

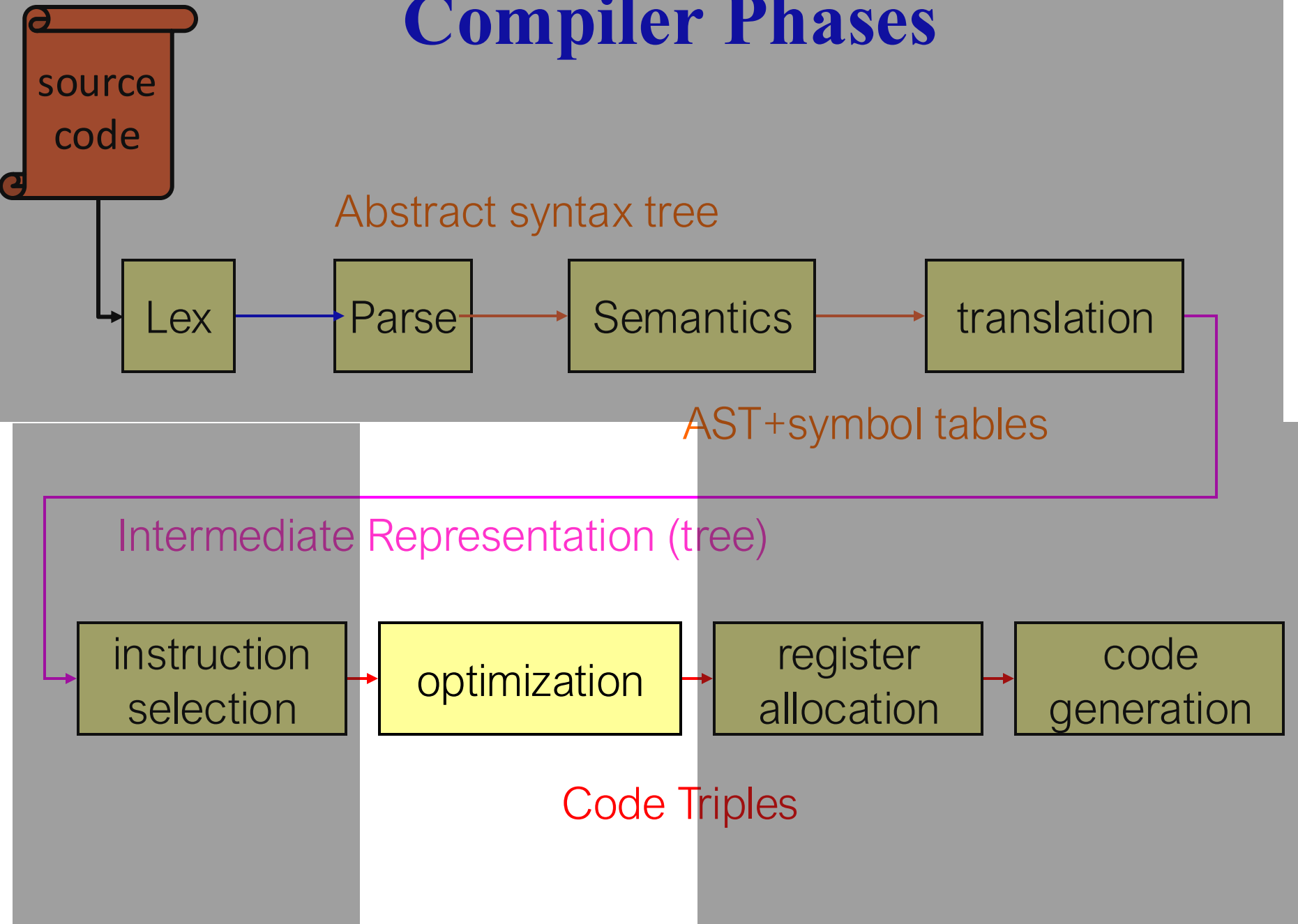
Optimization 1

15-411/15-611 Compiler Design

Seth Copen Goldstein

March 19, 2026

Compiler Phases



Scope of Optimizations

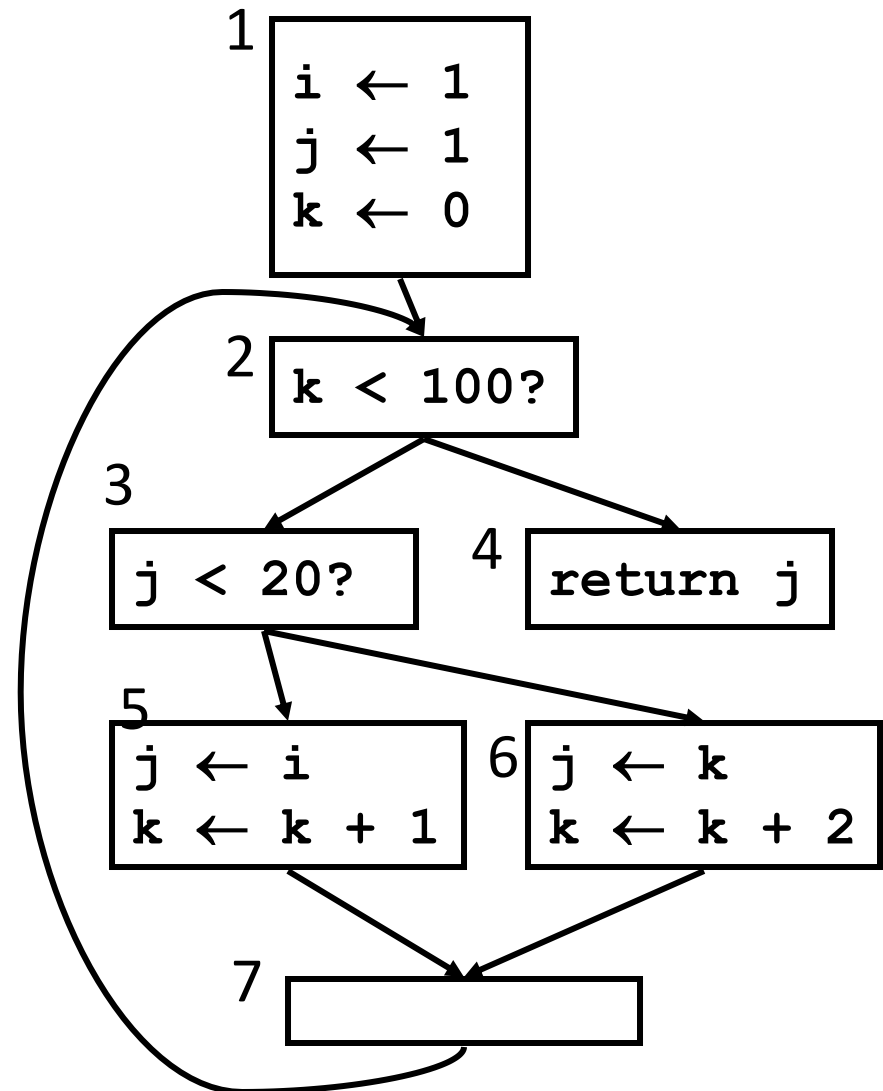
- Peephole
- Local
- Global
- Whole File
- Whole Program

Plan

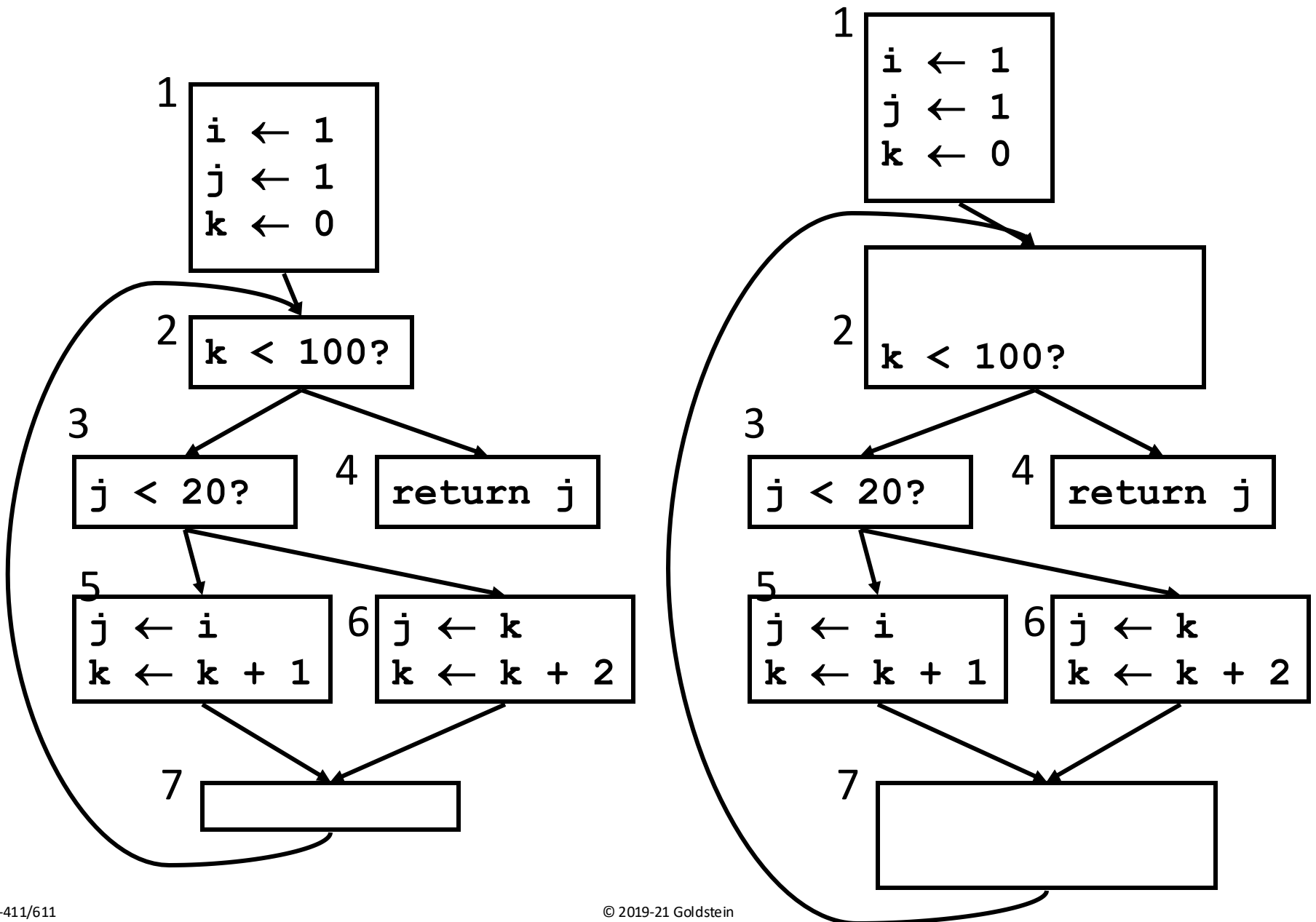
- (Re-)Motivation of SSA
 - SCCP
 - ADCE
 - Control Dependence and Dominance
- Introduction to Peephole
- Finding Loops
- Simple Loop-based Optimizations

Lets optimize the following:

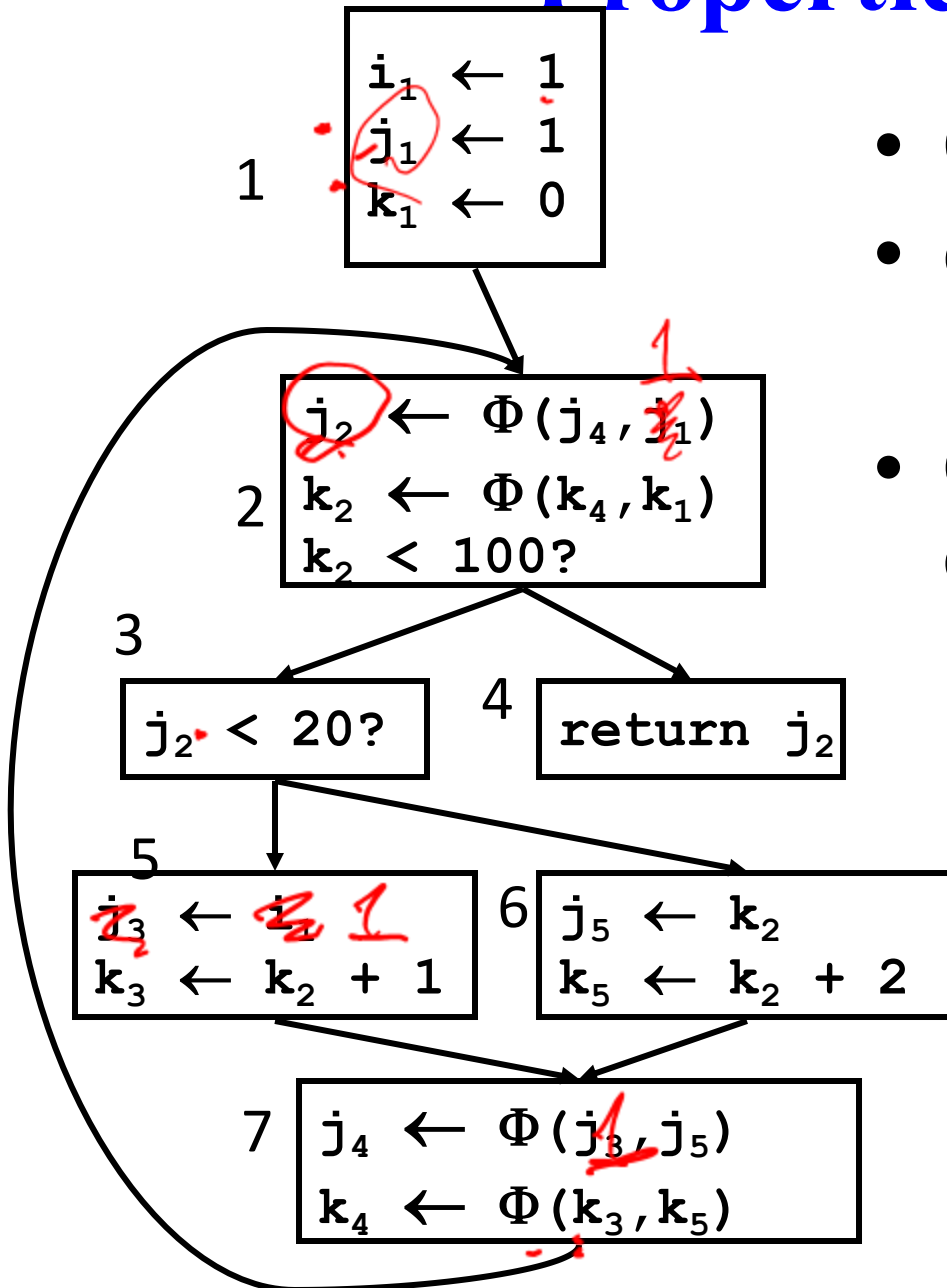
```
i=1;  
j=1;  
k=0;  
while (k<100) {  
  if (j<20) {  
    j=i;  
    k++;  
  } else {  
    j=k;  
    k+=2;  
  }  
}  
return j;
```



First, turn into SSA

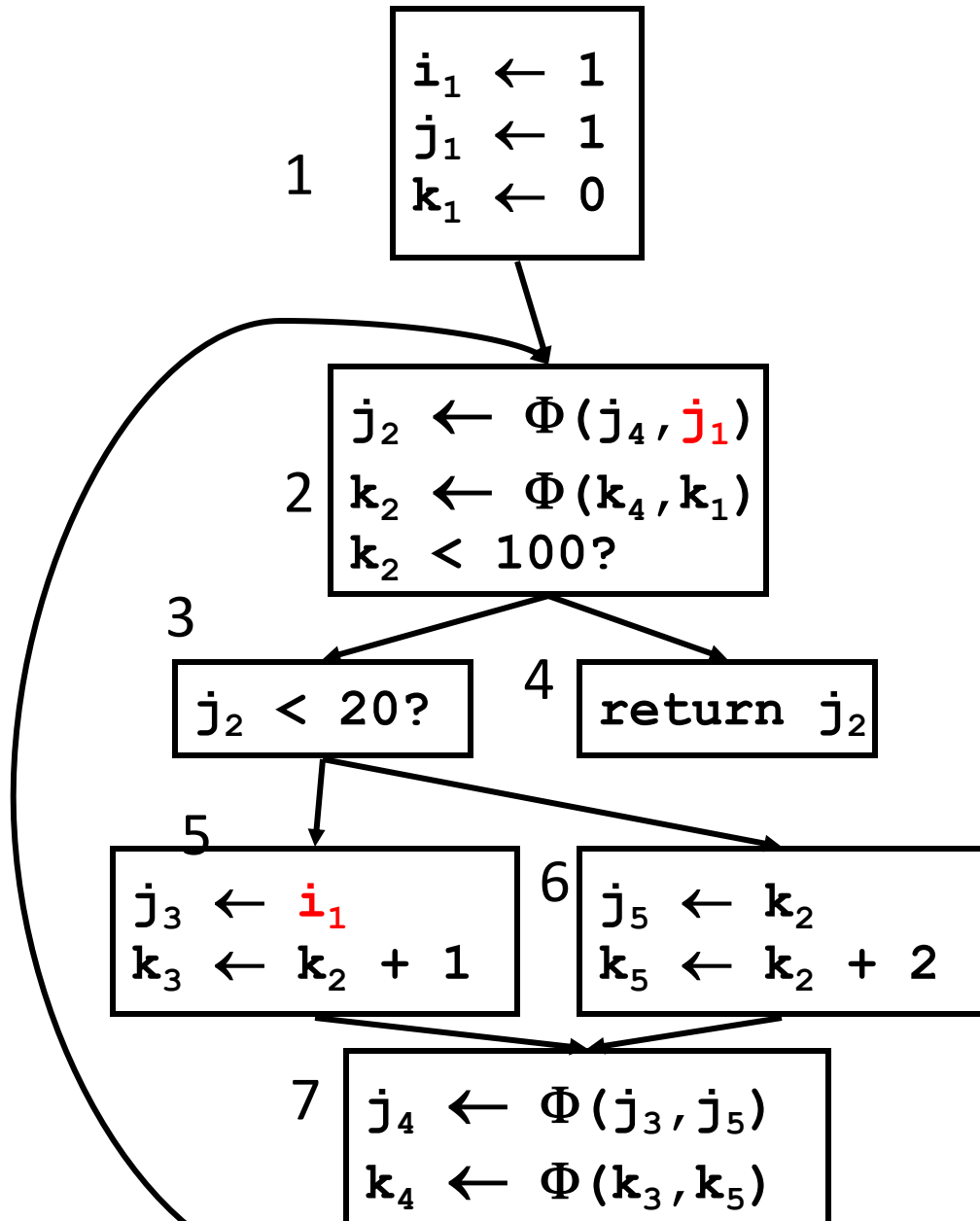


Properties of SSA



- Only 1 assignment per variable
- definitions dominate uses
- Can we use this to help with constant propagation?

Constant Propagation



Constant Propagation

- If " $v \leftarrow c$ ", replace all uses of v with c
- If " $v \leftarrow \Phi(c, c, c)$ ", replace all uses of v with c

$W \leftarrow$ list of all defs

while ! $W.isEmpty$ {

$Stmt\ S \leftarrow W.removeOne$

 if S has form " $v \leftarrow \Phi(c, \dots, c)$ "

 replace S with $V \leftarrow c$

 if S has form " $v \leftarrow c$ " then

 delete S

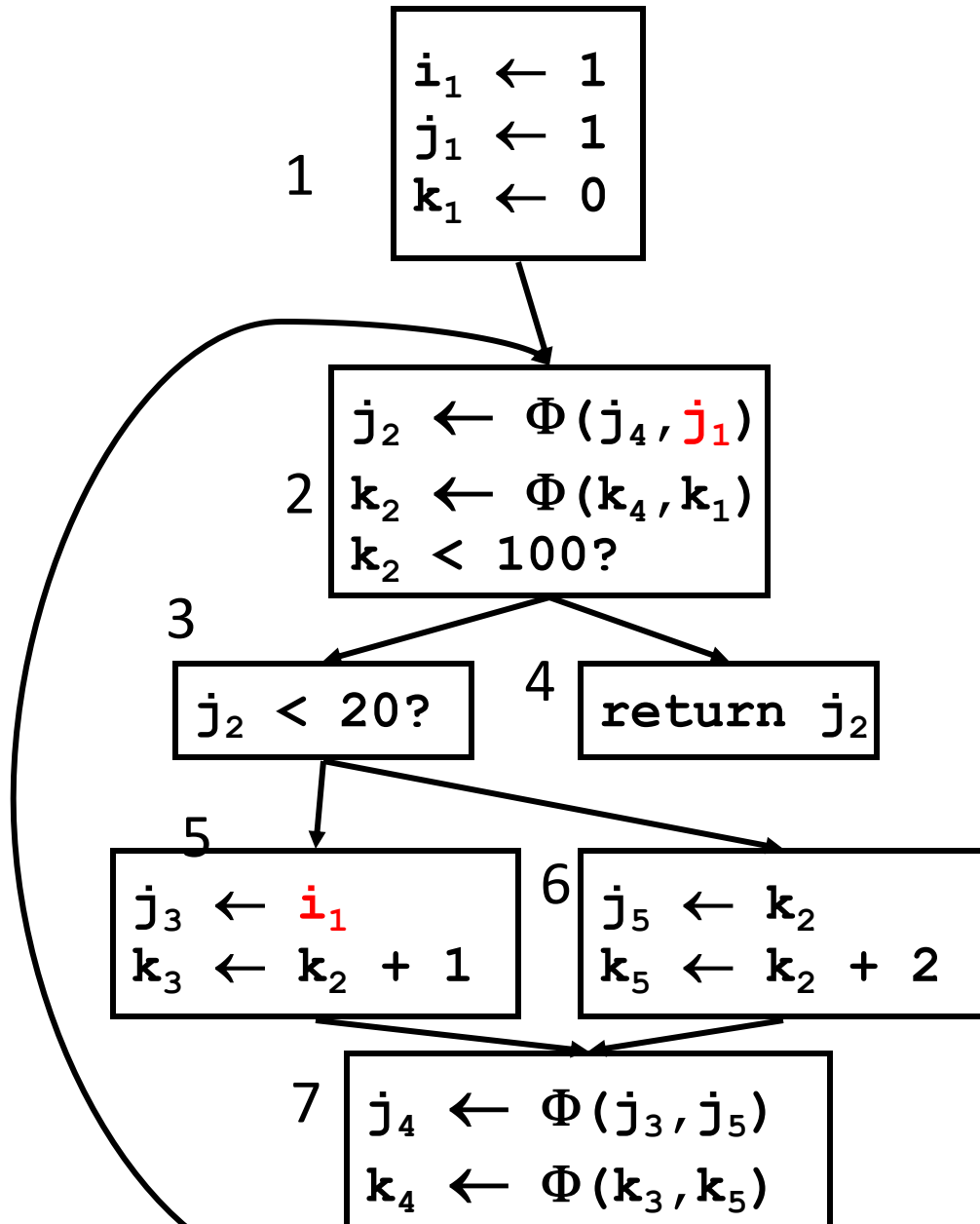
 foreach $stmt\ U$ that uses v ,

 replace v with c in U

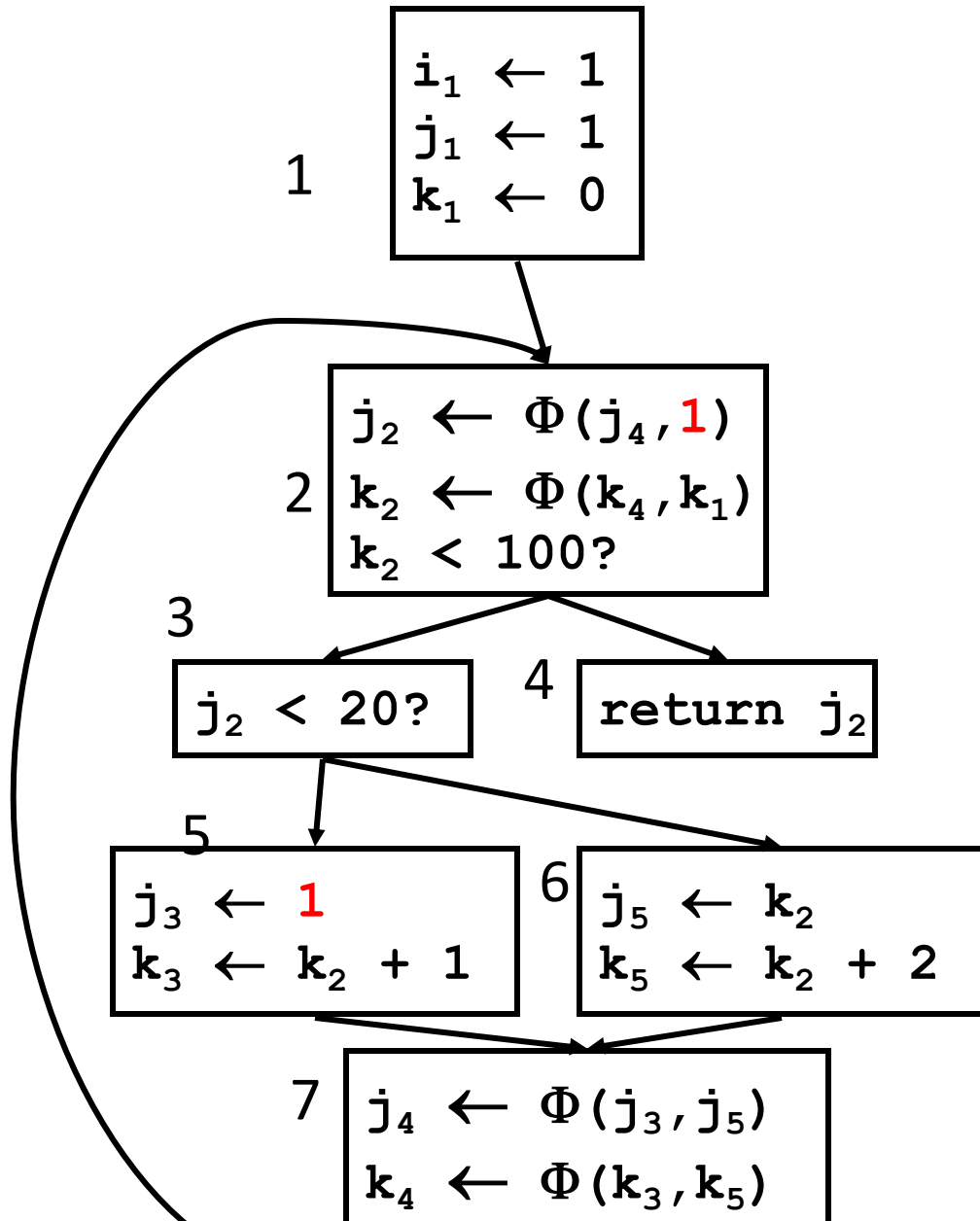
$W.add(U)$

}

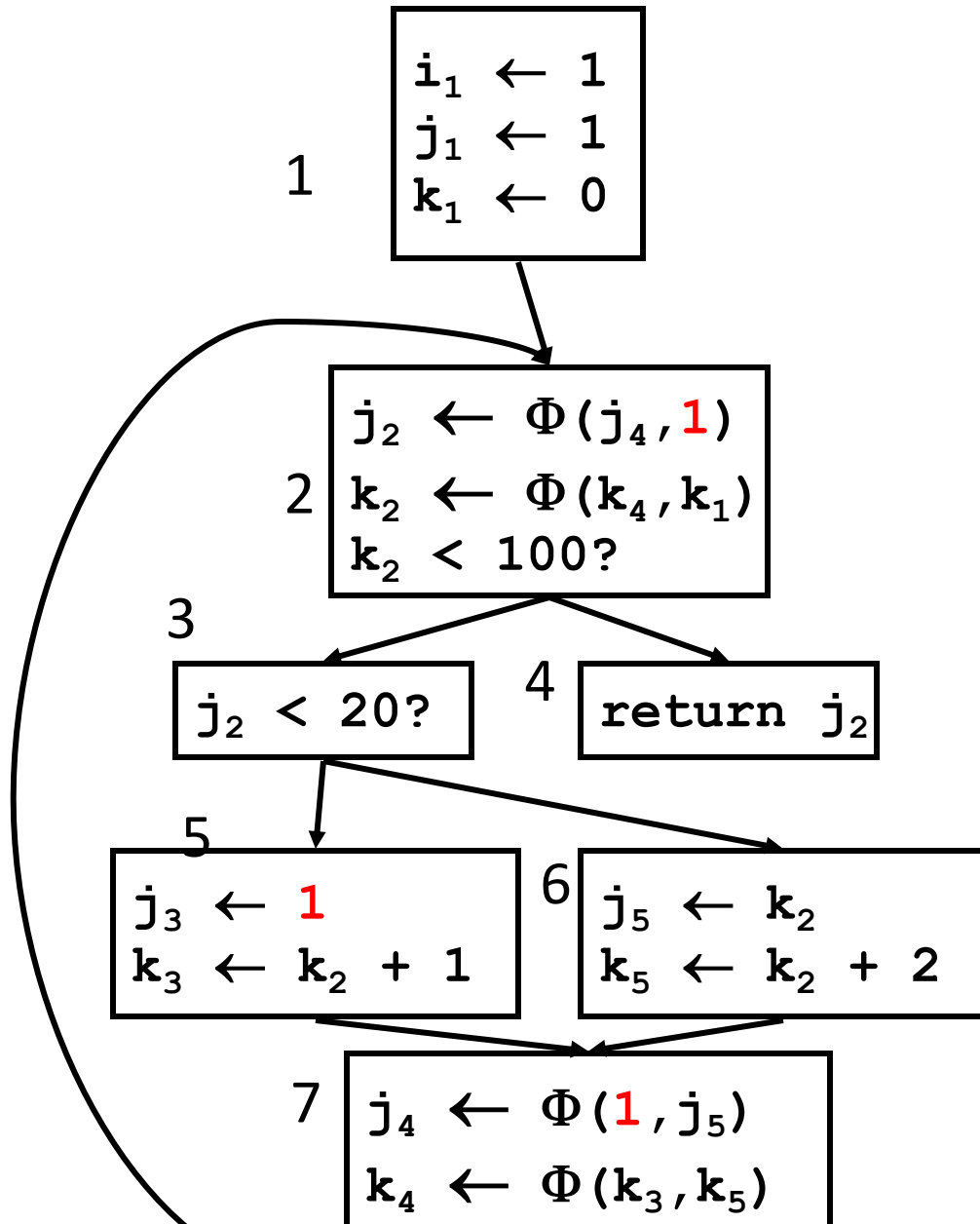
Constant Propagation



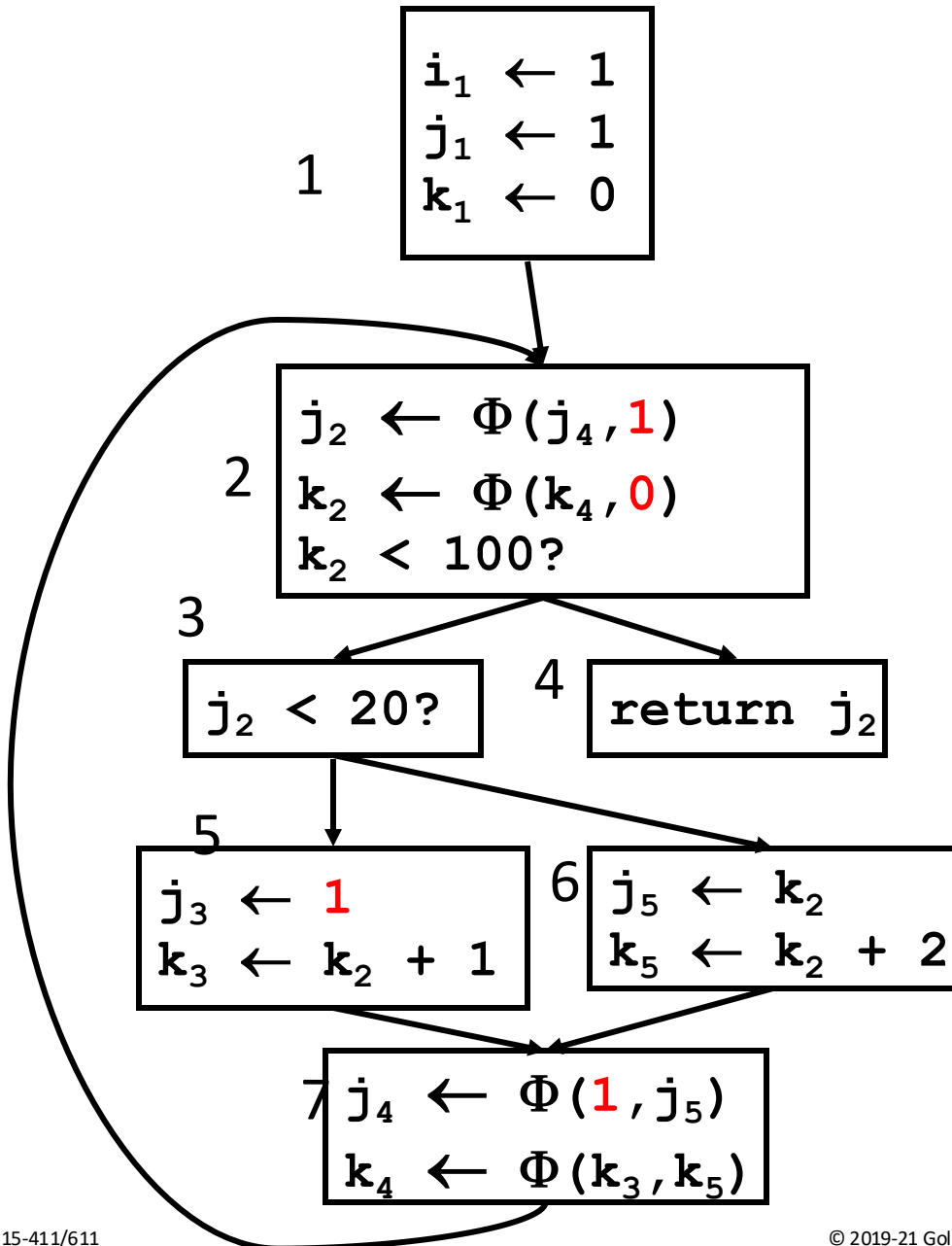
Constant Propagation



Constant Propagation

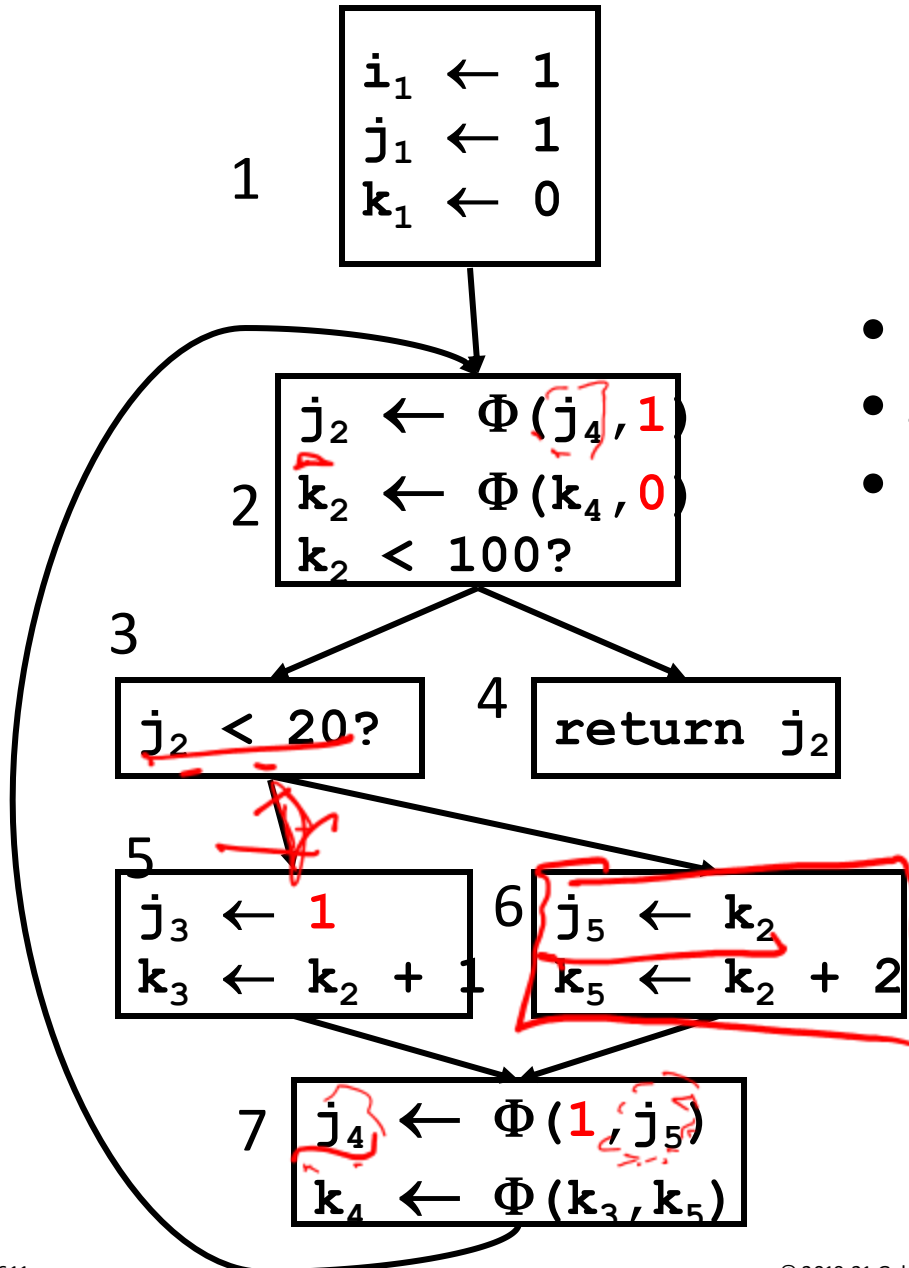


Constant Propagation



But, so what?

Conditional Constant Propagation



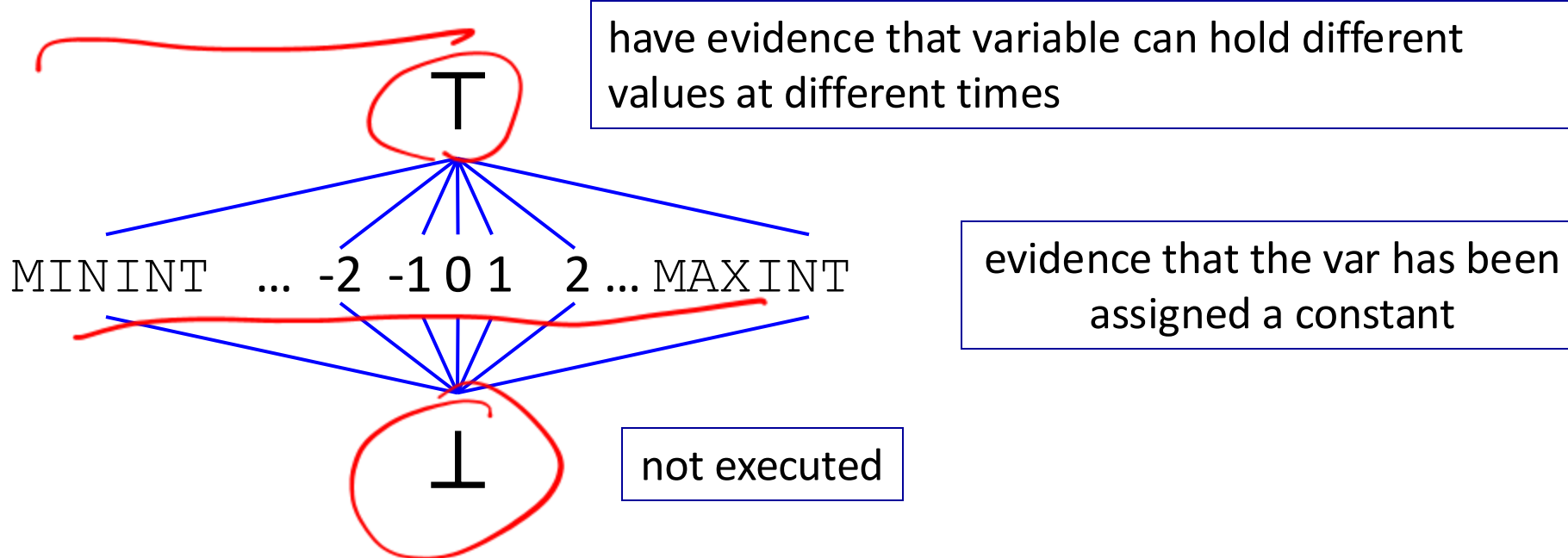
- Does block 6 ever execute?
- Simple CP can't tell
- CCP can tell:
 - Assumes blocks don't execute until proven otherwise
 - Assumes values are constants until proven otherwise

CCP data structures & lattice

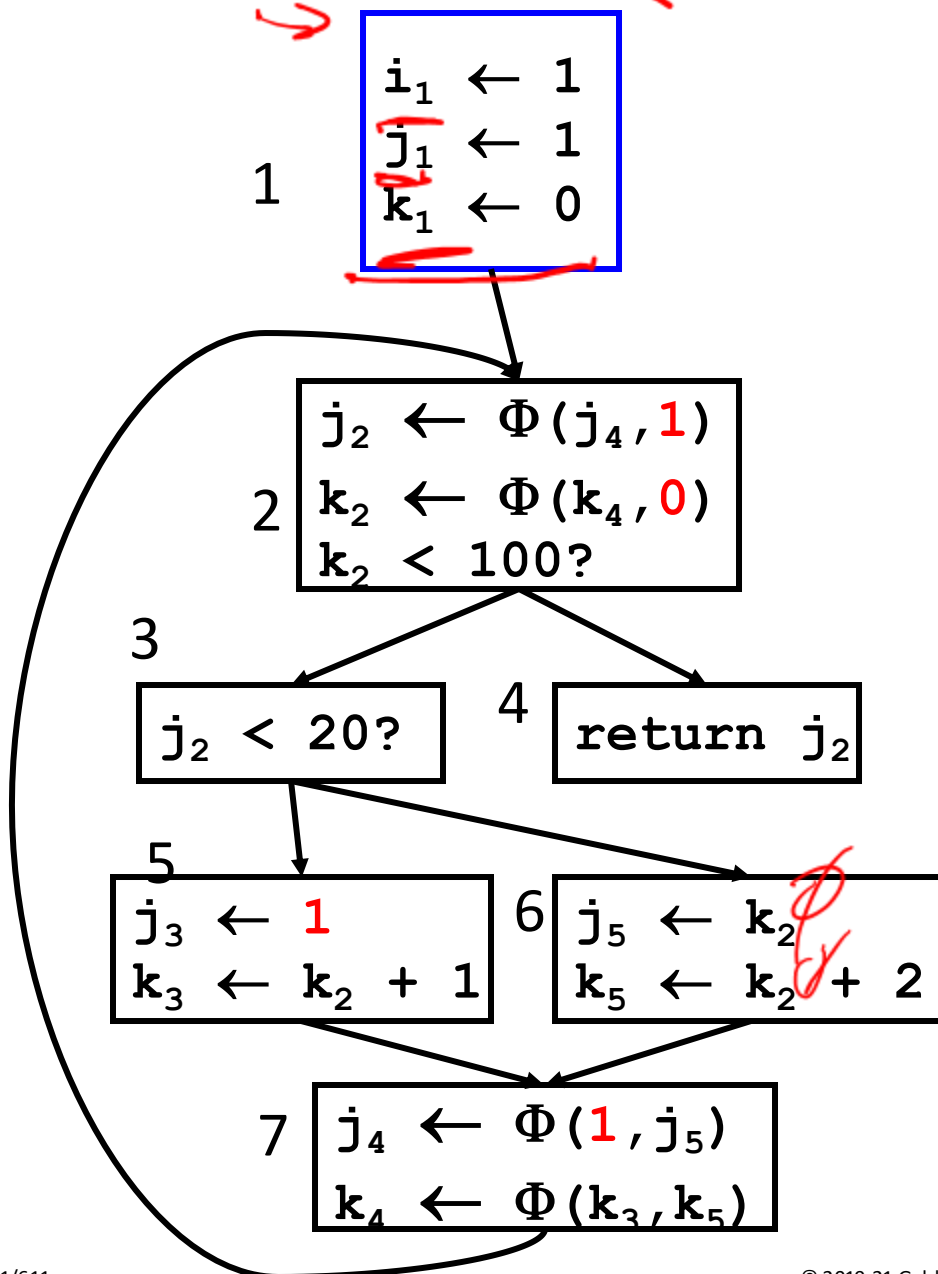
Keep track of:

- Blocks (assume unexecuted until proven otherwise)
- Variables (assume not executed, only with proof of assignments of a non-constant value do we assume not constant)

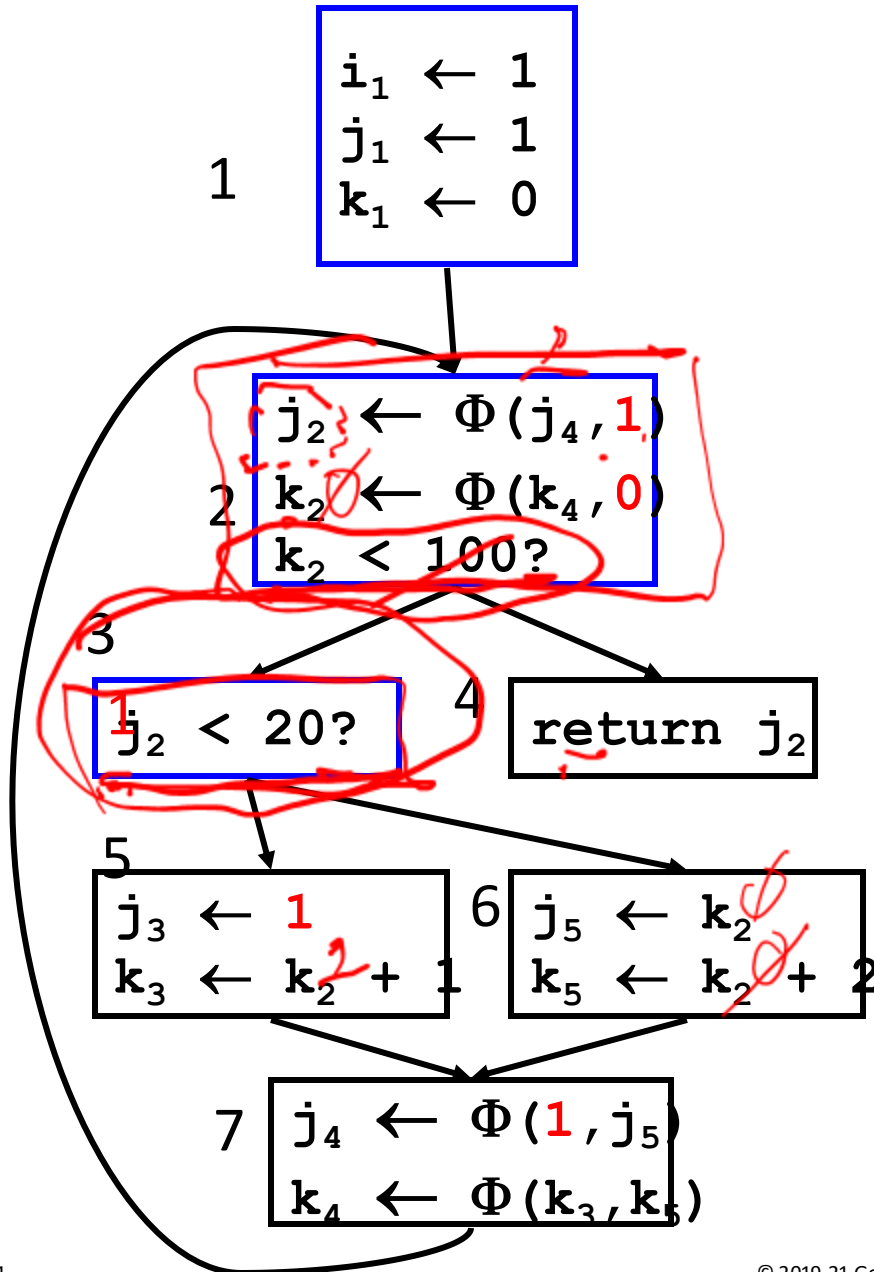
Use a lattice for variables:



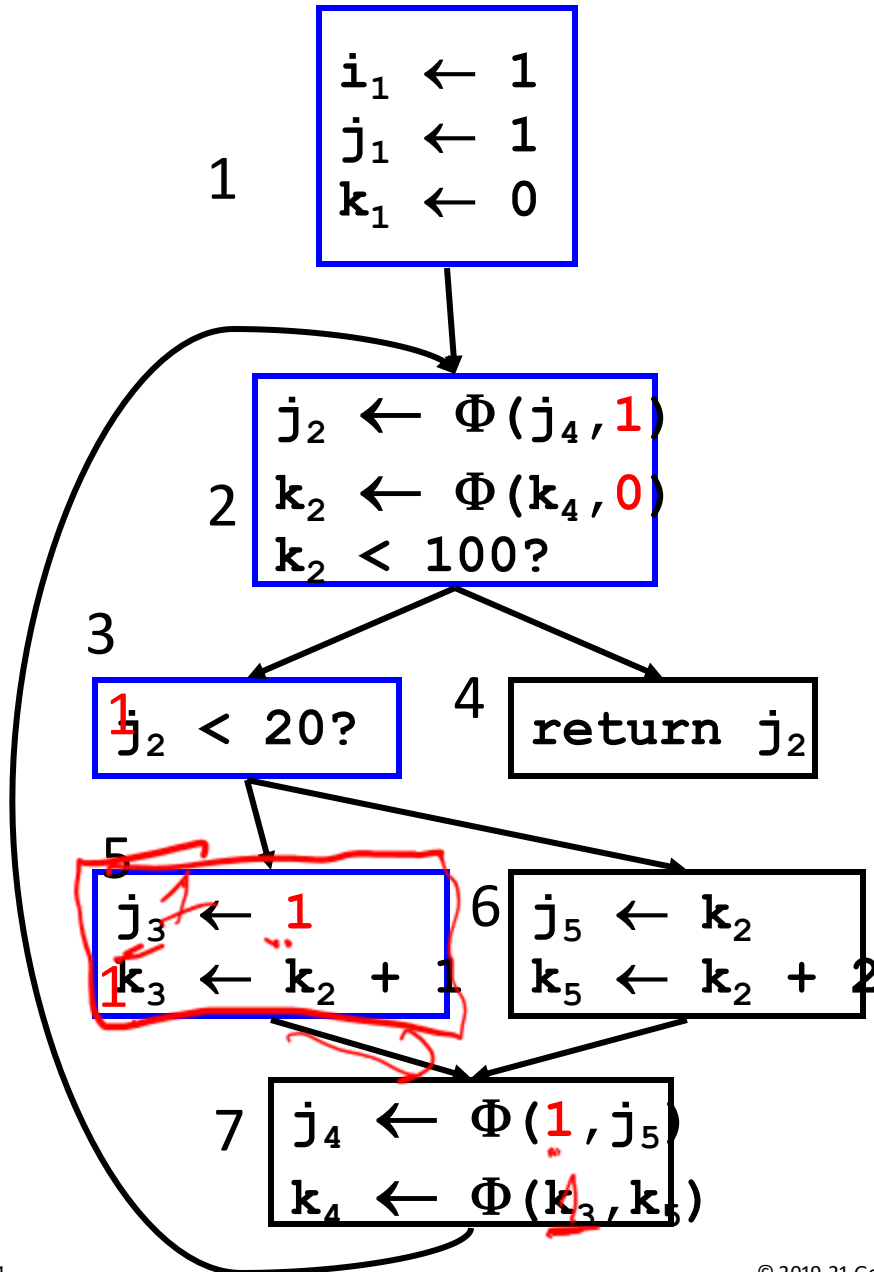
Conditional Constant Propagation



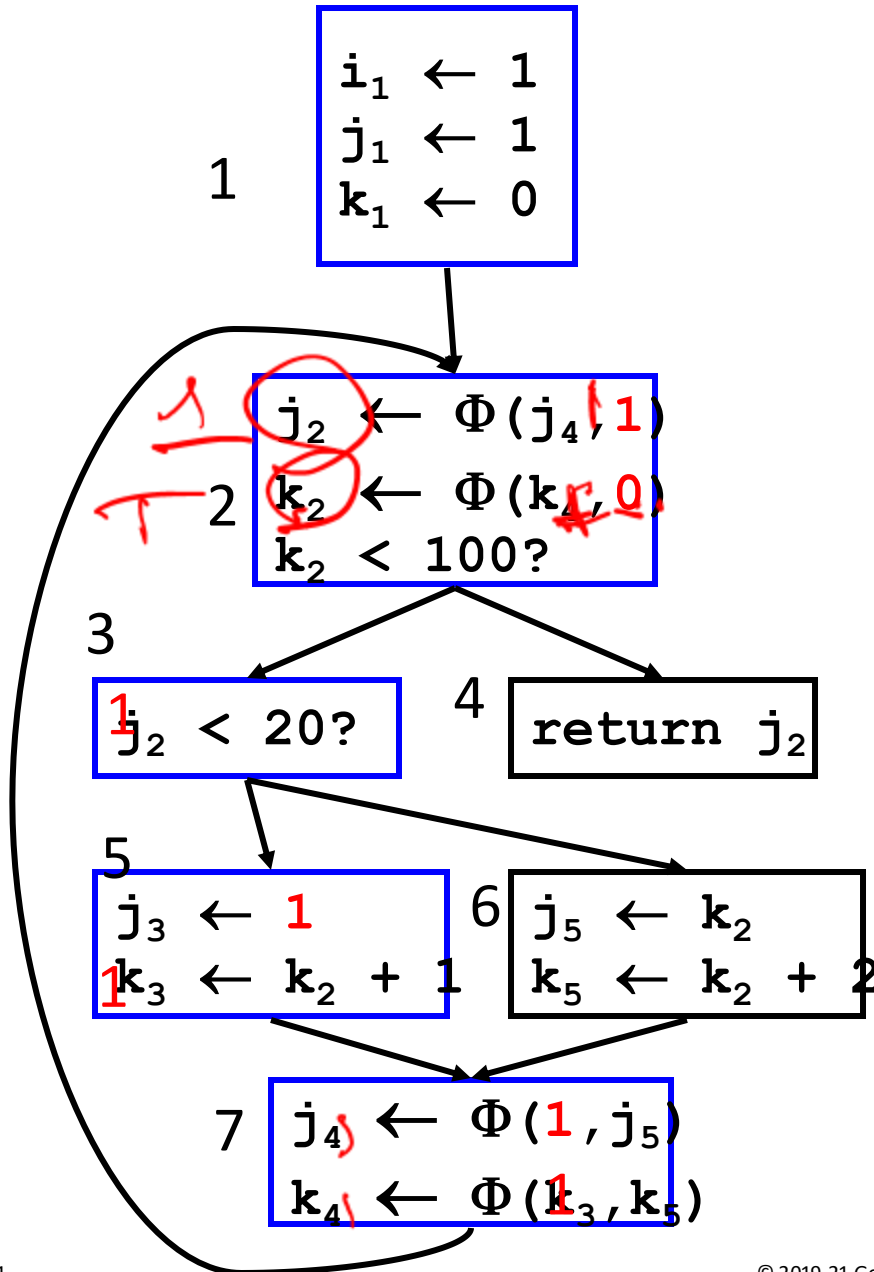
Conditional Constant Propagation



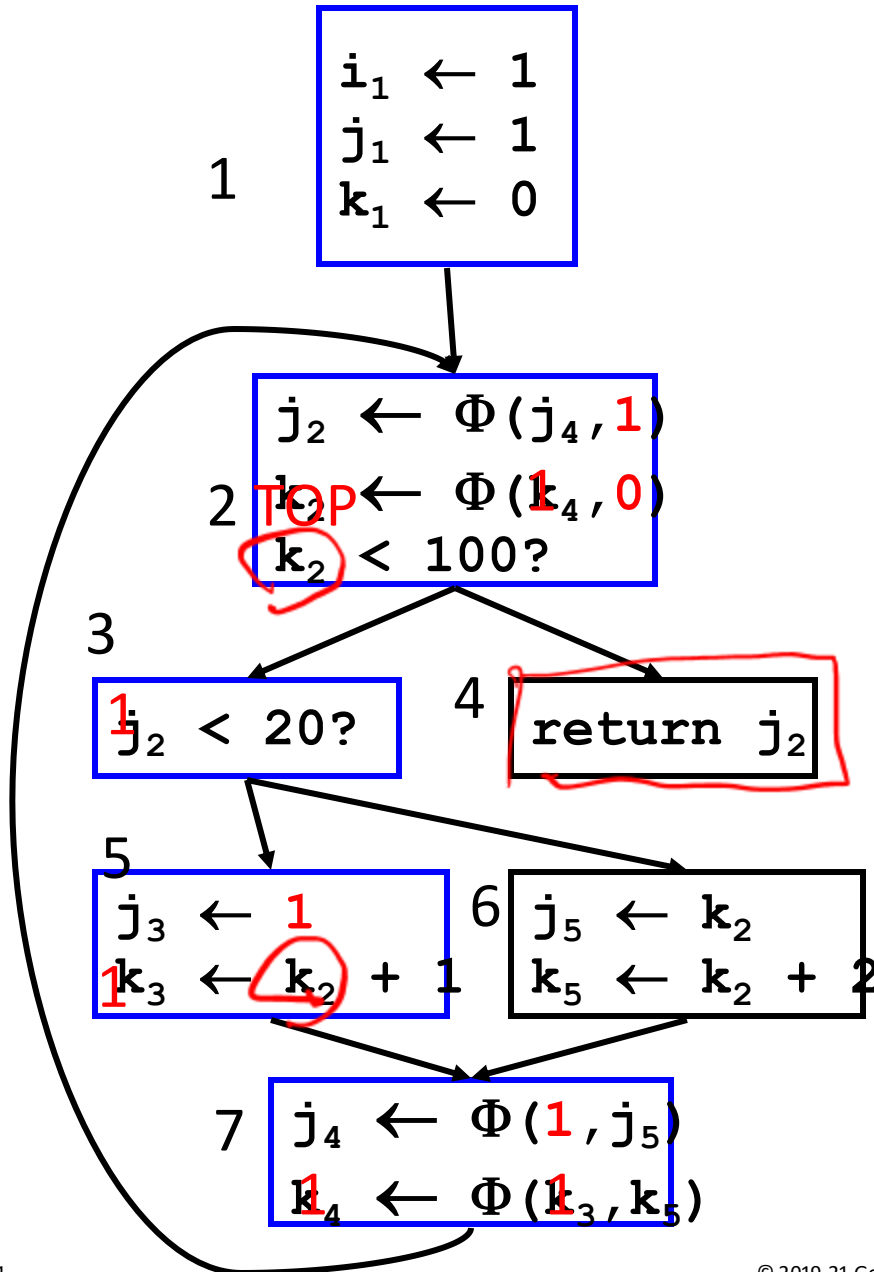
Conditional Constant Propagation



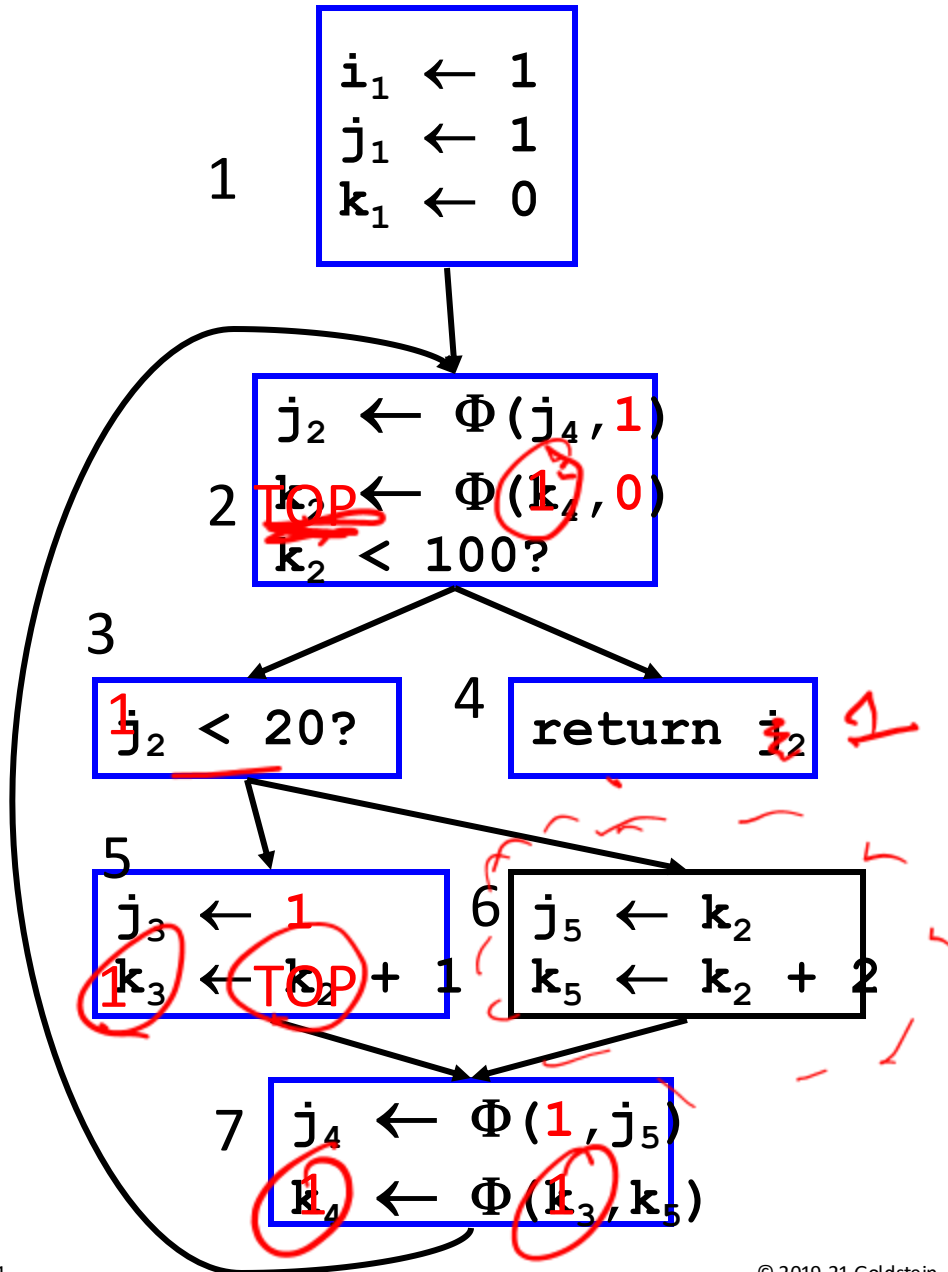
Conditional Constant Propagation



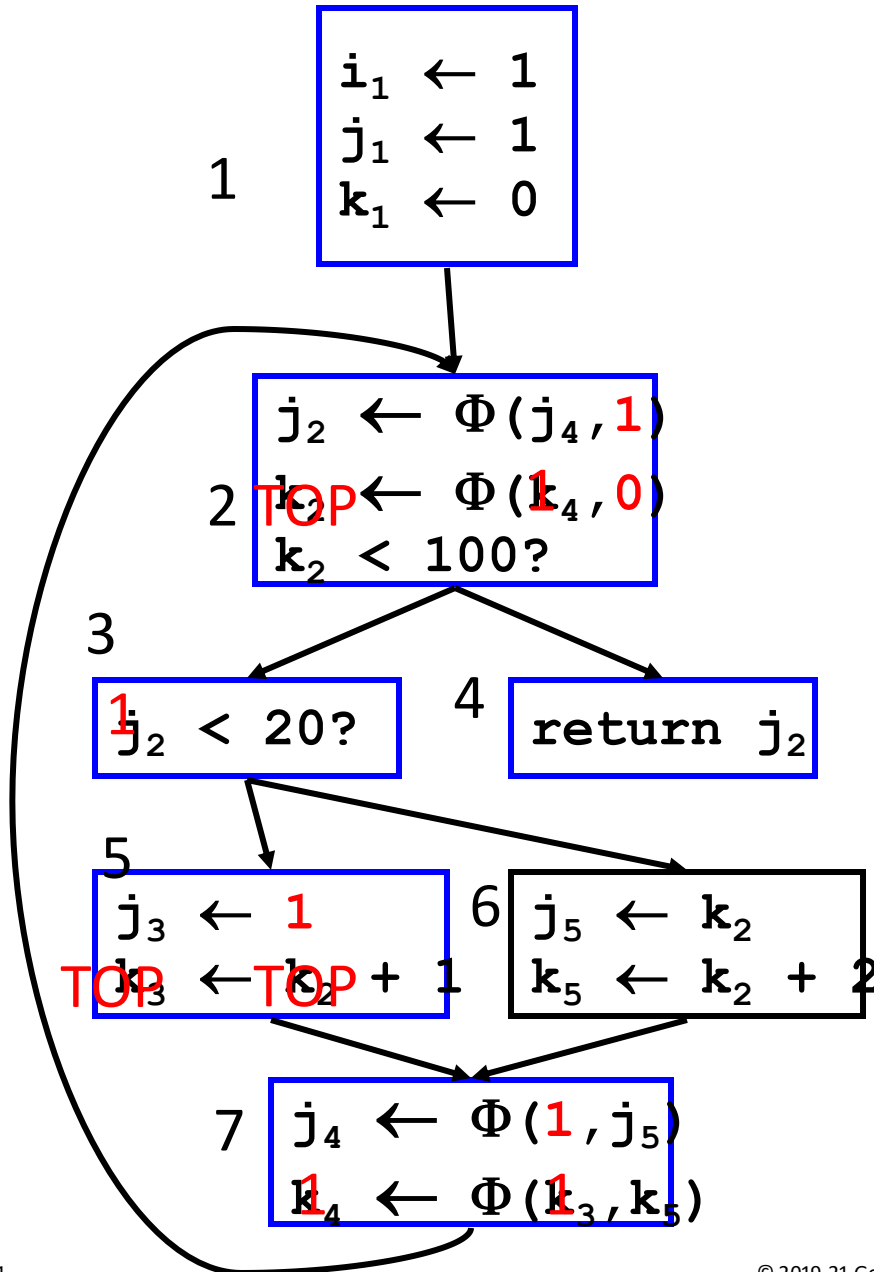
Conditional Constant Propagation



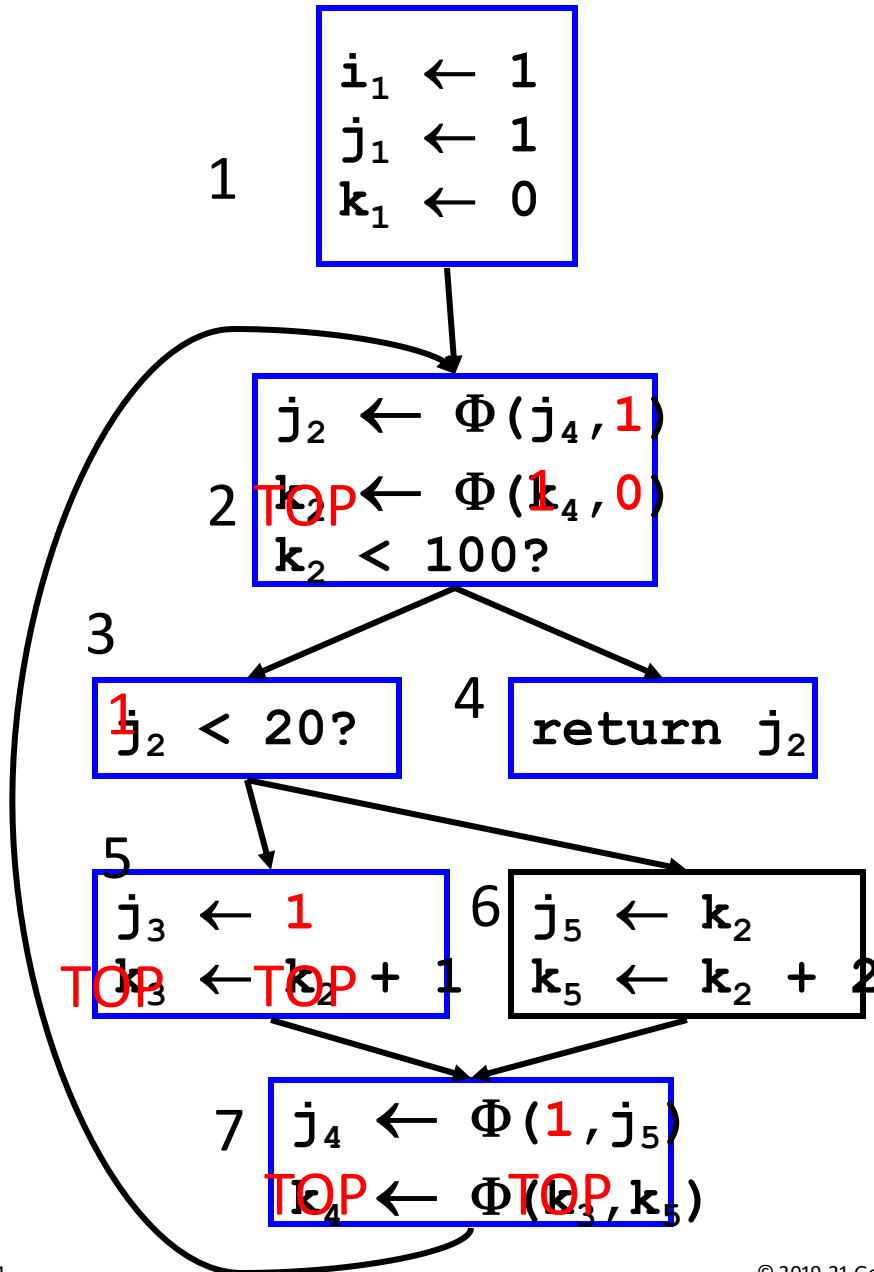
Conditional Constant Propagation



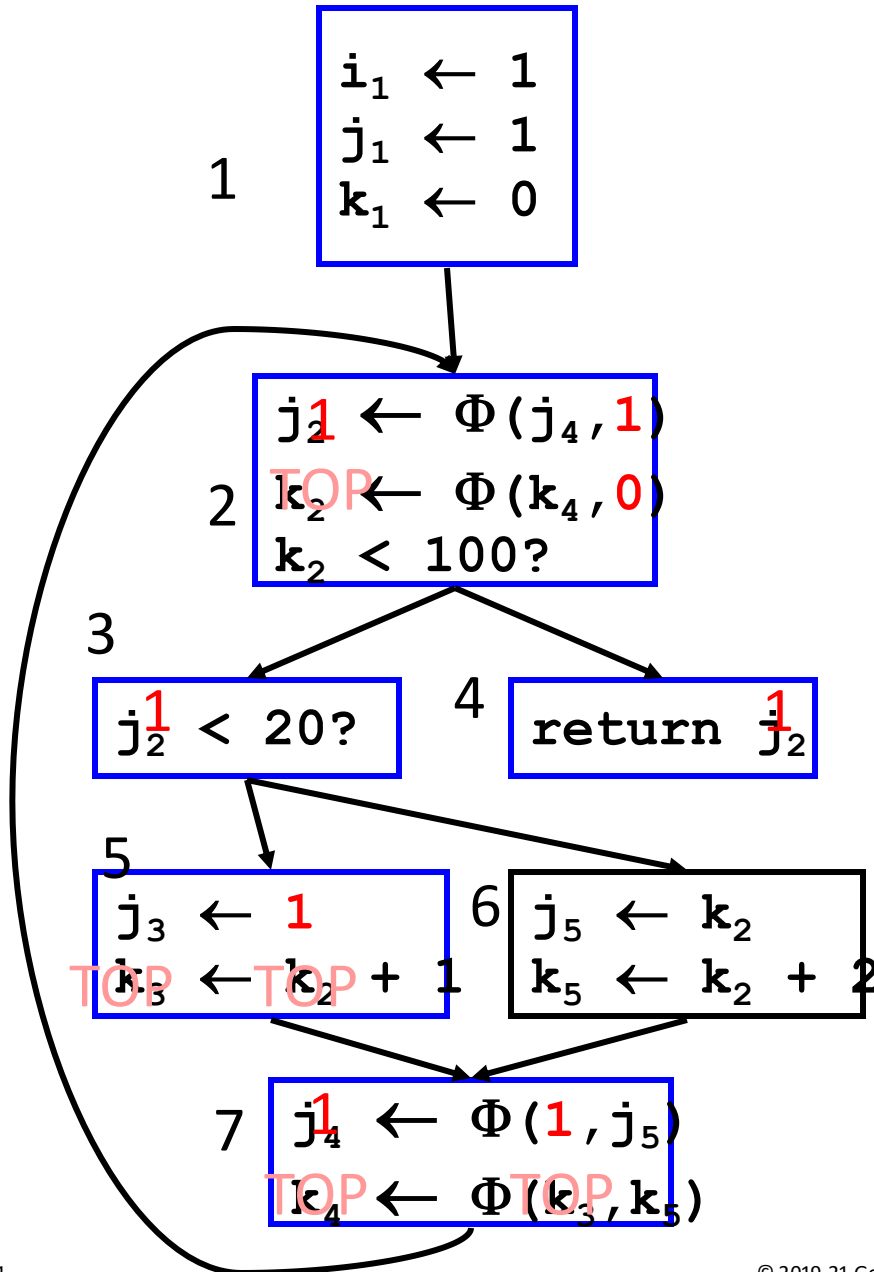
Conditional Constant Propagation



Conditional Constant Propagation

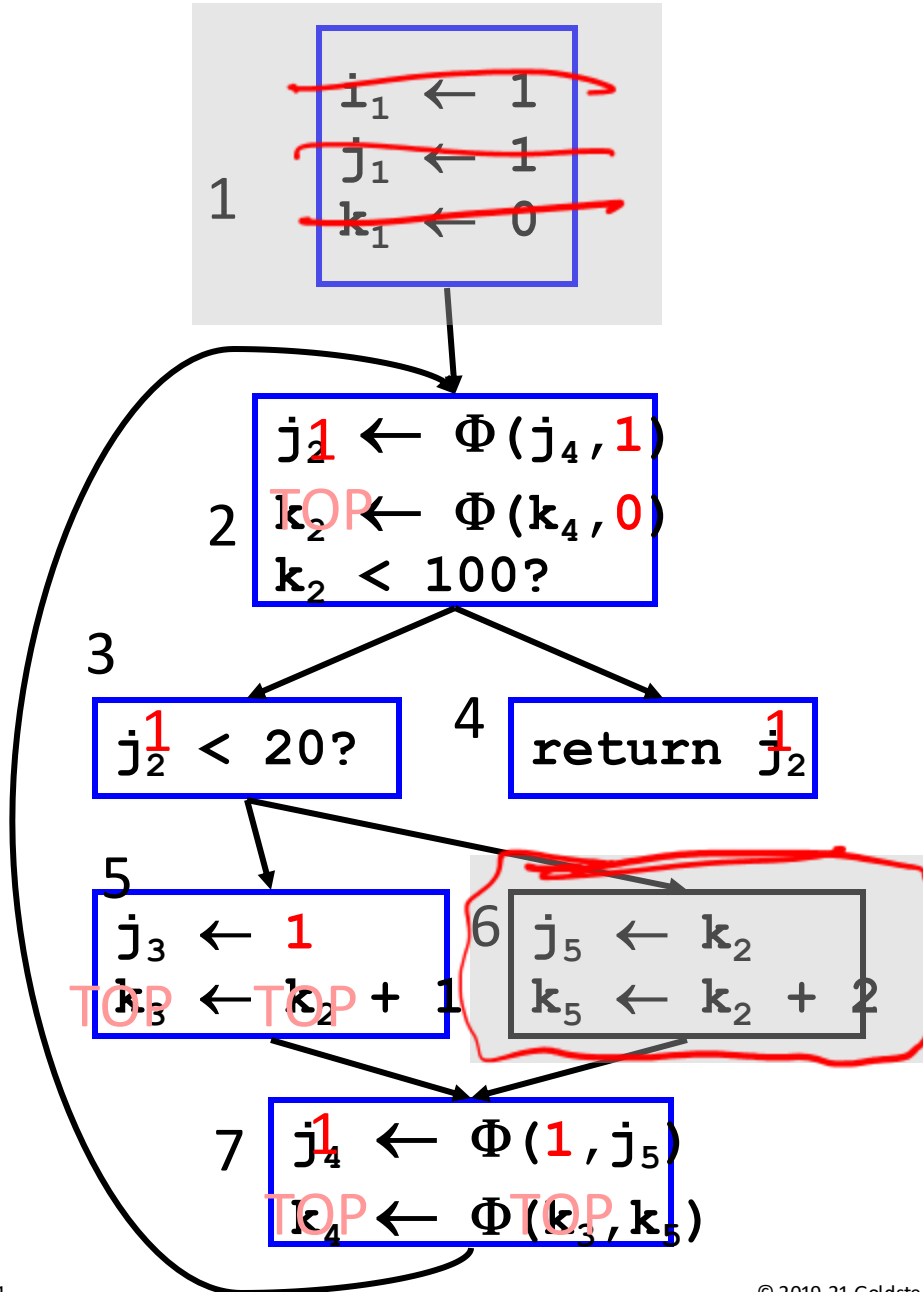


Conditional Constant Propagation



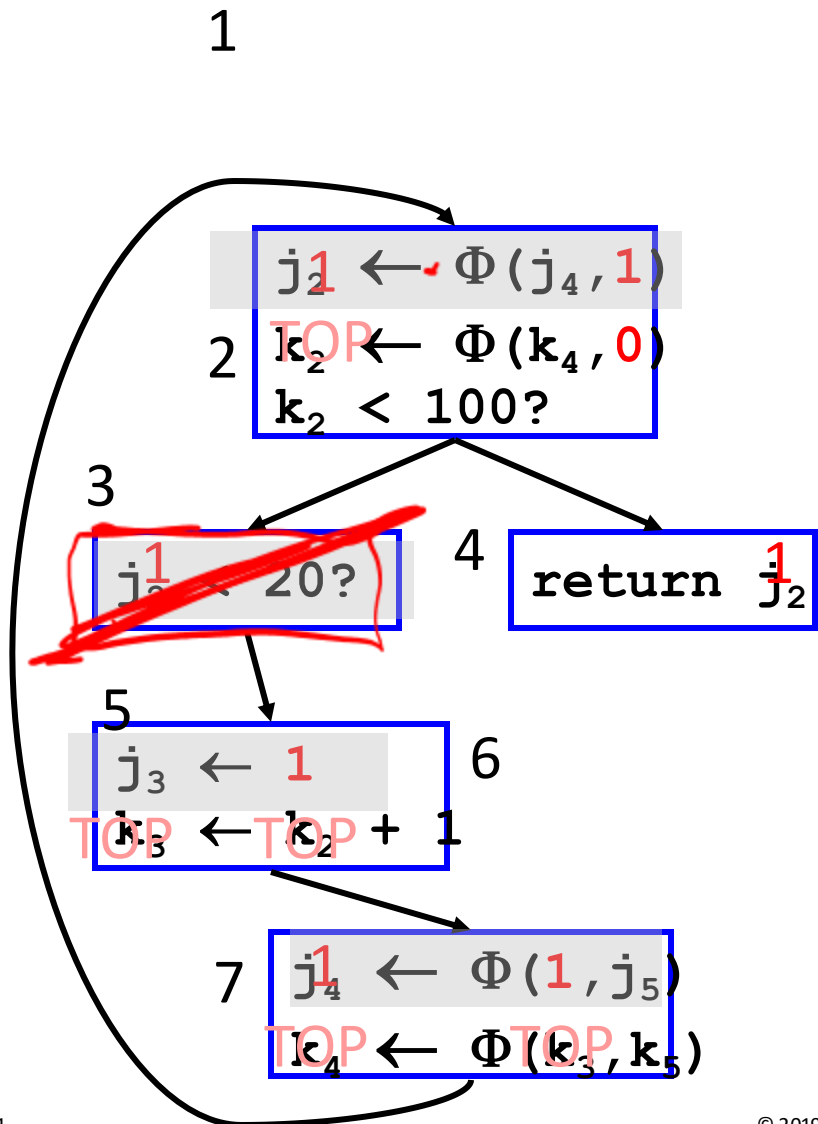
Now What?

Conditional Constant Propagation



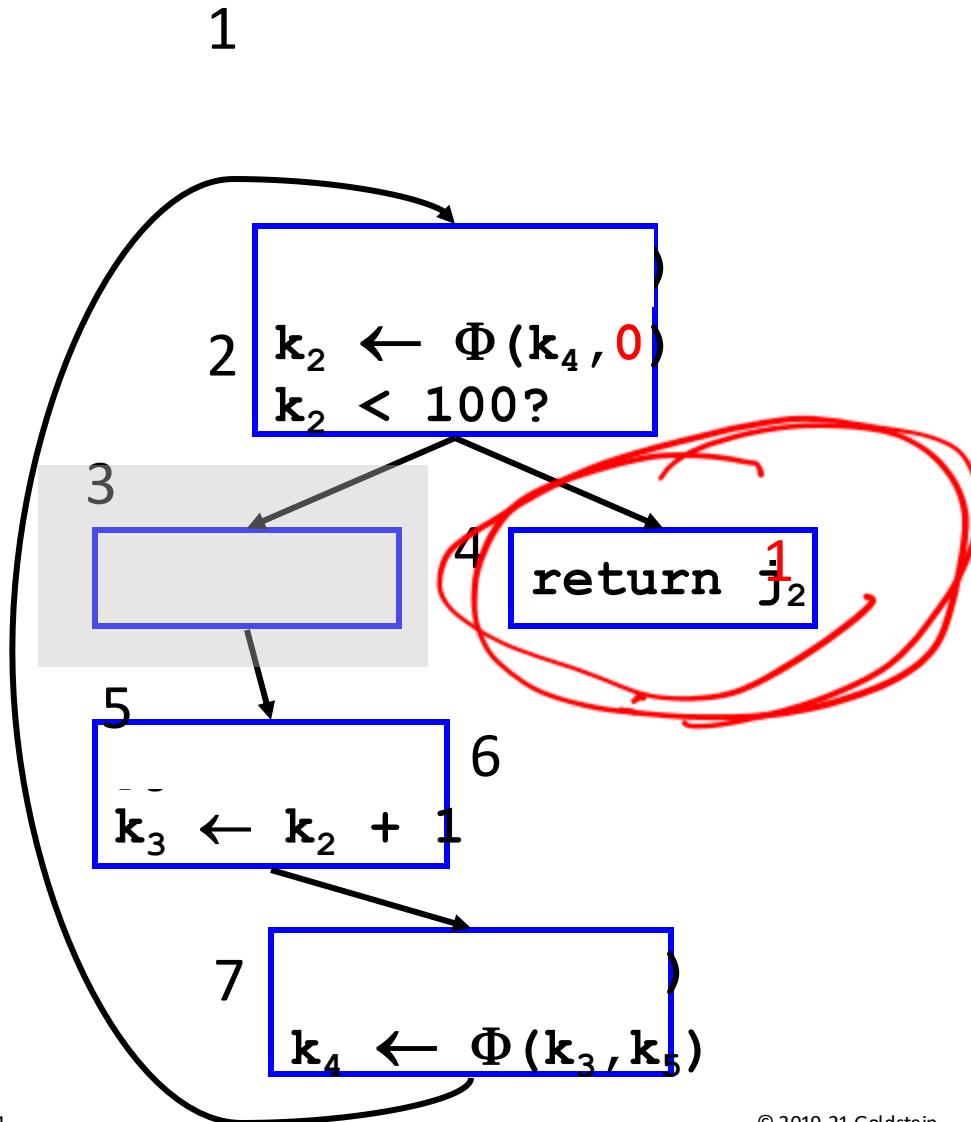
Now What?

Conditional Constant Propagation



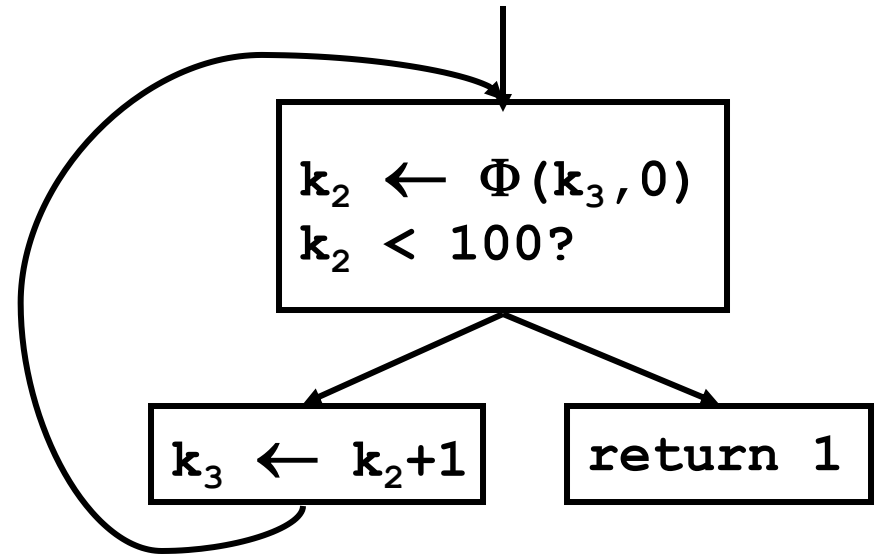
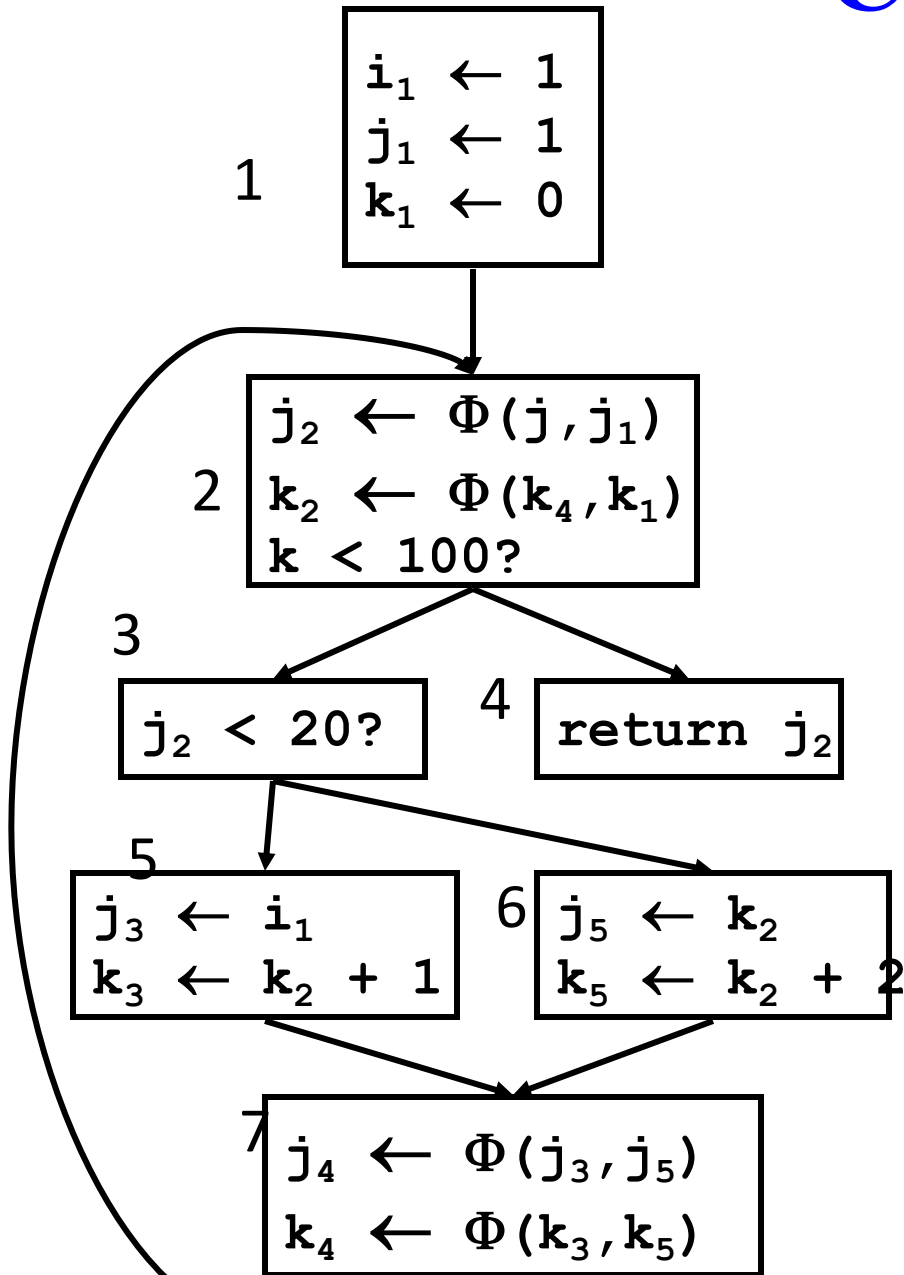
Now What?

Conditional Constant Propagation



Now What?

CCP



Just a taste of the kinds of optimizations that SSA enables.

ADCE

Dead Code Elimination

```
W <- list of all defs
```

```
while !W.isEmpty {
```

```
  Stmt S <- W.removeOne
```

```
  if |S.users| != 0 then continue
```

```
  if S.hasSideEffects() then continue
```

```
  foreach def in S.definers {
```

```
    def.users <- def.users - {S}
```

```
    if |def.users| == 0 then
```

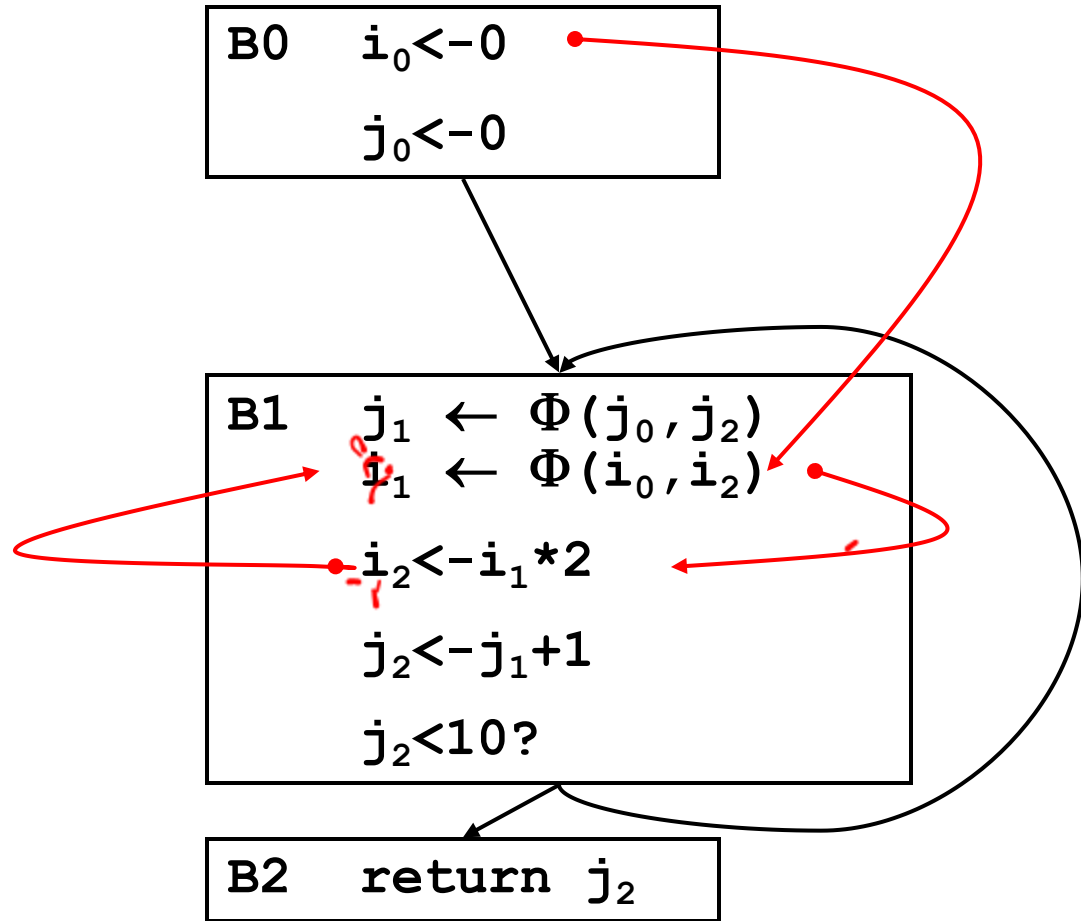
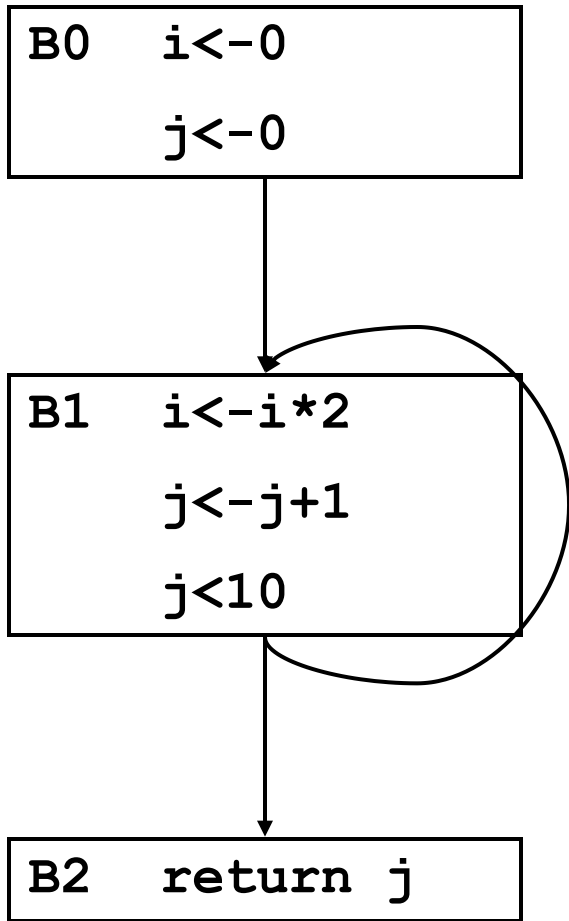
```
      W <- W UNION {def}
```

```
  }
```

```
}
```

Since we are using SSA, this is just a list of all variable assignments.

Example DCE



Standard DCE leaves Zombies!

Aggressive Dead Code Elimination

Assume a stmt is dead until proven otherwise.

init:

mark as live all stmts that have side-effects:

- I/O
- stores into memory
- returns
- calls a function that MIGHT have side-effects

As we mark S live, insert S.defs into W

```
while (|W| > 0) {  
  S <- W.removeOne()  
  if (S is live) continue;  
  mark S live, insert S.defs into W  
}
```

Example DCE

B0 $i_0 \leftarrow -0$
 ~~$j_0 \leftarrow -0$~~

B1 $j_1 \leftarrow \Phi(j_0, j_2)$
 $i_1 \leftarrow \Phi(i_0, i_2)$
 $i_2 \leftarrow -i_1 * 2$
 ~~$j_2 \leftarrow j_1 + 1$~~
 $j_2 < 10?$

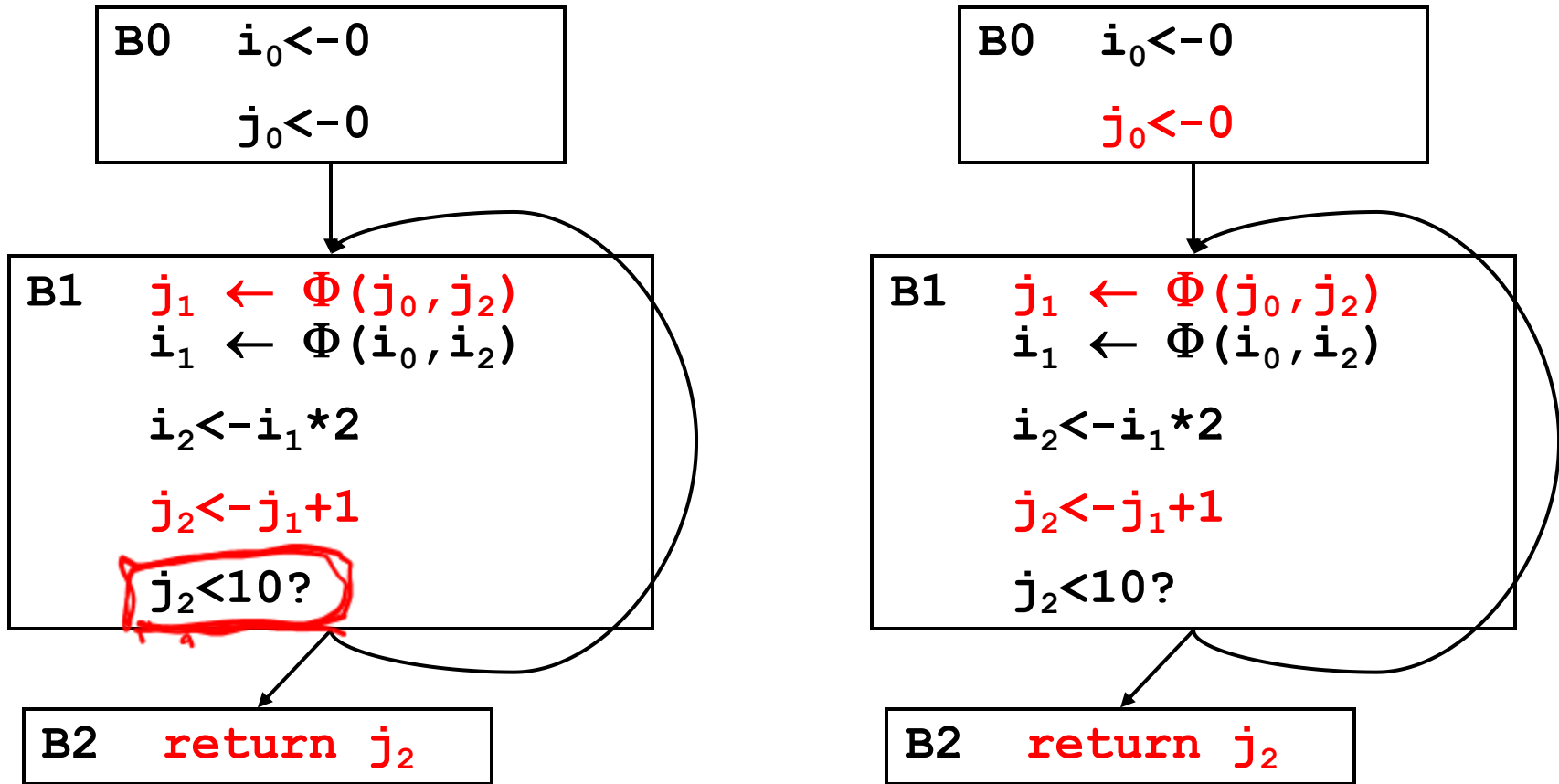
B2 ~~$\text{return } j_2$~~

B0 $i_0 \leftarrow -0$
 $j_0 \leftarrow -0$

B1 $j_1 \leftarrow \Phi(j_0, j_2)$
 $i_1 \leftarrow \Phi(i_0, i_2)$
 $i_2 \leftarrow -i_1 * 2$
 $j_2 \leftarrow j_1 + 1$
 $j_2 < 10?$

B2 $\text{return } j_2$

Example DCE

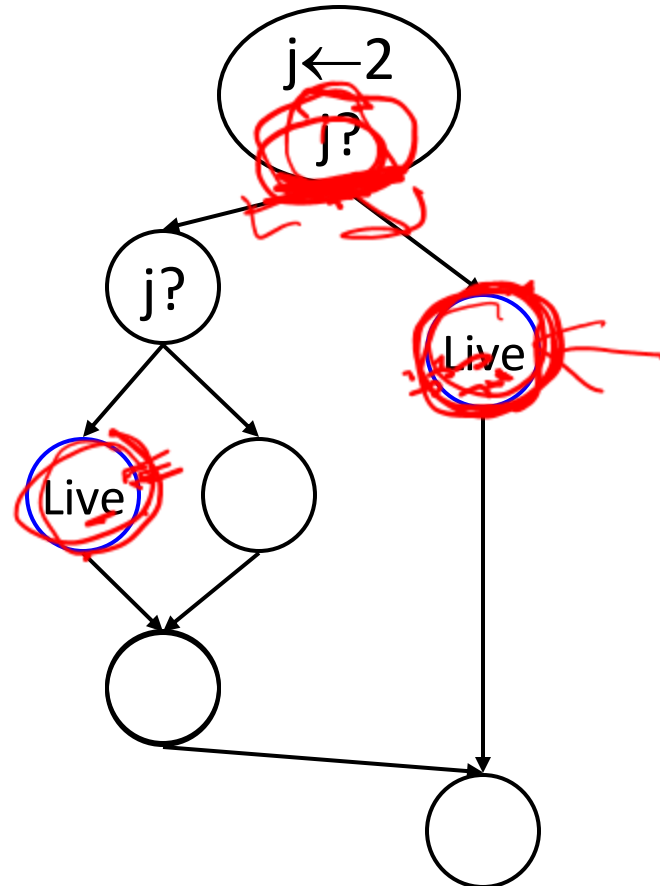


Problem!

Fixing ADCE

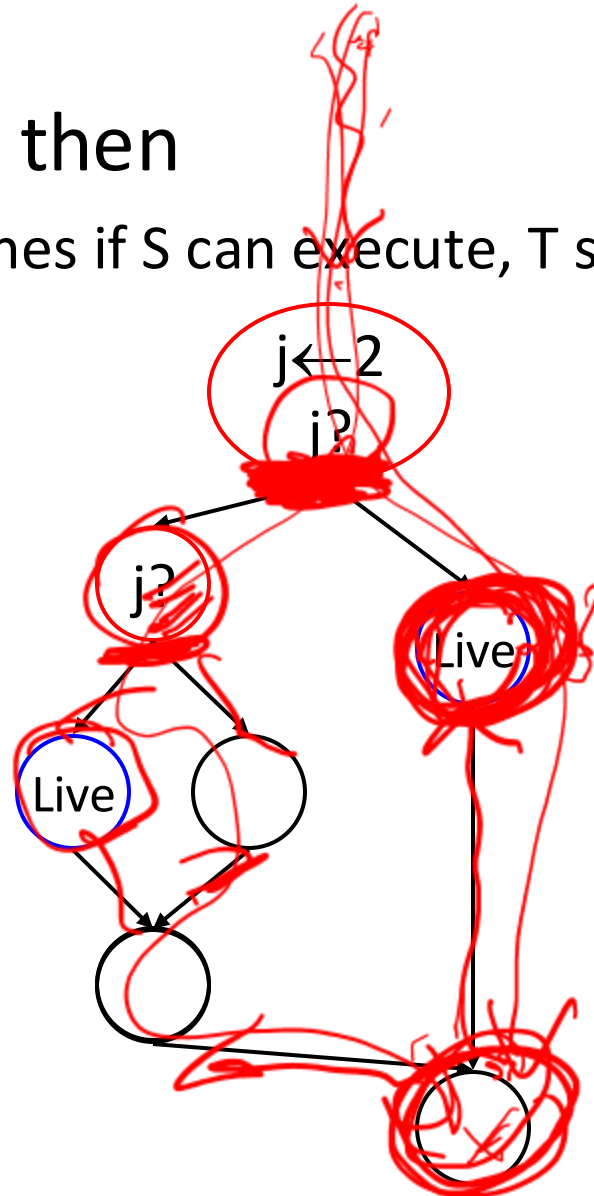
- If S is live, then

If T determines if S can execute, T should be live



Fixing DCE

- If S is live, then
If T determines if S can execute, T should be live

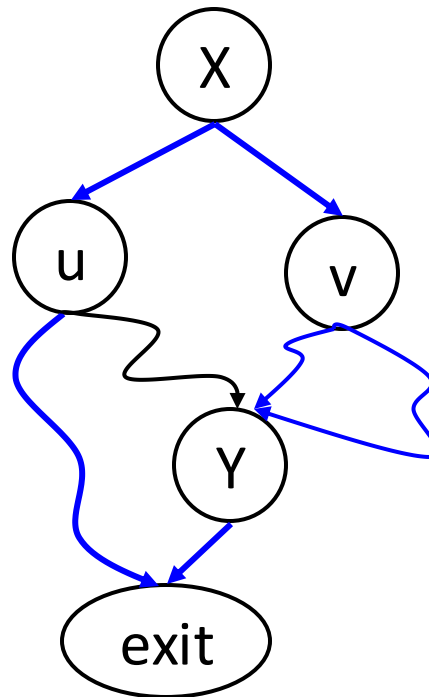


Control Dependence

Y is control-dependent on X if

- X branches to u and v
- \exists a path $u \rightarrow \text{exit}$ which does not go through Y
- \forall paths $v \rightarrow \text{exit}$ go through Y

IOW, X can determine whether or not Y is executed.

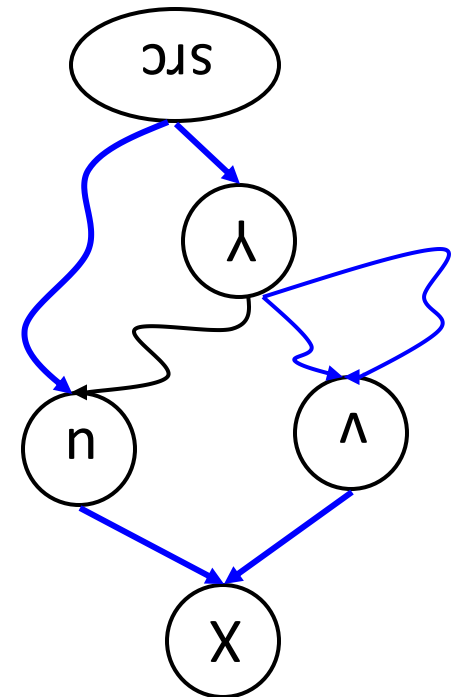
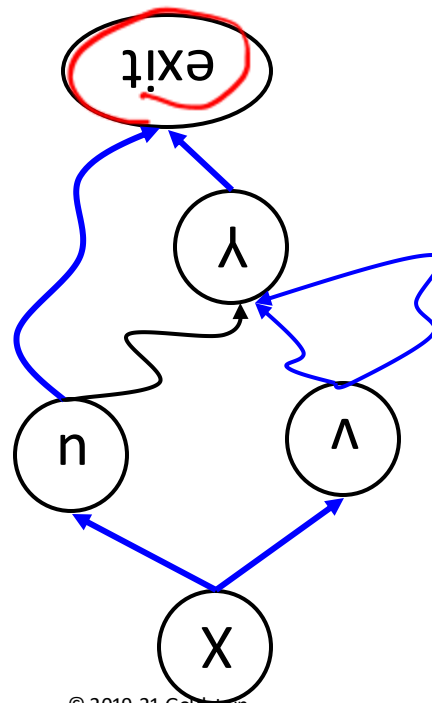
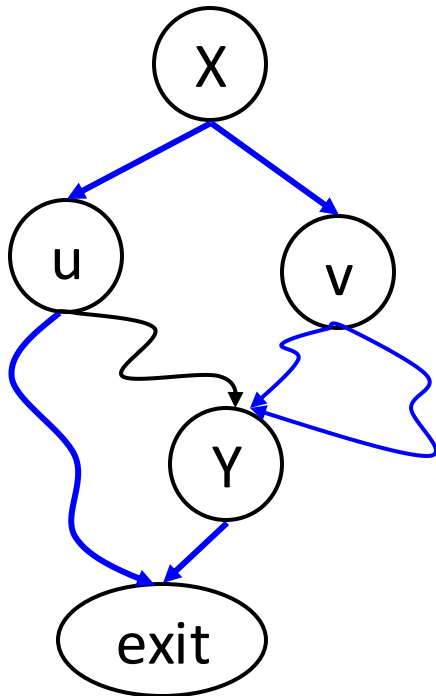


Finding the CDG

Y is control-dependent on X if

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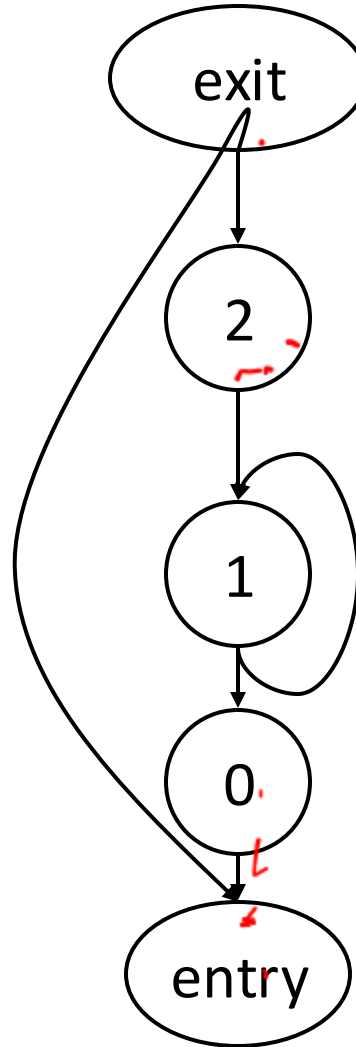
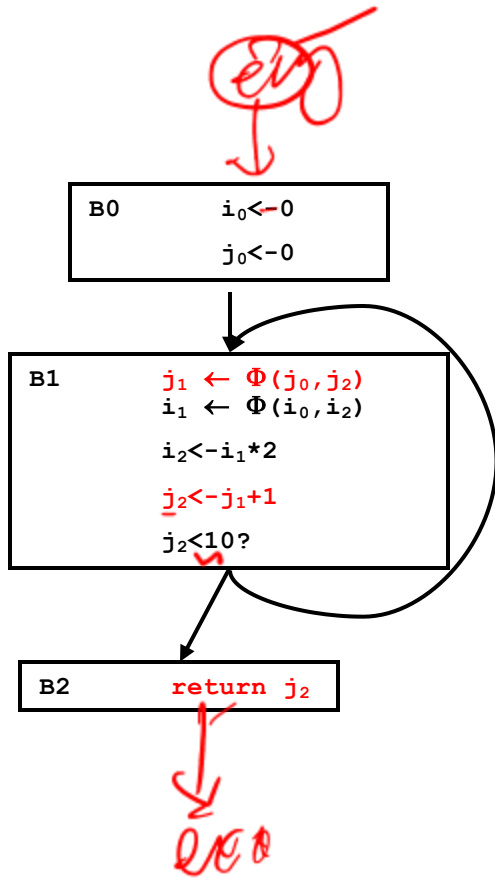
IOW, X can determine whether or not Y is executed.



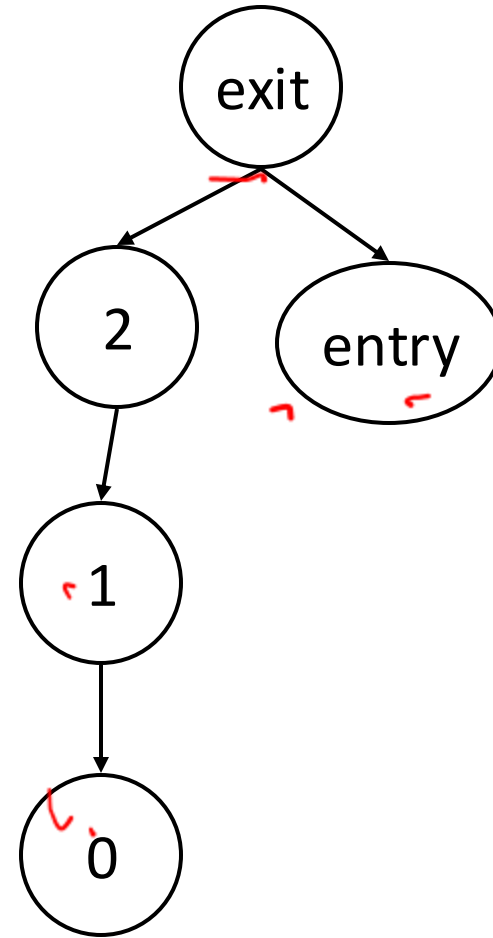
Finding the CDG

- Construct CFG
- Add entry node and exit node
- Add (entry,exit)
- Create G' , the reverse CFG
- Compute D-tree in G' (post-dominators of G)
- Compute $DF_{G'}(y)$ for all $y \in G'$ (post-DF of G)
- Add $(x,y) \in G$ to CDG if $x \in DF_{G'}(y)$

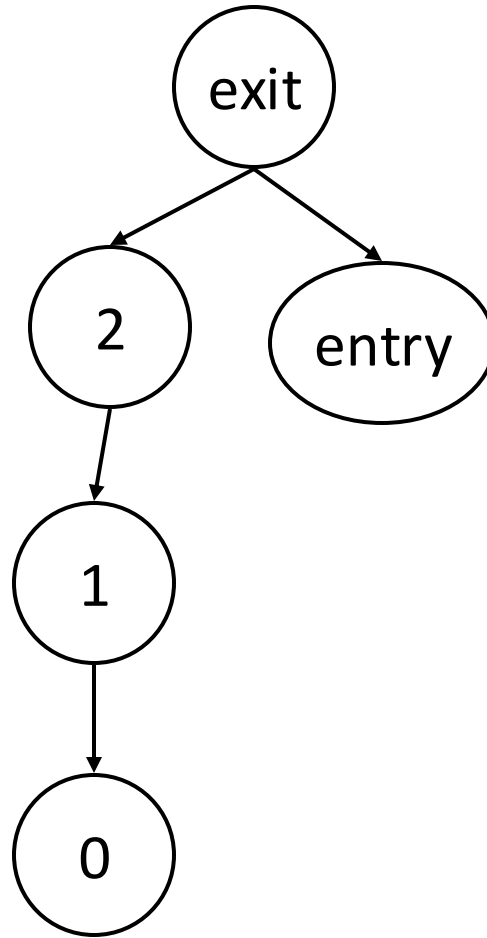
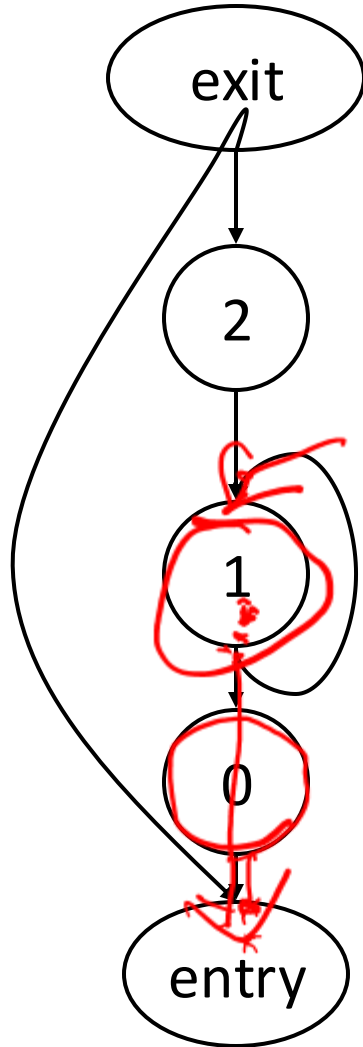
CDG of example



D-Tree



CDG of example



DF

exit: {}

2: {entry}

1: {1,entry}

0: {entry}

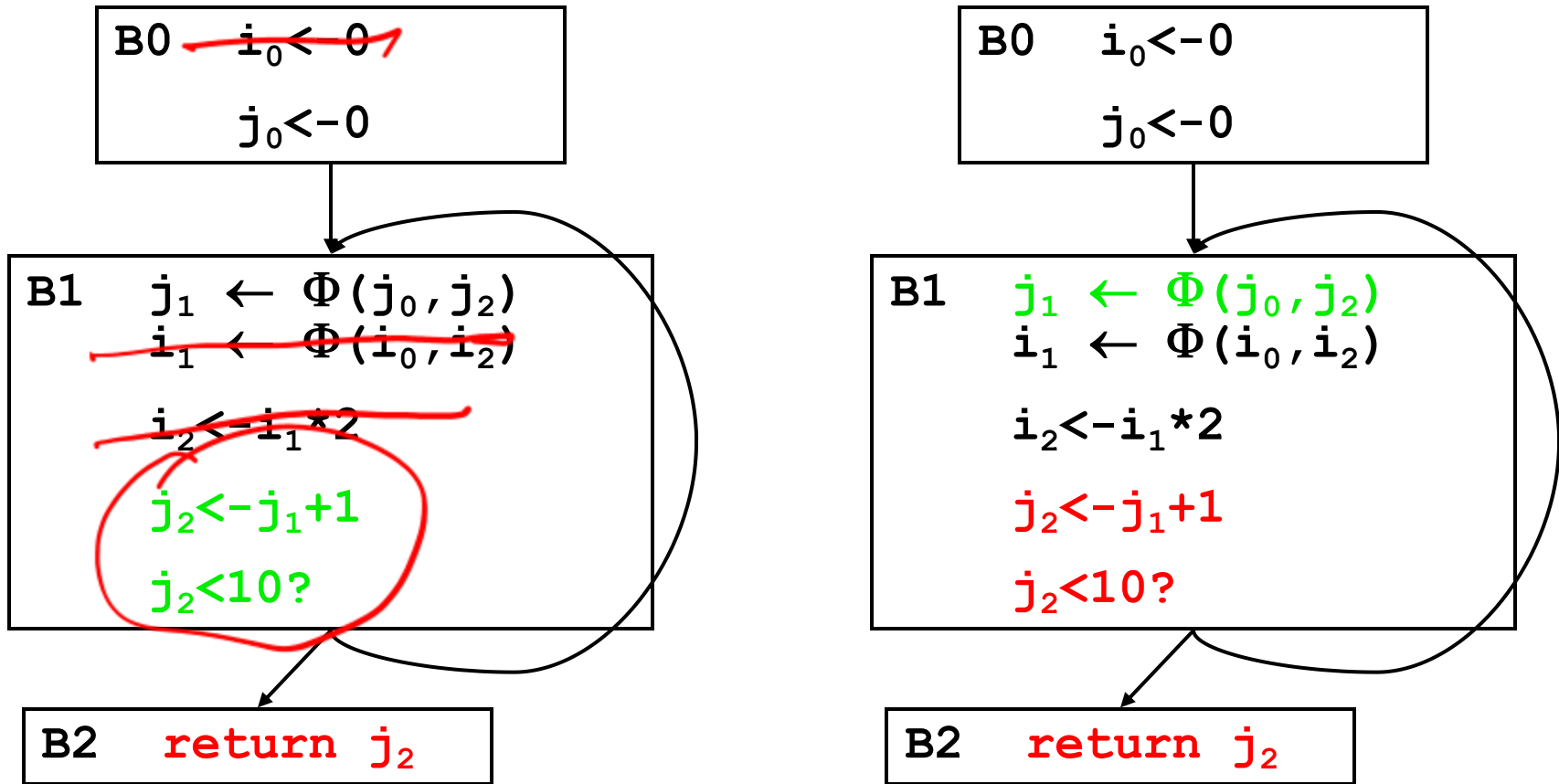
entry: {}

Aggressive Dead Code Elimination

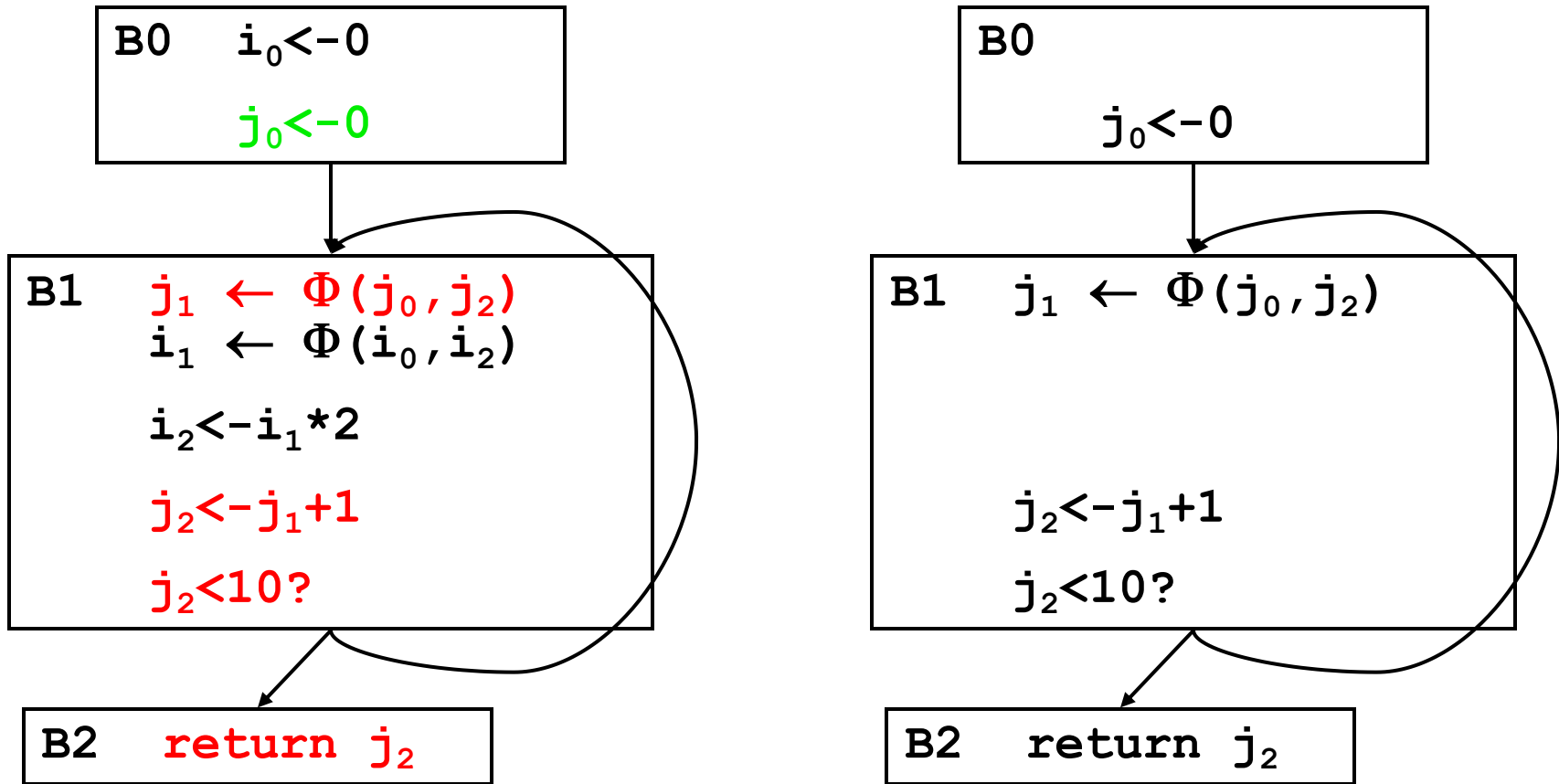
Assume a stmt is dead until proven otherwise.

```
while (|W| > 0) {  
  S <- W.removeOne()  
  if (S is live) continue;  
  mark S live, insert  
  - forall operands, S.operand.definers into W  
  - S.CD-1 into W  
}
```

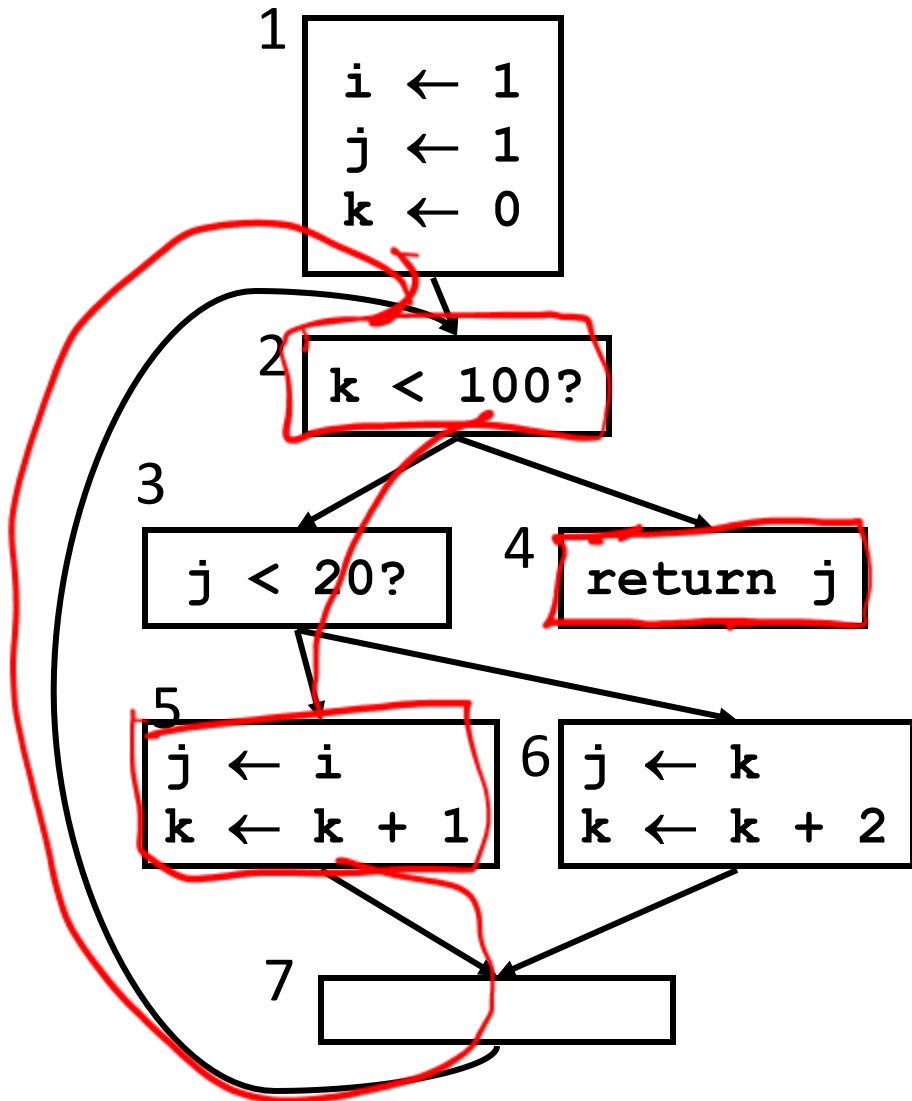
Example DCE



Example DCE

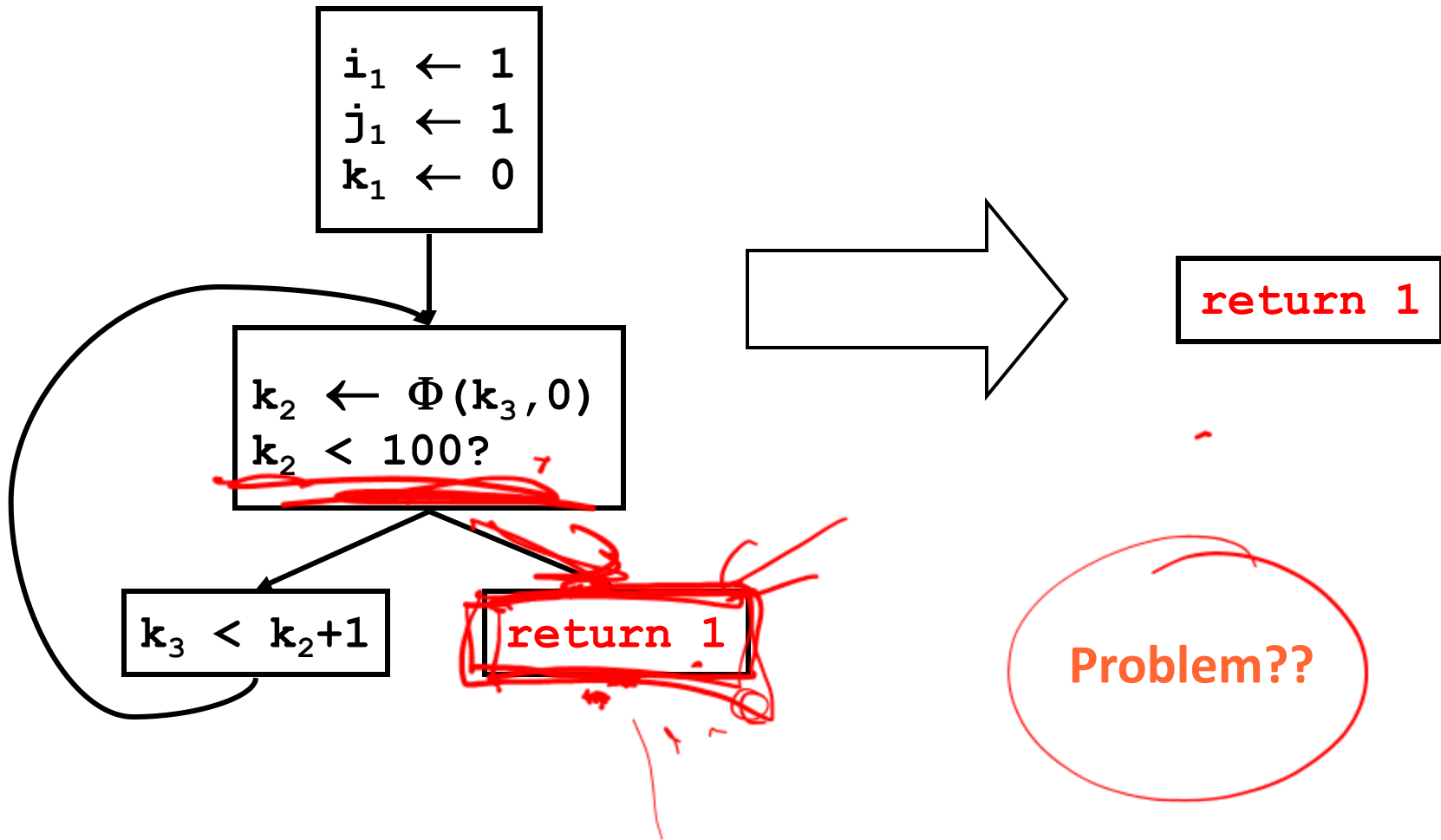


CCP Example



- Does block 6 ever execute?
- Simple CP can't tell
- CCP can tell:
 - Assumes blocks don't execute until proven otherwise
 - Assumes Values are constants until proven otherwise

CCP -> DCE



Some Peephole Optimizations

- Constant Folding
- Strength Reduction
- Null Sequence Elimination
- ... (hundreds and hundreds of these)

Constant Folding

$x \leftarrow C_1 \oplus C_2 \Rightarrow x \leftarrow C_3$ where $C_3 = C_1 \oplus C_2$

\oplus \oplus \oplus \Rightarrow raise warning

~~if \oplus then goto L1 else goto L2~~

can/feat

goto L1 ~ goto L2

?

Strength Reduction (AKA Algebraic Simplification)

$$\begin{array}{l}
 \cancel{a \neq 1} \quad a \\
 \hline
 a \neq \emptyset \quad \emptyset \\
 \hline
 a \neq 2^n \quad \underline{a \ll n} \\
 \hline
 \boxed{a / 2^n} \neq a \gg n \\
 \hline
 \boxed{a \neq 2^n + C_1 \Rightarrow \text{LEAF}}
 \end{array}$$

Null Sequence Elimination

~~X ← 0~~



movl leaf, leaf



Today

- What is a loop?
- Control Flow Analysis
- Finding Loops
- Natural Loops
- Reducibility
- Classic Loop Optimizations
 - LICM
 - Induction Variable Elimination

Common loop optimizations

- Hoisting of loop-invariant computations
 - pre-compute before entering the loop
- Elimination of induction variables
 - change $p=i*w+b$ to $p=b, p+=w$, when w, b invariant
- Loop unrolling
 - to improve scheduling of the loop body

Scalar opts,
DF analysis,
Control flow
analysis

- Software pipelining
 - To improve scheduling of the loop body
- Loop permutation
 - to improve cache memory performance

Requires
understanding
data
dependencies

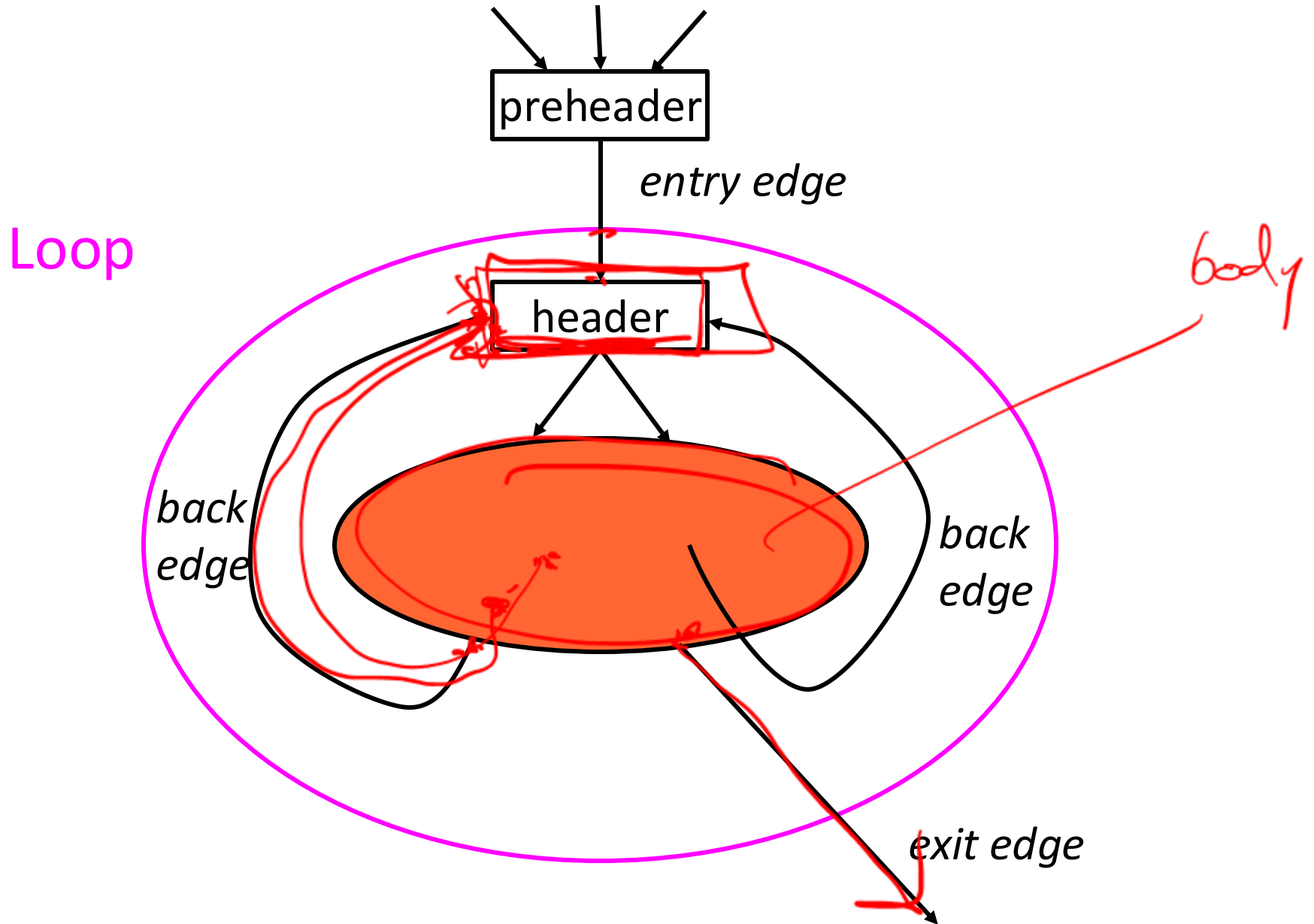
Loops are Key

- Loops are **extremely** important
 - the “90-10” rule
- Loop optimization involves
 - understanding control-flow structure
 - Understanding data-dependence information
 - sensitivity to side-effecting operations
 - extra care in some transformations such as register spilling

Finding Loops

- To optimize loops, we need to find them!
- Could use source language loop information in the abstract syntax tree...
- **BUT:**
 - There are multiple source loop constructs: for, while, do-while, even goto in C
 - Want IR to support different languages
 - Ideally, we want a single concept of a loop so all have same analysis, same optimizations
 - **Solution:** dismantle source-level constructs, then re-find loops from fundamentals

A Loop

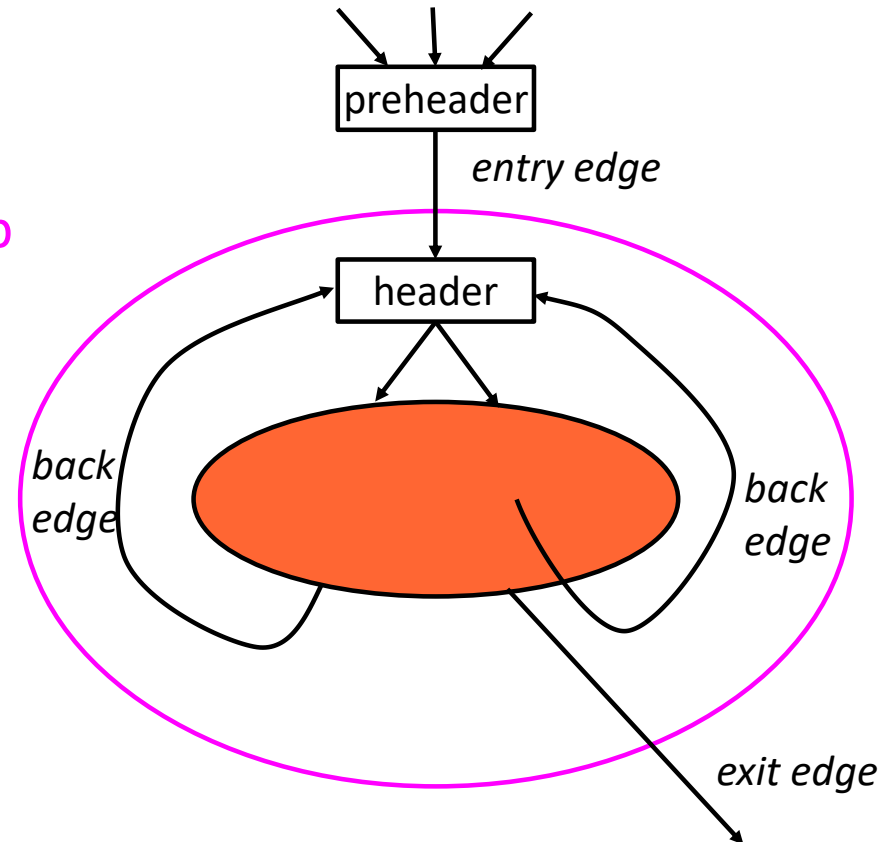


Loop Terminology

Loop: Strongly Connected Component of CFG



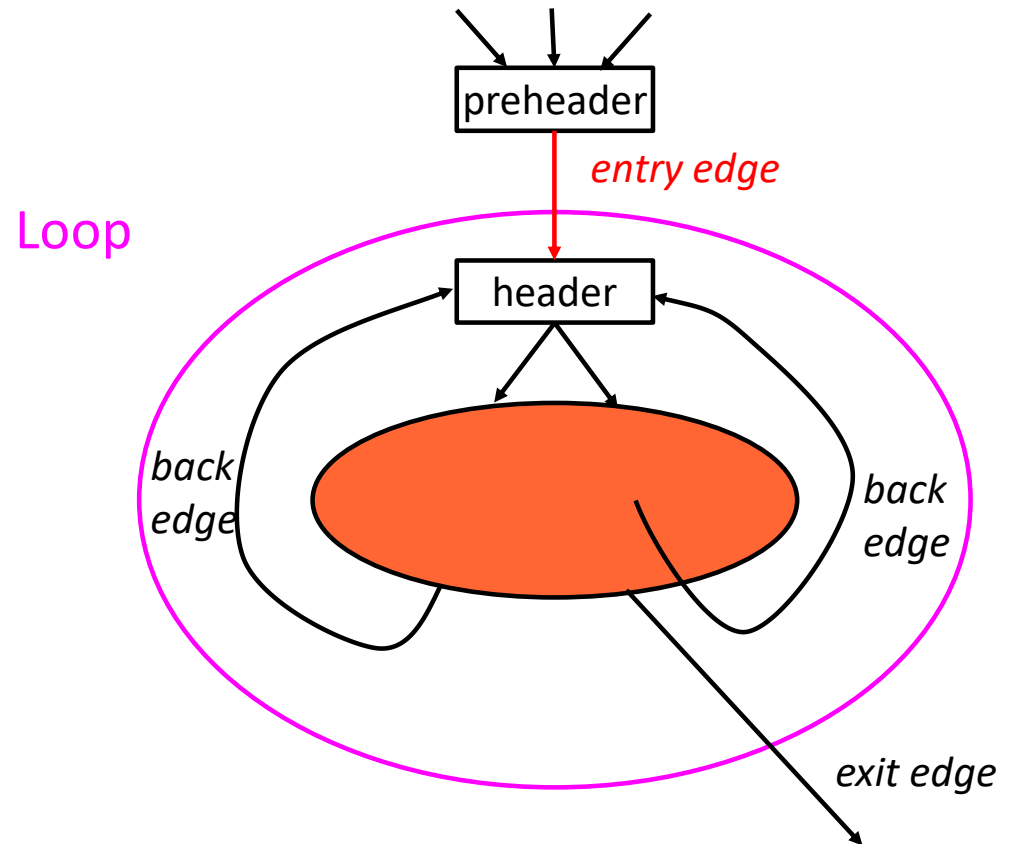
Loop



Loop Terminology

Loop: Strongly Connected Component of CFG

Entry Edge: tail not in loop, head in loop.

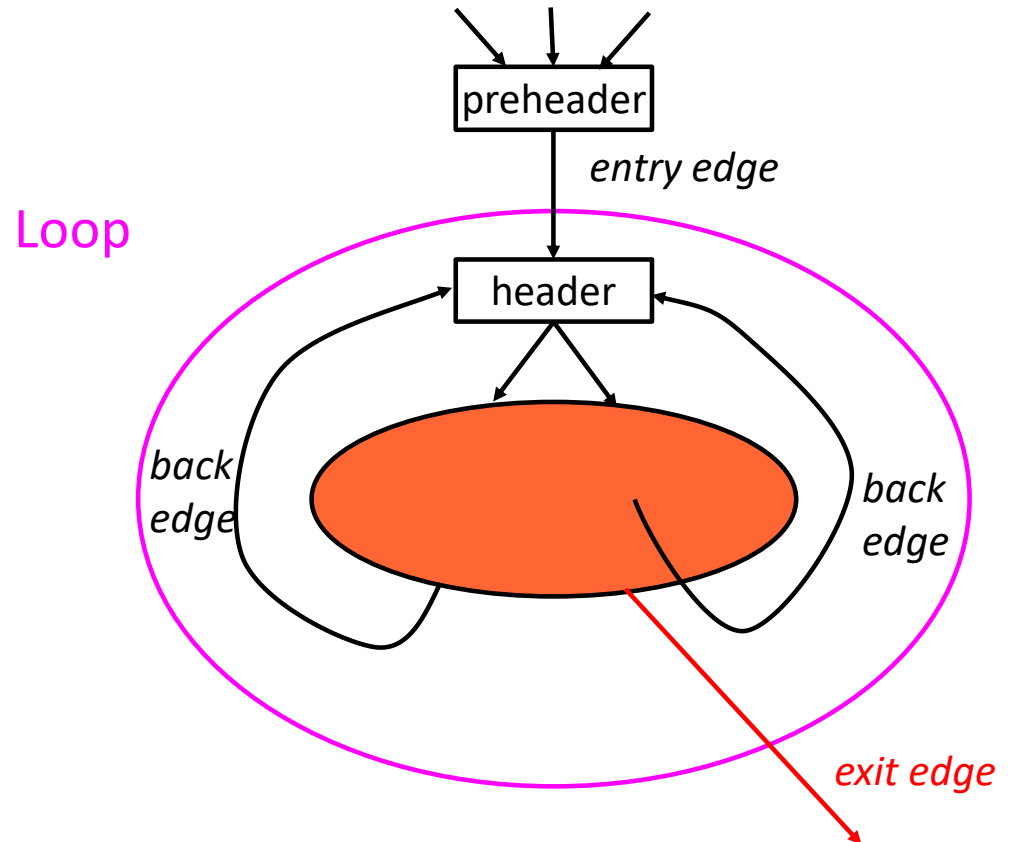


Loop Terminology

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Entry Edge: tail not in loop, head in loop.

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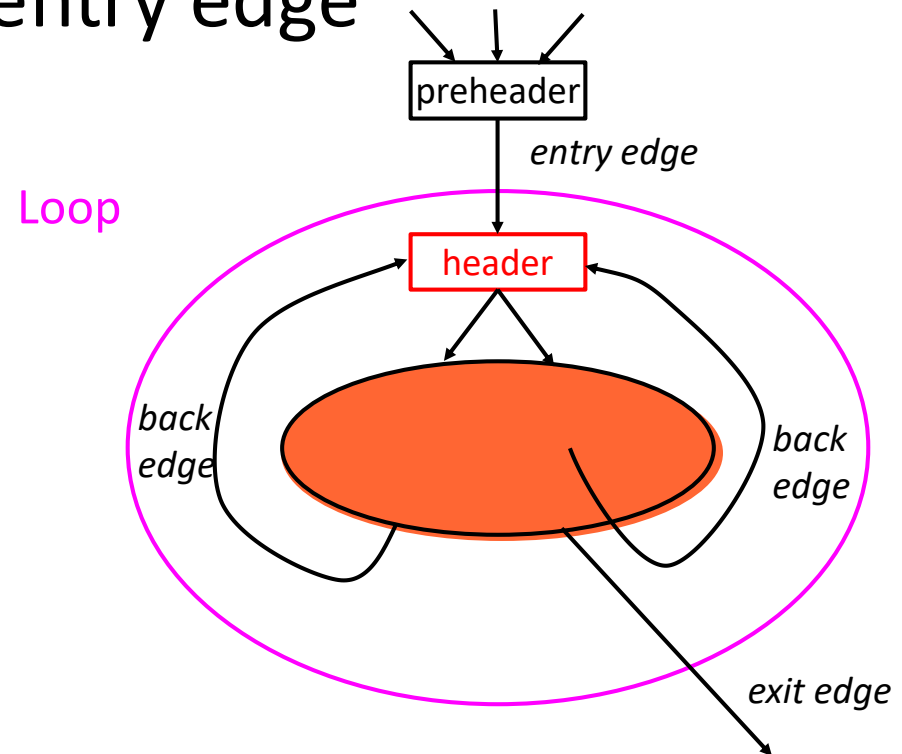
Loop Terminology

Loop: Strongly Connected Component of CFG

Entry Edge: tail not in loop, head in loop.

Exit edge: tail in loop, head not in loop

Loop Header: target of entry edge



Loop Terminology

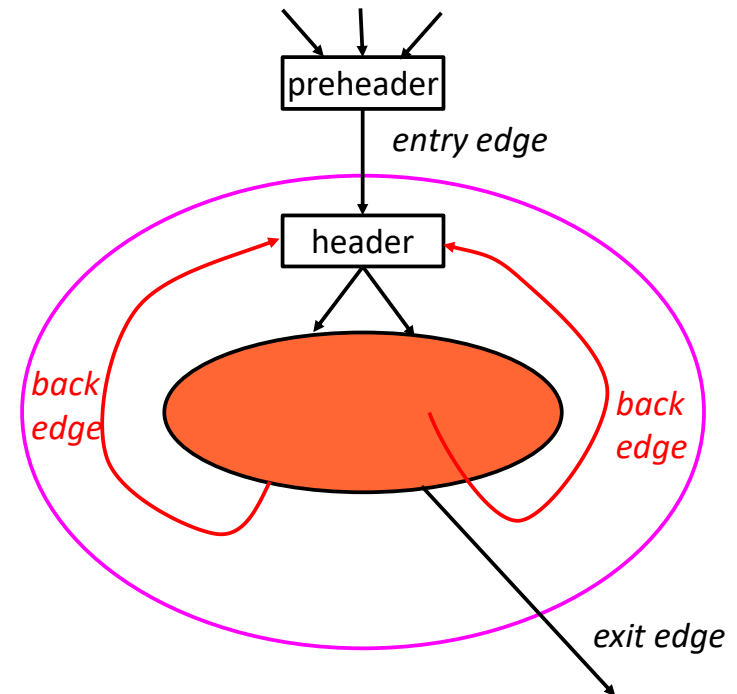
Loop: Strongly Connected Component of CFG

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Back Edge: target is header,
source is in loop



Loop Terminology

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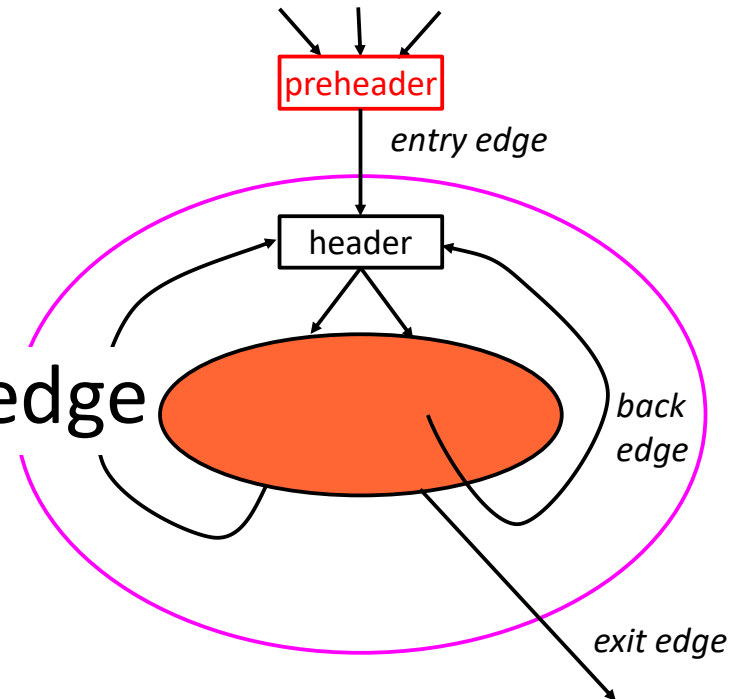
Exit edge: tail in loop, head not in loop

Loop Header: target of entry edge

Back Edge: target is header,
source is in loop

Preheader:

Source of the only entry edge



(You may have to add a preheader.)

Loop Terminology

Loop: Strongly Connected Component of CFG

Entry Edge: tail not in loop, head in loop.

Exit edge: tail in loop, head not in loop

Loop Header: target of entry edge

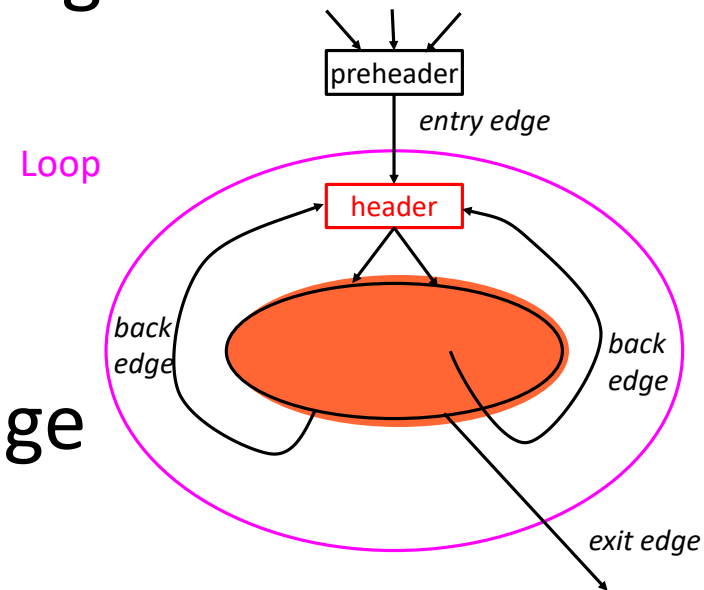
Back Edge: target is header,
source is in loop

Preheader:

Source of the only entry edge

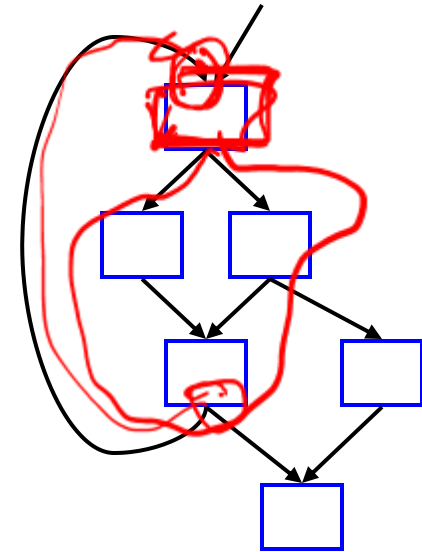
Natural Loop:

A Loop with only a single loop header



Finding Loops

- To optimize loops, we need to find them!
- Specifically:
 - loop-header node(s)
 - nodes in a loop that have immediate predecessors not in the loop
 - back edge(s)
 - control-flow edges to previously executed nodes
 - all nodes in the loop body



Control-flow analysis

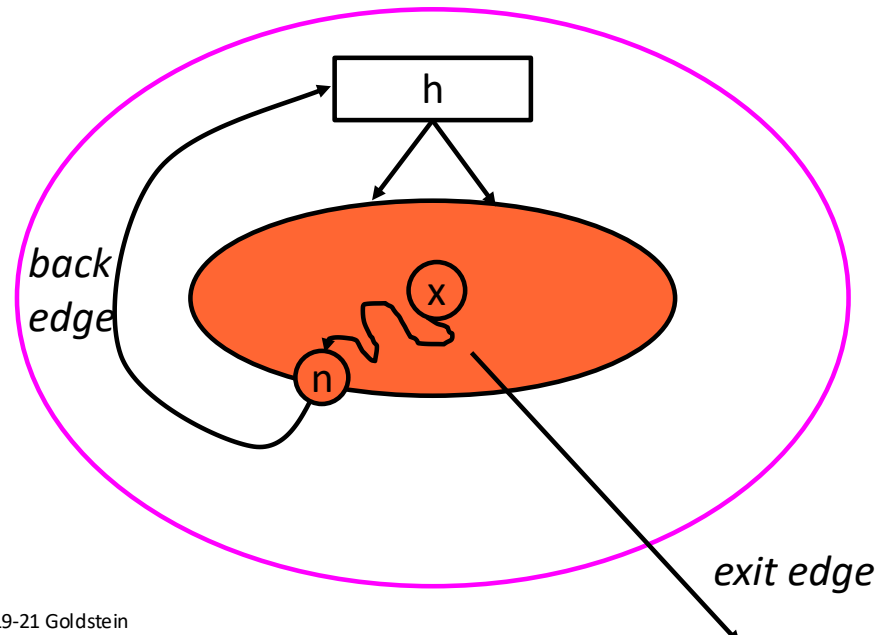
- Many languages have goto and other complex control, so loops can be hard to find in general
- Determining the control structure of a program is called **control-flow analysis**
- Based on the notion of **dominators**

Recall: Dominators

- $a \text{ dom } b$
 - node a dominates b if every possible execution path from entry to b includes a
- $a \text{ sdom } b$
 - a strictly dominates b if $a \text{ dom } b$ and $a \neq b$
- $a \text{ idom } b$
 - a immediately dominates b if $a \text{ sdom } b$, AND there is no c such that $a \text{ sdom } c$ and $c \text{ sdom } b$

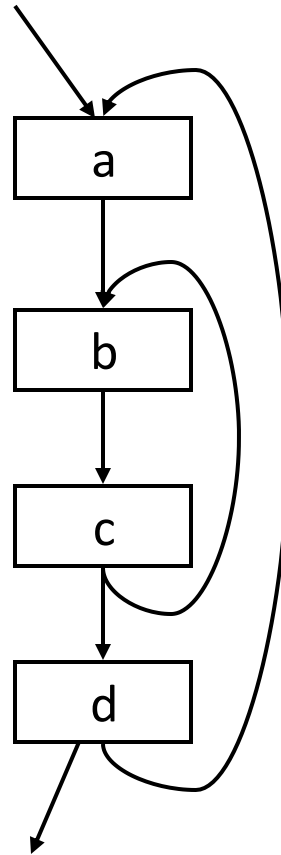
Natural loop

- Consider a back edge from node n to node h
- The natural loop of $n \rightarrow h$ is the set of nodes L such that for all $x \in L$:
 - $h \text{ dom } x$ and
 - there is a path from x to n not containing h



Examples

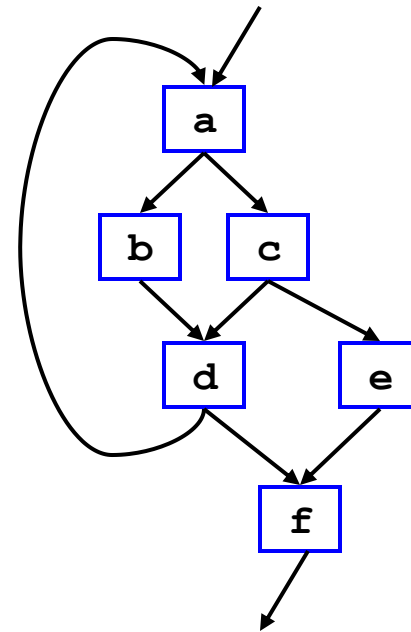
Simple example:



(often it's more complicated, since a FOR loop found in the source code might need an if/then guard)

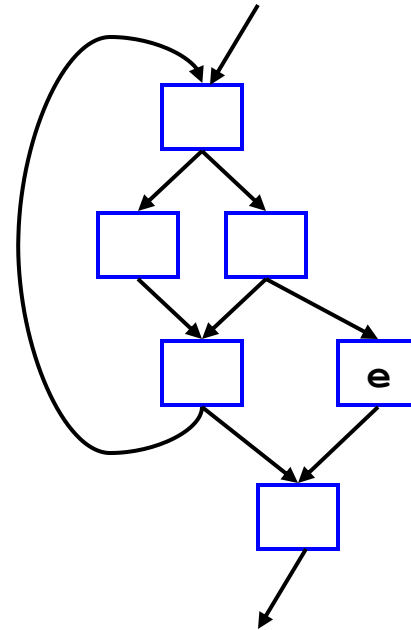
Examples

Try this:



Examples

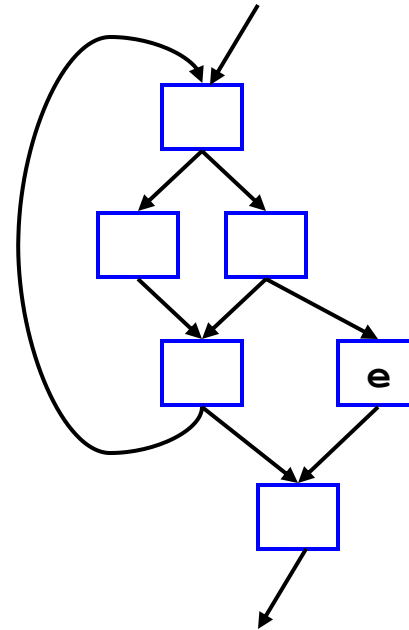
```
for (...) {  
  if {  
    ...  
  } else {  
    ...  
    if (x) {  
      e;  
      break;  
    }  
  }  
}
```



Examples

```
for (...) {  
  if {  
    ...  
  } else {  
    ...  
    if (x) {  
      e;  
      break;  
    }  
  }  
}
```

lexically, in loop,
but not in natural
loop

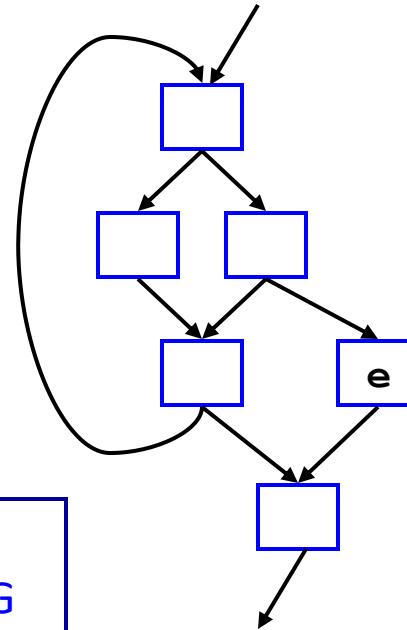


Examples

```
for (...) {  
  if {  
    ...  
  } else {  
    ...  
    if (x) {  
      e;  
      break;  
    }  
  }  
}
```

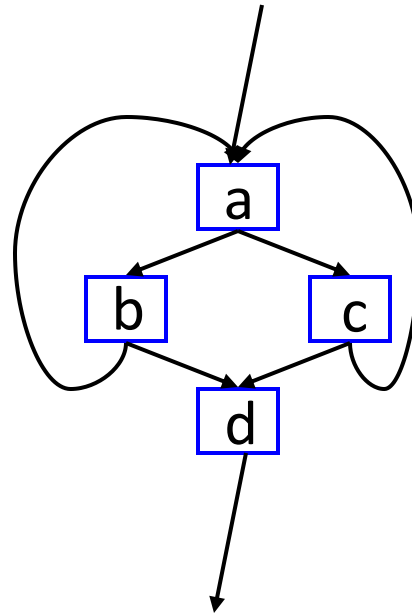
lexically, in loop,
but not in natural
loop

and another
reason why CFG
analysis is
preferred over
source/AST loops



Examples

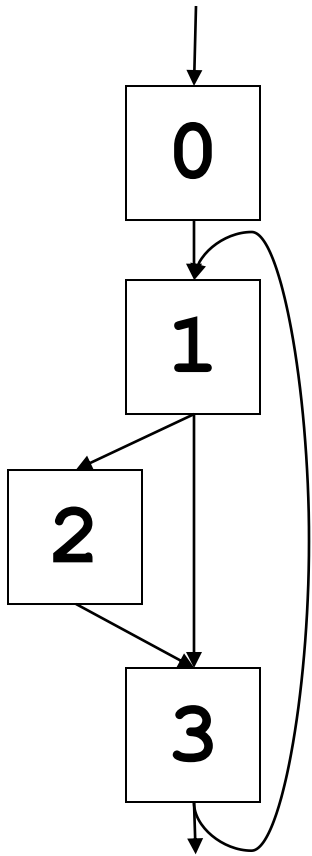
- Yes, it can happen in C



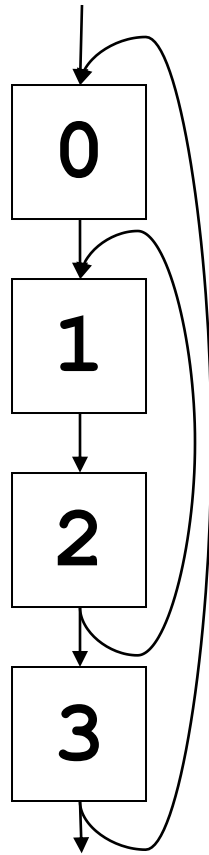
Natural Loops

One loop per header..

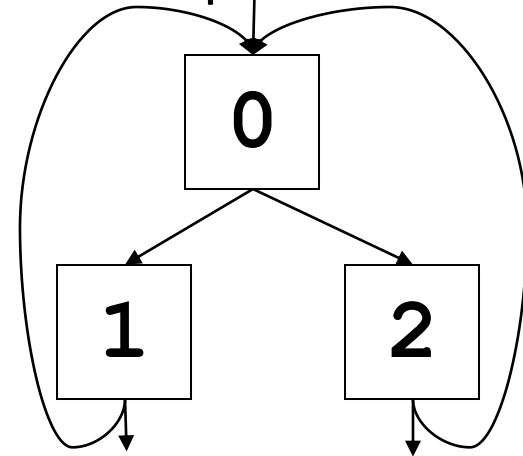
What are the natural loops?



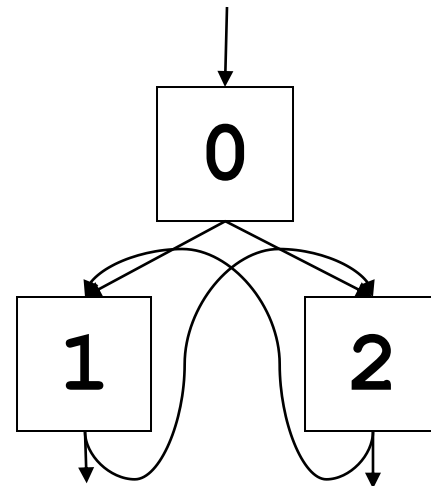
$\{1, 2, 3\}$



$\{1, 2\}, \{0, 1, 2, 3\}$



$\{0, 1, 2\}$



$\{\}$

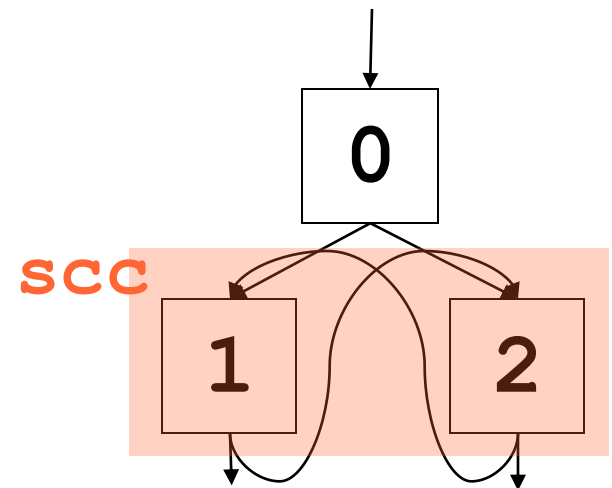
Nested Loops

- Unless two natural loops have the same header, they are either disjoint or **nested** within each other
- If **A** and **B** are loops (sets of blocks) with headers **a** and **b** such that $a \neq b$ and $b \in A$
 - $B \subset A$
 - loop **B** is *nested* within **A**
 - **B** is the *inner loop*
- Can compute the loop-nest tree

General Loops

- A more general looping structure is a *strongly connected component* of the control flow graph
 - subgraph $\langle N_{\text{SCC}}, E_{\text{SCC}} \rangle$ such that

every block in N_{SCC} is reachable from every other node using only edges in E_{SCC}



Not very useful definition of a loop

Reducible Flow Graphs

There is a special class of flow graphs, called **reducible flow graphs**, for which several code-optimizations are especially easy to perform.

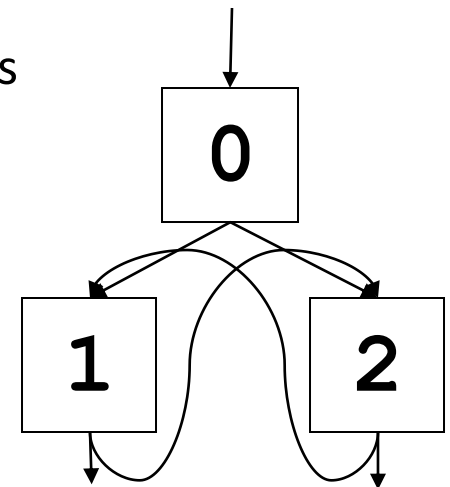
In reducible flow graphs **loops are unambiguously defined and dominators can be efficiently computed.**

Reducible flow graphs

Definition: A flow graph G is **reducible** iff we can partition the edges into two disjoint groups, **forward edges** and **back edges**, with the following two properties.

1. The forward edges form an acyclic graph in which every node can be reached from the initial node of G .
2. The back edges consist only of edges whose heads dominate their tails.

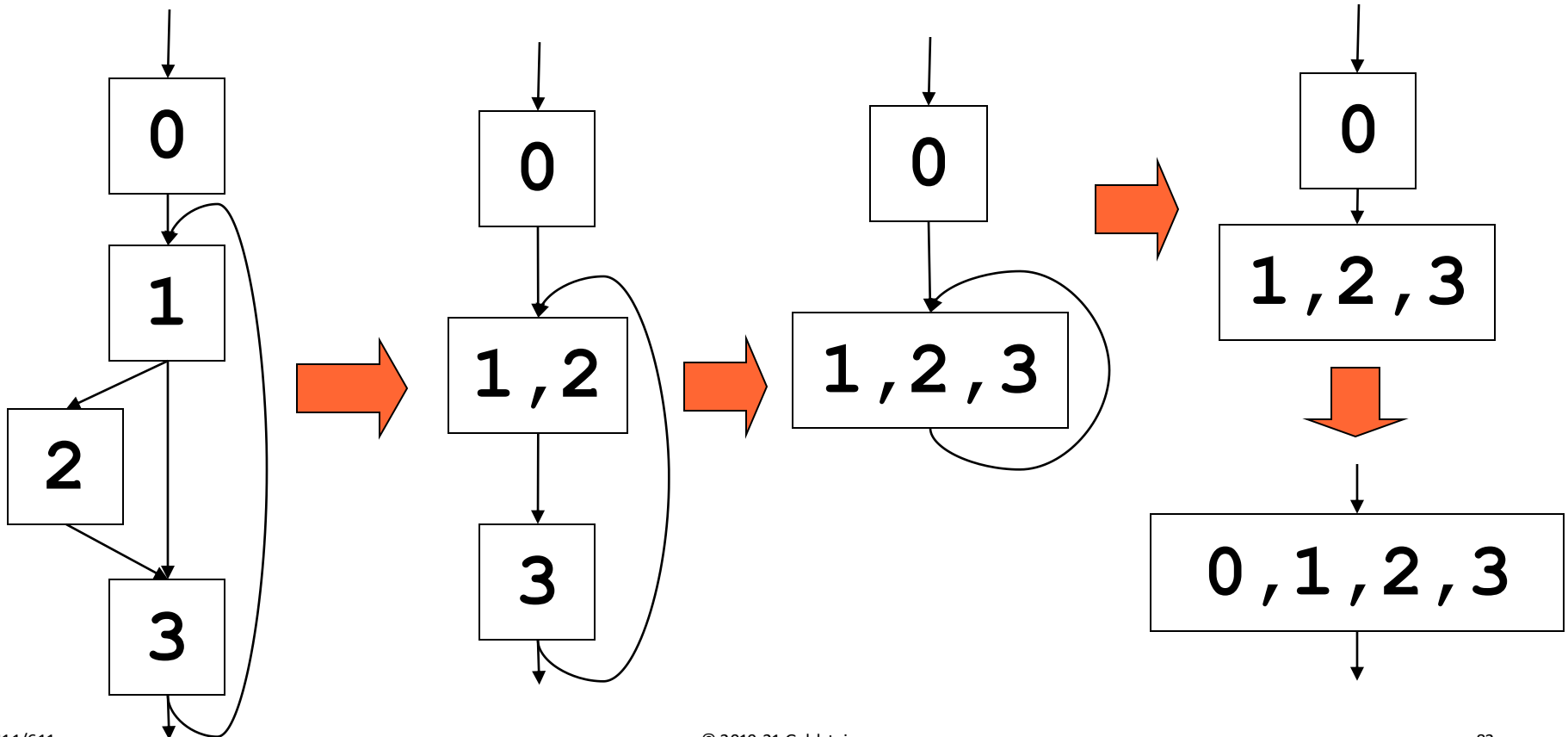
Why isn't this reducible?



*This flow graph has **no back edges**. Thus, it would be reducible if the entire graph were acyclic, which is not the case.*

Alternative definition

- **Definition:** A flow graph G is **reducible** if we can repeatedly collapse (reduce) together blocks (x,y) where x is the only predecessor of y (ignoring self loops) until we are left with a single node



Good News

- Most flow graphs are reducible
- Languages prohibit irreducibility
 - goto free C
 - Java
 - C0 😊
- Programmers usually don't use such constructs even if they're available
 - >90% of old Fortran code reducible

Dealing with Irreducibility

- Don't
- Can split nodes and duplicate code to get reducible graph
 - possible exponential blowup
- Other techniques...

