

Lock-free Programming

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Context

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 - Instructions run “out-of-order” on every CPU!
 - Single data items are cached many times on many CPUs!
 - Causality is violated between variables!
- How can any program work??

Context

- Within a CPU
 - Instructions run “out-of-order”
 - *Data dependencies* delay when instructions start
 - Instruction outcomes are *published* when they are safe
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 - All caches return an up-to-date version of each cache line

Context

- Within a CPU
 - Instructions run “out-of-order”
 - *Data dependencies* delay when instructions start
 - Instruction outcomes are *published* when they are safe
 - It is possible to write single-threaded code.
- Cache coherence
 - Caches talk to each other with a MSI-like protocol
 - All caches return an up-to-date version of each cache line
- Memory consistency
 - *Barrier instructions* separate code regions that import/export data across threads
 - Programs can depend on causality across multiple cache lines

Today

- Lock-free programming
 - A particular kind of multi-threaded code
 - Multi-threaded access to a single data structure - without locks!

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Today

- Lock-free programming
 - A particular kind of multi-threaded code
 - Multi-threaded access to a single data structure - without locks!
 - Something people might expect you to know about
 - An example to help think about modern machines
 - (Not a kind of code most people write.)

*Outline**Introduction**Lock-Free Linked List Insertion**Lock-Free Linked List Deletion**Read-Copy-Update Mutual Exclusion*

Introduction

- Suppose some madman says “We shouldn’t use locks!”
- You know that this results (eventually!) in inconsistent data structures.
 - Loss of invariants within the data structure
 - Live pointers to dead memory
 - Live pointers to undead memory (Hey, my type changed! Stop poking there!)

Introduction

Locks Might Take A While

- Consider XCHG style locks which use
`while(xchg(&locked, LOCKED) == LOCKED)`
 as their core operation.

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while( xchg( &locked, LOCKED ) == LOCKED )
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- We could spend an unbounded amount of time here spinning...
- *Contended* locks will have very high latency...

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Locks Might Take A While

- Consider XCHG style locks which use
`while(xchg(&locked, LOCKED) == LOCKED)`
as their core operation.
- We could spend an unbounded amount of time here spinning...
- *Contended* locks will have very high latency...
- Locks *by definition* reduce parallelism.

Introduction

Locks Might Take A While

- Locks *by definition* reduce parallelism.
 - If N people are contending for a lock, $N - 1$ of them are just wasting time.
 - “It would be nice” if they could all work at once . . .
 - . . . but this requires a way to “handle” data-structure conflicts.

Introduction

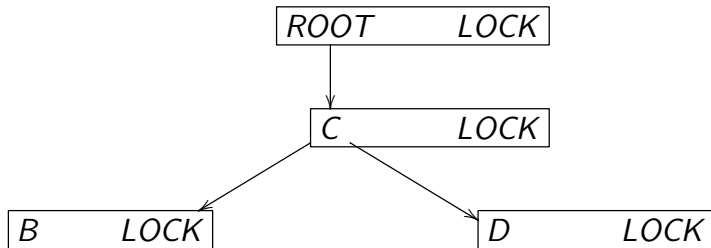
Locks Might Take A While

- For a large data structure, we would like multiple *local* (independent) operations to be allowed concurrently.
 - e.g. “lookup” and “insert” in parallel threads
- Approaches:
 - “Data structure full of locks” — today
 - Lock-free data structures — today
 - “Hardware transactional memory” [Her] — not today

Introduction

Locks Can Be... Not So Bad?

- Instead of a lock around a tree, we could have a tree with locks:

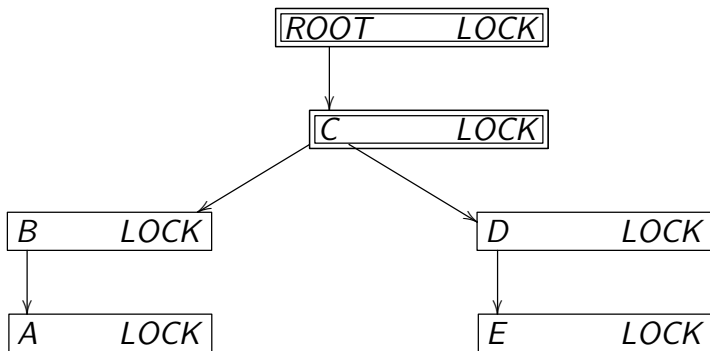


- The protocol: lock the root, then (lock child & unlock parent) as you go down.
 - This kind of *lock handoff* is a very common design.

Introduction

Locks Can Be... Not So Bad?

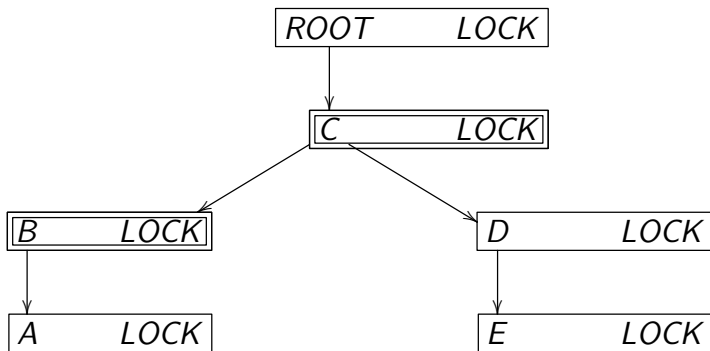
- Trying to find node A.
- Step 1: lock root pointer and top node



Introduction

Locks Can Be... Not So Bad?

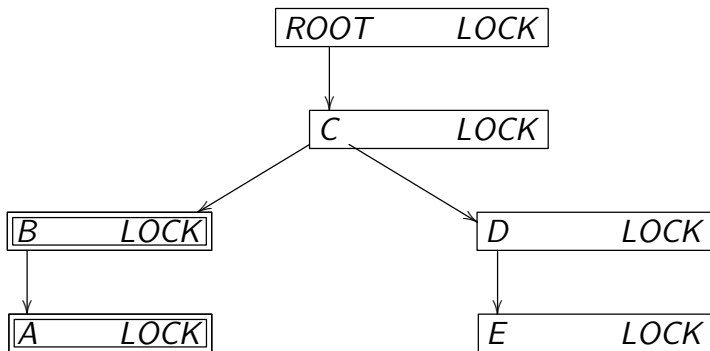
- Trying to find node A.
- Step 2: lock left child and unlock parent.



Introduction

Locks Can Be... Not So Bad?

- Trying to find node A.
- Step 3: lock left child and unlock parent



Introduction

- This dance is sometimes called “hand-over-hand locking”.
- In a binary tree, each traversal by one thread “opens half of the tree” for other threads.

Introduction

But let's see what we can do without any locks at all.

Lock-Free Linked List Node

- Node definition is simple:

label_t label

void* next

- When drawing, we'll use a shorthand:

label_t label = A

void* next = &B

 \Leftrightarrow

A	&B
---	----

Insertion into a Linked List Without Locks

Insertion Code

```
insertAfter(after, newlabel) {
    //lockList();
    new = newNode(newlabel);
    prev = findLabel(after);
    new->next = prev->next;
    prev->next = new;
    //unlockList();
}
```


Insertion into a Linked List Without Locks
“Good trace”

insertAfter(A,B)	insertAfter(A,C)
prev = &A	
B.next=A.next	
A.next=&B	
	prev = &A
	C.next=A.next
	A.next=&C

Insertion into a Linked List Without Locks

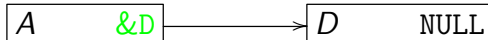
Race trace

insertAfter(A,B)	insertAfter(A,C)
prev = &A	
B.next = A.next	
	prev = &A
	C.next = A.next
A.next = &B	A.next = &C

- Either of these assignments makes sense in isolation, but one of them will override the other!

Insertion into a Linked List Without Locks

Precondition



- One list, two items on it: *A* and *D*.

Insertion into a Linked List Without Locks

First step

<i>C</i>	NULL
----------	------

<i>A</i>	<i>&D</i>	→	<i>D</i>	NULL
----------	---------------	---	----------	------

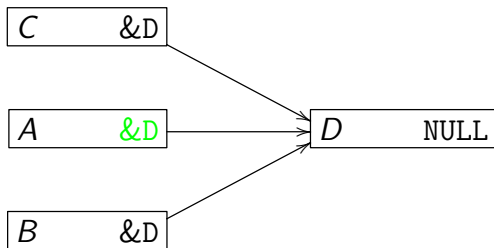
<i>B</i>	NULL
----------	------

- Two threads get two nodes, *B* and *C*, and want to insert.

new = newNode(<i>B</i>);	new = newNode(<i>C</i>);
prev = & <i>A</i>	prev = & <i>A</i>

Insertion into a Linked List Without Locks

Second step

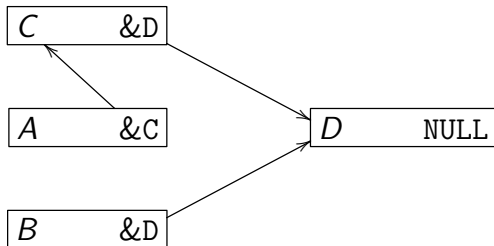


- Two threads point their respective nodes *C* and *B* into list at *D*

B.next=&D	C.next=&D
-----------	-----------

Insertion into a Linked List Without Locks

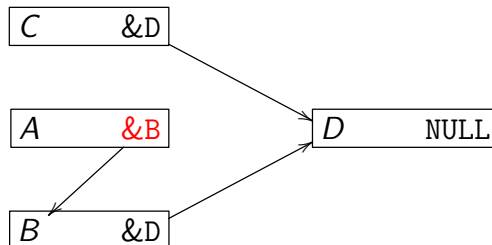
One thread goes



- Suppose the thread owning *C* completes its assignment first.



Insertion into a Linked List Without Locks And the other...



- And the other (owning *B*) completes second, overwriting

A.next=&B	
-----------	--

- Node *C* is unreachable!

Insertion into a Linked List Without Locks

- What went wrong?
 1. Thread B observed that `&A->next == D`
 2. Thread C observed that `&A->next == D`
 3. Thread C changed `&A->next` “from D to C”
 4. Thread B changed `&A->next` “from D to B” (oops!)

Insertion into a Linked List Without Locks

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- How to fix that?

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- How to fix that?
 1. Give B and C critical sections and serialize them
 - Then there is no gap between observation and changing
 - But that requires locking, which we are avoiding...

Insertion into a Linked List Without Locks

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- How to fix that?
 1. Give B and C critical sections and serialize them
 - Then there is no gap between observation and changing
 - But that requires locking, which we are avoiding...
 2. The pattern for today
 - 2.1 Assume update collisions happen rarely
 - 2.2 Detect when they do happen — hardware support
 - 2.3 Figure out how to “try again”

Insertion into a Linked List Without Locks
The Lock Free / Transactional Approach

while(not done)

Determine preconditions for the update

Prepare for update

ATOMICALLY

if(preconditions still hold)

make update;

done = true;

- Does this pattern finish in bounded time?

Insertion into a Linked List Without Locks
The Lock Free / Transactional Approach

while(not done)

 Determine preconditions for the update

 Prepare for update

ATOMICALLY

 if(preconditions still hold)

 make update;

 done = true;

- Does this pattern finish in bounded time?
 - No: could “encounter trouble” unboundedly.
- But if threads “almost never” spatially collide...
 - We gain “a lot” of parallelism by deleting locks.
 - We pay “a little” work handling retries.

Insertion into a Linked List Without Locks

- Re-writing list-insert in this pattern:

insertAfter(A,B)	insertAfter(A,C)
while(!done)	while(!done)
findLabel(A)	findLabel(A)
<i>ATOMICALLY</i> if (A->next == D) A->next = B done = 1	<i>ATOMICALLY</i> if (A->next == D) A->next = C done = 1

- If we do that, one critical section will *safely* fail out and tell us to try again.
- How do we do this *ATOMICALLY* without locking?

Review of Atomic Primitives

- Remember our old friend XCHG?
- XCHG (ptr, val)

ATOMICALLY

```
// "lock bus" (not really)
old_val = *ptr;
*ptr = val;
// "unlock bus" (not really)
return old_val;
```

- Summary: one fetch and one store under (mini) lock.

Review of Atomic Primitives

XCHG(ptr,new)	CAS(ptr, expect, new)
<i>ATOMICALLY</i>	<i>ATOMICALLY</i>
old = *ptr;	old = *ptr;
*ptr = new;	if(old == expect)
return old;	*ptr = new;
	return old;

Note that CAS is no harder:

- Still one read, one write under same lock.
- (logic time \ll memory time)

Insertion into a Lock-free Linked List

- Our assignments were really supposed to be

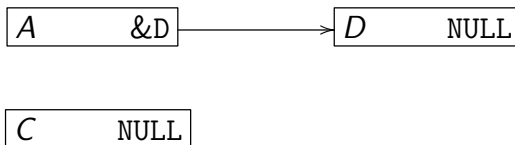
insertAfter(A,B)	insertAfter(A,C)
while(!done)	while(!done)
findLabel(A)	findLabel(A)
<i>ATOMICALLY</i> if (A->next == D) A->next = B done = 1	<i>ATOMICALLY</i> if (A->next == D) A->next = C done = 1

- This translates into

```
while(!done)
    prev = B->next = A->next;
    done = (CAS(&A->next,prev,B) == prev)
```

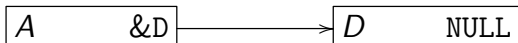
- CAS will assign if match, or bail otherwise.

Insertion into a Lock-free Linked List
Simple case, setup

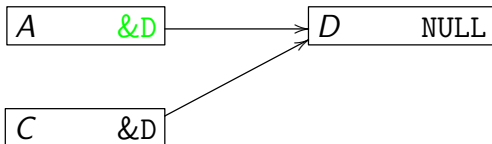


- Some thread constructs the bottom node *C*; wishes to place it between the two above, *A* and *D*.
- `new = newNode(C);`
- `prev = findLabel(A); /* == &A */`

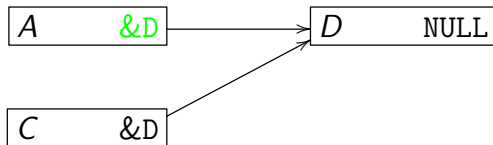
Insertion into a Lock-free Linked List
Simple case, first step



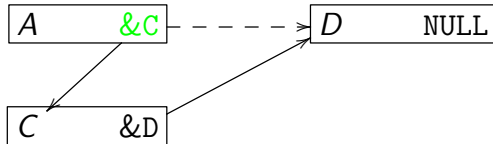
- Thread points C node's next into list at D .
- $C.\text{next} = A.\text{next};$



Insertion into a Lock-free Linked List
Simple case, second step



- `CAS(&A.next, &D, &C);`



Insertion into a Lock-free Linked List
Race case, setup

C	NULL
-----	------

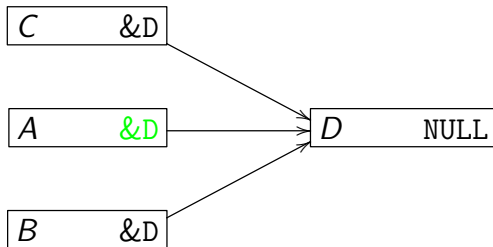
A	&D	→	D	NULL
-----	----	---	-----	------

B	NULL
-----	------

- Two threads get their respective nodes B and C .

<code>new = newNode(B);</code>	<code>new = newNode(C);</code>
<code>prev = &A</code>	<code>prev = &A</code>

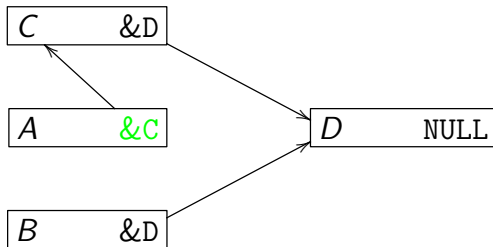
Insertion into a Lock-free Linked List
Race case, first step



- Both set their new node's next pointer.

B.next=&D	C.next=&D
-----------	-----------

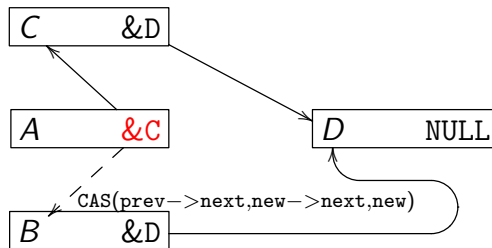
Insertion into a Lock-free Linked List
Race case, first thread



- Thread C goes first ...

	CAS(&A->next, D, C)
--	---------------------

Insertion into a Lock-free Linked List
Race case, second thread



- And the other (owning *B*)...

```
CAS(&A->next, D, B)
```

- ... fails since `A->next == C`, not `D`.
- So this thread tries again.

Insertion into a Lock-free Linked List

- Rewrite the insertion code to be

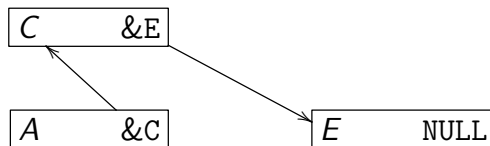

```
insertAfter(after, newlabel) {
    new = newNode(newlabel);
    do {
        prev = findLabel(after);
        expected = new->next = prev->next;
    } while
        ( CAS(&prev->next, expected, new)
          != expected);
}
```

That's great!

- It works!
 - No locks!
 - Threads can simultaneously scan and scan the list...
 - Threads can simultaneously scan and *grow* the list!
 - Threads can simultaneously *grow* and grow the list!
- All those while loops... (retrying over and over?)
 - Remember, mutexes had while loops too...
 - maybe even around CAS()!
 - Here, whenever we retry we *know* somebody else got work done!
- Are we done?
 - Have we implemented all the standard operations?

Deletion is easy?

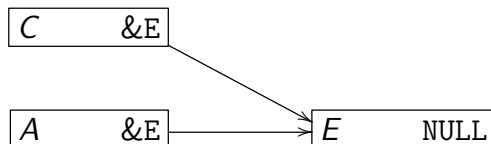
- Suppose we have



- And want to get rid of C.
- So `CAS(&A.next, &C, &E)`

Deletion is easy?

- Now we have

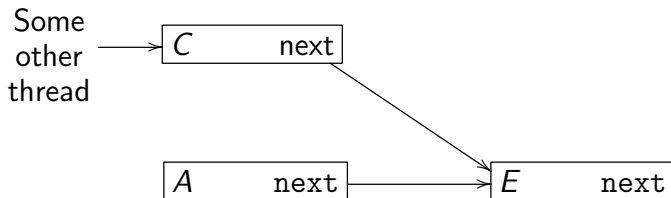


- Great, looks like deletion to me!
 - It's off the data-structure (*logically deleted*) ...
- But not *freed* (*"actually" deleted / reclaimed*).

Deletion is easy?

Continued

- Imagine there was another thread accessing *C* (say, scanning the list).



- We don't know when that thread is done with *C*!
- So we can never `free(C)` ;

Deletion is easy?
What's to be done?

- We need *some* way to reclaim that memory for reuse..
- Some implementations cheat and assume a stop-the-world garbage collector.
 - (That's like a giant lock!)
- Doing deletion honestly is remarkably tricky!
 - We're not going to really have time to cover it.

Deletion is easy?
What's to be done?

- Assume: once some memory is committed to being a LF list node that it's OK if it's *always* a LF list node.
- So we can have two lists: the “real” list and a “free” list.
 - This is not real free() but is hard enough.
- In particular, we run into the “ABA problem”.

ABA Problem: Introduction

- A problem of confused identity

global = malloc(sizeof(Foo))	
local ₁ = global	local ₂ = global
global = NULL	
free(local ₁)	
global = malloc(sizeof(Foo))	
	/* Validity check */ if (global == local ₂) global->foo_baz = ...

ABA Problem: Introduction

- A problem of confused identity

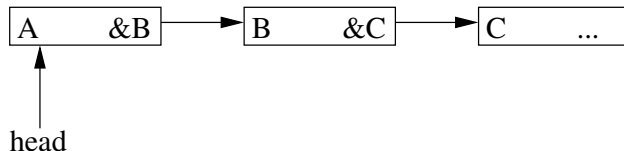
global = malloc(sizeof(Foo))		//0x1337
local ₁ = global	local ₂ = global	
global = NULL		
free(local ₁)		//0x1337
global = malloc(sizeof(Foo))		//0x1337
	/* Validity check */ if (global == local ₂) global->foo_baz = ...	

- Even though local₂ and global might point to the same address, they don't *really* mean the same thing.

ABA Problem: Introduction

Preliminaries

- We begin with an innocent linked list:

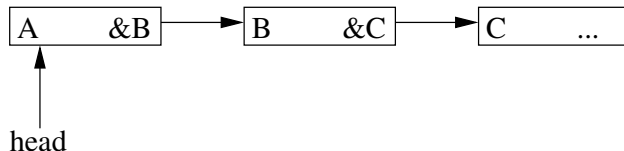


- Where head is a global pointer to the list.
- We're just going to do operations at the head – treating the list like a stack.

ABA Problem: Introduction

Pop

- We begin with a linked list:



- Removing the head looks like

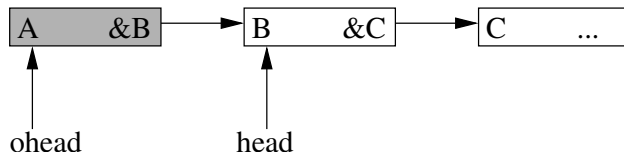
ohead = head	/* == &A */
onext = ohead->next	/* == &B */
CAS(head, ohead, onext);	

- If not, retry.

ABA Problem: Introduction

Pop

- If successful,



- is the result of

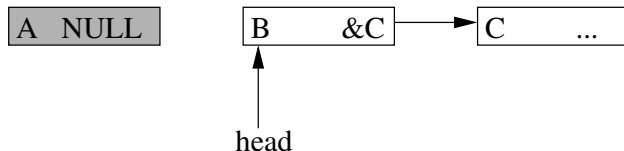
ohead = head	/* == &A */
onext = ohead->next	/* == &B */
CAS(head, ohead, onext);	

- If not, retry.

ABA Problem: Introduction

Push

- We begin with a linked list and private item



- Inserting at the head looks like

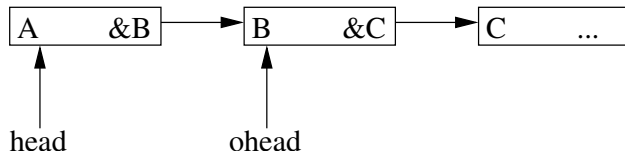
<code>ohead = head</code>	<code>/* == &B */</code>
<code>A.next = ohead</code>	<code>/* A points at B */</code>
<code>CAS(head, ohead, &A);</code>	

- If not, retry.

ABA Problem: Introduction

Push

- If that works, we get



- from

ohead = head	/* == &B */
A.next = ohead	/* A points at B */
CAS(head, ohead, &A);	

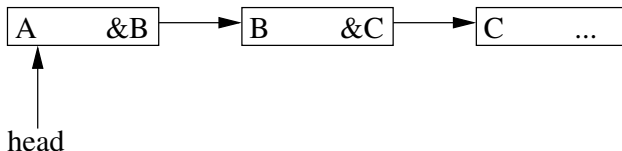
- If not, retry.

*ABA Problem: Things go south
And now it breaks!*

Here's a 30,000-foot look at how this is going to break.

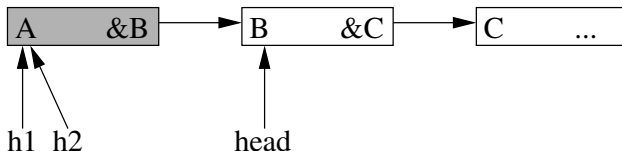
Thread 1	Thread 2	Thread 3
Pop	Pop	
		Pop
	Push	
BANG!		

- An extremely slow pop is racing against
 - A thread which pops and then immediately pushes.
 - A third which thread executes a pop.

ABA Problem: Things go south

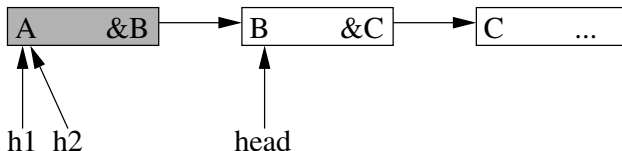
- The first thread gets one instruction into its pop, while
- The second thread completes its pop operation:

h1 = head	h2 = head	== &A
	n2 = h2->next	== &B
	CAS(head, h2, n2)	Success!

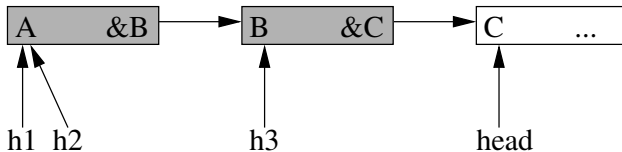
ABA Problem: Things go south

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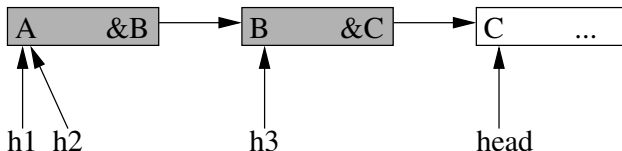
h1 = head	h2 = head	== &A
	n2 = h2->next	== &B
	CAS(head, h2, n2)	Success!

ABA Problem: Things go south

- The third thread executes a pop operation.

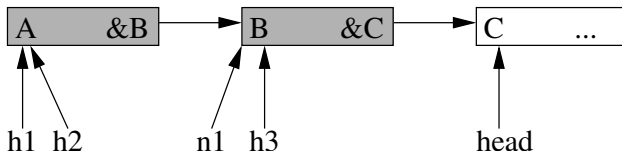
ABA Problem: Things go south

- The third thread executed a pop operation.

ABA Problem: Things go south

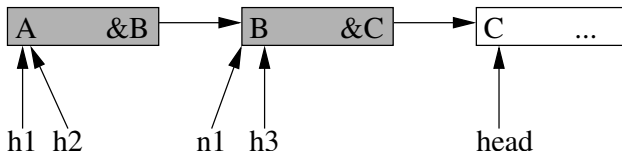
And the slower thread gets a few more instructions:

n1 = h1->next;		== &B
----------------	--	-------

ABA Problem: Things go south

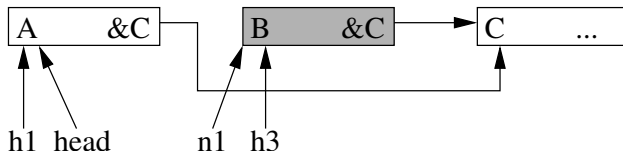
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----------------	--	-------

ABA Problem: Things go south

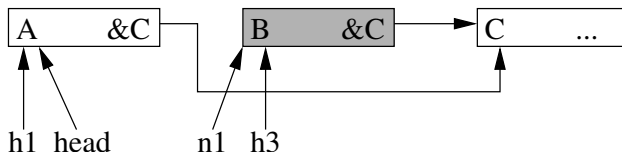
Now the second thread does its push operation...

	<code>h2 = head;</code>	<code>== &C</code>
	<code>h2->next = h2;</code>	<code>A.next ← &C</code>
	<code>CAS(head, h2, &A)</code>	Success!

ABA Problem: Things go south

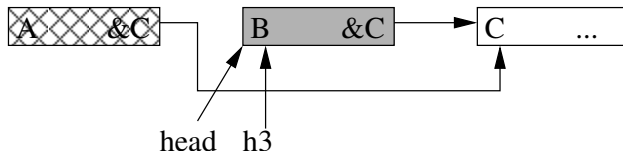
Now the second thread did its push operation...

	<code>h2 = head;</code>	<code>== &C</code>
	<code>h2->next = h2;</code>	<code>A.next ← &C</code>
	<code>CAS(head, h2, &A)</code>	Success!

ABA Problem: Things go south

And the slower thread finally completes its pop operation...

CAS(head, h1, n1)	Success!
-------------------	----------

ABA Problem: Things go south

And the slower thread finally completed its pop operation...

CAS(head, h1, n1)		Success?
-------------------	--	----------

B, which was well and quite off the list, and not owned by Thread 1, is now at the head!

ABA Problem: Things go south

- Thread 1 missed its chance to be notified of having stale data.
 - All that matters is that *A* ended up back on the list head when Thread 1 was CAS-ing.
- There's relatively little that *thread 1* can do about this!
- For fun, try designing a different failure case.
 - Try getting a circular list.

Fixing ABA

- Generation counters are a simple way to solve ABA
 - Let's replace all pointers with


```
struct versioned_ptr {
    void * p; /* Pointer */
    unsigned int v; /* Version */
};
```
- This will allow a “reasonably large” number of pointer updates before we have to worry.

Fixing ABA

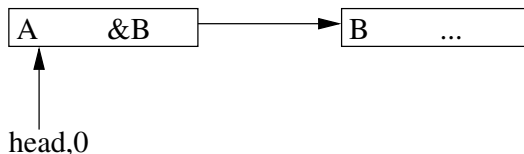
- Suppose we had a primitive which let us write things like
ATOMICALLY

```
if ((head.p == &C) && (head.v == 4))
    head.p = &D
    head.v = 5
```

Fixing ABA

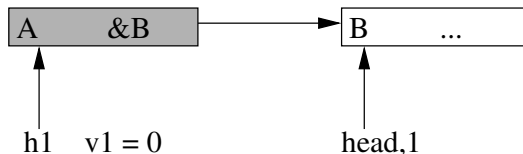
- Like CAS, we want a CAS2, which operates on two (adjacent) words at once:
CAS2(*curs, *expects, *news) atomically:
 olds[0] = curs[0]; olds[1] = curs[1];
 if (curs[0]==expects[0] && curs[1]==expects[1])
 curs[0] = news[0]; curs[1]= news[1];
 return { olds[0], olds[1] };
- CAS2 looks more expensive than CAS?
 - Two reads, two writes.
 - With luck, it's one cache line; without, it could be two.
 - May be $(1 + \epsilon)$ times as hard as CAS...
 - May be ∞ times as hard as CAS...

Fixing ABA
2nd thread pops...



h1 = head.p v1 = head.v	h2 = head.p	== &A
	n2 = h2->next.p v2 = head.v	== &B == 0
	CAS2(head, {h2, v2}, {n2, v2+1})	Success!

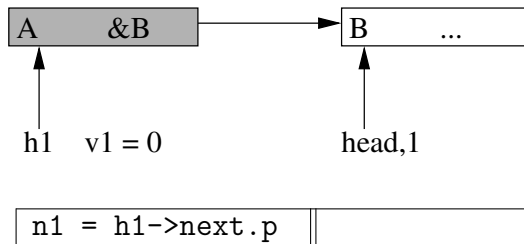
Fixing ABA
2nd thread popped...



h1 = head.p	h2 = head.p	== &A
	n2 = h2->next.p	== &B
	v2 = head.v	== 0
	CAS2(head, {h2, v2}, {n2, v2+1})	Success!

Fixing ABA

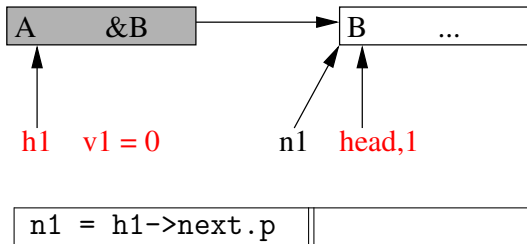
1st thread reads n1



- n1 and v1 are just local variables in preparation for...
CAS2(head, {h1, v1}, {n1, v1+1})

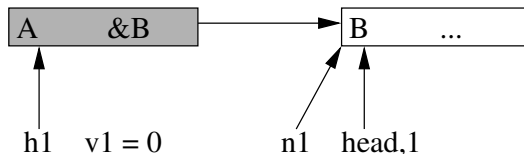
Fixing ABA

1st thread read n1

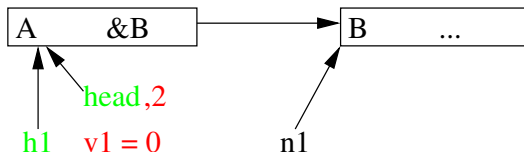


- `n1` and `v1` are just local variables in preparation for...
`CAS2(head, {h1, v1}, {n1, v1+1})`
- So if that were to happen right now...

Fixing ABA
2nd thread pushes...



	h2 = head.p;
	v2 = head.v;
	A.next = h2;
	CAS2(head, {h2, v2}, {&A, v2+1})

*Fixing ABA**2nd thread pushed; here's where it broke before*

		h2 = head.p;
		v2 = head.v;
		A.next.p = h2;
		CAS2(head, {h2, v2}, {&A, v2+1})

- CAS2(head, {h1, v1}, {n1, v1+1})
- head == h1 but v1 == 0 ≠ 2. Hooray!

Fixing ABA For Real

- Generation counters kinda stink.
- Be more clever:
 - Find some way to wait until the coast is clear.
 - Look at [FR04] or [Mic02a] (or others) for more details.
- Or use different hardware (“make the EEs do it”):
 - Old world: “Load-Linked/Store-Conditional/Validate”
 - New world: Hardware Transactional Memory
 - These assure you of no ABA because the $A \rightarrow B$ transition nullifies your ability to successfully store (aborts the transaction), even if B turns back into A .
 - To the EEs in the room: no missed edges!

Real-world applications

- CAS-based LF algorithms are relatively rare in the wild.
- But: motivation for transactional memory, which appears to finally be here to stay.
- So: forever more, you will be able to run a chunk of code touching (increasingly large amounts of) memory and “see if it worked.”
- A very powerful tool for concurrency design.
 - [RHP⁺] shows potential neat uses of HTM in Linux.

Read-Copy-Update Mutual Exclusion Preliminaries

- The deletion problem would be solved if we could wait for everyone who might have read what is now a stale pointer to complete.
- Phrased slightly differently, we need to separate the *memory update* (*atomic delete* or *logical delete*) phase from the *private use* (e.g. `free()`) phase.
- And ensure that no readers hold a critical section that might see the update *and* private phases.
 - Seeing one or the other is OK!

Read-Copy-Update Mutual Exclusion Preliminaries

- Read-Copy-Update (RCU, [Wikc, McK03]; earlier papers) uses techniques from lock-free programming.
- Is used in several OSes, including Linux.
- It's a bit more complicated than the examples given here and not truly lock-free, but certainly interesting.

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Read-Copy-Update Mutual Exclusion Preliminaries

- Looks like a reader-writer lock from 30,000 ft.
- Key assumptions:
 - Many more readers than writers.
 - Reader critical sections are *short*:
 - No `yield()`, `malloc()`, page faults, ...
 - One writer at a time is OK.
 - Some consistency requirements can be relaxed.
 - Use-after-free, pointers to garbage: definitely bad.
 - Double-linked-list invariant `node->next->prev != node` may be OK if violated during reader execution.
- Big feature: writers can tell when all “earlier” readers are done.

Read-Copy-Update Mutual Exclusion API

- Reader critical section functions.
 - `void rcu_read_lock(void);`
 - `void rcu_read_unlock(void);`
 - Note the absence of parameters (how odd!).
- Accessor function(s):
 - `void * rcu_assign(void *, void *);` is used to assign a new value to an RCU protected pointer.
 - (Other architectures may require more)
- Writer function:
 - `void rcu_wait(void);` called after updates are complete.
 - Move from “update” to “private” phase.

Read-Copy-Update Mutual Exclusion API: Reader's View

- Suppose we have a global list, called `list`, that we want to read under RCU.
- The code for iteration looks like

```
rcu_read_lock();
list_head_t *llist = list;
list_node_t *node = llist->head;
while(node != NULL) {
    ... /* Do something reader-like */
    node = node->next;
}
rcu_read_unlock();
```

Read-Copy-Update Mutual Exclusion

API: Writer's View

- Example: delete the head of the same global list, `list`.
- Use writer exclusion mutex, `list_wlock`.
- Updates use `rcu_assign()`, finish with `rcu_wait()`.

```
void delete_head_of_list() {
    list_node_t *head;
    mutex_lock(&list_wlock); // No other writers
    head = list->head;
    list_node_t *next = head->next;
    rcu_assign(list, next);
    mutex_unlock(&list_wlock);
    rcu_wait();
    free(head); /* Reclaim phase */
}
```

Read-Copy-Update Mutual Exclusion API: Summary

- Like rwlock:
 - It allows an arbitrary number of readers to run together.
 - It prevents multiple writers from writing at once.
- It is absolutely unlike a rwlock because
 - readers and writers do not exclude each other!

Read-Copy-Update Mutual Exclusion API: Wait, WHAT?

Readers can run alongside (at most one!) writer!

CPU 1 (reader)	CPU 2 (writer)
<code>rcu_read_lock();</code>	<code>mutex_lock(...);</code>
<code>llist = list;</code>	<code>...</code>
	<code>rcu_assign(list, new);</code>
	<code>rcu_wait();</code>
<code>read llist->head</code>	

Read-Copy-Update Mutual Exclusion Implementation: Key Ideas

- “All the magic is inside `rcu_wait()`” ...
- The deletion problem (like ABA) was a problem of not knowing when nobody had a stale reference.
- If
 - readers agree to drop *all* references in bounded time
 - AND writers can tell *when* readers have dropped references
- Then we know when it is safe to consider memory private.
- Being safe for *private use* is exactly the same as being safe for *reuse*.

Read-Copy-Update Mutual Exclusion Implementation: Approximation

- Want:
 - readers agree to drop *all* references in bounded time
 - AND writers can tell when readers have dropped references
- You can imagine that there's an array of `looking[i]` values out there, with each thread having its own index...
- Each reader increments `looking[me]` when done.
- The writer then scans waiting for each to change.
- The writer then knows that no readers have stale references, and is now OK to free deleted item(s).
- Nice idea, but doesn't work (how sad!)

Read-Copy-Update Mutual Exclusion Implementation

- So how does RCU *actually* do this?
 - “All the magic is inside `rcu_wait()`” ...
- `rcu_read_lock()` simply disables interrupts.
 - So we need readers that won't call `yield()`.
- `rcu_assign()` ensures ordering of writes.
- Too much detail for today's lecture.
- It's “the right kind of write”.
- (Inserts a write memory barrier *before* it does the assignment requested.)

Read-Copy-Update Mutual Exclusion Implementation

- Given all of this, what does `rcu_wait()` do?
- It waits until every CPU takes an interrupt!
 - Could just have a counter per CPU and wait for each to fire, or...
- Or! Each `rcu_wait` runs sequentially on each CPU.
 - Because readers are non-preemptible, waiting until all CPUs preempt means that all readers must have dropped their “lock” and so have forgotten any pointers to memory we want to free.

*Read-Copy-Update Mutual Exclusion
Confessions of an Instructor*

Real-world RCU once upon a time worked this way but more recent implementations are much fancier. For the really enthusiastic, see things like Linux's "Sleepable RCU" implementation [McK06].

Conclusion

- Discussed...
 - “Tree of locks”
 - The lock-free pattern
 - “replace locks with luck (plus detection and fixup)”
 - CAS/CAS2 as “mini-transactions”
 - A simple wrong idea
 - “address == meaning”
 - The “ABA problem”
 - “RCU: Wait for people to leave the room”
- Note: “classical” LF may be replaced by HTM (another lecture)

Conclusion

Words of Warning

- It's *extremely hard* to roll your own lockfree algorithm.
- But moreover, it's *almost impossible* to debug one.
- Thus all the papers are long not because the algorithms are hard, ...
- ...but because they prove the correctness of the algorithm so they at least don't have to debug that.

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Thanks. Questions?

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Acknowledgements

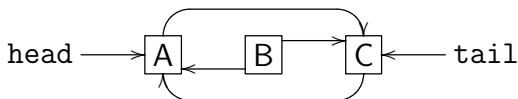
- Dave Eckhardt (de0u) has seen this lecture about as often as I have, and has produced useful commentary on every release.
- Bruce Maggs (bmm) for moral support and big-picture guidance
- Jess Mink (jmink), Matt Brewer (mbrewer), and Mr. Wright (mrwright) for being victims of beta versions of this lecture.
- [Nobody on this list deserves any of the blame, but merely credit, for this lecture.]

Pictures for RCU
Writer view

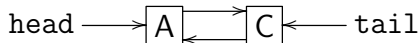
- Let's again take a linked list, this time a doubly linked one.



- Now suppose the writer acquires the write lock and updates to delete *B*:



- Now the writer synchronizes, forcing all readers with references to *B* out of the list. Only then can *B* be reclaimed!



Pictures for RCU
Reader View

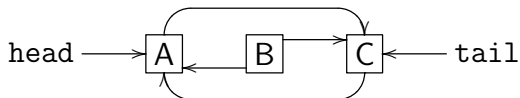
- Looking at that again, from the reader's side now.
Originally



- The writer first sets it to



- And then



Pictures for RCU
Pictures

- The writer forced memory consistency (fencing) between each update.
- So each reader's dereference occurred *entirely before* or *entirely after* each write.
- So the reader's traversal in either direction is entirely consistent!
 - (moving back and forth might expose the writer's action.)
- But it's OK, because we'll just see a disconnected node.
- It's not *gone* yet, just disconnected.
- It won't be reclaimed until we drop our critical section.



Full fledged deletion & reclaim

- Even though we might be able to solve ABA, it still doesn't solve memory reclaim!
- Imagine that instead of being reclaimed by the list, the deleted node before had been reclaimed by something else...
 - A different list
 - A tree
 - For use as a thread control block



Full fledged deletion & reclaim

- What if we looked at ABA differently . . .
- It only matters if there is the possibility of confusion.
- In particular, might demonstrate strong interest in things that might confuse me
 - Hazard Pointers (“Safe Memory Reclamation” or just “SMR”) [Mic02b] and [Mic04]
 - Wait-free reference counters [Sun05]
- These are ways of asking “If I, Thread 189236, were to put something here, would anybody be confused?”
- This solves ABA, but really as a side effect: it lets us reclaim address space (and therefore memory) because we know nobody’s using it!



Some real algorithms?

[Mic02a] specifies a CAS-based lock-free list-based sets and hash tables using a technique called SMR to solve ABA and allow reuse of memory.

- SMR actually solves ABA as a side effect of safely reclaiming memory. Instead of blocking the writer until everybody leaves a critical section, it can efficiently scan to see if threads are interested in a particular chunk of memory.
- Their performance figures are worth looking at.
Summary: fine-grained locks (lock per node) show linear-time increase with $\#$ threads, their algorithm shows essentially constant time.



The SMR Algorithm

- Every thread comes pre-equipped with a *finite* list of “hazards”
- Memory reclaim involves scanning everybody’s hazards to see if there’s a collision
- Threads doing reclaim `yield()` (to the objecting thread) until the hazard is clear
- Difficulty
 - Show that hazards can only decrease when deletions are pending
 - Show that deletions eventually succeed (can’t deadlock on hazards)
 - Managing the list of threads’ hazards is difficult

Observation On Object Lifetime

Instance of a general problem [Mem06]:

*Things get tricky when the object must go away. [...]
Any thread looking up the object – by definition –
does not yet have the object and thus cannot hold
the object's lock during the lookup operation. [...]
Thus, whatever higher-level synchronization is used
to coordinate the threads looking up the object must
also be used as part of removing the object from
visibility.*

Miscellany

Locking vs. RCU

- Interestingly, this kind of RCU tends to decrease the number of (bus) atomic operations.
 - Uses scheduler to get per-CPU atomicity.
- RCU requires the ability to force a thread to run on every CPU or at least observe when every CPU has context switched.
 - Difficult to use RCU in userland!
- RCU, like lockfree, suffers a slowdown from cache line shuffling, but will make progress due to having at most one writer.

Miscellany
Lockfree vs. Locking.

- Most lock-free algorithms increase the number of atomic operations, compared to the lockful variants.
- Thus we may starve processors for bus activity on bus-locking systems.
- On systems with cache coherency protocols, we might livelock with no processor able to make progress due to cacheline stealing and high transit times.
 - Nobody can get all the cachelines to execute an instruction before a request comes in and and steals one of the ones they had.