

Warm-up

1. https://www.sporcle.com/games/MrChewypoo/minimalist_disney
2. <https://www.sporcle.com/games/Stanford0008/minimalist-cartoons-slideshow>
3. <https://www.sporcle.com/games/MrChewypoo/minimalist>

Announcements

HW3

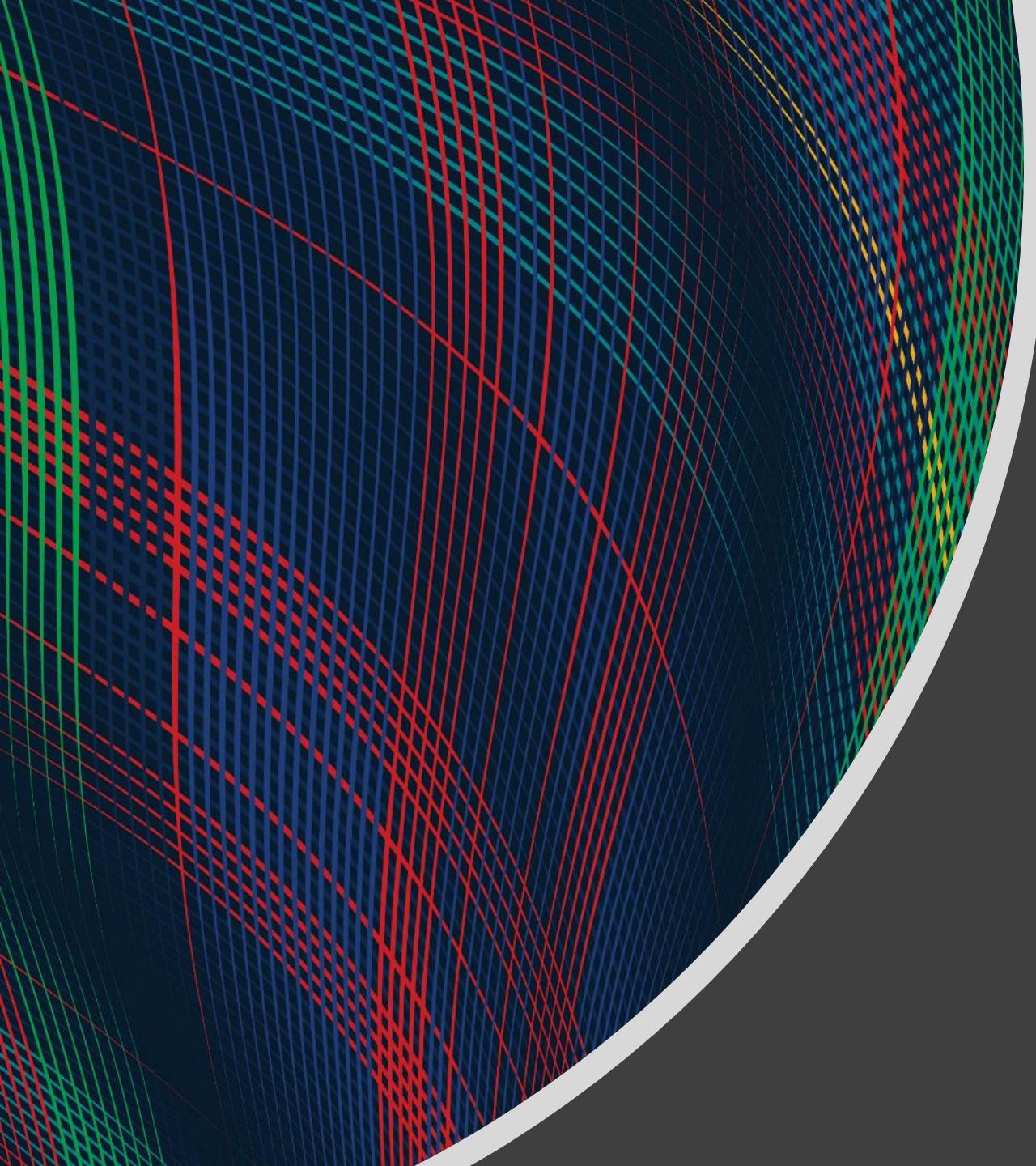
- Due Sat 10/9

Quiz3

- Mon 10/11, last 15 min. of class (probability, statistics)

Next week

- Mon 10/11: Review session
- Wed 10/13: No class
- Thu 10/14: Final exam, 1-4 pm



Mathematical Foundations for Machine Learning

Probability/Statistics
& PCA Application

Instructor: Pat Virtue

Plan

Today

Probability/Statistics

- Expectation
- Variance
- Covariance
- Covariance matrix

10-606 Application: PCA

Expectation and Variance

Expectation and Variance

The **expected value** of X is $E[X]$. Also called the mean.

- Discrete random variables:

Suppose X can take any value in the set \mathcal{X} .

$$E[X] = \sum_{x \in \mathcal{X}} xp(x)$$

- Continuous random variables:

$$E[X] = \int_{-\infty}^{+\infty} xf(x)dx$$

Expectation and Variance

The **variance** of X is $Var(X)$.

$$Var(X) = E[(X - \mu)^2]$$

• Discrete random variables:

$$Var(X) = \sum_{x \in \mathcal{X}} (x - \mu)^2 p(x)$$

$\mu = E[X]$

• Continuous random variables:

$$Var(X) = \int_{-\infty}^{+\infty} (x - \mu)^2 f(x) dx$$

Covariance

Expectation:

$$E[x] = \sum x p(x)$$

Variance:

$$\text{Var}[x] = E[(x - E(x))^2]$$

Covariance:

$$\text{Cov}[x_1, x_2] = E[(x_1 - E[x_1])(x_2 - E[x_2])]$$

Vector of random variables:

$$X = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix}$$

Covariance matrix:

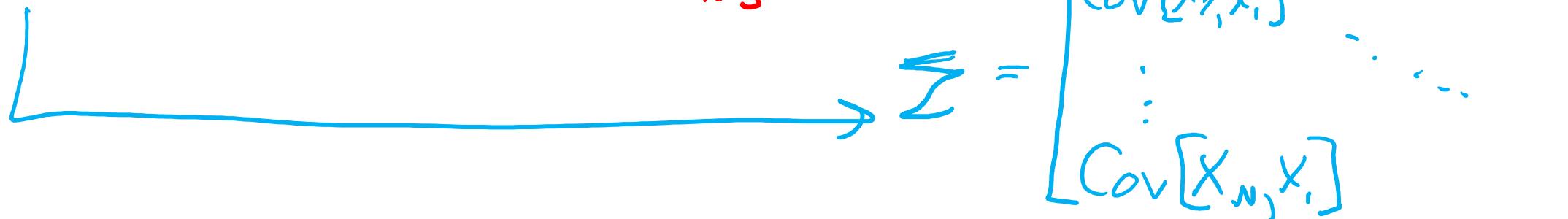


Diagram illustrating the relationship between a vector of random variables X and its covariance matrix Σ . A blue arrow points from the vector X to the covariance matrix Σ . The covariance matrix Σ is defined as:

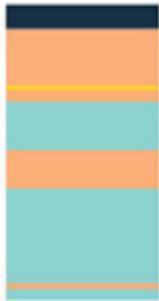
$$\Sigma = \begin{bmatrix} \text{Var}[x_1] & \text{Cov}[x_1, x_2] & \dots \\ \text{Cov}[x_2, x_1] & \ddots & \dots \\ \vdots & \dots & \dots \\ \text{Cov}[x_N, x_1] & \dots & \dots \end{bmatrix}$$

Principal Component Analysis

Warm-up as you log in

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Dimensionality Reduction



Dimensionality Reduction



Dimensionality Reduction

For each $x^{(i)} \in \mathbb{R}^M$ find representation $z^{(i)} \in \mathbb{R}^K$ where $K \ll M$

Dimensionality Reduction

<http://timbaumann.info/svd-image-compression-demo/>

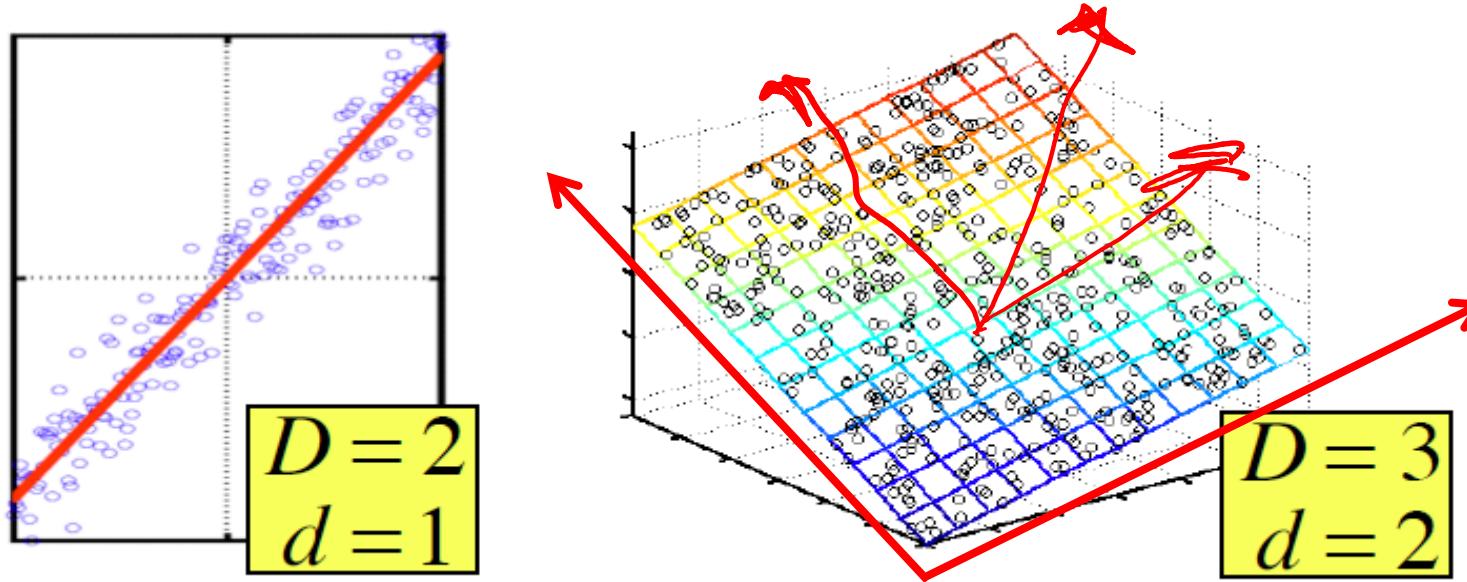
<https://cs.stanford.edu/people/karpathy/convnetjs/demo/autoencoder.html>

PCA Worksheet

Lagrange multipliers for PCA

$$\begin{aligned}\hat{\mathbf{v}} = \operatorname{argmax}_{\mathbf{v}} \quad & \mathbf{v}^T A \mathbf{v} \\ \text{s.t.} \quad & \|\mathbf{v}\|_2^2 = 1\end{aligned}$$

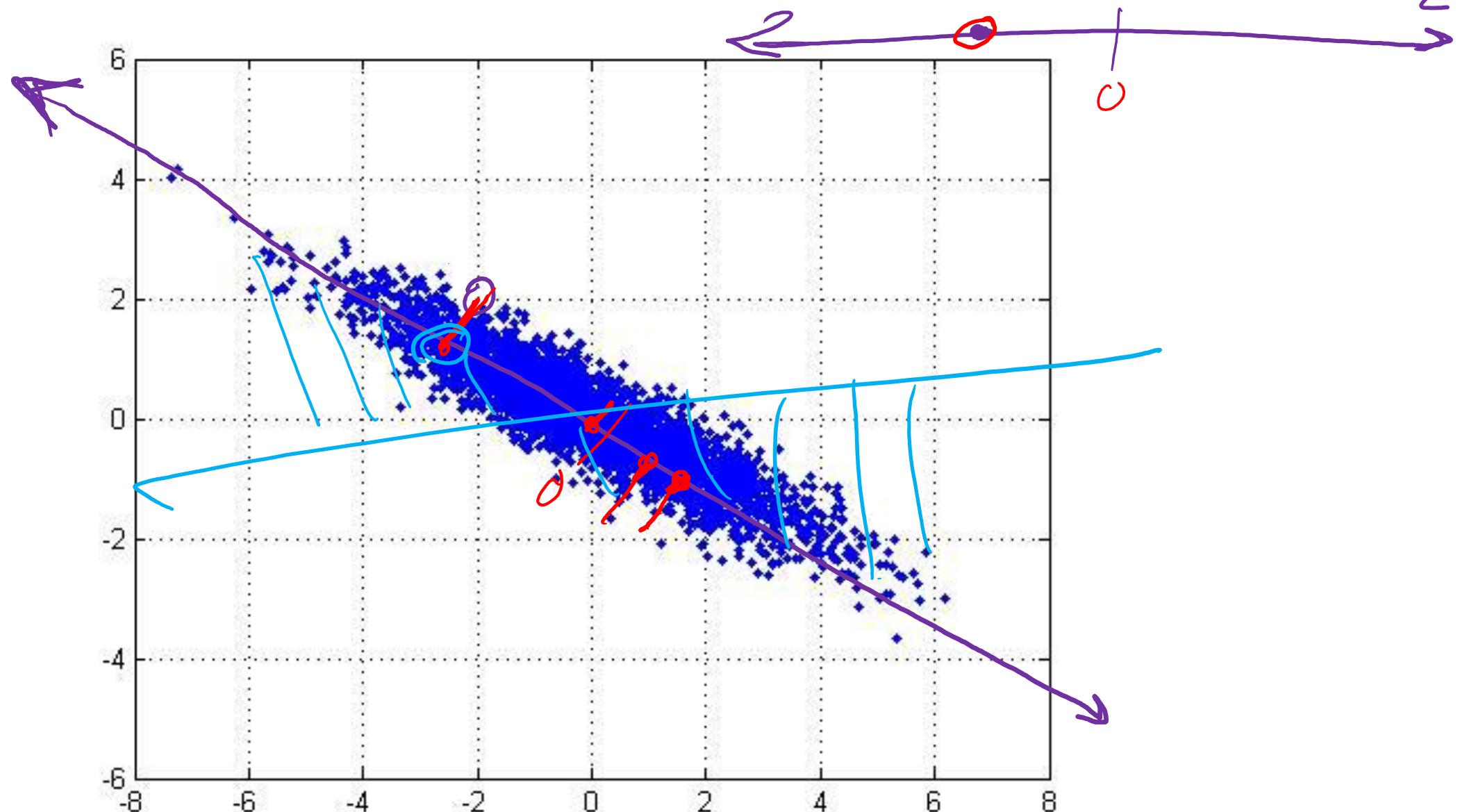
Principal Component Analysis (PCA)



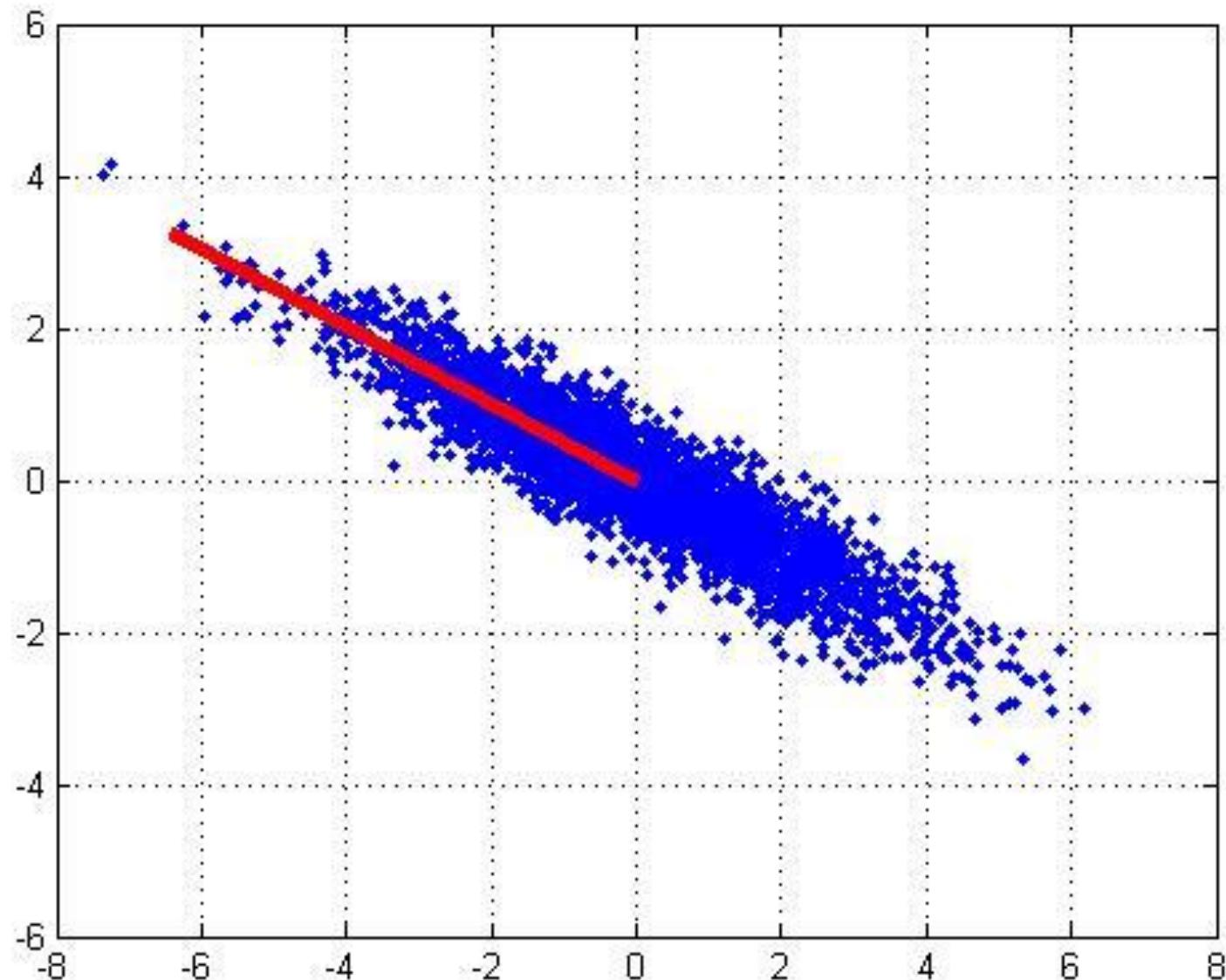
In case where data lies on or near a low d -dimensional linear subspace, axes of this subspace are an effective representation of the data.

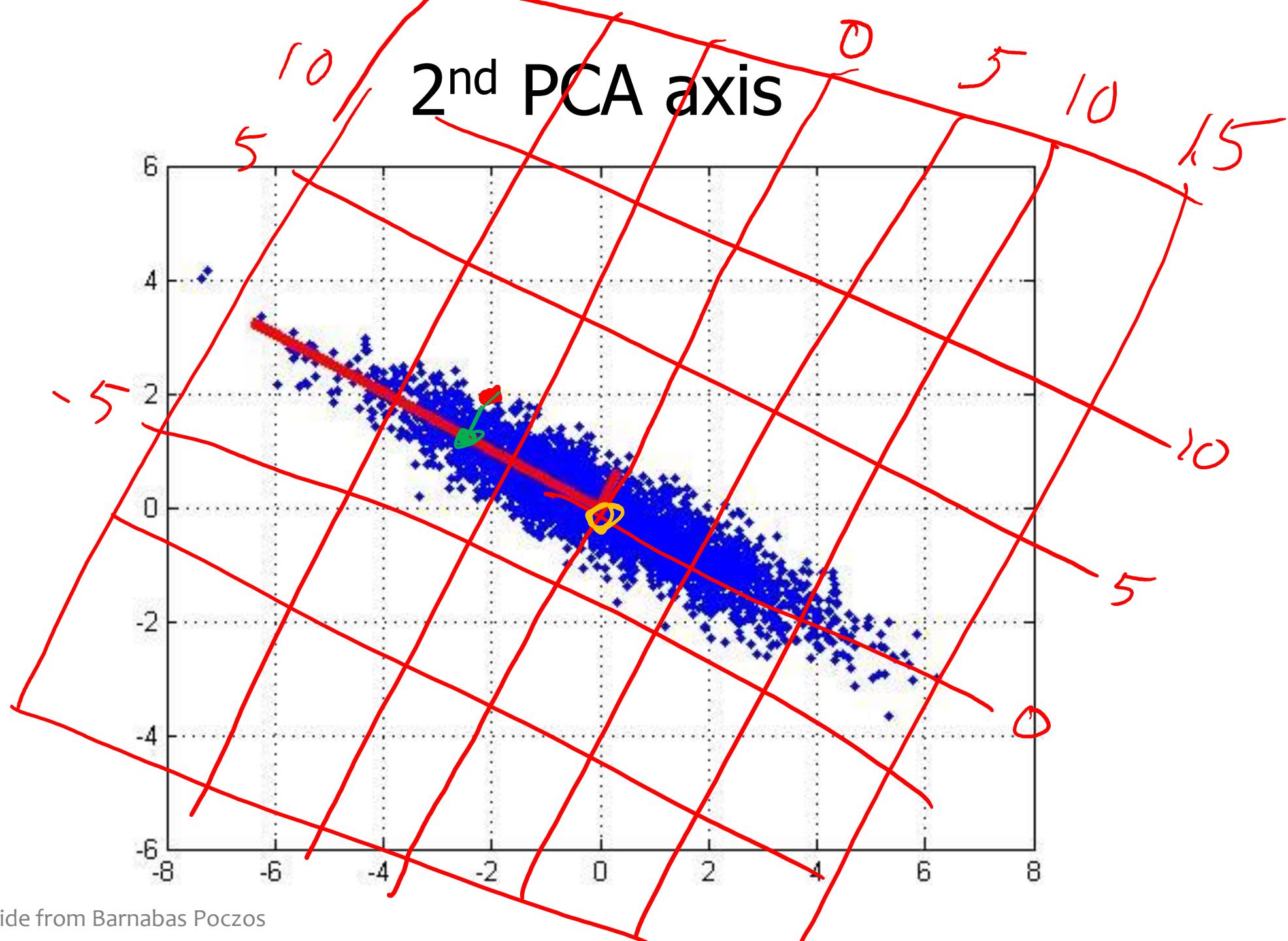
Identifying the axes is known as [Principal Components Analysis](#), and can be obtained by using classic matrix computation tools (Eigen or Singular Value Decomposition).

2D Gaussian dataset



1st PCA axis





Data for PCA

$$\mathcal{D} = \{\mathbf{x}^{(i)}\}_{i=1}^N$$

$$\mathbf{X} = \begin{bmatrix} (\mathbf{x}^{(1)})^T \\ (\mathbf{x}^{(2)})^T \\ \vdots \\ (\mathbf{x}^{(N)})^T \end{bmatrix}$$

We assume the data is **centered**

$$\mu = \frac{1}{N} \sum_{i=1}^N \mathbf{x}^{(i)} = \mathbf{0}$$

Q: What if
your data is
not centered?

A: Subtract
off the
sample mean

Sample Covariance Matrix

The sample covariance matrix is given by:

$$\Sigma_{jk} = \frac{1}{N} \sum_{i=1}^N (x_j^{(i)} - \mu_j)(x_k^{(i)} - \mu_k)$$

Since the data matrix is centered, we rewrite as:

$$\Sigma = \frac{1}{N} \mathbf{X}^T \mathbf{X}$$

$$\mathbf{X} = \begin{bmatrix} (\mathbf{x}^{(1)})^T \\ (\mathbf{x}^{(2)})^T \\ \vdots \\ (\mathbf{x}^{(N)})^T \end{bmatrix}$$

PCA Algorithm

Input: X, X_{test}, K

1. Center data (and scale each axis) based on training data $\rightarrow X, X_{test}$
2. $V = \text{eigenvectors}(X^T X)$
3. Keep only the top K eigenvectors: V_K
4. $Z_{test} = X_{test} V_K$

Optionally, use V_K^T to rotate Z_{test} back to original subspace X'_{test} and uncenter