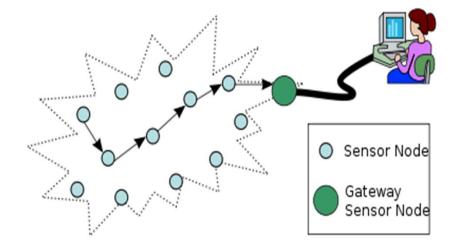
## Lecture: The Data Stream Model

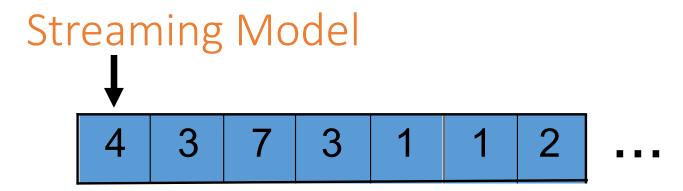
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#### **Data Streams**

- A stream is a sequence of data, that is too large to be stored in available memory
- Examples
  - Internet search logs
  - Network Traffic
  - Sensor networks



• Scientific data streams (astronomical, genomics, physical simulations)...



- Stream of elements  $a_1, ..., a_i, ...$  each from an alphabet  $\Sigma$  and taking b bits to represent
- Single or small number of passes over the data
- Almost all algorithms are randomized and approximate
  - Usually necessary to achieve efficiency
  - Randomness is in the algorithm, not the input
- Goals: minimize space complexity (in bits), processing time

#### **Example Streaming Problems**

- Let  $a_{[1:t]} = \langle a_1, ..., a_t \rangle$  be the first t elements of the stream
- Suppose  $a_1, ..., a_t$  are integers in  $\{-2^b + 1, -2^b + 2, ..., -1, 0, 1, 2, ..., 2^b 1\}$ 
  - Example stream: 3, 1, 17, 4, -9, 32, 101, 3, -722, 3, 900, 4, 32
- How many bits do we need to maintain  $f(a_{[1:t]}) = \sum_{i=1,...,t} a_i$ ?
  - Outputs on example: 3, 4, 21, 25, 16, 48, 149, 152, -570, -567, 333, 337, 379, ...
  - O(b + log t)
- How many bits do we need to maintain  $f(a_{[1:t]}) = \max_{i=1,...,t} a_i$ ?
  - Outputs on example: 3, 3, 17, 17, 17, 32, 101, 101, 101, 101, 900, 900, 900, ...
  - O(b) bits

#### **Example Streaming Problems**

- The median of all the numbers we've stored so far
  - Example stream: 3, 1, 17, 4, -9, 32, 101, 3, -722, 3, 900, 4, 32
  - Median: 3, 1, 3, 3, 3, 3, 4, 3, ...
  - This seems harder...
- The number of distinct elements we've seen so far?
  - Outputs on example: 1, 2, 3, 4, 5, 6, 7, 7, 8, 8, 9, 9, 9, ...
- The elements that have appeared at least an  $\epsilon$ -fraction of the time? These are the  $\epsilon$ -heavy hitters
  - Cover today

#### Many Applications

- Internet router may want to figure out which IP connections are heavy hitters, e.g., the ones that use more than .01% of your bandwidth
- Or maybe the router wants to know the median (or 90-th percentile) of the file sizes being transferred
- Hashing is a key technique

#### Finding $\epsilon$ -Heavy Hitters

- $S_t$  is the multiset of items at time t, so  $S_0 = \emptyset$ ,  $S_1 = \{a_1\}, ..., S_i = \{a_1, ..., a_i\}$ , count<sub>t</sub>(e) =  $|\{i \in \{1, 2, ..., t\} \text{ such that } a_i = e\}|$
- $e \in \Sigma$  is an  $\epsilon$ -heavy hitter at time t if  $count_t(e) > \epsilon \cdot t$
- Given  $\epsilon > 0$ , can we output the  $\epsilon$ -heavy hitters?
  - Let's output a set of size  $\frac{1}{\epsilon}$  containing all the  $\epsilon$ -heavy hitters
- Note: can output "false positives" but not allowed to output "false negatives", i.e., not allowed to miss any heavy hitter, but could output non-heavy hitters

#### Finding $\epsilon$ -Heavy Hitters

- Example: E, D, B, D,  $D_5$  D, B, A, C,  $B_{10}$  B, E, E, E,  $E_{15}$ , E (the subscripts are just to help you count)
- At time 5, the element D is the only 1/3-heavy hitter
- At time 11, both B and D are 1/3-heavy hitters
- At time 15, there is no 1/3-heavy hitter
- At time 16, only E is a 1/3-heavy hitter

Can't afford to keep counts of all items, so how to maintain a short summary to output the  $\epsilon$ -heavy hitters?

#### Finding a Majority Element

• At end of the stream, return the element in memory

# 31211

```
Memory = 3, Count = 1
```

Memory = 
$$3$$
, Count =  $0$ 

Memory = 
$$2$$
, Count =  $1$ 

Memory = 
$$2$$
, Count =  $0$ 

#### Analysis of Finding a Majority Element

- If there is no majority element, we output a false positive, which is OK
- If there is a majority element, we will output it. Why?
- When we discard an element  $a_t$ , we throw away a different element
- When we throw away a copy of a majority element, we throw away another element
  - Either majority element is in memory, or majority element arrives in stream but some other item is in memory
- Majority element is more than half the total number of elements, so can't throw away all of them

#### Extending to $\epsilon$ -Heavy Hitters

Set 
$$k = \left[\frac{1}{\epsilon}\right] - 1$$

Array T[1, ..., k], where each location can hold one element from  $\Sigma$  Array C[1, ..., k], where each location can hold a non-negative integer C[i]  $\leftarrow$  0 and T[i]  $\leftarrow$  $\bot$  for all i

If there is  $j \in \{1, 2, ..., k\}$  such that  $a_t = T[j]$ , then C[j] + +Else if some counter C[j] = 0 then  $T[j] \leftarrow a_t$  and  $C[j] \leftarrow 1$ Else decrement all counters by 1 (and discard element  $a_t$ )

 $est_t(e) = C[j]$  if e == T[j] for some j, and  $est_t(e) = 0$  otherwise

#### **Analyzing Counts**

- Lemma:  $0 \le \text{count}_t(e) \text{est}_t(e) \le \frac{t}{k+1} \le \epsilon \cdot t$
- Proof:  $count_t(e) \ge est_t(e)$  since we never increase a counter for e unless we see e

If we don't increase  ${\sf est}_t(e)$  by 1 for an update to e, we decrement k counters and discard the current update to e

- Either e is in memory and we decrement its count, or e is a stream update and we discard it

So we drop k+1 distinct stream updates, but there are t total updates, so we won't increase  $\text{est}_t(e)$  by 1, when we should, at most  $\frac{t}{k+1} \le \epsilon \cdot t$  times

#### Heavy Hitters Guarantee

- At any time t, all  $\epsilon$ -heavy hitters e are in the array T. Why?
- For an  $\epsilon$ -heavy hitter e, we have  $\operatorname{count}_{\mathsf{t}}(\mathsf{e}) > \epsilon \cdot \mathsf{t}$
- But  $est_t(e) \ge count_t(e) \epsilon \cdot t$
- So  $est_t(e) > 0$ , so e is in array T
- Space is O(k (log( $|\Sigma|$ ) + log t)) = O(1/ $\epsilon$ ) (log( $|\Sigma|$ ) + log t) bits

#### Heavy Hitters with Deletions

- Suppose we can delete elements e that have already appeared
- Example: (add, A), (add, B), (add, A), (del, B), (del, A), (add, C)
- Multisets at different times

$$S_0 = \emptyset$$
,  $S_1 = \{A\}$ ,  $S_2 = \{A, B\}$ ,  $S_3 = \{A, A, B\}$ ,  $S_4 = \{A, A\}$ ,  $S_5 = \{A\}$ ,  $S_6 = \{A, C\}$ , ...

• "active" set  $S_t$  has size  $|S_t| = \sum_{e \in \Sigma} count_t(e)$  and can grow and shrink

#### Data Structure for Approximate Counts

- Query "What is  $count_t(e)$ ?", should output  $est_t(e)$  with:  $\Pr[|est_t(e) count_t(e)| \le \epsilon |S_t|] \ge 1 \delta$
- Want space close to our previous  $O(1/\epsilon)$  (log( $|\Sigma|$ ) + log t) bits
- Let h:  $\Sigma \to \{0,1,2,...,k-1\}$  be a hash function (will specify later)
- Maintain an array A[0, 1, ..., k-1] to store non-negative integers

when update a<sub>t</sub> arrives:

if 
$$a_t = (add, e)$$
 then  $A[h(e)] + +$   
else  $a_t = (del, e)$ , and  $A[h(e)] - -$ 

•  $\operatorname{est}_{\mathsf{t}}(\mathsf{e}) = \mathsf{A}[\mathsf{h}(\mathsf{e})]$ 

#### Data Structure for Approximate Counts

•  $A[h(e)] = \sum_{e' \in \Sigma} count_t(e') \cdot \mathbf{1}(h(e') = h(e))$ , where  $\mathbf{1}(condition)$  evaluates to 1 if the condition is true, and evaluates to 0 otherwise

• 
$$A[h(e)] = count_t(e) + \sum_{e'\neq e} count_t(e') \cdot \mathbf{1}(h(e') = h(e)),$$

• 
$$\operatorname{est}_{\mathsf{t}}(\mathsf{e}) - \operatorname{count}_{\mathsf{t}}(\mathsf{e}) = \sum_{\mathsf{e}' \neq \mathsf{e}} \operatorname{count}_{\mathsf{t}}(\mathsf{e}') \cdot \mathbf{1}(\mathsf{h}(\mathsf{e}') = \mathsf{h}(\mathsf{e}))$$

• Since we have a small array A with k locations, there are likely many  $e' \neq e$  with h(e') = h(e), but can we bound the expected error?

#### Data Structure for Approximate Counts

- Recall: Family H of hash functions h: U -> {0, 1, ..., k-1} is universal if for all  $x \neq y$ ,  $\Pr_{h \leftarrow H}[h(x) = h(y)] \leq \frac{1}{k}$
- There is a simple family where h can be specified using O(log |U|) bits. Here,  $|U| = |\Sigma|$

• 
$$E[est_t(e) - count_t(e)] = E[\sum_{e' \neq e} count_t(e') \cdot \mathbf{1}(h(e') = h(e))]$$
  

$$= \sum_{e' \neq e} count_t(e') \cdot E[\mathbf{1}(h(e') = h(e))]$$

$$= \sum_{e' \neq e} count_t(e') \cdot Pr[h(e') = h(e)]$$

$$\leq \sum_{e' \neq e} count_t(e') \cdot \left(\frac{1}{k}\right)$$

$$= \frac{|S_t| - count_t(e)}{k} \leq \frac{|S_t|}{k}$$

 $k = 1/\epsilon$  makes this at most  $\epsilon \cdot |S_t|$ . Space is  $O(\frac{1}{\epsilon})$  counters plus storing hash function

#### High Probability Bounds for CountMin

- Have  $0 \le \operatorname{est}_t(e) \operatorname{count}_t(e) \le |S_t|/k$  in expectation from CountMin
  - With probability at least 1/2,  $\operatorname{est}_t(e) \operatorname{count}_t(e) \le 2|S_t|/k$  Why?
- Can we make the success probability 1- $\delta$ ?
  - Independent repetition: pick m hash functions  $h_1, ..., h_m$  with  $h_i \colon \Sigma \to \{0, 1, 2, ..., k-1\} \text{ independently from H. Create array } A_i \text{ for } h_i$  when update  $a_t$  arrives:

for each i from 1 to m

if 
$$a_t = (add, e)$$
 then  $A_i[h_i(e)] + +$   
else  $a_t = (del, e)$  and  $A_i[h_i(e)] - -$ 

### High Probability Bounds and Overall Space

What is our new estimate of  $count_t(e)$ ?

$$best_t(e) := \min_{i=1}^m A_i[h_i(e)].$$

- Each A<sub>i</sub>[h<sub>i</sub>(e)] is an overestimate to count<sub>t</sub>(e)
- By independence,  $\Pr[\text{for all i, } A_i[h_i(e)] \text{count}_t(e) \ge 2|S_t|/k] \le \left(\frac{1}{2}\right)^m$
- For  $k = \frac{2}{\epsilon}$  and  $m = \log_2\left(\frac{1}{\delta}\right)$ , the error is at most  $\epsilon |S_t|$  with probability 1- $\delta$
- Space:  $m \cdot k = O(\frac{\log(\frac{1}{\delta})}{\epsilon})$  counters each of O(lg t) bits

$$m \cdot O(\log |\Sigma|) = O(\log (\frac{1}{\delta}) \log |\Sigma|)$$
 bits to store hash functions

#### **∈**-Heavy Hitters

• Our new estimate  $best_t(e)$  satisfies  $\Pr[|best_t(e) - count_t(e)| \le \epsilon |S_t|] \ge 1 - \delta$ 

and uses 
$$O(\frac{\log(\frac{1}{\delta})\log t}{\epsilon} + \log(\frac{1}{\delta})\log |\Sigma|)$$
 bits of space

- What if we want with probability 9/10, simultaneously for all e,  $|\text{best}_{t}(e) \text{count}_{t}(e)| \le \epsilon |S_{t}|$ ?
- Set  $\delta = \frac{1}{10|\Sigma|}$  and apply a union bound over all  $e \in \Sigma$