

Instruction Selection

15-411/15-611 Compiler Design

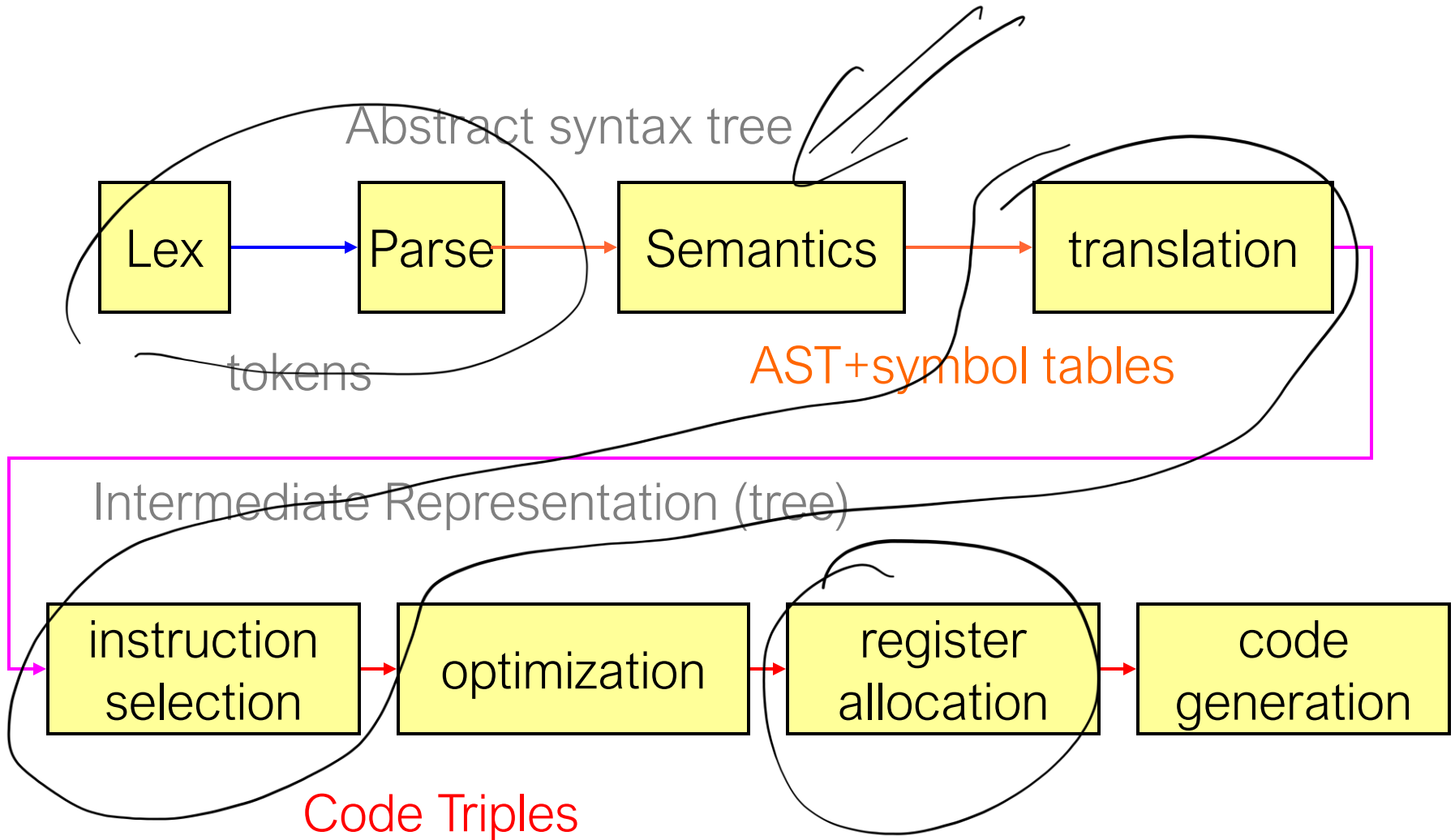
Seth Copen Goldstein

January 22, 2026

Today

- Context
- Abstract Assembly
- $AST \rightarrow IR$
- Maximal Munch
- Issues
- Simple SSA
- x86 and 2-adr Instructions

Cartoon Compiler



Simple Source Language

- A language of assignments, expressions, and a return statement.
- Straight-line code
- Basically lab1 subset of C0

Simple Source Language

program $:= s_1 ; s_2 ; \dots s_n ;$ sequence of statements

s $:= v = e$ assignment

 | **return** e return

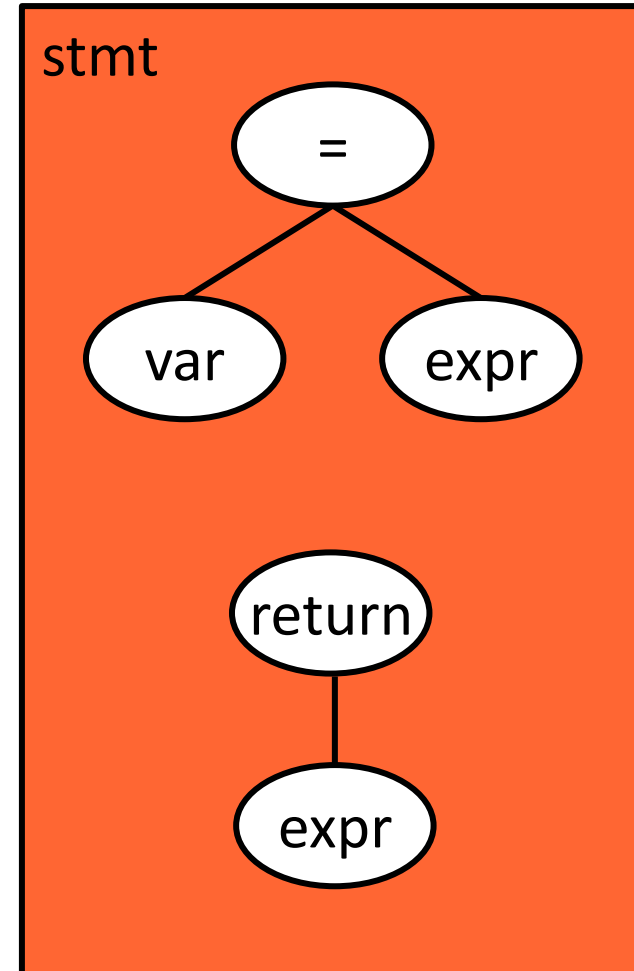
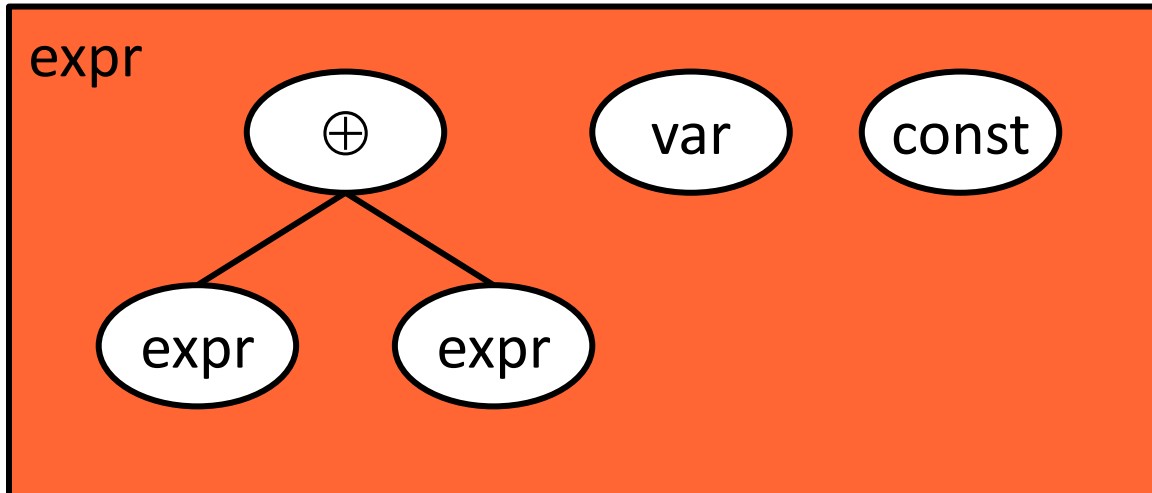
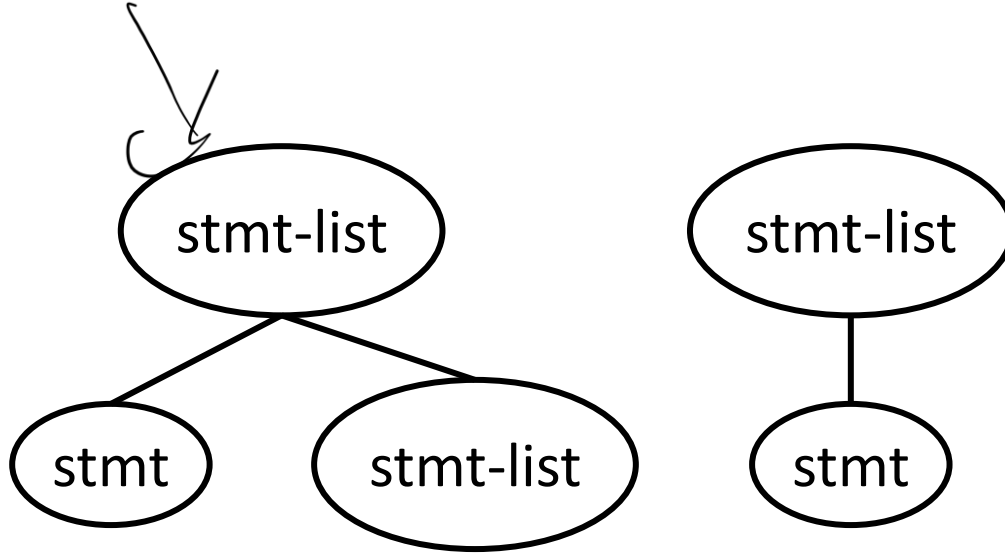
e $:= c$ constant

 | v variable

 | $e_1 \oplus e_2$ binary operation

$\oplus$ $:= + \mid - \mid * \mid / \mid \%$

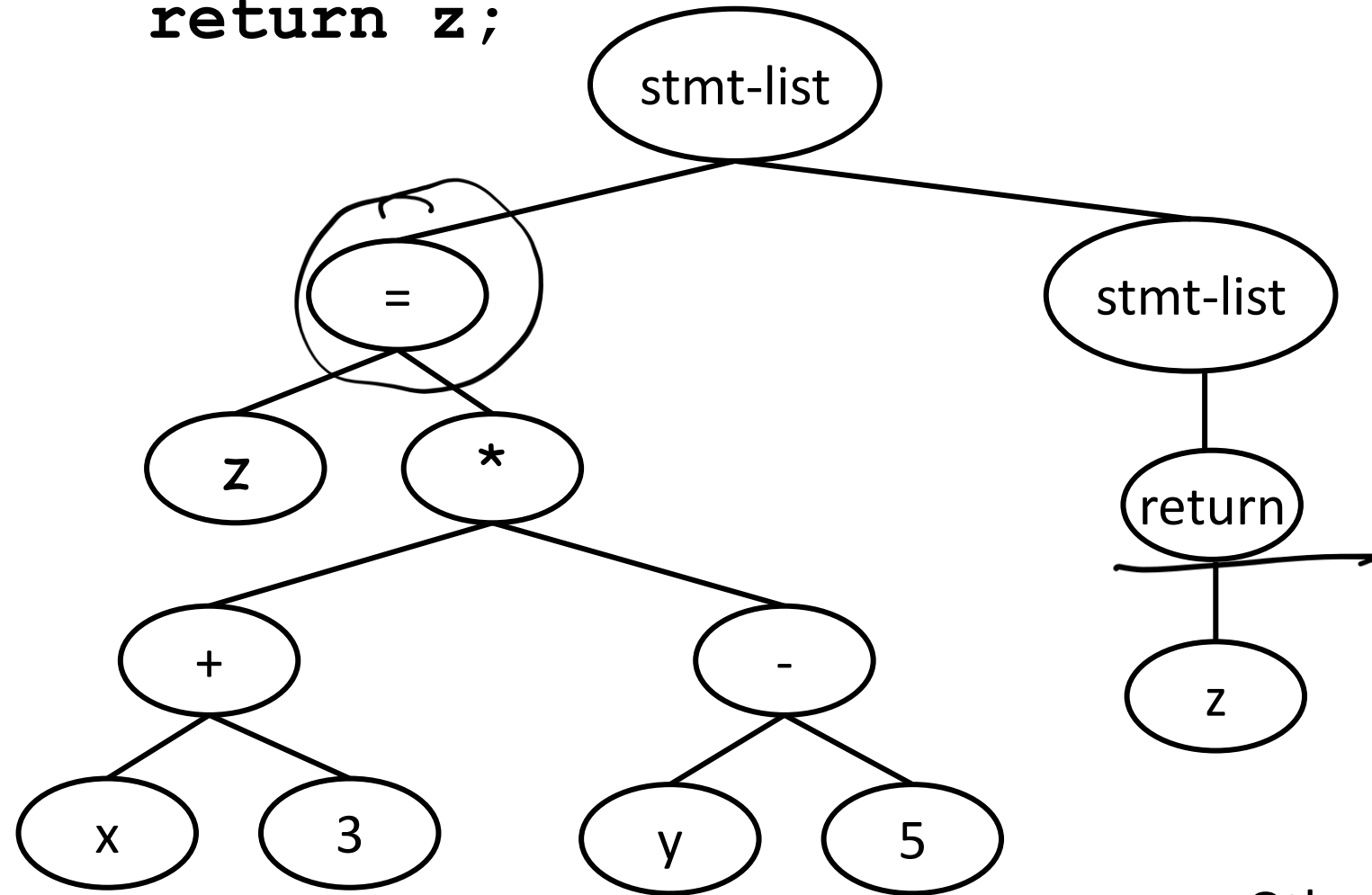
Abstract Syntax Tree



Example

`z = x + 3 * y - 5;`

`return z;`



Other possibilities?

Today

- Context
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Abstract Assembly as IR

- Lowering of AST
- Facilitate
 - Analysis & optimizations
 - Translation to actual assembly
- Features:
 - Unlimited number of “temporaries”
 - May not restrict how memory is used
 - Simple operations
 - May not restrict how constants are used
 - May specify certain “special registers”

Abstract Assembly as IR

- Features:
 - Unlimited number of “registers” (aka “temps”)
 - May (or may not) restrict how memory is used
 - Simple operations
 - May not restrict how constants are used
 - May specify certain “special registers”
- Form:



$\text{dest} \leftarrow \text{src}_1 \text{ operator } \text{src}_2$
 $\text{dest} \leftarrow \text{operator } \text{src}_1$
 operator

src can be:

- constant
- temp
- special register
- memory

Abstract Assembly

program := $i_1 i_2 \dots i_n$ seq of instructions

i := $d \leftarrow s$ move

 | $d \leftarrow s_1 \oplus s_2$ binop

 | **return** return what is in **rax**

The ABI log

s := c intermediate

 | t temporary

 | r register

d := t

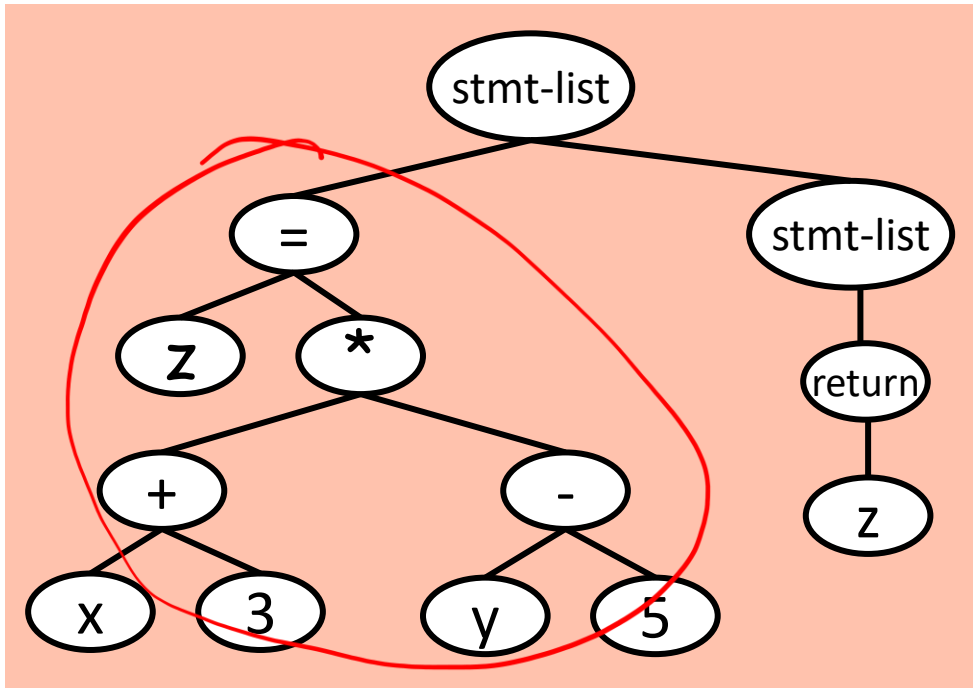
 | r

$\oplus$:= + | - | * | / | %

Example Goal

```
z = x + 3 * y - 5;  
return z;
```

61/4



t1 ← x + 3
t2 ← y - 5
z ← t1 * t2
rax ← z
return

Today

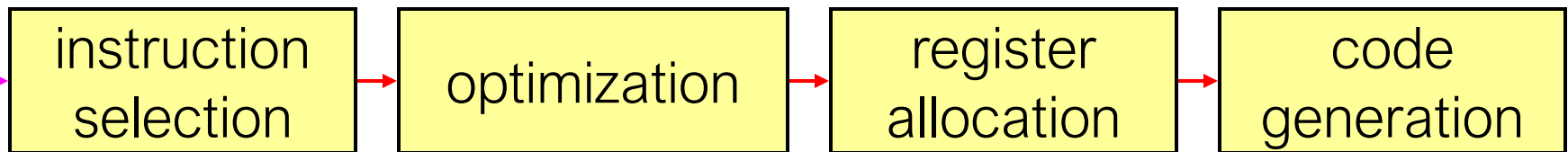
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Abstract syntax tree



Intermediate Representation (tree)



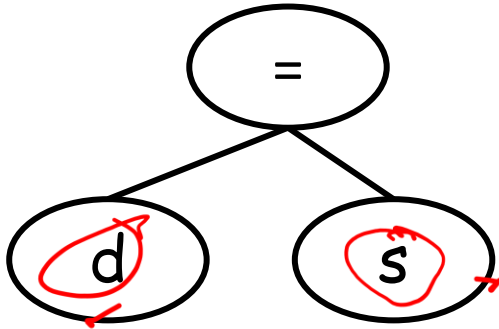
~~Code Triples~~

Alternatives abound

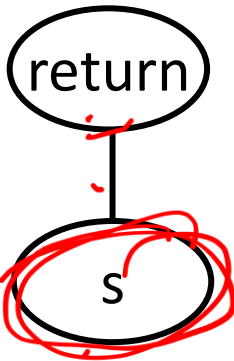
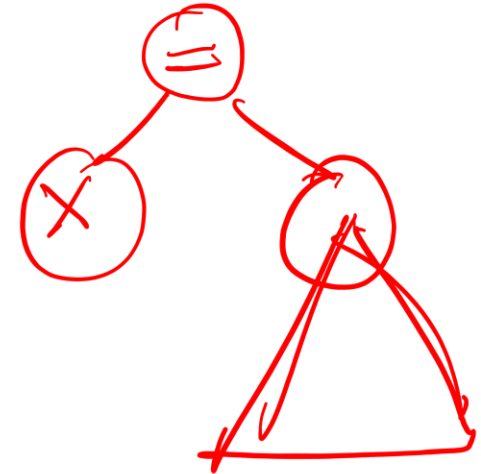
Translating AST to IR

- Converting from tree structured IR to sequence of instructions
 - Create temporary locations to store values
 - choose which operations we want
 - can combine or
 - breakup original operations
- Match portions of tree and convert to triple

Tree Patterns (aka Tiles)

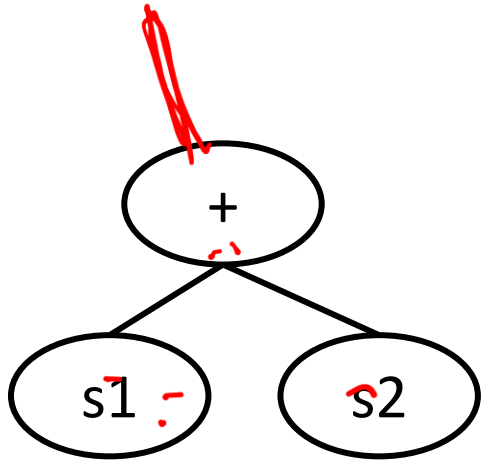


$d \leftarrow s$
min s, d



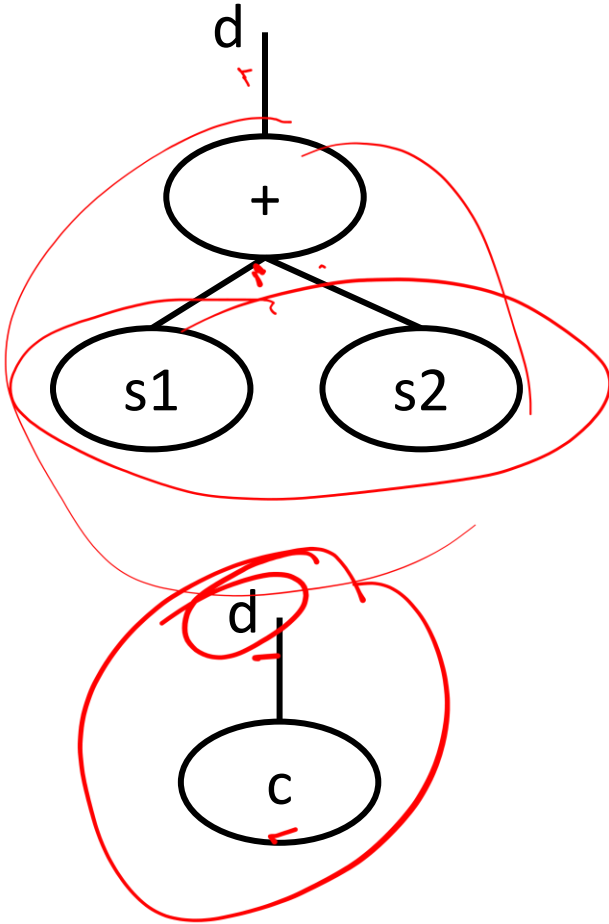
$rax \leftarrow s$
ret

Tree Patterns



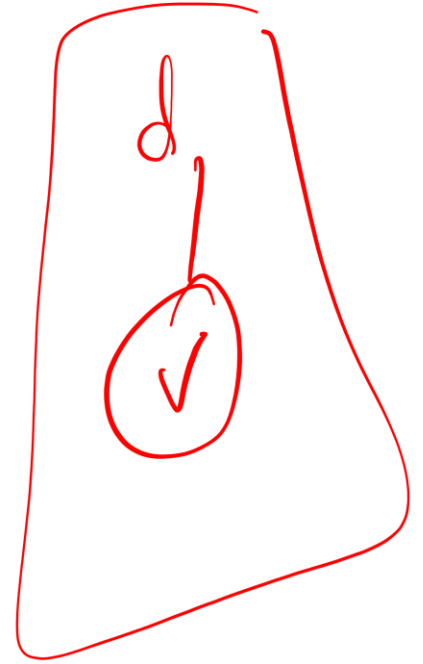
$s1 + s2$

Tree Patterns



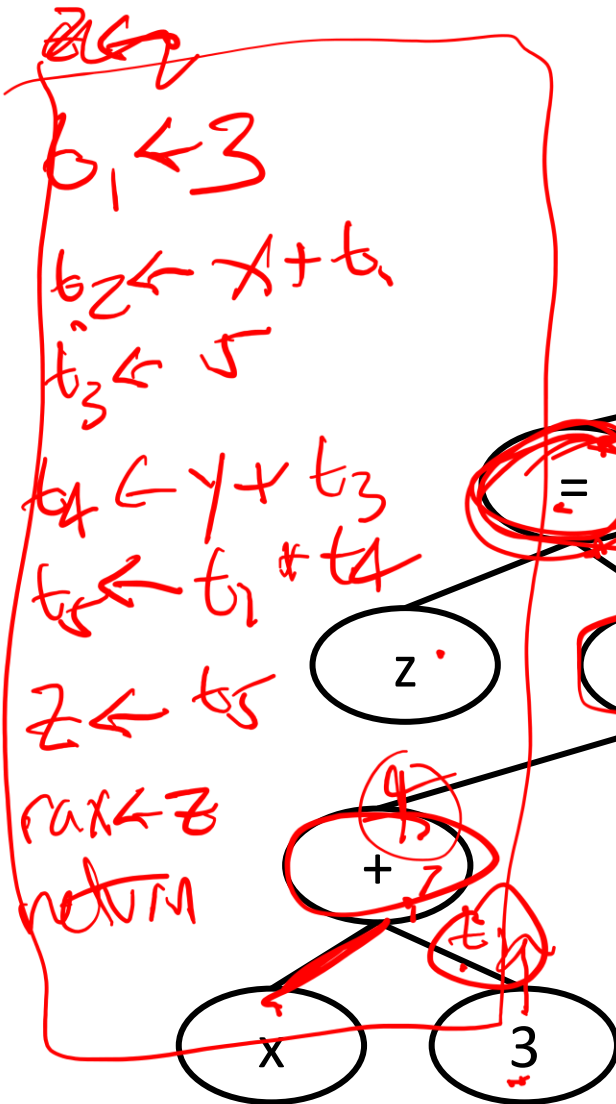
$$d \leftarrow s_1 + s_2$$

$$d \leftarrow c$$

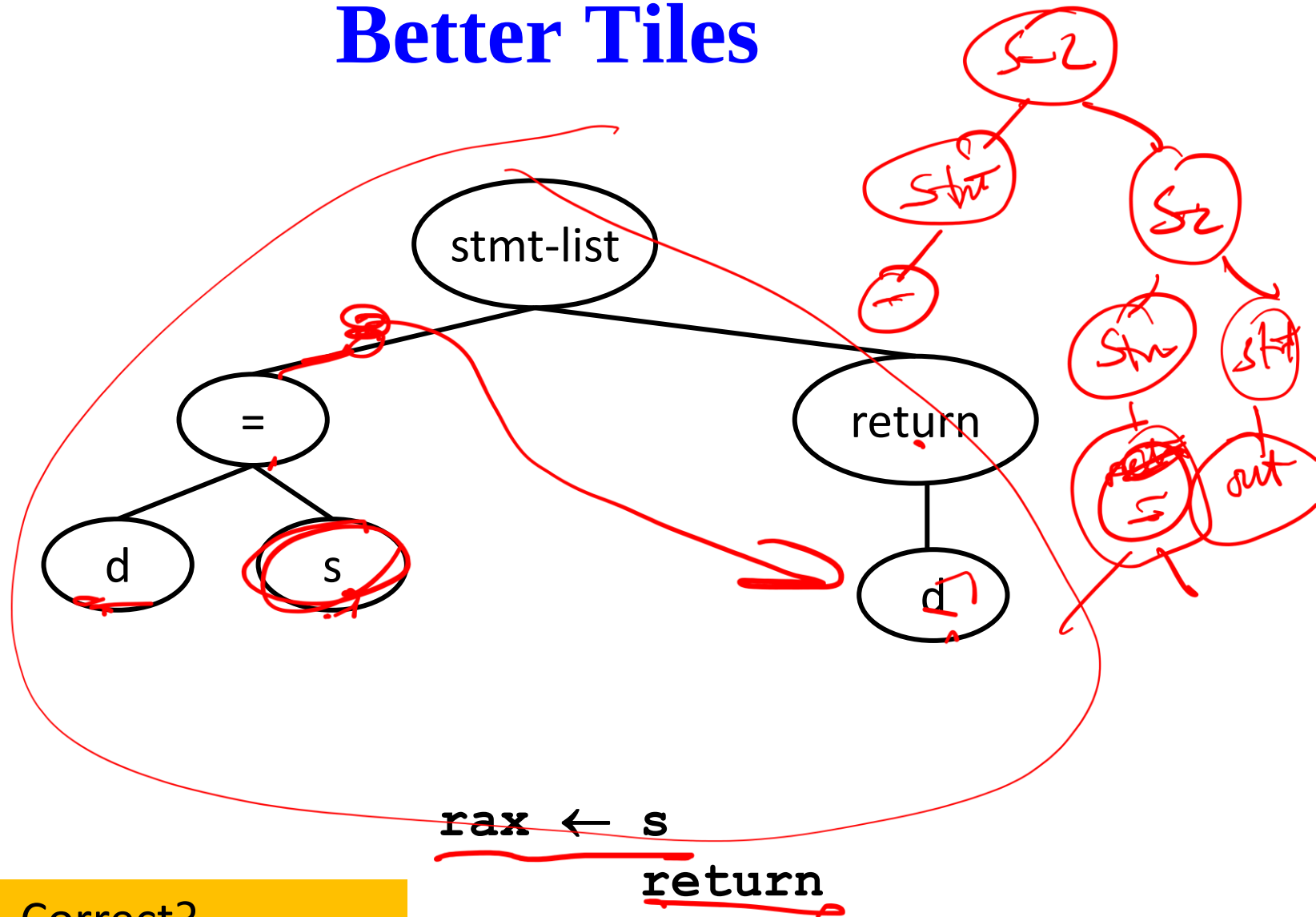


Tiling a Tree

$t_2 \leftarrow x + 3$



Better Tiles



Correct?

If correct: better or worse?

Today

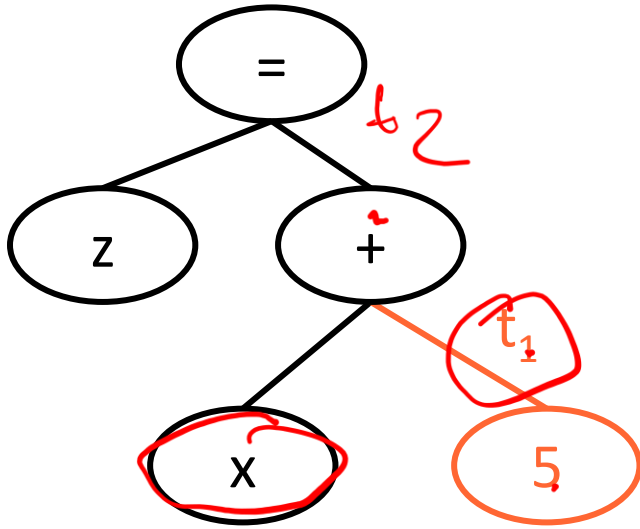
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Maximal Munch

- recursively match tree
- At each step, pick “best” tile

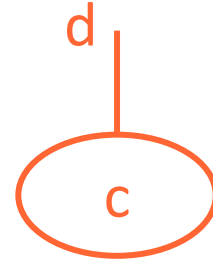
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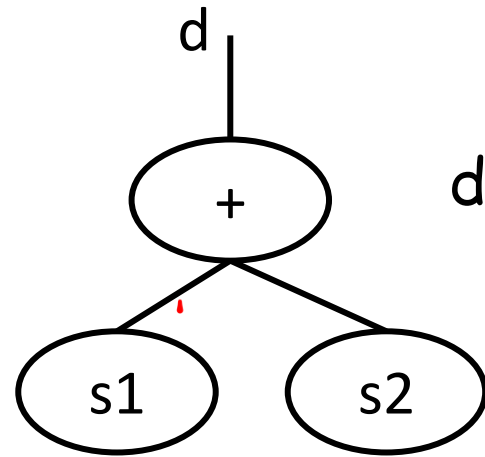


$$t_1 \leftarrow 5$$

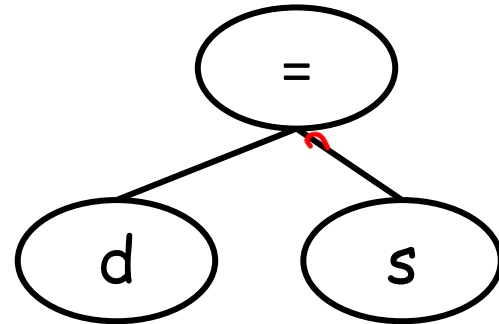
$$t_2 \leftarrow x + t_1$$



$d \leftarrow c$



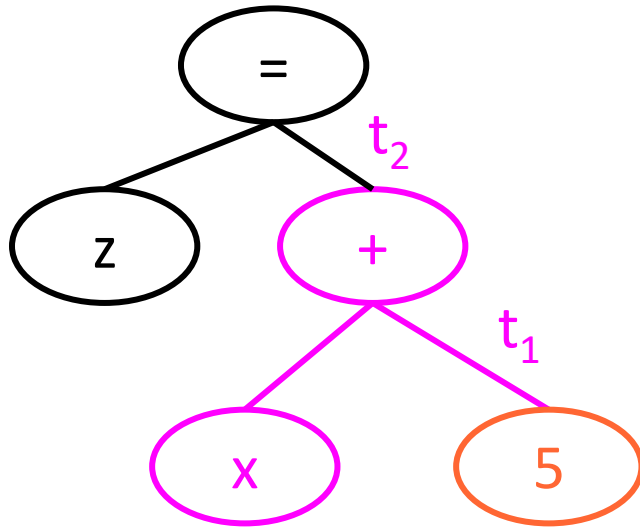
$$d \leftarrow s_1 + s_2$$



$$d \leftarrow s$$

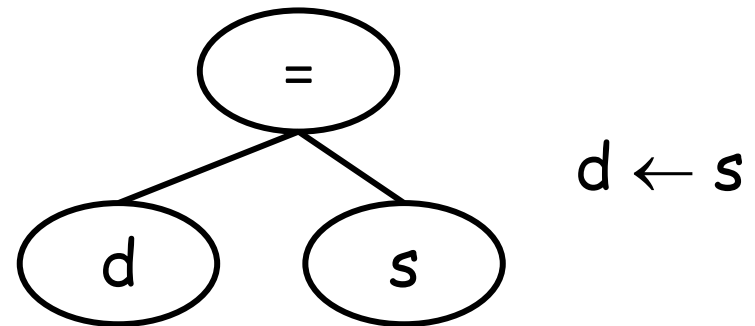
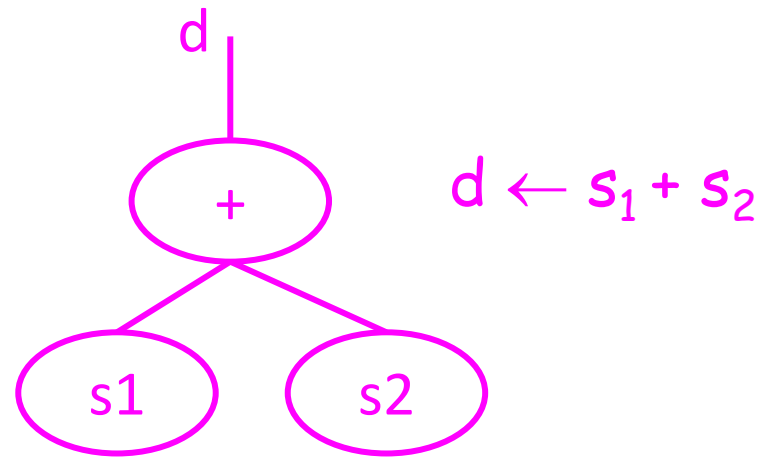
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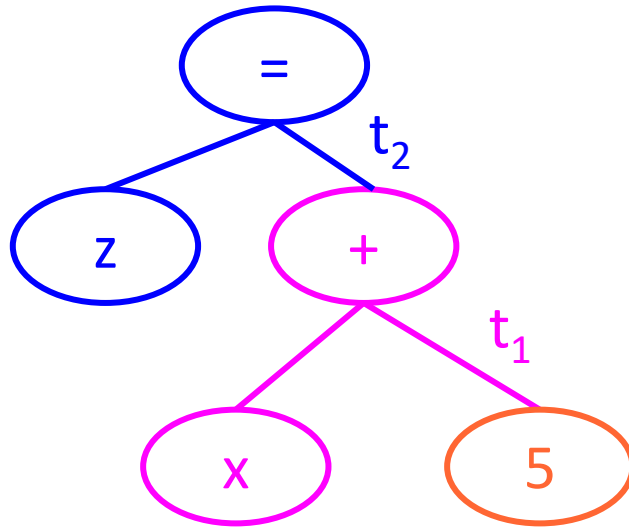
$$t_1 \leftarrow 5$$

$$t_2 \leftarrow x + t_1$$

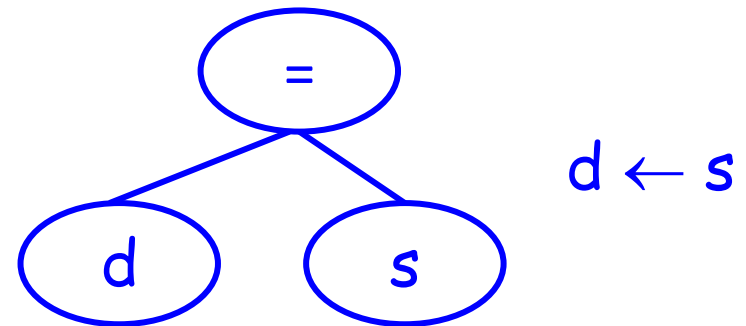
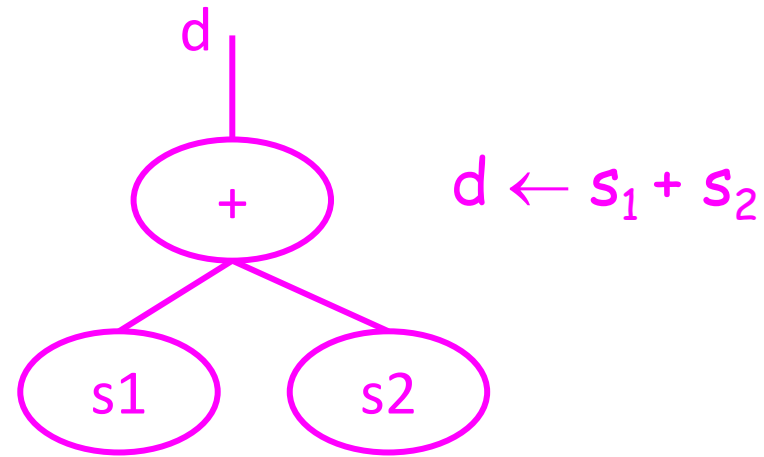


Maximal Munch

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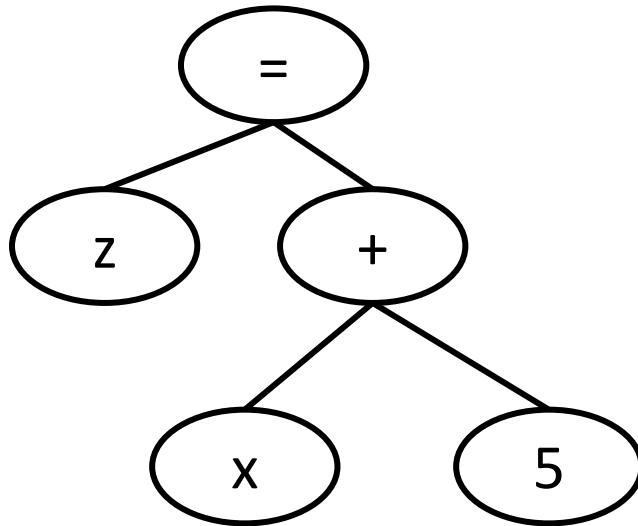
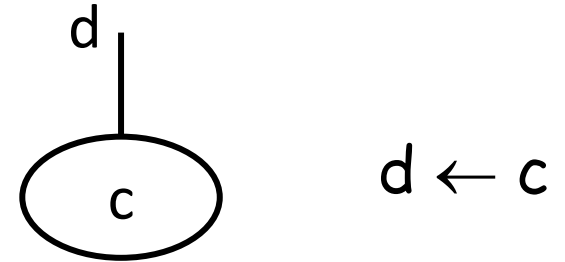


$t_1 \leftarrow 5$
 $t_2 \leftarrow x + t_1$
 $z \leftarrow t_2$

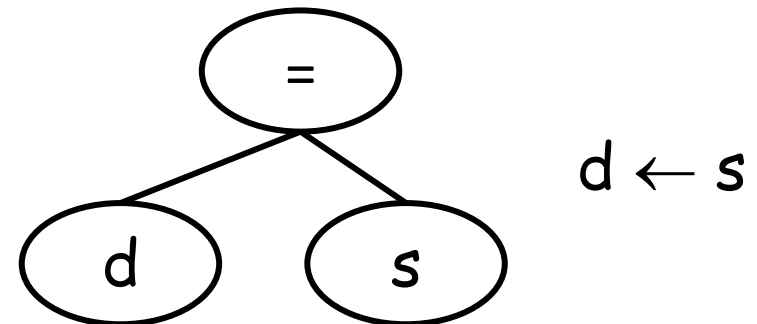
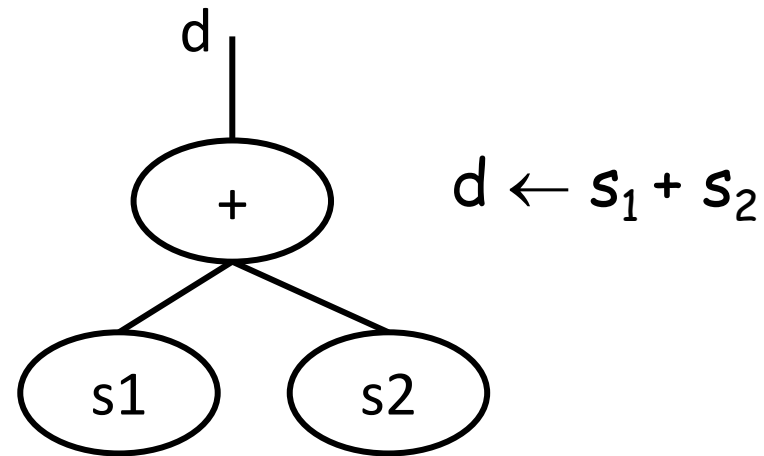


Maximal Munch

- recursively match tree
- At each step, pick “best” tile



$t_1 \leftarrow 5$
 $t_2 \leftarrow x + t_1$
 $z \leftarrow t_2$



Maximal Munch

- recursively match tree
- At each step, pick “best” tile
- need to indicate what destinations are
 - choose either to supply destination
 - or generate a destination

codegen $Codegen(d, e)$

$\textcircled{z}$

$\downarrow d$
 $\textcircled{c}$

$\textcircled{+}$
 $e_1 \quad e_2$

e	codegen(d, e)
c	$d \leftarrow c$
$\textcircled{v}$	$d \leftarrow z$
$\textcircled{+} \quad e_1 \oplus e_2$	$Codegen(t_1, e_1)$ <u>fresh t_1 & t_2</u> $Codegen(t_2, e_2)$ $\textcircled{d \leftarrow t_1 \oplus t_2}$
s	codegen(s)
$v = e$	$Codegen(v, e)$ <u>fresh t</u> , v
<u>return e</u>	$Codegen(Rax, e)$ return

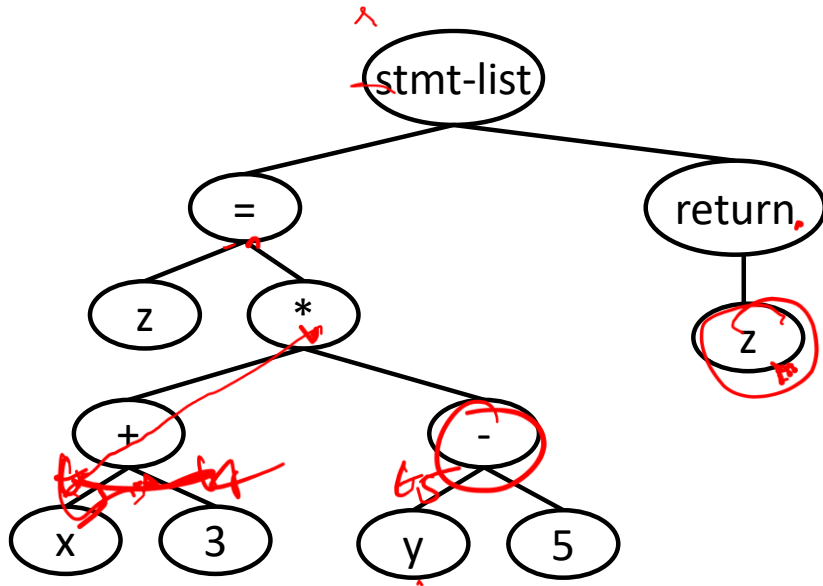
codegen

e	codegen(d, e)
c	$d \leftarrow c$
v	$d \leftarrow v$
$e_1 \oplus e_2$	codegen(t_1 , e_1) codegen(t_2 , e_2) $d \leftarrow t_1 \oplus t_2$

s	codegen(s)
$v = e$	codegen(v, e)
return e	codegen(rax, e) return



Example

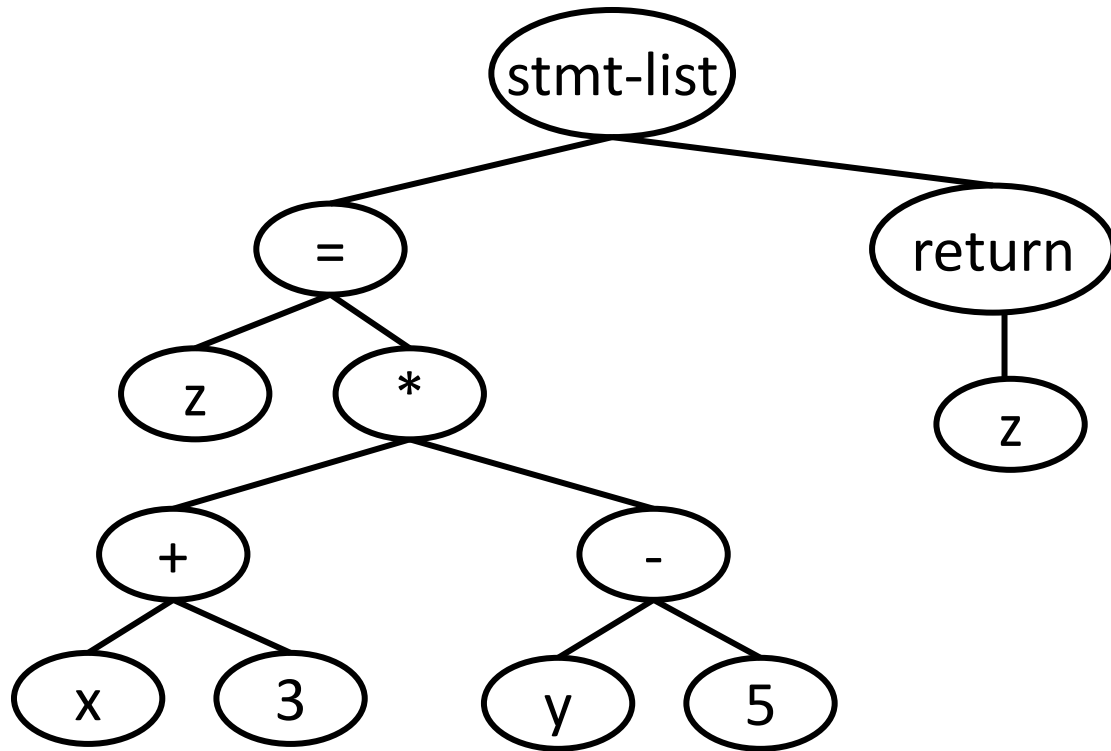


e	codegen(d, e)
c	$d \leftarrow c$
v	$d \leftarrow x$
$e_1 \oplus e_2$	$\text{codegen}(t_1, e_1)$ $\text{codegen}(t_2, e_2)$ $d \leftarrow t_1 \oplus t_2$
s	codegen(s)
$v = e$	$\text{codegen}(v, e)$
return e	$\text{codegen}(rax, e)$ return

$t_3 \leftarrow x$
 $t_4 \leftarrow 3$
 $t_1 \leftarrow t_3 + t_4$
 $t_5 \leftarrow y$
 $t_6 \leftarrow 5$
 $t_2 \leftarrow t_5 - t_6$
 $z \leftarrow t_1 * t_2$
 $rax \leftarrow z$
 return

~~$\text{codegen}(t_1, t_2)$~~
 ~~$\text{cg}(t_1, t_2)$~~
 ~~$\text{cg}(t_3, x)$~~
 ~~$\text{cg}(t_4, 3)$~~

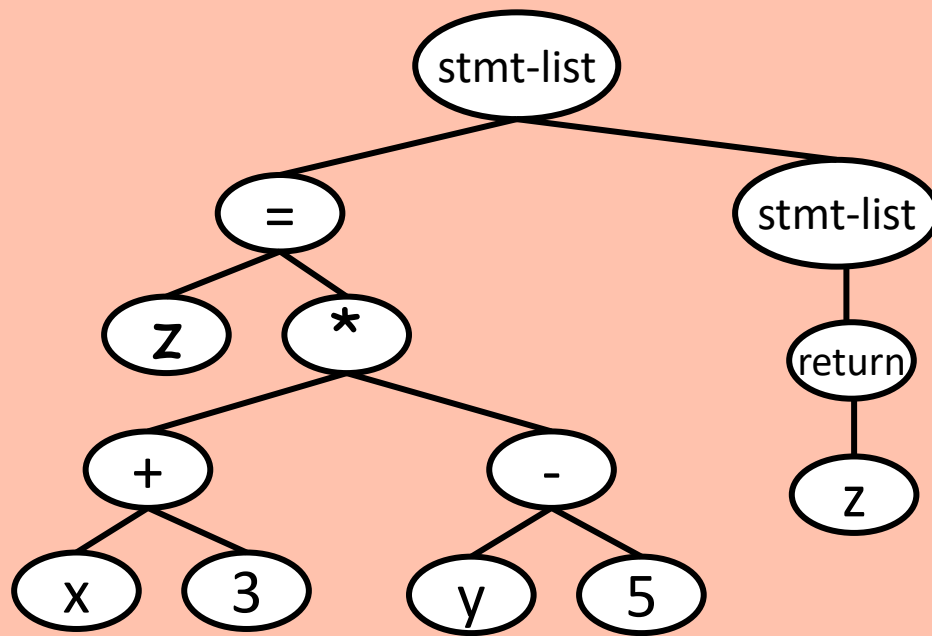
Result



$t_3 \leftarrow x$
 $t_4 \leftarrow 3$
 $t_1 \leftarrow t_3 + t_4$
 $t_5 \leftarrow y$
 $t_6 \leftarrow 5$
 $t_2 \leftarrow t_5 * t_6$
 $z \leftarrow t_1 * t_2$
 $rax \leftarrow z$
 ret

Example Goal

```
z = x + 3 * y - 5;  
return z;
```



```
t1 ← x + 3  
t2 ← y - 5  
z ← t1 * t2  
rax ← z  
return
```

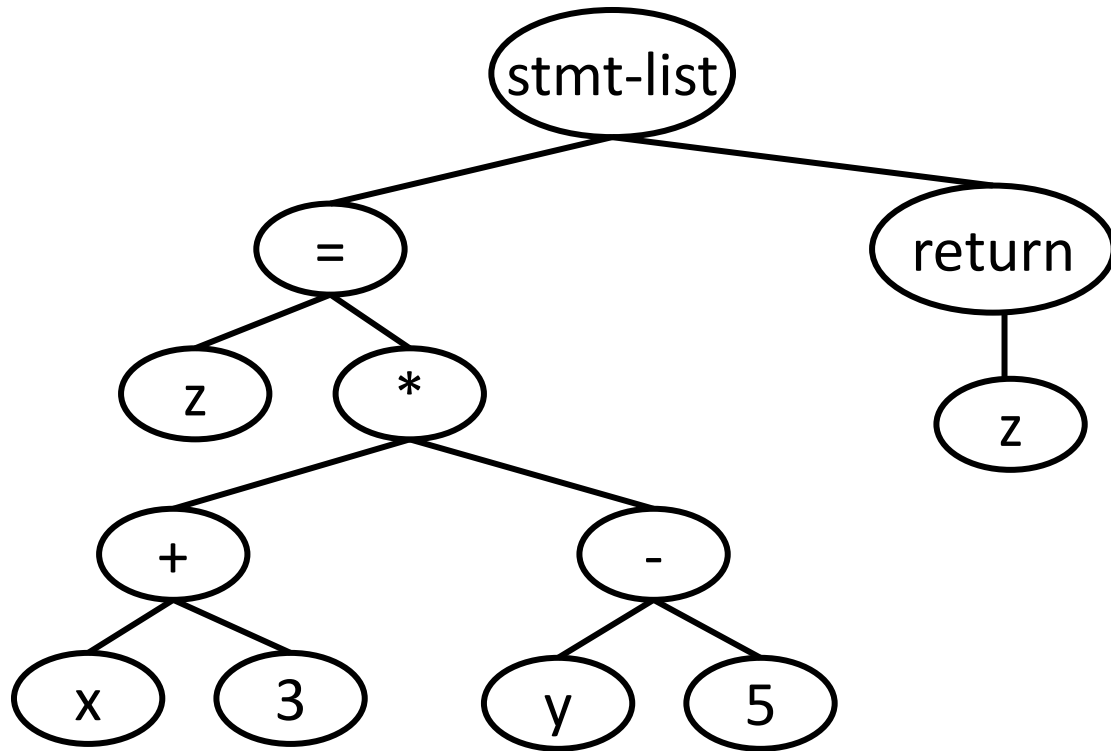
Goal

```
t1 ← x + 3
t2 ← y - 5
z  ← t1 * t2
rax ← z
    return
```

What we got

```
t3 ← x
t4 ← 3
t1 ← t3 + t4
t5 ← y
t6 ← 5
t2 ← t5 * t6
z  ← t1 * t2
rax ← z
    ret
```

How Can we Improve this?



$t_3 \leftarrow x$

$t_4 \leftarrow 3$

$t_1 \leftarrow t_3 + t_4$

$t_5 \leftarrow y$

$t_6 \leftarrow 5$

$t_2 \leftarrow t_5 * t_6$

$z \leftarrow t_1 * t_2$

$rax \leftarrow z$

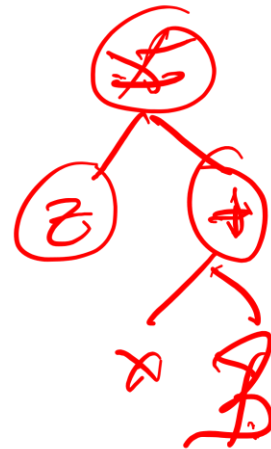
ret

How Can we Improve this?

- Investigate generating a source operand
- Special cases
- Don't bother?

Generating Destinations

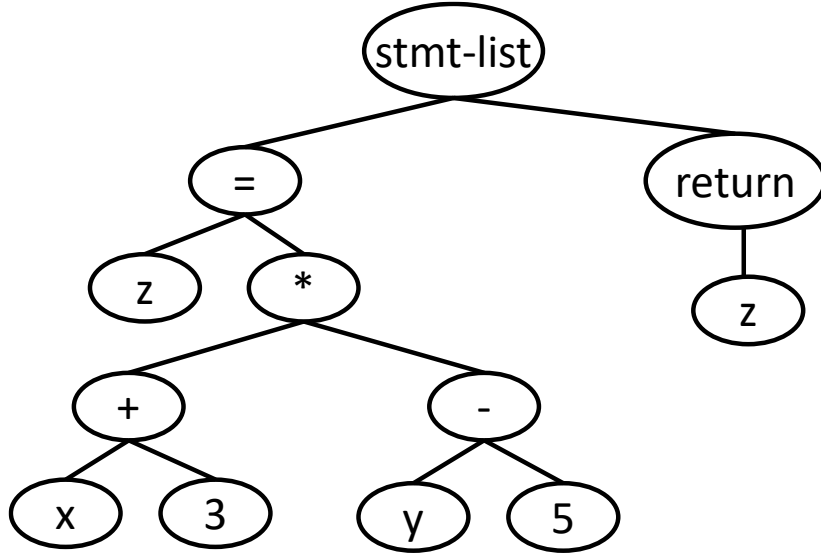
e	codegen(e)	up
c		c
v		v
$e_1 \oplus e_2$	$t_1 = \text{codegen}(e_1) \oplus \text{codegen}(e_2)$	t_1



s	codegen(s)
$v = e$	$v \leftarrow \text{codegen}(e)$
return e	$\text{rax} \leftarrow \text{codegen}(e)$ return



Example



e	codegen(e)	up
c		c
v		v
$e_1 \oplus e_2$	$t_1 = \text{codegen}(e_1) \oplus \text{codegen}(e_2)$	t_1

s	codegen(s)
$v = e$	$v \leftarrow \text{codegen}(e)$
return e	$\text{rax} \leftarrow \text{codegen}(e)$ return

Special Cases

e	codegen(d, e)
c	$d \leftarrow c$
v	$d \leftarrow x$
$c \oplus e_2$	$\text{codegen}(t_2, e_2)$ $d \leftarrow c \oplus t_2$
$e_1 \oplus c$	$\text{codegen}(t_1, e_1)$ $d \leftarrow t_1 \oplus c$
$v \oplus e_2$	$\text{codegen}(t_2, e_2)$ $d \leftarrow v \oplus t_2$
$e_1 \oplus v$	$\text{codegen}(t_1, e_1)$ $d \leftarrow t_1 \oplus v$
$e_1 \oplus e_2$	$\text{codegen}(t_1, e_1)$ $\text{codegen}(t_2, e_2)$ $d \leftarrow t_1 \oplus t_2$

Generally not recommended

The “don’t bother” case

- What should we really do?

$t_3 \leftarrow x$
 $t_4 \leftarrow 3$
 $t_1 \leftarrow t_3 + t_4$
 $t_5 \leftarrow y$
 $t_6 \leftarrow 5$
 $t_2 \leftarrow t_5 * t_6$
 $z \leftarrow t_1 * t_2$
 $rax \leftarrow z$
 ret

		e	codegen(d, e)
Constant Propagation		c	$d \leftarrow c$
		v	$d \leftarrow x$
		$c \oplus e_2$	codegen(t_2 , e_2) $d \leftarrow c \oplus t_2$
		$e_1 \oplus c$	codegen(t_1 , e_1) $d \leftarrow t_1 \oplus c$
Copy Propagation		$v \oplus e_2$	codegen(t_2 , e_2) $d \leftarrow v \oplus t_2$
		$e_1 \oplus v$	codegen(t_1 , e_1) $d \leftarrow t_1 \oplus v$
		$e_1 \oplus e_2$	codegen(t_1 , e_1) codegen(t_2 , e_2) $d \leftarrow t_1 \oplus t_2$

Constant Propagation

$t_3 \leftarrow x$

~~$t_4 \leftarrow 3$~~

$t_1 \leftarrow t_3 + t_4 \quad 3$

$t_5 \leftarrow y$

~~$t_6 \leftarrow 5$~~

$t_2 \leftarrow t_5 * t_6 \quad 5$

$z \leftarrow t_1 * t_2$

$rax \leftarrow z$

ret

Copy Propagation

~~$t_3 \leftarrow x$~~

$t_1 \leftarrow \cancel{t_3} x + 3$ ✓

~~$t_5 \leftarrow y$~~

$t_2 \leftarrow \cancel{t_5} y * 5$ ✓

$z \leftarrow t_1 * t_2$ ✓

$rax \leftarrow z$ ✓

ret

Have to be careful

- Constant propagation:

$x \leftarrow 5$

$y \leftarrow \cancel{x} - 4 + 1$

$x \leftarrow \cancel{y} + 7 + 8$

$z \leftarrow \cancel{x}$

- Copy Propagation:

$x \leftarrow y$

$y \leftarrow u - 4$

$z \leftarrow x + 7$

Have to be careful

- Constant propagation:

- Can't just replace all x's with 5
- Stop if x is redefined

x ← 5

y ← x - 4

x ← y + 7

z ← x

- Copy Propagation:

x ← y

y ← u - 4

z ← x + 7

Have to be careful

- Constant propagation:

- Can't just replace all x's with 5
- Stop if x is redefined

x ← 5

y ← x - 4

x ← y + 7

z ← x

- Copy Propagation:

- Can't just replace all x's with y's
- Stop if x or y is redefined

x ← y

y ← u - 4

z ← x + 7

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Static Single Assignment

- Must keep track of what definition each use refers to in order to properly do constant/copy propagation.
- Much simpler if only one definition for each name.
- SSA: Each name is assigned in only one location.

Static Single Assignment

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- SSA: Each name is **assigned** in only one location.
- Easy for fresh temporaries

e	codegen(d, e)
$e_1 \oplus e_2$	codegen(t_1 , e_1) codegen(t_2 , e_2) $d \leftarrow t_1 \oplus t_2$

Static Single Assignment

- Must keep track of what definition each use refers to in order to properly do constant/copy propagation.
- Much simpler if only one definition for each name.
- SSA: Each name is **assigned** in only one location.
- Easy for fresh temporaries
- What about variables?

SSA for Straight-line code

- Give each variable a version number.
- Scan code in program order
- Whenever we encounter a definition, increment the version number
- Whenever we encounter a use, use the most recently assigned version number.

$x \leftarrow 5$

$y \leftarrow x - 4$

$x \leftarrow y + 7$

$z \leftarrow x$

$x_0 \leftarrow 5$

$y \leftarrow x - 4$

$x \leftarrow y + 7$

$z \leftarrow x$

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$z \leftarrow x$

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$z \leftarrow x$

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$y_0 \leftarrow x_0 - 4$

$x \leftarrow y + 7$

$z \leftarrow x$

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$x_1 \leftarrow y_0 + 7$

$z \leftarrow x$

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$x \leftarrow 5$

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$x \leftarrow y + 7$

$z \leftarrow x$

$x_0 \leftarrow 5$

$y_0 \leftarrow x_0 - 4$

$x_1 \leftarrow y_0 + 7$

$z_0 \leftarrow x_1$

Now easy

- Constant propagation:
 - Can replace all x_0 with 5.

$$x_0 \leftarrow 5$$

$$y_0 \leftarrow x_0 - 4$$

$$x_1 \leftarrow y_0 + 7$$

$$z_0 \leftarrow x_1$$

- Copy Propagation:
 - Can replace all x_0 with y_0

$$x_0 \leftarrow y_0$$

$$y_1 \leftarrow u_0 - 4$$

$$z_0 \leftarrow x_0 + 7$$

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Real Assembly on x86

- x86 doesn't have 3 address instructions!

$$d \leftarrow s_1 + s_2$$

Real Assembly on x86

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$$d \leftarrow s_1 + s_2$$

Triples	2-adr	x86
$d \leftarrow s_1 + s_2$ 	$d \leftarrow s_1$ $d \leftarrow d + s_2$ 	$\text{MOVx } s_1, d$ $\text{ADDx } s_2, d$ 

Real Assembly on x86

- x86 doesn't have 3 address instructions!

Triples	2-adr	x86
$d \leftarrow s_1 + s_2$	$d \leftarrow s_1$ $d \leftarrow d + s_2$	MOVx s_1, d ADDx s_2, d

- All kinds of special register requirements

$$d \leftarrow s_1 * s_2$$

What about edx?

Triples	2-adr	x86
$d \leftarrow s_1 * s_2$	$d \leftarrow s_1$ $d \leftarrow d * s_2$	MOVL s_1, rax IMUL s_2 MOVL rax, d

From AST to Machine Assembly

- Implied Approach:
 - AST → Triples using unlimited temporaries
 - Map temporaries to registers/memory
 - Lower Triples to real assembly
- What about Interaction between registers and instructions?
- Cost model?
- KISS:
 - Keep things simple, but
 - Prepare for other passes to fix things up.