

Warm-up As You Walk In

What does this function look like when you plot it as a surface in 3D (y vs x_1, x_2)?

How about as a contour map in 2D (drawn on the x_1, x_2 plane)?

- $y = f(\mathbf{x}) = \left\| \mathbf{x} - \begin{bmatrix} 3 \\ 2 \end{bmatrix} \right\|_2^2, \quad \mathbf{x} \in \mathbb{R}^2$

Announcements

HW1

- Grades can be released after second slip day expires

HW2

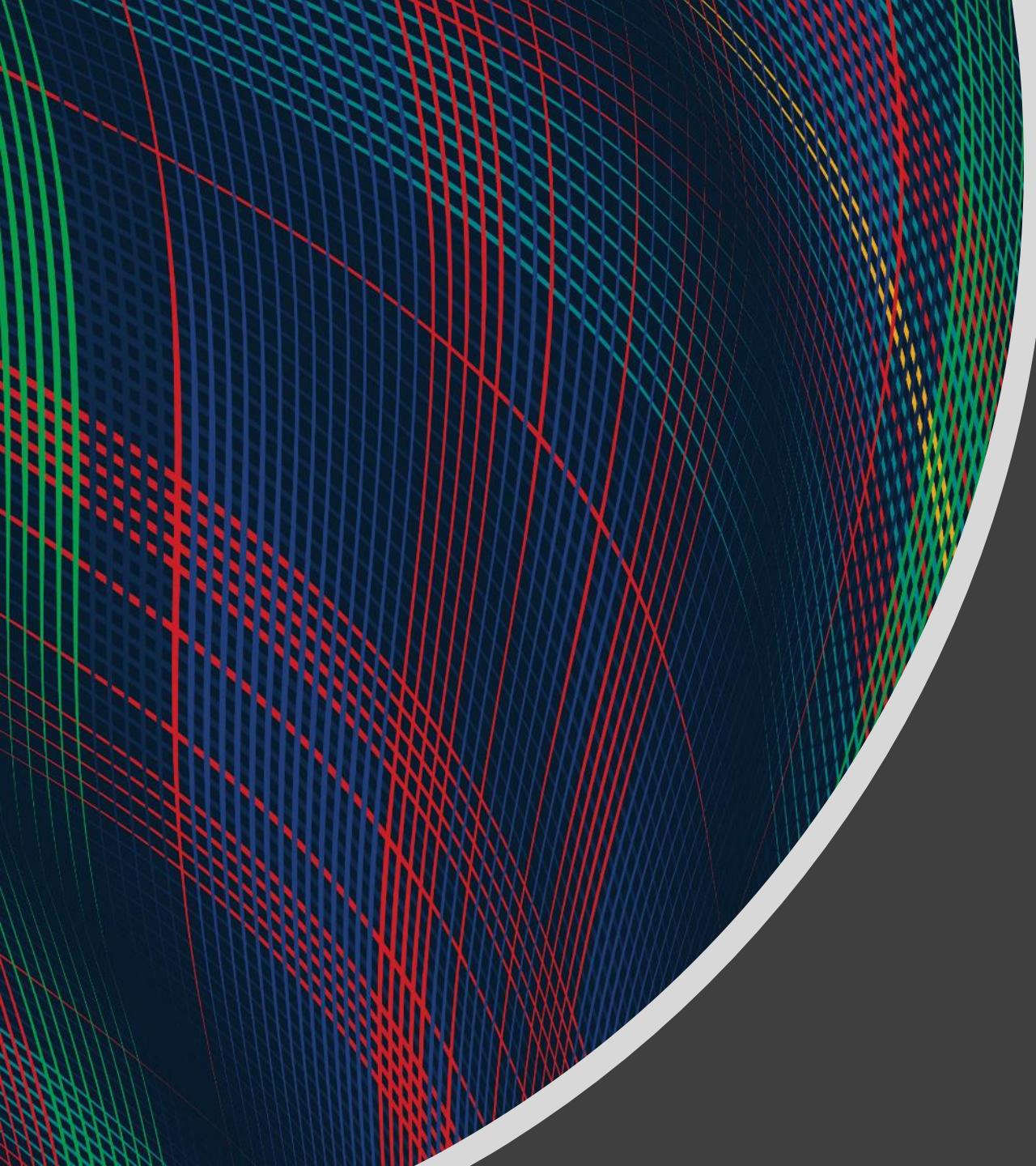
- Out this week

Quiz

- Today, last 15 min. of class

Survey

- Thanks for the feedback!



Mathematical Foundations for Machine Learning

Lagrange Multipliers & Probability

Instructor: Pat Virtue

Plan

Last time

End class with minimax game

Today

Constrained optimization

- Formulation
- Solving with Lagrange multipliers

Probability

- Vocab
- Properties
- Discrete distributions

Constrained Optimization

Method of Lagrange multipliers

Exercise

Mini-max game

$$L(x, \lambda) = 2x + 9 - \lambda(x^2 - 2)$$

Two teams

Team λ :

- Goes first
- Chooses a value for λ in attempt to *maximize* $L(x, \lambda)$

Team x :

- Goes second
- Chooses a value for x in attempt to *minimize* $L(x, \lambda)$

Constrained Optimization

Notation

Method of Lagrange Multipliers

Goal

$$\min_{\mathbf{x}} \quad f(\mathbf{x})$$

$$\text{s.t.} \quad g(\mathbf{x}) = 0$$

Step 1: Construct Lagrangian

$$\mathcal{L}(\mathbf{x}, \lambda) = f(\mathbf{x}) - \lambda g(\mathbf{x})$$

Step 2: Solve

$$\min_{\mathbf{x}} \quad \max_{\lambda} \quad \mathcal{L}(\mathbf{x}, \lambda)$$

Find saddle point:

$$\nabla \mathcal{L}(\mathbf{x}, \lambda) = 0$$

Example

Mini-max game

$$\min_{\mathbf{x}} \quad 2x + 9$$

$$\text{s.t.} \quad x^2 = 2$$

Goal

$$\min_{\mathbf{x}} \quad f(\mathbf{x})$$

$$\text{s.t.} \quad g(\mathbf{x}) = 0$$

Step 1: Construct Lagrangian

$$\mathcal{L}(\mathbf{x}, \lambda) = f(\mathbf{x}) - \lambda g(\mathbf{x})$$

Step 2: Solve

$$\min_{\mathbf{x}} \max_{\lambda} \mathcal{L}(\mathbf{x}, \lambda)$$

(Step 2: Find saddle point)

$$\nabla \mathcal{L}(\mathbf{x}, \lambda) = 0$$

Method of Lagrange Multipliers

Lagrangian

$$\mathcal{L}(\mathbf{x}, \lambda) = f(\mathbf{x}) - \lambda g(\mathbf{x})$$

Find saddle point:

$$\nabla \mathcal{L}(\mathbf{x}, \lambda) = \mathbf{0}$$

Method of Lagrange Multipliers

Goal

$$\min_{\mathbf{x}} \quad f(\mathbf{x})$$

$$\text{s.t.} \quad g(\mathbf{x}) = 0$$

Step 1: Construct Lagrangian

$$\mathcal{L}(\mathbf{x}, \lambda) = f(\mathbf{x}) - \lambda g(\mathbf{x})$$

Step 2: Solve

$$\min_{\mathbf{x}} \quad \max_{\lambda} \quad \mathcal{L}(\mathbf{x}, \lambda)$$

Find saddle point:

$$\nabla \mathcal{L}(\mathbf{x}, \lambda) = 0$$

Equivalent to solving:

$$\nabla f(\mathbf{x}) = \lambda \nabla g(\mathbf{x}) \quad \text{and} \quad g(\mathbf{x}) = 0$$

Method of Lagrange Multipliers (Inequality)

Goal

$$\min_{\mathbf{x}} \quad f(\mathbf{x})$$

$$\text{s.t.} \quad g(\mathbf{x}) \leq 0$$

Step 1: Construct Lagrangian

$$\mathcal{L}(\mathbf{x}, \lambda) = f(\mathbf{x}) + \lambda g(\mathbf{x})$$

Step 2: Solve

$$\min_{\mathbf{x}} \quad \max_{\lambda \geq 0} \quad \mathcal{L}(\mathbf{x}, \lambda)$$

Find saddle point:

$$\nabla \mathcal{L}(\mathbf{x}, \lambda) = \mathbf{0} \quad \text{s.t.} \quad \lambda \geq 0$$

Equivalent to solving:

$$\nabla f(\mathbf{x}) = \lambda \nabla g(\mathbf{x}) \quad \text{s.t.} \quad \lambda \geq 0 \quad \text{and} \quad g(\mathbf{x}) = 0$$

Method of Lagrange Multipliers (multiple constraints)

Goal

$$\min_{\mathbf{x}} \quad f(\mathbf{x})$$

$$\text{s.t.} \quad g_1(\mathbf{x}) = 0$$

$$g_2(\mathbf{x}) = 0$$

Step 1: Construct Lagrangian

$$\mathcal{L}(\mathbf{x}, \lambda) = f(\mathbf{x}) - \lambda_1 g_1(\mathbf{x}) - \lambda_2 g_2(\mathbf{x})$$

Find saddle point:

$$\nabla \mathcal{L}(\mathbf{x}, \lambda_1, \lambda_2) = 0$$

Step 2: Solve

$$\min_{\mathbf{x}} \quad \max_{\lambda_1, \lambda_2} \quad \mathcal{L}(\mathbf{x}, \lambda_1, \lambda_2)$$

Vector Norms

$$\mathbf{u} \in \mathbb{R}^M$$

p-norm (general)

$$\|\mathbf{u}\|_p = \left(\sum_i^M |u_i^p| \right)^{1/p}$$

L2 norm (Euclidean norm)

$$\|\mathbf{u}\|_2 = \left(\sum_i^M u_i^2 \right)^{1/2} = (\mathbf{u}^T \mathbf{u})^{1/2}$$

L1 norm

$$\|\mathbf{u}\|_1 = \sum_i^M |u_i|$$

L0 “norm” (not really a norm)

$$\|\mathbf{u}\|_0 = |\{u_i \mid u_i \neq 0\}| \quad \text{Number of non-zero entries}$$

Probability

Probability Vocab

Outcomes

Events

Probability

Random variable

Discrete random variable

Continuous random variable

Probability mass function

Probability density function

Probability Vocab

Outcomes

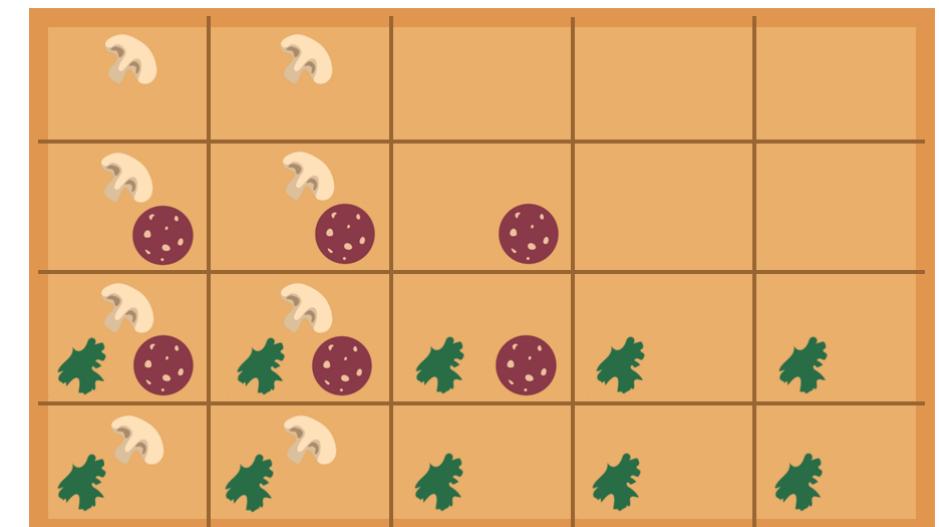
Events

Probability

Random variable

Discrete random variable

Probability mass function



Probability Toolbox

- Algebra
- Three axioms of probability
- Theorem of total probability
- Definition of conditional probability
- Product rule
- Bayes' theorem
- Chain rule
- Independence
- Conditional independence

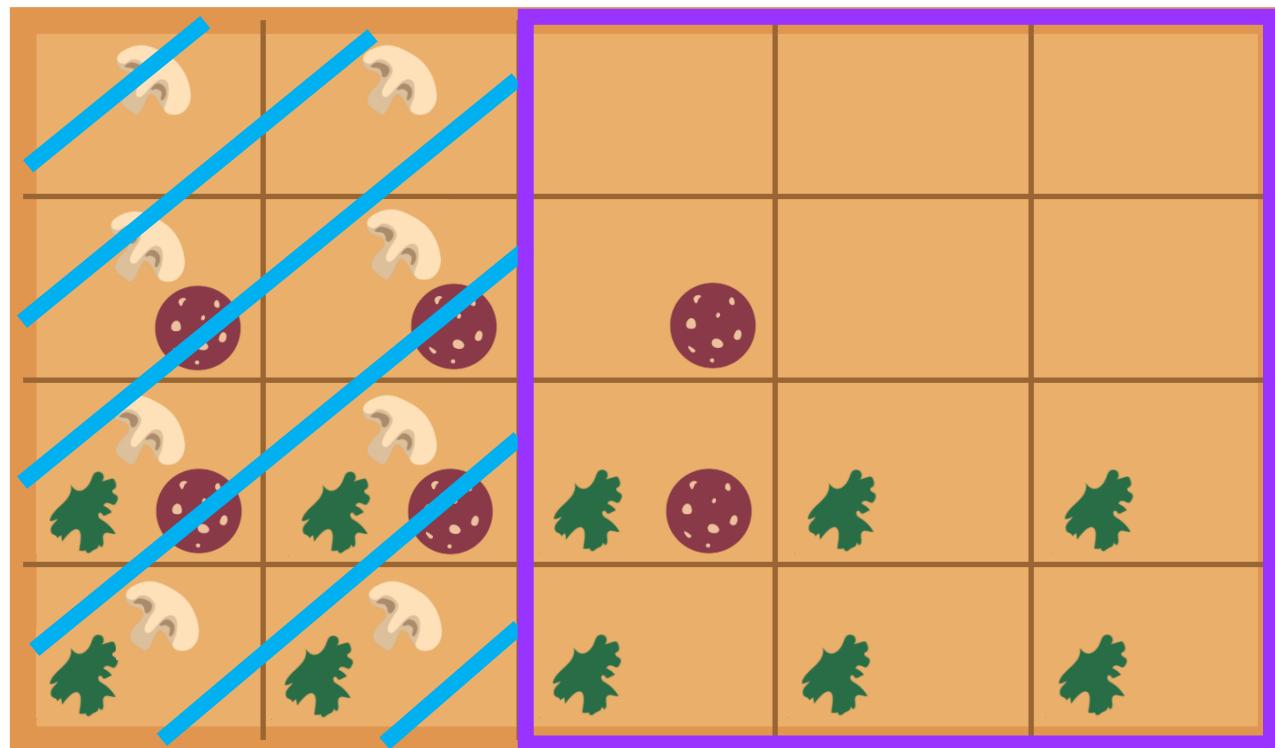
Omega Pizzeria

Three questions: What is the probability of getting a slice with:

- 1) No mushrooms
- 2) Spinach and no mushrooms
- 3) Spinach, when asking for slice with no mushrooms

New information (condition)

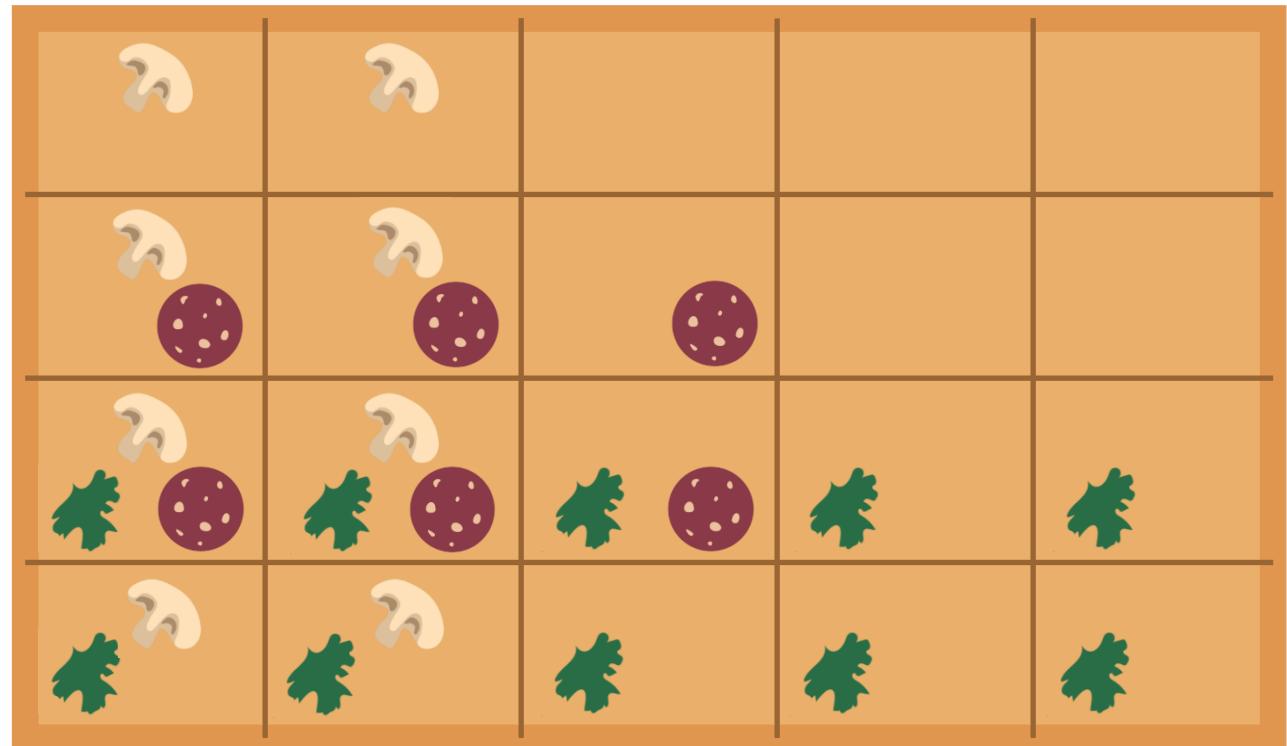
Adjust sample space



Omega Pizzeria

Formalize this a bit

- Ω : set of all possible slices
- S : Spinach random variable
 - $S(\text{no spinach}) = s_1$
 - $S(\text{spinach}) = s_2$
- M : Mushroom random variable
 - $M(\text{no mushrooms}) = m_1$
 - $M(\text{mushrooms}) = m_2$



Omega Pizzeria

Formalize this a bit

- Ω : whole pizza
- S : Spinach random variable
 - $S(\text{no spinach}) = s_1$
 - $S(\text{spinach}) = s_2$
- M : Mushroom random variable
 - $M(\text{no mushrooms}) = m_1$
 - $M(\text{mushrooms}) = m_2$

- 1) No mushrooms
 $P(M = m_1)$
- 2) Spinach and no mushrooms
 $P(S = s_2, M = m_1)$
- 3) Spinach, when asking for slice with no mushrooms
 $P(S = s_2 | M = m_1)$

Vocab alert!

Probability Vocab

Marginal

Joint

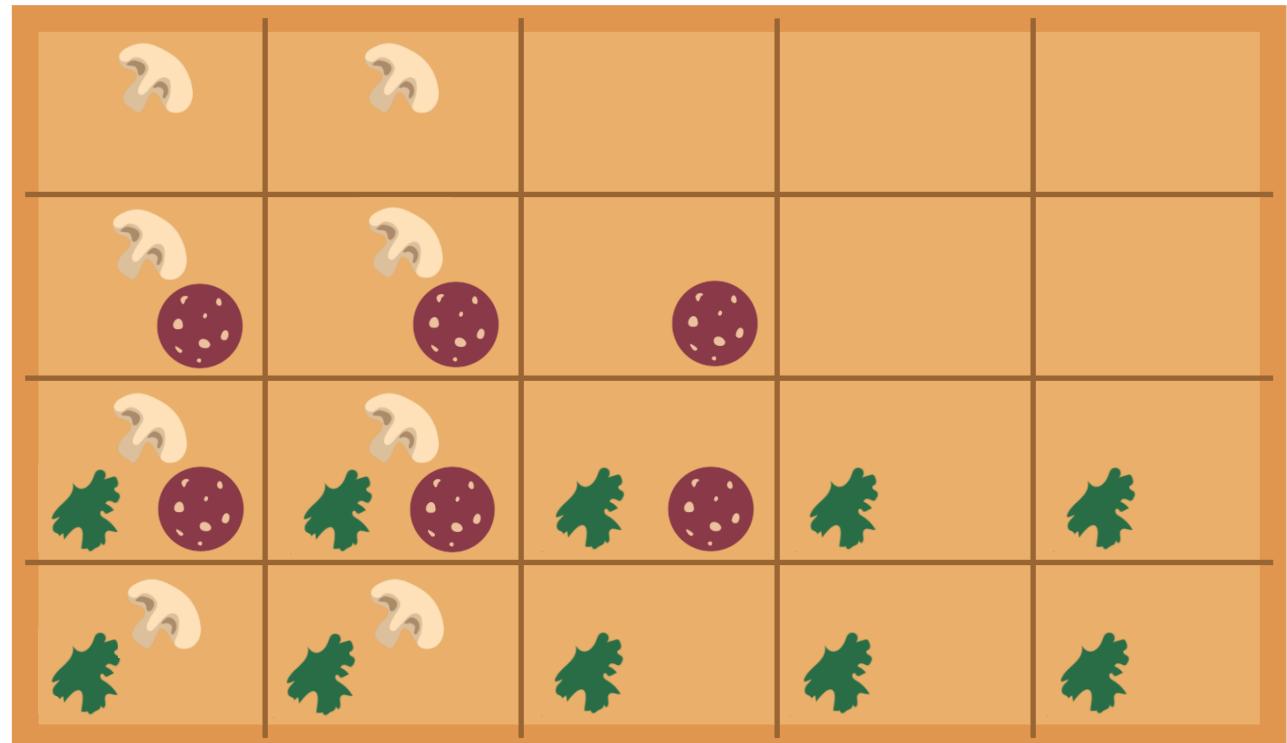
Conditional

Omega Pizzeria

More questions: What is the probability of getting a slice with:

- 1) No mushrooms
- 2) Spinach and no mushrooms
- 3) Spinach, when asking for slice with no mushrooms

- Mushrooms
- Spinach
- No spinach
- No spinach and mushrooms
- No spinach when asking for no mushrooms
- No spinach when asking for mushrooms
- Spinach when asking for mushrooms
- No mushrooms and no spinach

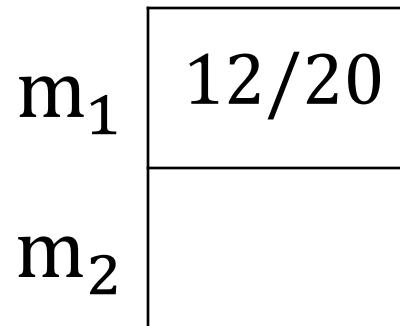


Icons: CC, <https://openclipart.org/detail/296791/pizza-slice>

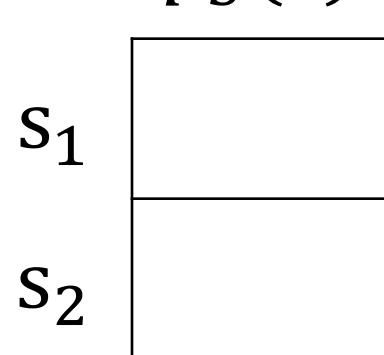
Omega Pizzeria

You can fill out all of these probability mass functions

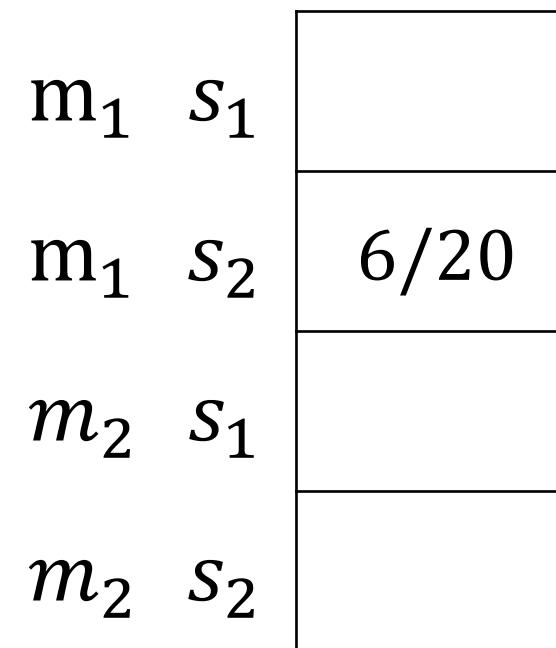
$$p_M(m)$$



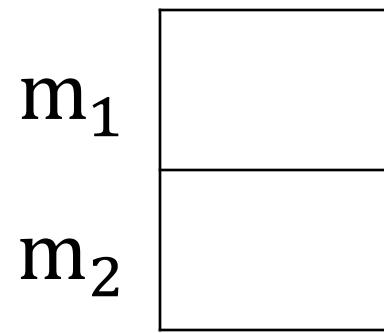
$$p_S(s)$$



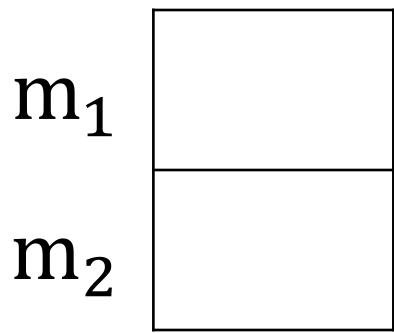
$$p_{M,S}(m, s)$$



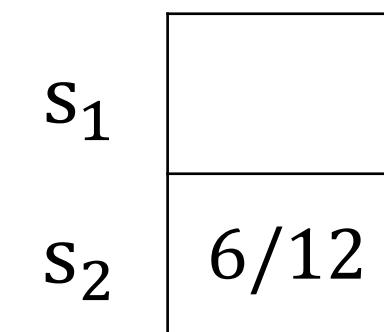
$$p_{M|S}(m \mid s_1)$$



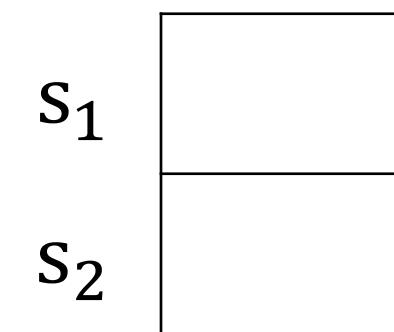
$$p_{M|S}(m \mid s_2)$$



$$p_{S|M}(s \mid m_1)$$



$$p_{S|M}(s \mid m_2)$$



Definition of Conditional Probability

Definition:

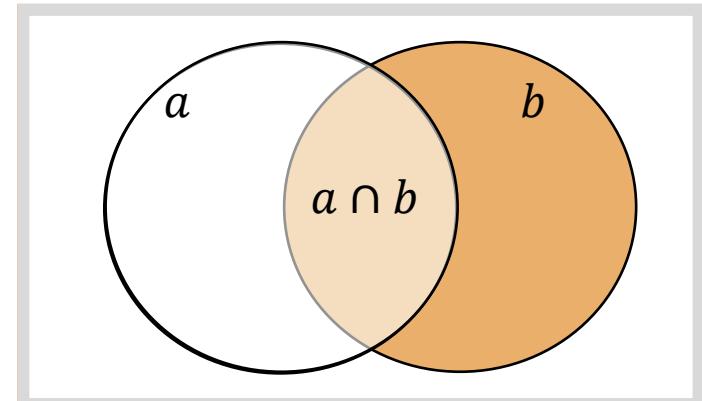
*If $P(b) > 0$, then the **conditional probability** of a given b is:*

$$P(a|b) = \frac{P(a, b)}{P(b)}$$

Counting: proportions

$$P(a) = \frac{\text{Count}(a)}{\text{Count}(\Omega)}$$

$$P(a|b) = \frac{\text{Count}(a \cap b)}{\text{Count}(b)}$$



Omega Pizzeria

Apply definition of conditional probability

- No mushrooms

$$p(m_1) = \frac{12}{20}$$

- Spinach and no mushrooms

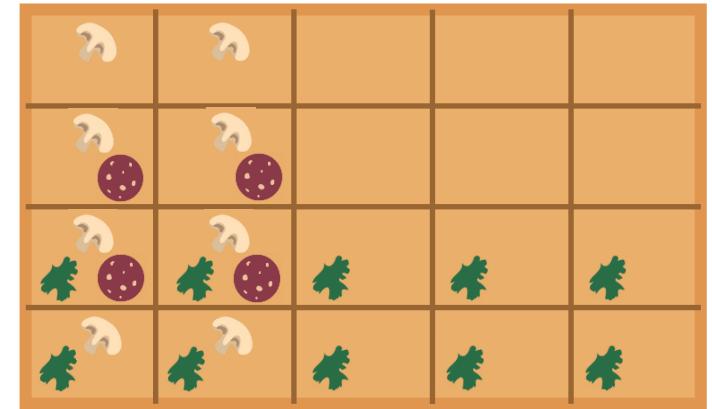
$$p(s_2, m_1) = \frac{6}{20}$$

- Spinach, when asking for slice with no mushrooms

$$p(s_2|m_1) = \frac{6}{12}$$

Conditional
Probability:

$$p(a|b) = \frac{p(a,b)}{p(b)}$$



Omega Pizzeria

Apply definition of conditional probability

- No mushrooms

$$p(m_1) = \frac{12}{20}$$

- Spinach and no mushrooms

$$p(s_2, m_1) = \frac{6}{20}$$

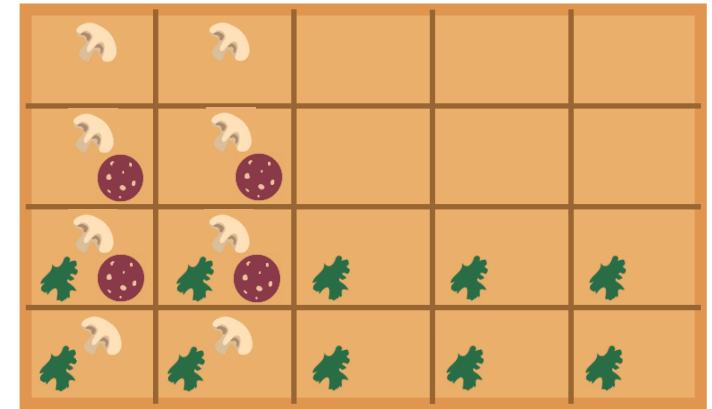
- Spinach, when asking for slice with no mushrooms

$$p(s_2|m_1) = \frac{6}{12}$$

Conditional Probability:

$$p(a|b) = \frac{p(a,b)}{p(b)}$$

$$p(s_2|m_1) = \frac{p(s_2, s_1)}{p(s_1)} = \frac{\frac{6}{20}}{\frac{12}{20}} = \frac{6}{12}$$



Definition of Conditional Probability

Definition:

*If $P(B) > 0$, then the **conditional probability** of A given B is:*

$$P(A|B) = \frac{P(A, B)}{P(B)}$$



Achievement unlocked
Conditional Probability

Normalization Trick

$P(X | Y=0) ?$

$P(X, Y)$

X	Y	P
1	1	0.2
1	0	0.3
0	1	0.4
0	0	0.1

SELECT the joint
probabilities
matching the
evidence



NORMALIZE the
selection
(make it sum to one)



To Normalize

(Dictionary) To bring or restore to a **normal condition**

All entries sum to **ONE**

Procedure:

- Step 1: Compute $Z = \text{sum over all entries}$
- Step 2: Divide every entry by Z

Example 1

W	$p_{W,T}(w,1)$
sun	0.2
rain	0.3

Normalize \rightarrow $Z = 0.5$

W	$p(w)$
sun	0.4
rain	0.6

Example 2

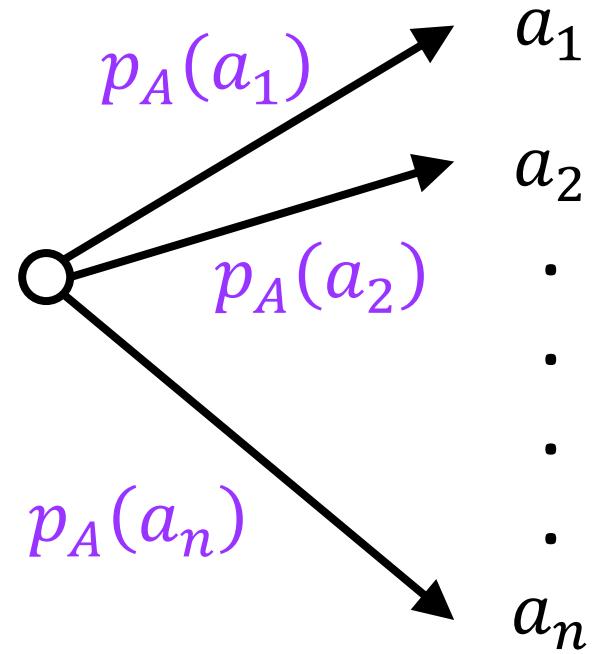
T	W	Count
hot	sun	20
hot	rain	5
cold	sun	10
cold	rain	15

Normalize \rightarrow $Z = 50$

T	W	$P(t,w)$
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3

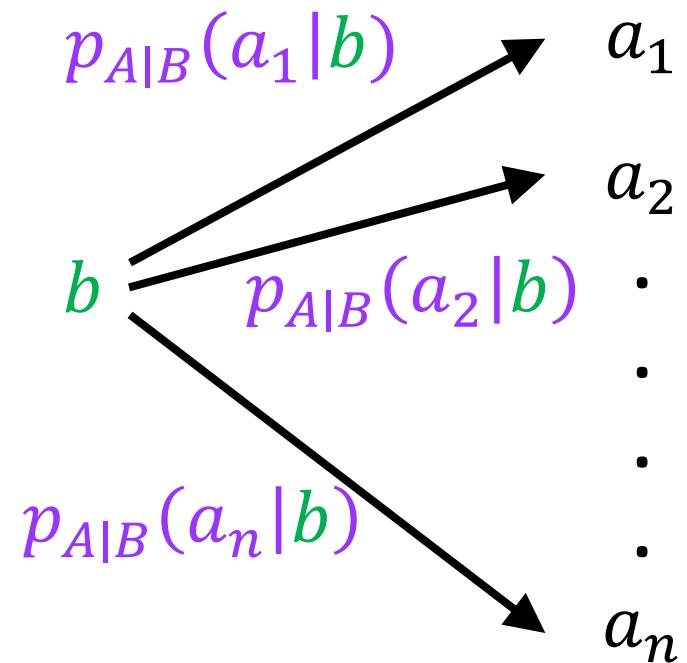
Sum over all values of a discrete random variable

For all possible discrete real values of a random variable A : a_1, a_2, \dots, a_n
 $\sum_{i=1}^n p_A(a_i) = 1$.



Partition given Event, Still Sums to One

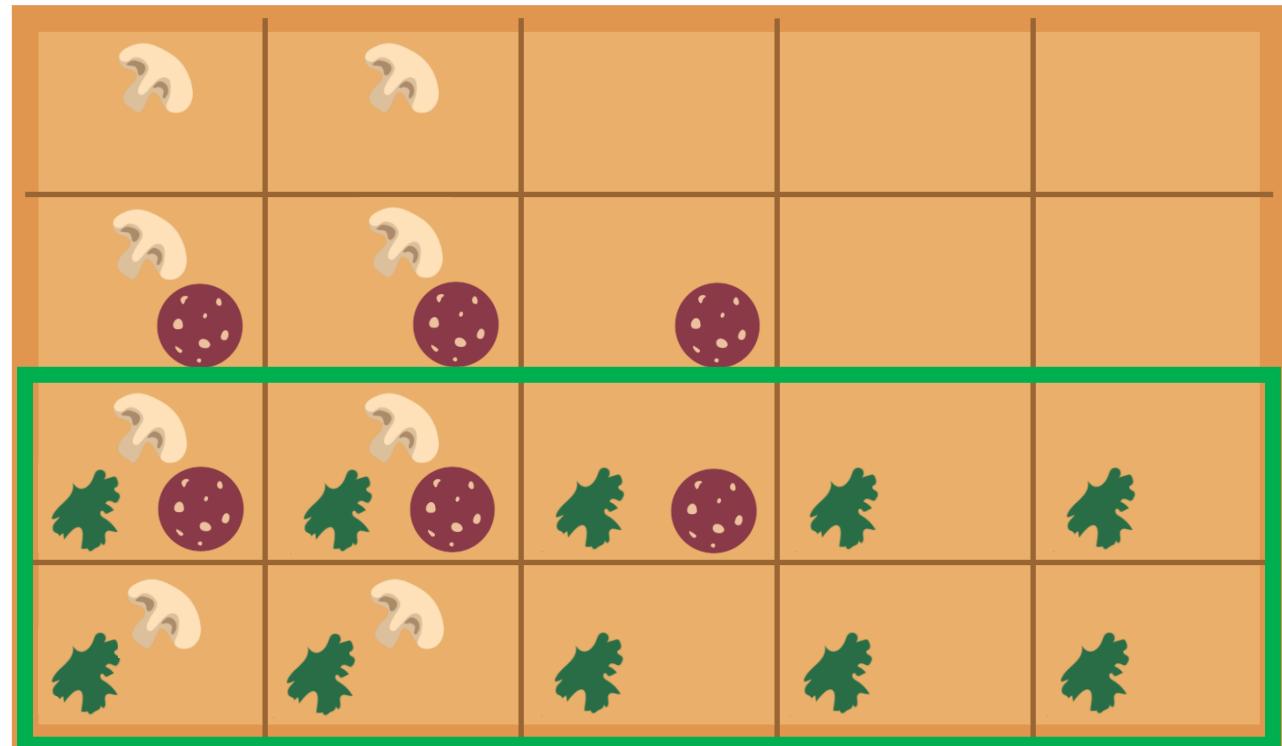
For a given value of random variable $B = b$ and all possible discrete real values of a random variable A : a_1, a_2, \dots, a_n , $\sum_{i=1}^n p_{A|B}(a_i | b) = 1$:



Partition given Event, Still Sums to One

For a given value of random variable $B = b$ and all possible discrete real values of a random variable A : a_1, a_2, \dots, a_n , $\sum_{i=1}^n p_{A|B}(a_i | b) = 1$:

$$s_2 \begin{cases} p(m_1 | s_2) \rightarrow m_1 \\ p(m_2 | s_2) \rightarrow m_2 \end{cases}$$
$$p(m_1 | s_2) + p(m_2 | s_2)$$



Product Rule and Bayes' Theorem

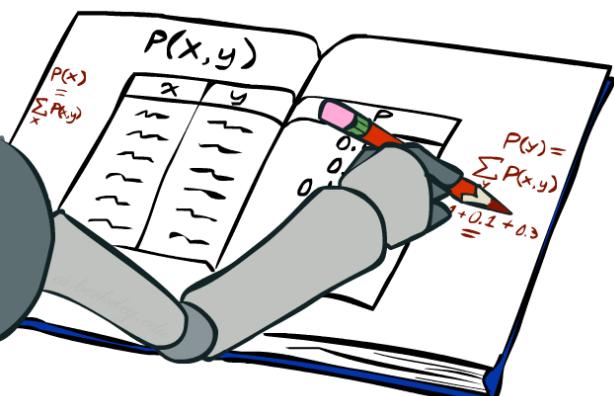
Reformulations of definition of conditional probability

Product rule:

$$\begin{aligned} P(A, B) &= P(A|B)P(B) \\ &= P(B|A)P(A) \end{aligned}$$

Bayes' theorem:

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$



Achievement unlocked
Product Rule

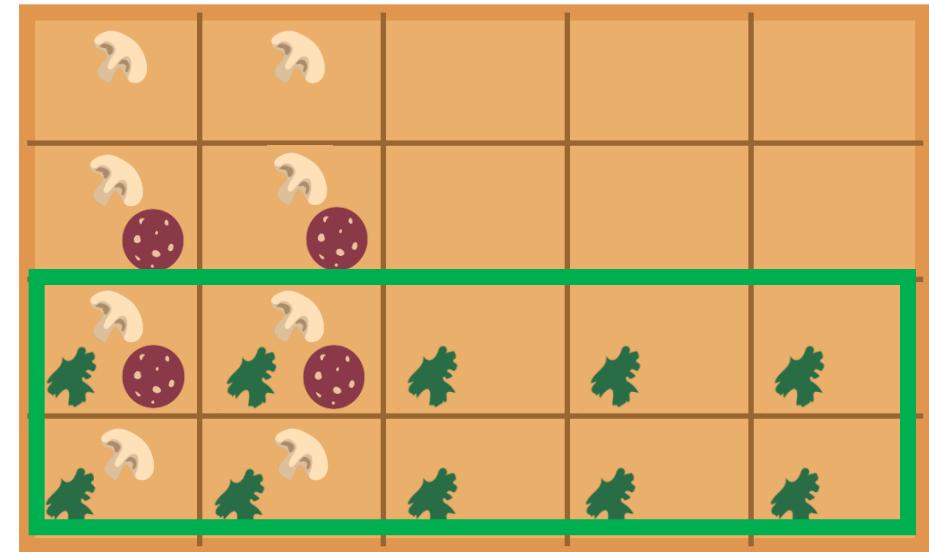
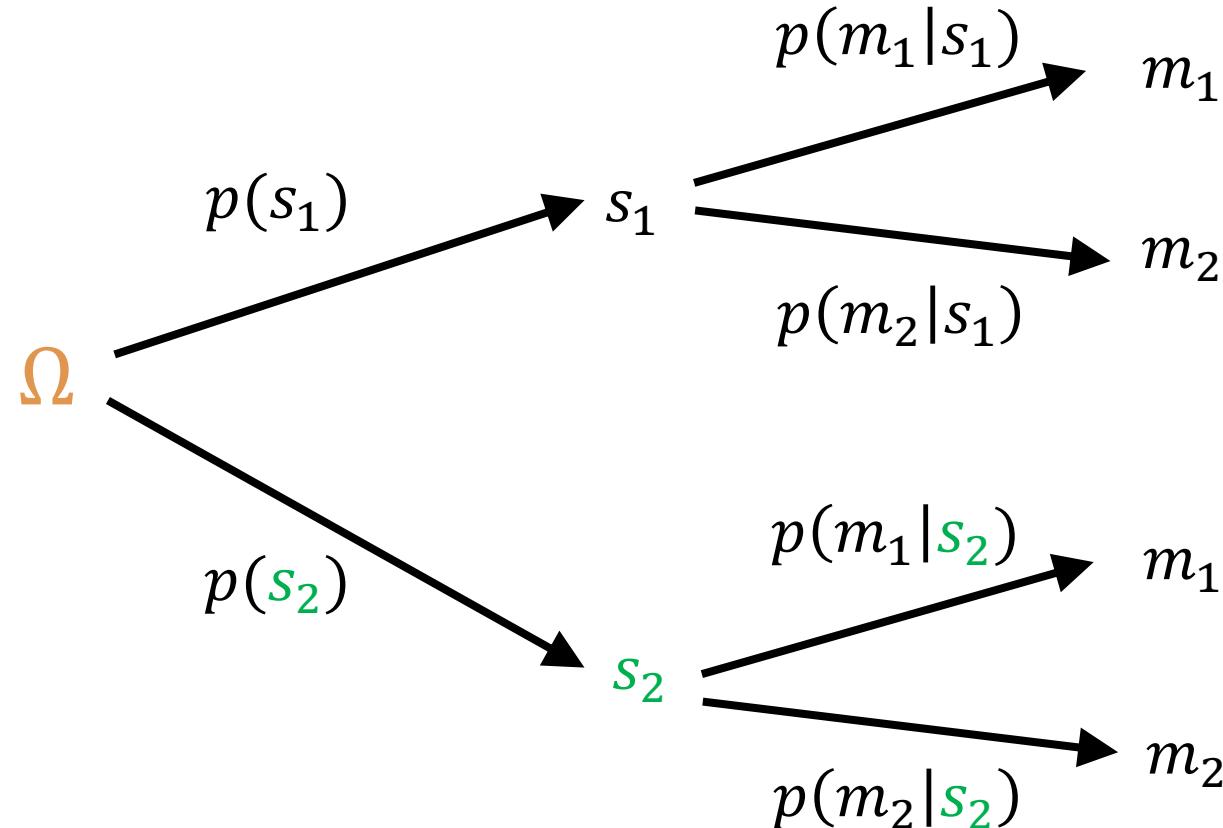


Achievement unlocked
Bayes' Theorem

Product Rule: Tree

Product rule:

$$p(a, b) = p(a|b)p(b)$$



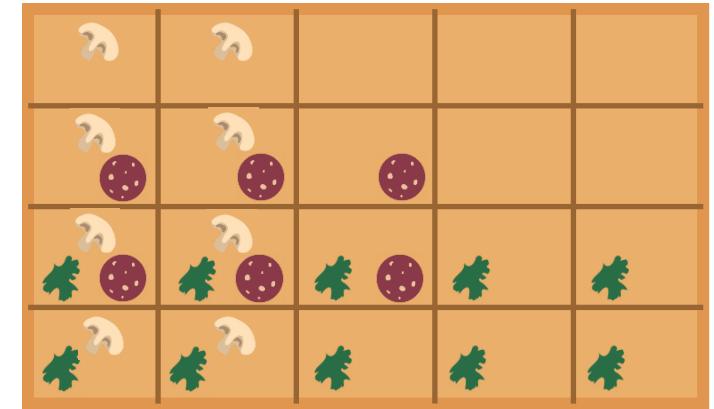
$$p(\textcolor{green}{s_2}) p(m_1|\textcolor{green}{s_2}) = \frac{1}{2} \cdot \frac{6}{10}$$

$$p(m_1, s_2) = \frac{6}{20}$$

Exercise: Product Rule: Tree

Demonstrate, using trees, that product rule works both ways:

$$\begin{aligned} P(A, B) &= P(A|B)P(B) \\ &= P(B|A)P(A) \end{aligned}$$



Bayes' Theorem

Bayes' theorem:

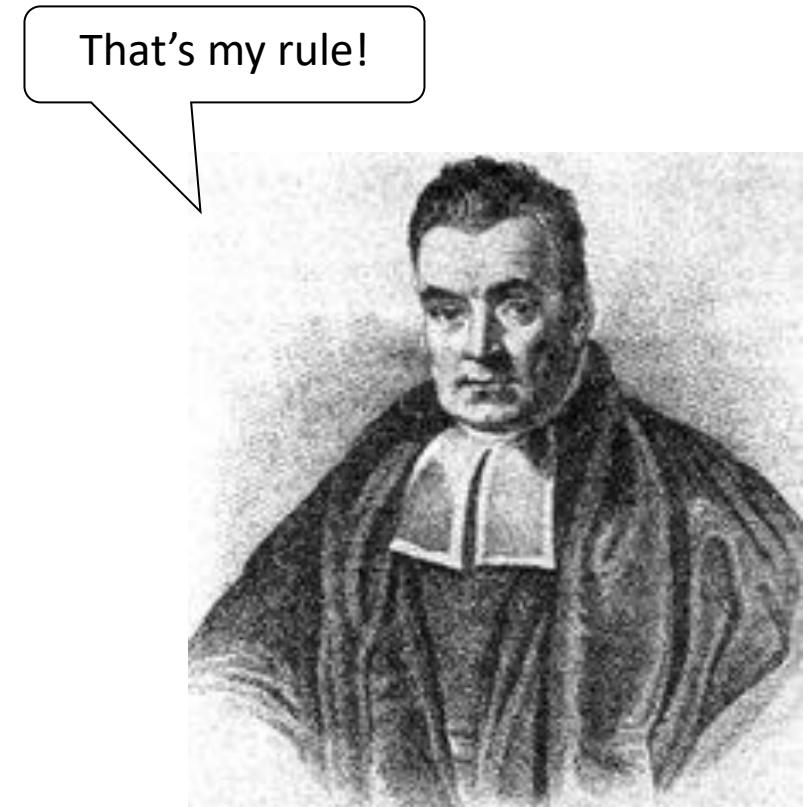
$$P(a_1|b) = \frac{P(b|a_1)P(a_1)}{P(b)}$$

Also:

$$P(a_1|b) = \frac{P(b|a_1)P(a_1)}{\sum_{i=1}^n P(b|a_i)P(a_i)}$$

Why is this at all helpful?

- Lets us build one conditional from its reverse
- Often one conditional is tricky but the other one is simple
- Describes an “update” step from prior $P(a)$ to posterior $P(a | b)$
- Foundation of many probabilistic systems



Inference with Bayes' Theorem

Example: Diagnostic probability from *causal probability*:

$$P(\text{cause} \mid \text{effect}) = \frac{P(\text{effect} \mid \text{cause}) P(\text{cause})}{P(\text{effect})}$$

Example:

- Your friend has a stiff neck ($+s$)
- Knowledge:

$$\begin{aligned}P(+s) &= 0.01 \\P(+m) &= 0.0001 \\P(+s \mid +m) &= 0.8\end{aligned}$$

$$\begin{aligned}P(+m \mid +s) &= \frac{P(+s \mid +m) P(+m)}{P(+s)} \\&= \frac{0.8 \times 0.0001}{0.01} = 0.008\end{aligned}$$

- What are the chances your friend has meningitis ($+m$)?

Tools Summary

Adding to our toolbox

1. Definition of conditional probability
2. Product Rule
3. Bayes' theorem
4. Chain Rule...

$$P(A|B) = \frac{P(A, B)}{P(B)}$$

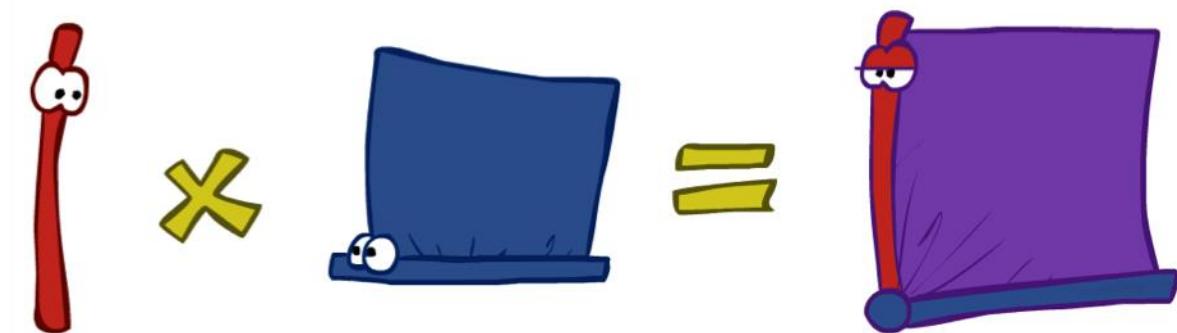
$$P(A, B) = P(A|B)P(B)$$

$$P(B|A) = \frac{P(A|B)P(B)}{P(A)}$$

The Product Rule

Sometimes have conditional distributions but want the joint

$$P(y)P(x|y) = P(x, y) \quad \longleftrightarrow \quad P(x|y) = \frac{P(x, y)}{P(y)}$$



The Product Rule

$$P(y)P(x|y) = P(x, y)$$

Example:

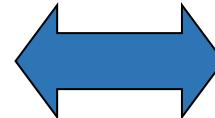
R	P
sun	0.8
rain	0.2

$$P(D|W)$$

D	W	P
wet	sun	0.1
dry	sun	0.9
wet	rain	0.7
dry	rain	0.3

$$P(D, W)$$

D	W	P
wet	sun	
dry	sun	
wet	rain	
dry	rain	



The Chain Rule

More generally, can always write any joint distribution as an incremental product of conditional distributions

$$P(x_1, x_2, x_3) = P(x_1)P(x_2|x_1)P(x_3|x_1, x_2)$$

$$P(x_1, x_2, \dots, x_n) = \prod_i P(x_i|x_1 \dots x_{i-1})$$