

# 451/651 Lecture 16 – **NP**-completeness

## Outline

- ▶ Reductions and expressiveness
- ▶ Formal definitions: decision problems, **P** and **NP**.
- ▶ Circuit-SAT and 3-SAT
- ▶ Examples of showing **NP**-completeness.

# Reductions and Expressiveness

In the last few lectures we have seen:

- ▶ Bipartite matching can be solved with a max flow algorithm.
- ▶ The max flow problem can be solved by a linear programming algorithm.

In this lecture we expand the idea of a reduction from one problem to another. And we expand the application of reductions to prove lower bounds on problem difficulty.

# Polynomial Time

**Definition:** We say that an algorithm runs in **Polynomial Time** if, for some constant  $c$ , its running time is  $O(n^c)$ , where  $n$  is the size of the input.

Input size: size of the problem description in bits.

*Think about why the basic Ford-Fulkerson algorithm is not a polynomial-time algorithm for network flow when edge capacities are written in binary, but both of the Edmonds-Karp algorithms are polynomial-time.*

# Reducibility

**Definition:** A problem  $A$  is **poly-time reducible** to problem  $B$  (written as  $A \leq_p B$ ) if we can solve problem  $A$  in polynomial time given a polynomial time black-box algorithm for problem  $B$ .<sup>1</sup> Problem  $A$  is **poly-time equivalent** to problem  $B$  ( $A =_p B$ ) if  $A \leq_p B$  and  $B \leq_p A$ .

Think about the examples mentioned above – bipartite matching, max flow, linear programming.

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<sup>1</sup>You can loosely think of  $A \leq_p B$  as saying “ $A$  is no harder than  $B$ , up to polynomial factors.”

# Decision Problems

We consider *decision problems*, whose answer is YES or NO.

E.g., “Does the given network have a flow of value at least  $k$ ?”

E.g., “Does the given graph have a 3-coloring?”

For such problems, we split all instances into two categories: YES-instances (whose correct answer is YES) and NO-instances (whose correct answer is NO). We put any ill-formed instances into the NO category.

# Karp Reductions

**Definition: Karp reduction (aka Many-one reduction) from problem  $A$  to problem  $B$ :** To reduce problem  $A$  to problem  $B$  we want a function  $f$  that maps arbitrary instances of  $A$  to instances of  $B$  such that:

1. if  $x$  is a YES-instance of  $A$  then  $f(x)$  is a YES-instance of  $B$ .
2. if  $x$  is a NO-instance of  $A$  then  $f(x)$  is a NO-instance of  $B$ .
3.  $f$  can be computed in polynomial time.

Superficially this seems more limited than the  $B \leq_p A$  reductions we defined earlier. But it's cleaner and simpler and is not known to be different.

## Definition of **P**

We can now define the complexity classes **P** and **NP**. These are both classes of decision problems. (Sets of sets of strings.)

**Definition:** **P** is the set of decision problems solvable in polynomial time.

E.g., the decision version of the network flow problem: “Given a network  $G$  and a flow value  $k$ , does there exist a flow  $\geq k$ ?” belongs to **P**.

# The Concept of **NP**

Informally **NP** is the class of problems for which any YES-instance can be efficiently checked if given a proper hint.

The TRAVELING SALESPERSON PROBLEM asks: “Given a weighted graph  $G$  and an integer  $k$ , does  $G$  have a tour that visits all the vertices and has total length at most  $k$ ?”

If someone gave us such a tour we could easily check if it satisfied the desired conditions. Therefore it's in **NP**.

The 3-COLORING problem asks: “Given a graph  $G$ , can vertices be assigned colors red, blue, and green so that no two neighbors have the same color?”

Again, to check a proposed solution is easy. Therefore it's in **NP**.



# Formal Definition of **NP**

**Definition:** **NP** is the set of decision problems that have polynomial-time *verifiers*. Specifically, problem  $Q$  is in **NP** if there is a polynomial-time algorithm  $V(I, X)$  such that:

- ▶ If  $I$  is a YES-instance, then there exists  $X$  such that  $V(I, X) = \text{YES}$ .
- ▶ If  $I$  is a NO-instance, then for all  $X$ ,  $V(I, X) = \text{NO}$ .

Furthermore,  $X$  should have length polynomial in size of  $I$  (since we are really only giving  $V$  time polynomial in the size of the instance, not the combined size of the instance and solution).

The question: Does **NP** = **P** is THE major unsolved problem in theoretical computer science. We won't talk about it here.

## Definition of **NP**-Complete

Loosely speaking, **NP**-complete problems are the “hardest” problems in **NP**, if you can solve them in polynomial time then you can solve any other problem in **NP** in polynomial time. Formally,

**Definition:** Problem  $Q$  is **NP**-complete if:

1.  $Q$  is in **NP**, and
2. For any other problem  $Q'$  in **NP**,  $Q' \leq_p Q$ .

So if  $Q$  is **NP**-complete and you could solve  $Q$  in polynomial time, you could solve *any* problem in **NP** in polynomial time. If  $Q$  just satisfies part (2) of this definition, then it's called **NP**-hard.

# CIRCUIT-SAT – the First **NP**-complete problem

**CIRCUIT-SAT:** Input: an acyclic circuit  $C$  of NAND gates with a single output. Answer: YES if there is a setting of the inputs that causes  $C$  to output 1? NO otherwise.

**Theorem:** CIRCUIT-SAT is **NP**-complete.

**Proof:** Wave hands vigorously. (For more on how to wave your hands, read the lecture notes.)

## 3-SAT – the Second **NP**-complete problem

3-SAT: Given: a CNF formula (AND of ORs) over  $n$  variables  $x_1, \dots, x_n$ , where each clause has at most 3 variables in it. E.g.,  $(x_1 \vee x_2 \vee \bar{x}_3) \wedge (\bar{x}_2 \vee x_3) \wedge (x_1 \vee x_3) \wedge \dots$ . Answer YES if there exists an assignment to the variables that satisfies the formula, output NO otherwise.

The *literals* of each conjunction are distinct. (Delete duplicates.)

**Theorem:**  $\text{CIRCUIT-SAT} \leq_p \text{3-SAT}$ .

**Proof:** (Coming up in a moment)

Hence 3-SAT is **NP**-complete. Why?

CIRCUIT-SAT  $\leq_p$  3-SAT implies 3-SAT is  
**NP**-complete

Proof that CIRCUIT-SAT  $\leq_p$  3-SAT

## Proving NP-completeness in Two Easy Steps

If you want to prove that problem  $Q$  is NP-complete, you need to do two things:

1. Show that  $Q$  is in NP.
2. Choose some NP-hard problem  $P$  to reduce from. This problem could be 3-SAT or CLIQUE or  $\dots$  any of the zillions of NP-hard problems known.

Now you want to reduce **from  $P$  to  $Q$** . In other words, given any instance  $I$  of  $P$ , show how to transform it into an instance  $f(I)$  of  $Q$ , such that

$$I \text{ is a YES-instance of } P \iff f(I) \text{ is a YES-instance of } Q.$$

Note the “ $\iff$ ” in the middle—you *need to show both directions*.

You also need to show that the mapping  $f(\cdot)$  can be done in polynomial time (and hence  $f(I)$  has size polynomial in the size of the original instance  $I$ ).

Why is it useful to prove a problem is **NP**-complete?

From the point of view of algorithm design, why is this useful?



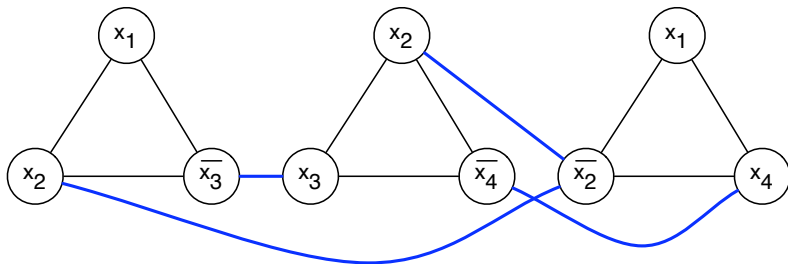
## Independent Set is **NP**-complete

The INDEPENDENT SET problem is: given a graph  $G$  and an integer  $k$ , does  $G$  have an independent set of size  $\geq k$ ?

**Theorem:** INDEPENDENT SET is **NP**-complete.

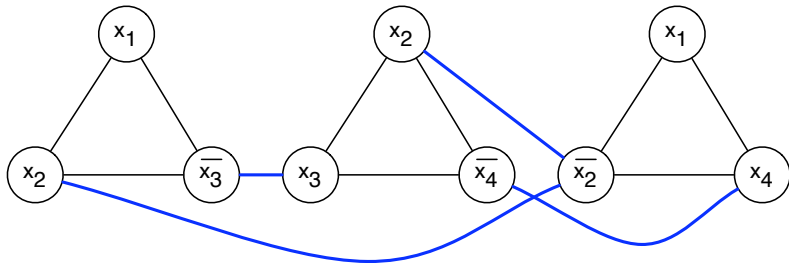
**Proof:** First we observe that INDEPENDENT SET  $\in$  **NP**. (Trivial.)  
Then we show that 3-SAT  $\leq_p$  INDEPENDENT SET, as shown in the following example:

$$(x_1 \vee x_2 \vee \overline{x_3}) \wedge (x_2 \vee x_3 \vee \overline{x_4}) \wedge (x_1 \vee \overline{x_2} \vee x_4)$$



## Independent Set is **NP**-complete, contd.

$$(x_1 \vee x_2 \vee \overline{x_3}) \wedge (x_2 \vee x_3 \vee \overline{x_4}) \wedge (x_1 \vee \overline{x_2} \vee x_4)$$



We need to show two things:

1. A satisfying assignment gives us an independent set of size  $k$ .
2. An independent set of size  $k$  gives us a satisfying assignment.  
(This one is subtle.)

# VERTEX COVER, SET COVER, CLIQUE

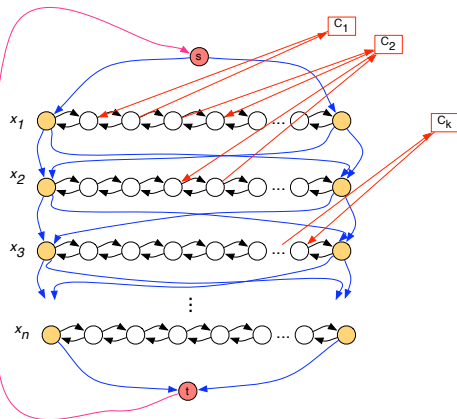
These are easy. See the lecture notes.

# HAM CYCLE

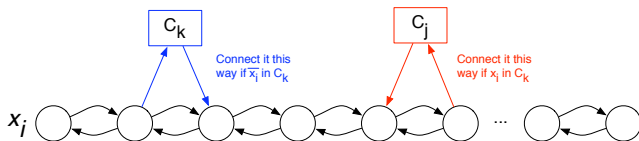
A *Hamiltonian cycle* is a cycle in a graph that visits every vertex exactly once. The HAM CYCLE problem asks, given a directed graph  $G$ , is there a Hamiltonian cycle.

**Theorem:** HAM CYCLE is **NP**-complete

**Proof:** Obviously HAM CYCLE is in **NP**. We reduce from 3-SAT. Let  $\phi$  be an arbitrary 3SAT instance with clauses  $c_1, \dots, c_m$  and variables  $x_1, \dots, x_n$ . Construct the following gadget that represents all possible truth assignments: (See next page)



Add a new node for each clause:



Direction we travel along this chain represents whether to set the variable to **true** or **false**.

← **true**  
**false** →