

# Program Synthesis

Ruben Martins

**Bug Catching: Automated Program Verification**  
**May 4, 2021**

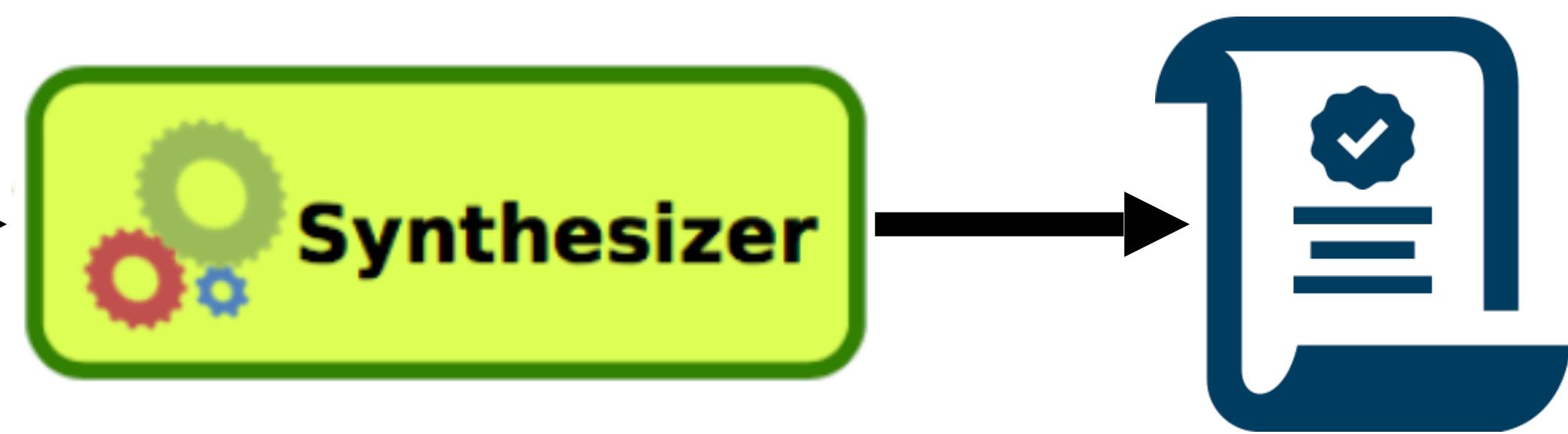
Carnegie  
Mellon  
University

# What is Program Synthesis?

Specifications  $\phi$



Program P



$$\exists P. \forall x. \phi(x, P(x))$$

- Find a program P that for all inputs x meets the specification  $\phi$

# Progress in Program Synthesis

**Automating String Processing in  
Spreadsheets Using Input-Output Examples**

**Synthesizing Data Structure Transformations  
from Input-Output Examples \***

John K. Feser

Rice University, USA

**Component-Based Synthesis for Complex APIs**

**Program Synthesis from Polymorphic Refinement Types**

tins

Austin, USA

Yuepeng Wang

University of Texas at Austin, USA

**Scaling Enumerative Program Synthesis  
via Divide and Conquer \***

Rajeev Alur, Arjun Radhakrishna, and Abhishek Udupa

University of Pennsylvania

**DEEPCODER: LEARNING TO WRITE PROGRAMS**

Matej Balog\*

Department of Engineering  
University of Cambridge

**Alexander L. Gaunt, Marc Brockschmidt,  
Sebastian Nowozin, Daniel Tarlow**  
Microsoft Research

# Program Synthesis is Industry



## Tensor reshaping

<https://blog.tensorflow.org/2020/08/introducing-tensorflow-coder-tool.html?LinkId=98162087>



## Data manipulation

<https://support.microsoft.com/en-us/office/using-flash-fill-in-excel-3f9bcf1e-db93-4890-94a0-1578341f73f7>

# How do Program Synthesizers Work?



**Enumerative Search**

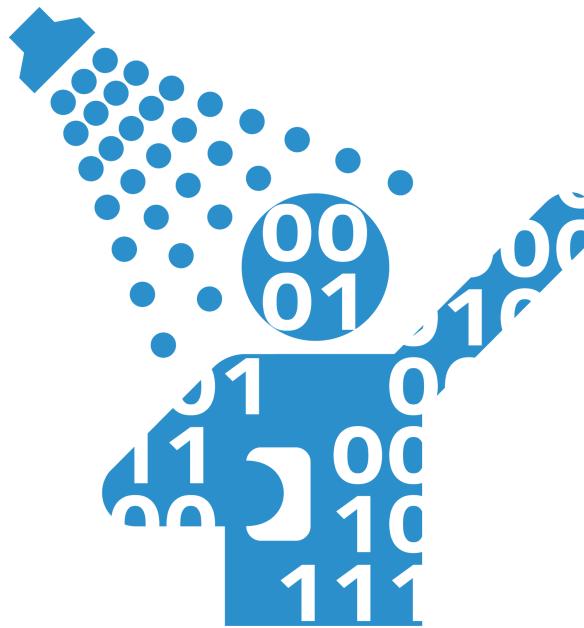


**Constraint Solving**



**Stochastic Search**

# Applications of Program Synthesis



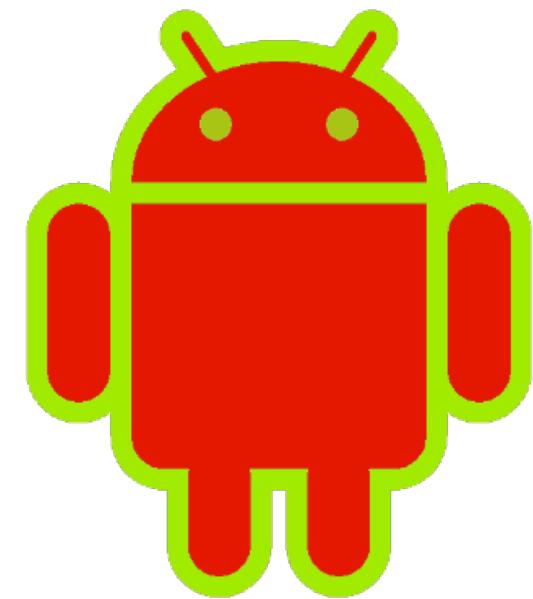
Data Science



Databases



Program Repair



Security



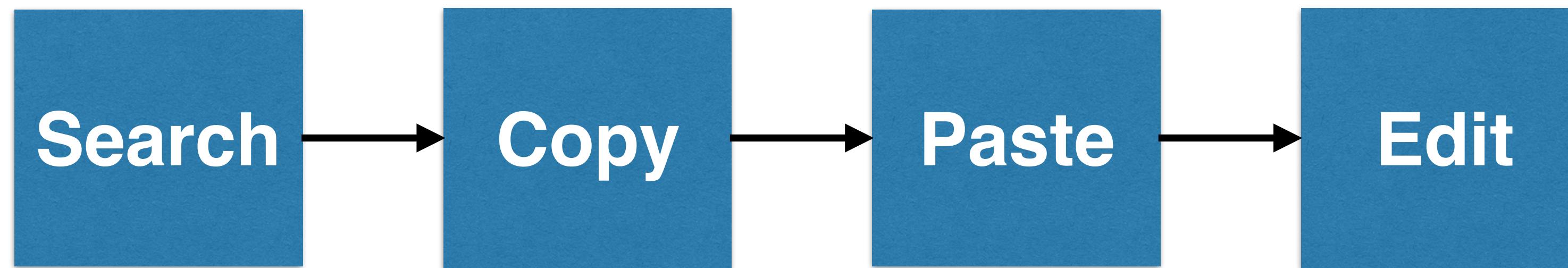
Software  
Engineering



And many others!

# Software Engineering

What happens when you need to implement a new module?



**Tedious and error prone approach!**



# Motivation

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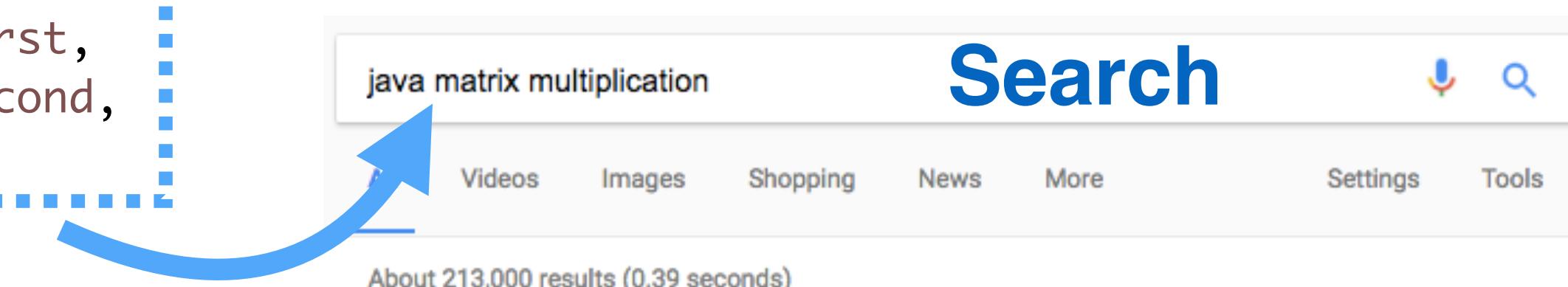
## Description: Matrix multiplication

```
void multiply(final Vector<Vector<Double>> first,  
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Jul 12, 2013 - I'm trying to make a simple matrix multiplication method using multidimensional arrays ([2][2]). I'm kinda new at this, and I just can't find what it ...

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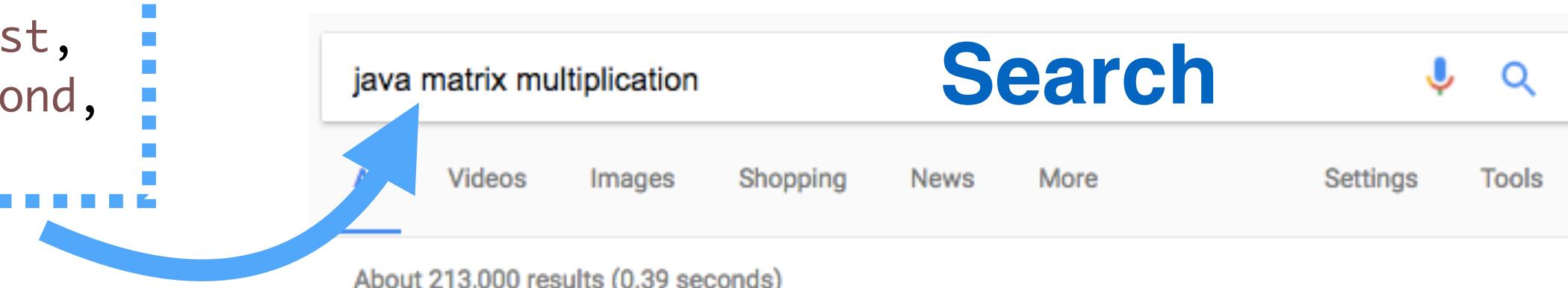
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Java. Matrix multiplication.

Tested with matrices of different size.

```
public class Matrix {  
  
    /**  
     * Matrix multiplication method.  
     * @param m1 Multiplicand  
     * @param m2 Multiplier  
     * @return Product  
     */  
    public static double[][] multiplyByMatrix(double[][] m1, double[][] m2) {  
        int m1ColLength = m1[0].length; // m1 columns length  
        int m2RowLength = m2.length; // m2 rows length  
        if(m1ColLength != m2RowLength) return null; // matrix multiplication is not possible  
        int mRowLength = m1.length; // m result rows length  
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        double[][] mResult = new double[mRowLength][mColLength];  
        for(int i = 0; i < mRowLength; i++) { // rows from m1  
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                for(int k = 0; k < m1ColLength; k++) { // columns from m1  
                    mResult[i][j] += m1[i][k] * m2[k][j];  
                }  
            }  
        }  
        return mResult;  
    }  
}
```

## Available Code



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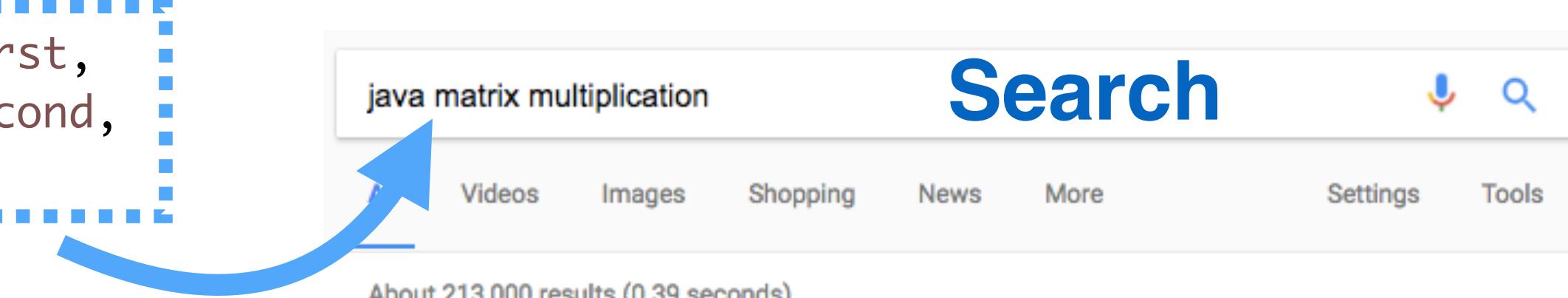
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                }  
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## Desired Code

Edit

# Motivation

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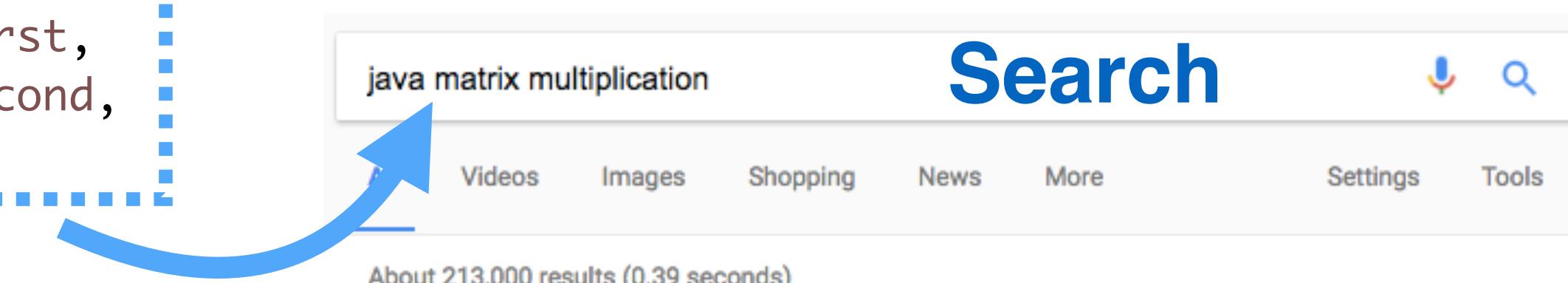
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## Available Code



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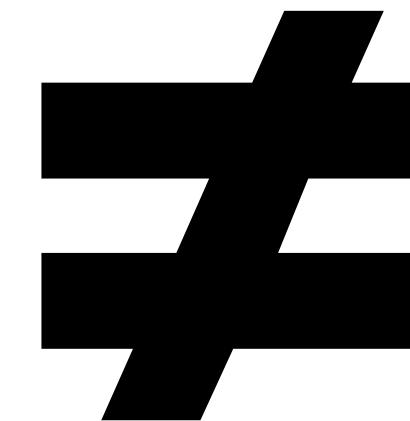
## Desired Code



Long time spent on search  
Significant effort required to edit!

# Traditional Approach

Available  
Code



Desired  
Code

**Significant effort required to edit!**



# Traditional Approach



Bugs are easily integrated while editing!



# Program Synthesis

- What if the program could write itself?



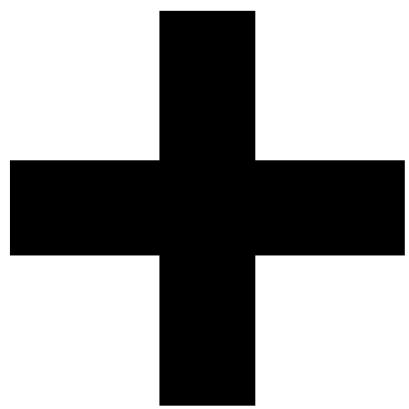
# Goal

Description

Desired  
Code

# Goal

Description



Desired  
Code

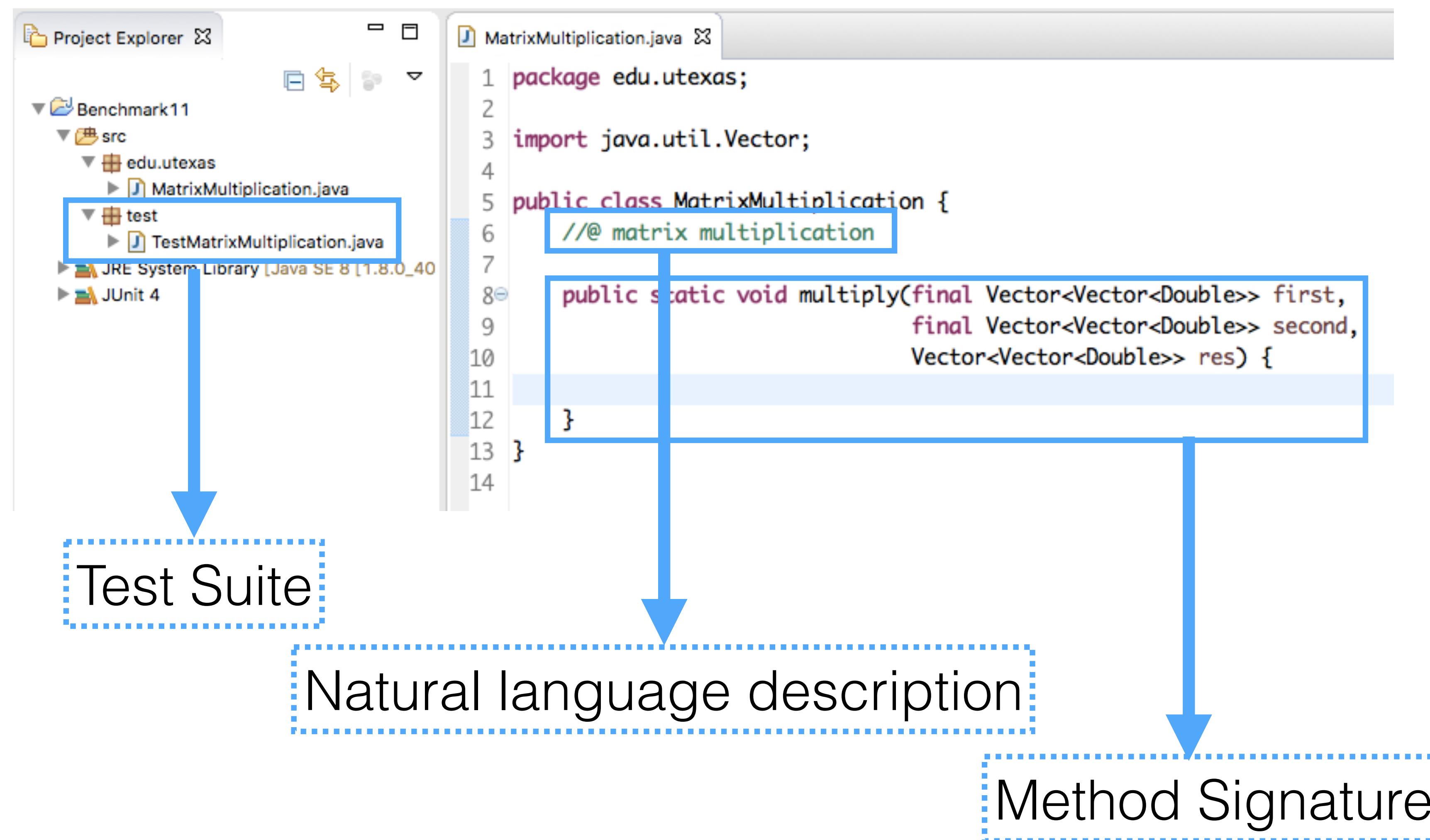
# Goal



- Search and reuse code **automatically**
- Method description
  1. Natural language description
  2. Method signature
  3. Test suite



# Hunter



# Hunter

The screenshot shows a Java development environment with the following details:

- Project Explorer:** Shows a project named "Benchmark11". Inside the "src" folder, there is a package "edu.utexas" containing "MatrixMultiplication.java" and a sub-package "org.misc.aux" containing "LinearAlgebra.java". A blue box highlights the "org.misc.aux" package.
- Code Editor:** The file "MatrixMultiplication.java" is open. It contains Java code for matrix multiplication using `java.util.Vector`. A large blue box highlights the body of the `multiply` method.

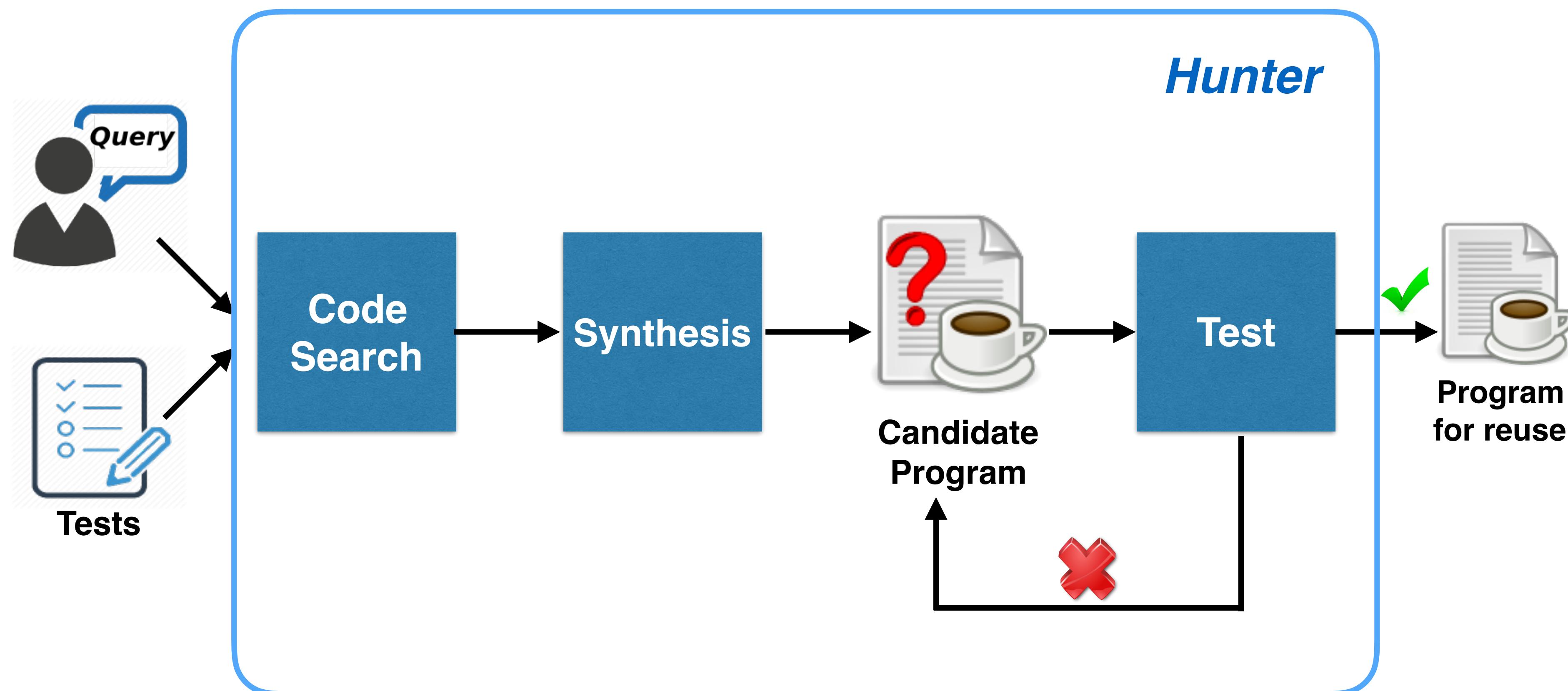
```
1 package edu.utexas;
2
3 import java.util.Vector;
4
5 public class MatrixMultiplication {
6     // @ matrix multiplication
7
8     public static void multiply(final Vector<Vector<Double>> first,
9                                 final Vector<Vector<Double>> second,
10                                Vector<Vector<Double>> res) {
11         double[] hunter_var1 = new double[first.size()];
12         int hunter_var5 = 0;
13         for (java.util.Vector<Double> hunter_var3 : first) {
14             int hunter_var6 = 0;
15             double[] hunter_var2 = new double[hunter_var3.size()];
16             for (double hunter_var4 : hunter_var3) {
17                 hunter_var2[hunter_var6] = hunter_var4;
18                 hunter_var6++;
19             }
20             hunter_var1[hunter_var5] = hunter_var2;
21             hunter_var5++;
22         }
23     }
24 }
```

Found code

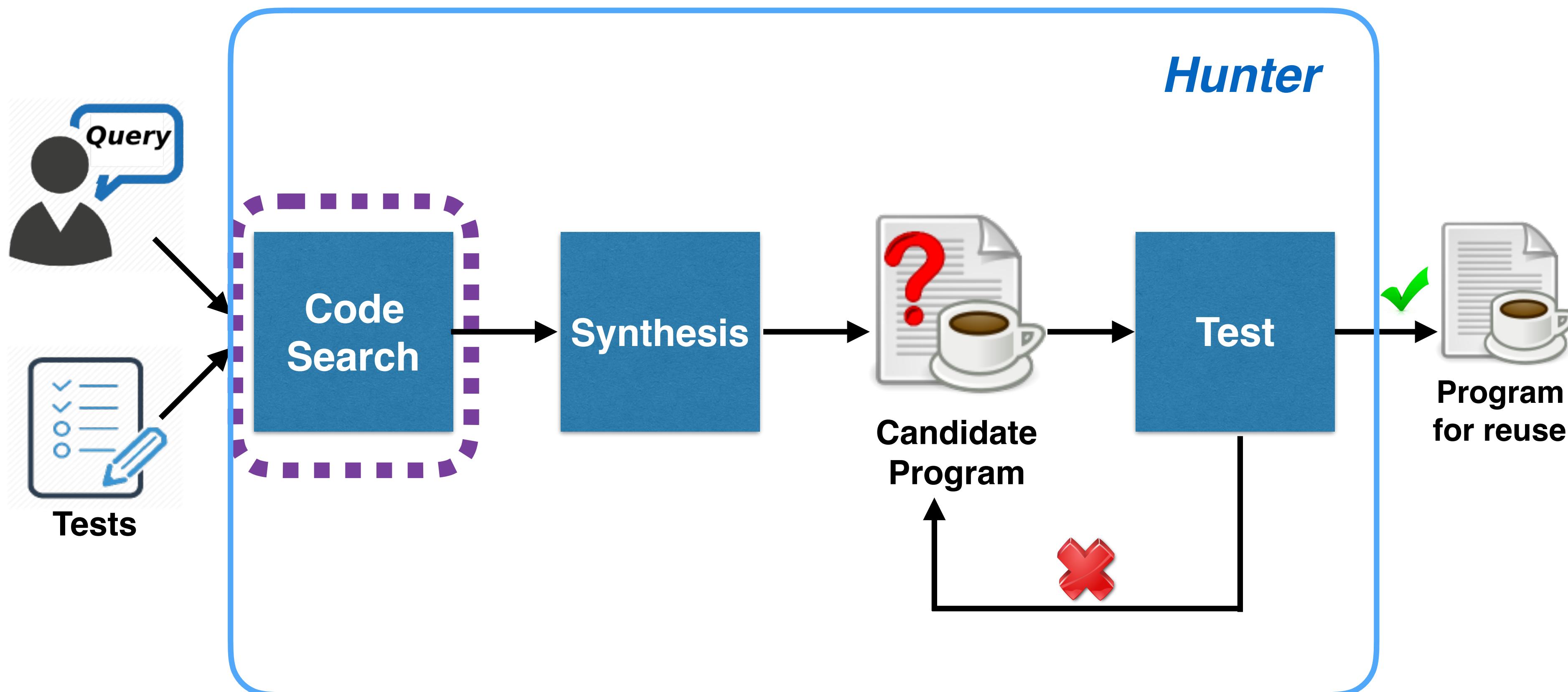
40+ lines

Wrapper code

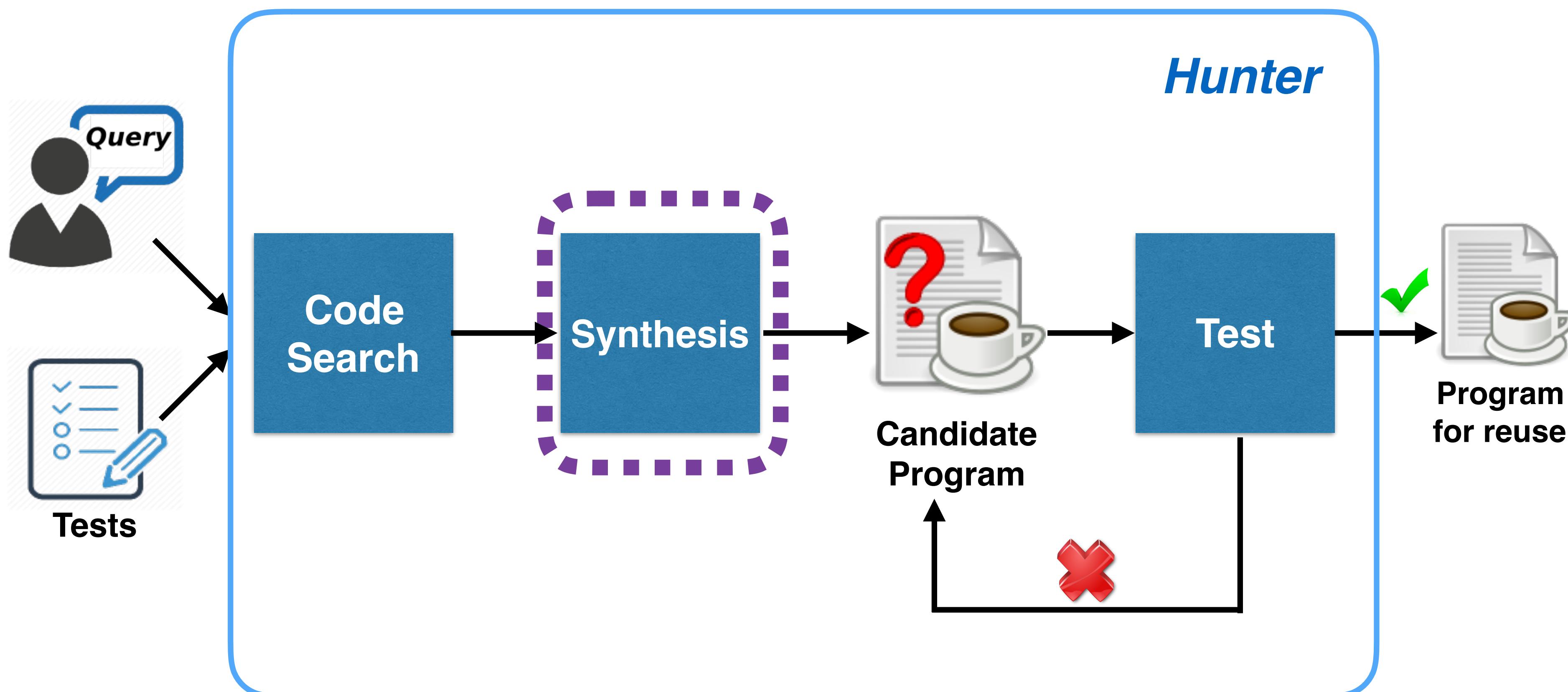
# Hunter architecture



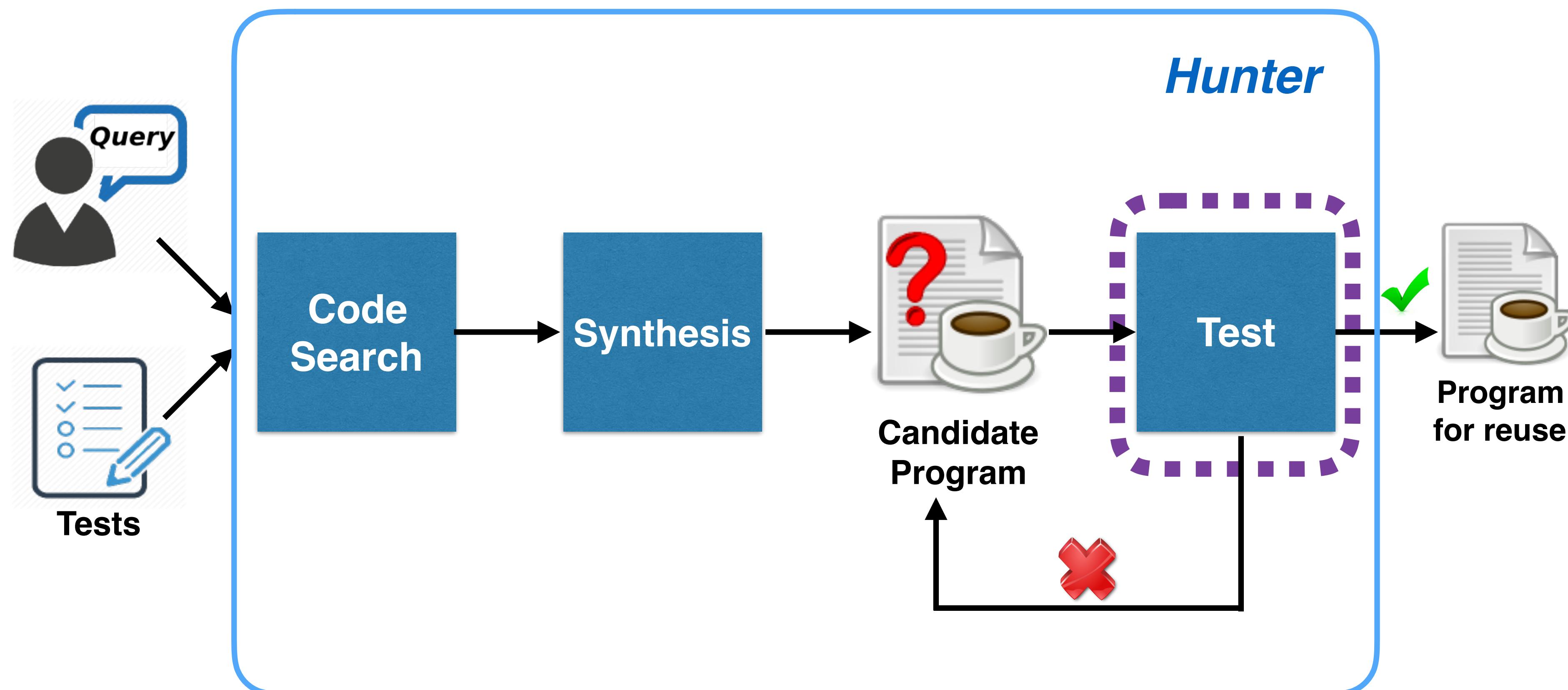
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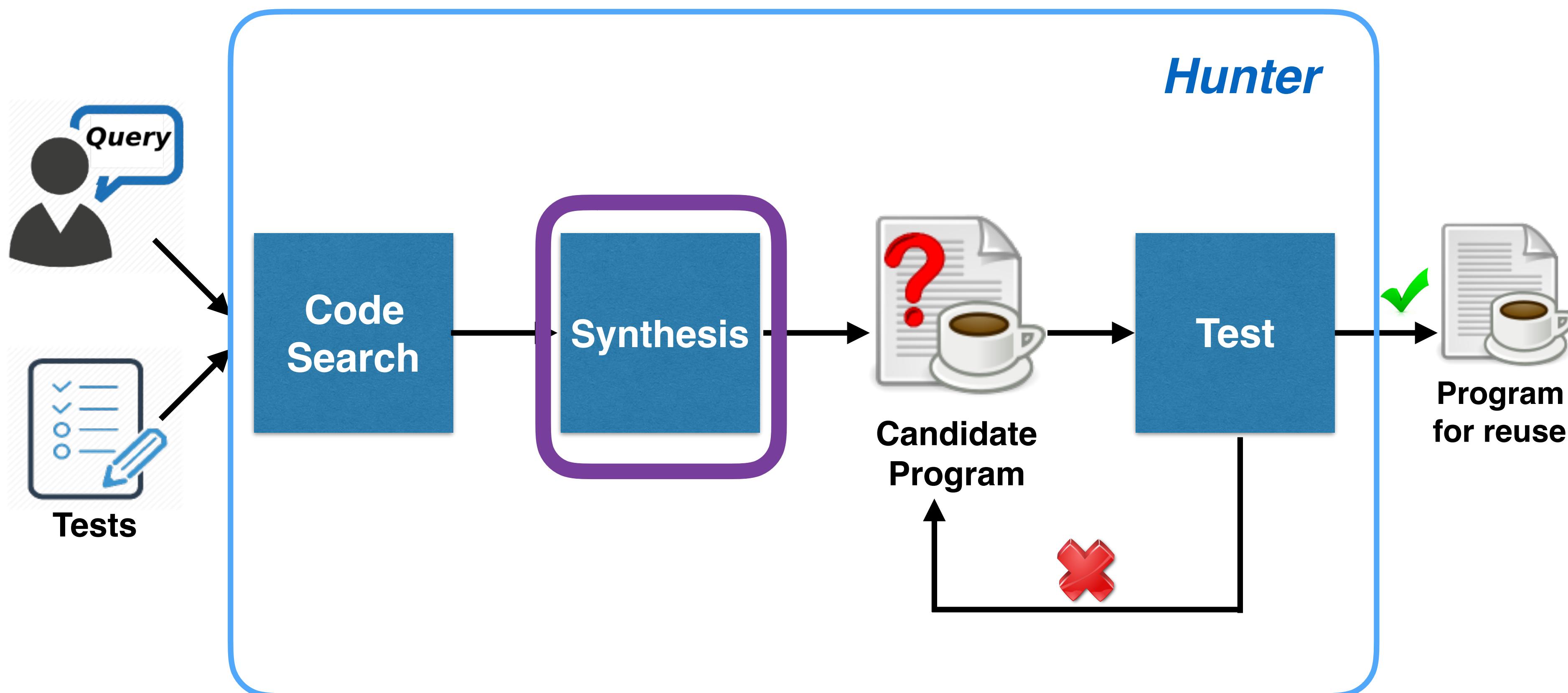
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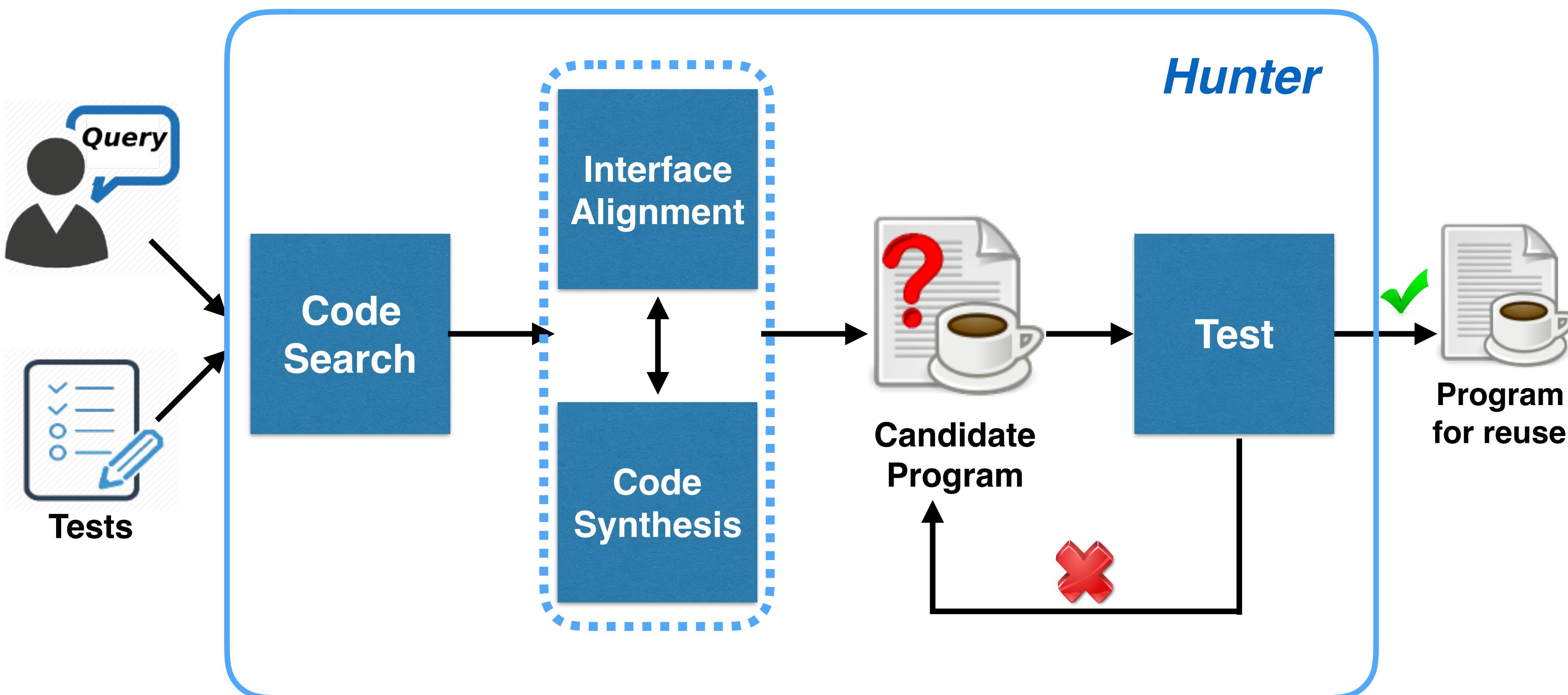
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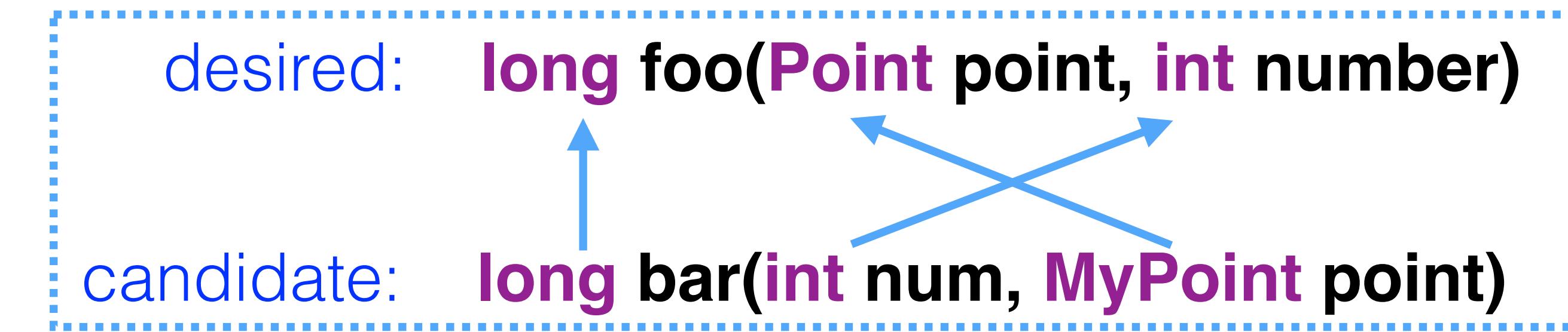


# Hunter architecture



# Interface alignment

- Generate reuse scheme by mapping arguments and return value from candidates to the desired signature



# Code synthesis

- Synthesize **wrapper** to invoke candidates properly
- Handle type conversions by building succinct graph representation and performing reachability analysis

# Code synthesis

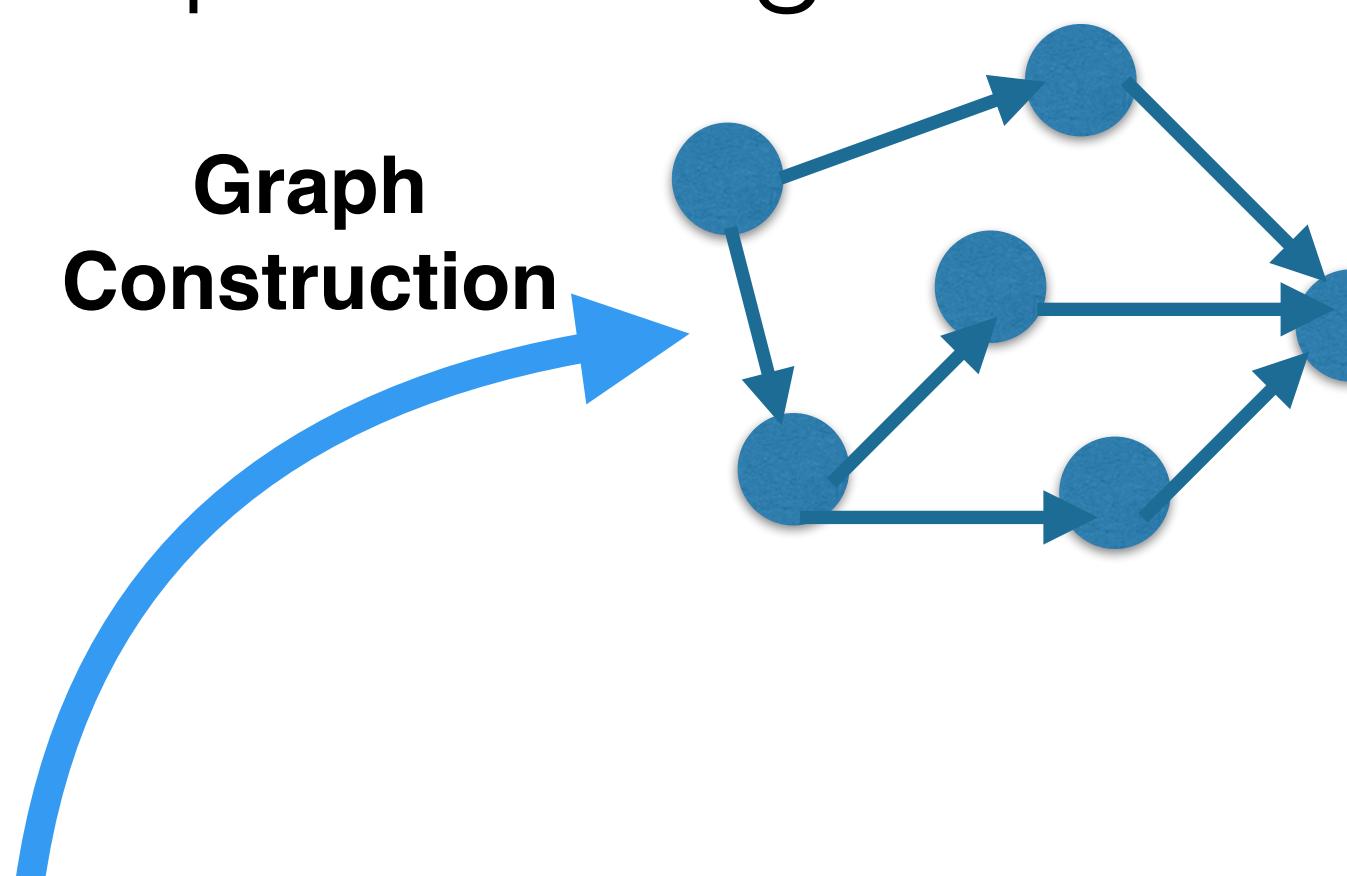
- Synthesize **wrapper** to invoke candidates properly
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```
class Point {  
    int x; int y;  
    Point(int _x, int _y);  
}  
class MyPoint {  
    int x; int y;  
    int getX();  
    int getY();  
}
```

# Code synthesis

- Synthesize **wrapper** to invoke candidates properly
- Handle type conversions by building succinct graph representation and performing reachability analysis

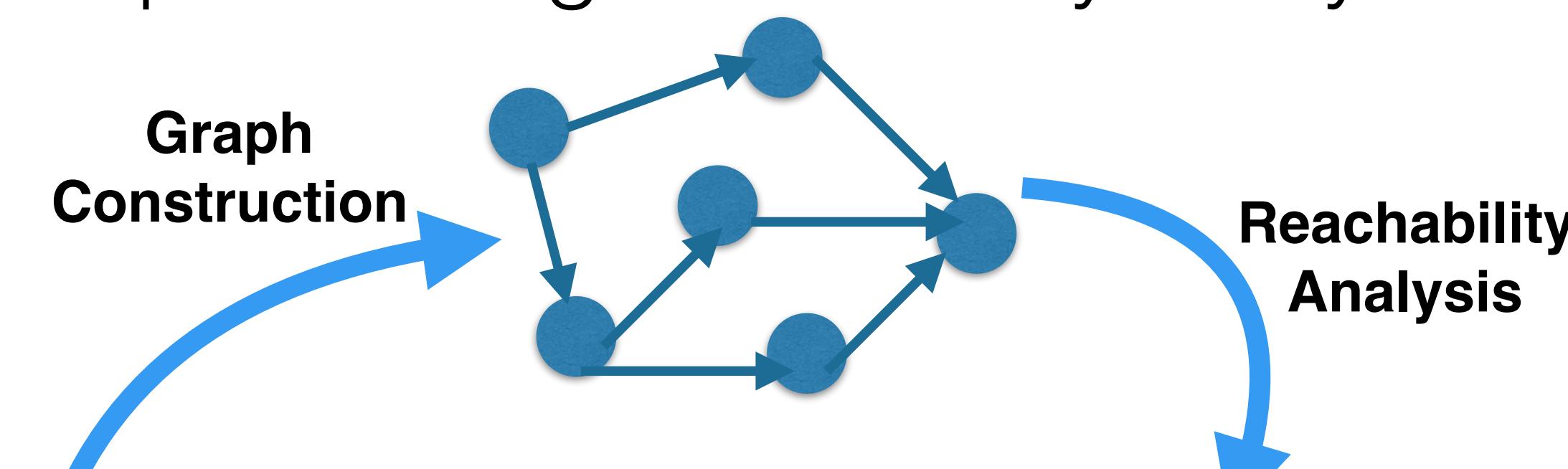
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# Code synthesis

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```



```
// MyPoint pt as argument  
int x = pt.getX();  
int y = pt.getY();  
Point p = new Point(x, y);
```

# Who can Program Synthesis help?



# Who can Program Synthesis help?

- Are we trying to replace programmers? **No!**
  - We want to make programmers life easier
  - Automating tedious and repetitive tasks



# Who can Program Synthesis help?



- Are we trying to replace programmers? **No!**
  - We want to make programmers life easier
  - Automating tedious and repetitive tasks
- 99% of computer users **cannot program!**
  - They struggle with simple repetitive tasks
  - Help non-CS people to automate their daily tasks

# Outline

Code  
Reuse

FSE'16



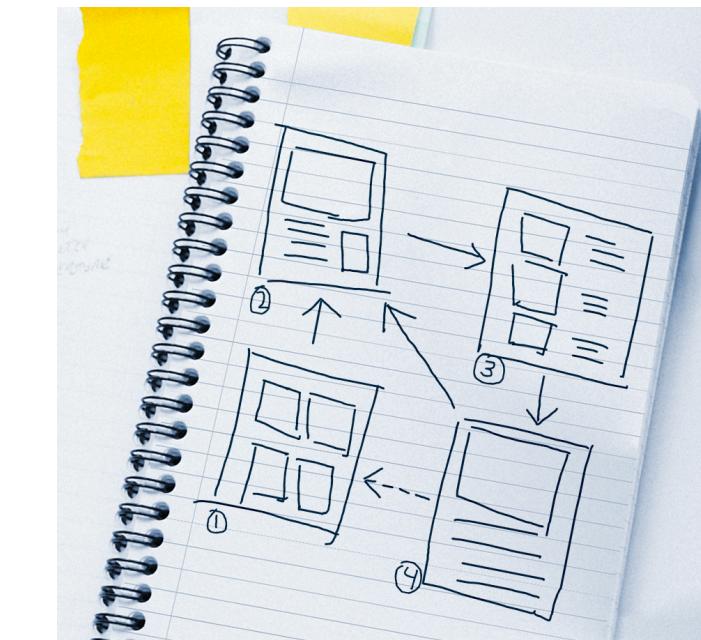
Complex  
Java APIs

POPL'17



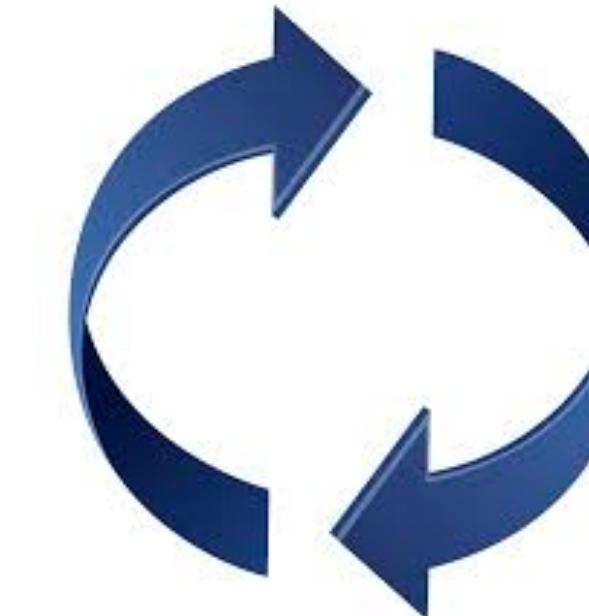
Program  
Sketching

PLDI'05



CEGIS

PLDI'08



SyGuS

FMCAD'13



# Outline

Code  
Reuse

FSE'16



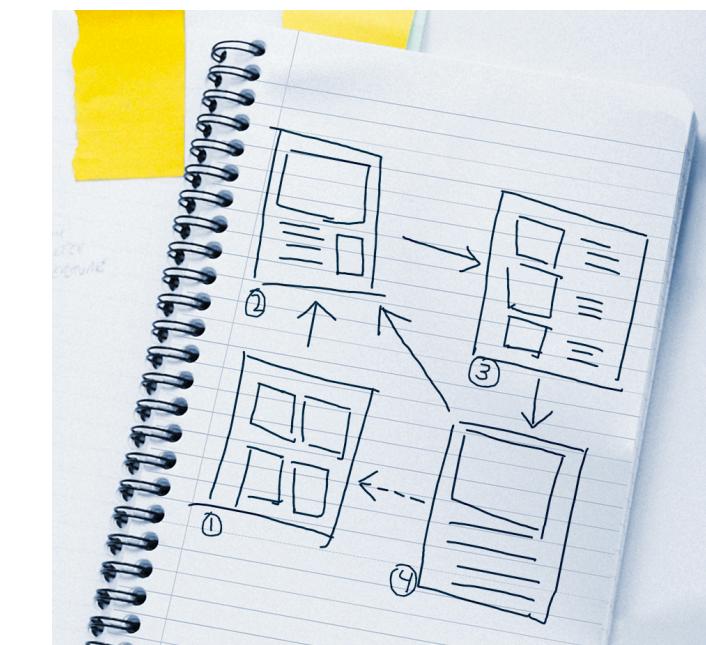
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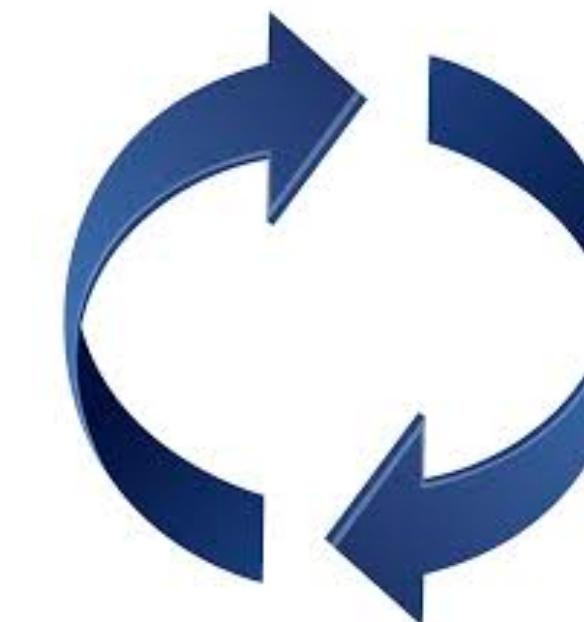
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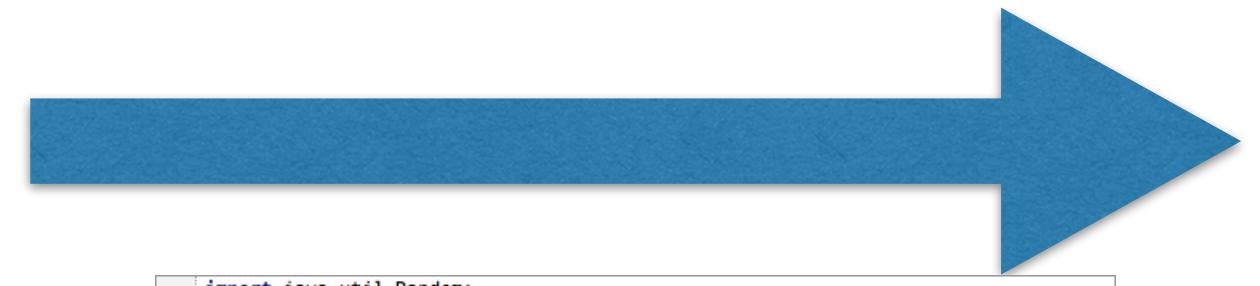
SyGuS

FMCAD'13





# API exploration can be tedious!



```
import java.util.Random;
public final class RandomInteger {
    public static void main(String[] args){
        log("Generating 10 random integers in range 0..99.");
        Random randomGenerator = new Random();
        for (int idx = 1; idx <= 10; idx++) {
            int randomInt = randomGenerator.nextInt();
            log("Generated : " + randomInt);
        }
        log("Done.");
    }
    private static void log(String message) {
        System.out.println(message);
    }
}
```

A screenshot of a Java code editor showing a code completion dropdown. The code generates 10 random integers between 0 and 99. A tooltip shows the current word being typed, 'Random', with a list of suggestions: Random (java.util), RandomInteger (default package), Readable (java.lang), Runnable (java.lang), Runtime (java.lang), RuntimeException (java.lang), and SecureRandom (java.security). A status bar at the bottom says: 'and ↑ will move caret down and up in the editor'.

**Send HTTP request  
Compute GCD  
Rotate an image**

Programmers spend a lot of effort  
learning APIs!

# Synthesizing programs with APIs

- Automatically synthesize an HTTP POST request:

```
import com.mashape.unirest.*;
```

```
String sendHttpPost(String url, String body) {
```

```
}
```



# Synthesizing programs with APIs

- Automatically synthesize an HTTP POST request:

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import com.mashape.unirest.*;
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String sendHttpPost(String url, String body) {
```

```
    HttpRequestWithBody req = post(url);
    RequestBodyEntity ent = req.body(body);
    BaseRequest breq = ent;
    HttpResponse resp = breqasString();
    String result = resp.getStringBody();
    return result;
}
```

```
}
```



# How to find the correct program?

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Use **Petri net reachability** analysis to look for well-typed programs of the desired type

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- Model relationships between components using Petri nets

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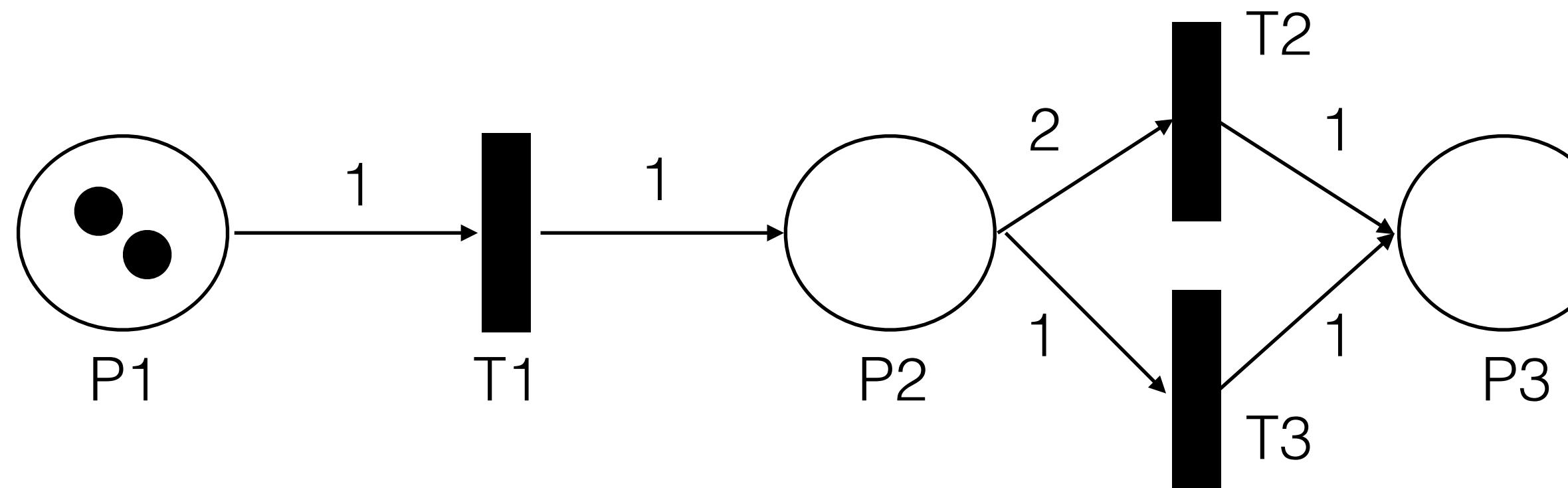
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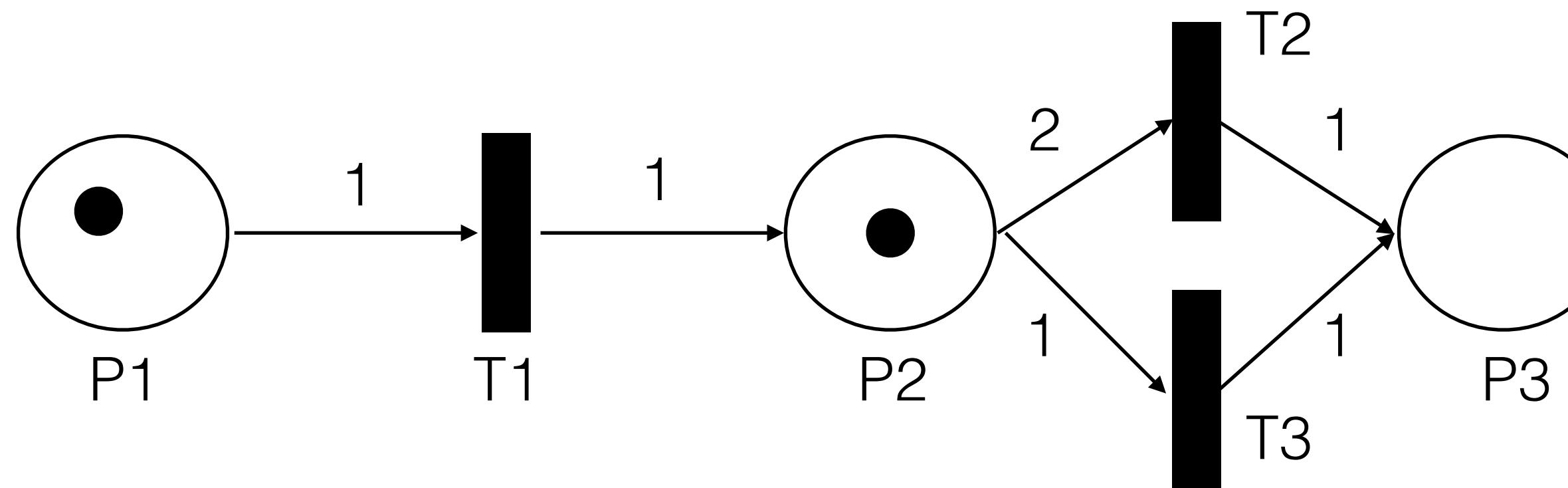
- Model relationships between components using Petri nets
- Use type signature of desired method to mark initial and target configurations
- Perform reachability analysis to find valid sequences of method calls

# Petri nets in a nutshell



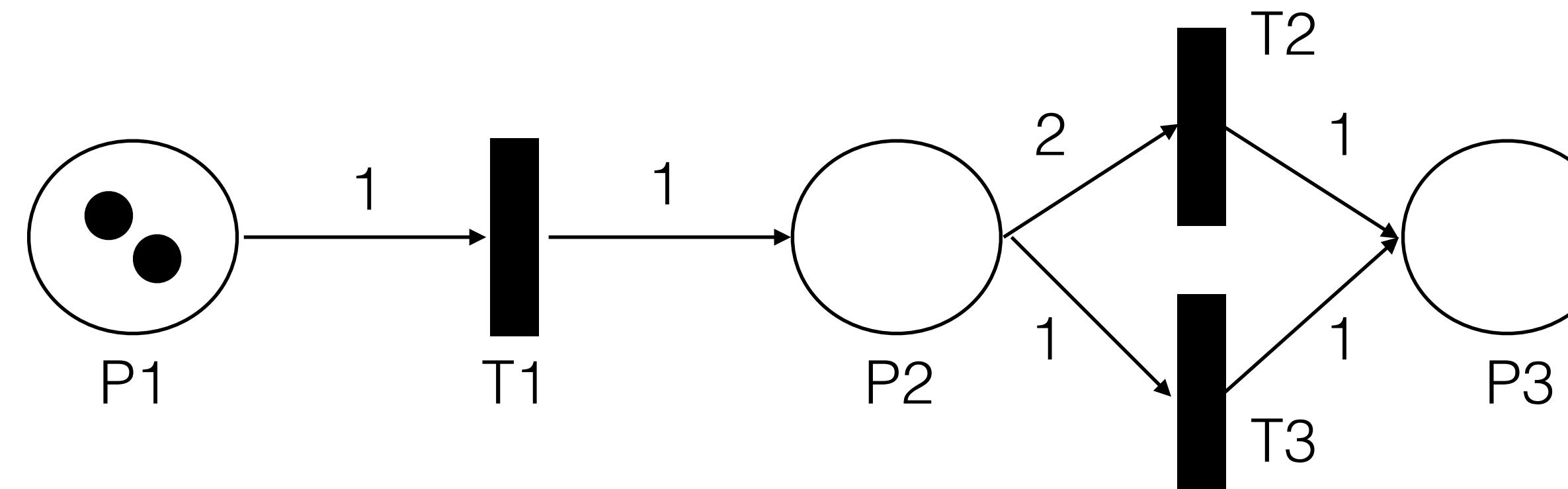
- Petri net is a generalized graph with two kinds of nodes: **places** and **transitions**
- Each place contains zero or more tokens; edges are labeled with a number (of tokens)
- A transition  $T$  can fire if, for each edge  $(p,T)$  with label  $n$ , place  $p$  contains at least  $n$  tokens
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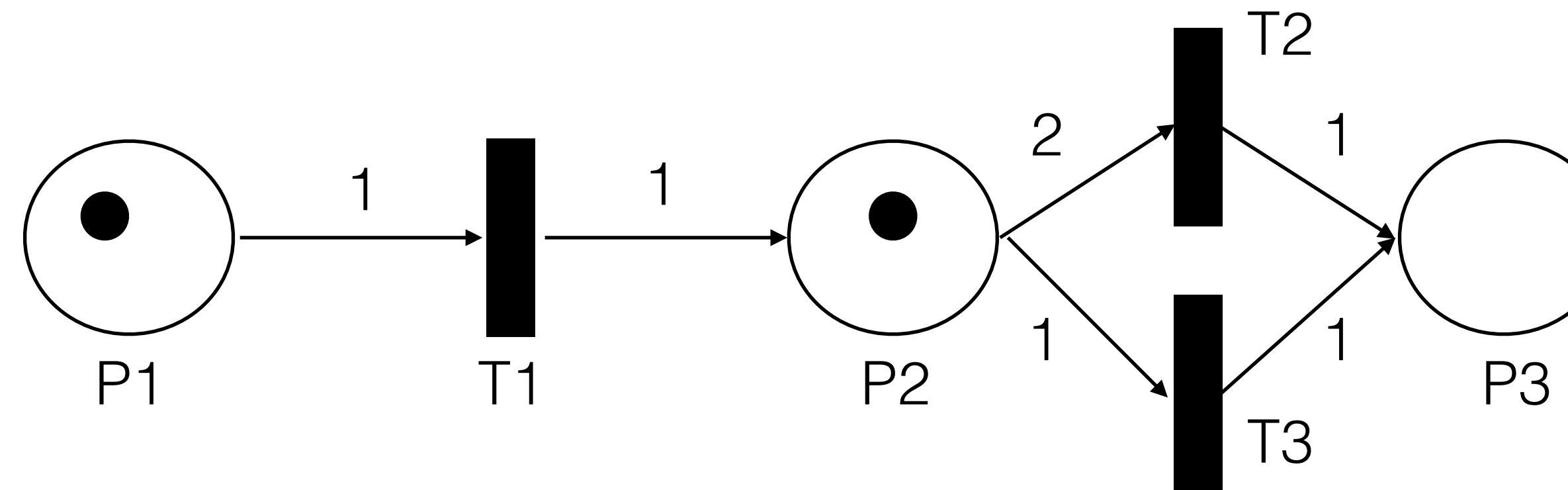
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# Reachability problem in Petri nets



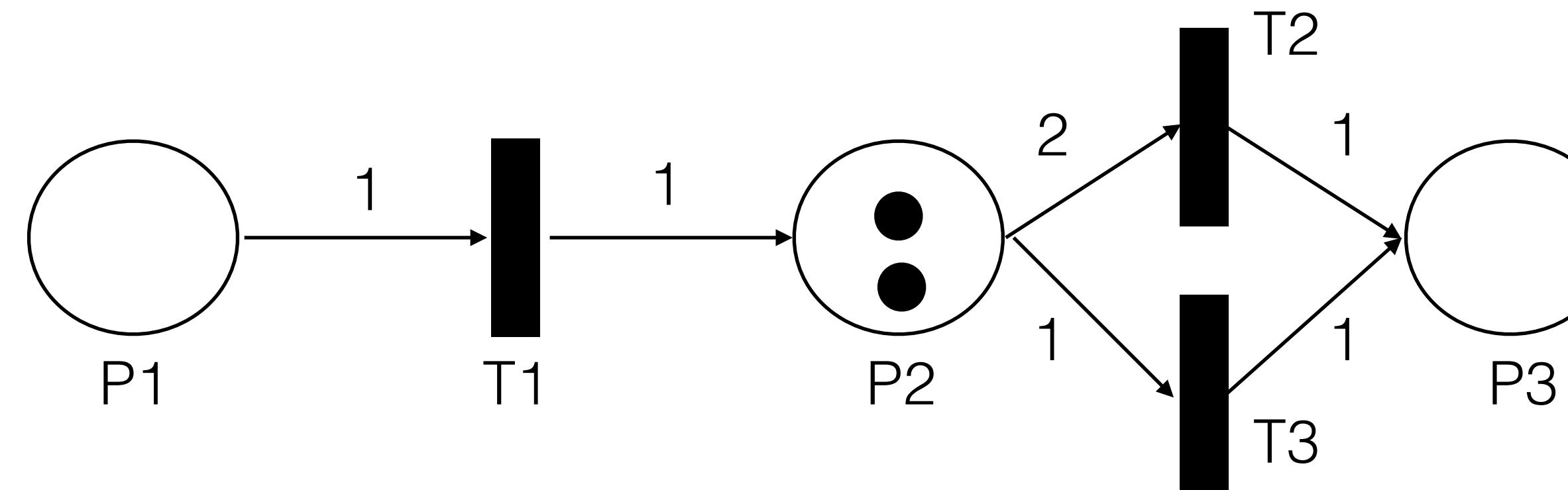
- Reachability problem: Given a Petri net with initial marking  $M$  and a target marking  $M'$ , is it possible to obtain  $M'$  by firing a sequence of transitions?
- Example: Consider marking  $M' : [P1 \rightarrow 0, P2 \rightarrow 0, P3 \rightarrow 1]$ .
- This marking is reachable, and accepting run is  $T1, T1, T2$ .

# Reachability problem in Petri nets



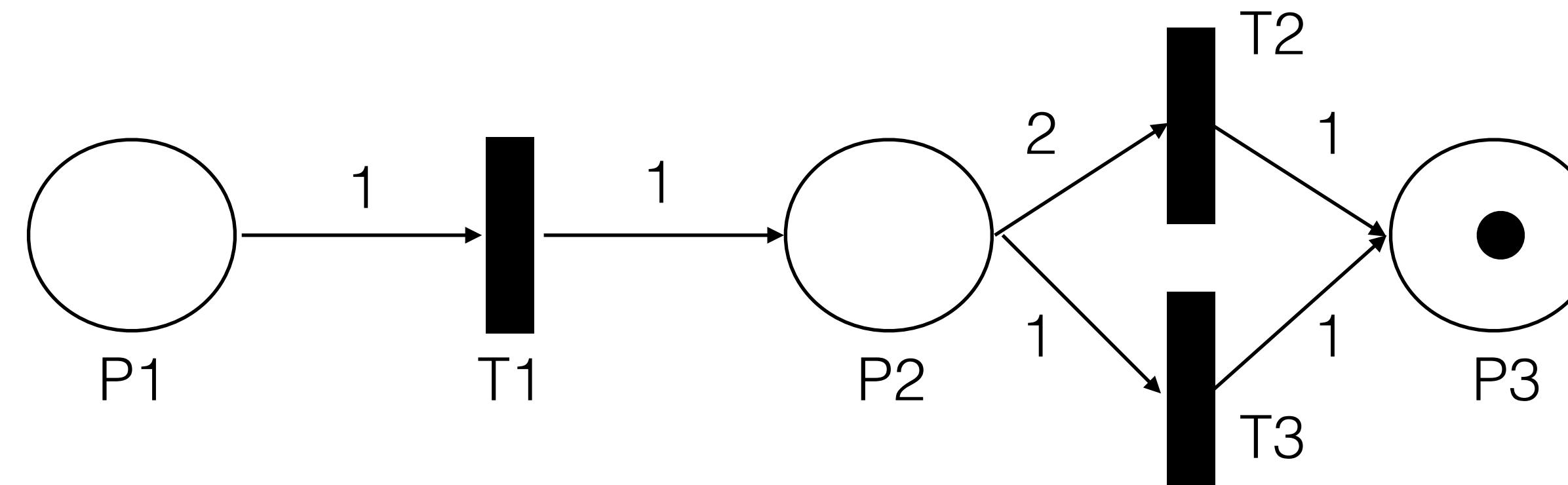
- Reachability problem: Given a Petri net with initial marking  $M$  and a target marking  $M'$ , is it possible to obtain  $M'$  by firing a sequence of transitions?
- Example: Consider marking  $M' : [P1 \rightarrow 0, P2 \rightarrow 0, P3 \rightarrow 1]$ .
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# Reachability problem in Petri nets



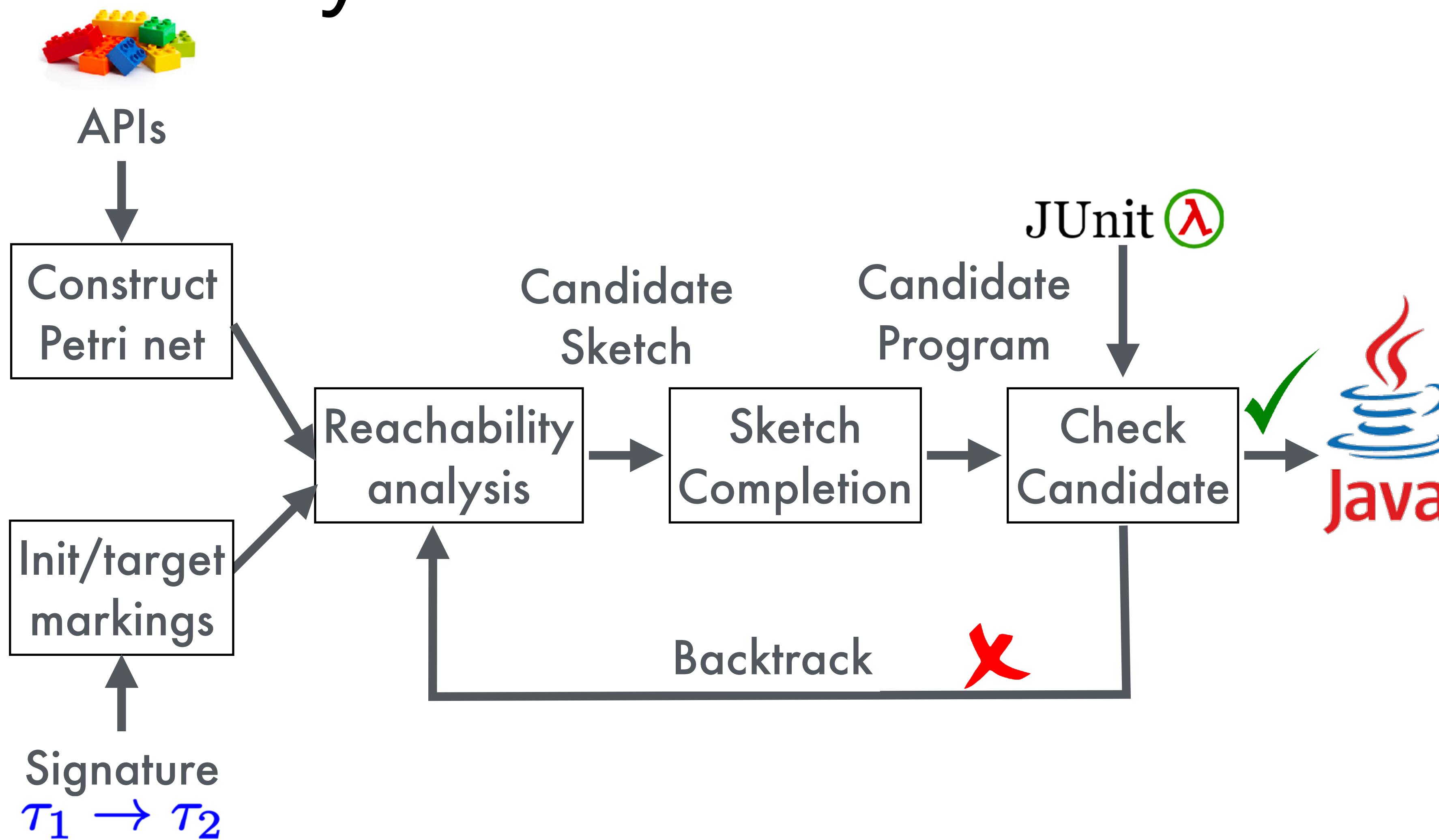
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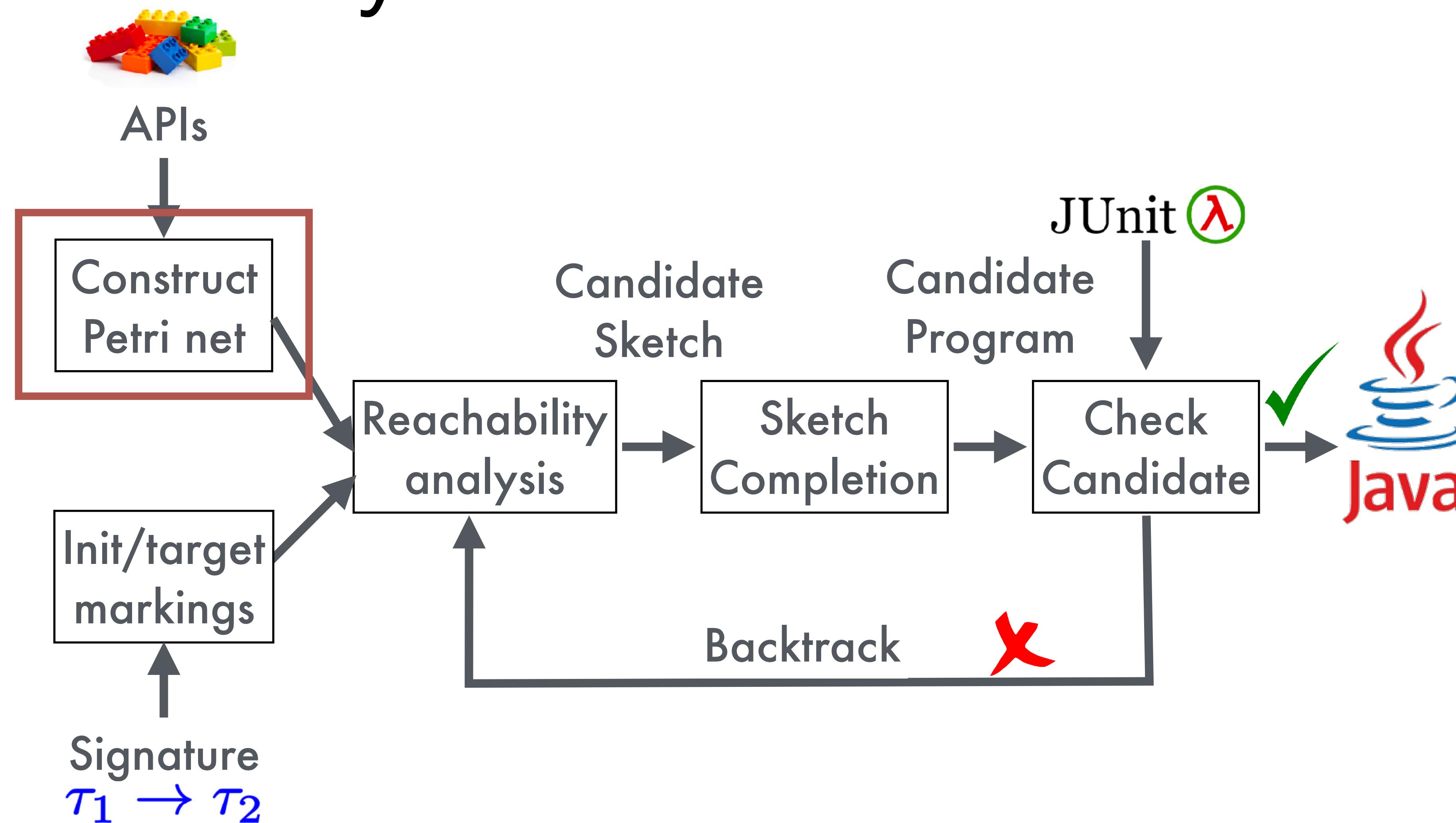


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# SyPet architecture

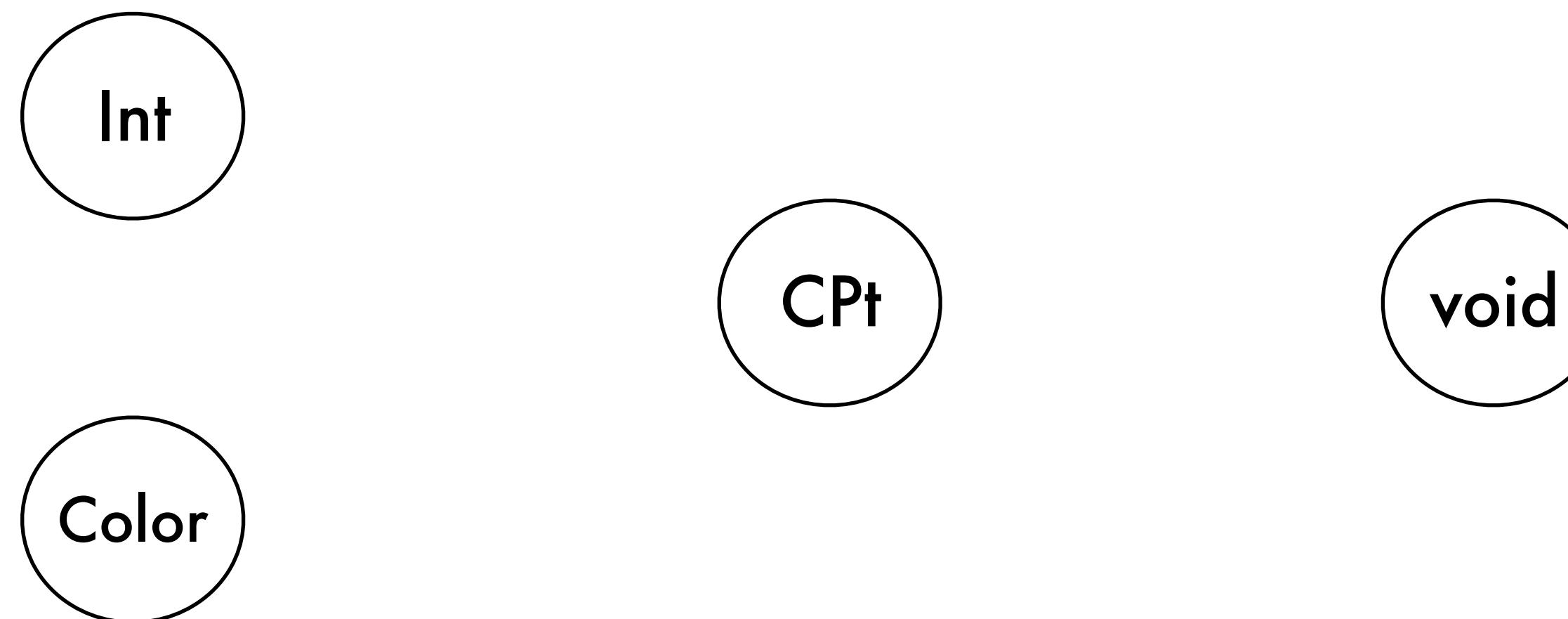


# SyPet architecture



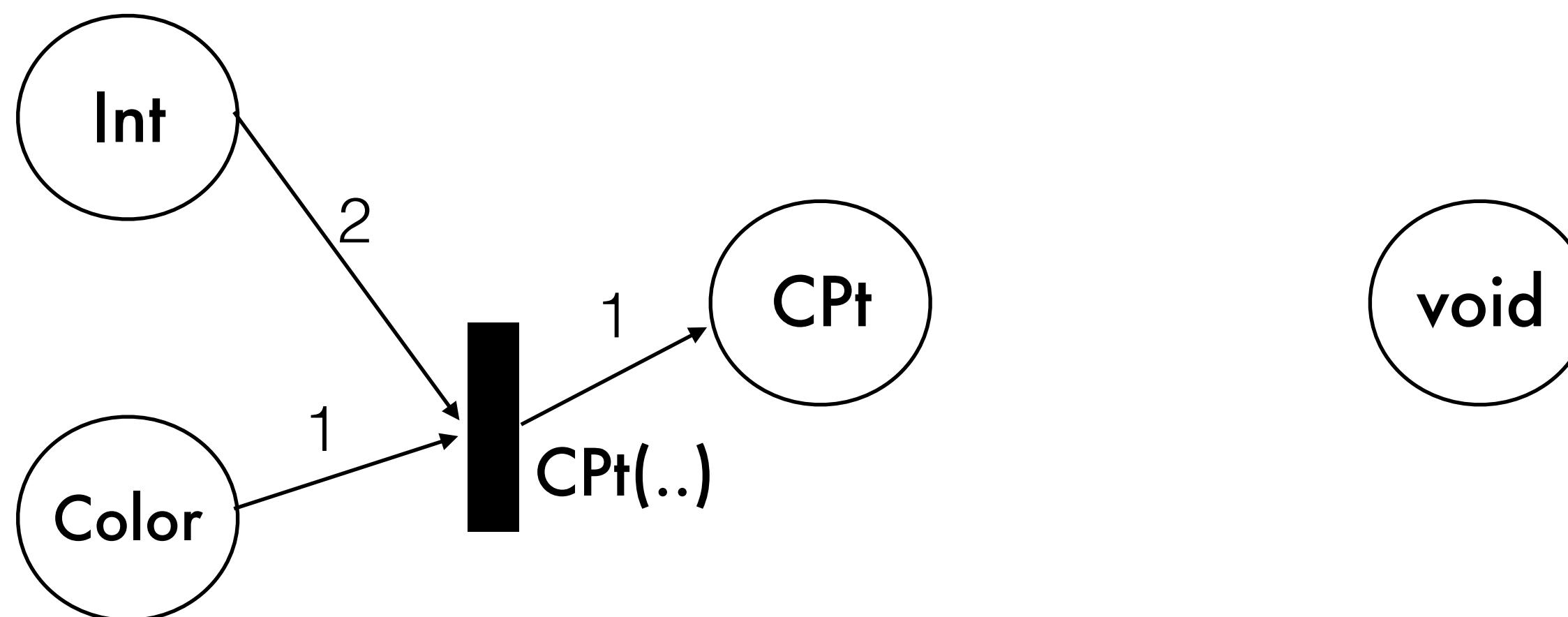
# Petri net construction

```
class CPt {  
    CPt(Int x, Int y, Color c);  
    Int getX();  
    void setColor(Color c);  
    ...  
}
```



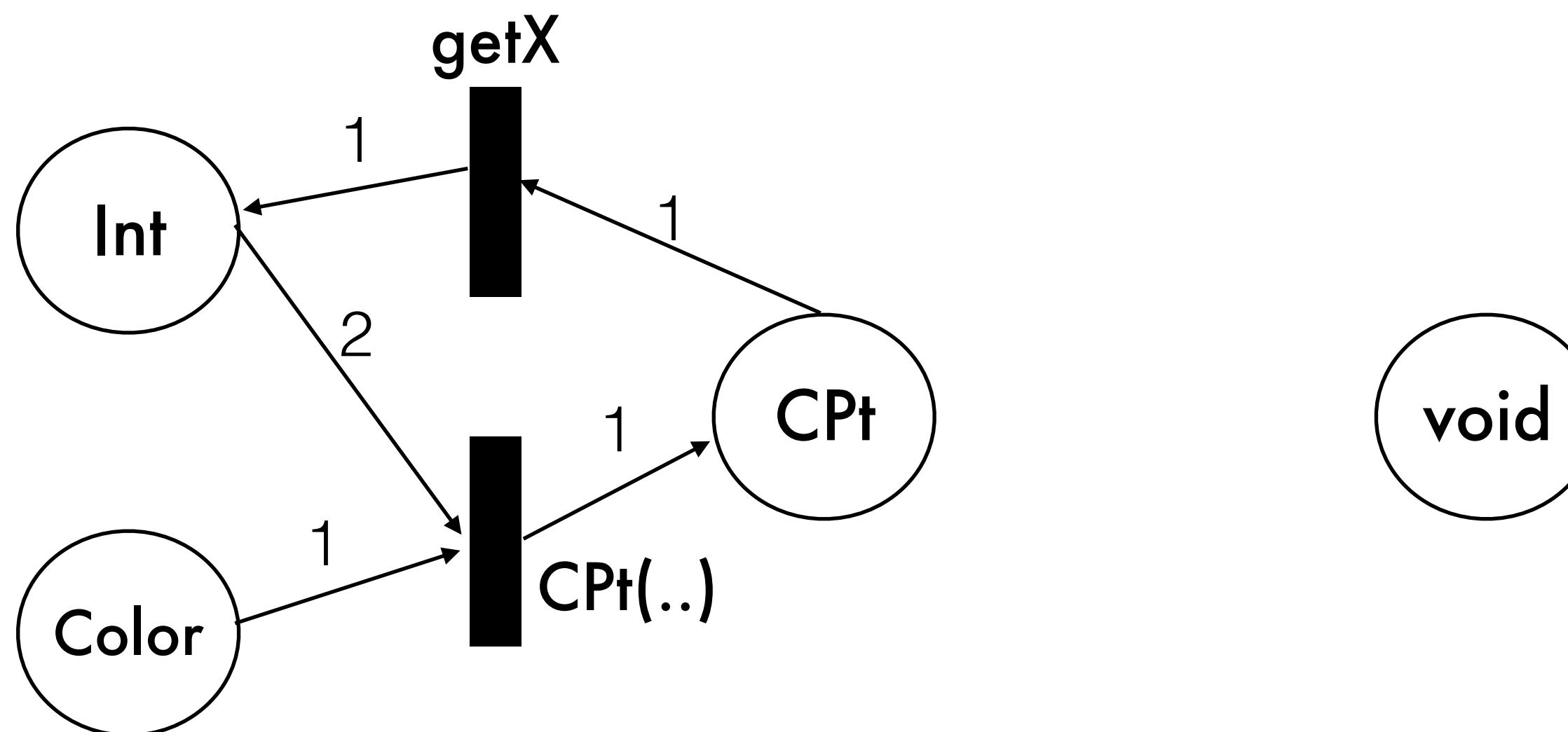
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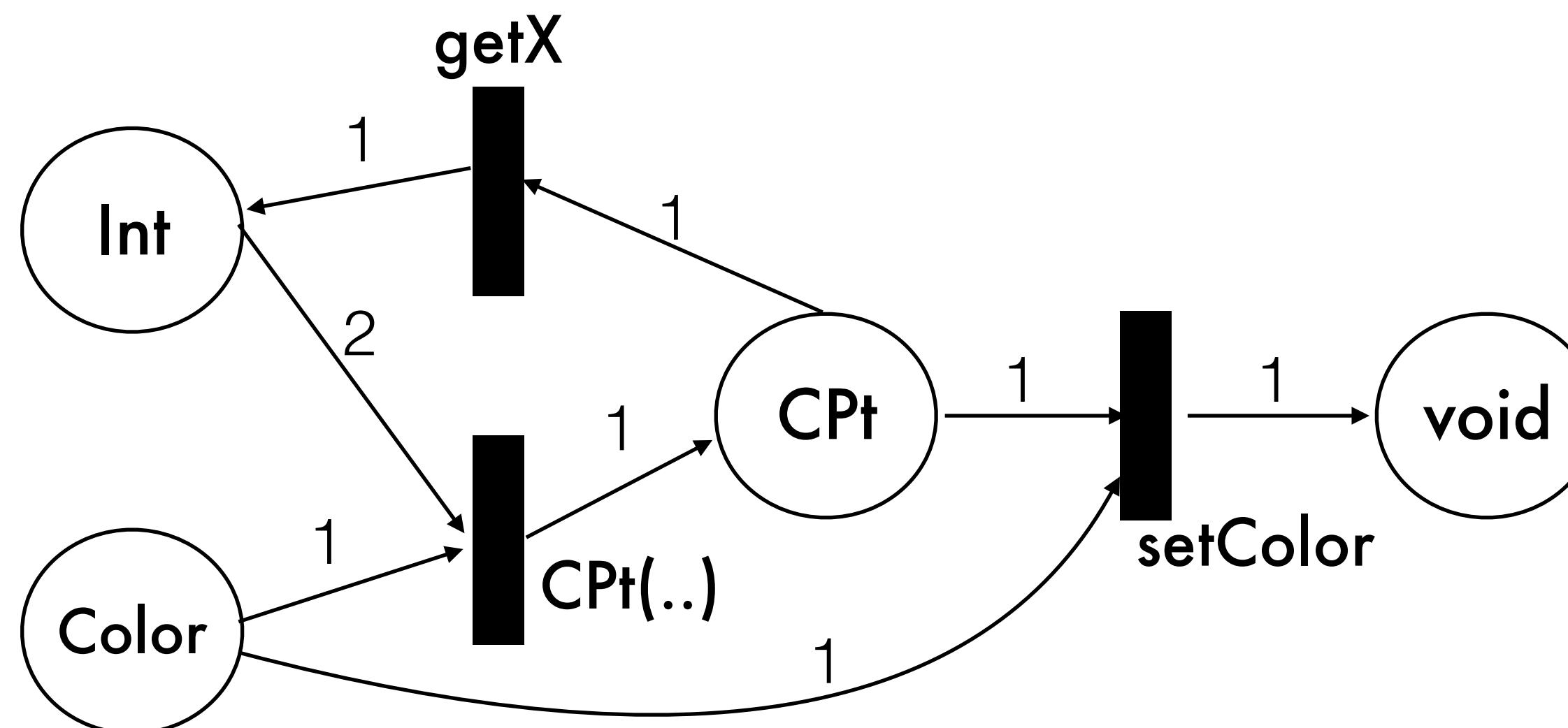
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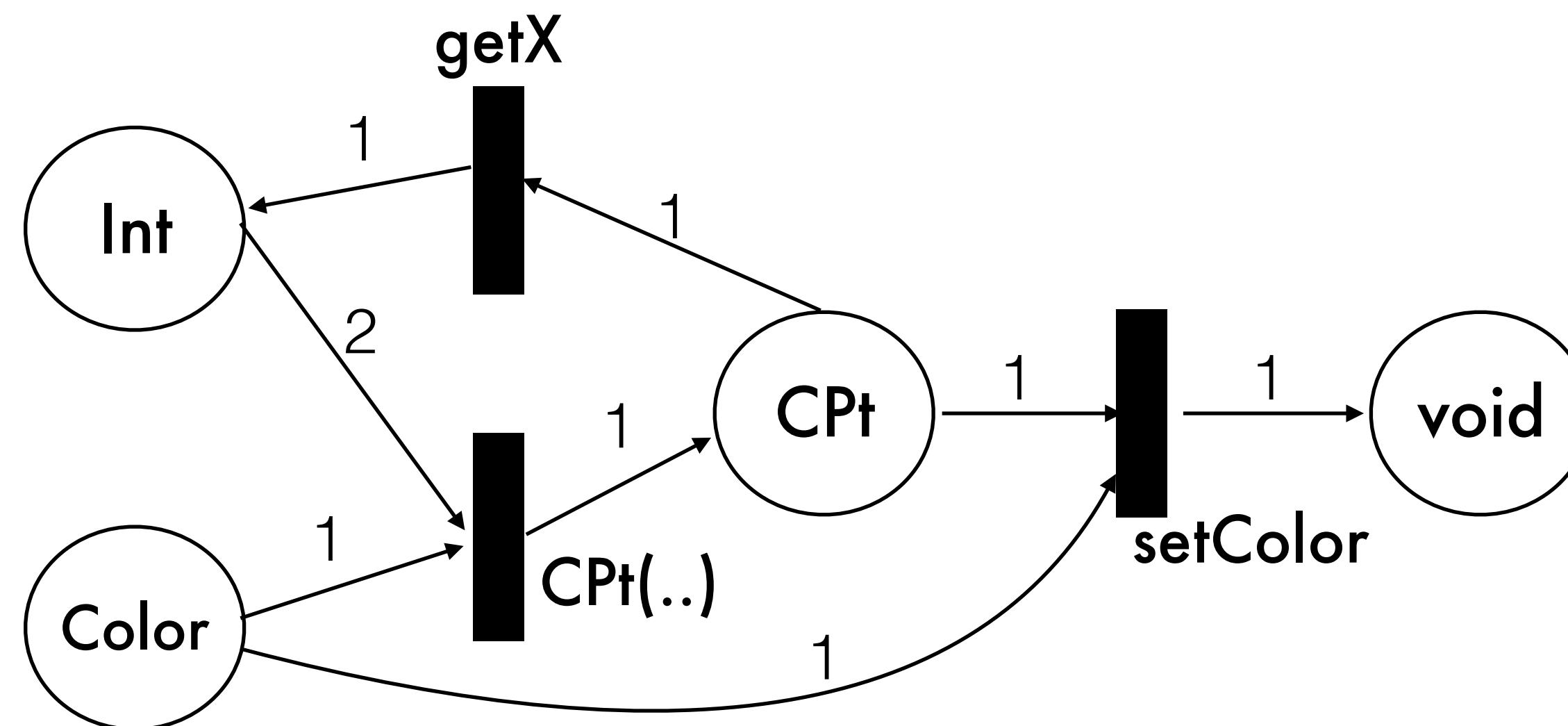


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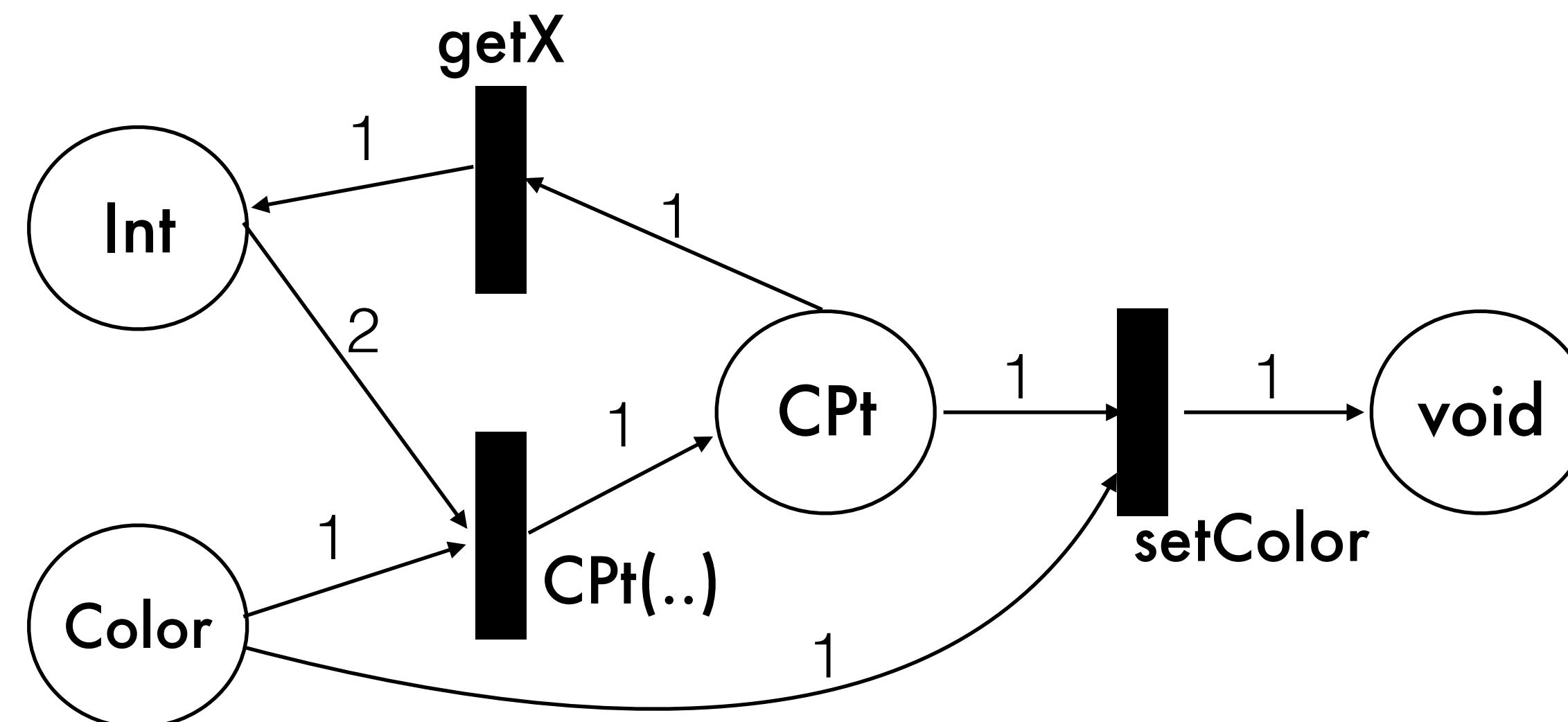


# Clone transitions



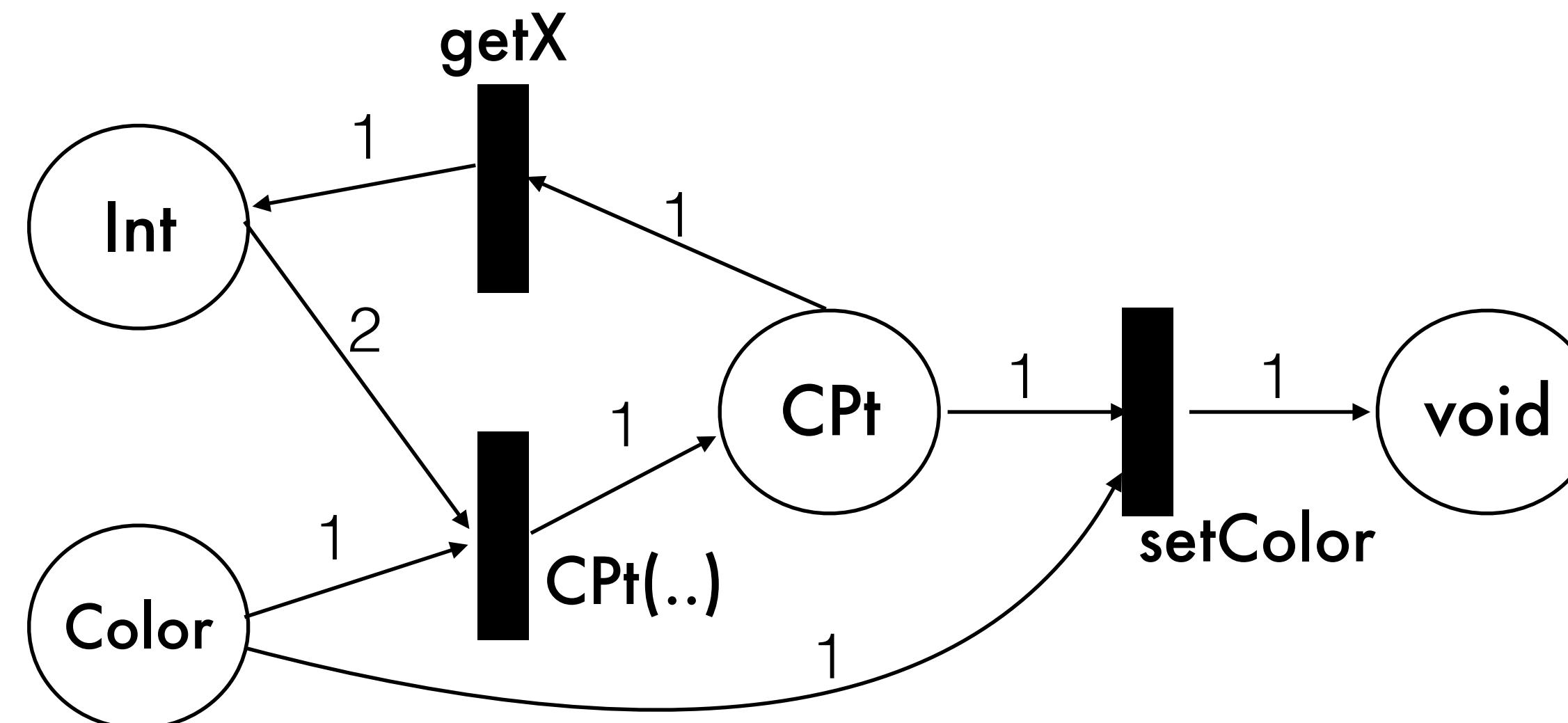
# Clone transitions

- Our construction so far views objects as “resources” – every method “consumes” and “produces” objects



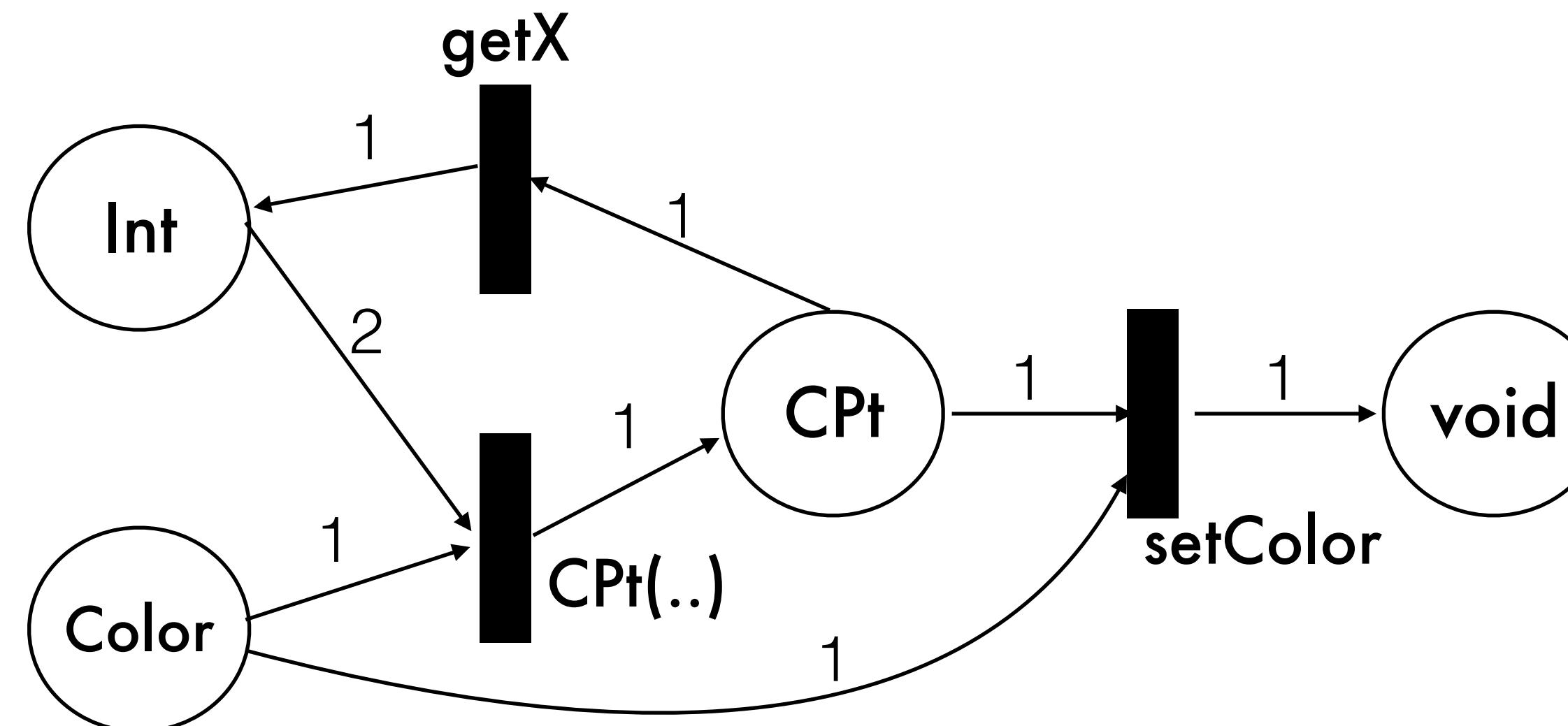
# Clone transitions

- Our construction so far views objects as “resources” – every method “consumes” and “produces” objects
- But in conventional languages, we can reuse objects!



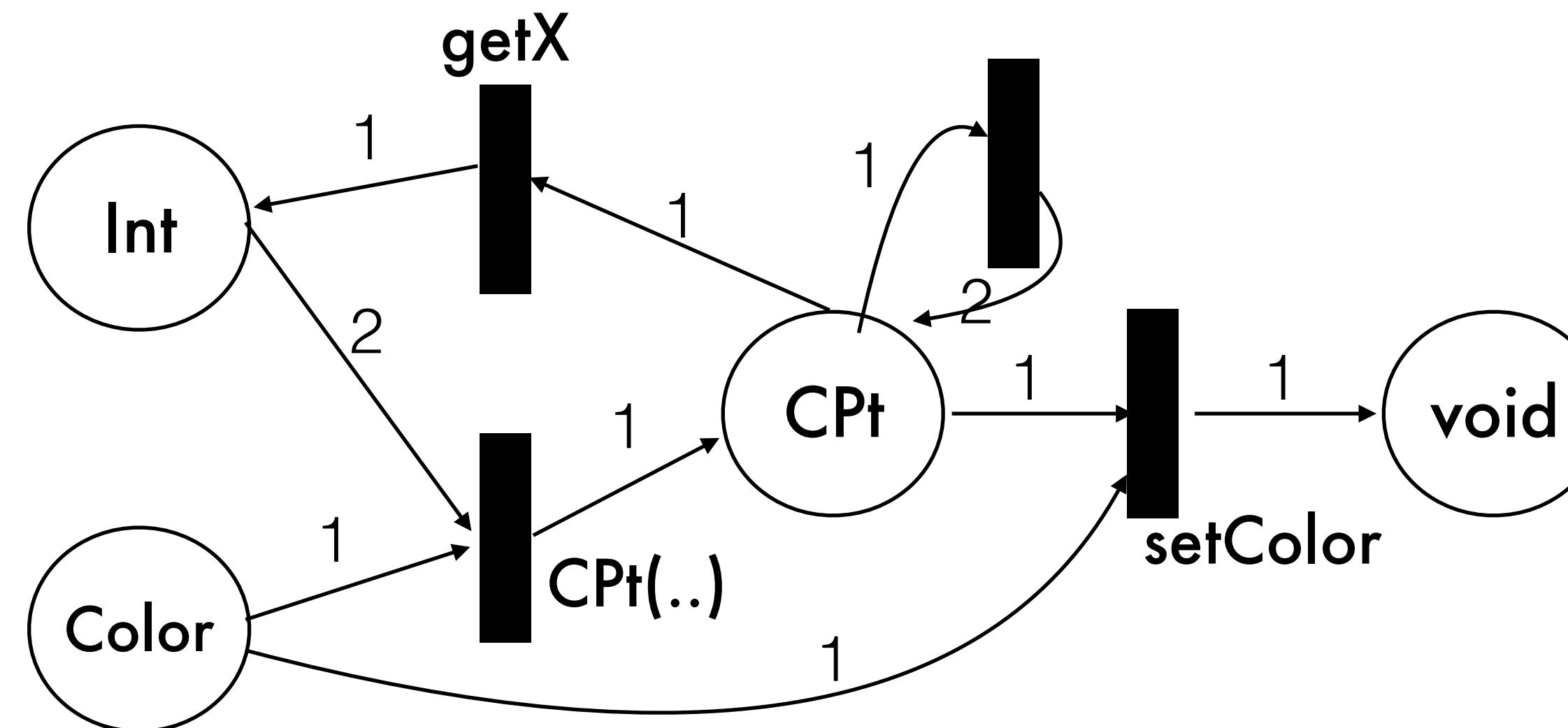
# Clone transitions

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- But in conventional languages, we can reuse objects!
- Therefore, augment Petri net model with **clone transitions**



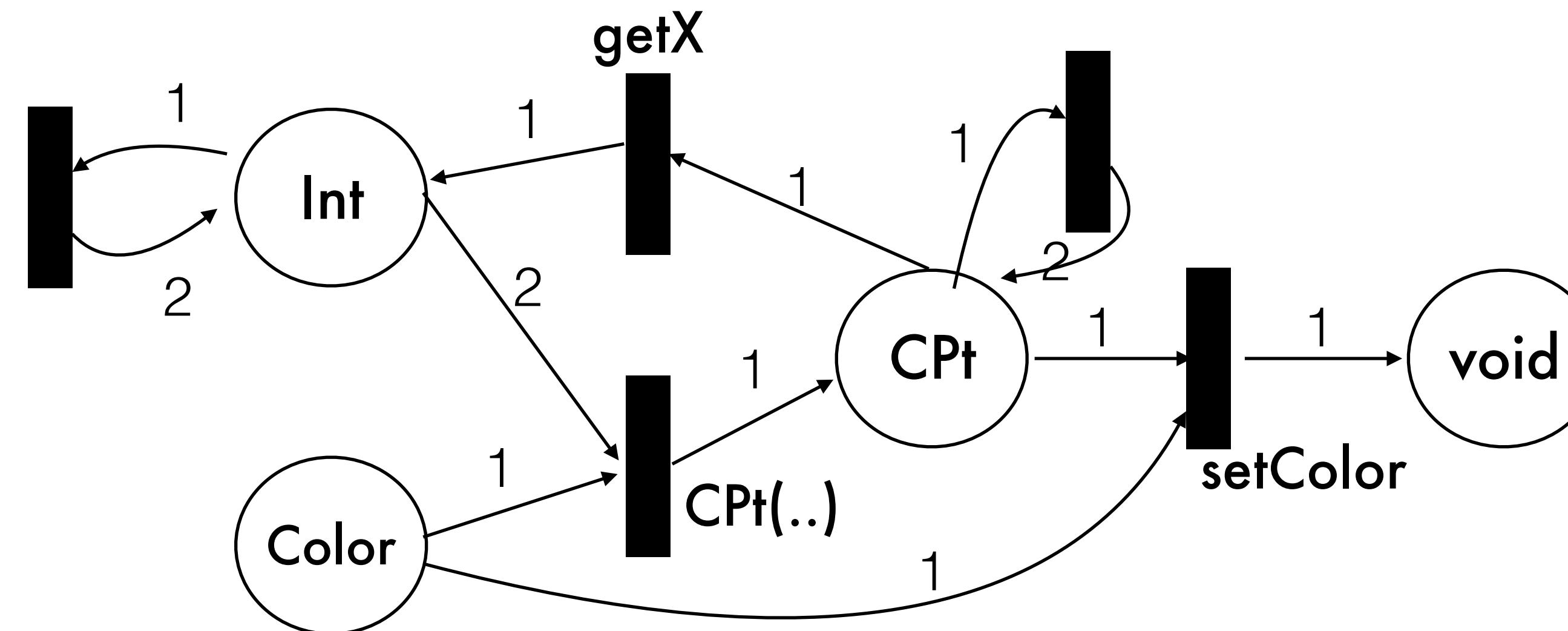
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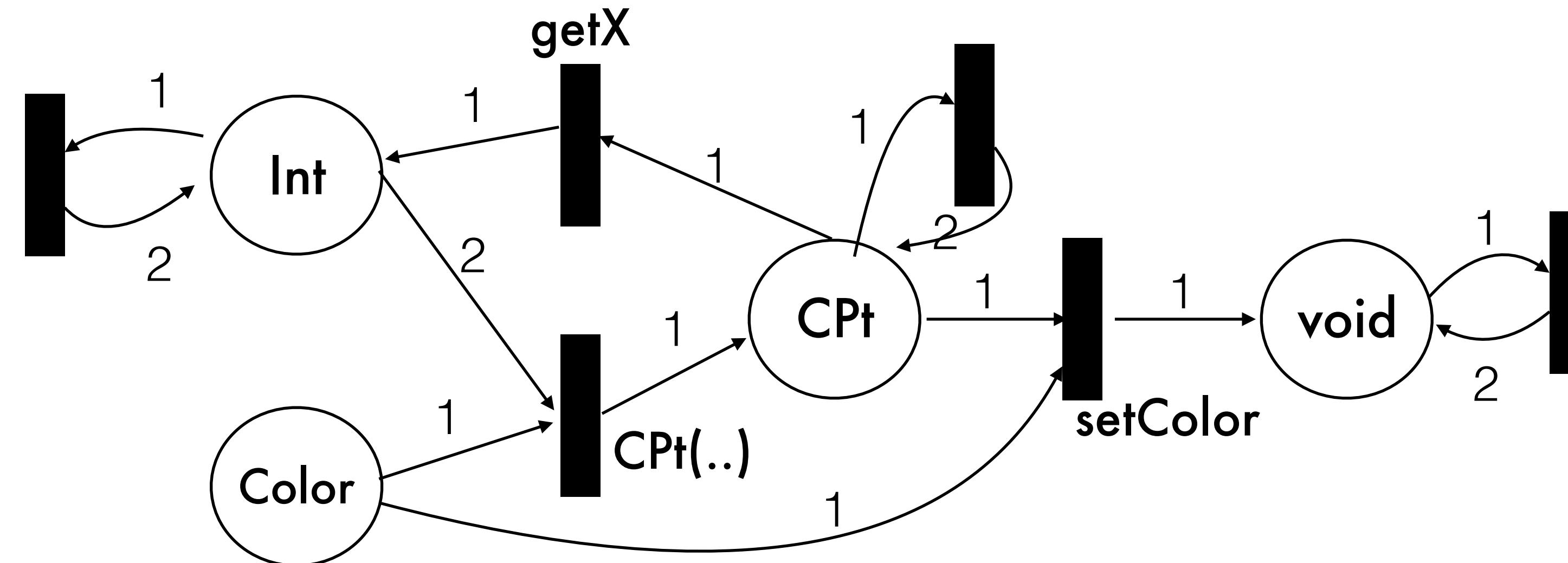
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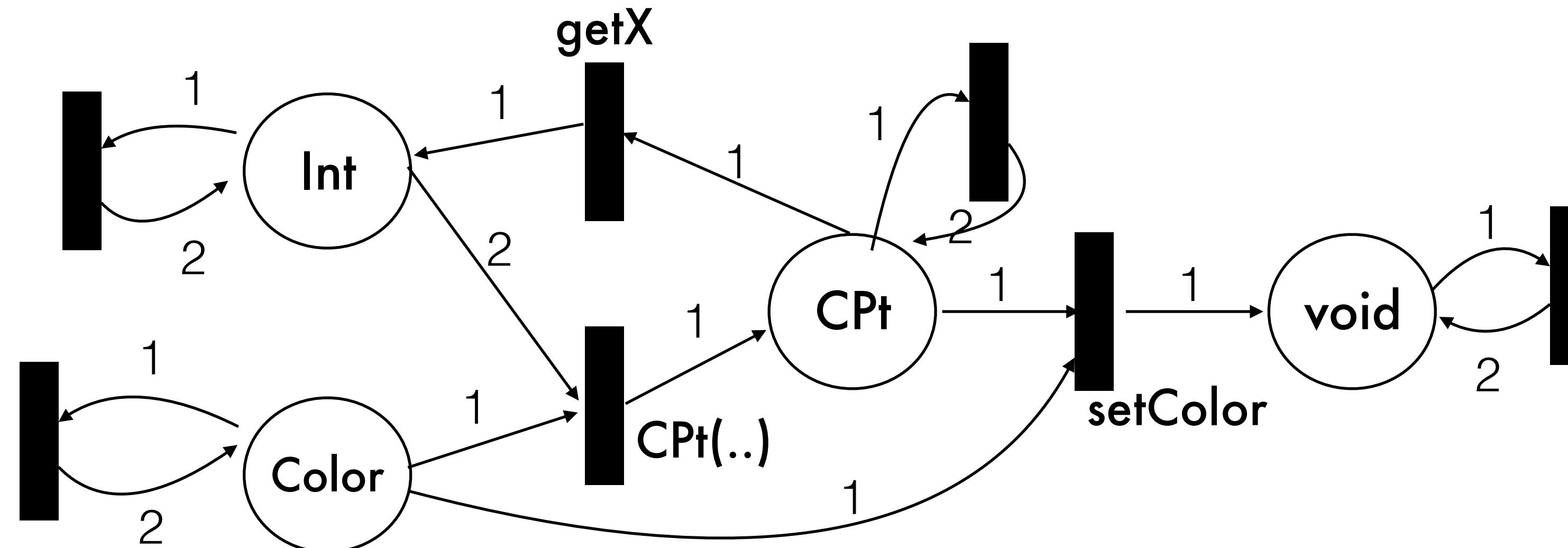
# Clone transitions

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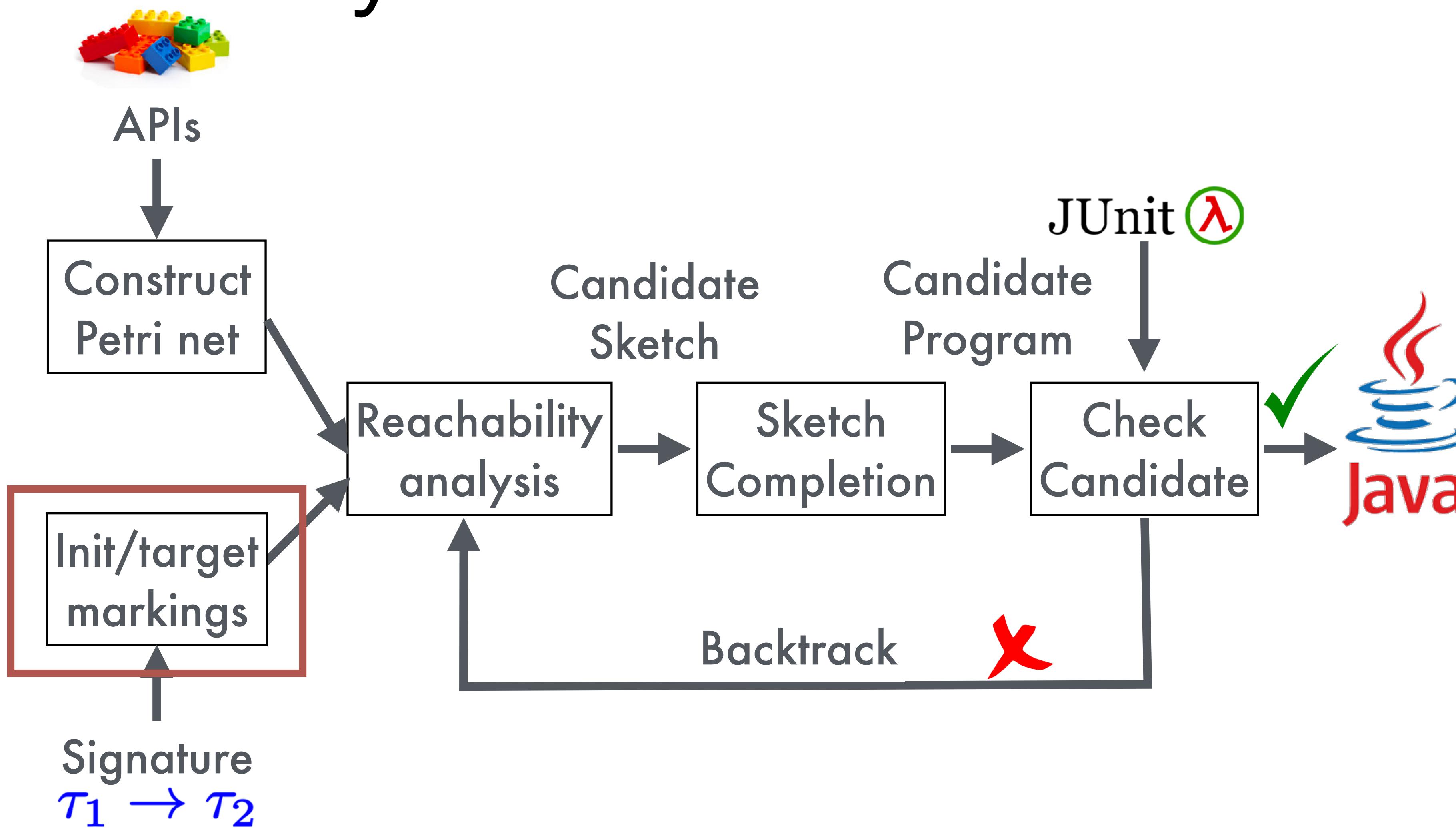


# Clone transitions

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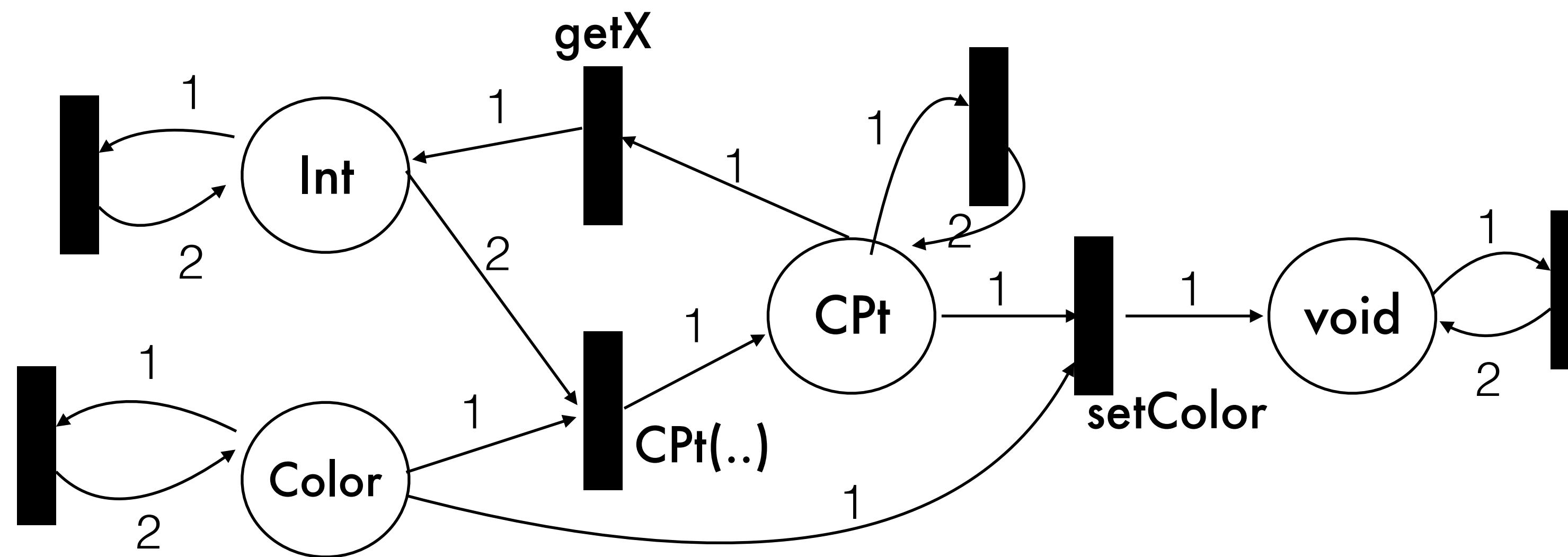


# SyPet architecture



# Initial and target markings

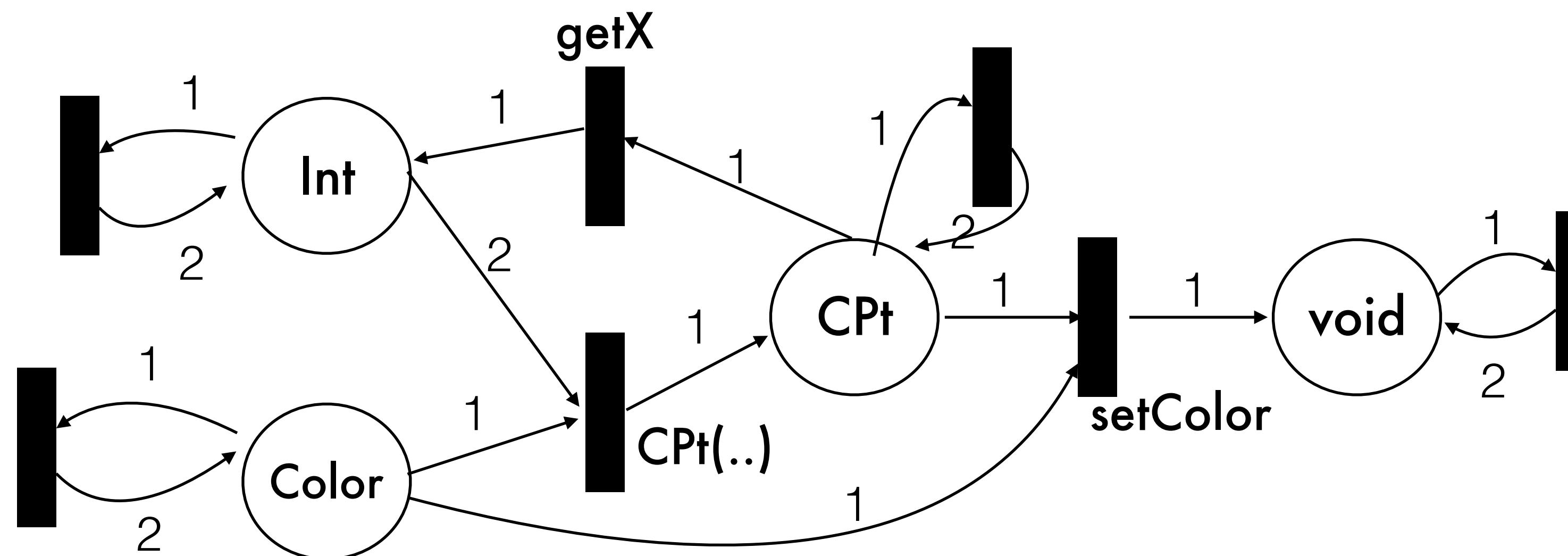
Use signature to determine initial and target markings of Petri net



# Initial and target markings

Use signature to determine initial  
and target markings of Petri net

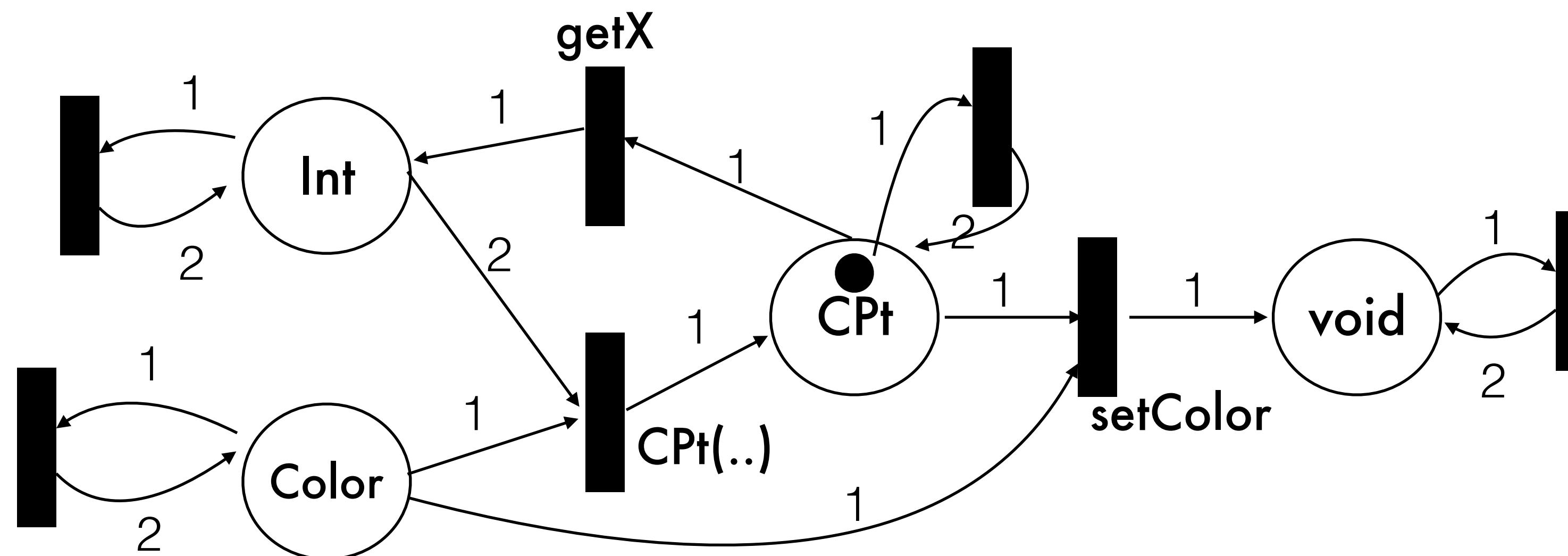
CPt shift (CPt p, Int shiftX, Int shiftY)



# Initial and target markings

Use signature to determine initial  
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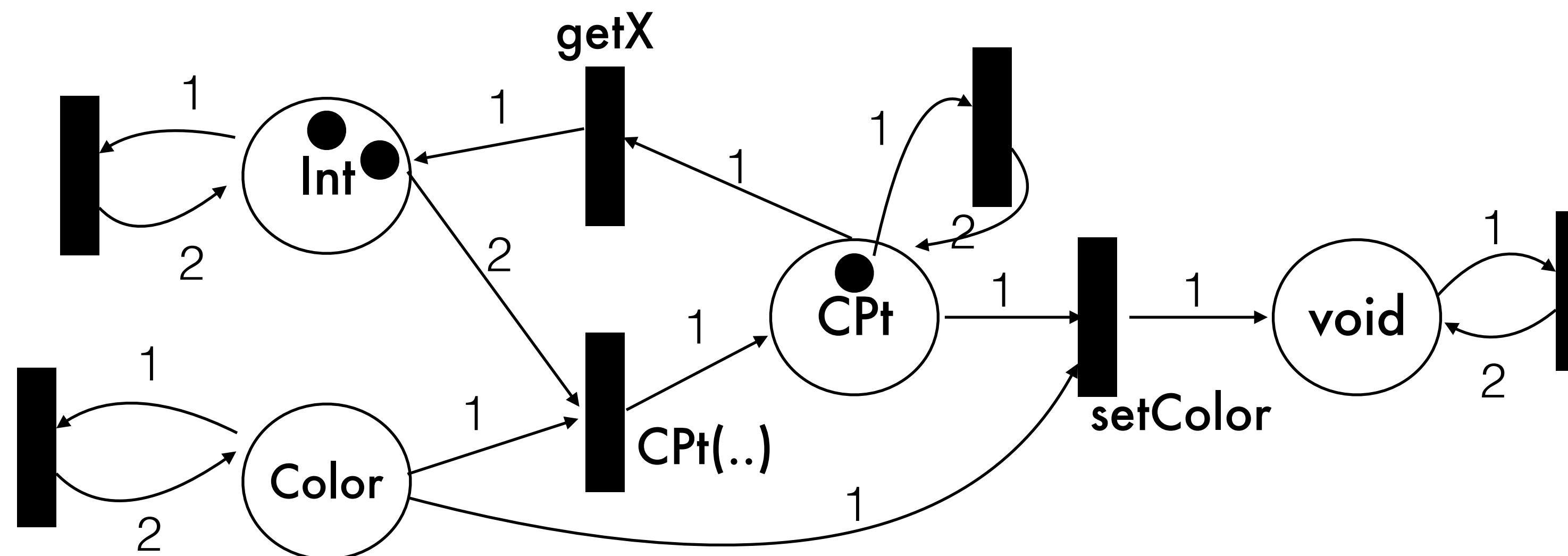
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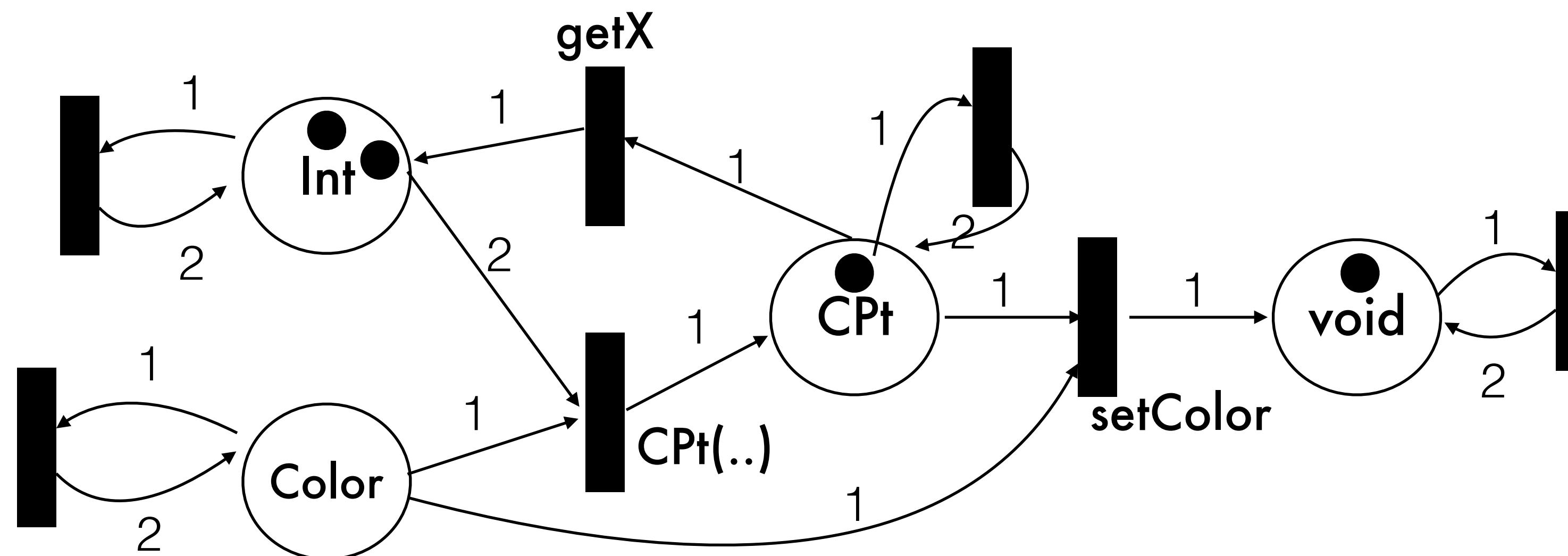
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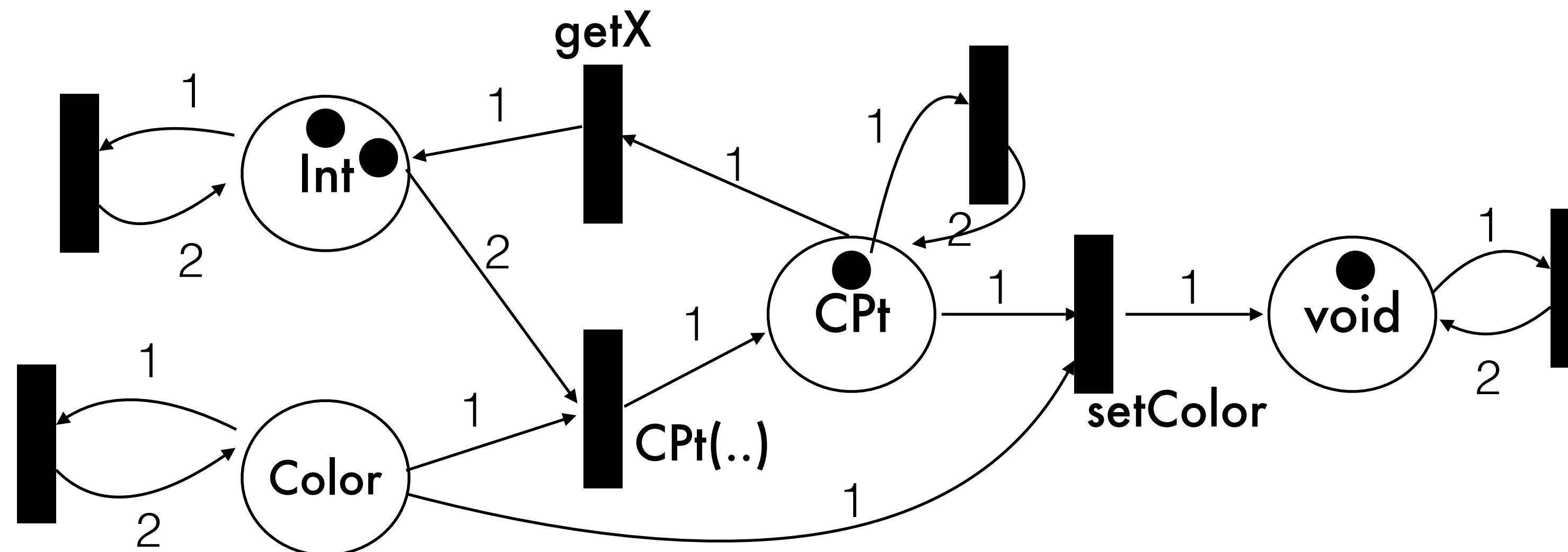
CPt shift (CPt p, Int shiftX, Int shiftY)



# Initial and target markings

Use signature to determine initial  
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CPt shift (CPt p, Int shiftX, Int shiftY)  
Target marking:



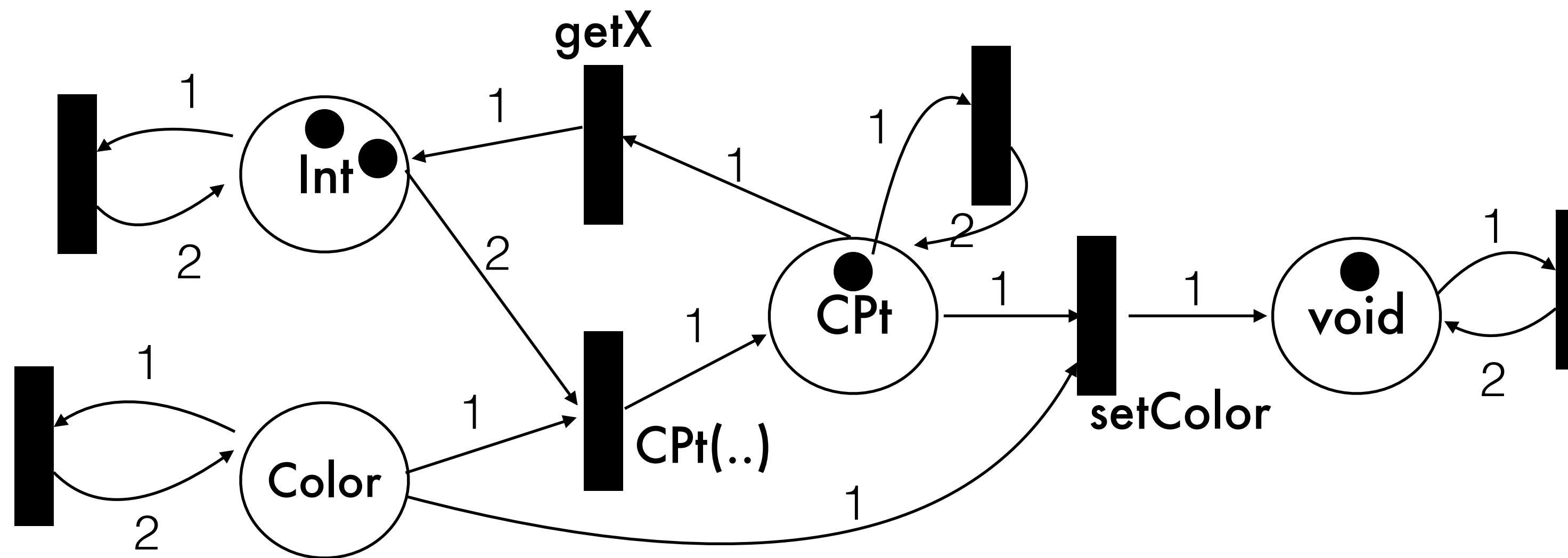
# Initial and target markings

Use signature to determine initial  
and target markings of Petri net

CPt shift (CPt p, Int shiftX, Int shiftY)

Target marking:

CPt = 1



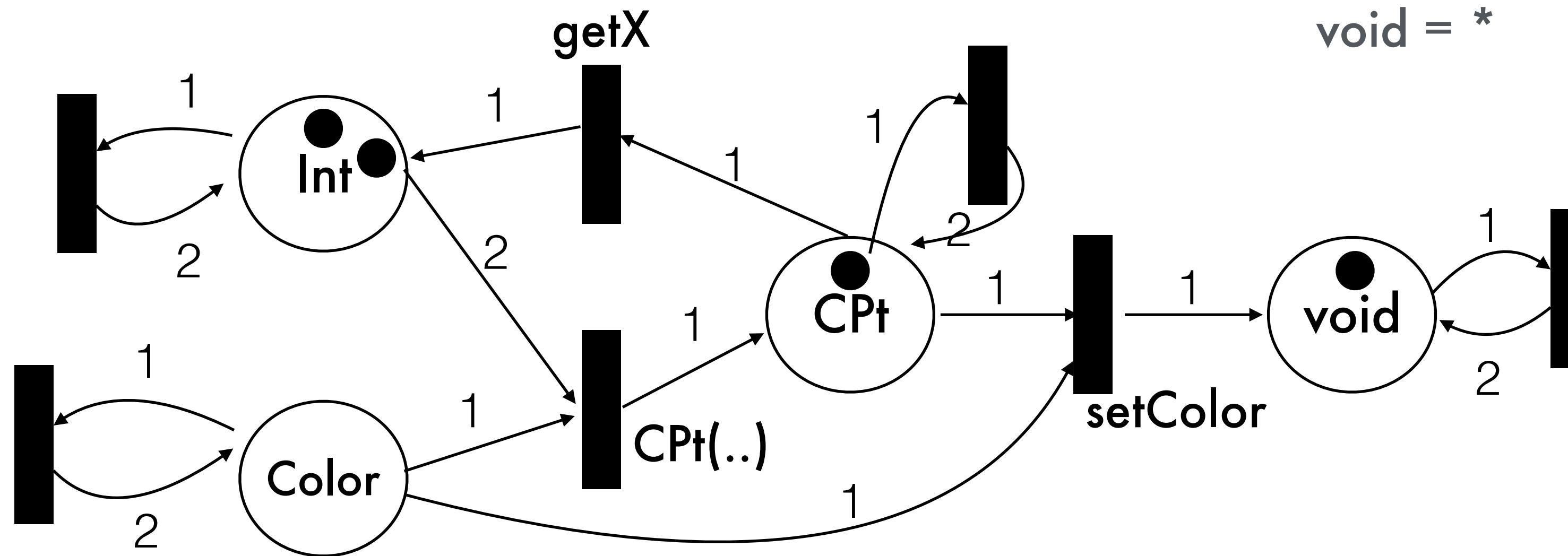
# Initial and target markings

Use signature to determine initial  
and target markings of Petri net

CPt shift (CPt p, Int shiftX, Int shiftY)

Target marking:

CPt = 1  
void = \*



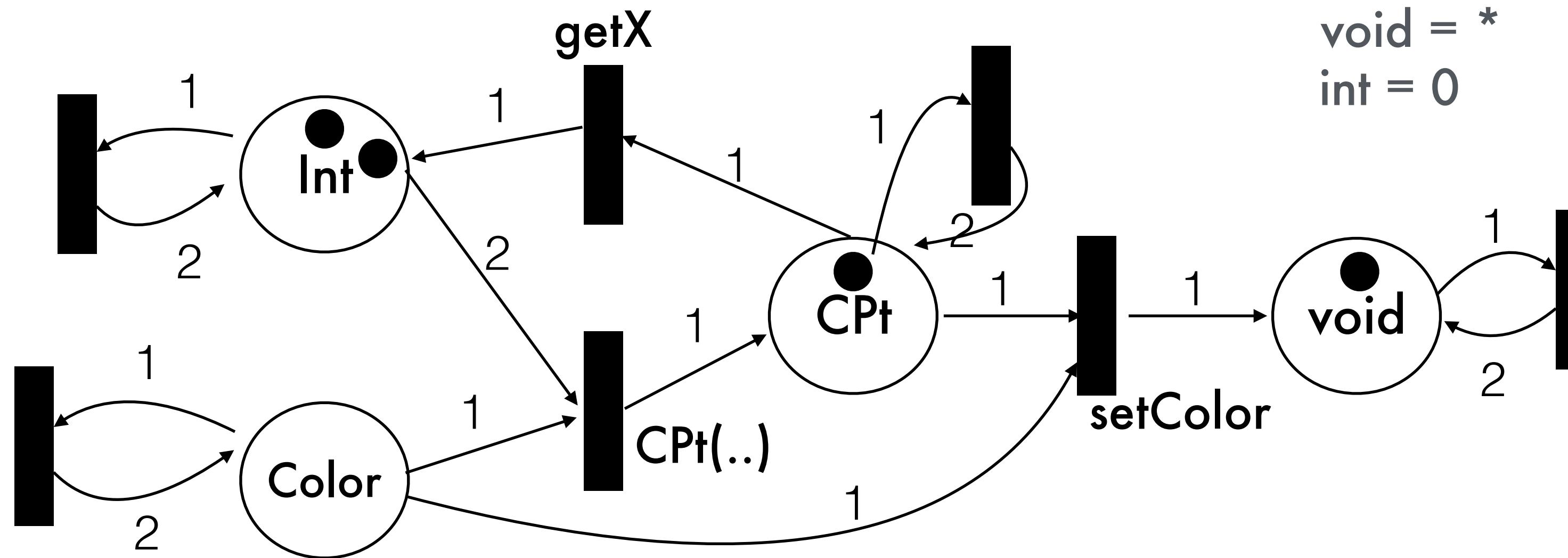
# Initial and target markings

Use signature to determine initial  
and target markings of Petri net

CPt shift (CPt p, Int shiftX, Int shiftY)

Target marking:

CPt = 1  
void = \*  
int = 0

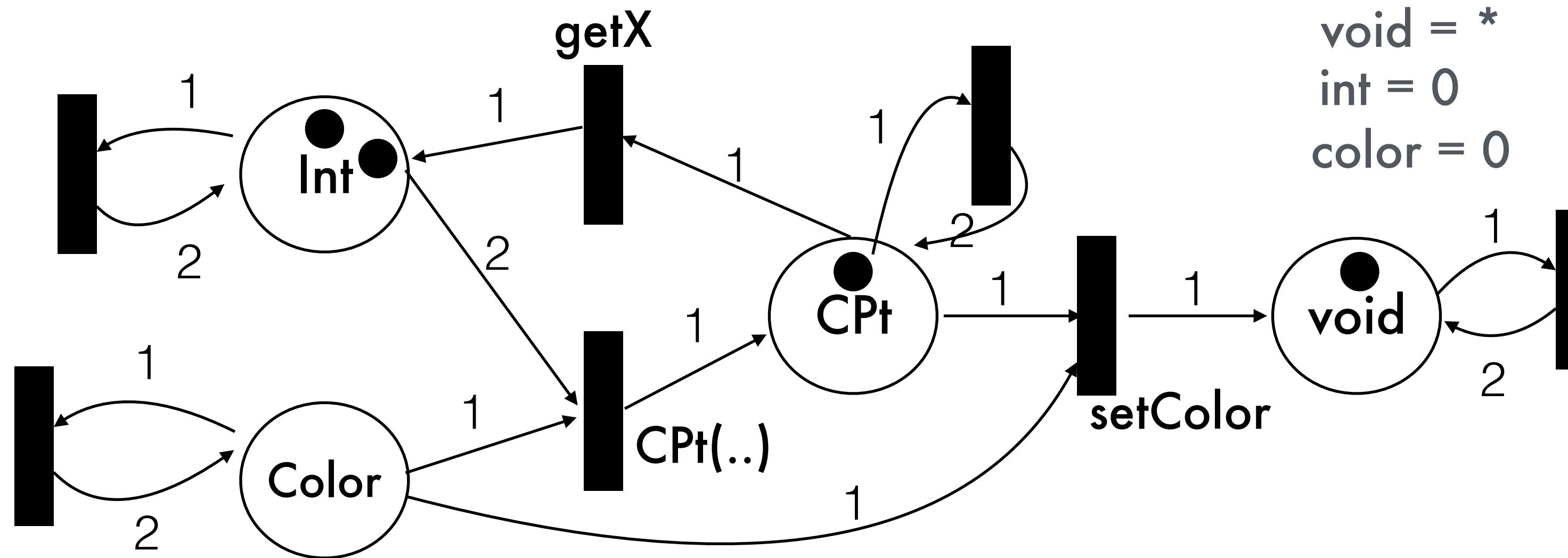


# Initial and target markings

Use signature to determine initial  
and target markings of Petri net

CPt shift (CPt p, Int shiftX, Int shiftY)

Target marking:



Cpt = 1  
void = \*  
int = 0  
color = 0

# Initial and target markings

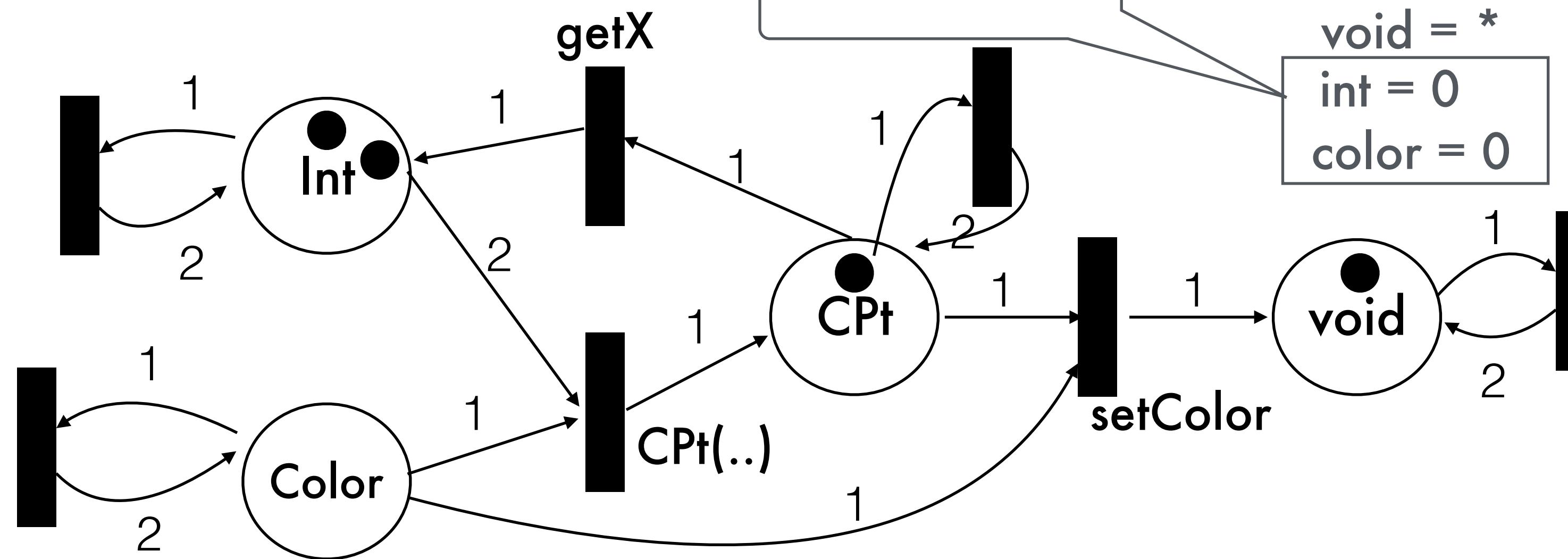
Use signature to determine initial  
and target markings of Petri net

CPt shift (CPt p, Int shiftX, Int shiftY)

All args must  
be used!

Target marking:

Cpt = 1  
void = \*  
int = 0  
color = 0



# Exercise 1: Building a Petri Net

```
class Point {  
    Point();  
    int getX();  
    int getY();  
    void setX(int);  
    void setY(int);  
}
```

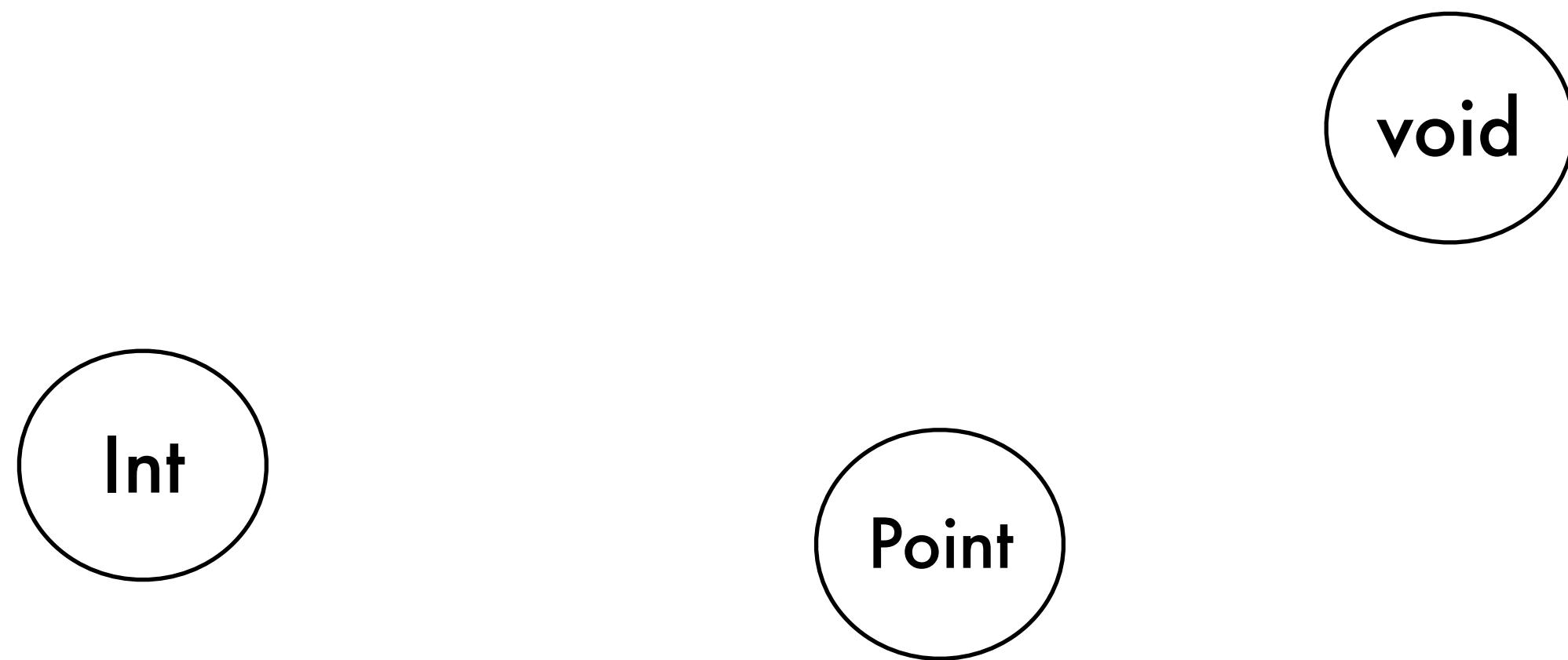
```
class MyPoint {  
    MyPoint(int x, int y);  
    int getX();  
    int getY();  
}
```

- Build a petri net with the classes Point and MyPoint:
  - Hint: What are the places (i.e., types)?
  - Hint: What are the transitions (i.e., methods)?
  - Hint: Don't forget the clone edges!

# Exercise 1: Solution

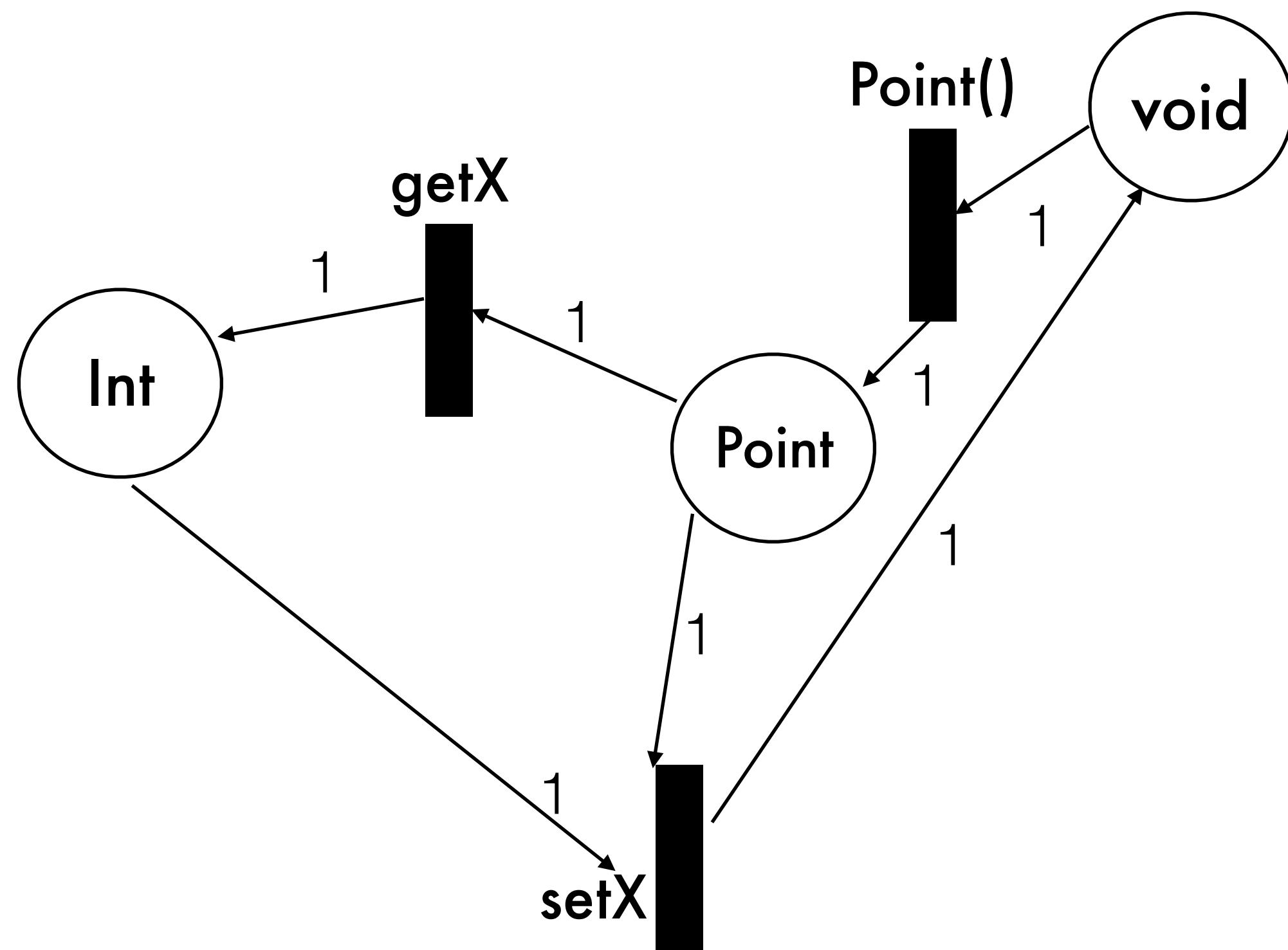
```
class Point {  
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    int getX();  
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    void setX(int);  
    void setY(int);  
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```

# Exercise 1: Solution



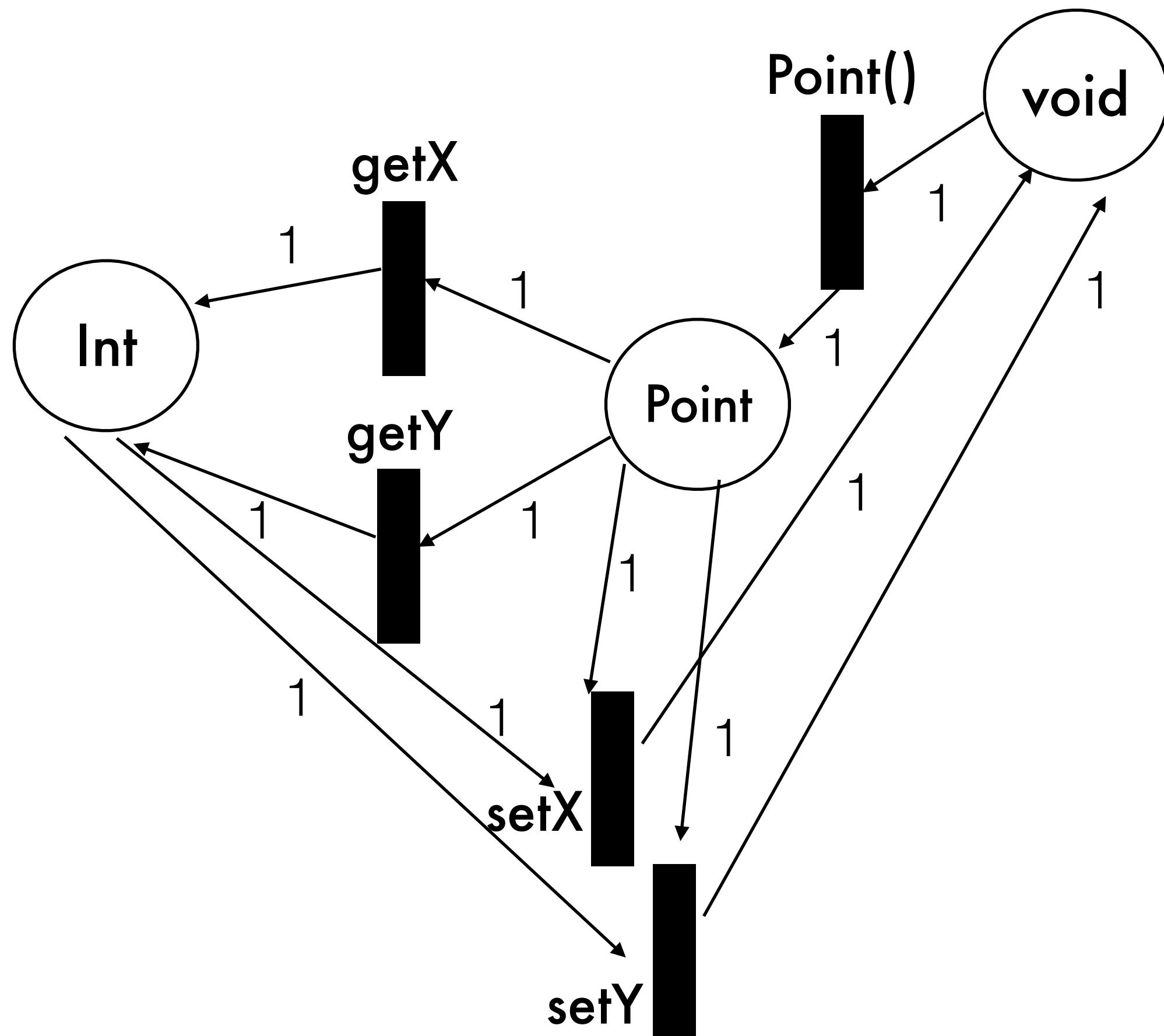
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class Point {  
    Point();  
    int getX();  
    int getY();  
    void setX(int);  
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}
```

# Exercise 1: Solution



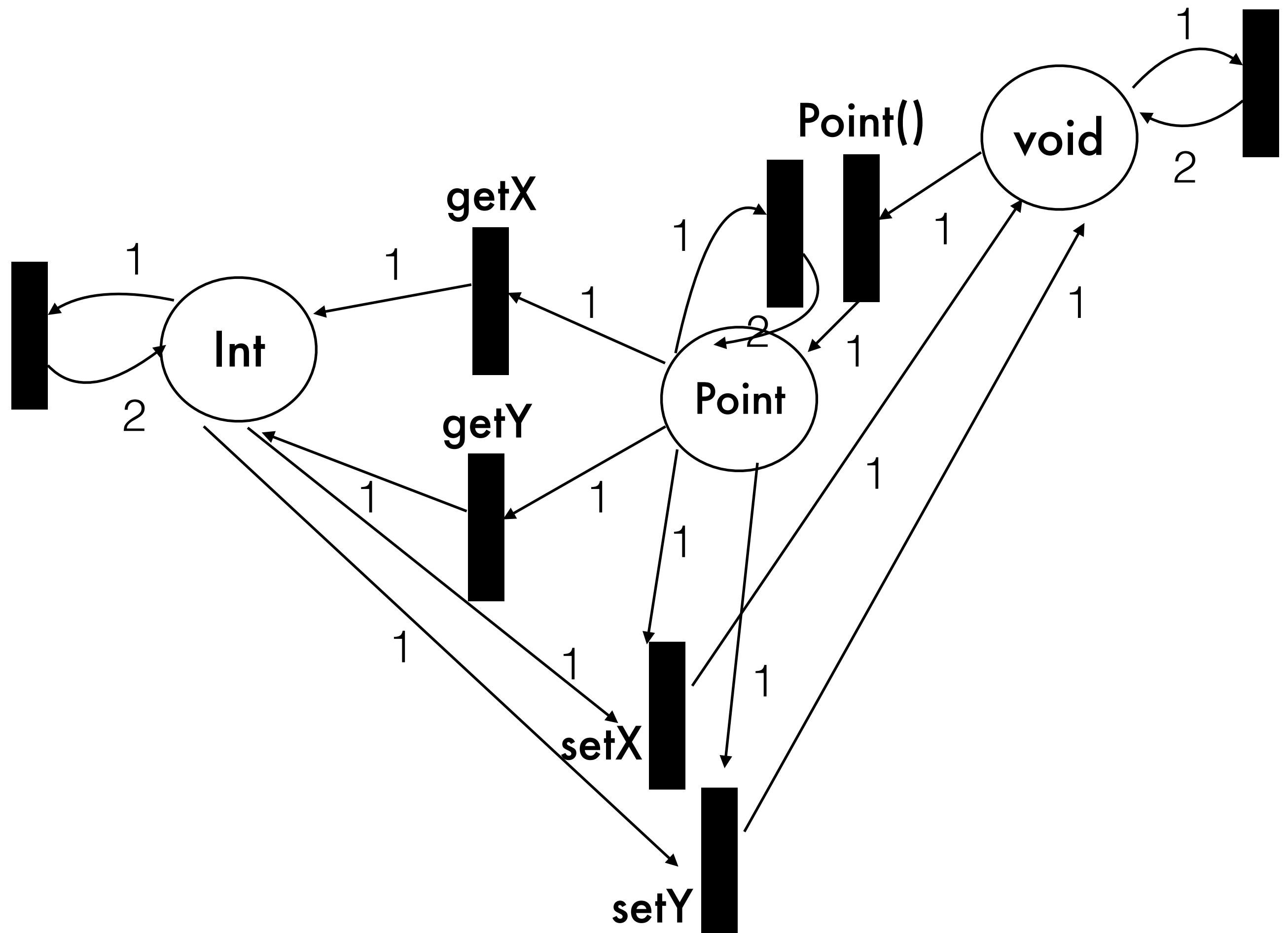
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    int getX();  
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    void setX(int);  
    void setY(int);  
}
```

# Exercise 1: Solution



```
class Point {  
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```

# Exercise 1: Solution

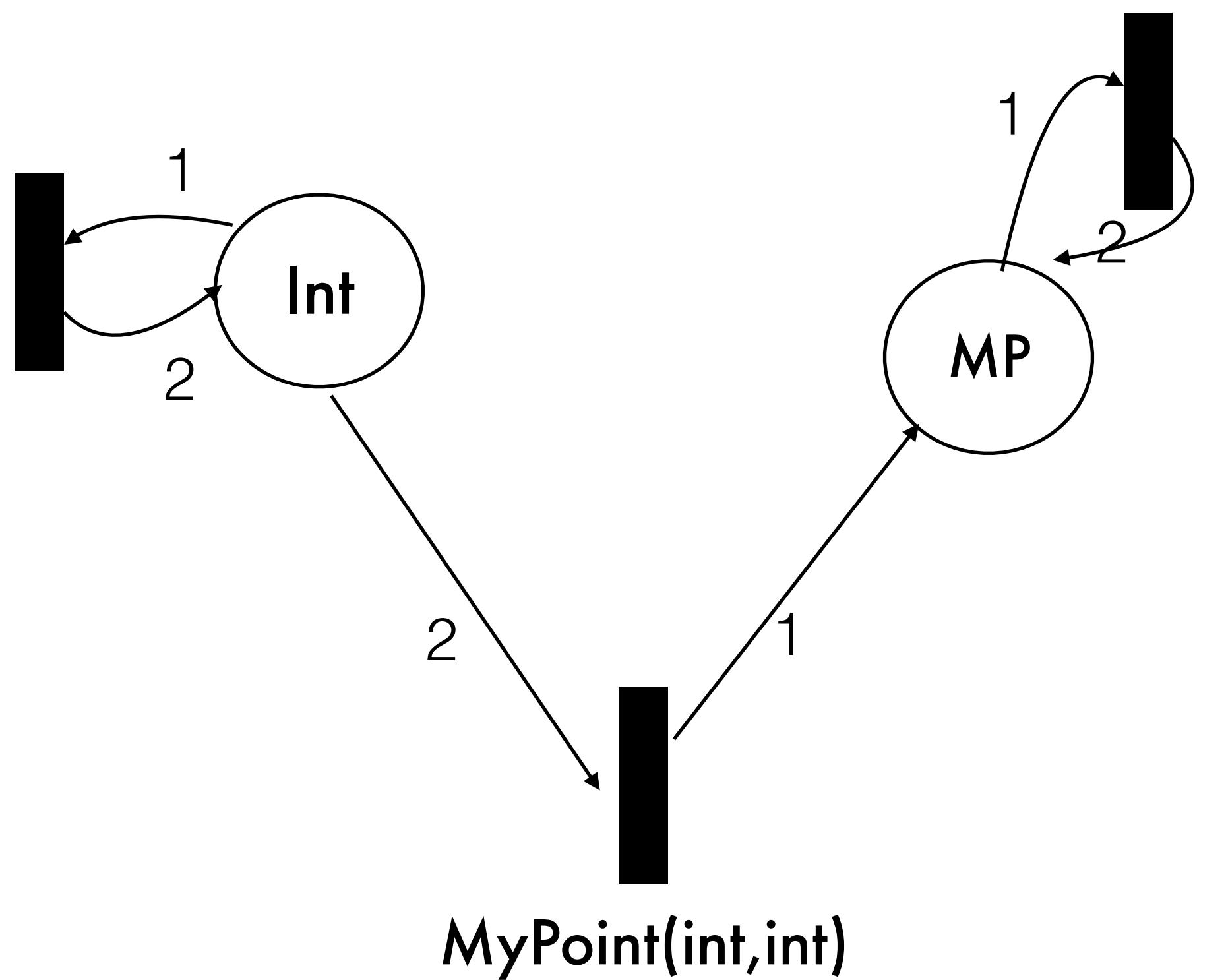


```
class Point {  
    Point();  
    int getX();  
    int getY();  
    void setX(int);  
    void setY(int);  
}
```

# Exercise 1: Solution

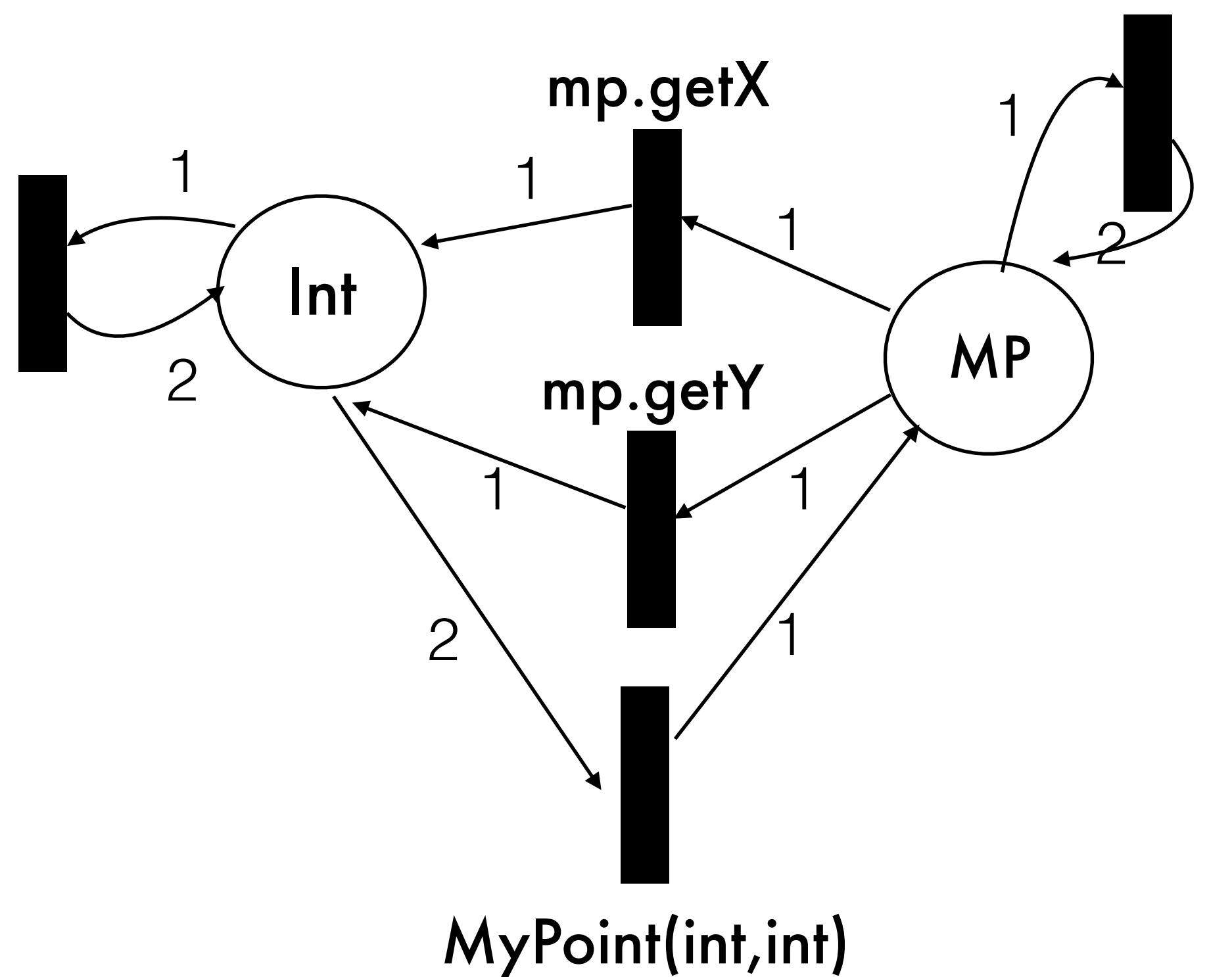
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class MyPoint {  
    MyPoint(int x, int y);  
    int getX();  
    int getY();  
}
```

# Exercise 1: Solution



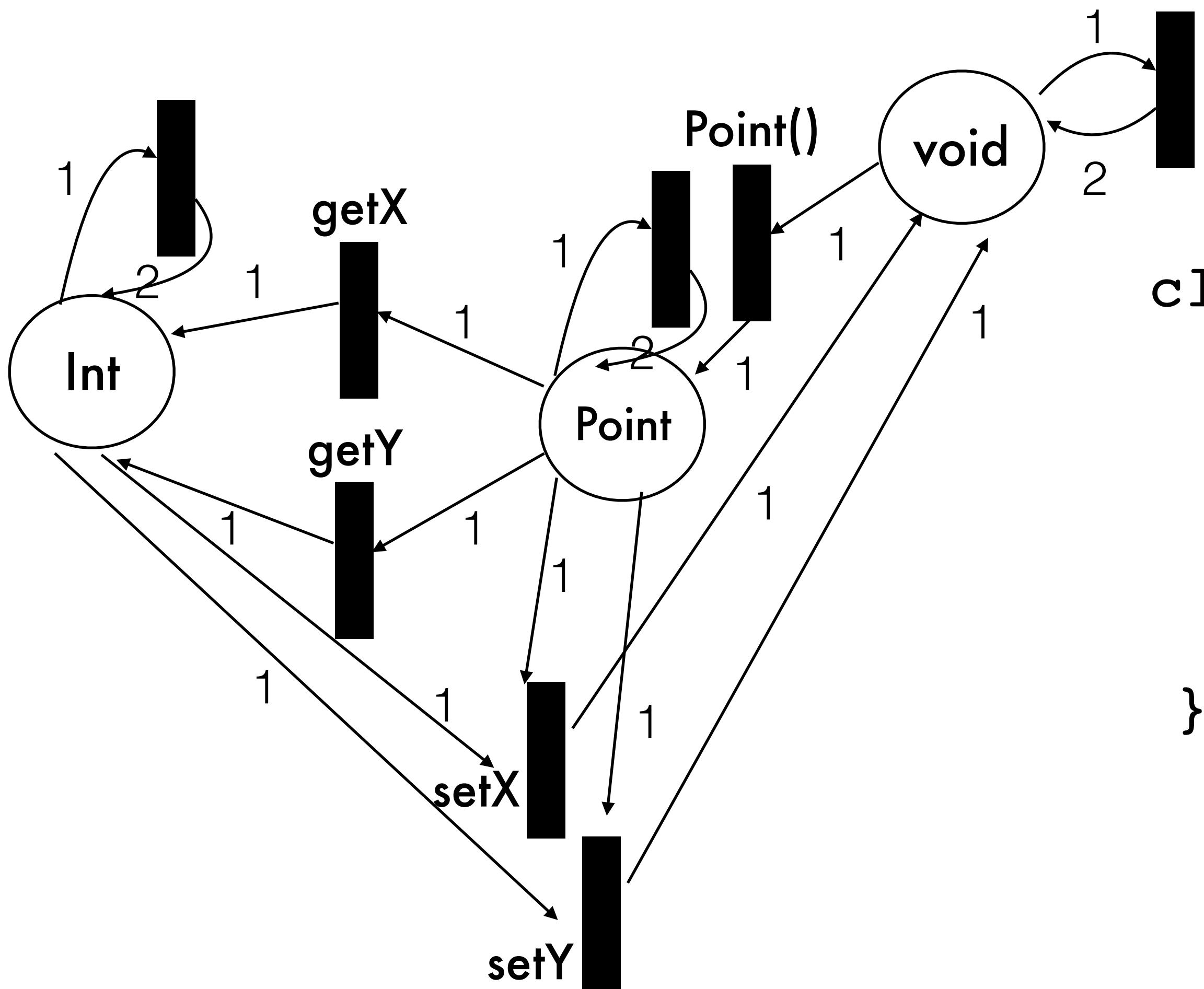
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# Exercise 1: Solution



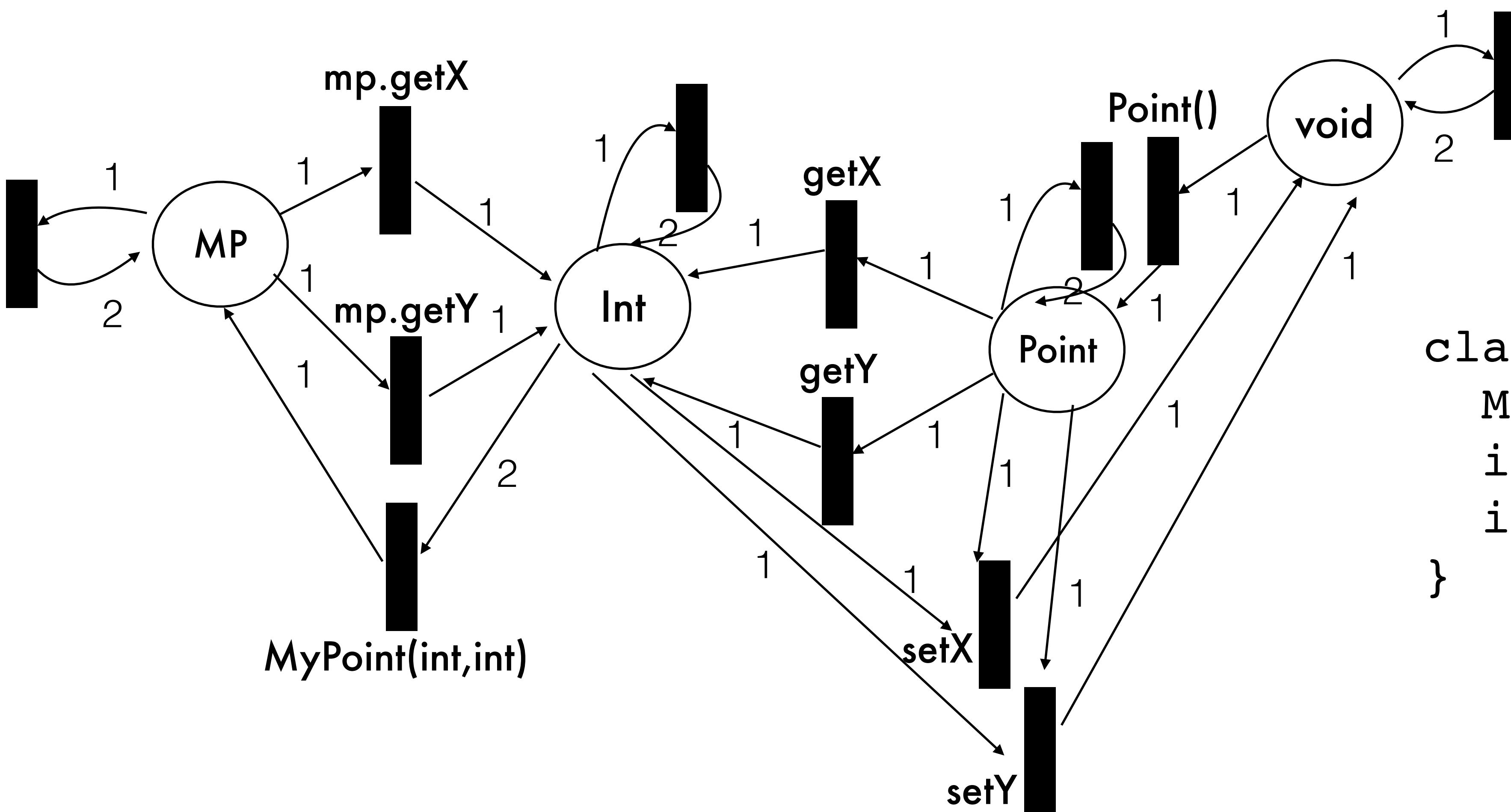
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# Exercise 1: Solution



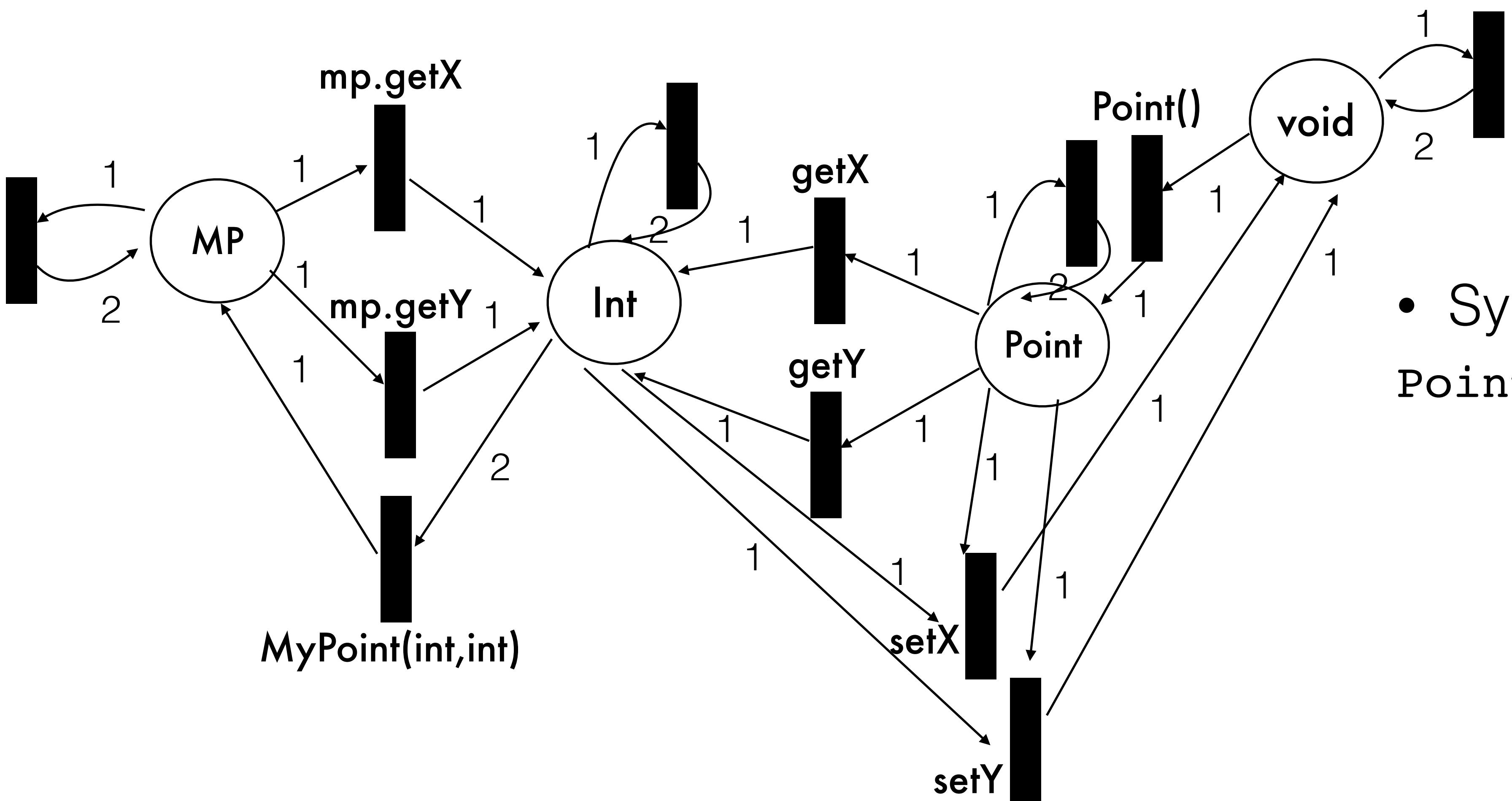
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}
```

# Exercise 1: Solution



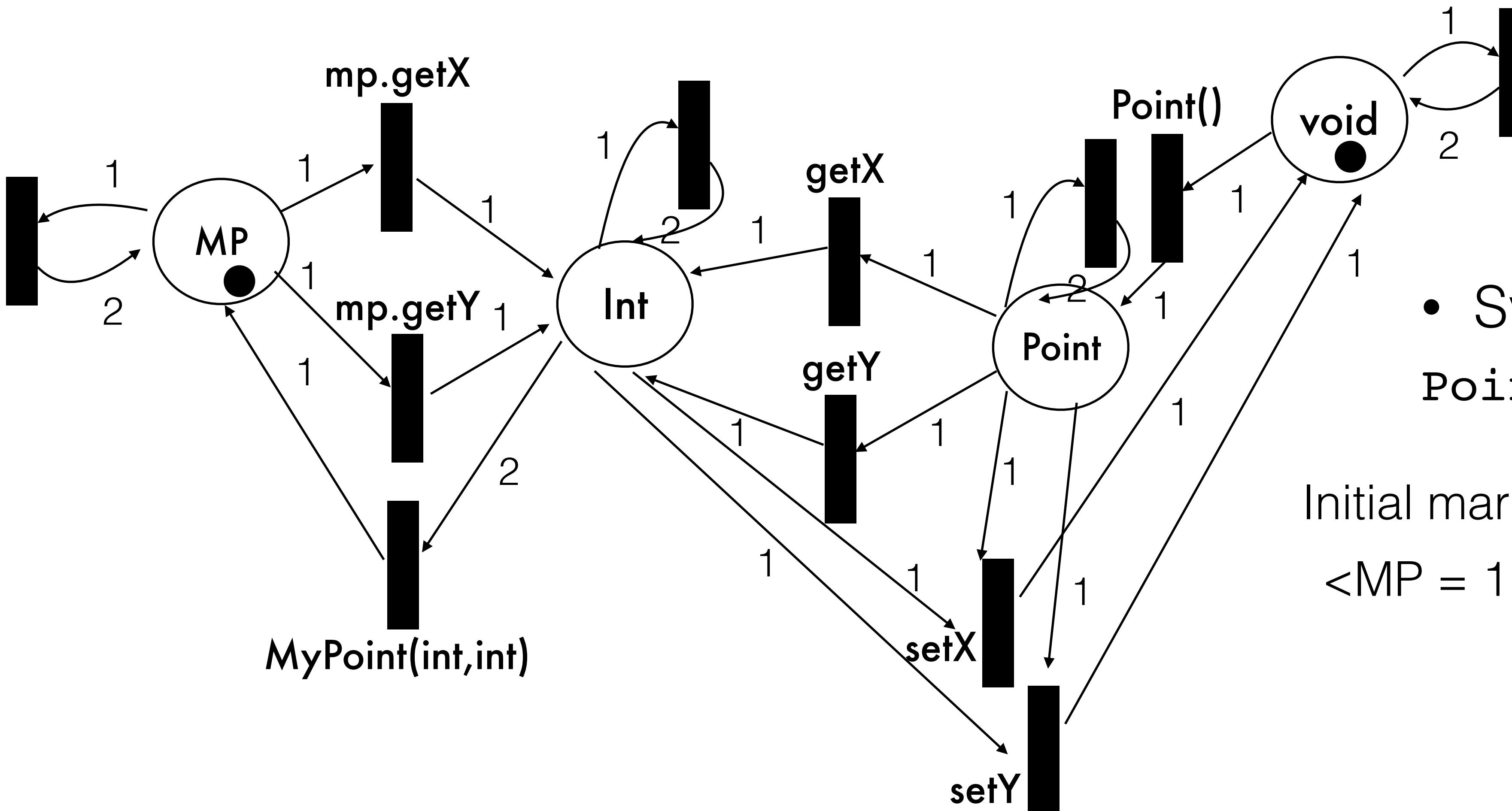
```
class MyPoint {  
    MyPoint(int x, int y);  
    int getX();  
    int getY();  
}
```

# What is the initial marking?



- Synthesize this function:  
`Point convert(Mypoint pt)`

# What is the initial marking?

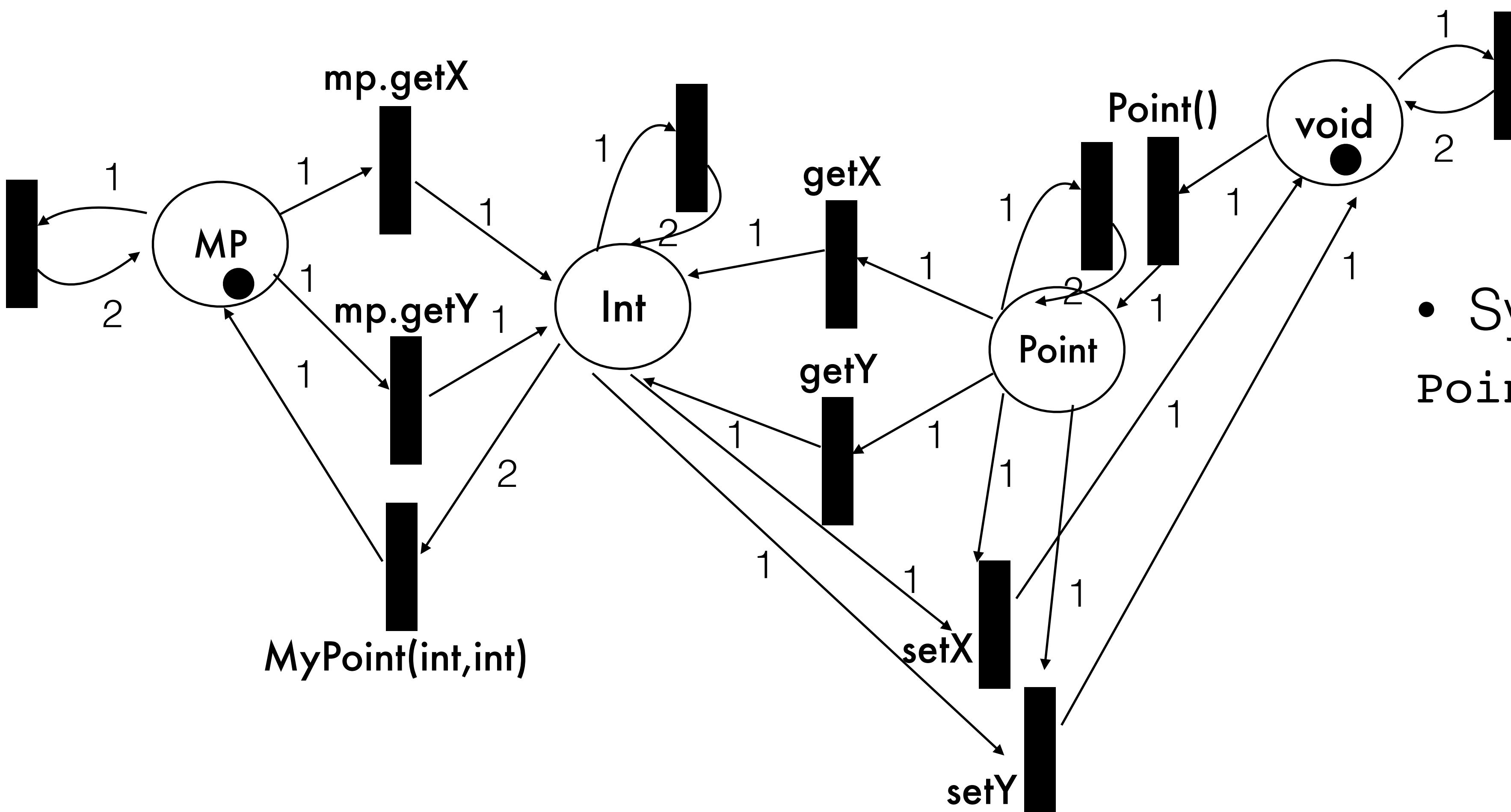


- Synthesize this function:  
**Point convert(Mypoint pt)**

Initial marking:

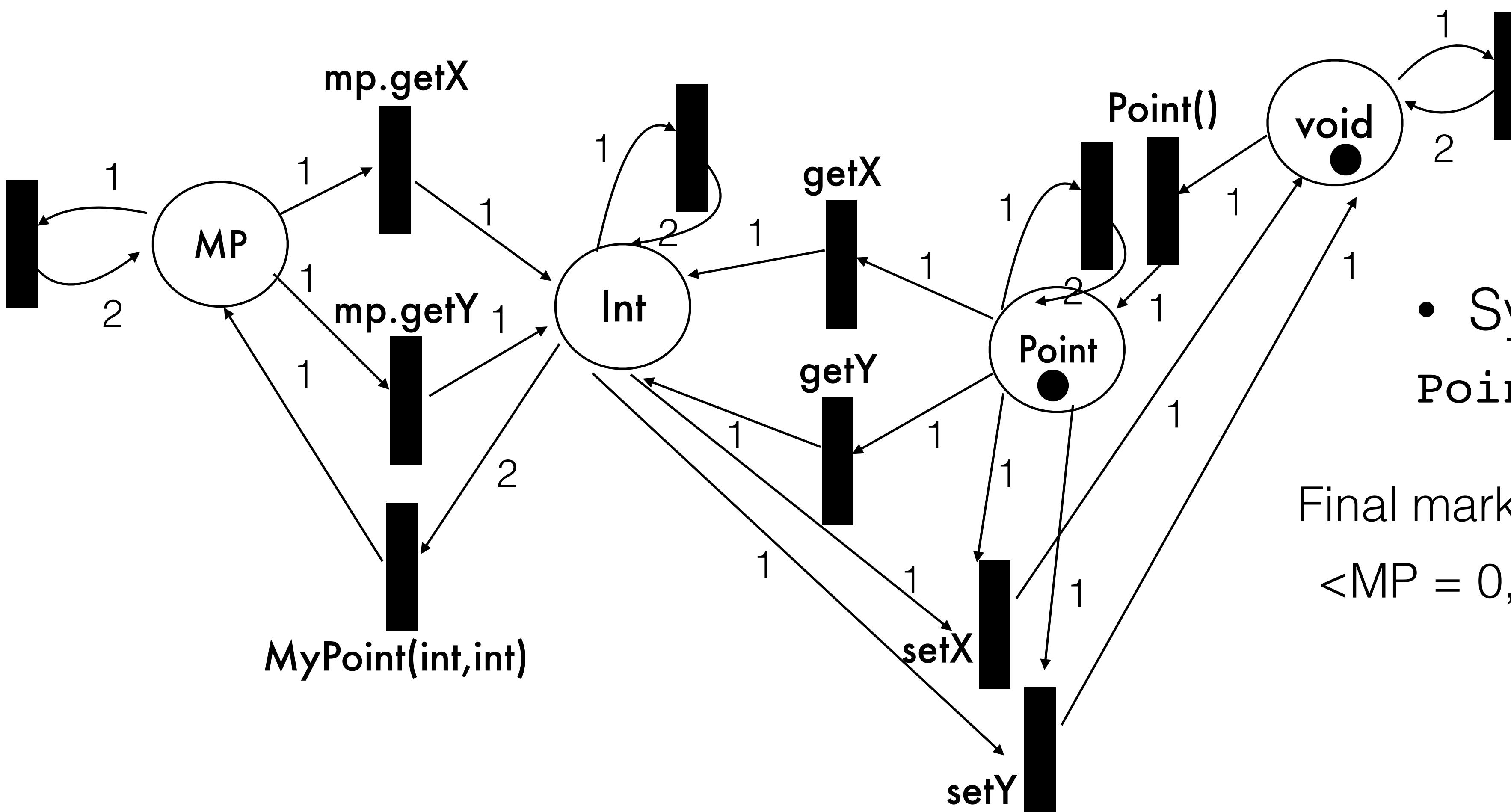
<MP = 1, void = 1, Int = 0, Point = 0>

# What is the final marking?



- Synthesize this function:  
Point convert(Mypoint pt)

# What is the final marking?

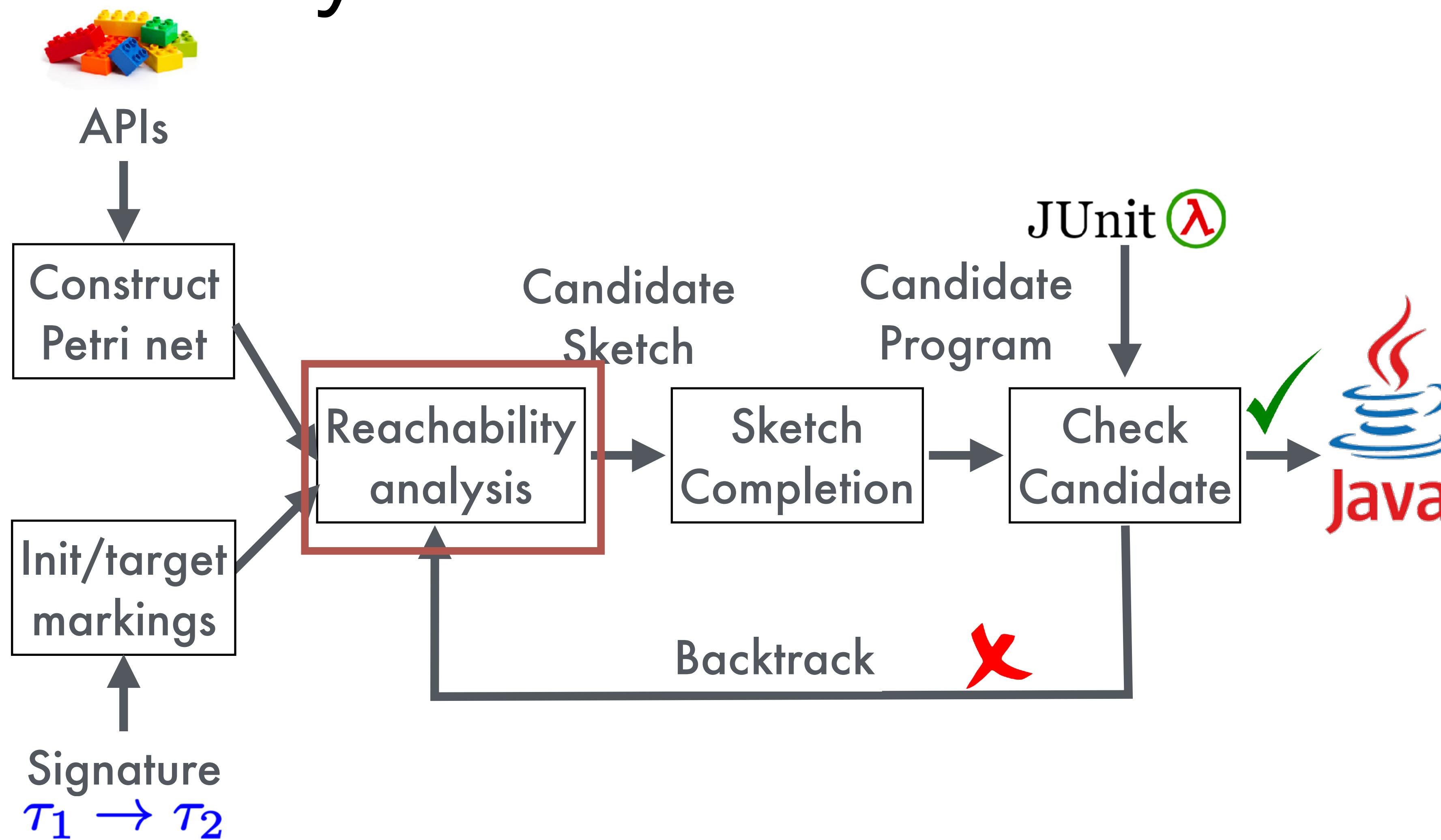


- Synthesize this function:  
**Point convert(Mypoint pt)**

Final marking:

**<MP = 0, void = \*, Int = 0, Point = 1>**

# SyPet Architecture

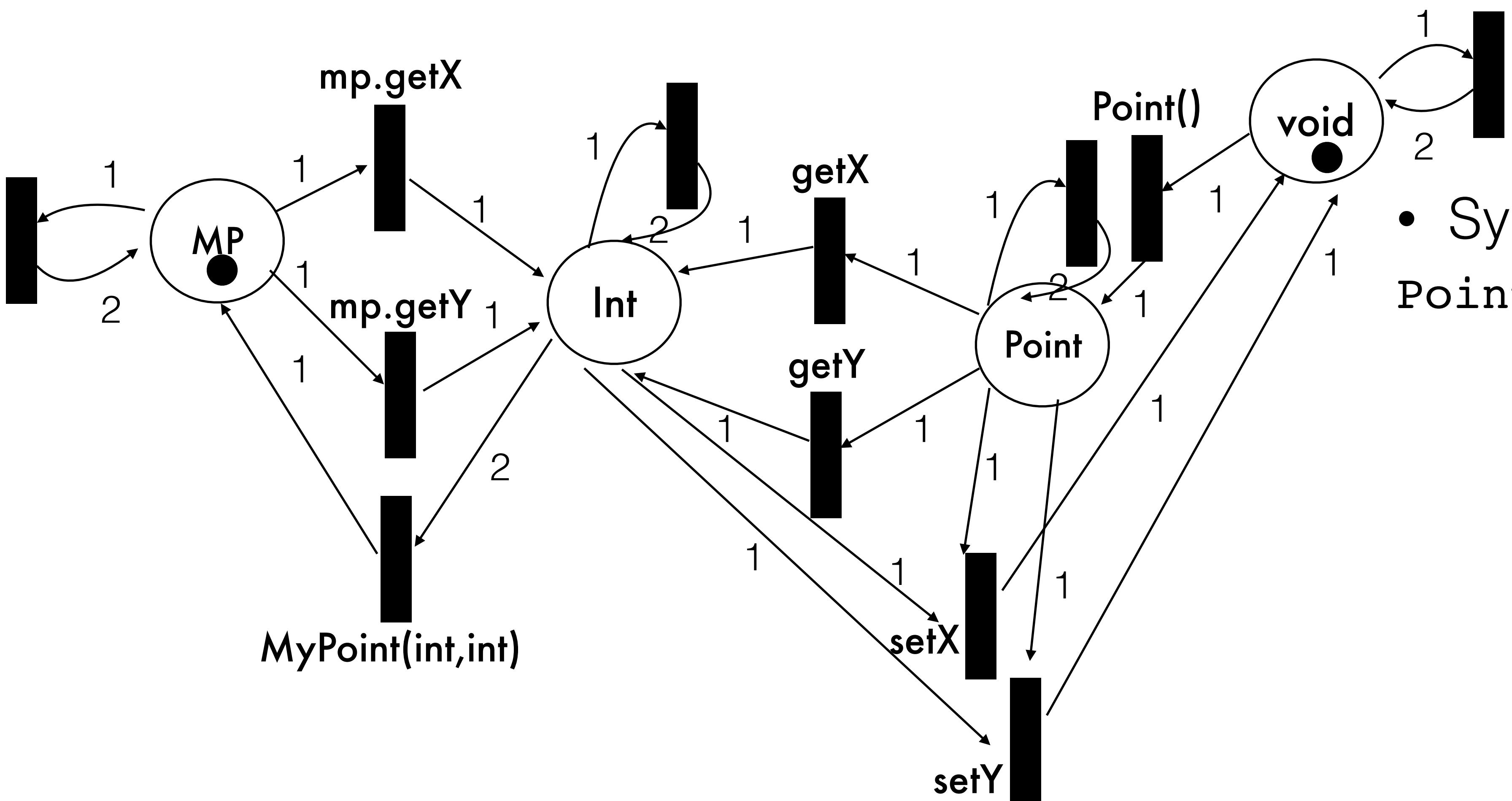


# Reachability analysis

All accepting runs of Petri net correspond to method call sequences with desired type signature!

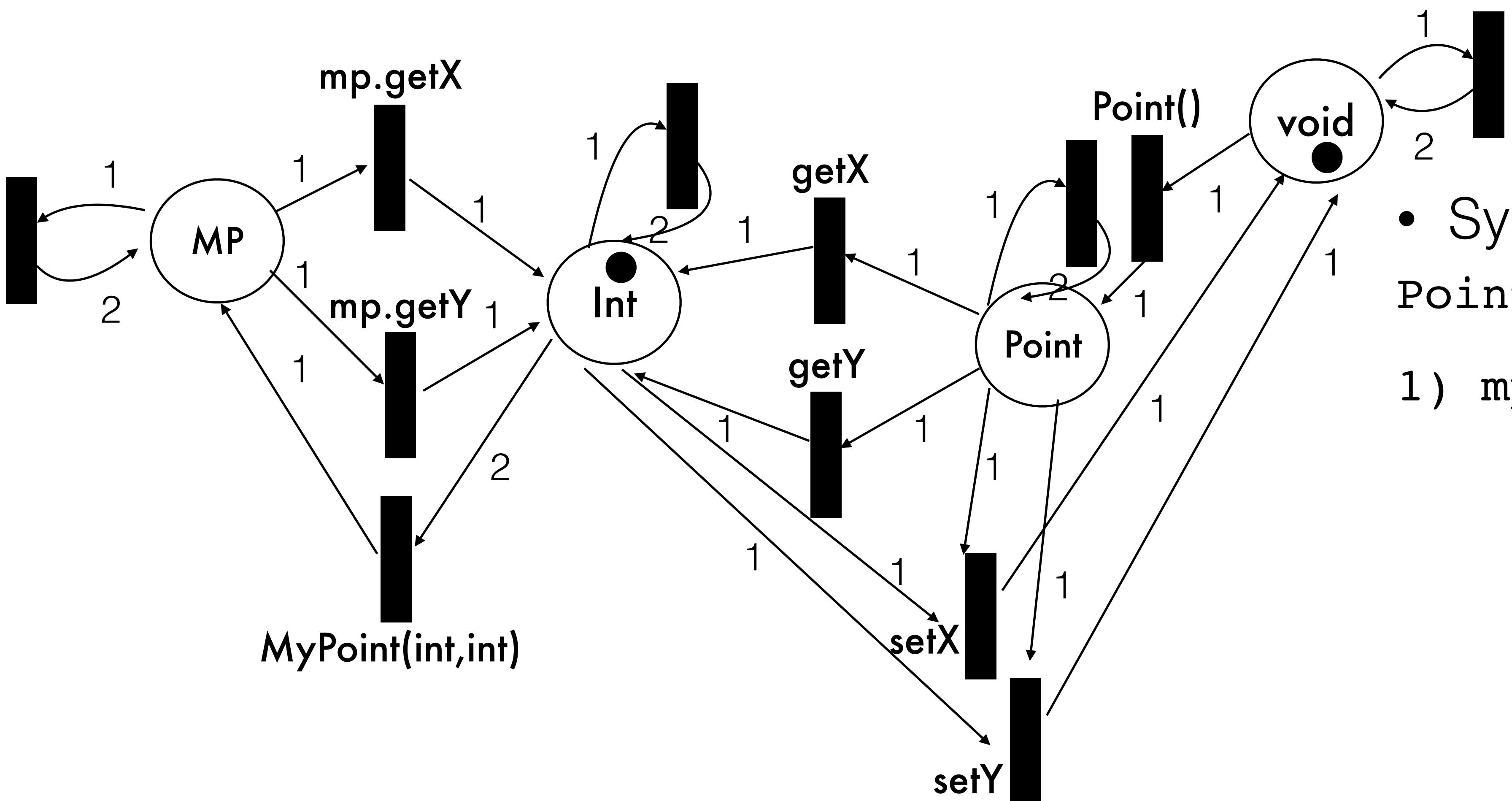
- Need to perform reachability analysis to identify accepting runs of the Petri Net
- Our solution reduces bounded reachability analysis to a SAT problem:
  - Find a reachable path of size  $k$
  - Enumerate all reachable paths

# Exercise 2: Reachable paths



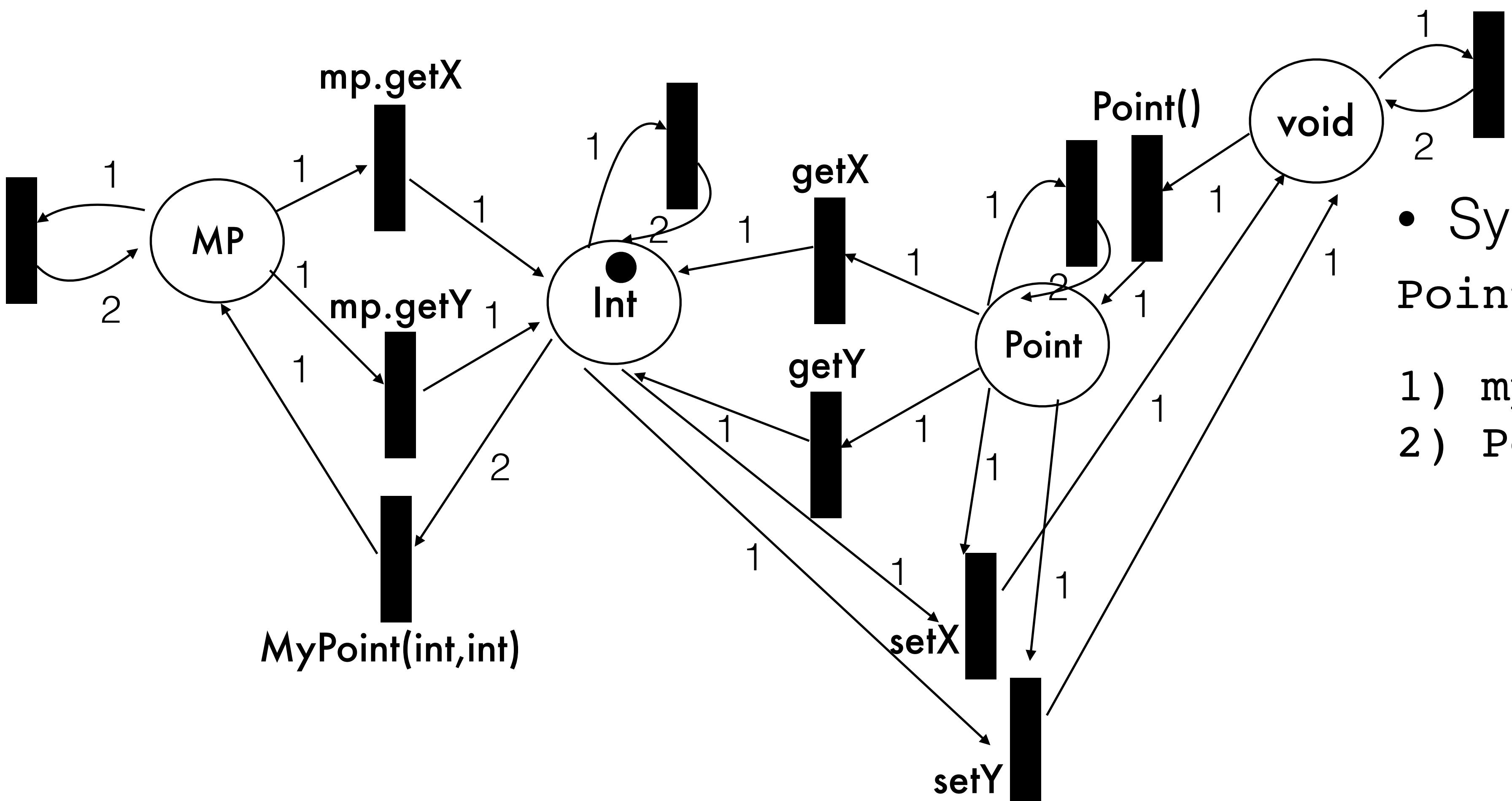
- Synthesize this function:  
`Point convert(Mypoint pt)`

# Exercise 2: Reachable paths



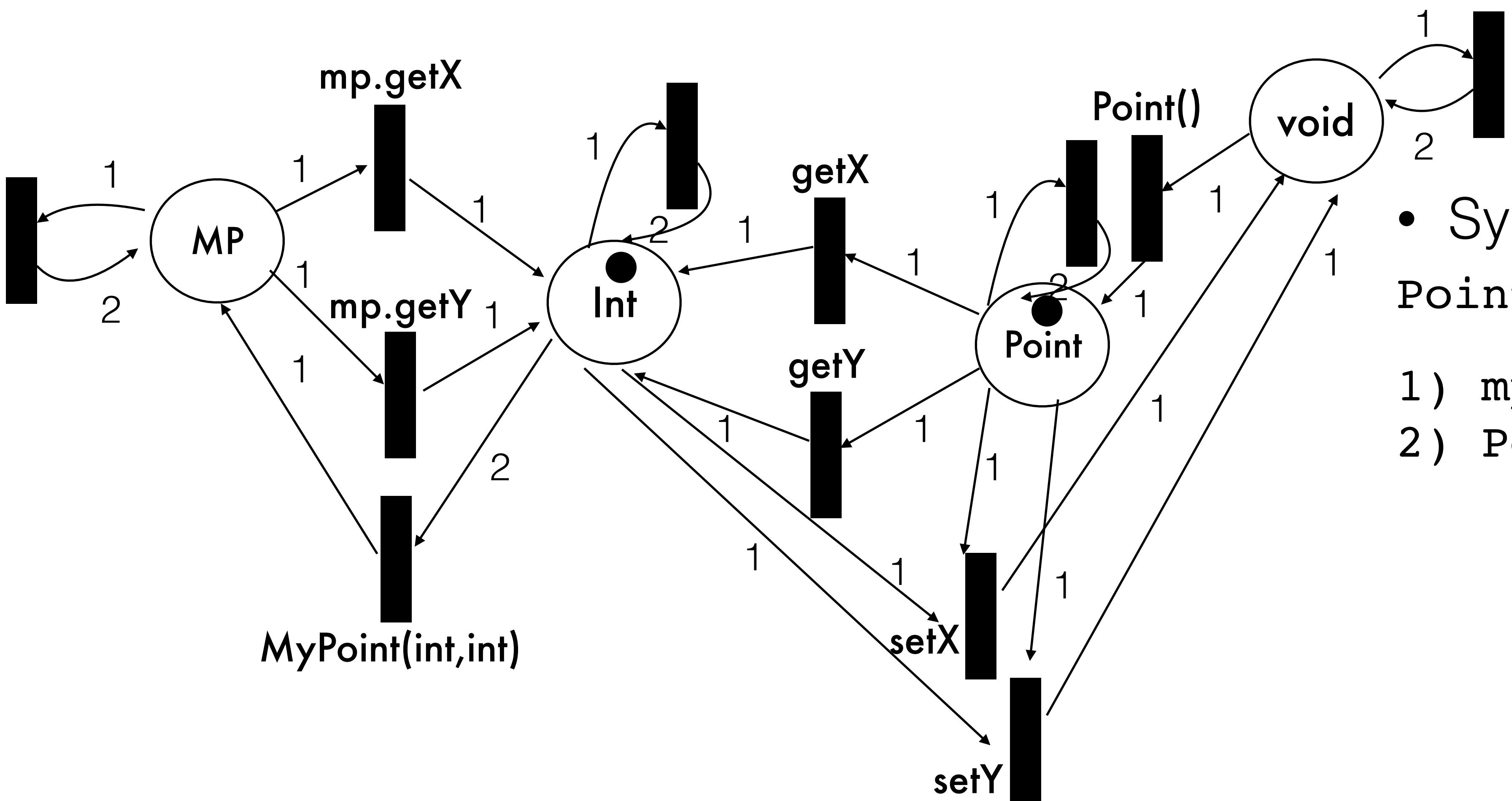
- Synthesize this function:  
`Point convert(Mypoint pt)`
- 1) `mp.getX`

# Exercise 2: Reachable paths



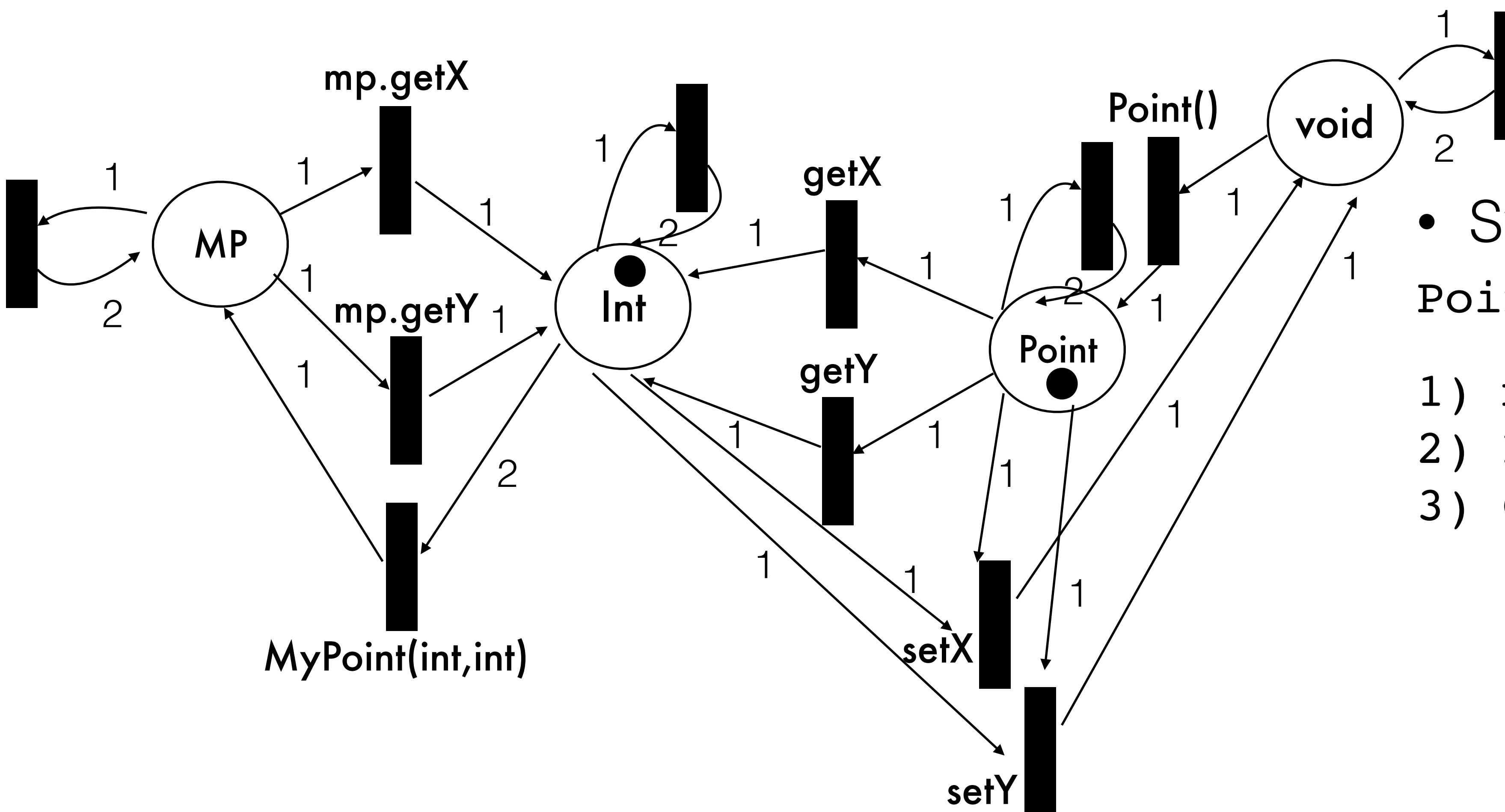
- Synthesize this function:  
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- 1) `mp.getX`
- 2) `Point()`

# Exercise 2: Reachable paths



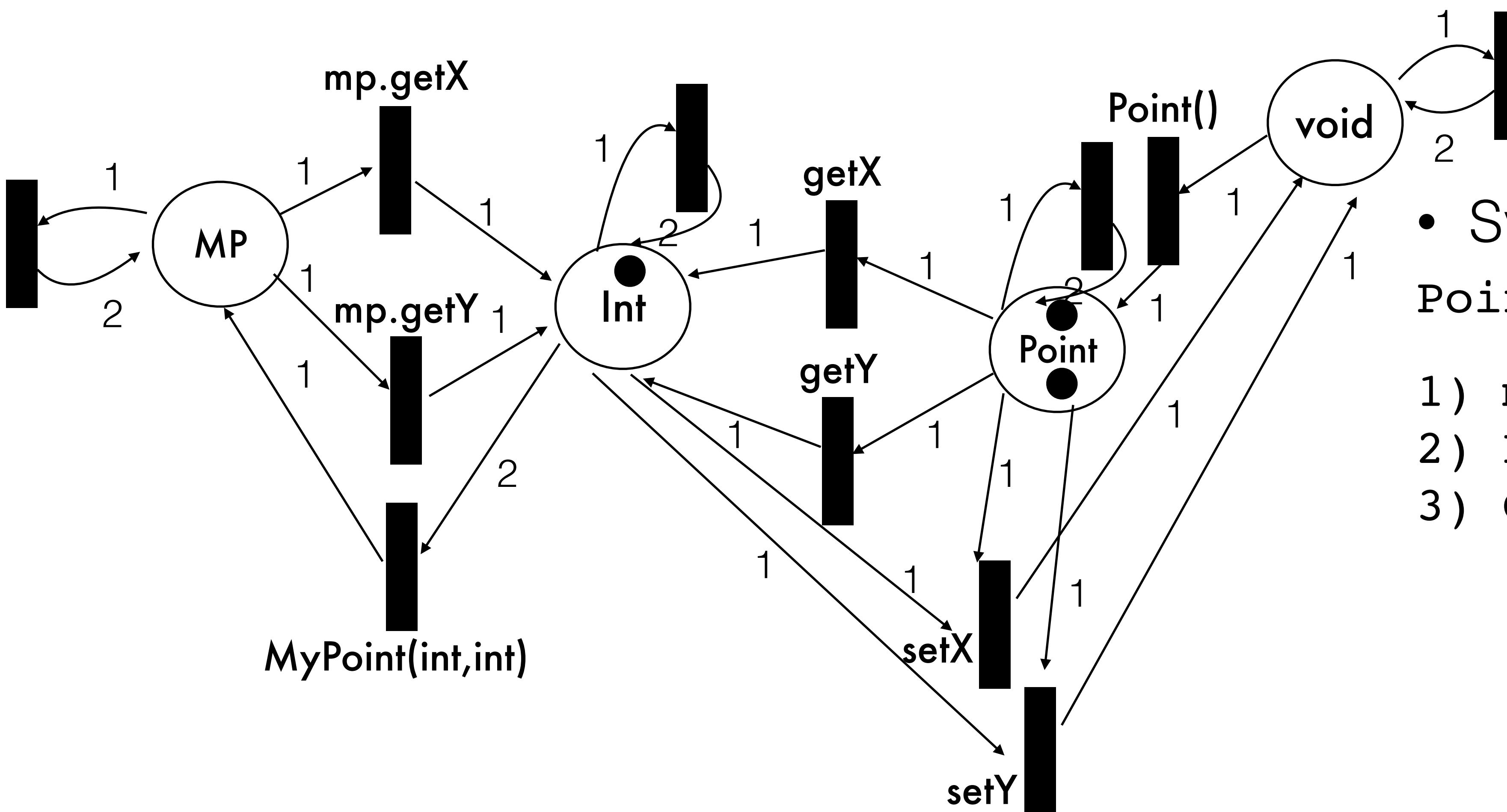
- Synthesize this function:  
**Point convert(Mypoint pt)**
  - 1) **mp.getX**
  - 2) **Point()**

# Exercise 2: Reachable paths



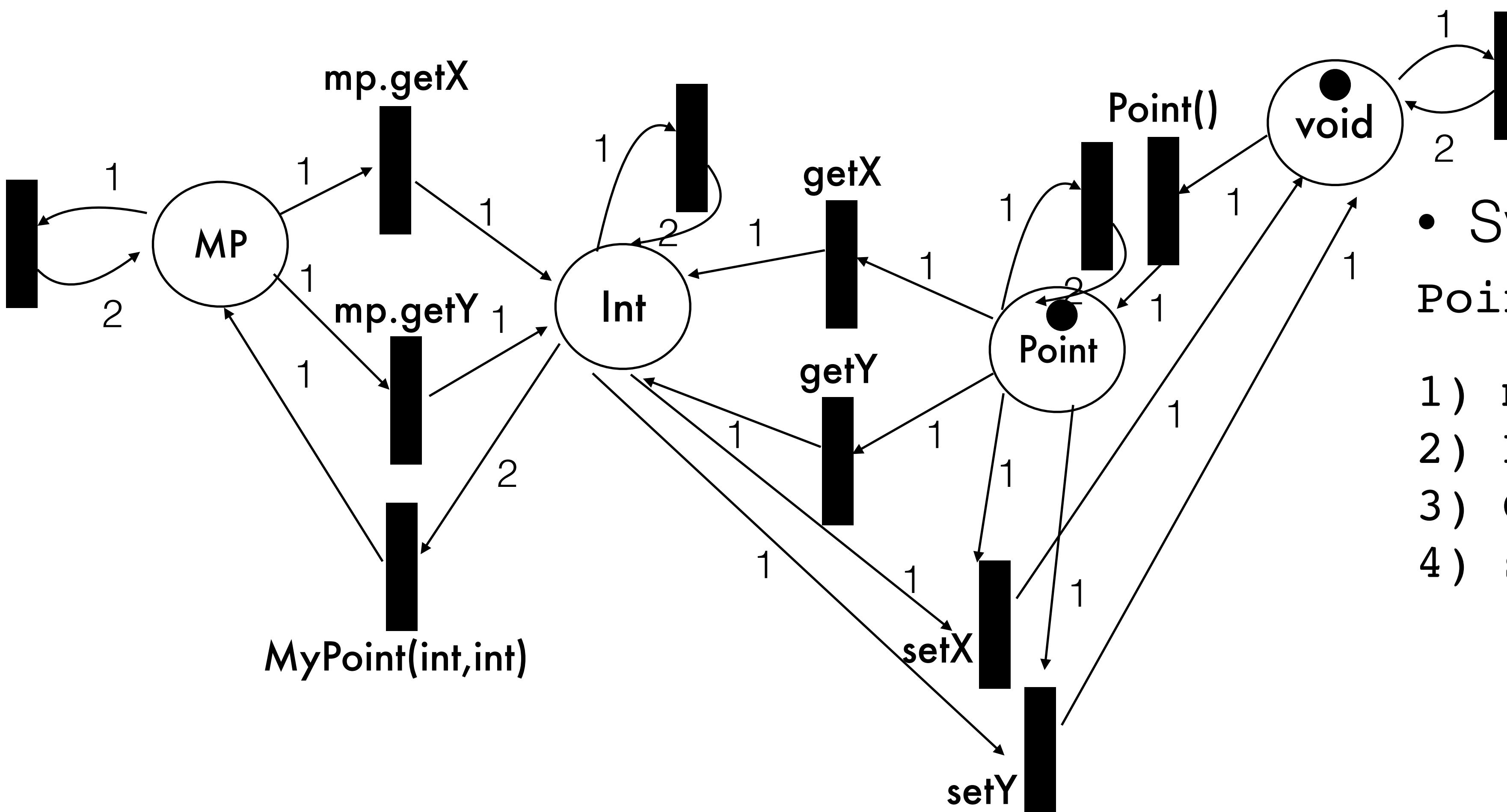
- Synthesize this function:  
`Point convert(Mypoint pt)`
- 1) `mp.getX`
- 2) `Point()`
- 3) `Clone-Point`

# Exercise 2: Reachable paths



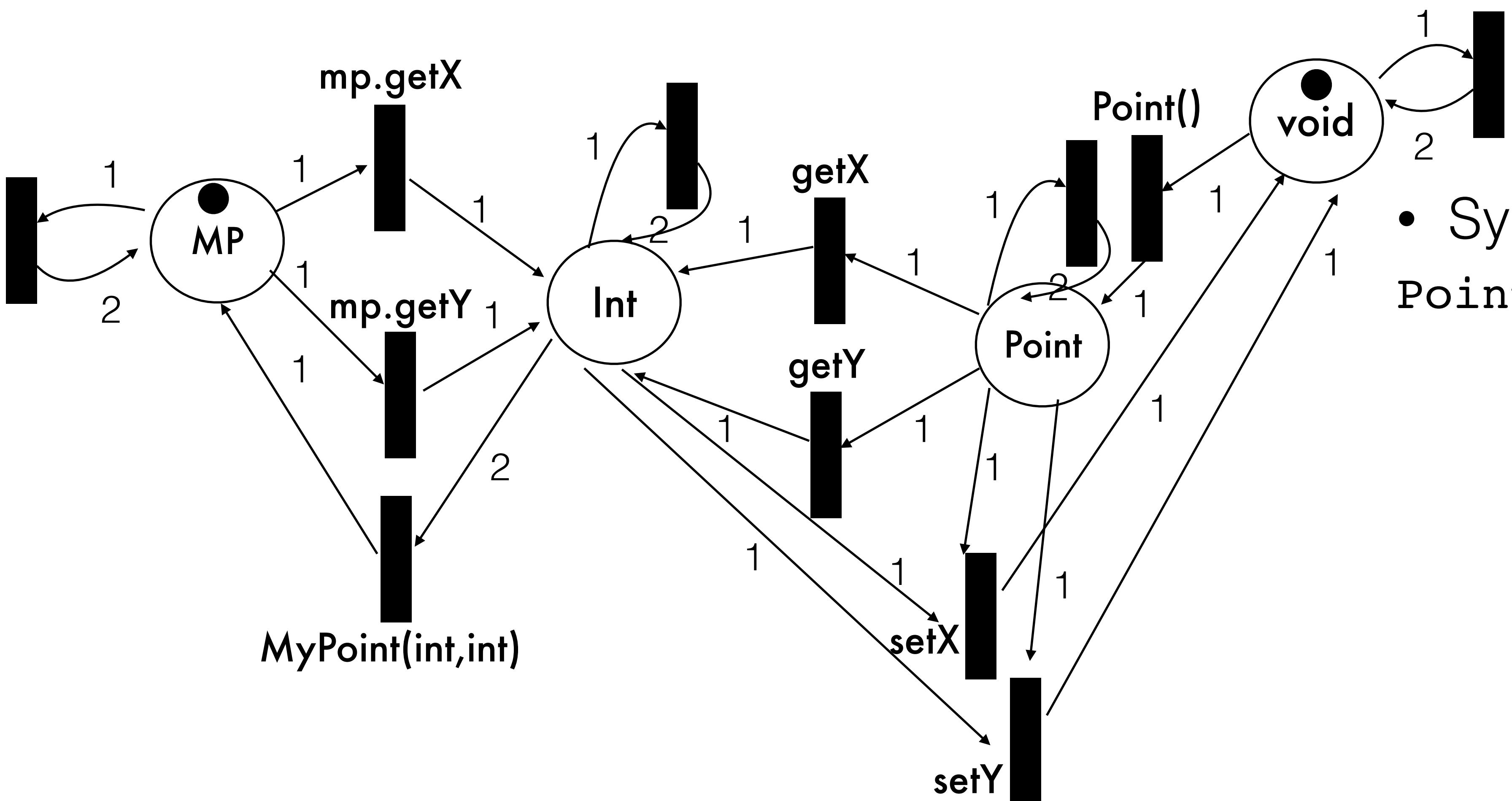
- Synthesize this function:  
Point convert(Mypoint pt)
  - 1) mp.getX
  - 2) Point()
  - 3) Clone-Point

# Exercise 2: Reachable paths



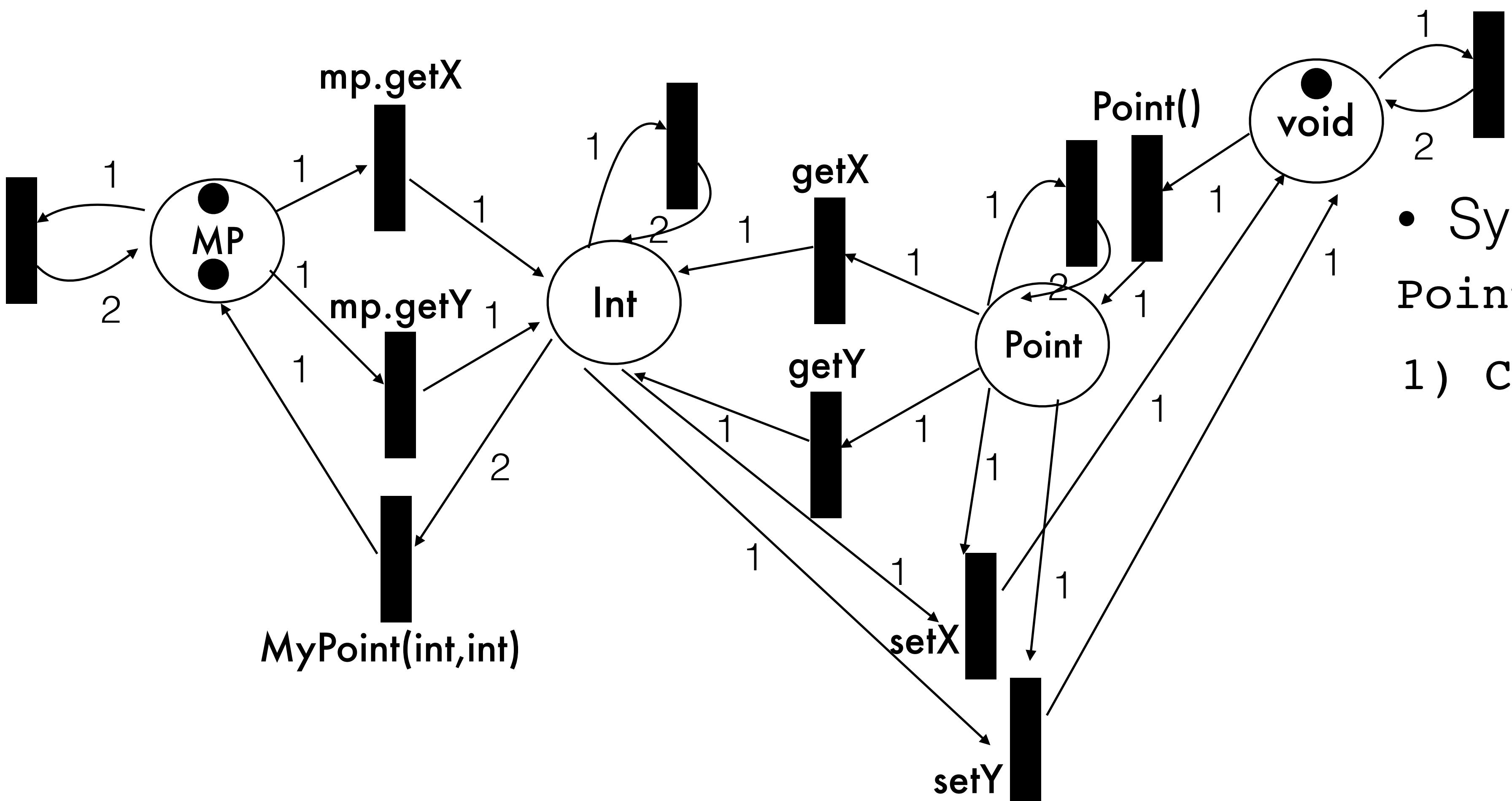
- Synthesize this function:  
`Point convert(Mypoint pt)`
- 1) `mp.getX`
  - 2) `Point()`
  - 3) `Clone-Point`
  - 4) `setX`

# Exercise 2: Reachable paths



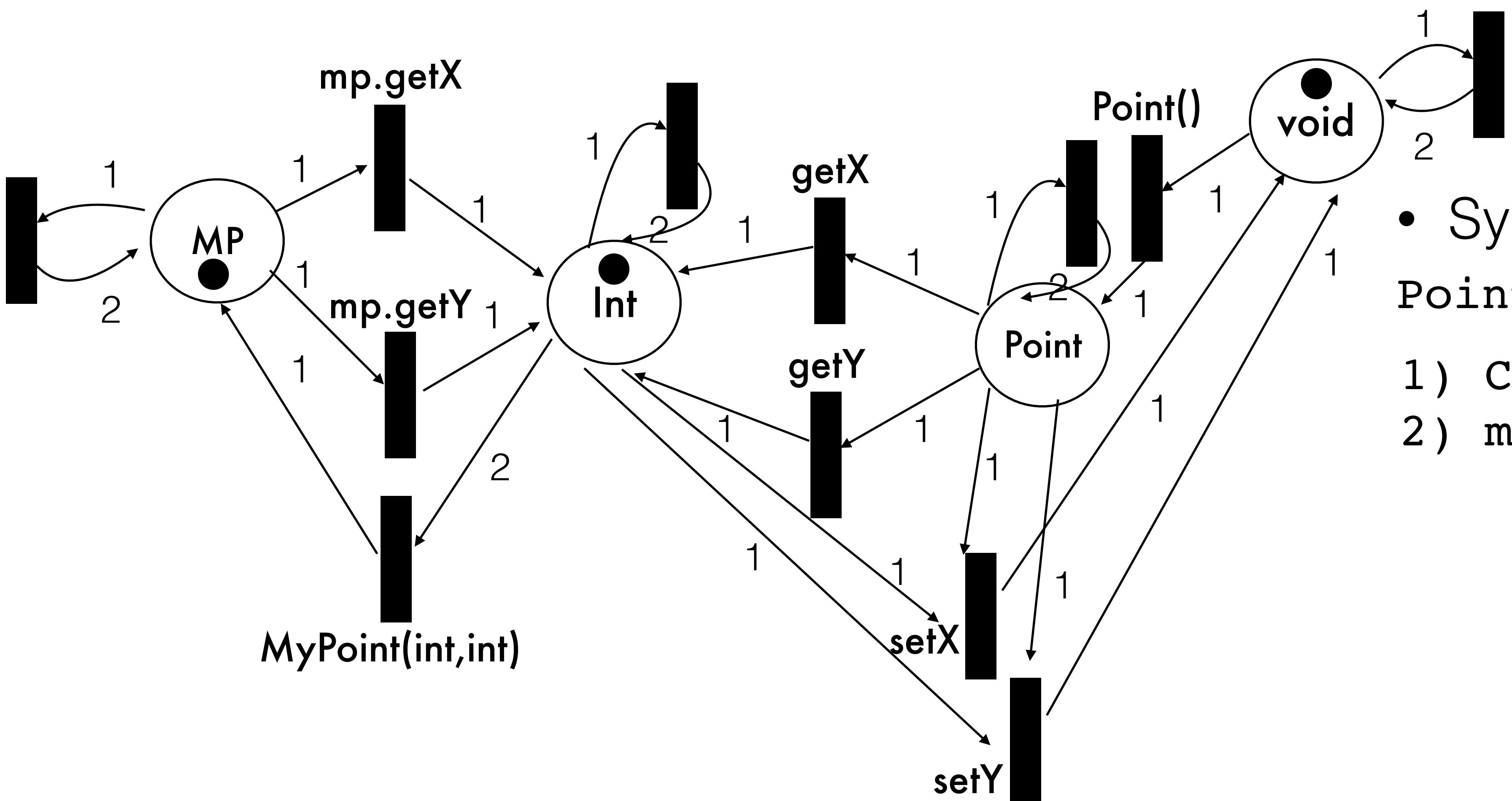
- Synthesize this function:  
`Point convert(Mypoint pt)`

# Exercise 2: Reachable paths



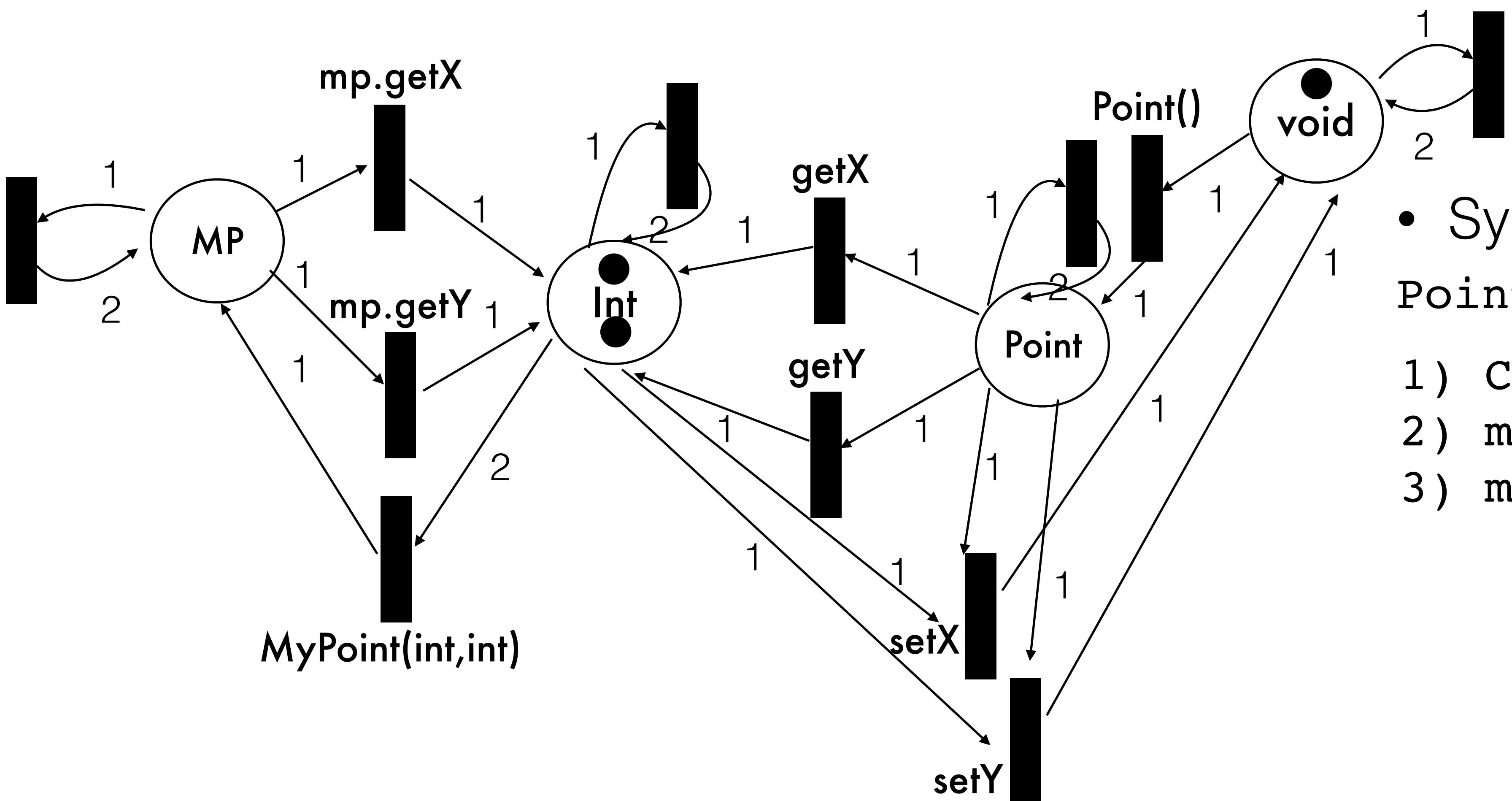
- Synthesize this function:  
Point convert(Mypoint pt)
  - 1) Clone-MP

# Exercise 2: Reachable paths



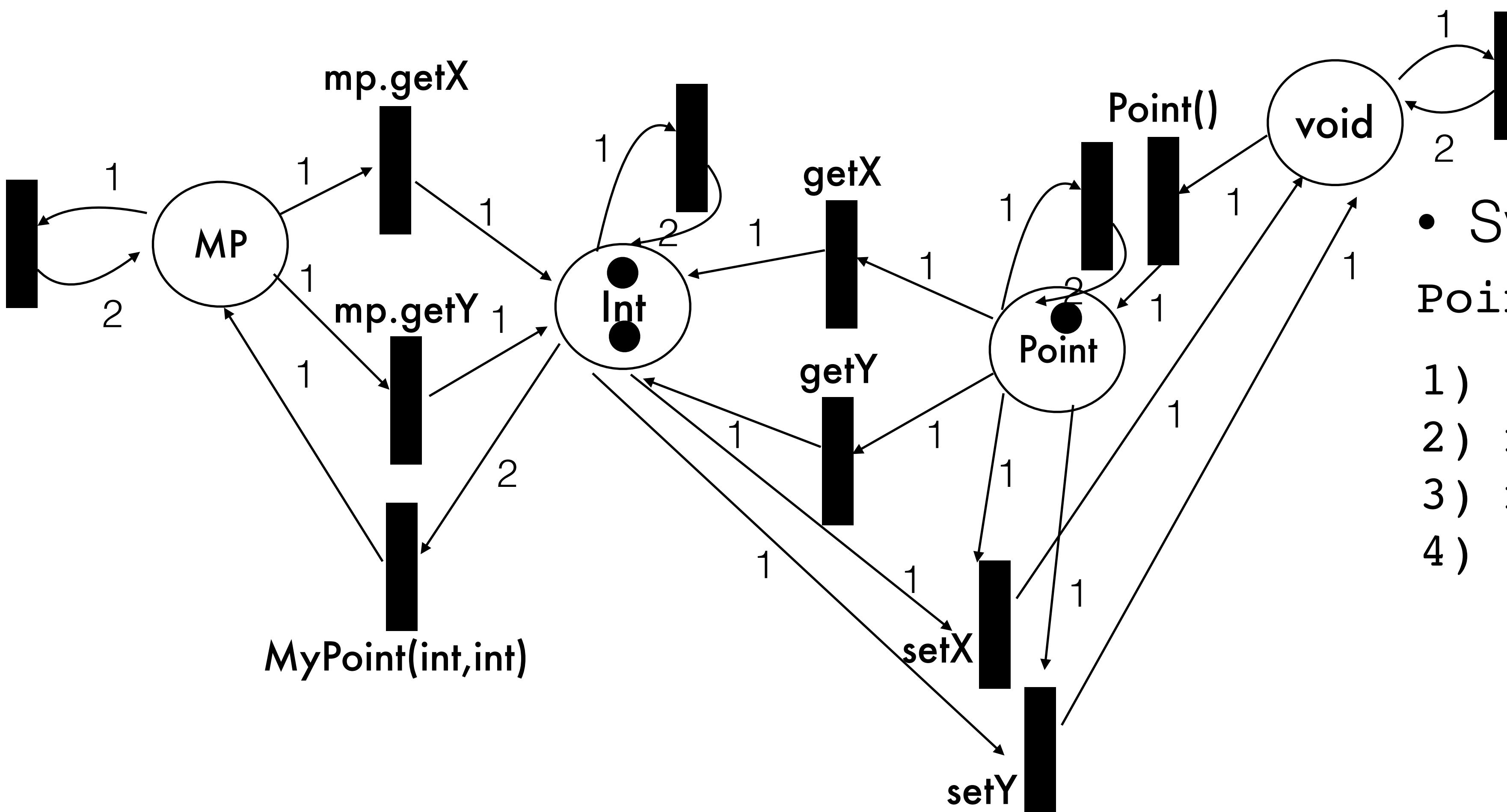
- Synthesize this function:  
`Point convert(Mypoint pt)`
- 1) Clone-MP
- 2) mp.getX

# Exercise 2: Reachable paths



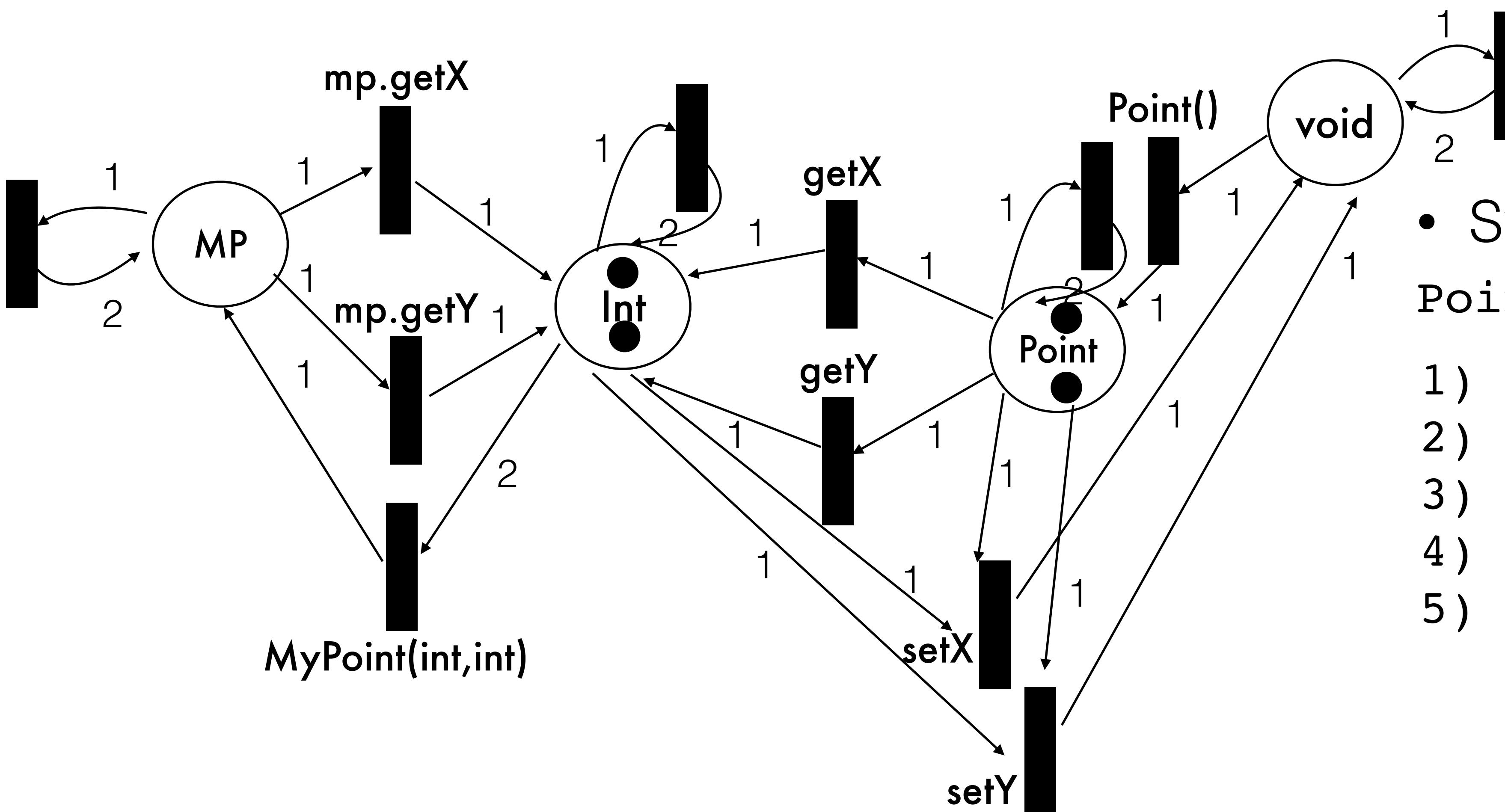
- Synthesize this function:  
`Point convert(Mypoint pt)`
- 1) Clone-MP
- 2) mp.getX
- 3) mp.getY

# Exercise 2: Reachable paths



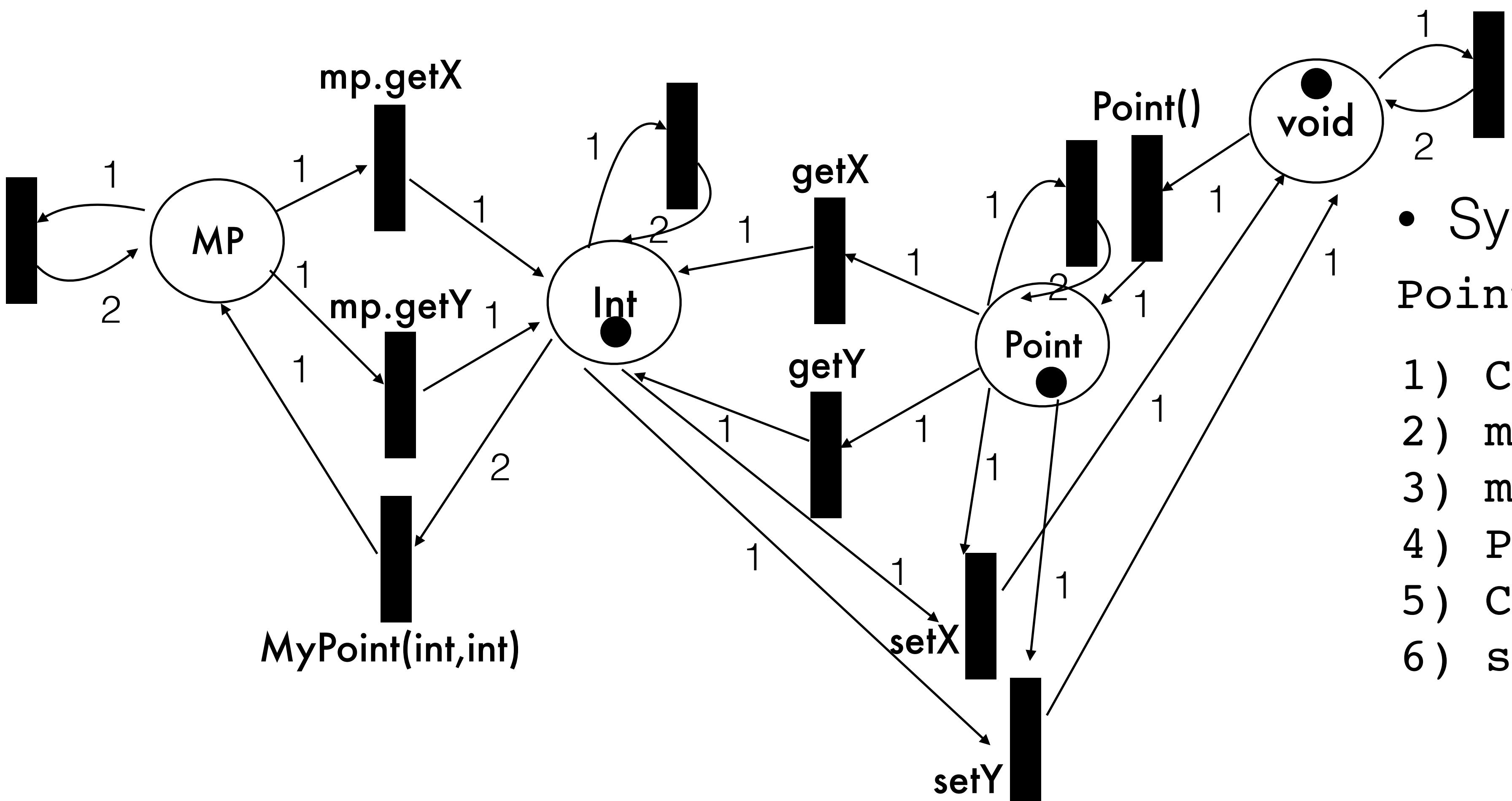
- Synthesize this function:  
`Point convert(Mypoint pt)`
- 1) Clone-MP
- 2) mp.getX
- 3) mp.getY
- 4) Point()

# Exercise 2: Reachable paths



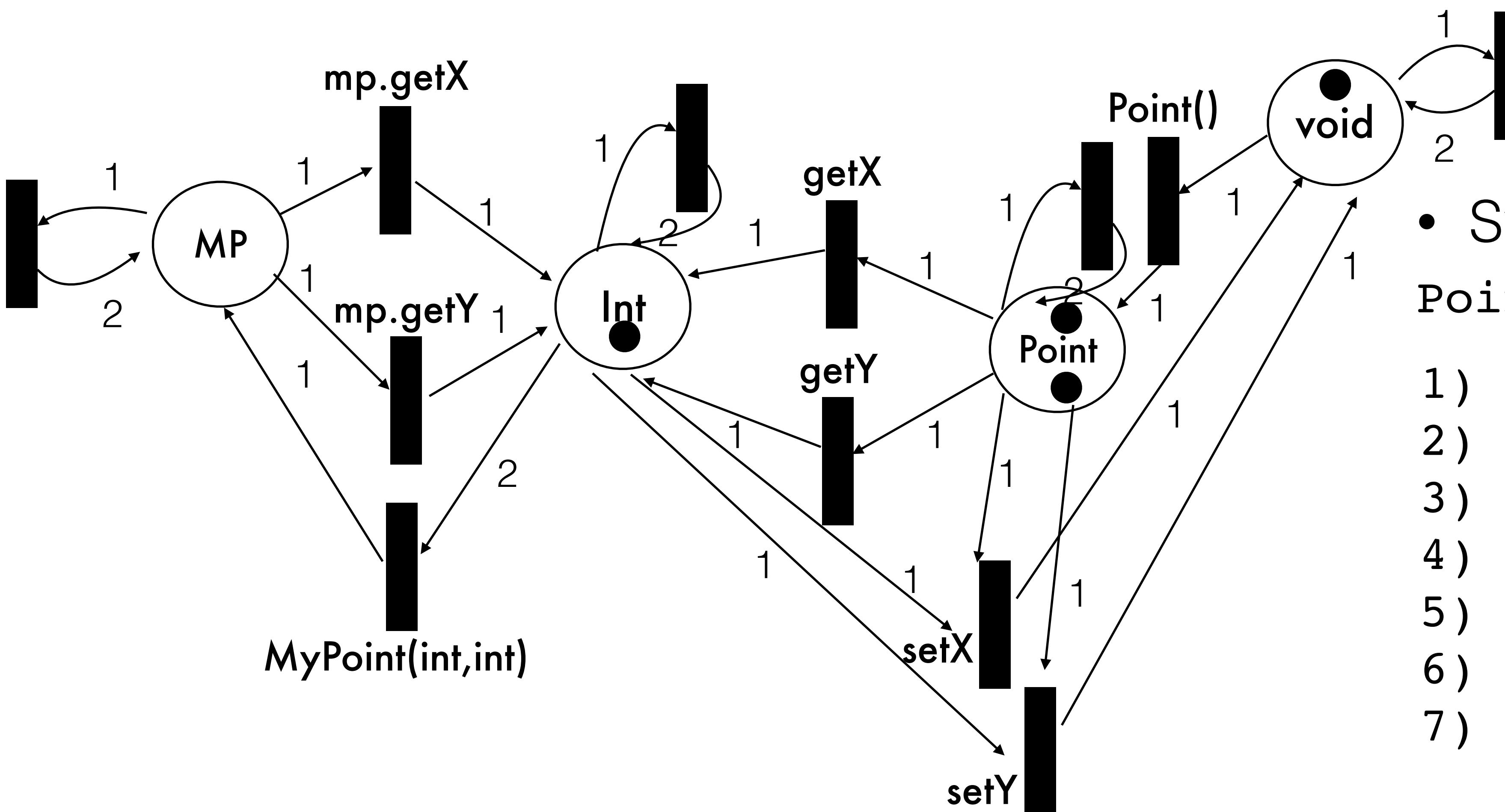
- Synthesize this function:  
**Point convert(Mypoint pt)**
- 1) Clone-MP
- 2) mp.getX
- 3) mp.getY
- 4) Point()
- 5) Clone-Point

# Exercise 2: Reachable paths



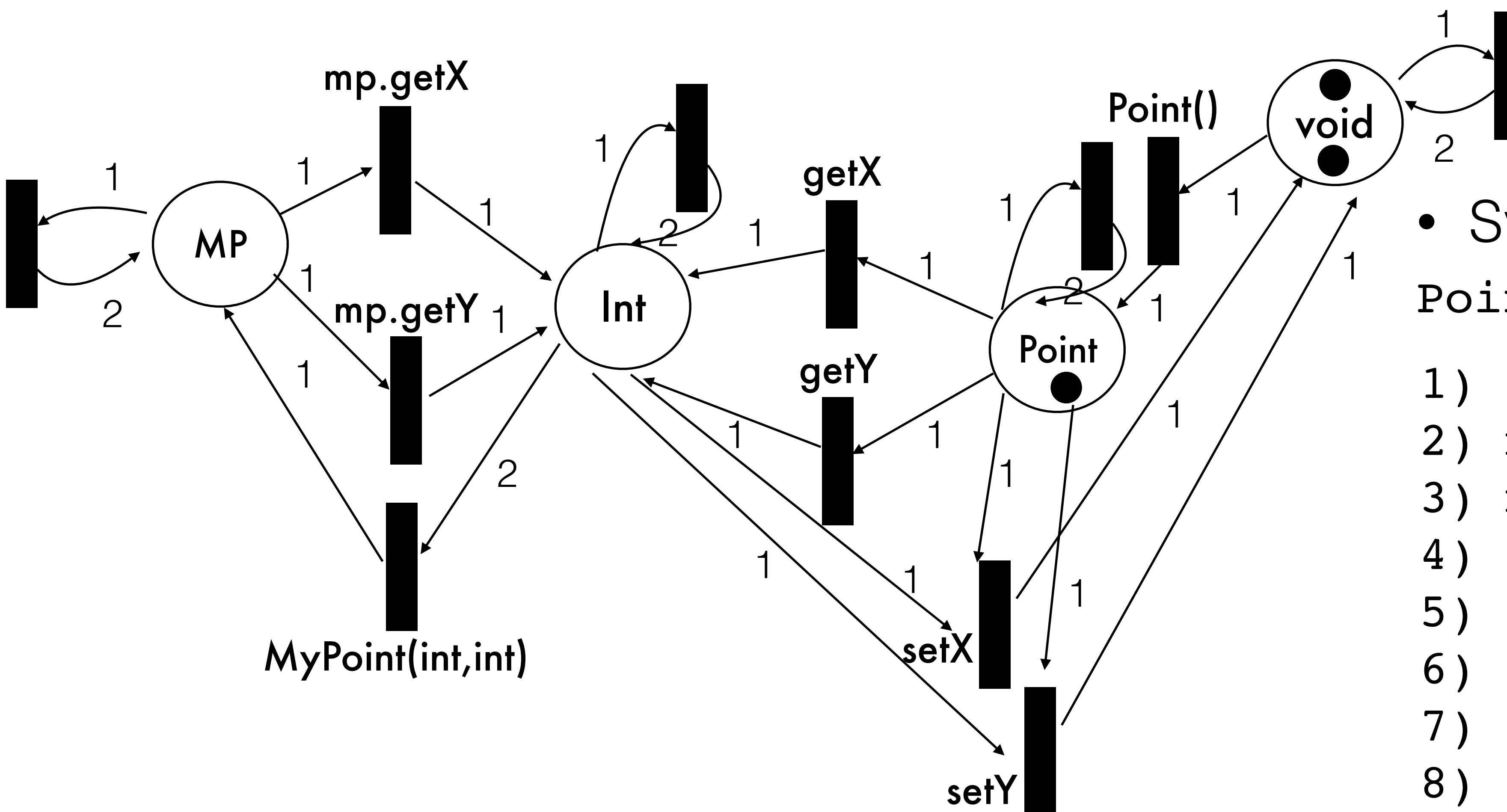
- Synthesize this function:  
`Point convert(Mypoint pt)`
- 1) Clone-MP
- 2) mp.getX
- 3) mp.getY
- 4) Point()
- 5) Clone-Point
- 6) setX

# Exercise 2: Reachable paths



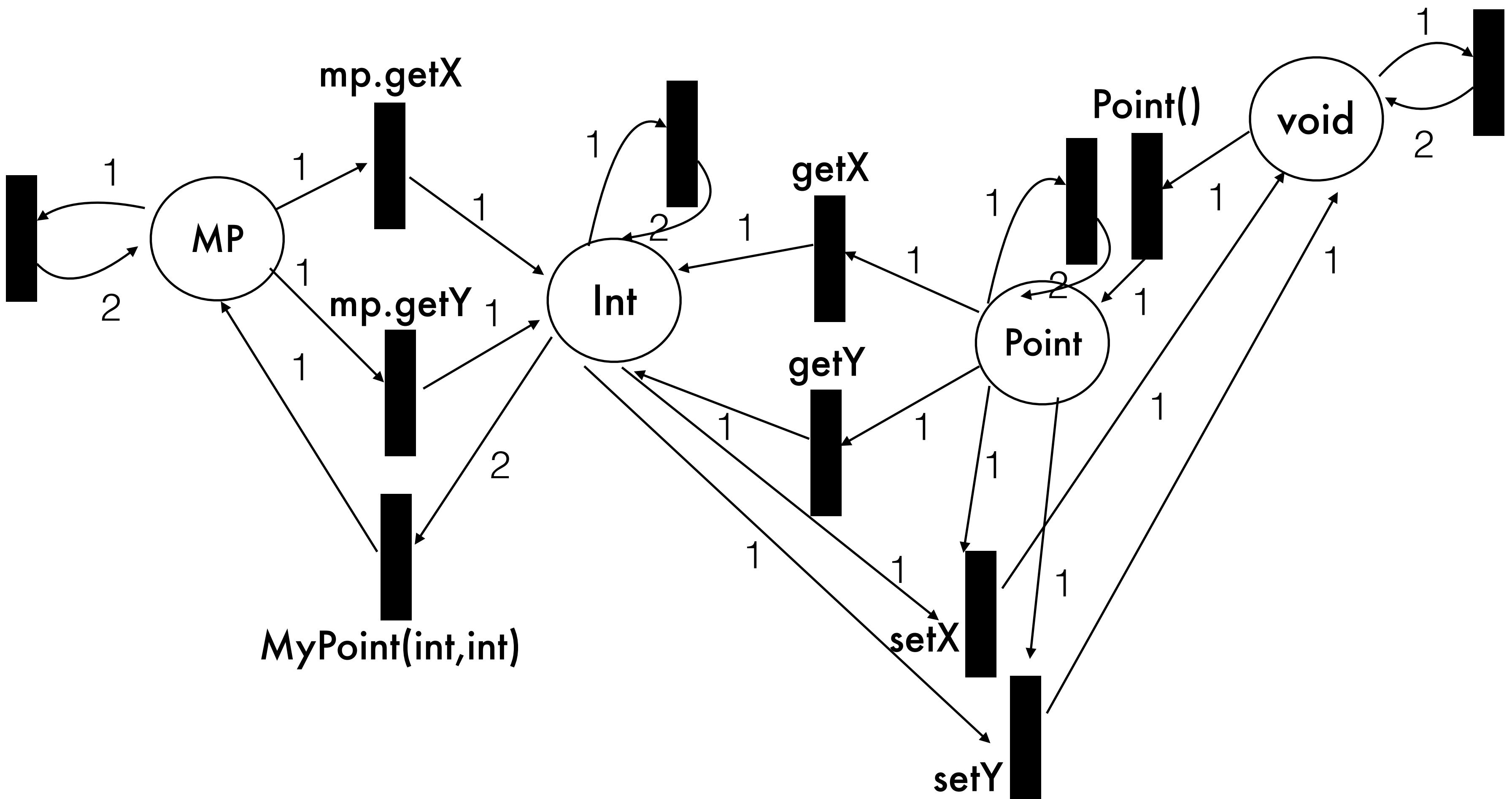
- Synthesize this function:  
Point convert(Mypoint pt)
- 1 ) clone-MP
- 2 ) mp.getX
- 3 ) mp.getY
- 4 ) Point()
- 5 ) Clone-Point
- 6 ) setX
- 7 ) Clone-Point

# Exercise 2: Reachable paths

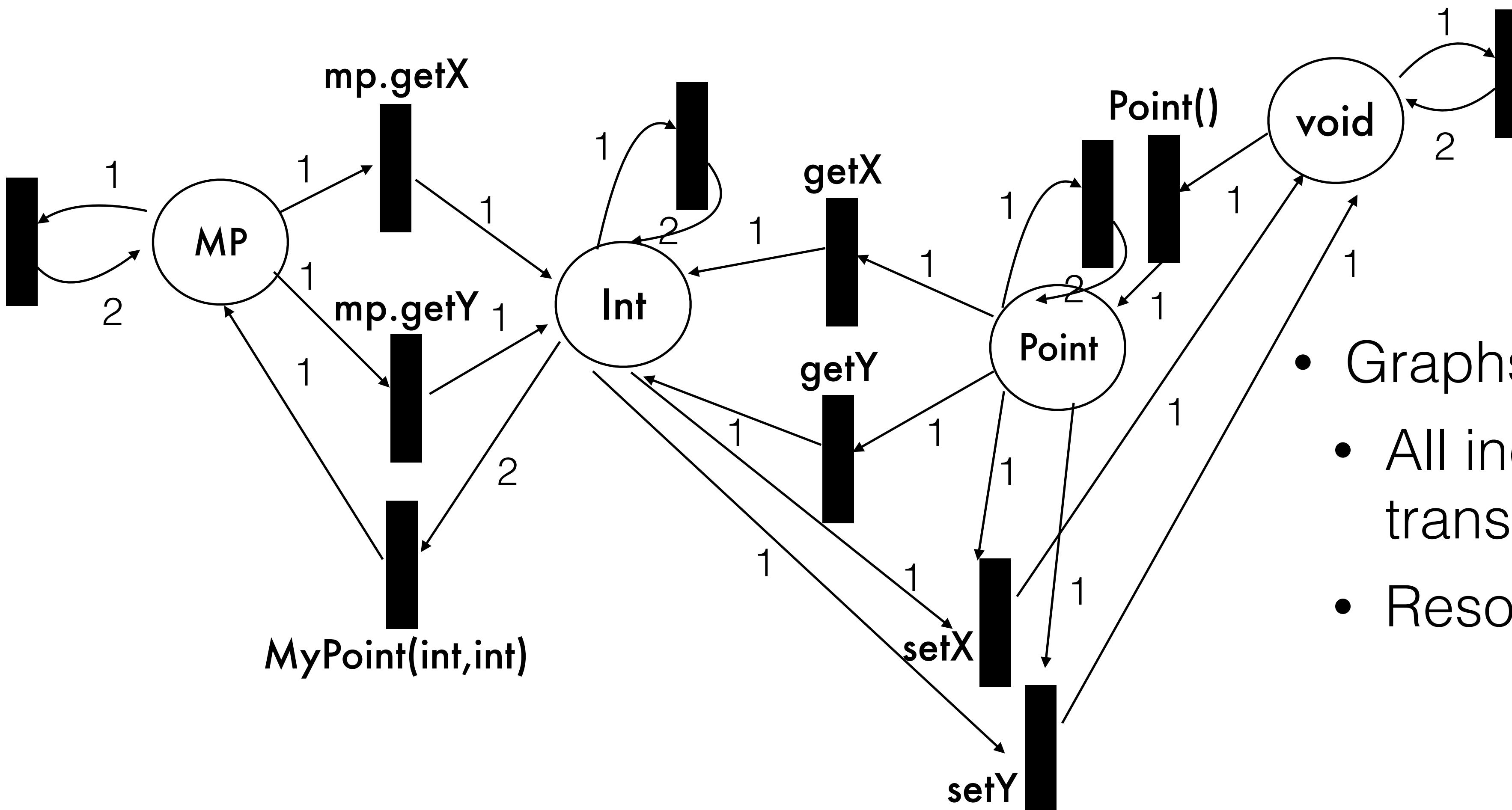


- Synthesize this function:  
Point convert(Mypoint pt)
  - 1 ) clone-MP
  - 2 ) mp.getX
  - 3 ) mp.getY
  - 4 ) Point()
  - 5 ) Clone-Point
  - 6 ) setX
  - 7 ) Clone-Point
  - 8 ) setY

# Why a Petri net and not a graph?

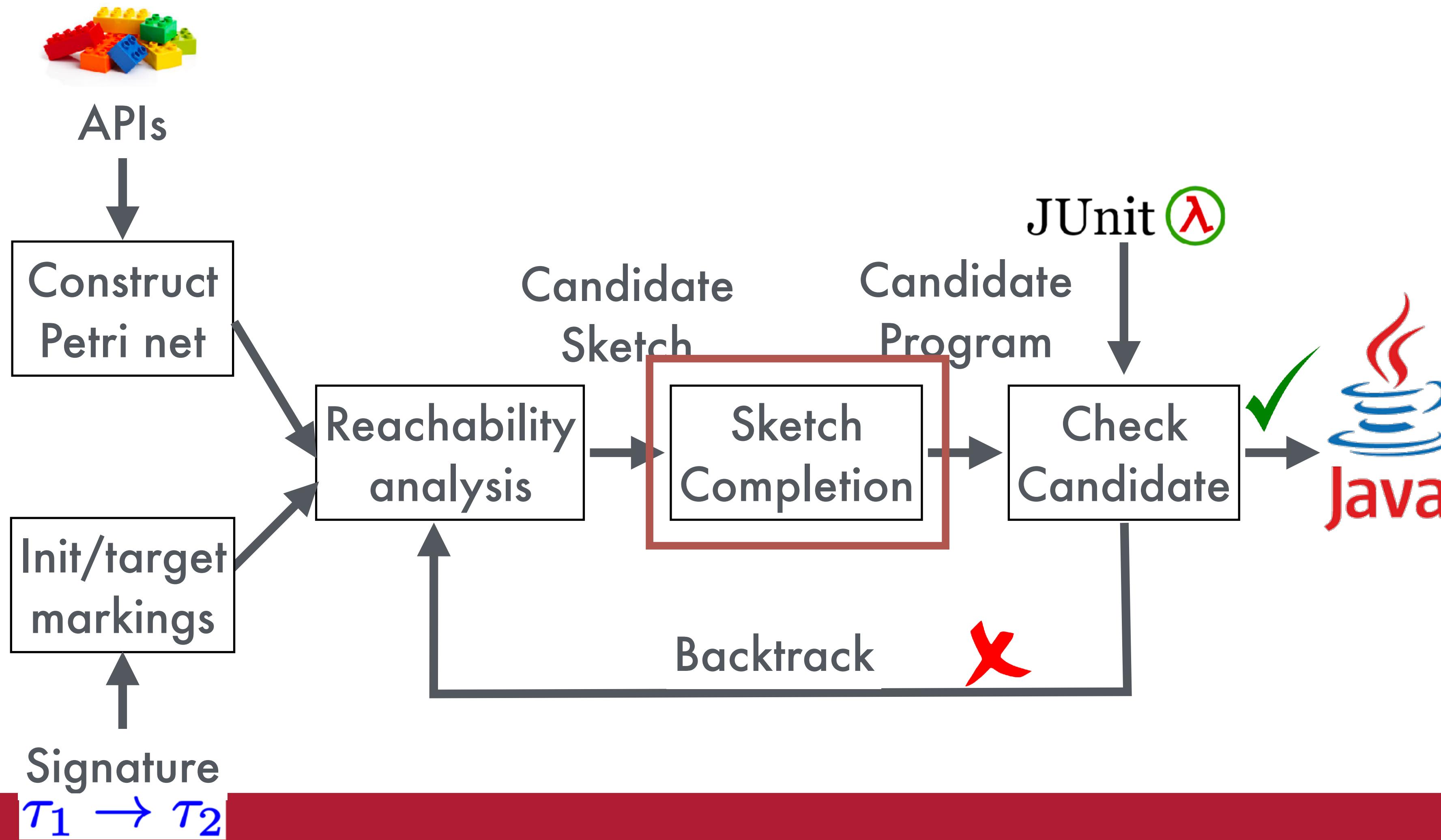


# Why a Petri net and not a graph?

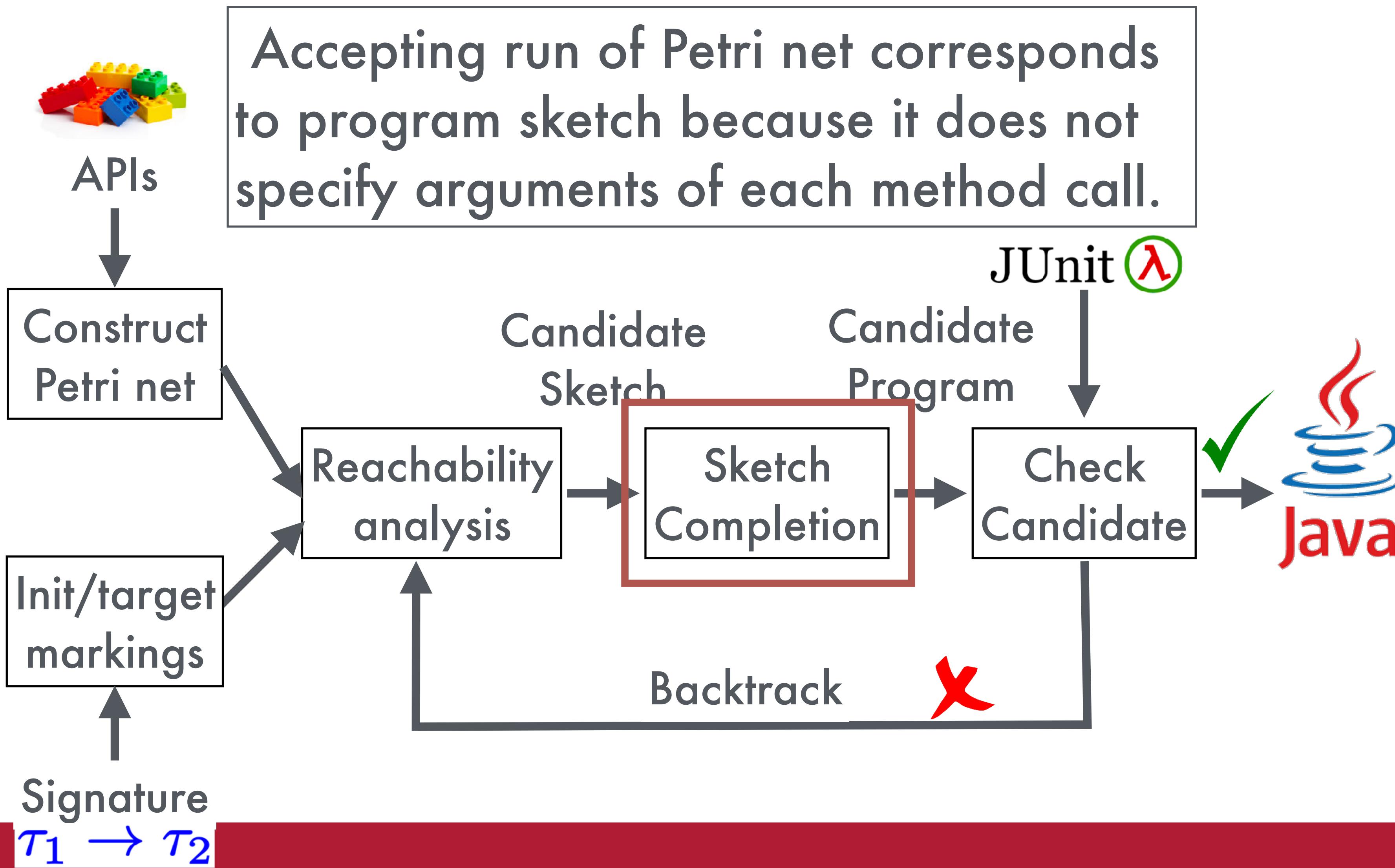


- Graphs do not support:
  - All incoming edges to a transition are part of the path
  - Resource consumption

# Accepting run as program sketch



# Accepting run as program sketch



# Sketch completion

```
x = #1.getX(); y = #2.getY();
#3.setToRotation(#4, #5, #6);
a = #7.createTransformedArea(#8);
return #9;
```

- Given a path:
  - getX -> getY -> setToRotation -> createTransformedArea
  - Find the arguments that should be used in each hole such that the program type checks

# Exercise 3: Sketch completion

- 1) Clone-MP
- 2) mp.getx
- 3) mp.gety
- 4) Point()
- 5) Clone-Point
- 6) setx
- 7) Clone-Point
- 8) sety

```
Point convert(Mypoint pt){  
}  
• Remove the Clone transitions
```

# Exercise 3: Sketch completion

- 2) mp.getx
- 3) mp.gety
- 4) Point()
- 6) setX
- 8) setY

```
Point convert(Mypoint pt){  
    }  
    }  
}
```

- What is the code with holes?

# Exercise 3: Sketch completion

- What is the code with holes?

```
Point convert(Mypoint pt){  
    2) mp.getX  
    3) mp.getY  
    4) Point()  
    6) setX  
    8) setY  
  
    int x = #1.getX();  
    int y = #2.getY();  
    Point p = new Point();  
    #3.setX(#4);  
    #5.setY(#6);  
    return #7;  
}
```

# Exercise 3: Sketch completion

- What is the code with holes?

```
Point convert(Mypoint pt){  
    2) mp.getX  
    3) mp.getY  
    4) Point()  
    6) setX  
    8) setY  
  
    int x = pt.getX();  
    int y = pt.getY();  
    Point p = new Point();  
    p.setX(#4);  
    p.setY(#6);  
    return p;  
}
```

# Exercise 3: Sketch completion

- 2) mp.getX
- 3) mp.getY
- 4) Point()
- 6) setX
- 8) setY

```
Point convert(Mypoint pt){  
    int x = pt.getX();  
    int y = pt.getY();  
    Point p = new Point();  
    p.setX(y);  
    p.setY(x);  
    return p;  
}
```

- What is the code with holes?

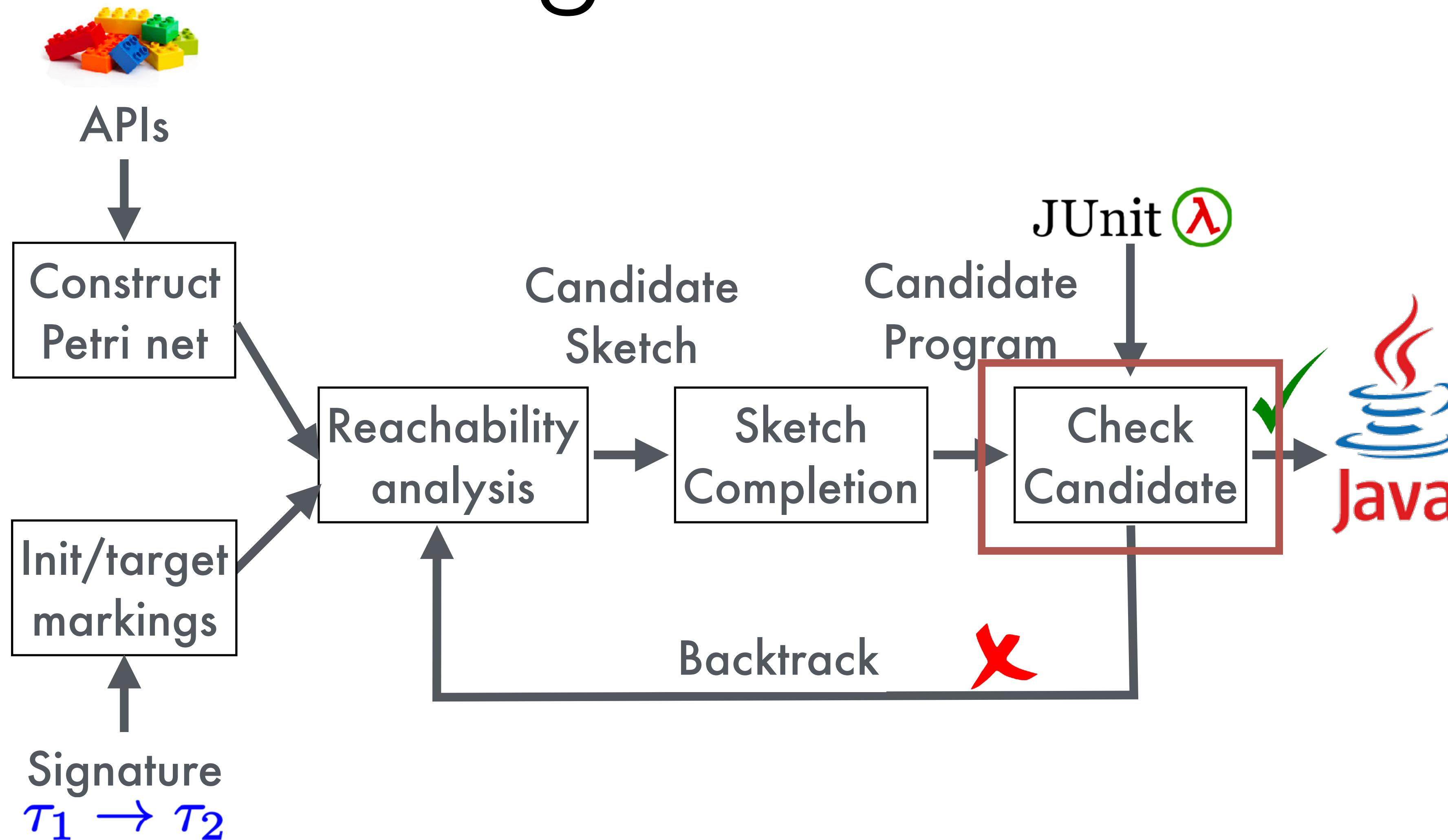
# Exercise 3: Sketch completion

- 2) mp.getX
- 3) mp.getY
- 4) Point()
- 6) setX
- 8) setY

```
Point convert(Mypoint pt){  
    int x = pt.getX();  
    int y = pt.getY();  
    Point p = new Point();  
    p.setX(x);  
    p.setY(y);  
    return p;  
}
```

- What is the code with holes?

# Checking the candidate



# Test cases

```
Point convert(MyPoint pt){  
  
    int x = pt.getX();  
    int y = pt.getY();  
    Point p = new Point();  
    p.setX(x);  
    p.setY(y);  
    return p;  
  
}
```

- Write a test case to check the conversion

# Test cases

```
Point convert(MyPoint pt){  
  
    int x = pt.getX();  
    int y = pt.getY();  
    Point p = new Point();  
    p.setX(x);  
    p.setY(y);  
    return p;  
  
}
```

- Write a test case to check the conversion
- ```
        bool test(){  
  
            MyPoint mp = new MyPoint(1,2);  
            Point p = convert(mp);  
            return (p.getX() == 1 &&  
                    p.getY() == 2);  
  
        }
```

# How does relate with SAT?

- Petri net reachability can encoded into SAT
- SyPet encodes this problem to SAT by viewing it as a **bounded** planning problem in STRIPS:
  - Variables
  - Actions: preconditions -> postconditions
  - Initial State
  - Goal State

# Using SyPet

## Demo

# SyPet's strengths

- Works for real code!
- Generic: can tackle any Java library
  - e.g. geometry, math, joda, unirest, xml, etc.
- Works well when there are many different types
- Scales to a large number of APIs

# SyPet's weaknesses

- Does not support conditionals
- Does not support loops
- For some applications it is hard to write test cases
- Does not scale when everything is the same type

# For more information



Program synthesis tool for Java libraries that  
automatically constructs programs by composing APIs.

[GITHUB](#)[DOWNLOAD](#)

<https://utopia-group.github.io/sy wholepet/>

# Outline

Code  
Reuse

FSE'16



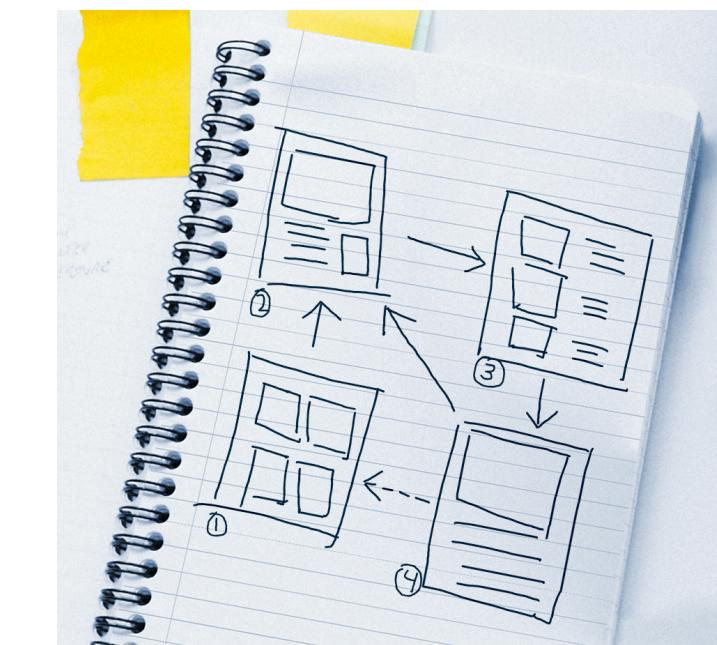
Complex  
Java APIs

POPL'17



Program  
Sketching

PLDI'05



CEGIS

PLDI'08



SyGuS

FMCAD'13



# Program Sketching

```
void doubleSketch(int x){  
    int t = x * ??;  
    assert t == x + x;  
}
```

- Program Sketching:
  - The user provides a partial program with holes
  - The synthesizer finds an assignment to the holes such that the specification is satisfied

# Program Sketching

```
void doubleSketch(int x){  
    int t = x * ??;  
    assert t == x + x;  
}
```

```
void doubleSketch(int x){  
    int t = x * 2;  
    assert t == x + x;  
}
```

- Program Sketching:
  - The user provides a partial program with holes
  - The synthesizer finds an assignment to the holes such that the specification is satisfied

# Program Sketching

## Demo

- For more details:
  - <https://people.csail.mit.edu/asolar/>
  - Manual: <https://people.csail.mit.edu/asolar/manual.pdf>

# Outline

Code  
Reuse

FSE'16



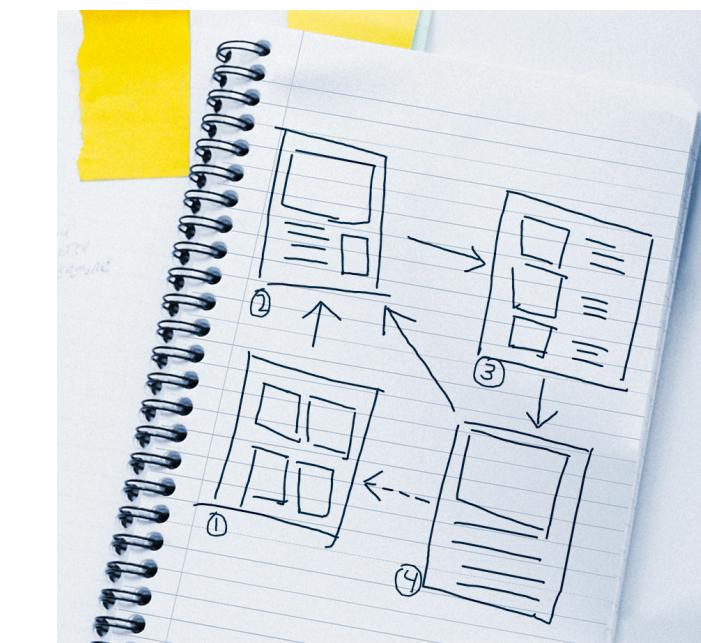
Complex  
Java APIs

POPL'17



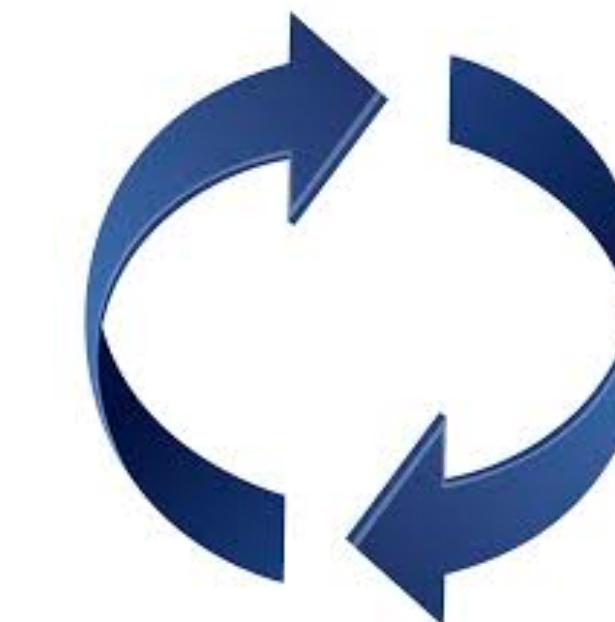
Program  
Sketching

PLDI'05



CEGIS

PLDI'08



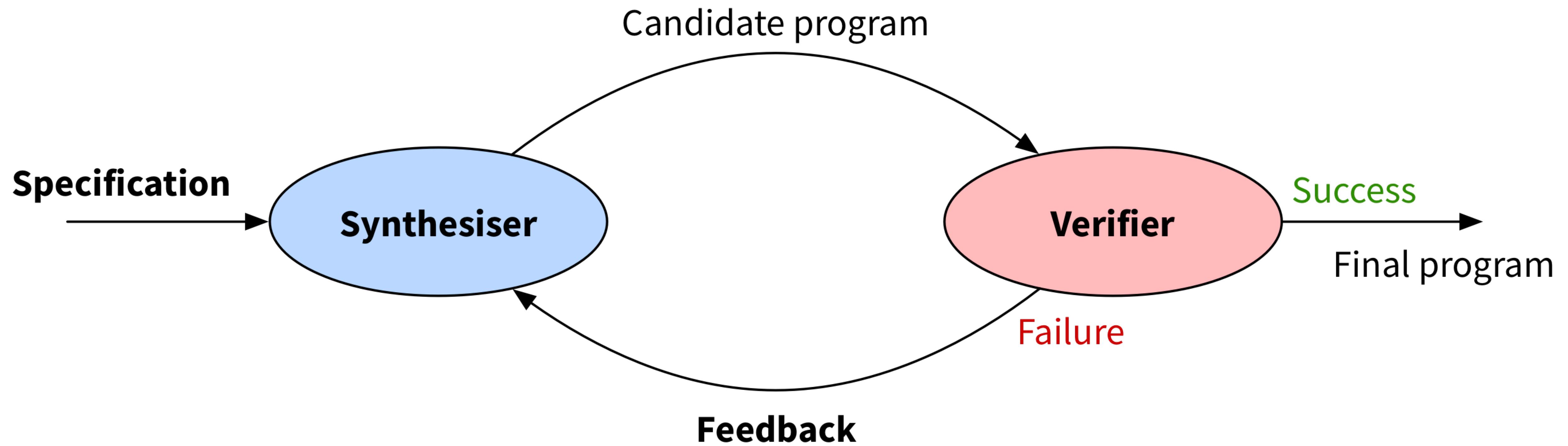
SyGuS

FMCAD'13



# Counterexample-Guided Inductive Synthesis

**CEGIS:**



# Outline

Code  
Reuse

FSE'16



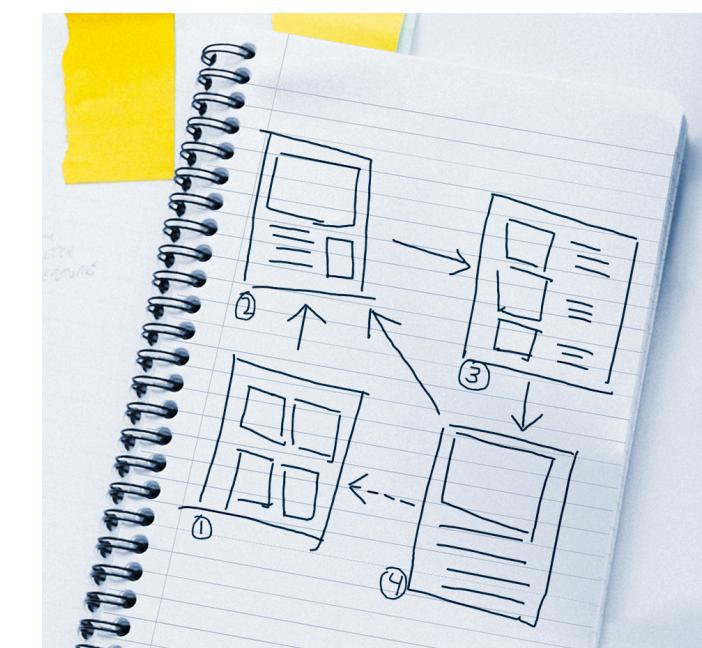
Complex  
Java APIs

POPL'17



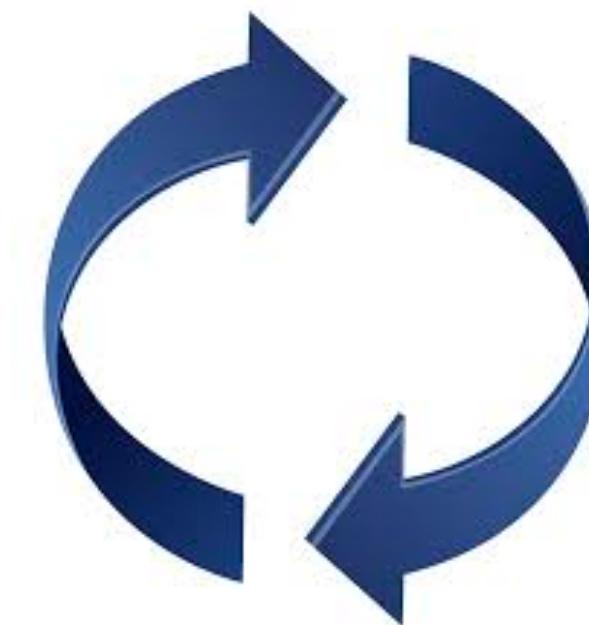
Program  
Sketching

PLDI'05



CEGIS

PLDI'08



SyGuS

FMCAD'13



# Syntax-Guided Synthesis

- Extends the SMT-Lib language to synthesis
- Advantages:
  - Same input format that can be reused by solvers
  - Easy to specify for users
- Disadvantages:
  - Limited to SMT theories

# Syntax-Guided Synthesis

```
;; The background theory is linear integer arithmetic
;; (set-logic LIA)

;; Name and signature of the function to be synthesized
(synth-fun max2 ((x Int) (y Int)) Int

;; Declare the non-terminals that would be used in the grammar
((I Int) (B Bool))

;; Define the grammar for allowed implementations of max2
((I Int (x y 0 1
           (+ I I) (- I I)
           (ite B I I)))
 (B Bool ((and B B) (or B B) (not B)
           (= I I) (<= I I) (>= I I))))
)

(declare-var x Int)
(declare-var y Int)

;; Define the semantic constraints on the function
(constraint (>= (max2 x y) x))
(constraint (>= (max2 x y) y))
(constraint (or (= x (max2 x y)) (= y (max2 x y)))))

(check-synth)
```

# Syntax-Guided Synthesis



- For more details and solvers:
  - <https://sygus.org/>

# Papers

FSE'16

Hunter: Next-Generation Code Reuse for Java

POPL'17

Component-Based Synthesis for Complex APIs

PLDI'05

Programming by sketching for bit-streaming programs

PLDI'08

Sketching concurrent data structures

FMCAD'13

Syntax-guided synthesis