

# Coding and Modulation in Cameras

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Mitsubishi Electric Research Labs (MERL)  
Cambridge, MA, USA



# Schedule

Introduction	Srinivasa, 10 mins
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Assorted Pixels	Srinivasa, 20 mins
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Coding and Modulation in Cameras	Amit, 45 mins
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Break	10 min
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Light Fields and Applications	Ankit, 60 mins
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Break	10 min
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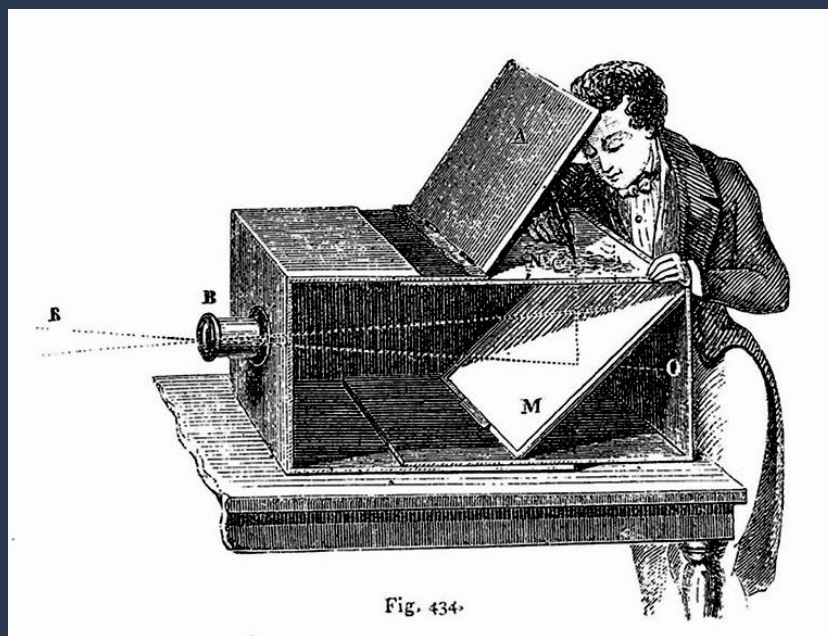
Computational Illumination	Srinivasa, 45 mins
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Future Trends	Amit, 15 mins
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Discussion	
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# Have Cameras Evolved?



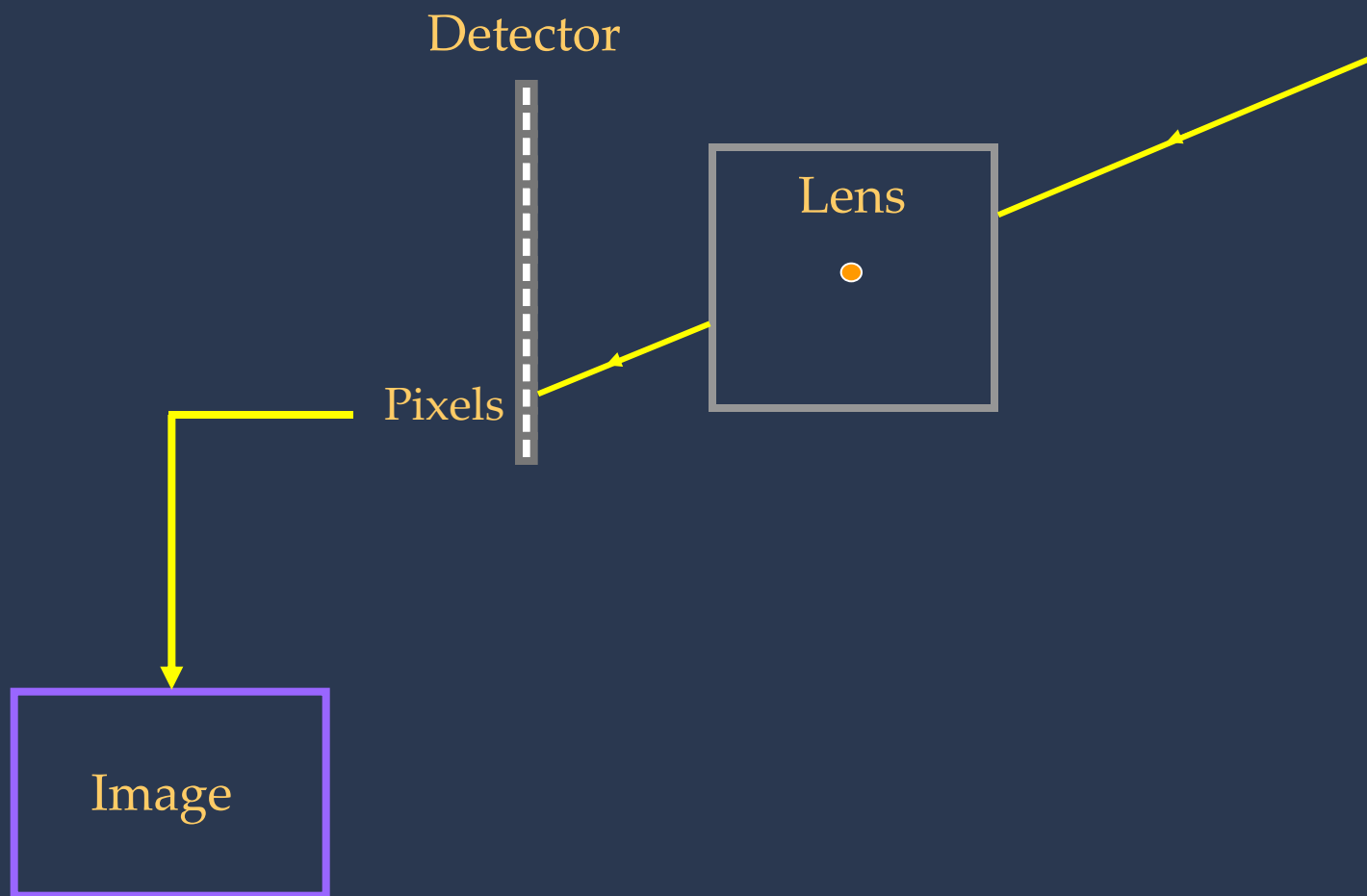
Lens Based Camera Obscura, 1568



Digital Cameras

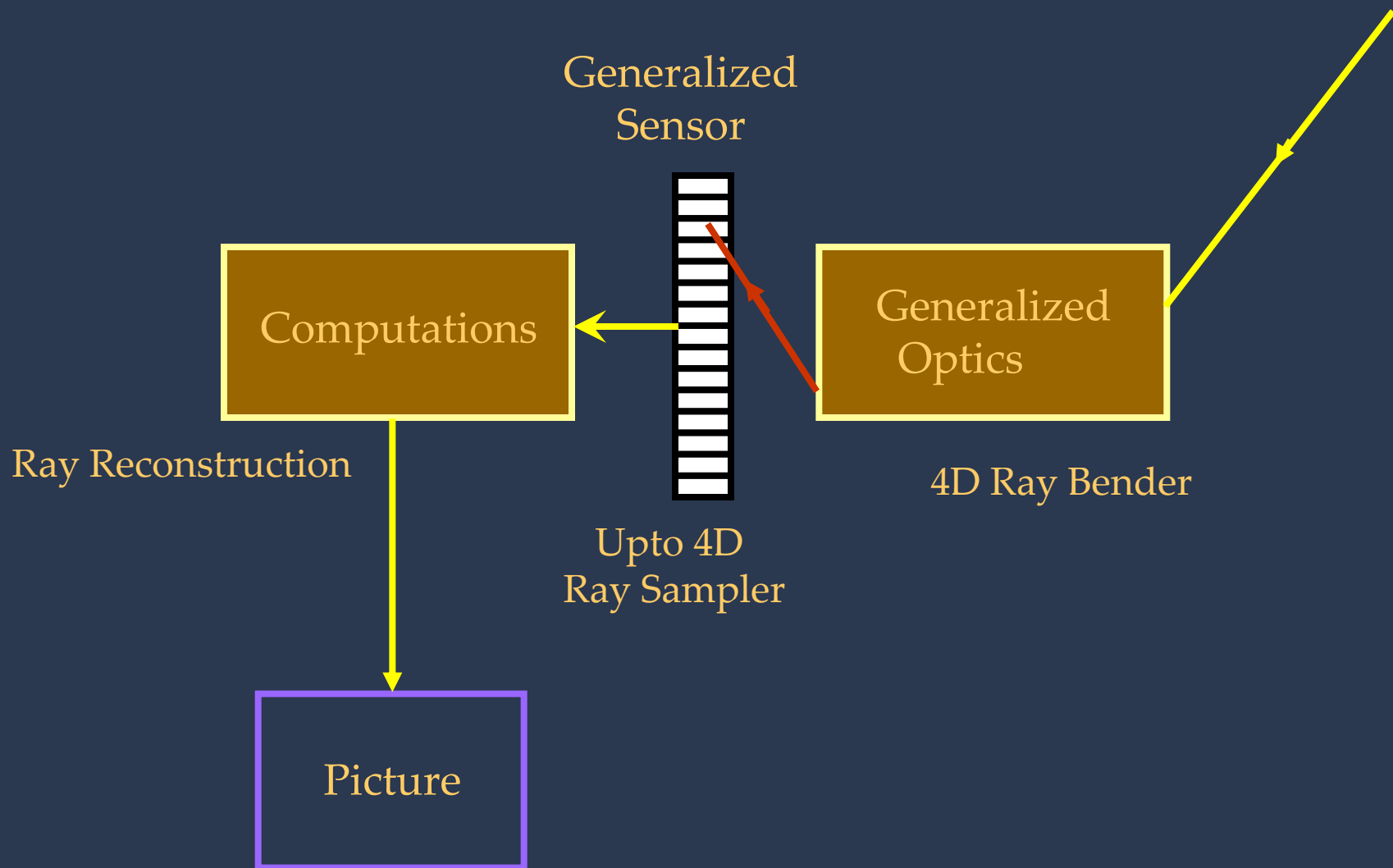


# Traditional Photography





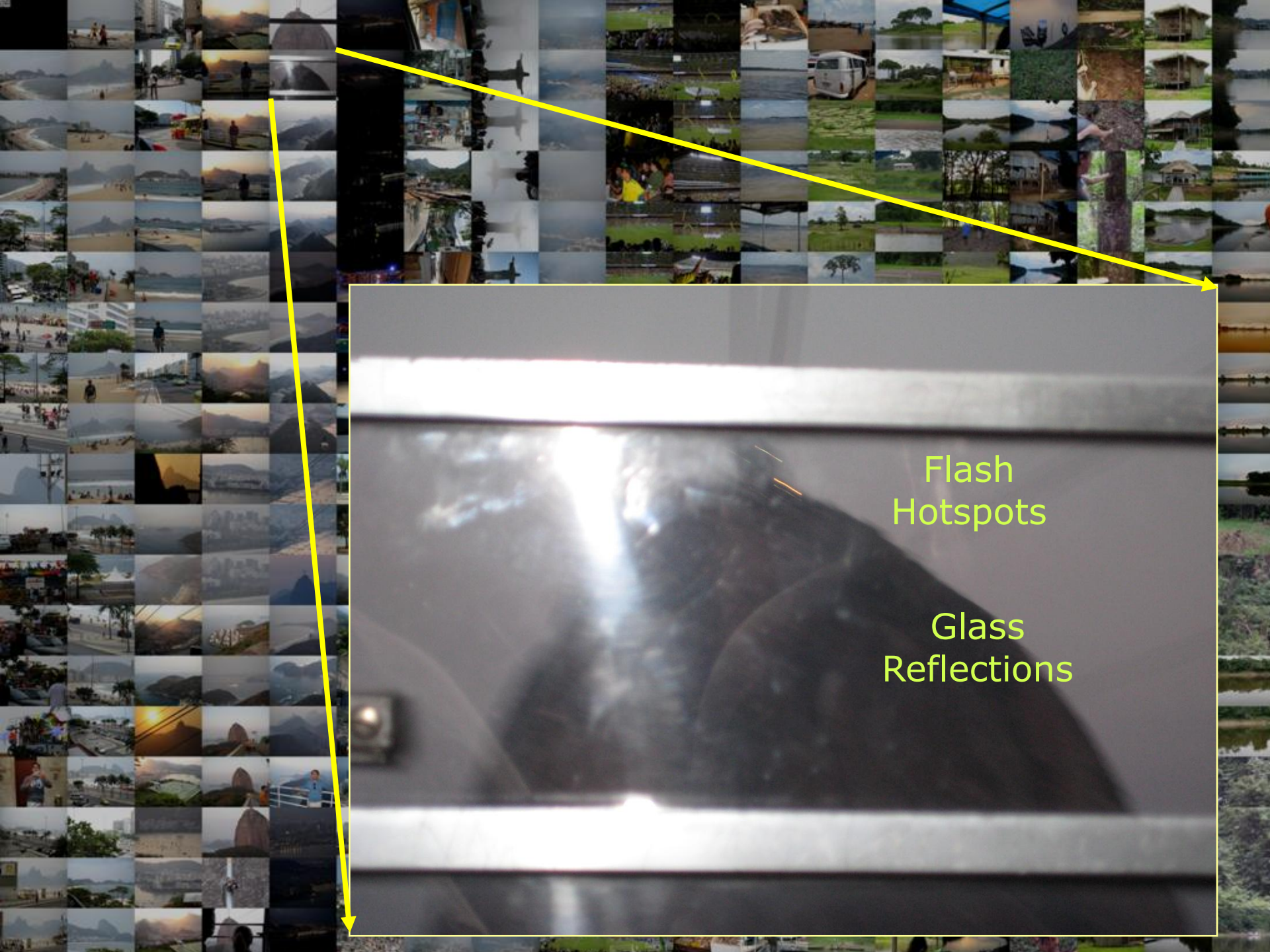
# Computational Imaging: Optics, Sensors and Computations











Flash  
Hotspots

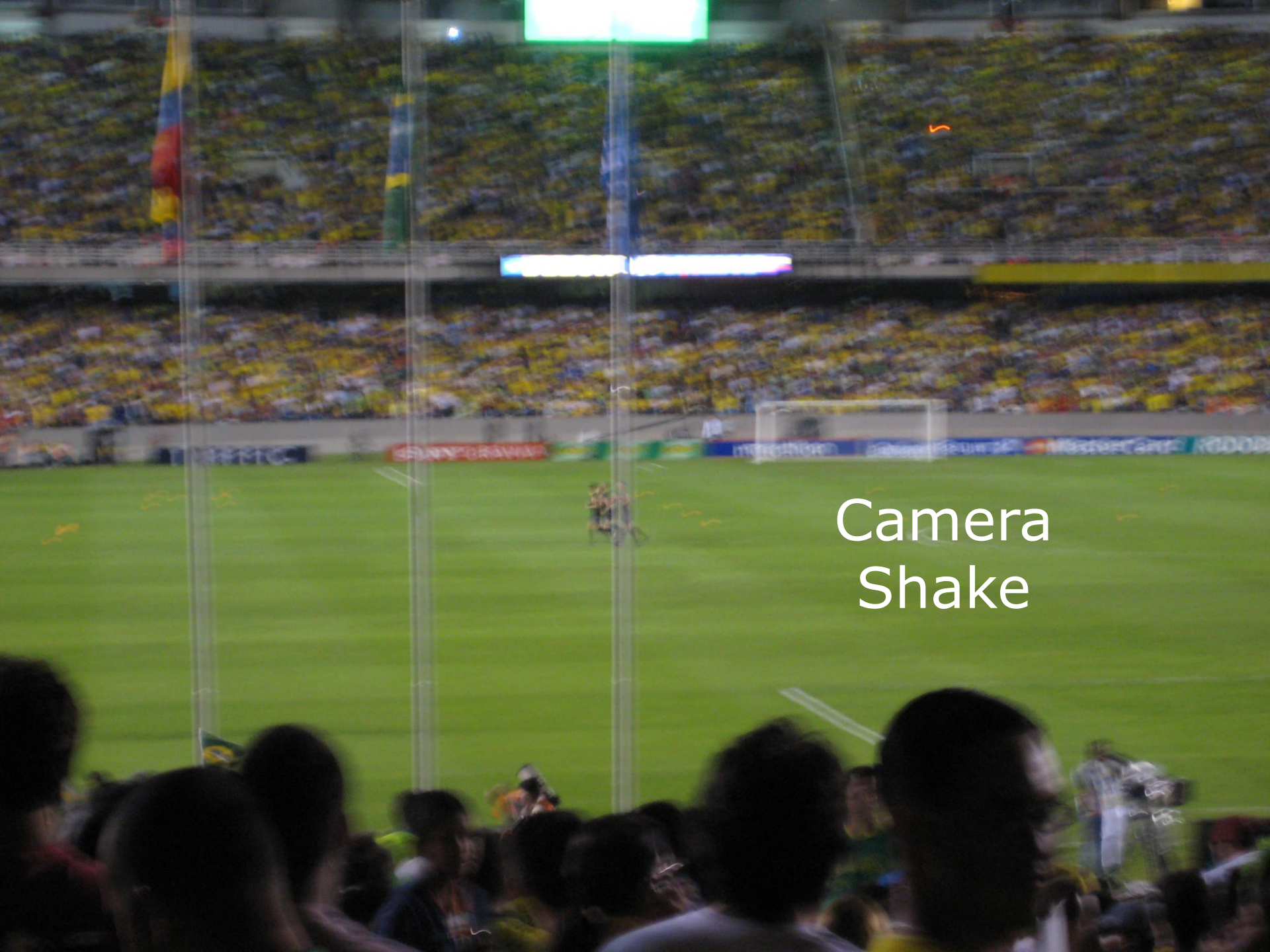
Glass  
Reflections





Motion  
Blur





Camera  
Shake





High Dynamic  
Range



Out of  
Focus







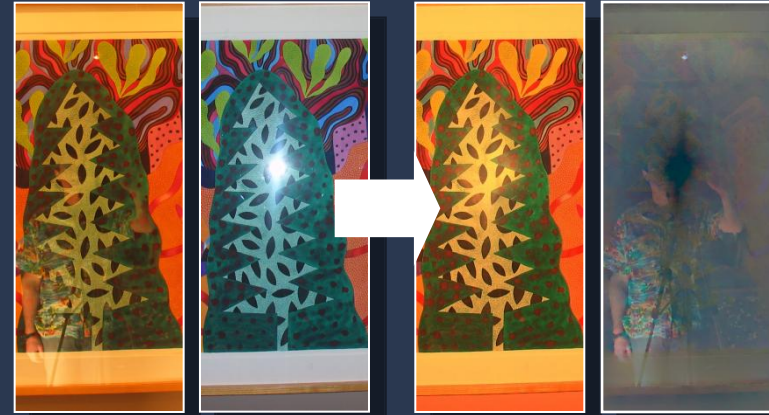
Fog, Haze,  
Bad  
Weather



# Computational Imaging

- Photo Manipulations

- Two photos are better than one!!
- Combine two+ photos
- Change camera parameters



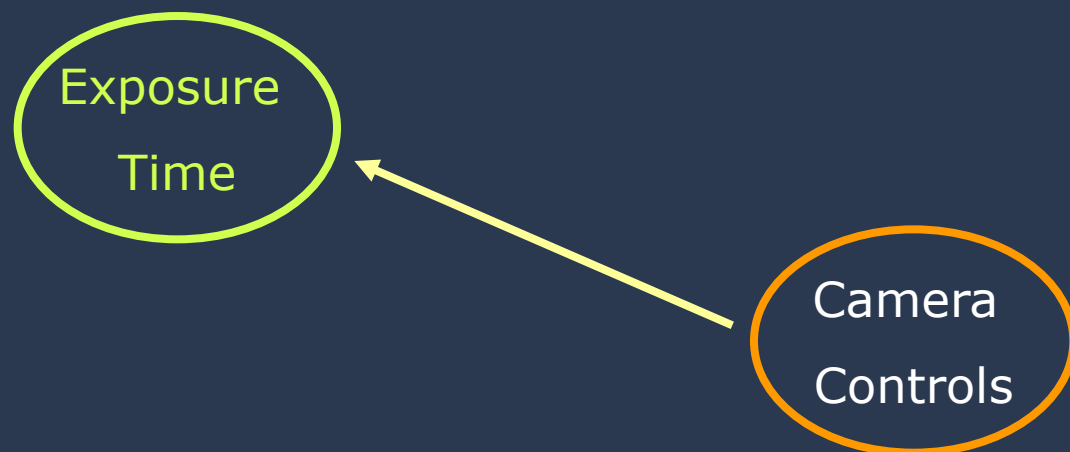
- Coding and Modulation

- Capture relevant information
- Decode in software





# Two photos are better than one







# Changing Exposure Time

- High dynamic range imaging
  - Mann and Picard, 95
  - Devebec and Malik, 97



Photo 1



Photo 2



Photo 3





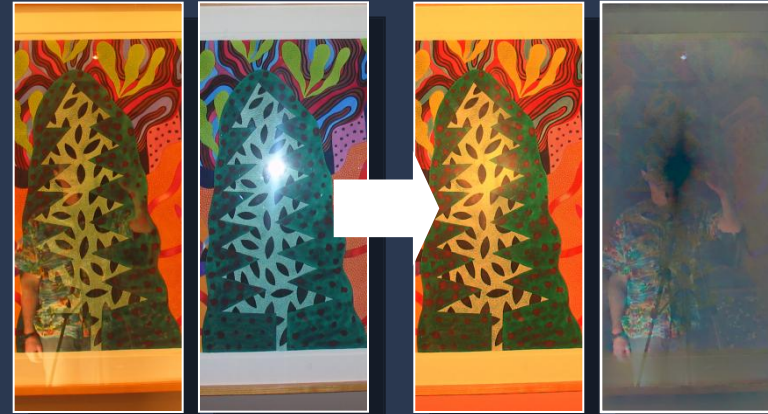
# Epsilon Photography

- Dynamic Range
  - Multiple exposures
- Noise Reduction
  - Flash/No-flash images, Multiple Images
- Motion Blur
  - Short + Long exposure
- Focus Blur
  - Focal Stack (Images focused at different depths)
- Spectrum
  - Visible + Near-IR
- Field of View
  - Panoramas
- Resolution
  - Multi-image super-resolution methods

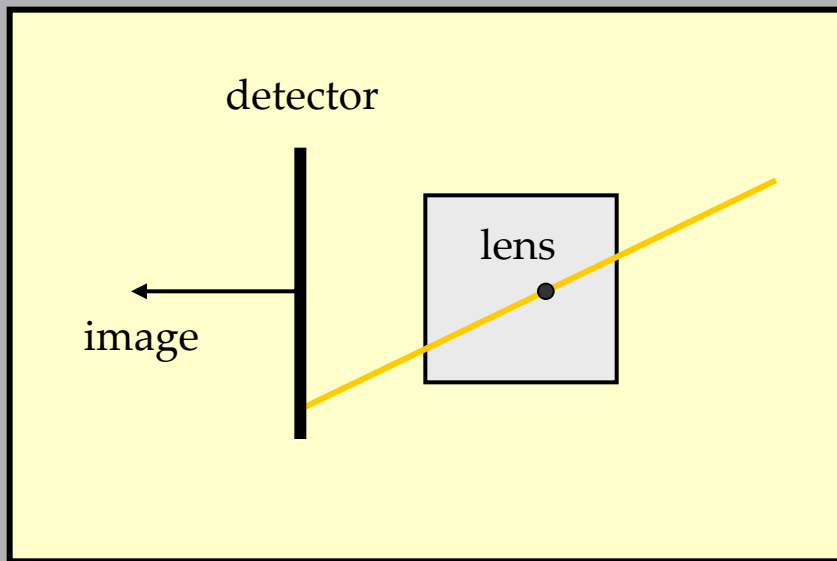


# Computational Imaging

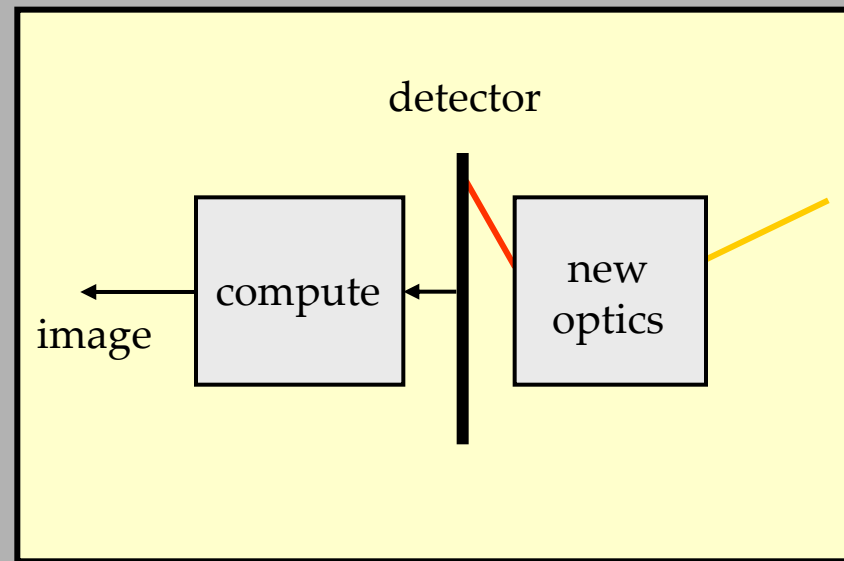
- Photo Manipulations
  - Two photos are better than one!!
  - Combine two+ photos
  - Change camera parameters
- Coding and Modulation
  - Capture relevant information
  - Decode in software







Traditional Camera



Computational Camera



# Computational Cameras

- Adaptive Dynamic Range Imaging, Nayar & Branzoi, ICCV 2003
- Omnidirectional Cameras, Gluckman & Nayar, ICCV 98
- Folded Catadioptric Cameras, Nayar & Peri, CVPR 99
- Catadioptric Imaging, Nayar 88
- Flexible Field of View, Kuthirummal & Nayar, 07
- Cata-Fisheye Camera for Panoramic Imaging, Krishnan & Nayar, 08
- Generalized Mosaicing, Schechner & Nayar, ICCV 01
- Motion Deblurring using Hybrid Imaging, Ben-Ezra & Nayar
- Jitter Camera, Ben-Ezra et al CVPR 04
- Programmable Imaging, Nayar et al 2004
- Single Lens Depth Camera, Gao & Ahuja, 2006
- Omnidirectional Stereo Vision System, Yi and Ahuja, 06
- Omnifocus Nonfrontal Imaging Camera, Aggarwal et al
- Split Aperture Imaging, Aggarwal and Ahuja, 2001
- Plenoptic Cameras, Adelson & Wang, Ng et al., Stanford
- Multi-Aperture Photography, Green et al. SIGGRAPH 07
- Coded Apertures, Wavefront Coding (CDM Optics)
- Assorted Pixels, Narasimhan & Nayar





# Coded Exposure [Raskar, Agrawal, Tumblin SIGGRAPH 2006]





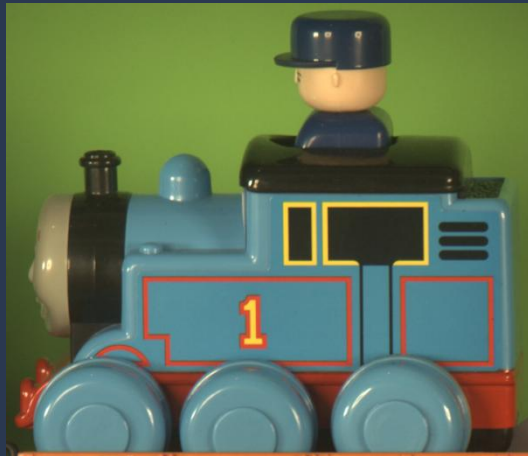
## Coded Exposure (Flutter Shutter) Camera

Raskar, Agrawal, Tumblin [Siggraph2006]

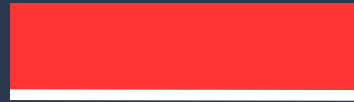


Coding in Time: Shutter is opened and closed

# Blurring == Convolution



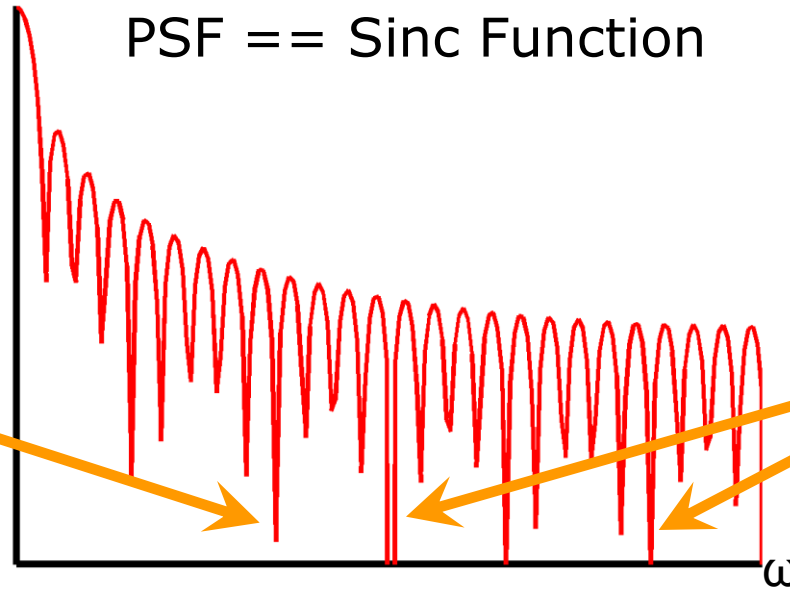
Sharp Photo



Blurred Photo

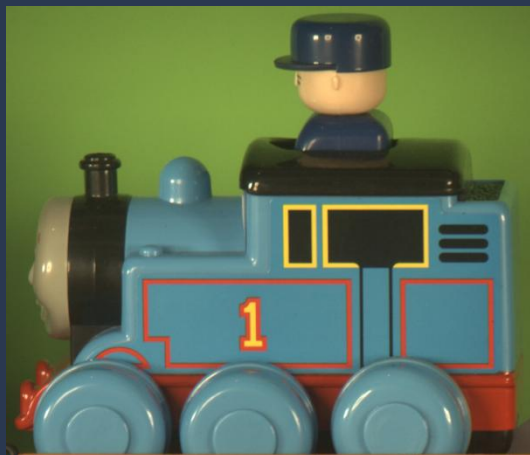


PSF == Sinc Function

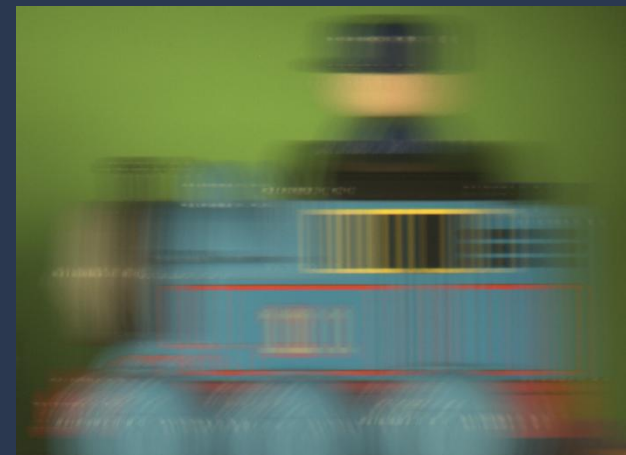
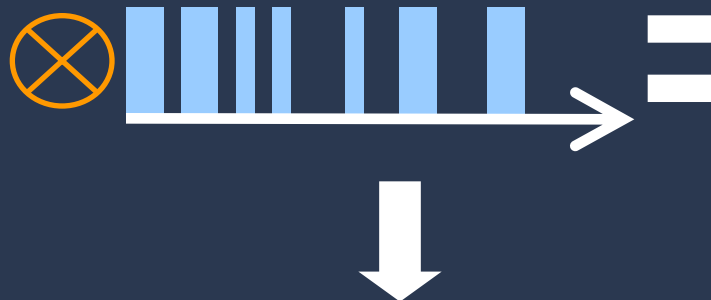


Traditional Camera: Shutter is OPEN: Box Filter

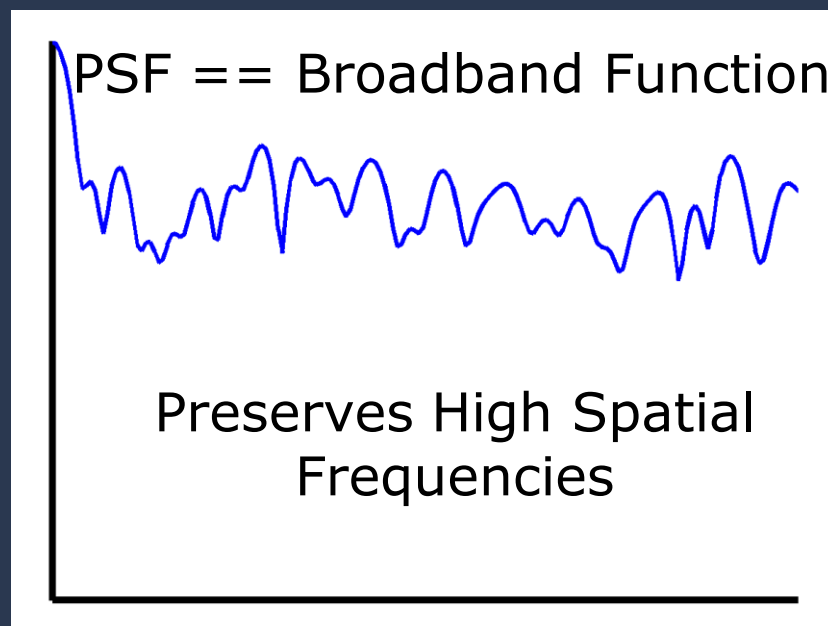




Sharp Photo

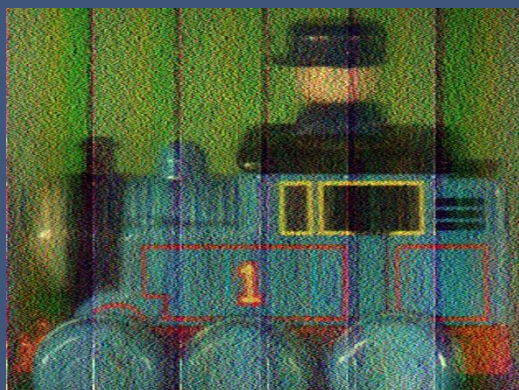
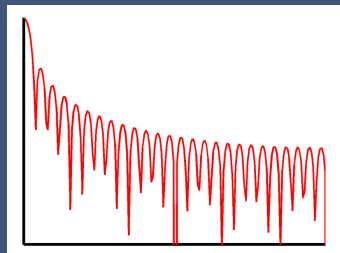


Blurred Photo



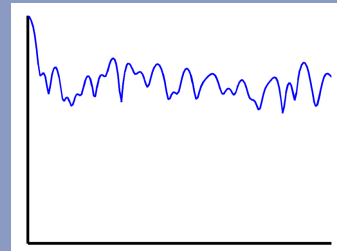
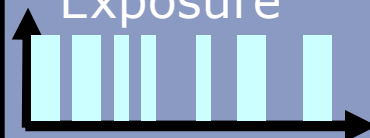
Flutter Shutter: Shutter is OPEN and CLOSED

Traditional



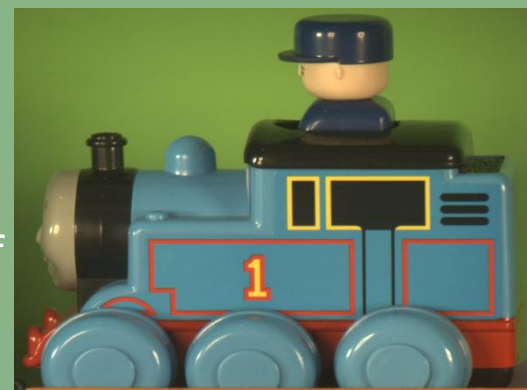
Deblurred  
Image

Coded  
Exposure



Deblurred  
Image

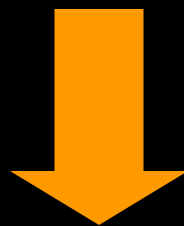
Image of  
Static  
Object











# Coded Exposure (Flutter Shutter) Camera



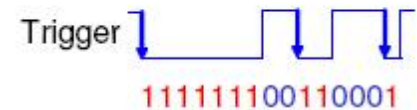
Raskar, Agrawal, Tumblin [Siggraph2006]



External Shutter  
with SLR Camera



Coded exposure camera



PointGrey Camera  
No additional Cost

Coding in Time: Shutter is opened and closed

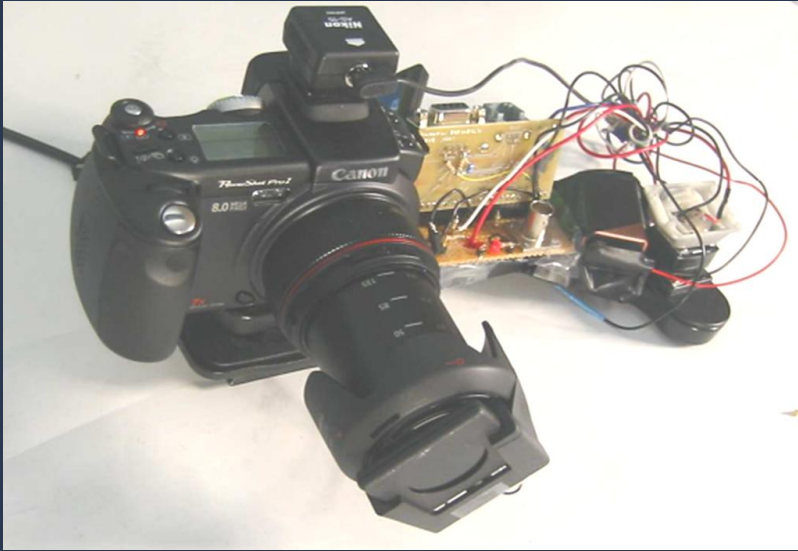


**How to handle  
focus blur?**



## Coded Exposure (Flutter Shutter)

Raskar, Agrawal, Tumblin  
SIGGRAPH 2006



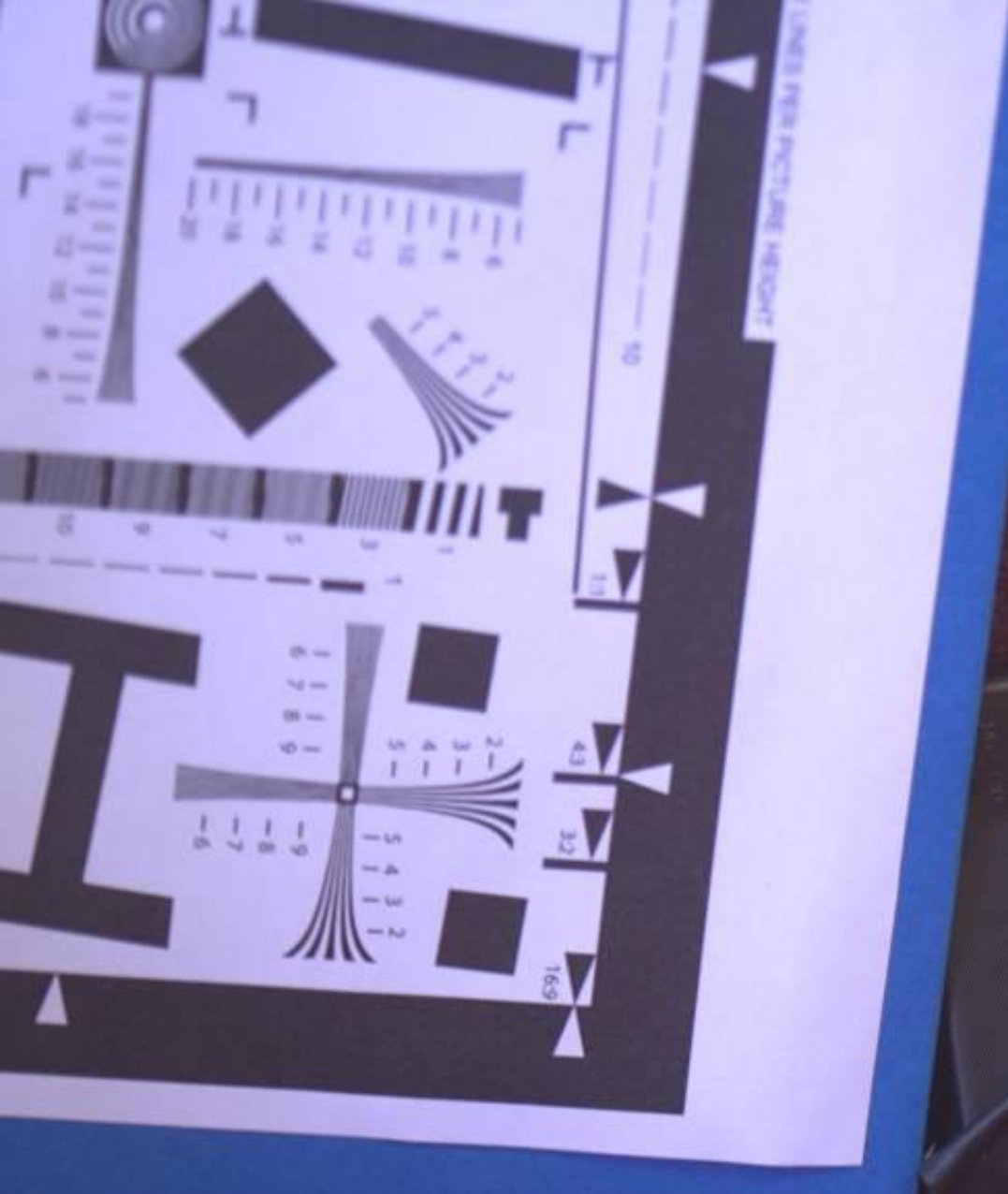
Temporal 1-D broadband code:  
**Motion** Deblurring

## Coded Aperture

with Veeraraghavan, Raskar, Tumblin, & Mohan,  
SIGGRAPH 2007



Spatial 2-D broadband code:  
**Focus** Deblurring



In Focus Photo



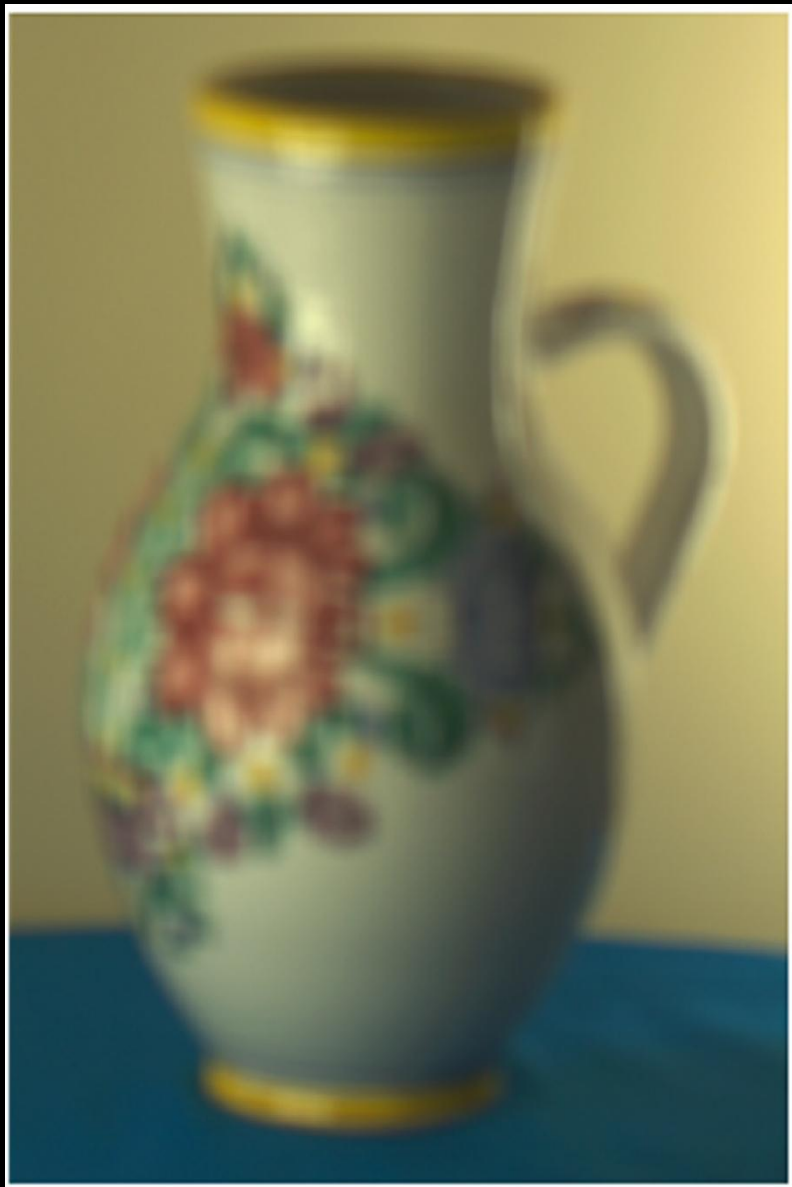


Out of Focus Photo: Open Aperture



Out of Focus Photo: Coded Aperture

# Blurred Photos



Open Aperture



Coded Aperture,  $7 \times 7$  Mask



# Deblurred Photos



Open Aperture

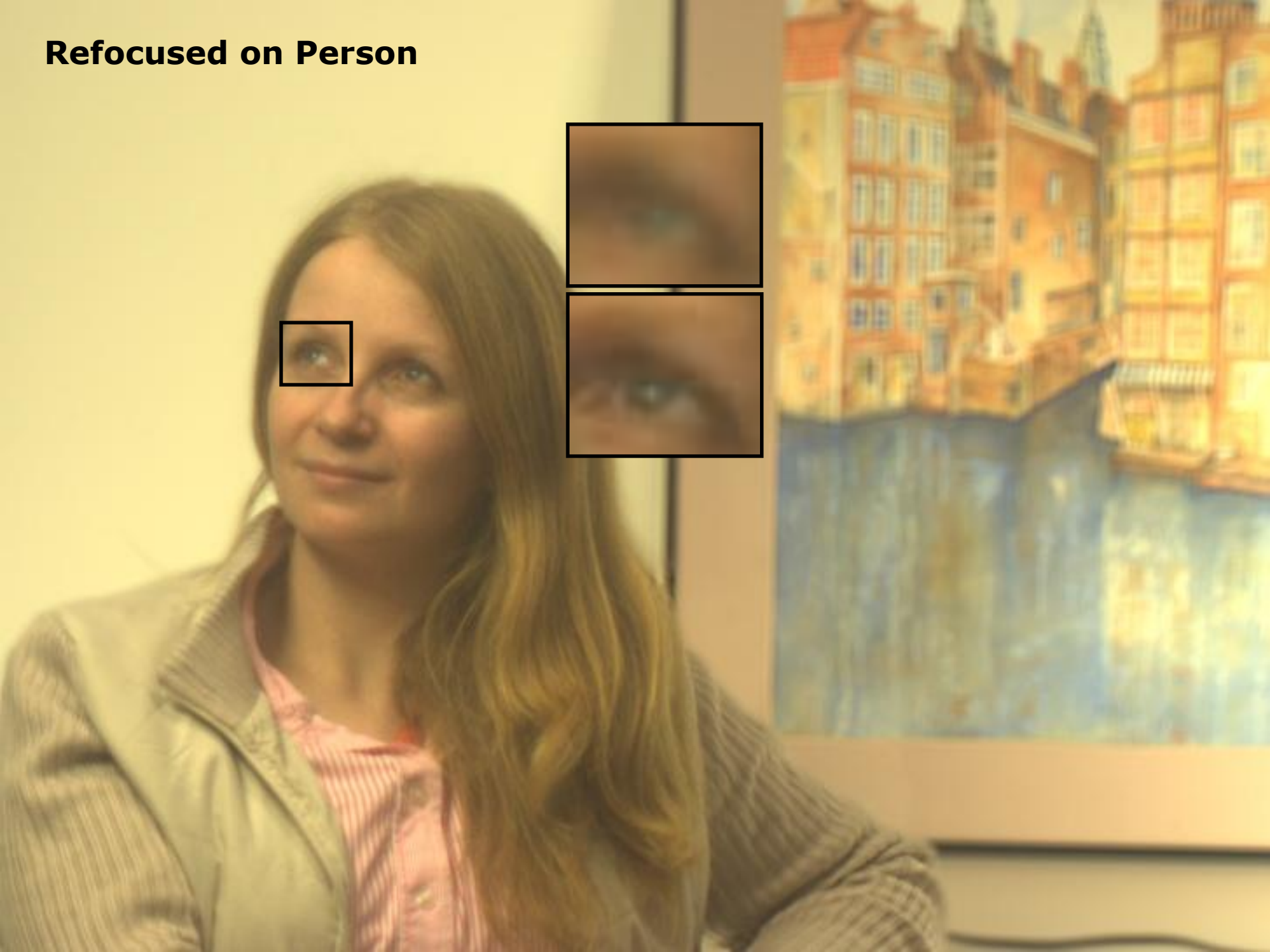


Coded Aperture, 7 \* 7 Mask

# Captured Blurred Photo



## Refocused on Person





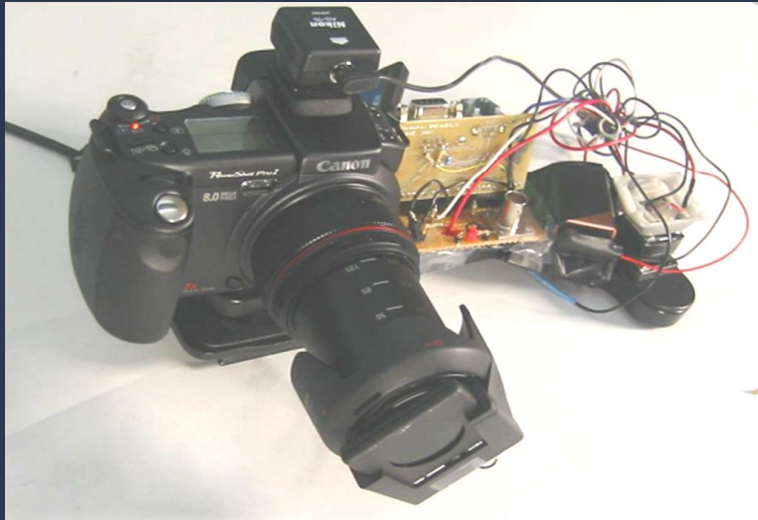
Beal.







# Blocking Light == More Information



Coded Exposure  
Coding in Time

Coded Aperture  
Coding in Space





# Key Concept 1: PSF Invertibility

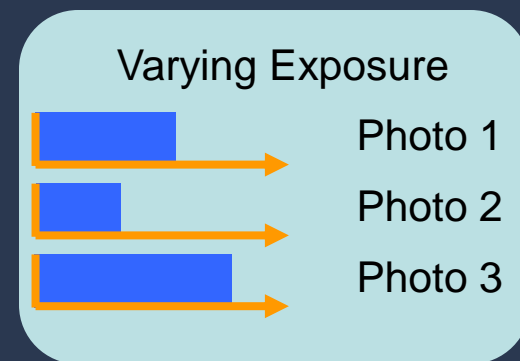
- Modify the PSF to be **invertible**
  - PSF == Impulse Response
- Traditional Camera
  - Non-invertible PSF (loses information)
- Coding in Camera
  - Invertible PSF
- Coding in Time == Coded Exposure
- Coding in Space == Coded Aperture





# Key Concept: PSF Null-Filling

- PSF invertibility using multiple photos
- No camera modification required
- Can do it on available SLR's
  - Using Exposure Bracketing mode (AEB)



# Traditional Exposure Video

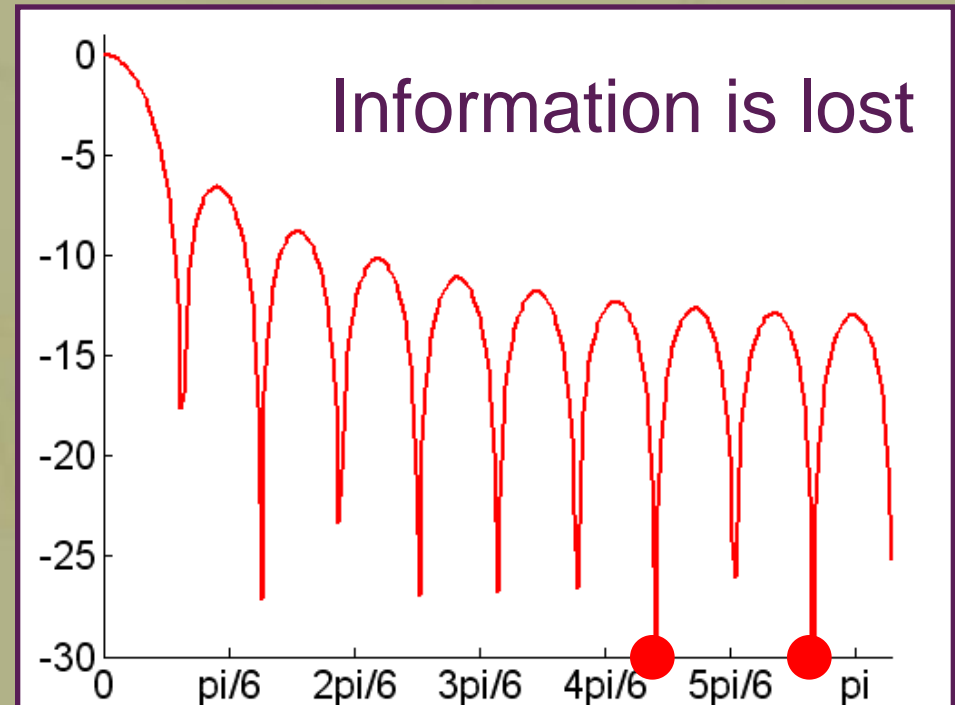


Motion PSF  
(Box Filter)



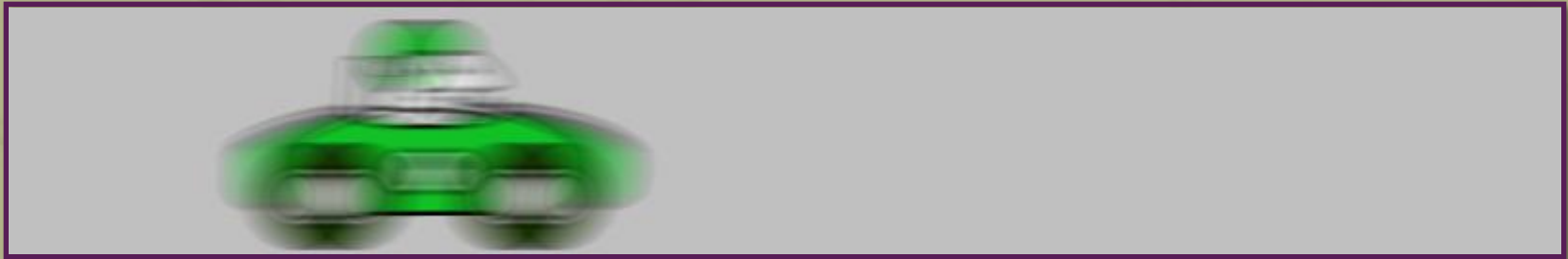
Exposure Time

Fourier  
Transform



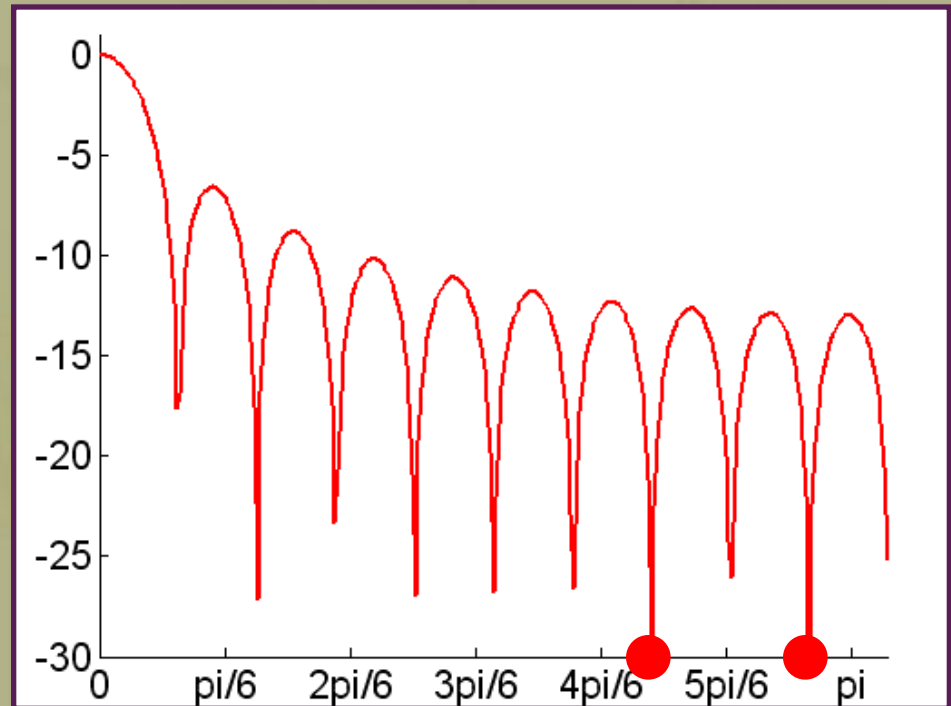


# Varying Exposure Video

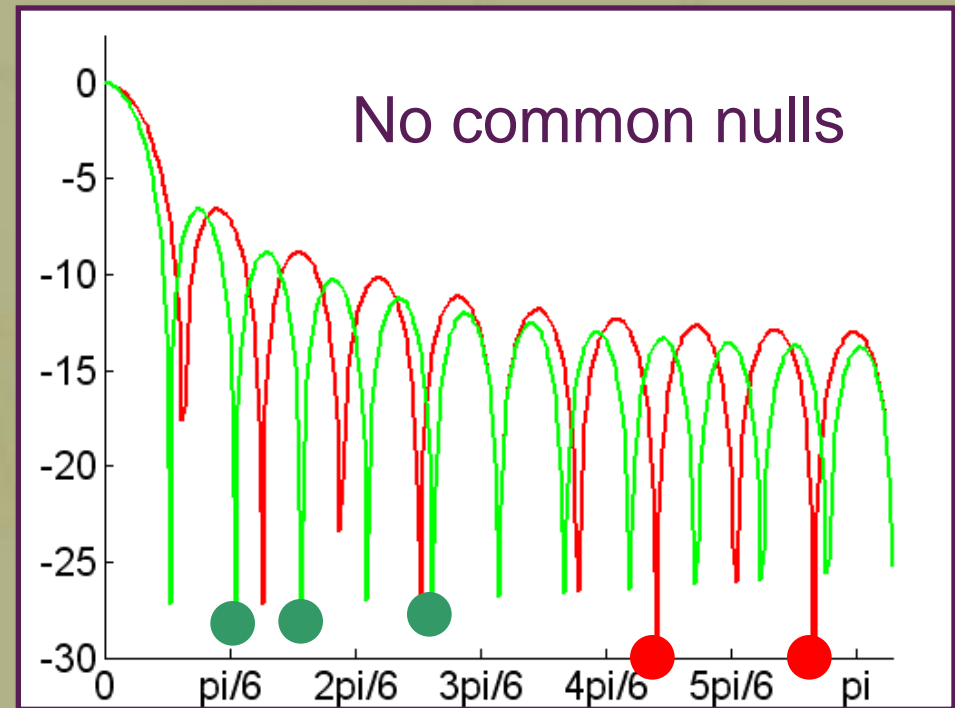
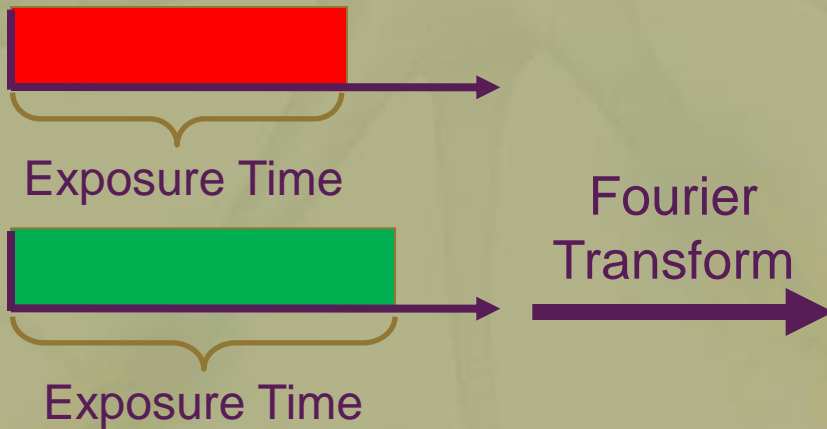


Exposure Time

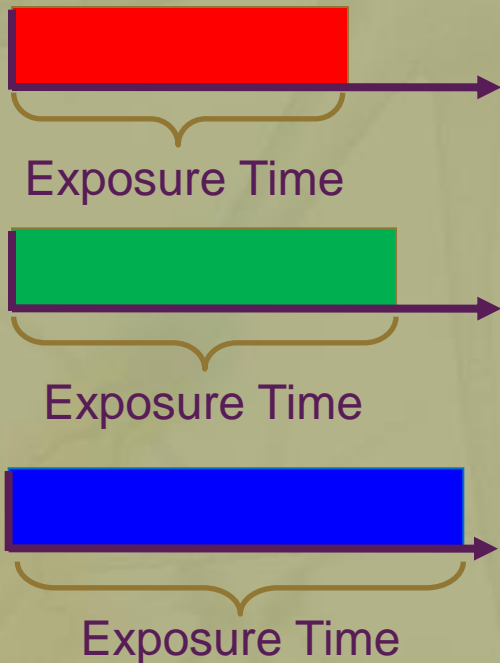
Fourier  
Transform



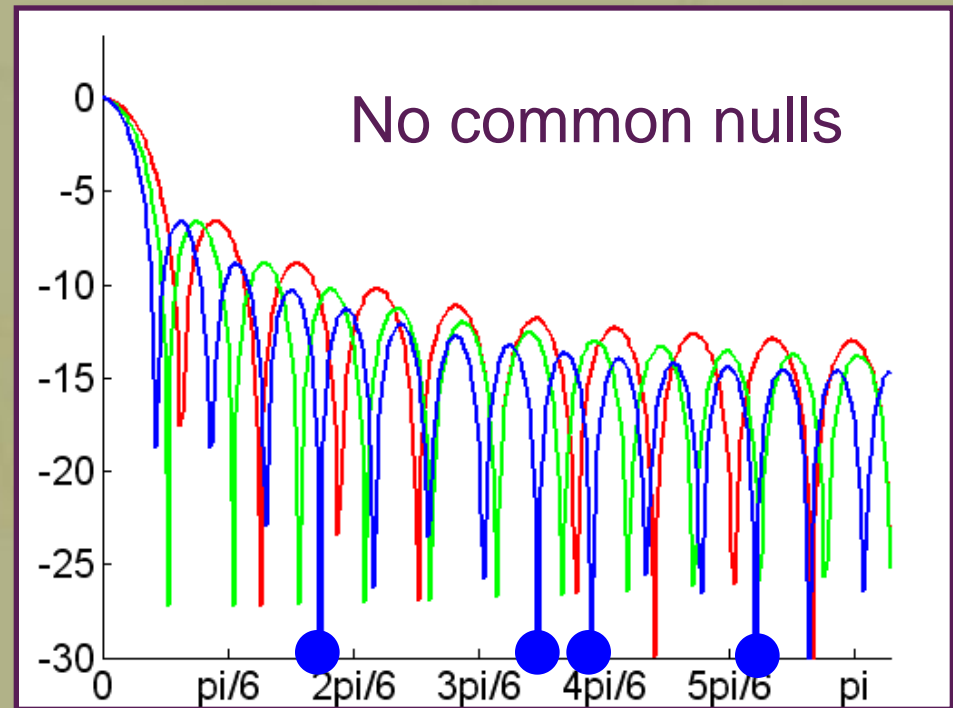
# Varying Exposure Video



# Varying Exposure Video

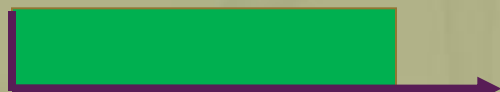
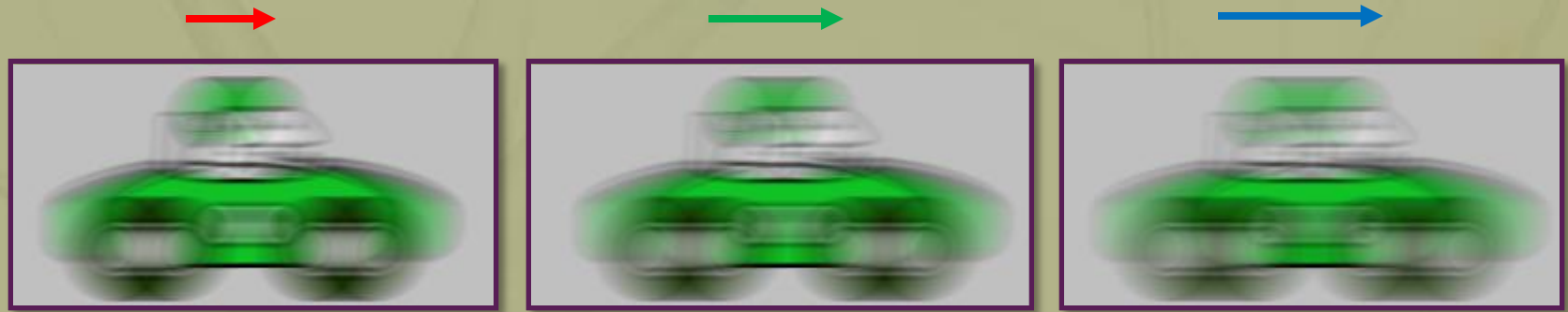


Fourier  
Transform

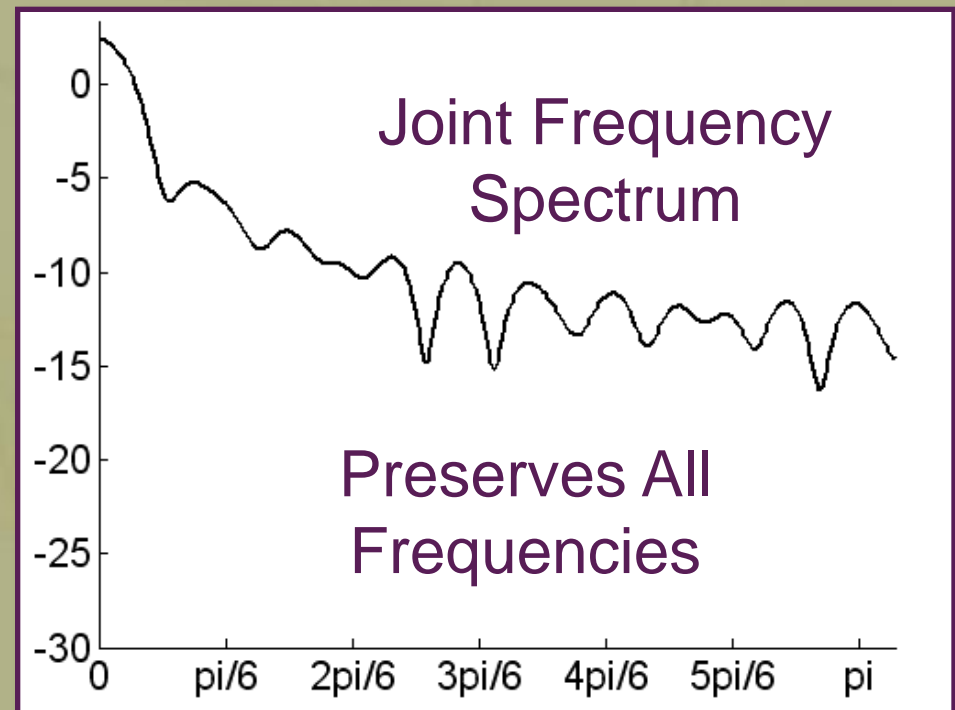




# Varying Exposure Video = PSF Null-Filling

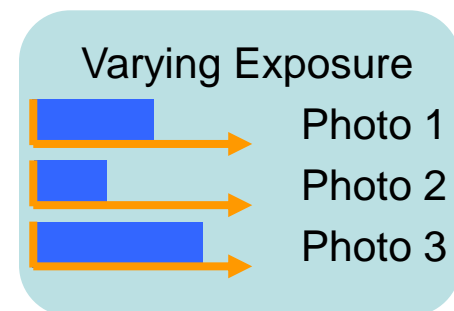
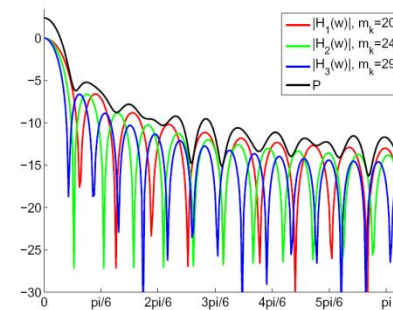


Fourier  
Transform



# Key Idea: PSF Null-Filling

- Individual non-invertible PSF's combined into jointly-invertible PSF
  - Information lost in any single photo is captured in some other photo
- For motion deblurring
  - Achieve PSF null-filling by varying the exposure time of successive photos



# Varying Exposure Video





**Blurred Photos**



**Deblurred Result**



# Outdoor Car

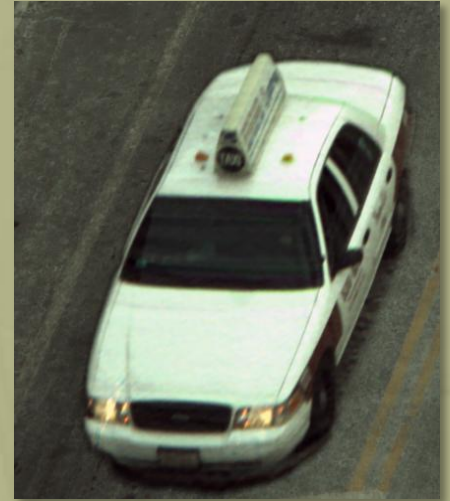
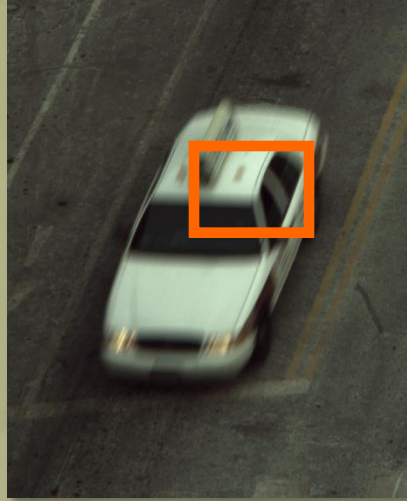


Photo 1

Photo 2

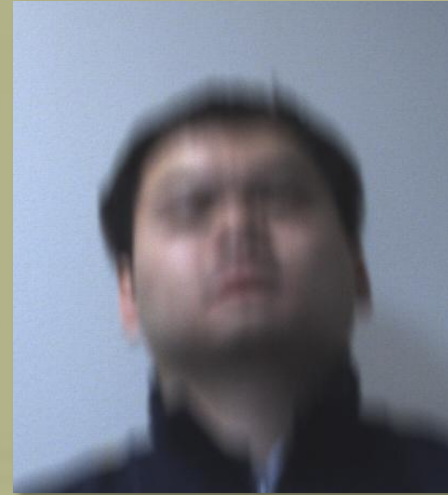
Photo 3

Deblurring

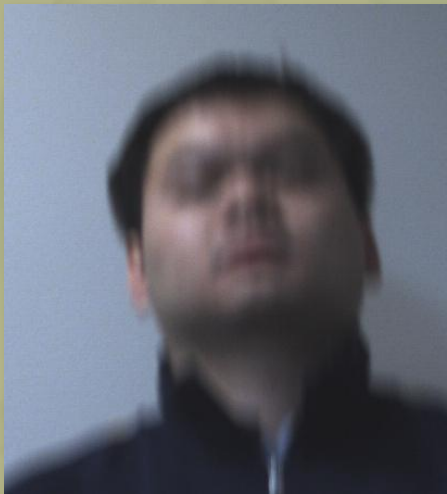
# Face



Blurred Photo 1



Blurred Photo 2



Blurred Photo 3



Deblurred

# Auto Exposure Bracketting (AEB) for Varying Exposure Deblurring



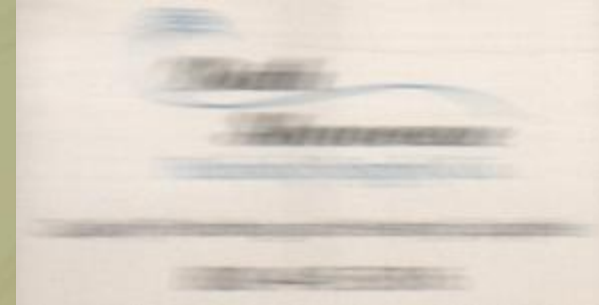
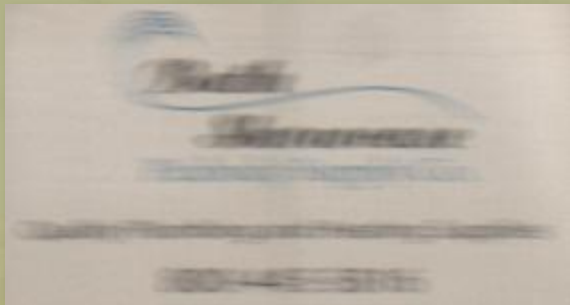
1/50s

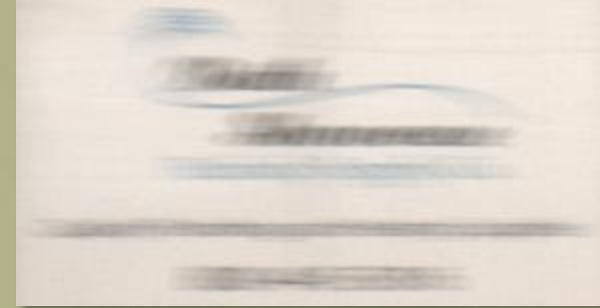
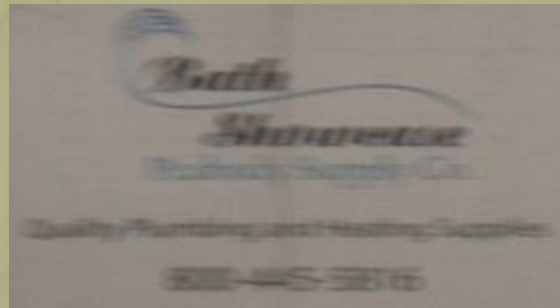
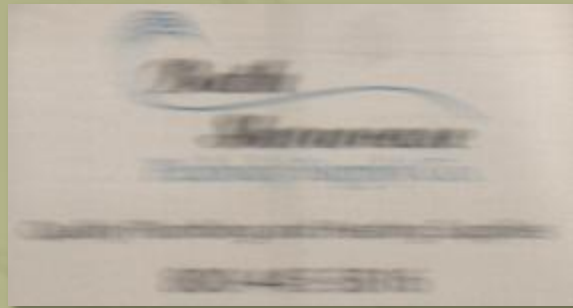


1/80s



1/30s





## Blurred Photos



## Deblurred Result





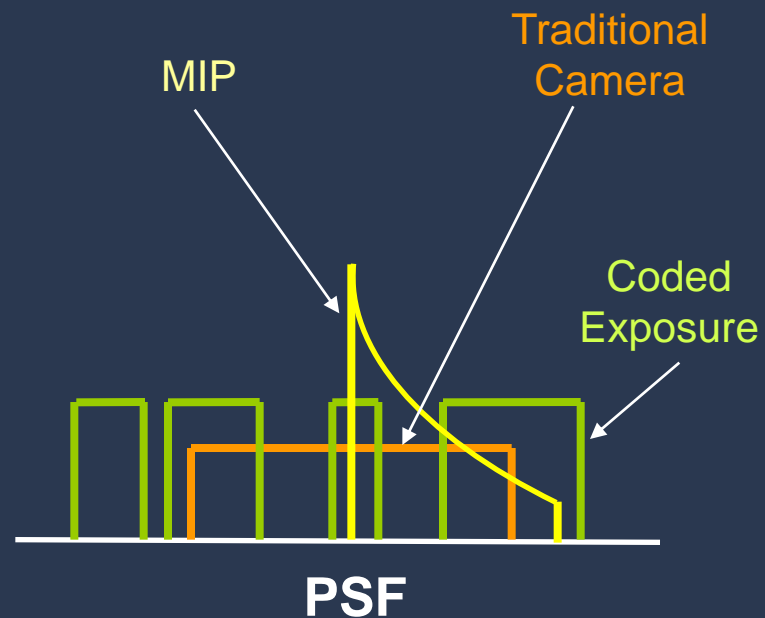
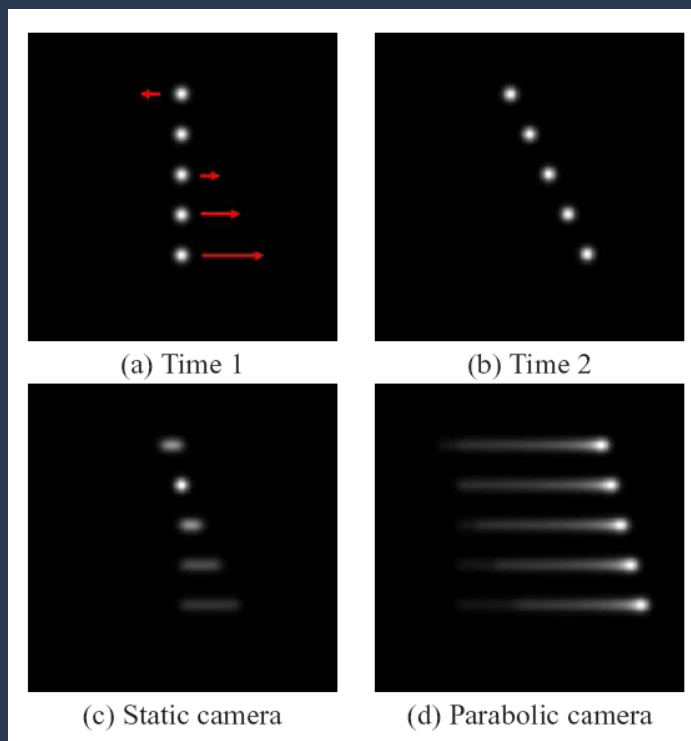
## Key Concept 2: PSF Invariance

- But...
  - Need to estimate depth or velocity for deblurring
- Modify the PSF to be **invariant**
- Motion Blur
  - Motion invariant Photography (MIP), Levin et al SIG08
- Focus Blur
  - Wavefront coding
  - Focus Sweep Camera
  - Spectral Sweep Camera
  - Diffusion coding



# PSF Invariance: Motion Blur

- Move the camera while taking photo
  - Constant Camera Acceleration
- Leads to similar PSF for object velocity in a range
- But requires knowledge of motion direction





# Comparison

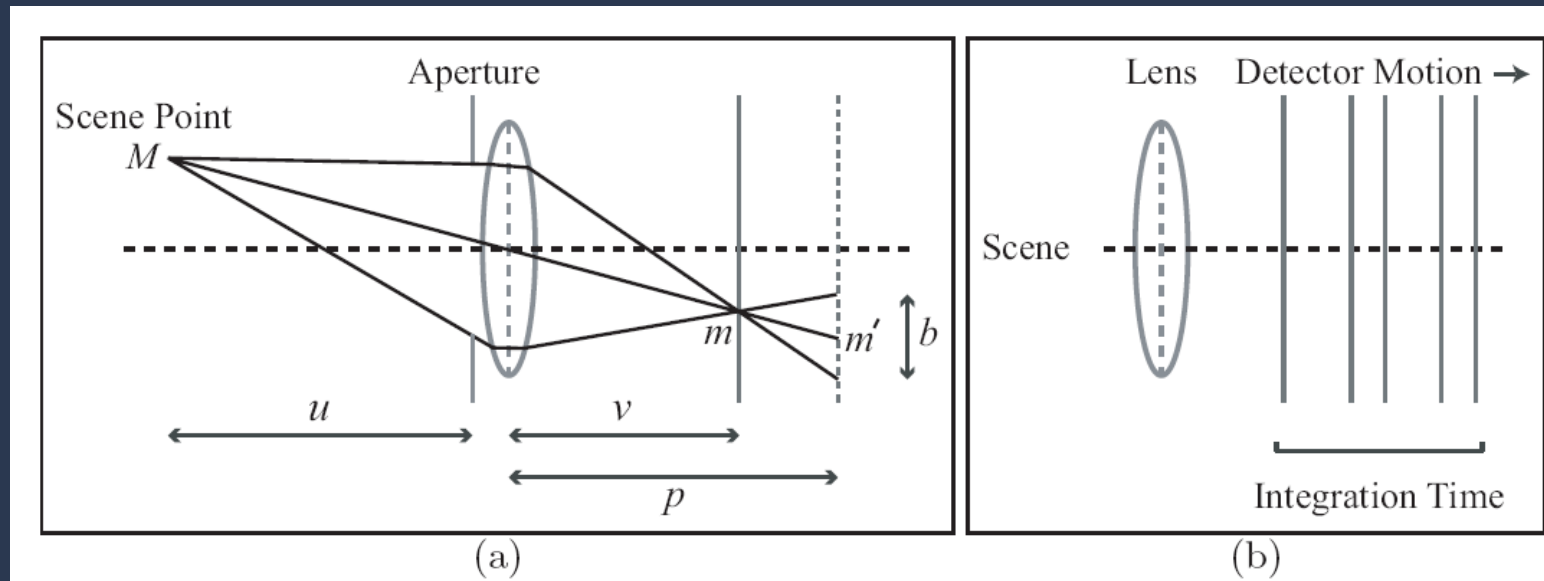
- Coded Exposure
  - Requires motion **magnitude** for deblurring
  - But works for any motion direction
- PSF Invariance
  - Requires motion **direction** to move the camera
  - But invariant PSF for motion magnitude within a range

Optimal Single Image Capture for Motion Deblurring, Agrawal and Raskar,  
CVPR 2009

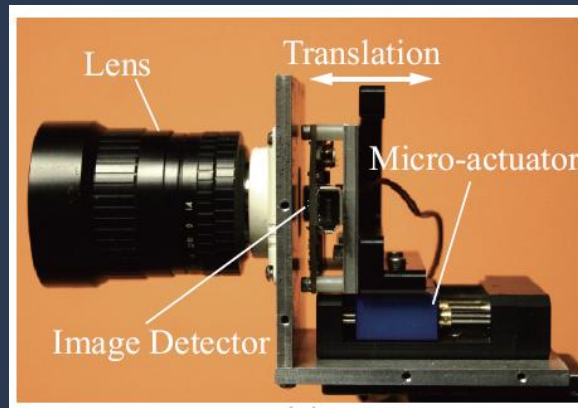


# PSF Invariance: Focus Blur

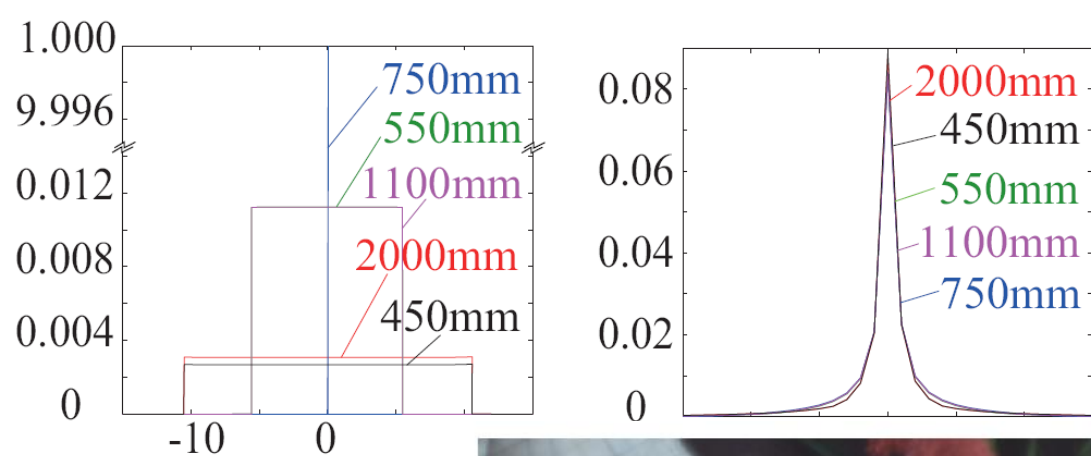
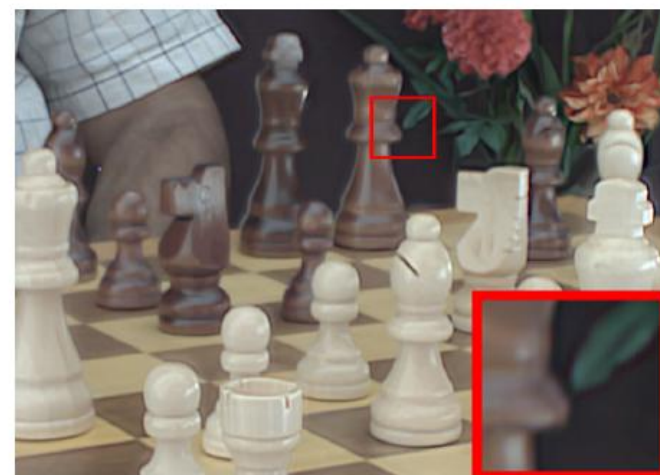
- Defocus PSF should be invariant of depth



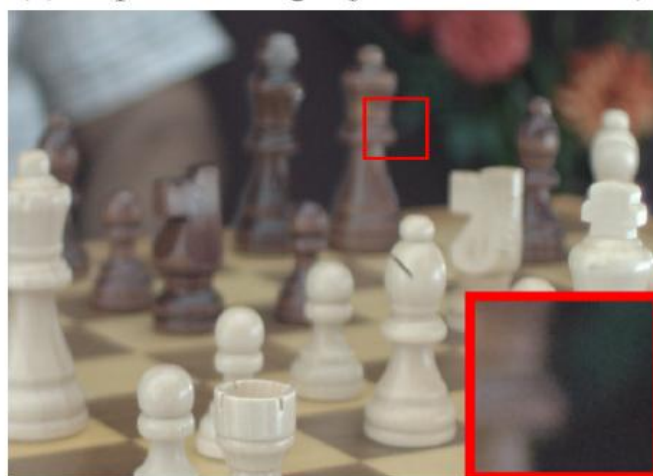
Nagahara et al.  
ECCV 2008





(a) Captured Image ( $f/1.4$ ,  $T=0.36\text{sec}$ )

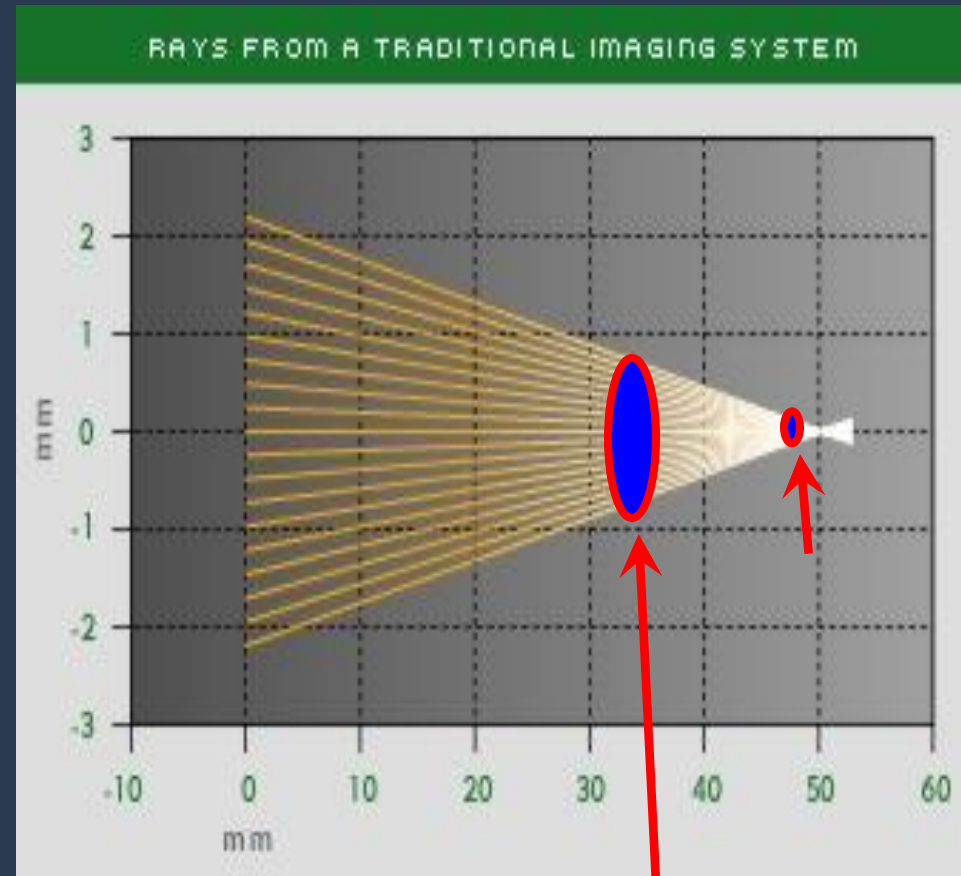
(b) Computed EDOF Image





# Wavefront Coding

- Traditional Lens:
  - Defocus (circle of confusion) dependent on distance from plane of focus

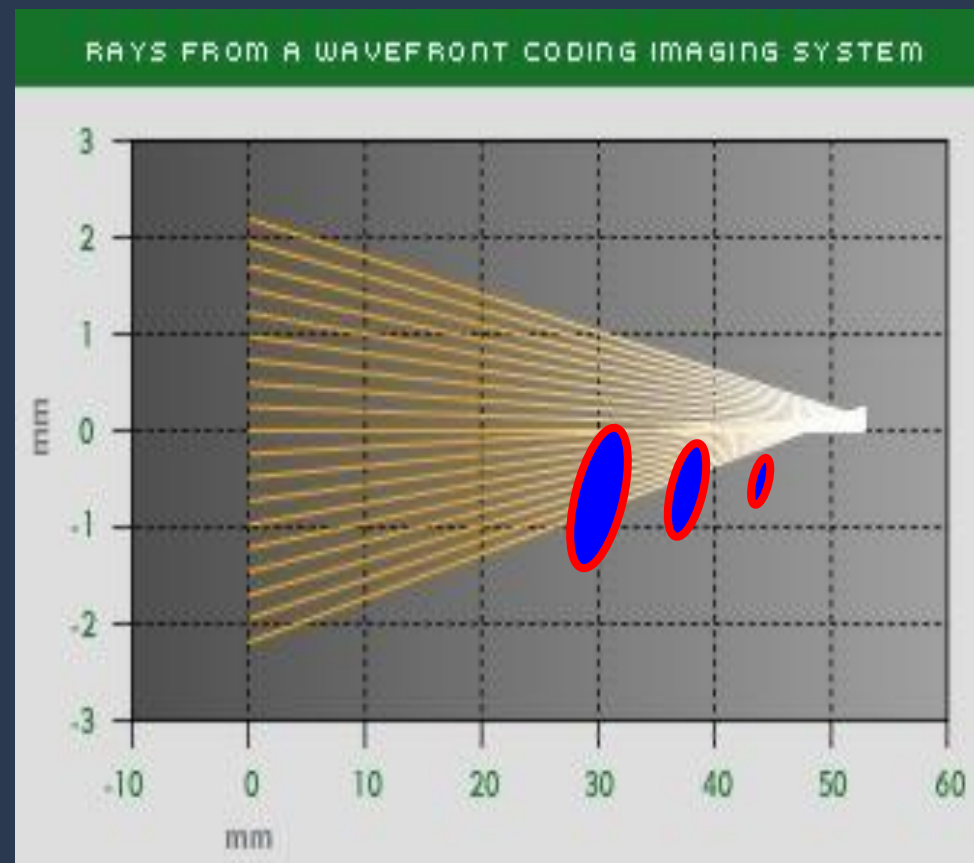


<http://www.cdm-optics.com>



# Wavefront Coding


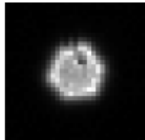
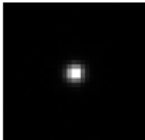
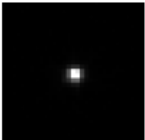
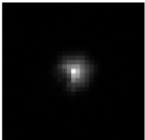



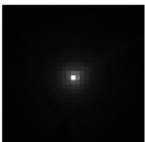
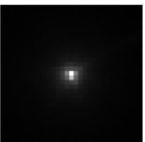

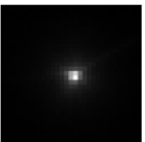
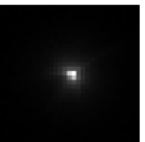
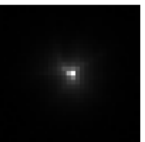
- Traditional Lens:
  - Defocus dependent on distance from plane of focus
- Cubic Phase Plate
  - Defocus nearly independent of distance
  - All points 'blurred'
  - Deconvolve to get sharper image



<http://www.cdm-optics.com>

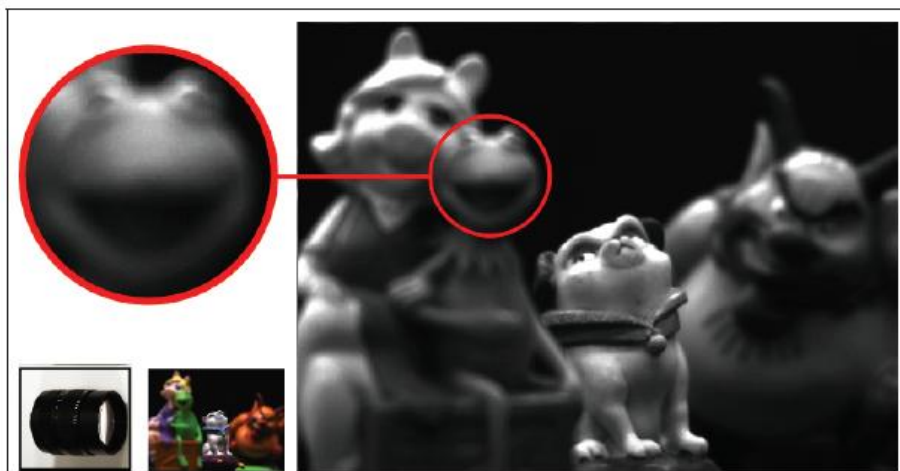
# Spectral Focal Sweep Lens



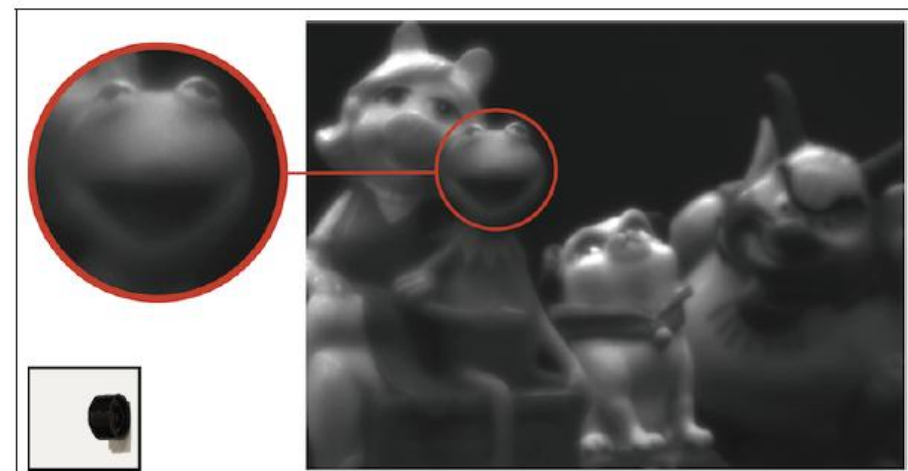
						
						
depth	914 mm	965 mm	1016 mm	1066 mm	1117 mm	1194 mm

Cossairt and Nayar, ICCP 2010

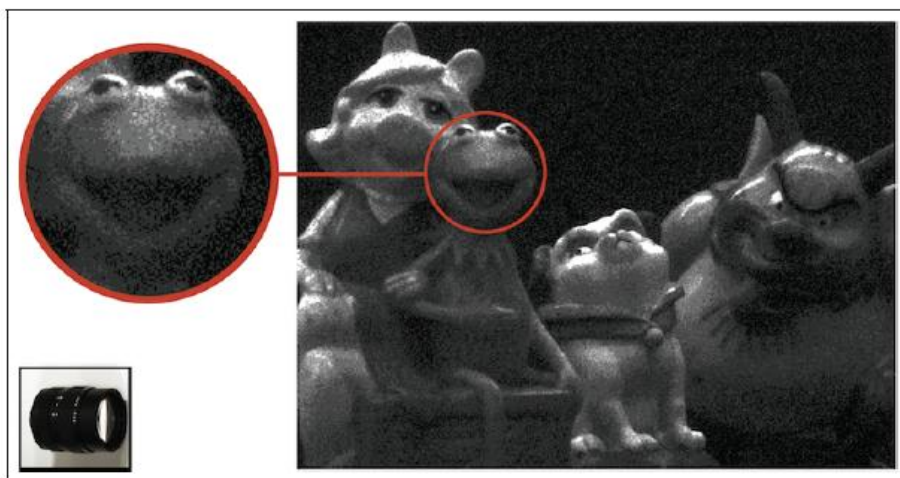




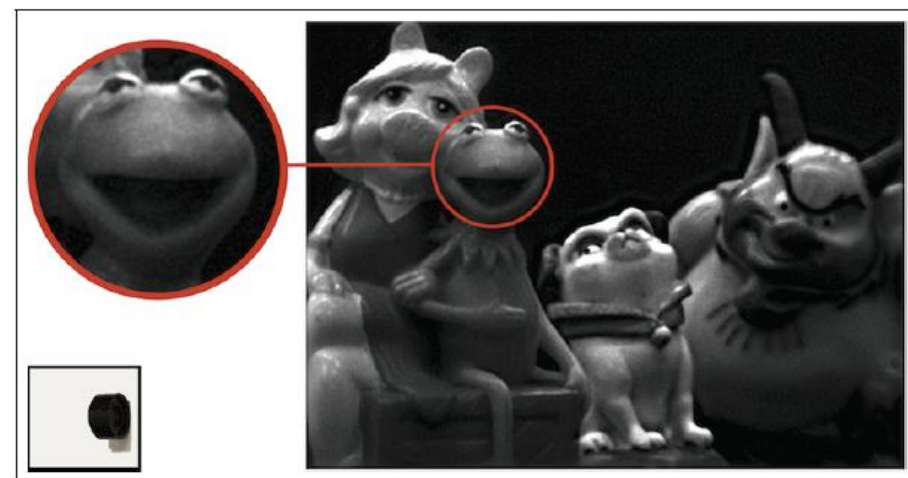
(a) Captured with a F/4 corrected lens (8ms exposure)



(b) Captured with our SFS lens (8ms exposure)



(c) Captured with a F/16 corrected lens (8ms exposure)



(d) The image in Figure 8(c) after deblurring



# PSF Invariance: Focus Blur

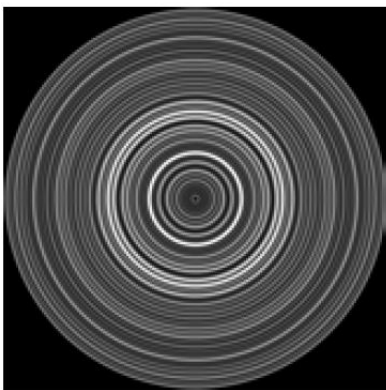
- Vary focal length in captured photo

Focal Length Variation	Hardware Implementation	Reference
Time	Sensor Motion	Nagahara et al. ECCV 2008
Phase/Angle	Cubic Phase Plate	Wavefront Optics
Wavelength	Lens with Chromatic Aberrations	Cossairt and Nayar, ICCP 2010
Aperture	Divide the aperture into different lens	Ben-Eliezer, Applied Optics 2005, Levin et al SIGGRAPH 2009



# PSF Invariance: Diffusion Coding

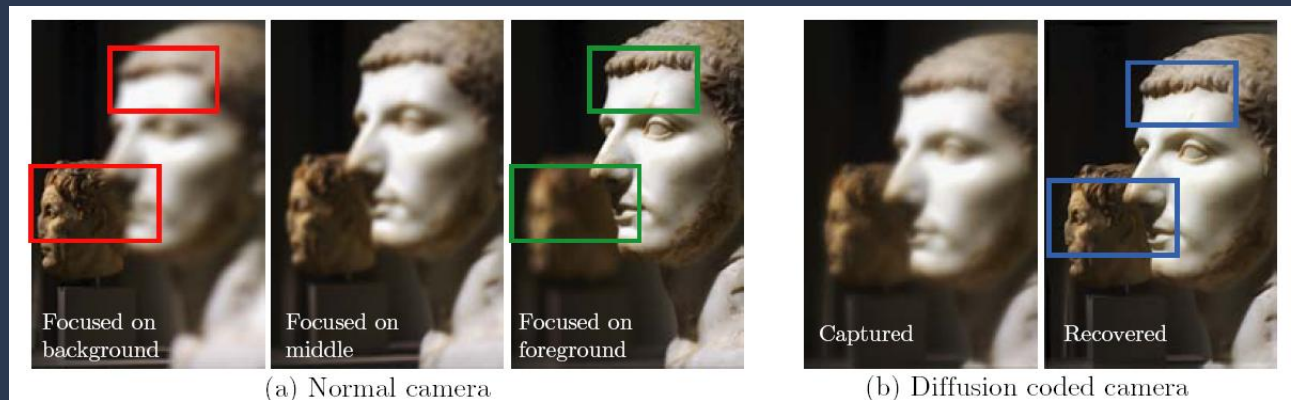
- Use a radially symmetric diffuser in aperture
- Cossairt and Nayar, SIGGRAPH 2010



(b) Diffuser height map



(d) The diffuser





# High Speed Imaging

- High speed cameras
  - Expensive
  - Require on-board memory
  - Fundamental Light Loss



**30 fps**



**500 fps**  
**-24.5 dB**



**2000 fps**  
**-36.5 dB**



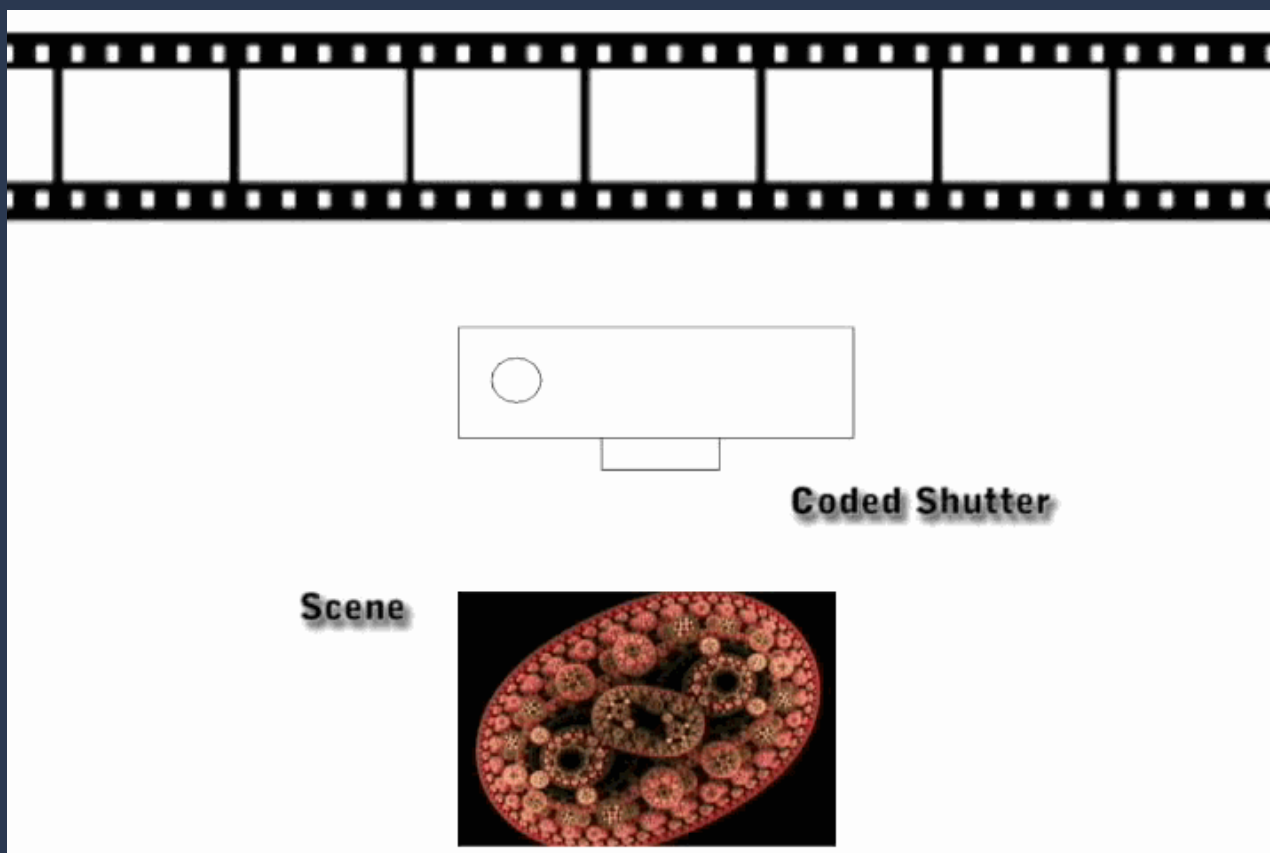
**4000 fps**  
**-42.5 dB**





# Coded Strobing Camera: 100x Temporal Super-Resolution

- For Periodic Signals
- Coded Exposure Video
  - Every frame is coded **differently**





# Battery powered Toothbrush



**20fps normal camera**



**20fps coded strobing camera**



**Reconstructed frames**



**1000fps hi-speed camera**



# Implementation

Can strobed at 1ms



Captured at 10fps PGR Dragonfly2

Can strobe at 250us



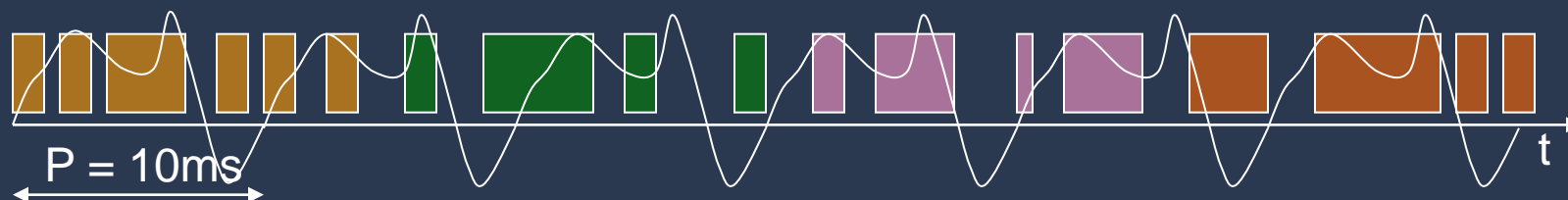
External FLC Shutter





# Temporally at a pixel

observe different linear combinations of the periodic signal



Advantage of the design:

Exposure coding is independent of the frequency periodic signal.

50% light throughput, far greater than traditional strobing.





# Compressive sensing Reconstruction



## Basis Pursuit De-noising

$$\min \|s\|_1 \text{ s.t. } \|y - As\|_2 \leq \varepsilon$$



# Battery powered Toothbrush



**20fps normal camera**



**20fps coded strobing camera**



**Reconstructed frames**



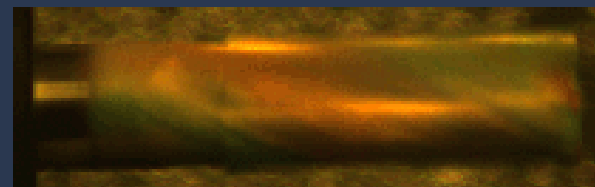
**1000fps hi-speed camera**



## Rotating Mill Tool captured by PointGrey Dragonfly2



**Normal Video: 25fps**



**Coded Strobing Video: 25fps**



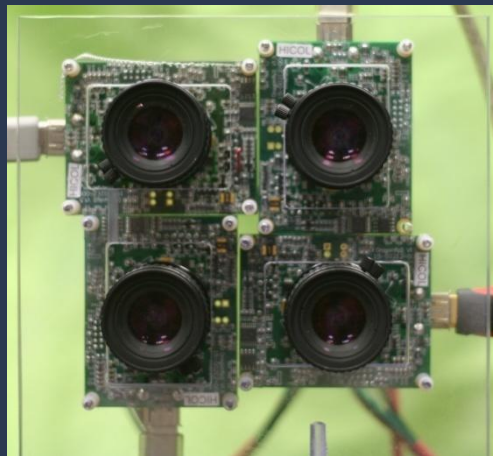
**Reconstructed Video at 2000fps**



# High Speed Imaging

- Coded Strobbing Camera for Periodic Signals
- For General Scenes?

Camera Arrays



Agrawal et al. CVPR 2010, Wilburn et al.  
CVPR 2004, Shechtman et al. ECCV 2002

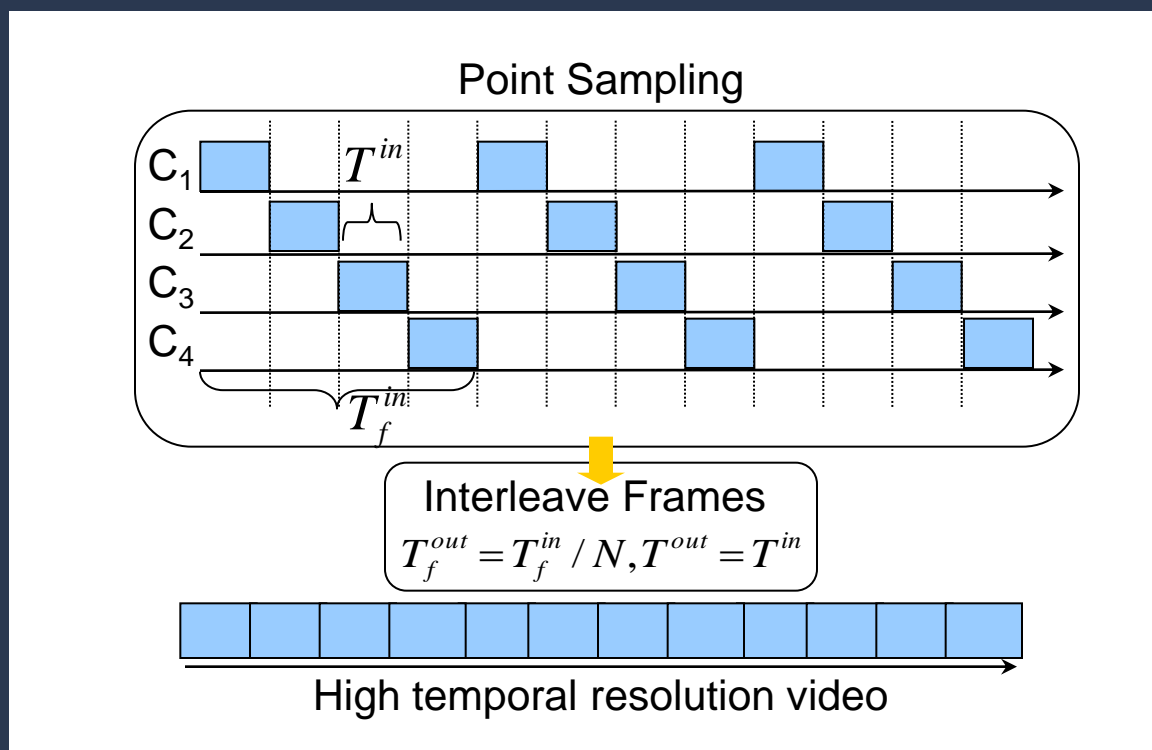
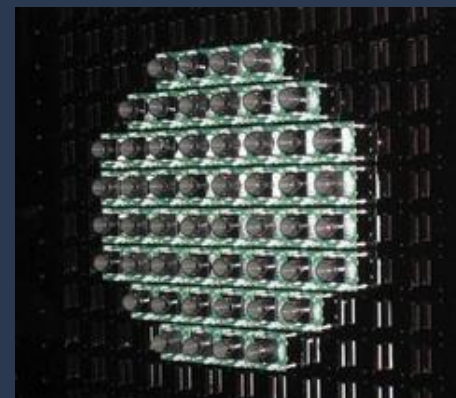




# Camera Arrays

- Point Sampling

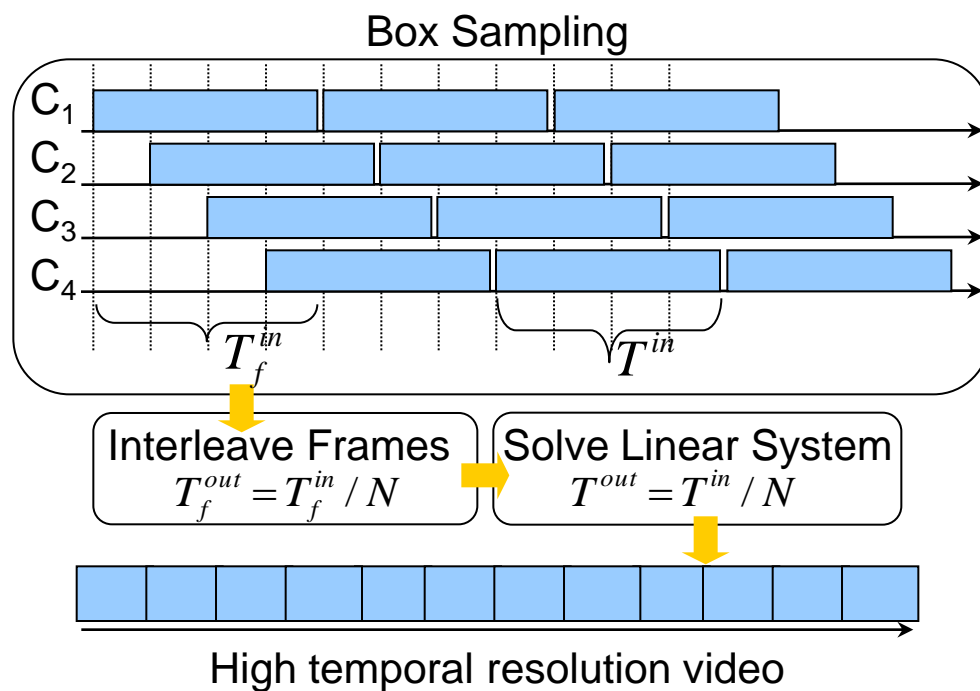
- Wilburn et al CVPR 2004
- Each camera captures independent sample of high speed video





# Camera Arrays

- Box Sampling



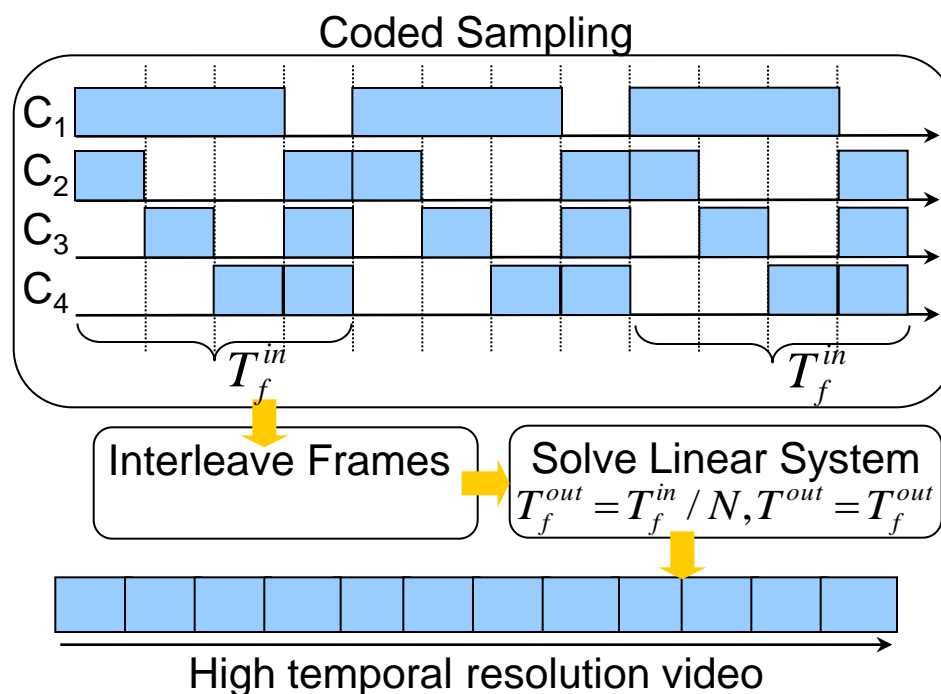


Space-Time Super-Resolution, Shechtman et al. ECCV 2002



# Camera Arrays

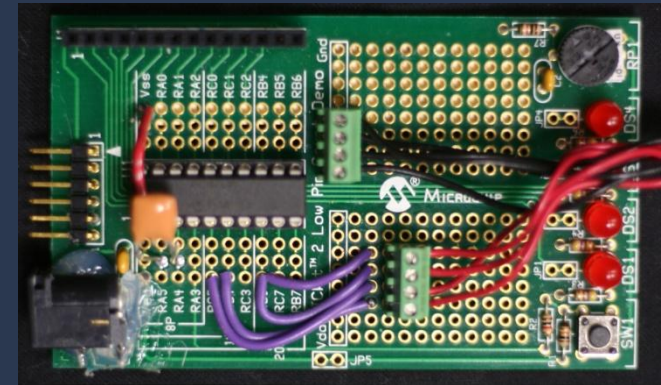
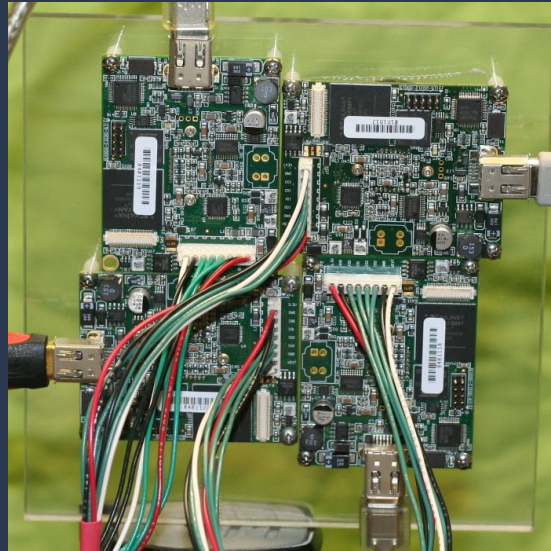
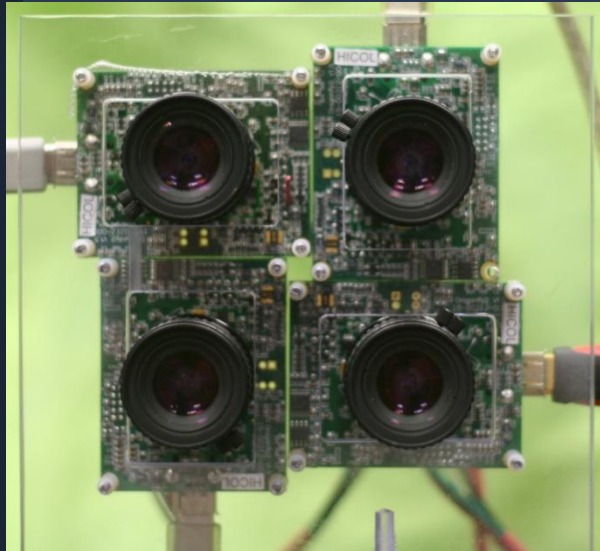
- Coded Sampling
- Agrawal, Gupta, Veeraraghavan and Narasimhan CVPR 2010







# Implementation





# Flexible Videography

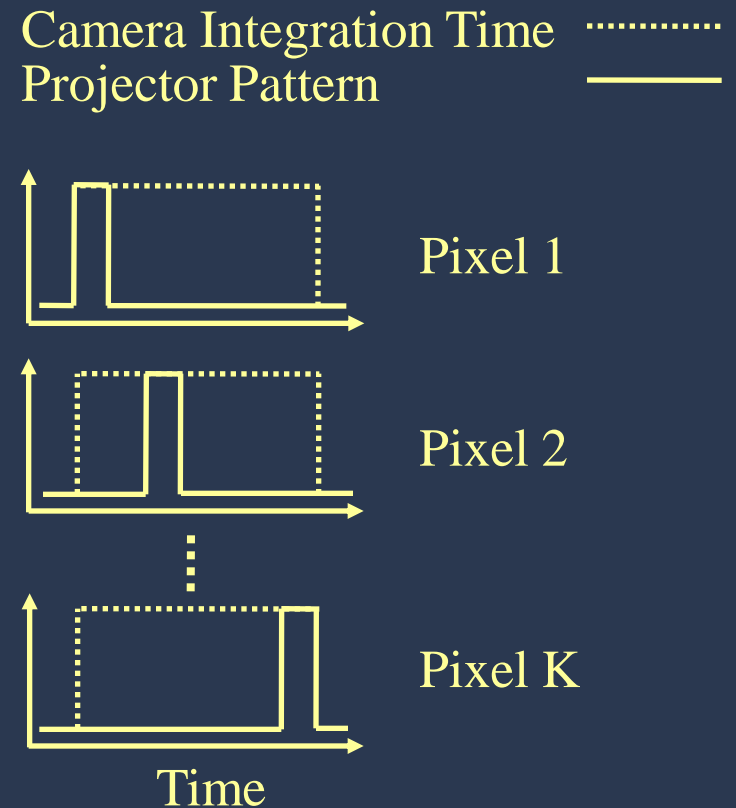
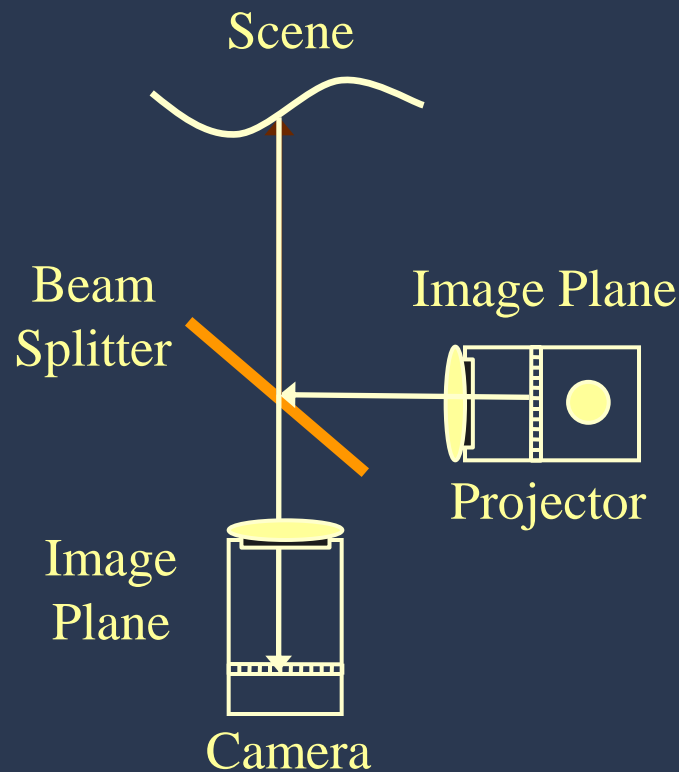
[Gupta, Agrawal, Veeraraghavan and Narasimhan, ECCV 2010]

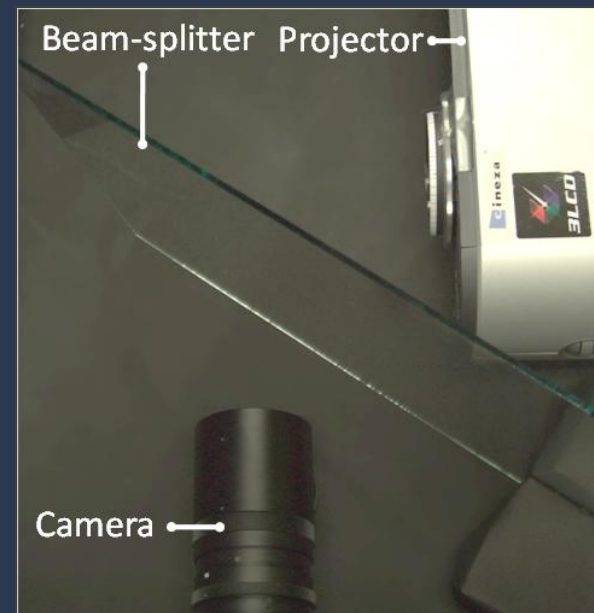
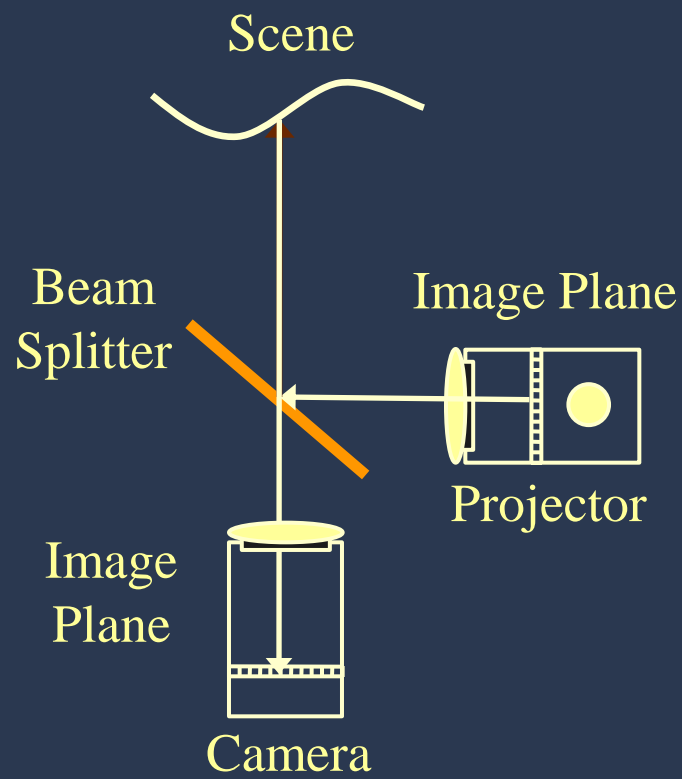
- Resolution Tradeoff: Traditional Video Camera
  - Fixed Space-Time Resolution
  - Independent of the scene
  - Same all over the image
- Flexible Videography
  - Change space-time resolution in **post capture**
  - Scene dependent Resolution
  - Different for different parts of the image



# Flexible Voxels

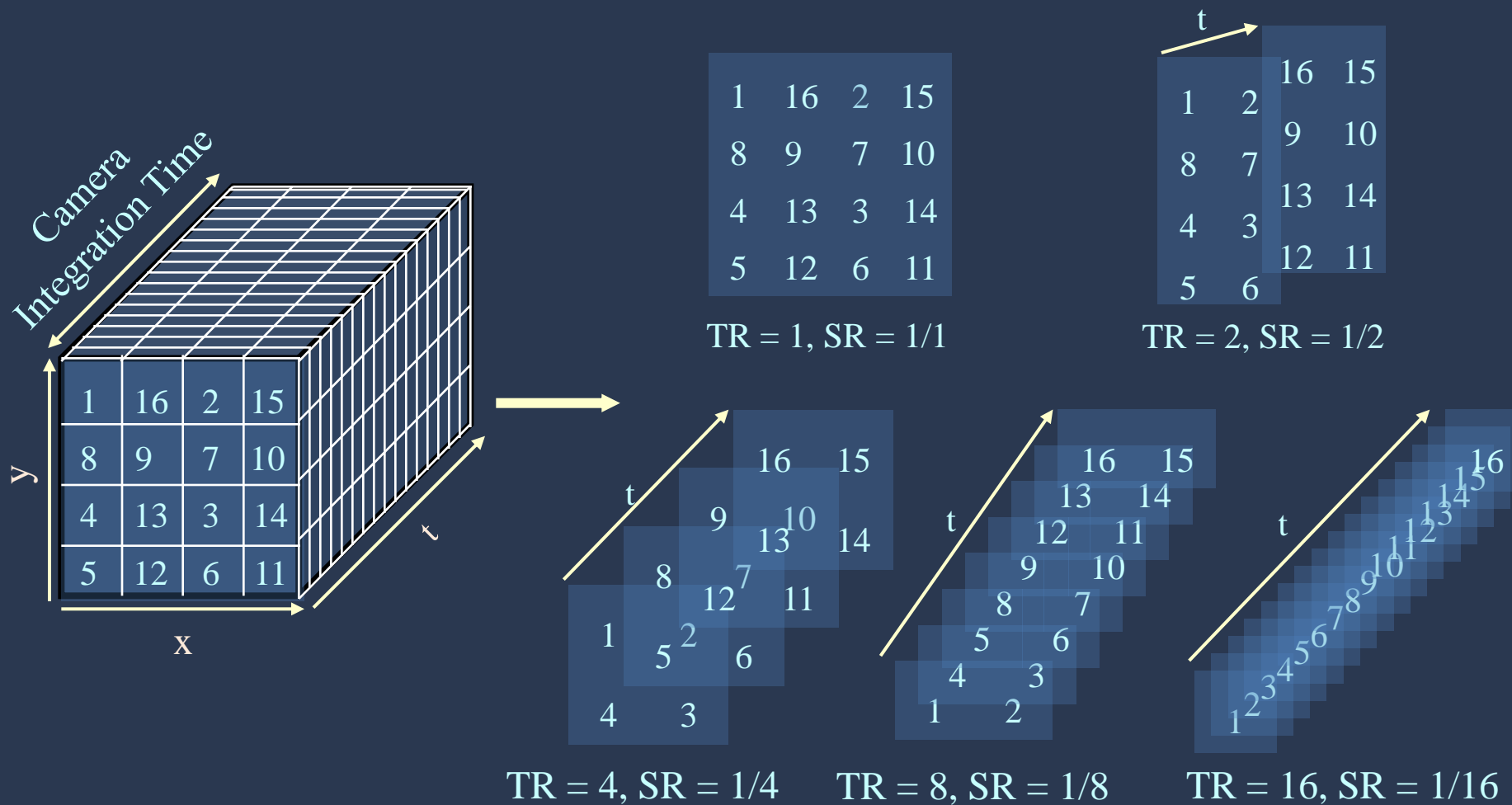
- Per pixel coded exposure
  - Different temporal modulation per pixel







# Sampling Strategy for 1-16x







Captured Video



Naïve Reconstruction

8X Temporal Super-res, but 8 times lower spatial resolution



Optical Flow Magnitudes



Motion Aware Reconstruction

8X Temporal Super-res on moving fan, same spatial resolution on static parts





Captured Video



Naïve  
Reconstruction



Optical Flow



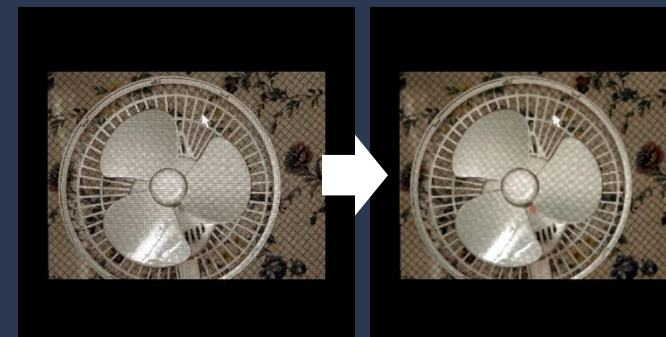
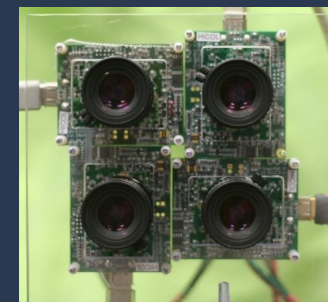
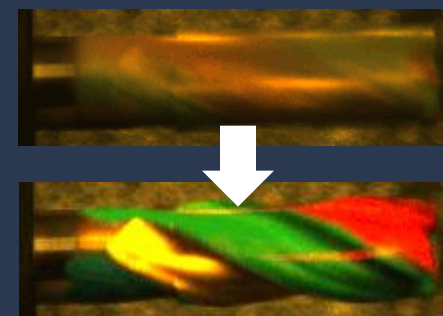
Motion Aware  
Reconstruction





# Summary: Temporal Modulations

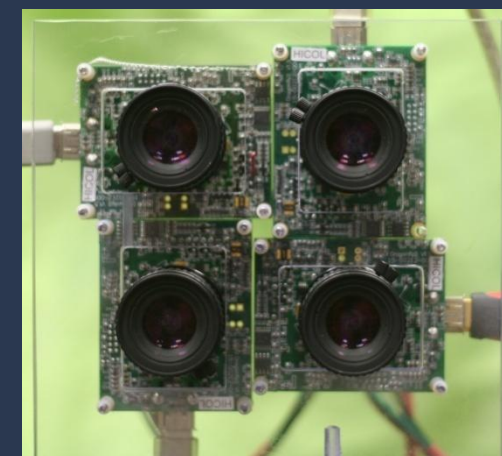
- Coded Exposure (Photo)
  - Same for all pixels
  - Motion deblurring
- Strobe Camera (Video)
  - Same for all pixels in a frame
  - Different across frames
  - Temporal Super-Resolution (100x)
- Multi-Camera Arrays (Video)
  - Same for all pixels in a frame
  - Same across frames, different across cameras
  - High Speed Imaging
- Flexible Voxels (Motion Aware Video)
  - Different for pixels in a frame
  - Same across frames
  - Post Capture Space Time Resolution Tradeoff





# Section Summary

- Coding and Modulation
  - Beyond Photo Manipulations
- Key Concepts
  - PSF Invertibility and PSF Invariance
- Motion Blur and Defocus blur
  - Coded exposure, Coded aperture, Wavefront coding etc.
- High Speed Imaging
  - Strobbing Camera
  - Coded Sampling for Camera Arrays
- Flexible Videography
  - Post-capture Resolution Tradeoff



# Schedule

Introduction	Srinivasa, 10 mins
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Assorted Pixels	Srinivasa, 20 mins
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Coding and Modulation in Cameras	Amit, 45 mins
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Break	10 min
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Light Fields and Applications	Ankit, 60 mins
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Break	10 min
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Computational Illumination	Srinivasa, 45 mins
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Future Trends	Amit, 15 mins
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Discussion	
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