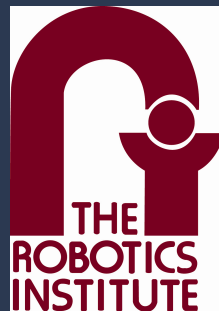


Coded Computational Imaging

Amit Agrawal, Ashok Veeraraghvan,
Srinivasa Narasimhan and Ankit Mohan

Mitsubishi Electric Research Labs (MERL)
Robotics Institute, CMU
MIT Media Lab



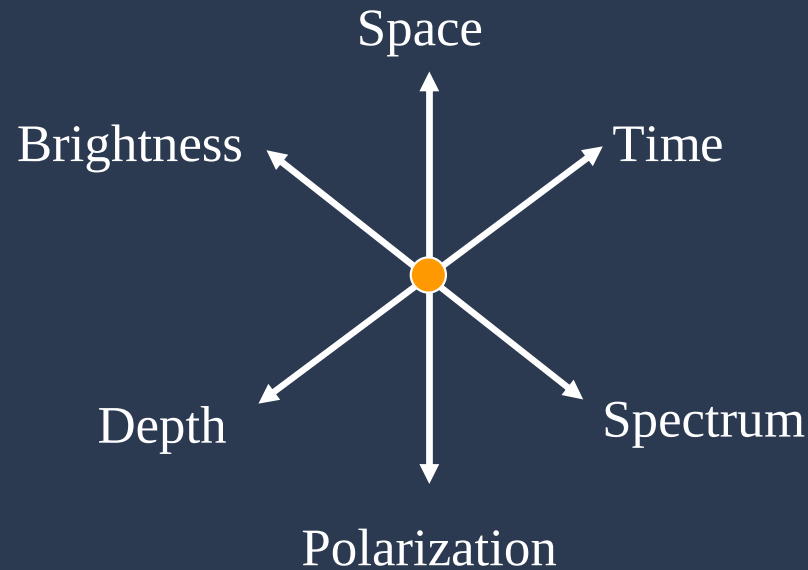
Course WebPage :

<http://www.umiacs.umd.edu/~aagrwal/CVPR10Tutorial/index.html>

Schedule

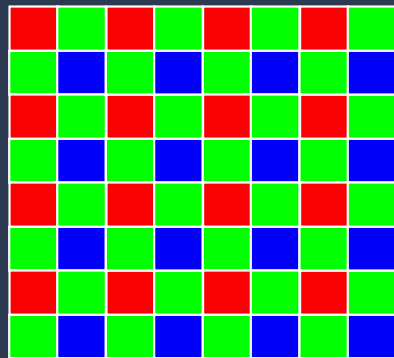
Introduction	Narasimhan, 10 mins
Assorted Pixels	Narasimhan, 20 mins
Coding and Modulation in Cameras	Agrawal, 45 mins
Break	10 min
Light Fields and Applications	Mohan, 60 mins
Break	10 min
Computational Illumination	Narasimhan, 45 mins
Future Trends	Agrawal, 15 mins
Discussion	

Dimensions of Imaging



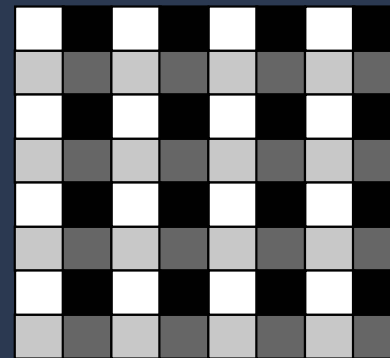
How can we capture information in multiple dimensions using only a two-dimensional array of pixels ?

Assorted Pixels: Multi-Sampled Images



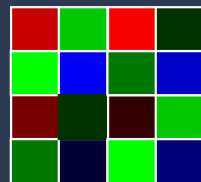
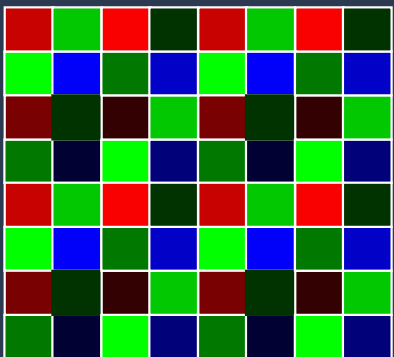
Base Pattern

SVC : Spatially Varying Color
(Bayer Pattern)



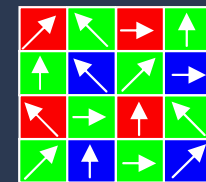
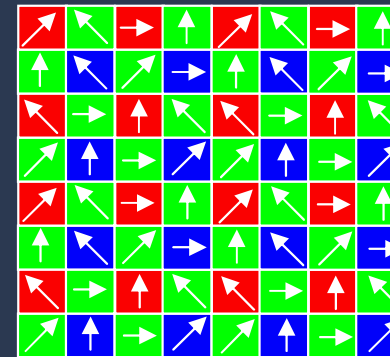
Base Pattern

SVE : Spatially Varying Exposure
(Nayar et. al., 00)



Base Pattern

SVEC : Spatially Varying Color
& Exposure (Narasimhan et al 02)

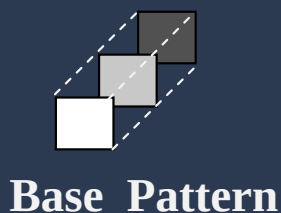
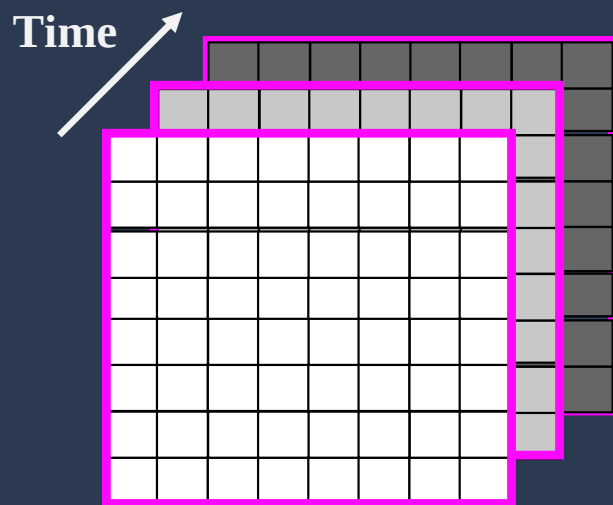


Base Pattern

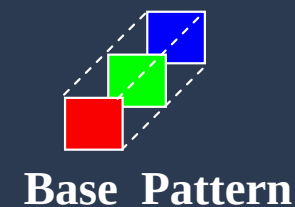
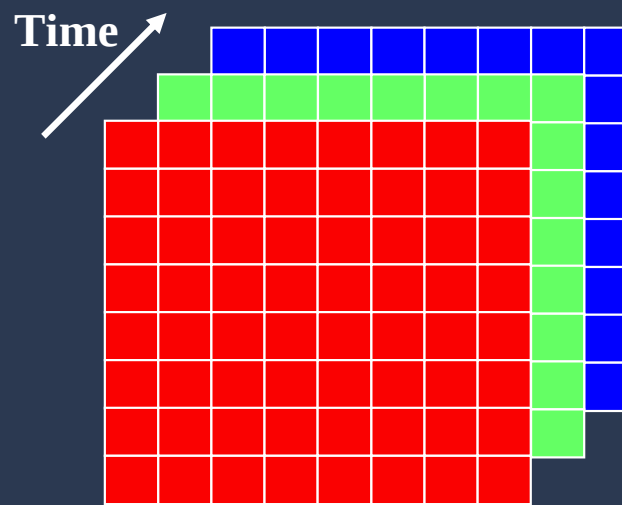
SVCP : Spatially Varying Color
and Polarization (Ben Ezra et al)

Simultaneous Sampling along Multiple Dimensions

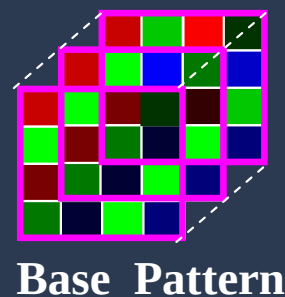
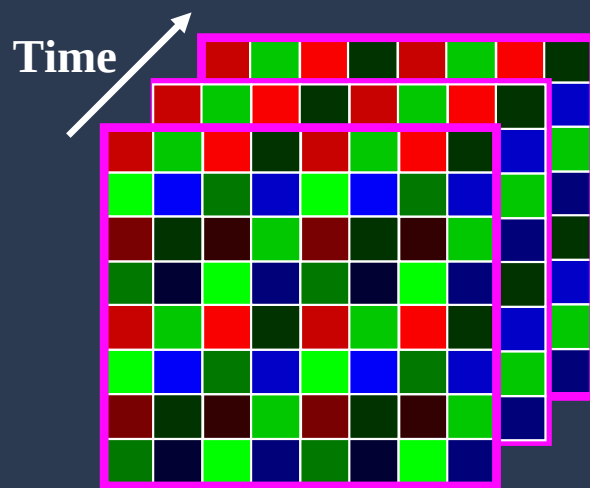
Assorted Voxels: Multi-Sampled Video



Sequential Exposure Changes

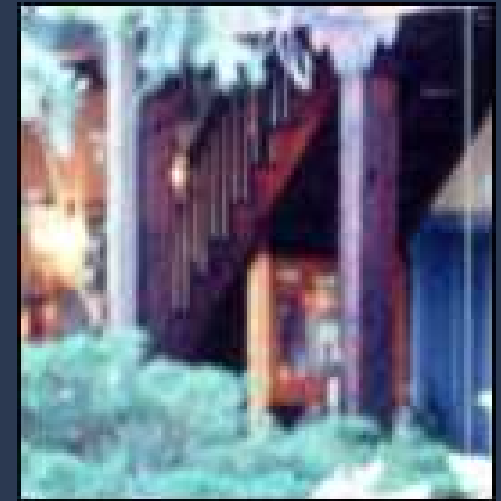
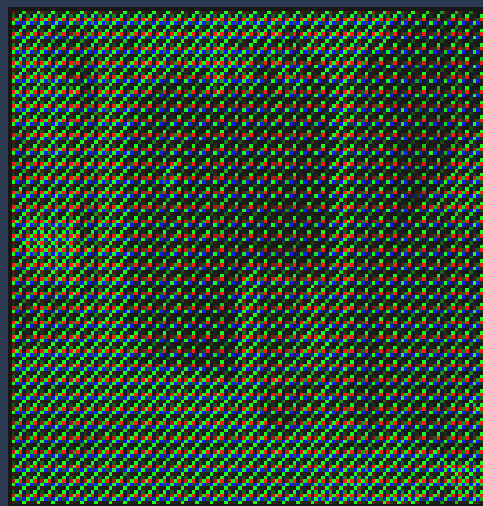


Sequential Color Changes



SVEC Video

Multi-Sampled Image Reconstruction



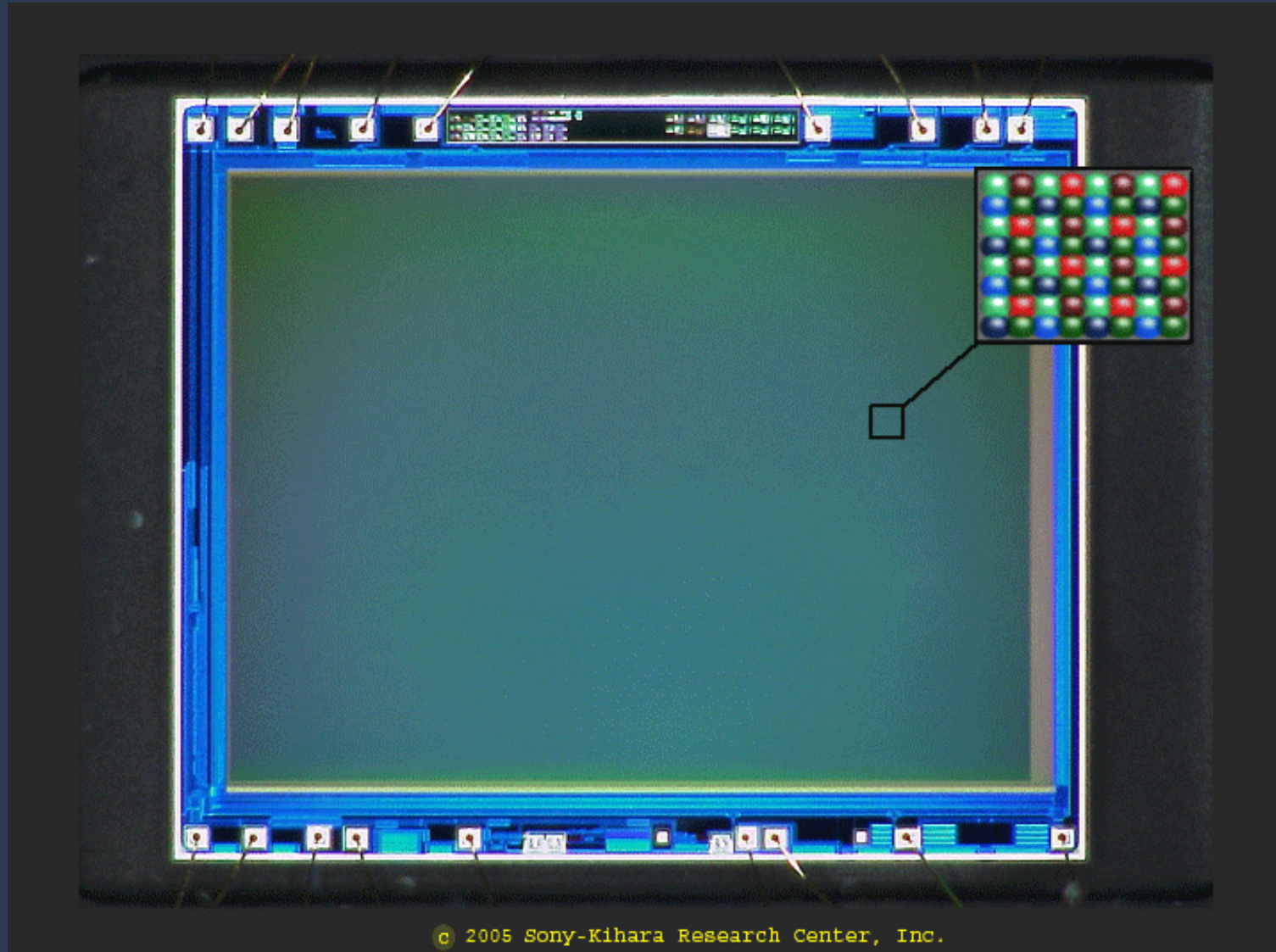
Multi-Sampled SVEC Image

Original Scene

- Can we do better than interpolating separately along different imaging dimensions?
- Can we beat a reconstruction method that is limited by Nyquist's sampling rate?

Assorted-Pixel Camera Prototype

(Courtesy : Sony Kihara Research Lab)



Assorted-Pixel Camera Prototype

(Courtesy : Sony Kihara Research Lab)

Digital Still Camera



Camera with Assorted Pixels



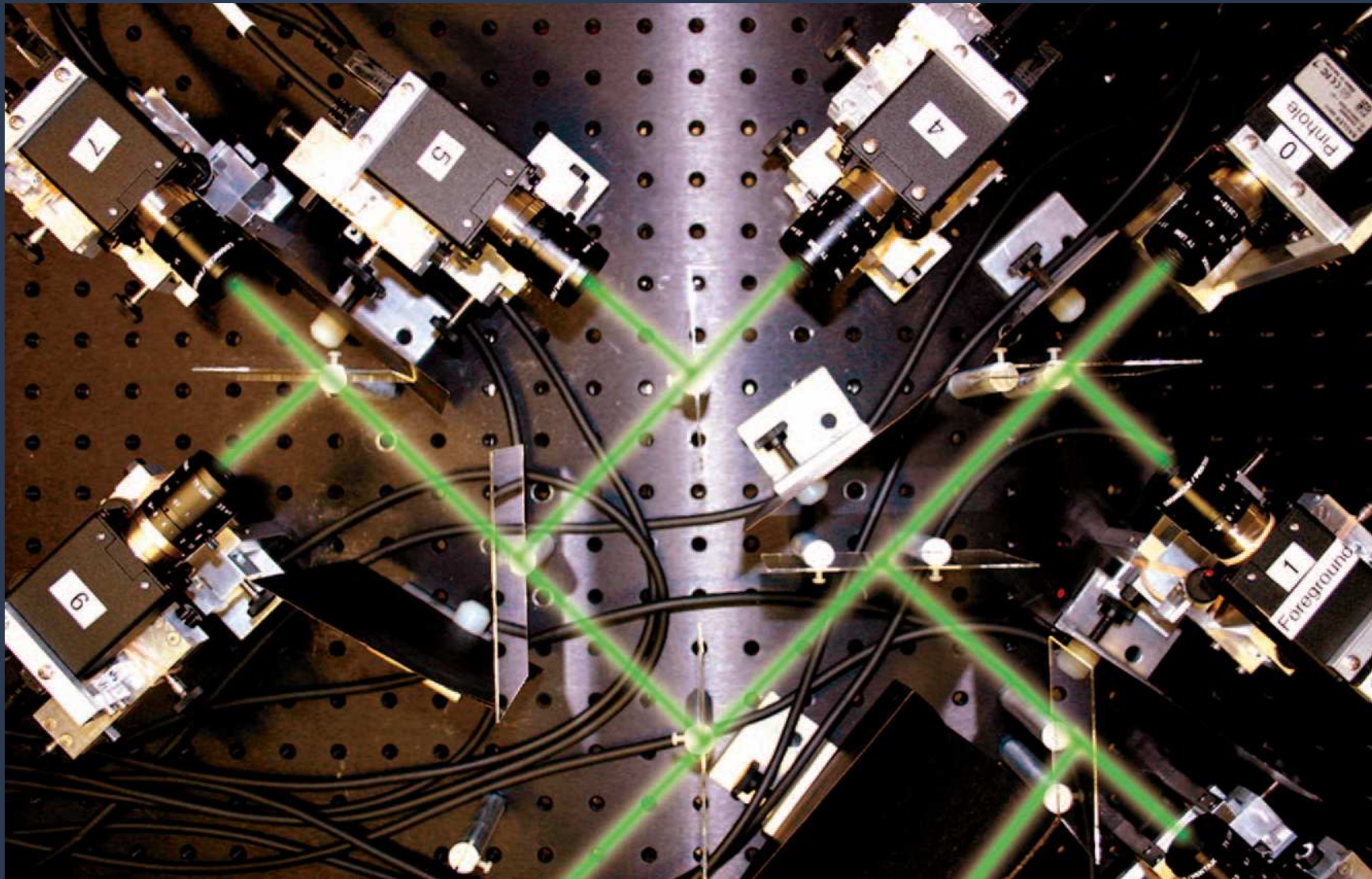
Normal Camera



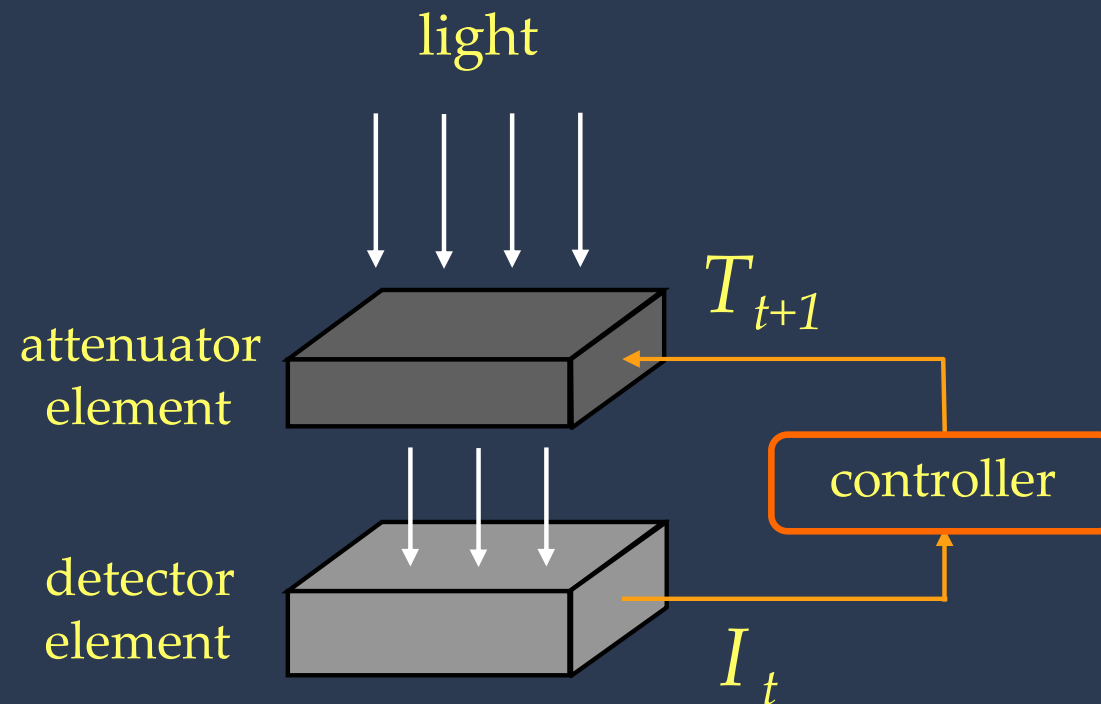
Assorted Pixel Camera



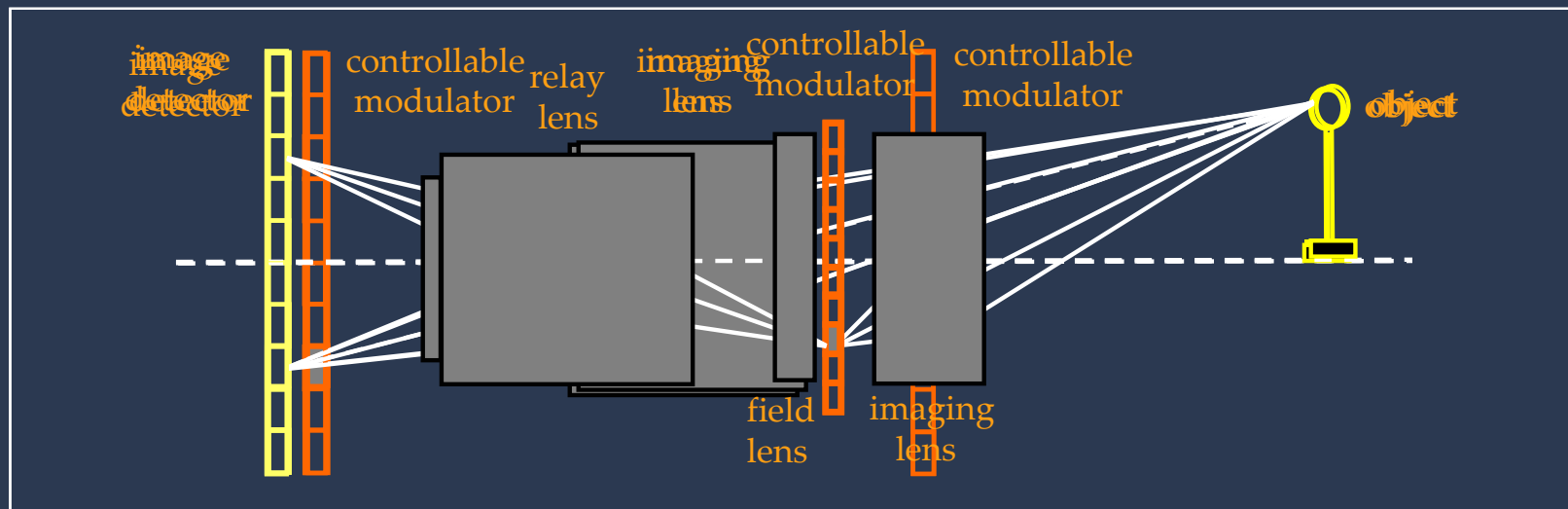
Optical Beam Splitting with Multiple Sensors



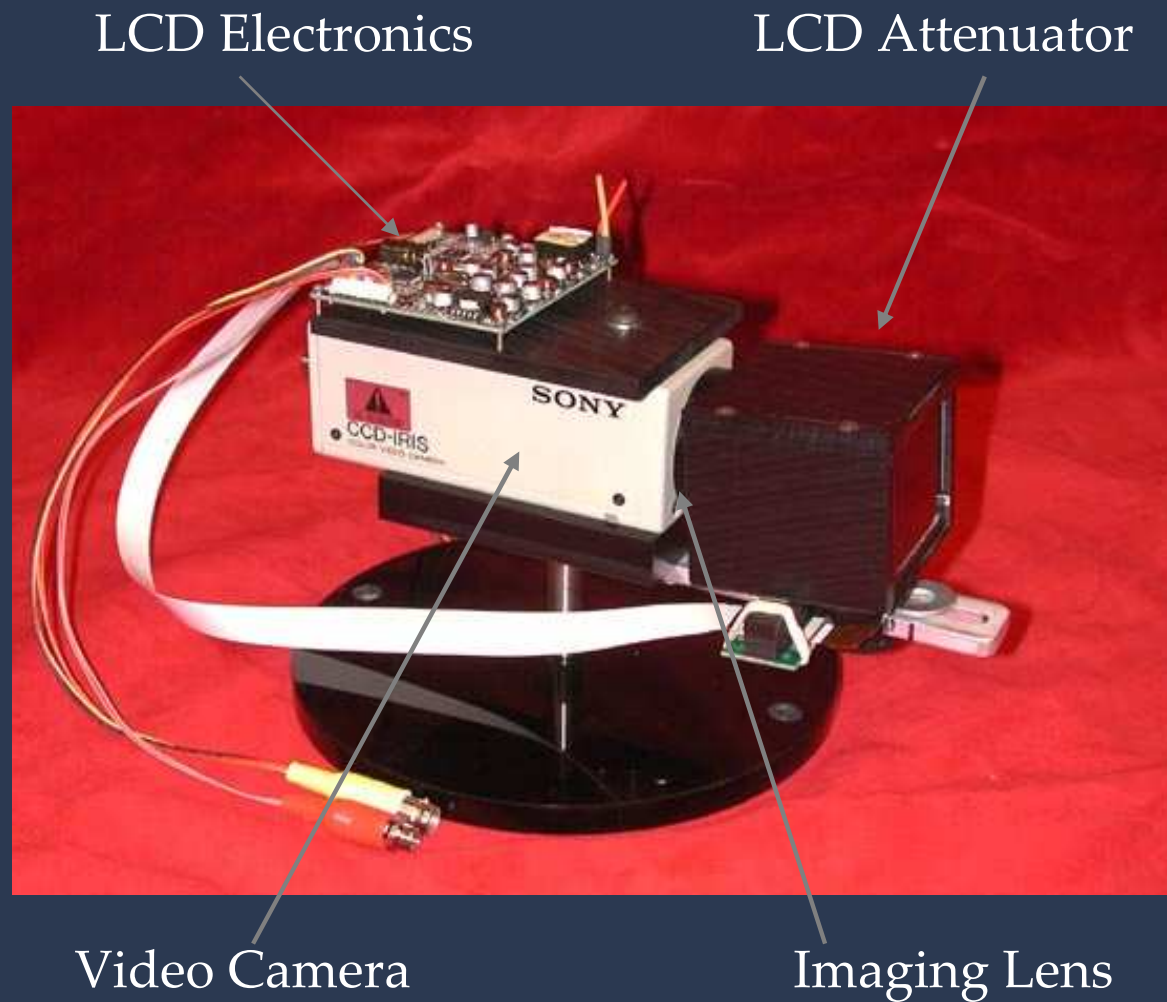
Pixel with Adaptive Exposure Control



Spatial Light Modulation (SLM)



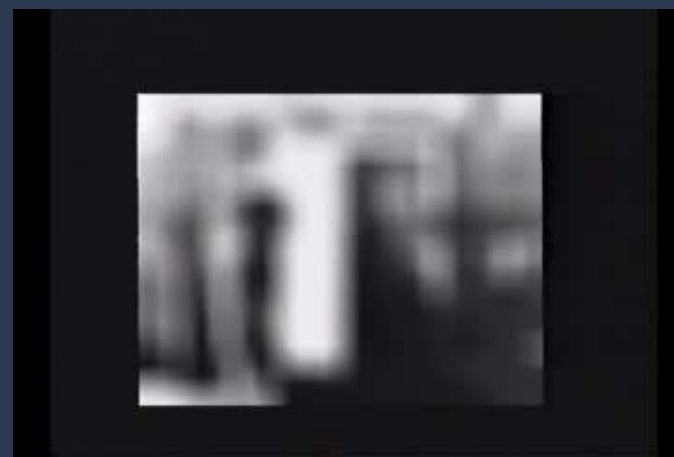
Adaptive Dynamic Range Camera (ADR)



Adaptive Dynamic Range Camera (ADR)

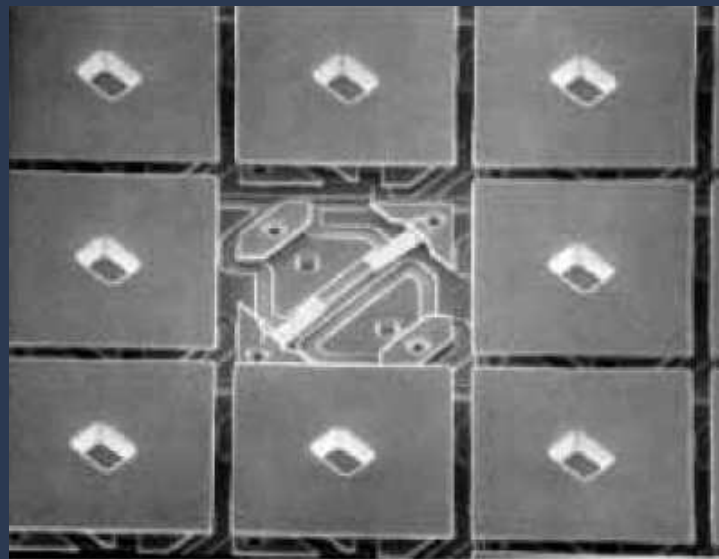


LCD Attenuation



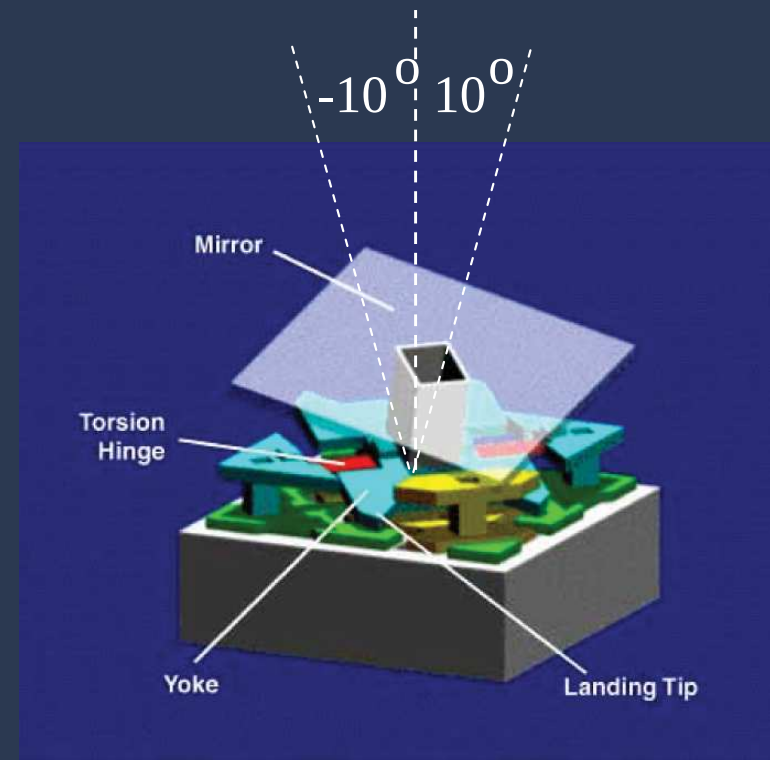
SLM using Digital Micro-mirror Arrays

DMD Array:



14 μm

Micromirror Architecture:



(by Texas Instruments)

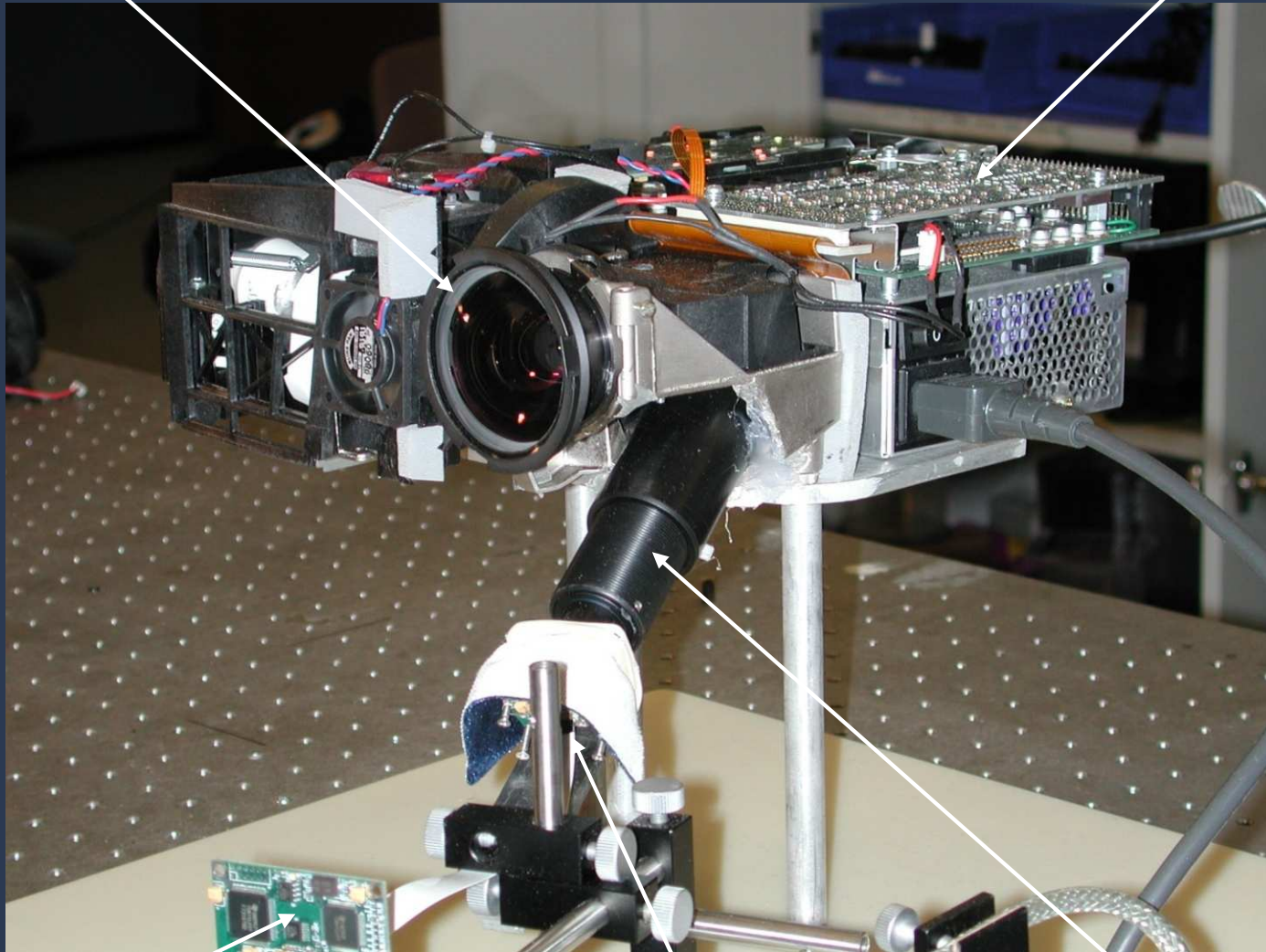
DMD for Imaging:

(Malbet et al. 95, Kearney et al. 98, Castracane et al. 99, Christensen et al. 02)

Programmable Imaging System

Imaging Lens

DMD Electronics



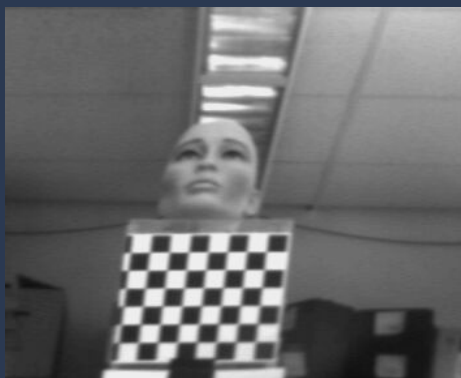
Camera Electronics

Tilted CCD

Lens Focused on DMD

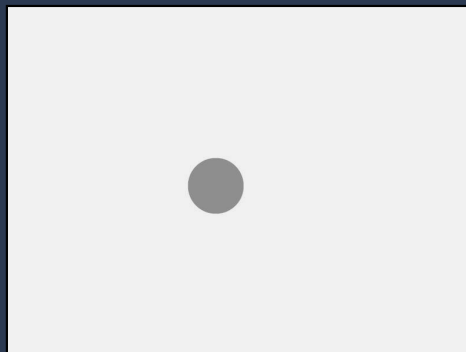
Modulation: Examples

Scene



*

DMD Image

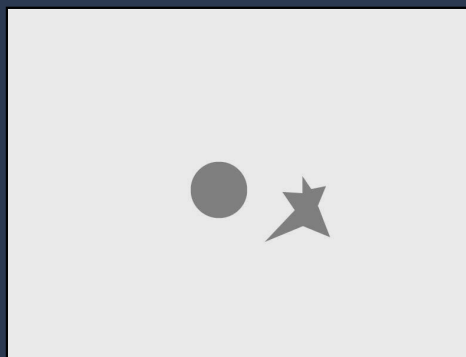


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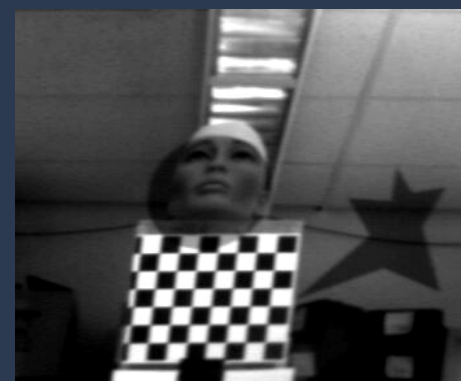
Camera Image



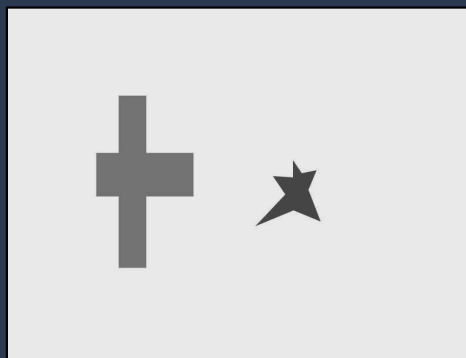
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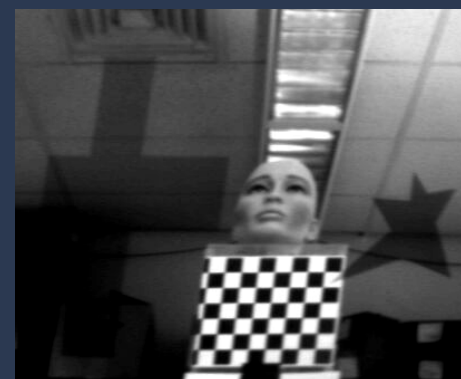
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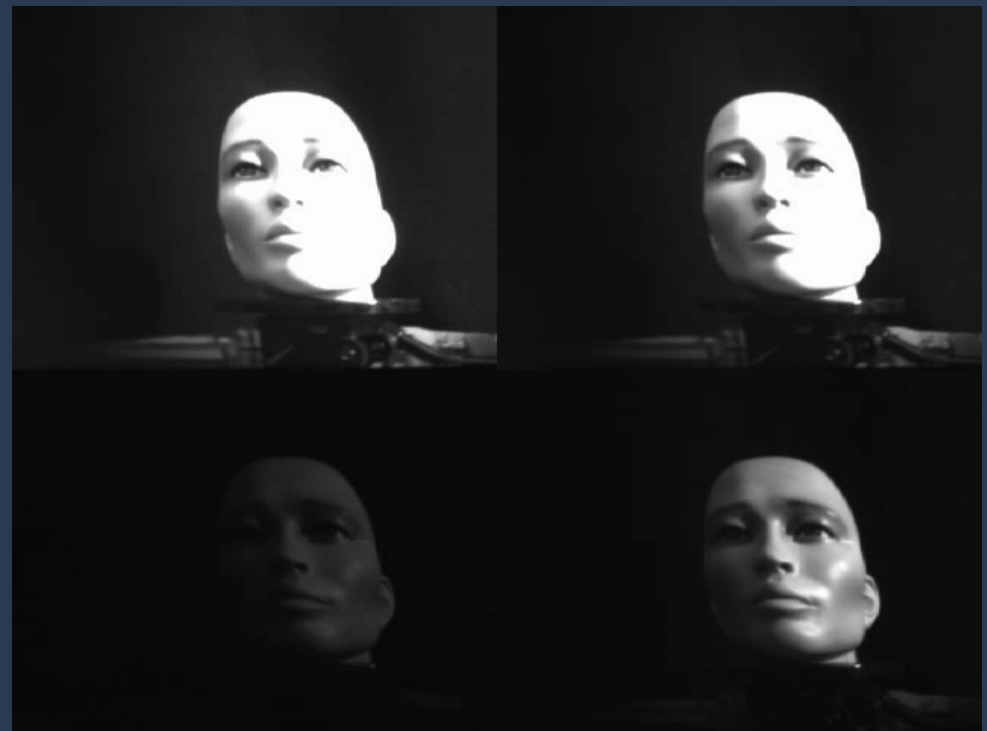


HDR: Temporal Exposure Variation

Captured Temporal Exposure Video
(4 Exposures)

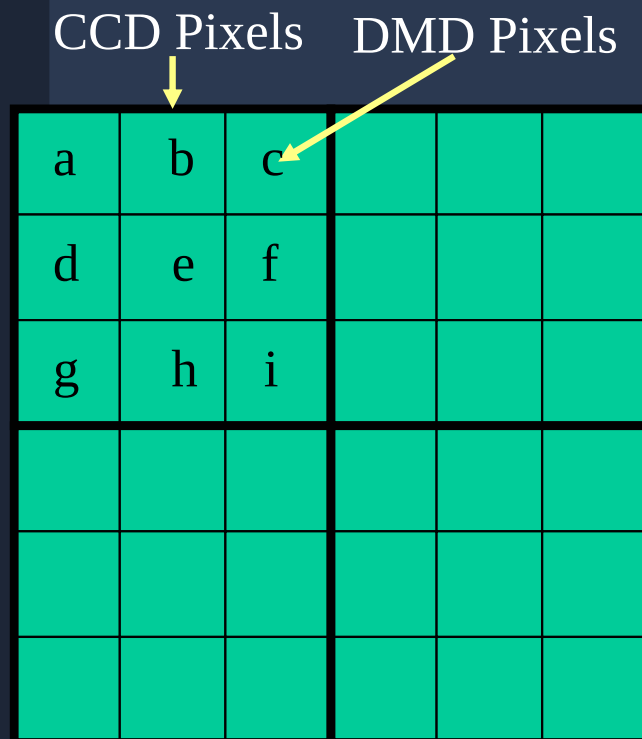


Multiple Video Streams with
Different Exposures



(Ginosar et al. 92, Kang et al. 03)

Optical Intra-Pixel Feature Detection



Laplacian:

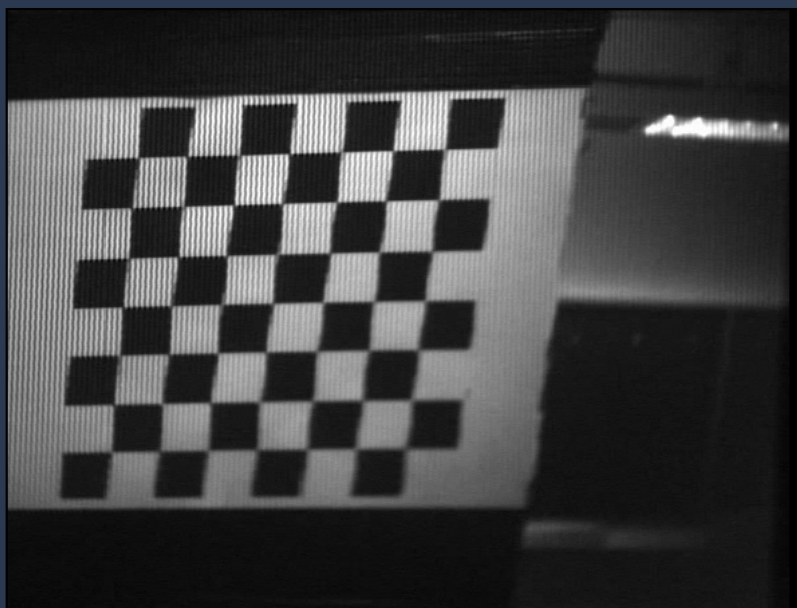
$$\begin{bmatrix} 1 & 4 & 1 \\ 4 & -20 & 4 \\ 1 & 4 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 4 & 1 \\ 4 & 0 & 4 \\ 1 & 4 & 1 \end{bmatrix} - \begin{bmatrix} 0 & 0 & 0 \\ 0 & 20 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Laplacian Image:

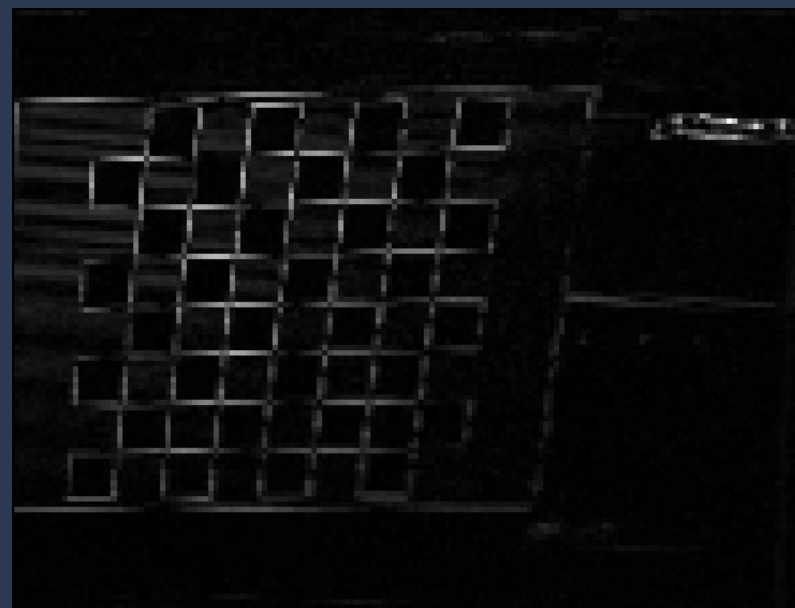
$$\begin{bmatrix} 1 & 4 & 1 & 1 & 4 & 1 \\ 4 & 0 & 4 & 4 & 0 & 4 \\ 1 & 4 & 1 & 1 & 4 & 1 \\ 1 & 4 & 1 & 1 & 4 & 1 \\ 4 & 0 & 4 & 4 & 0 & 4 \\ 1 & 4 & 1 & 1 & 4 & 1 \end{bmatrix} - \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 20 & 0 & 0 & 20 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 20 & 0 & 0 & 20 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Optical Edge Detection

Scene Video



Edge Video



Optical Appearance Matching

Real-Time Recognition

