## 1 Discussion Questions

- (a) What is the difference between Forward Checking and AC-3?
- (b) Why does a tree-structured CSP take  $O(nd^2)$  to solve?
- (c) Why would one use the following heuristics for CSP?
  - (i) Minimum Remaining Values (MRV)
  - (ii) Least Constraining Value (LCV)

## 2 CSP: Air Traffic Control

We have five planes: A, B, C, D, and E and two runways: international and domestic. We would like to schedule a time slot and runway for each aircraft to either land or take off. We have four time slots: 1, 2, 3, 4 for each runway, during which we can schedule a landing or take off of a plane. We must find an assignment that meets the following constraints:

- Plane B has lost an engine and must land in time slot 1.
- Plane D can only arrive at the airport to land during or after time slot 3.
- Plane A is running low on fuel but can last until at most time slot 2.
- Plane D must land before plane C takes off, because some passengers must transfer from D to C.
- No two aircrafts can reserve the same time slot for the same runway.
- (a) Complete the formulation of this problem as a CSP in terms of variables, domains, and constraints (both unary and binary). Constraints should be expressed implicitly using mathematical or logical notation rather than with words. Make sure to specify variables, domains, and constraints.

For the following parts, we add the following two constraints:

- Planes A, B, and C cater to international flights and can only use the international runway.
- Planes D and E cater to domestic flights and can only use the domestic runway.

(b) The addition of the two constraints above alters the CSP. Specifically, the domain does not need to include the runway type since this information is carried by the variable, and the binary constraints have changed. Determine the new domain and complete the constraint graph for this problem given the original constraints and the two added ones.

(c) What are the domains of the variables after enforcing arc-consistency? Begin by enforcing unary constraints. (Cross out values that are no longer in the domain.)

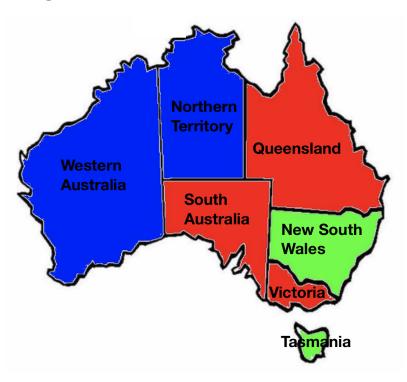
(d) Arc-consistency can be rather expensive to enforce, and we believe that we can obtain faster solutions using only forward-checking on our variable assignments. Using the Minimum Remaining Values heuristic, perform backtracking search on the graph, breaking ties by picking lower values and characters first. List the (variable, assignment) pairs in the order they occur (including the assignments that are reverted upon reaching a dead end). Enforce unary constraints before starting the search.

List of (variable, assignment) pairs:

(You don't have to use this table)

A	1	2	3	4
В	$egin{array}{c c} 1 \\ 1 \\ 1 \end{array}$	2	3	4
A B C D	1	2	3	4
D	1 1	2	3	4
$\mathbf{E}$	1	2	3	4

## 3 Map Coloring with Local Search



Recall the various local search algorithms presented in lecture. Local search differs from previously discussed search methods in that it begins with a complete, potentially conflicting state and iteratively improves it by reassigning values. We will consider a simple map coloring problem, and will attempt to solve it with hill climbing.

- (a) How is the map coloring problem defined (In other words, what are variables, domain and constraints of the problem)? How do you define states in this coloring problem?
- (b) Given a complete state (coloring), how could we define a neighboring state?
- (c) What could be a good heuristic be in this problem for local search? What is the initial value of this heuristic?
- (d) Use hill climbing to find a solution based on the coloring provided in the graph.
- (e) How is local search different from tree search?