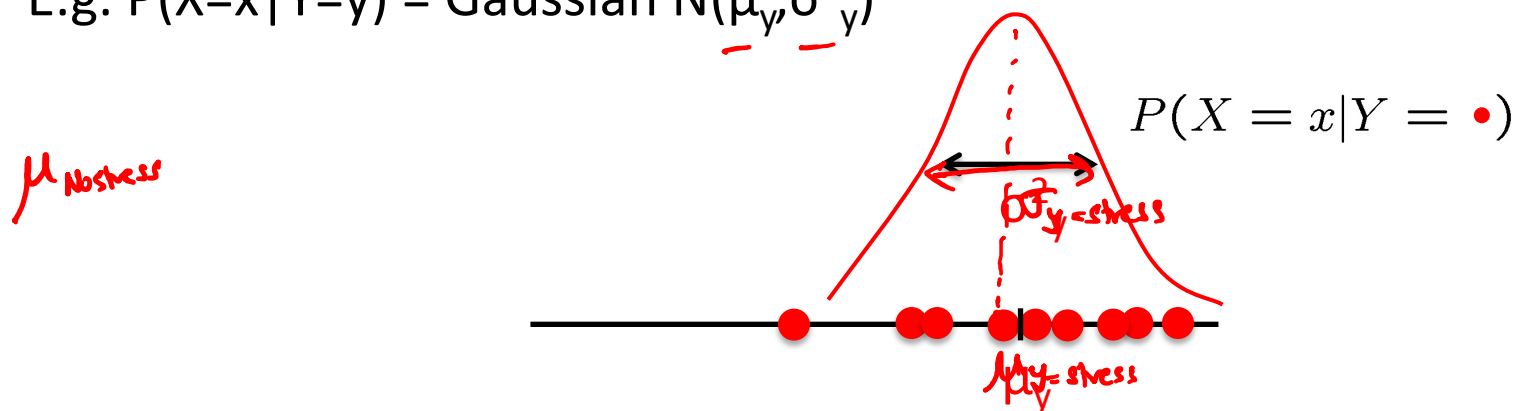
# Modeling class conditional distribution of inputs



Modeling class conditional distribution of input  $P(X=x|Y=y)$

➤ What distribution would you use?

E.g.  $P(X=x|Y=y) = \text{Gaussian } N(\mu_y, \sigma_y^2)$

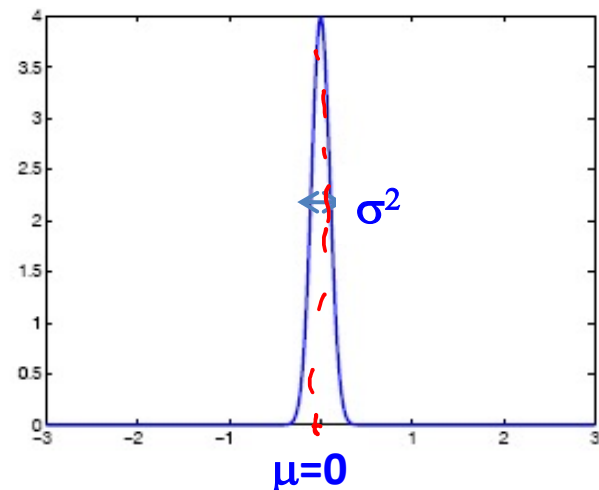
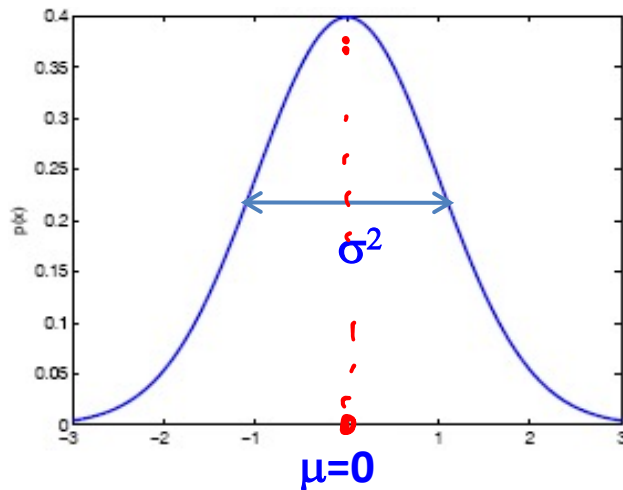


# 1-dim Gaussian distribution

X is Gaussian  $N(\mu, \sigma^2)$

$$\begin{aligned}\mu &= E[X] \\ \sigma^2 &= E[(X - E[X])^2]\end{aligned}$$

$$P(X = x | \mu, \sigma) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \quad \leftarrow$$



# 1-dim Gaussian Bayes classifier

$$\underline{f(X)} = \arg \max_{Y=y} \underbrace{P(X = x|Y = y)}_{\text{Class conditional Distribution of inputs}} \underbrace{P(Y = y)}_{\text{Class distribution}}$$

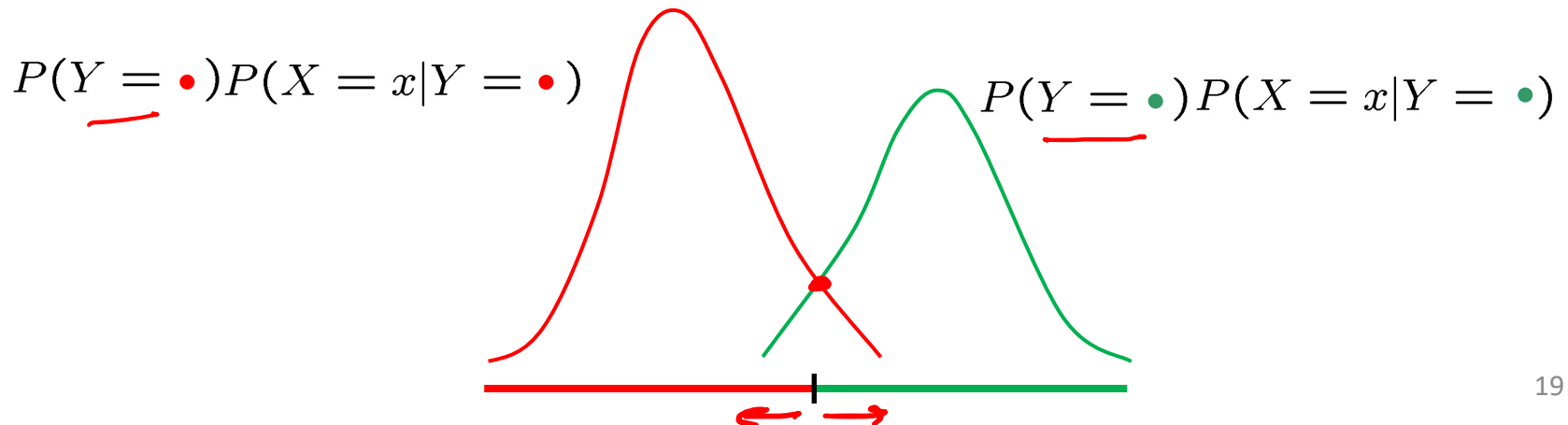
Learn parameters  $\theta$ ,  $\mu_y$ ,  $\sigma_y$  from data

Class conditional  
Distribution of inputs

Class distribution

Gaussian( $\mu_y$ ,  $\sigma_y^2$ )

Bernoulli( $\theta$ )



# Poll

- Is the Gaussian Bayes Classifier optimal under 0/1 loss?  
A. True                      B. False

$P_{XY}$  → Bayes optimal classifier  $\arg \max_y P(Y|X)$   
 $= \arg \max_y P(X|y) P(y)$

No stress      Stress      No stress  
x x x x x      x x x x x      x x x x x

# 1-dim Gaussian Bayes classifier

$$f(X) = \arg \max_{Y=y} \underbrace{P(X = x|Y = y)}_{\text{Class conditional Distribution of inputs}} \underbrace{P(Y = y)}_{\text{Class distribution}}$$

Class conditional

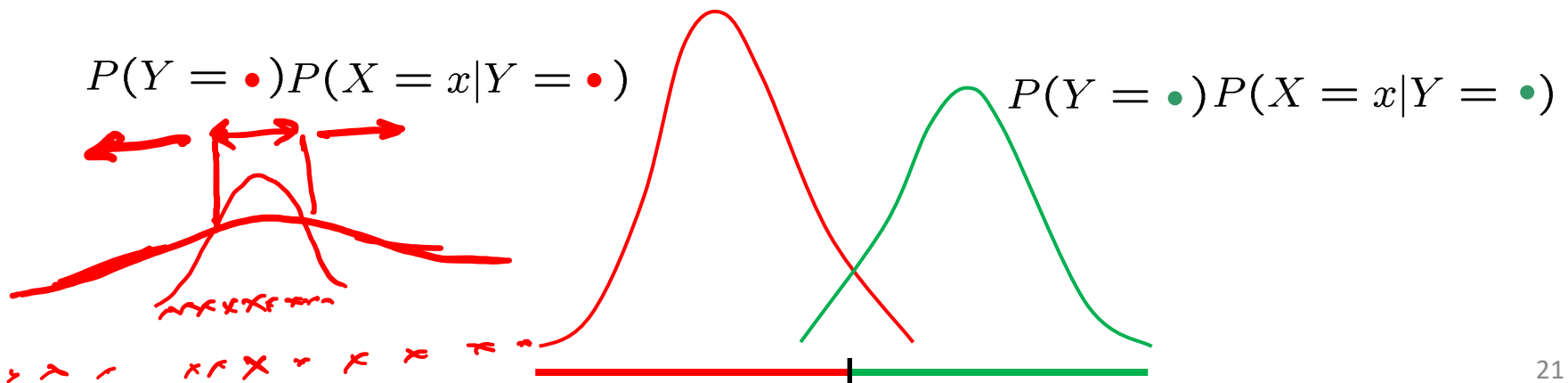
Distribution of inputs

Class distribution

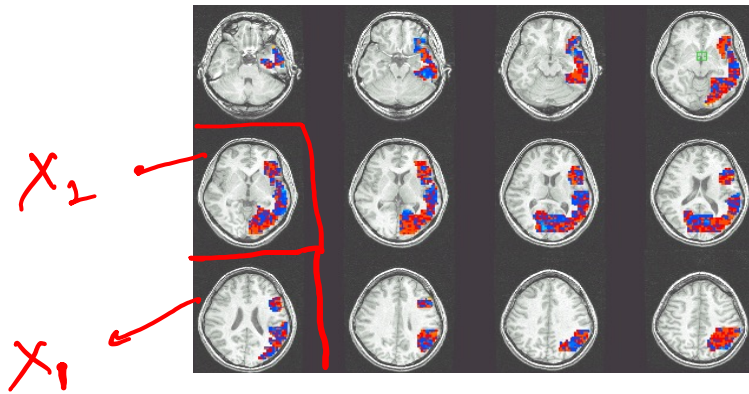
➤ What decision boundaries can we get in 1-dim?

Gaussian( $\mu_y, \sigma_y^2$ )

Bernoulli( $\theta$ )



# d-dimensional inputs



## Input feature vector, X



High Stress  
Moderate Stress  
Low Stress

**Label, Y**

$$X_1 = \begin{bmatrix} 0.05 \\ -0.06 \\ 0.1 \\ 0.3 \\ -0.1 \\ \vdots \end{bmatrix}$$

## Modeling class conditional distribution of input $P(X=x|Y=y)$

➤ What distribution would you use?

E.g.  $P(X=x|Y=y) = \text{Gaussian } N(\mu_y, \Sigma_y)$

$$\mu_y = \int x f(x) dx$$

$$\Sigma_y = \begin{bmatrix} \boxed{\phantom{0}} & \boxed{\phantom{0}} & \boxed{\phantom{0}} & \boxed{\phantom{0}} & \boxed{\phantom{0}} \\ & \boxed{\phantom{0}} & \boxed{\phantom{0}} & \boxed{\phantom{0}} & \boxed{\phantom{0}} \\ & & \boxed{\phantom{0}} & \boxed{\phantom{0}} & \boxed{\phantom{0}} \\ & & & \boxed{\phantom{0}} & \boxed{\phantom{0}} \\ & & & & \boxed{\phantom{0}} \end{bmatrix}^1$$

# d-dim Gaussian distribution

$$\mu = E[X] \quad \Sigma_{ij} = E[(X_{(i)} - EX_{(i)})(X_{(j)} - EX_{(j)})] \leftarrow$$

X is Gaussian  $N(\mu, \Sigma)$

$\mu$  is d-dim vector,  $\Sigma$  is dxd dim matrix

$$\Sigma_{ii} = E[(X_{(i)} - EX_{(i)})^2] \leftarrow \text{var}(X_{(i)})$$

$$P(X = x | \mu, \Sigma) = \frac{1}{\sqrt{(2\pi)^d |\Sigma|}} \exp \left( -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right),$$

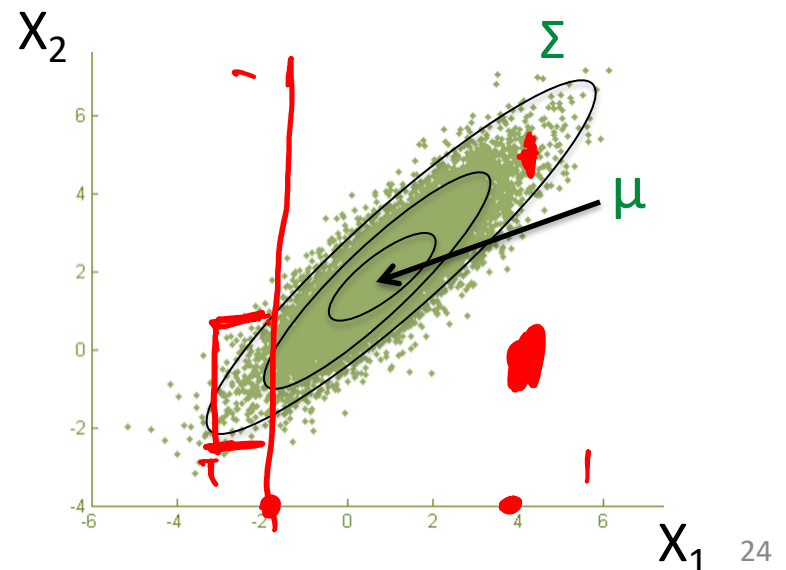
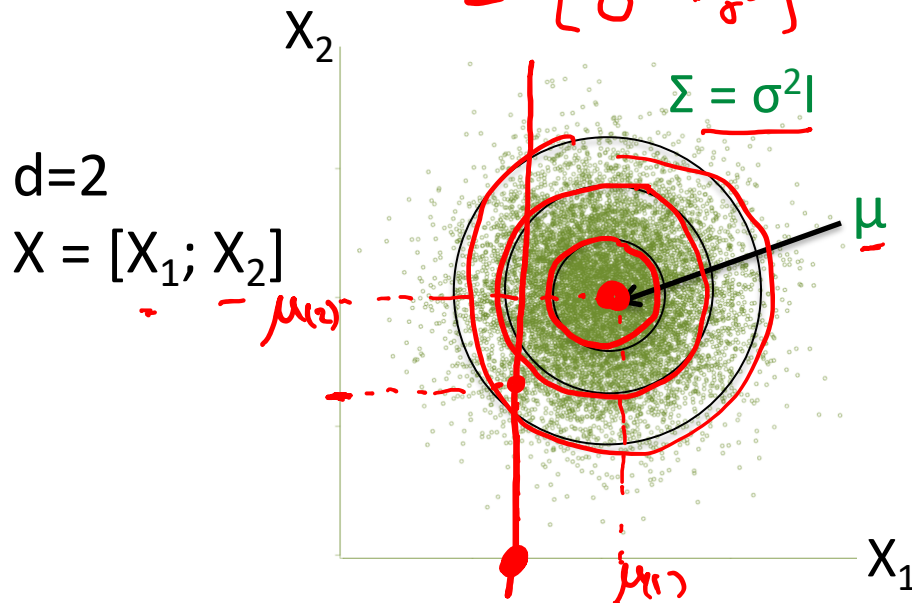
# d-dim Gaussian distribution

$X$  is Gaussian  $N(\mu, \Sigma)$

$\mu$  is d-dim vector,  $\Sigma$  is dxd dim matrix

$$P(X = x | \mu, \Sigma) = \frac{1}{\sqrt{(2\pi)^d |\Sigma|}} \exp \left( -\frac{1}{2} (\mathbf{x} - \underline{\mu})^T \Sigma^{-1} (\mathbf{x} - \underline{\mu}) \right),$$

$$\Sigma = \begin{bmatrix} \sigma^2 & 0 & \dots & 0 \\ 0 & \sigma^2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma^2 \end{bmatrix}$$





# d-dim Gaussian Bayes classifier

$$f(X) = \arg \max_{Y=y} \underbrace{P(X = x|Y = y)}_{\text{Class conditional Distribution of inputs}} \underbrace{P(Y = y)}_{\text{Class distribution}}$$

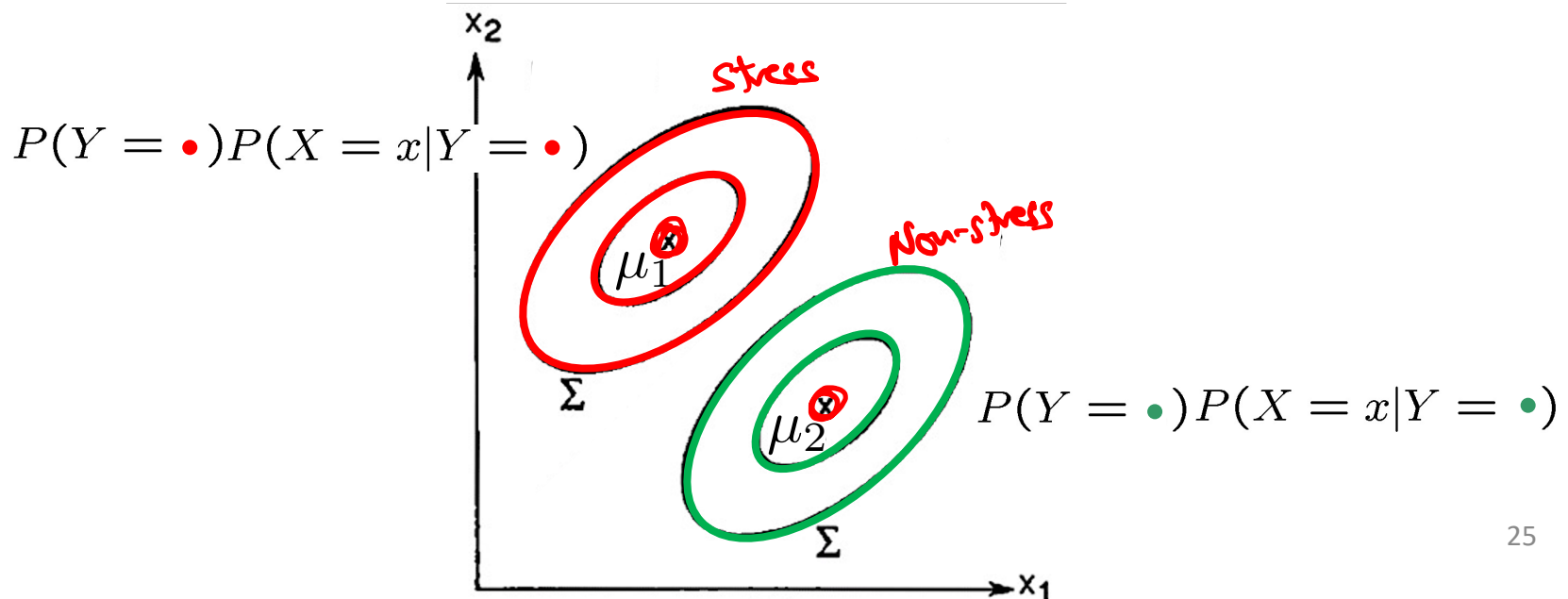
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Class conditional  
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# d-dim Gaussian Bayes classifier

$$f(X) = \arg \max_{Y=y} \underbrace{P(X = x|Y = y)}_{\text{Class conditional}} \underbrace{P(Y = y)}_{\text{Class distribution}}$$

➤ What decision boundaries can we get in d-dim?

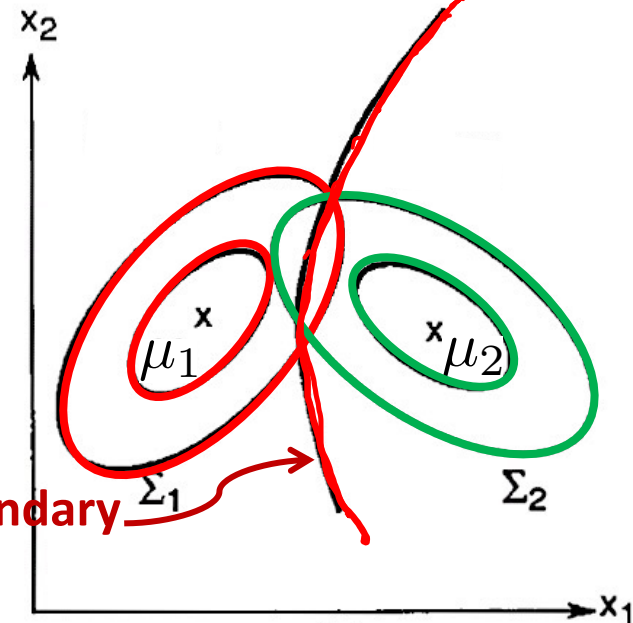
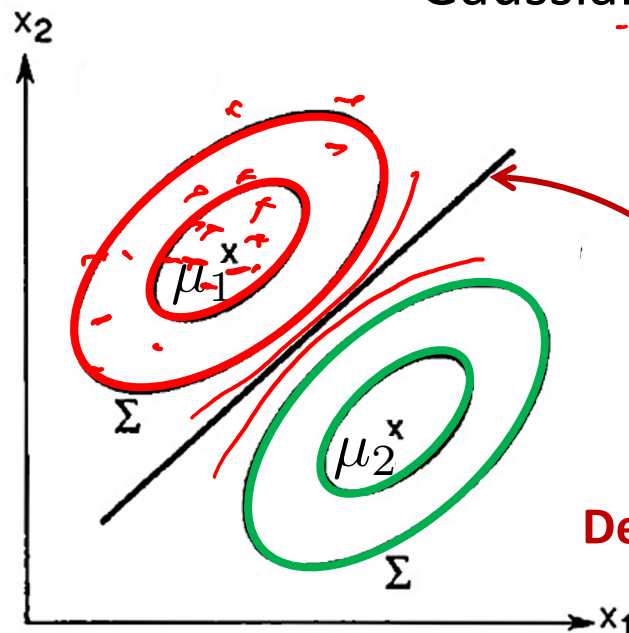
Class conditional

Distribution of inputs

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Gaussian( $\mu_y, \Sigma_y$ )

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Decision Boundary