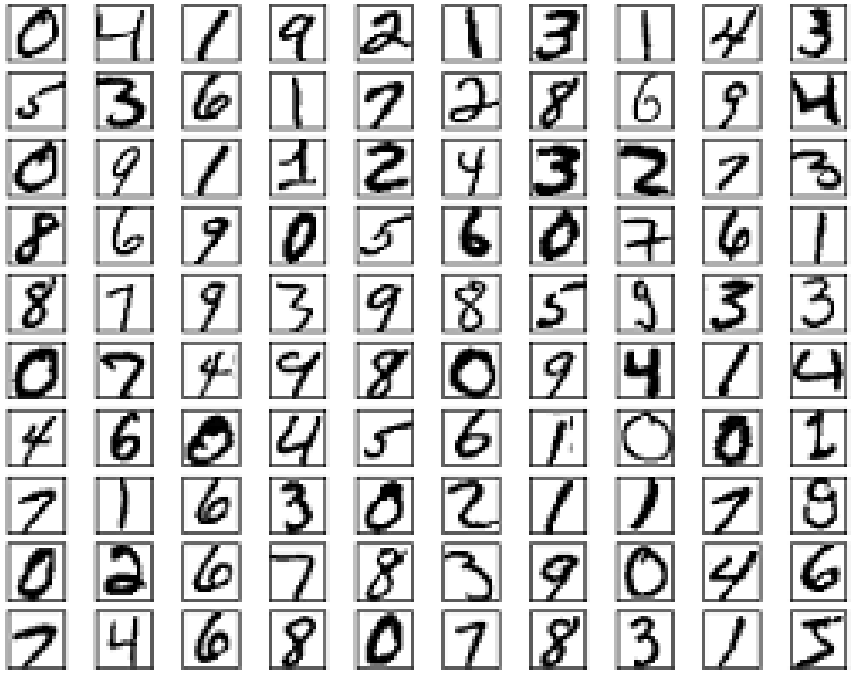
Announcements

Assignments

- HW9 (online)
  - Due Thu 4/16, 11:59 pm

Dimensionality Reduction

MNIST digit autoencoder



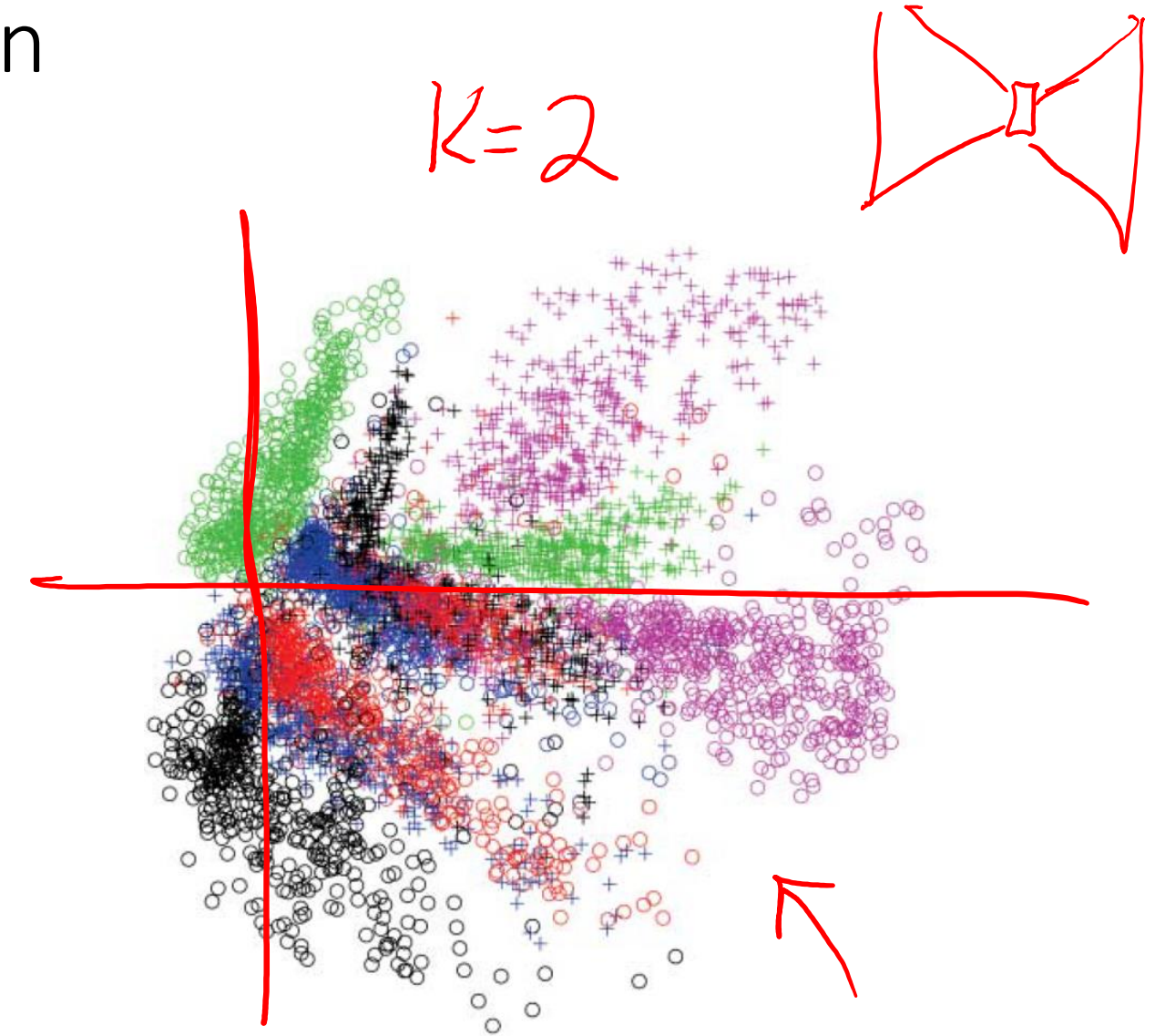


Image: Hinton & Salakhutdinov. *Science* 313.5786 (2006): 504-507.

Piazza Poll 1

Are autoencoders an example of unsupervised learning?

A. Yes
B. Calamity
C. No

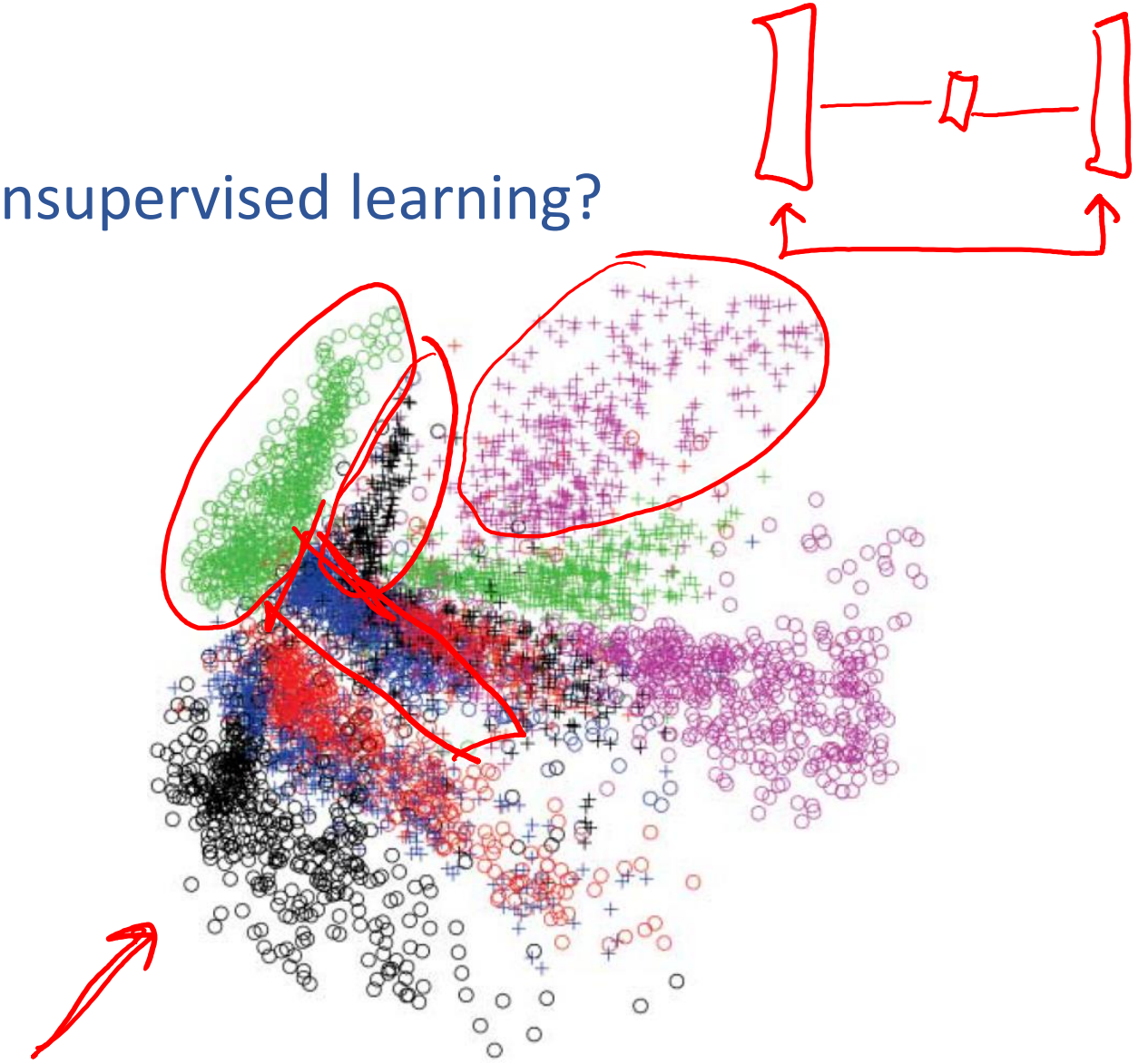
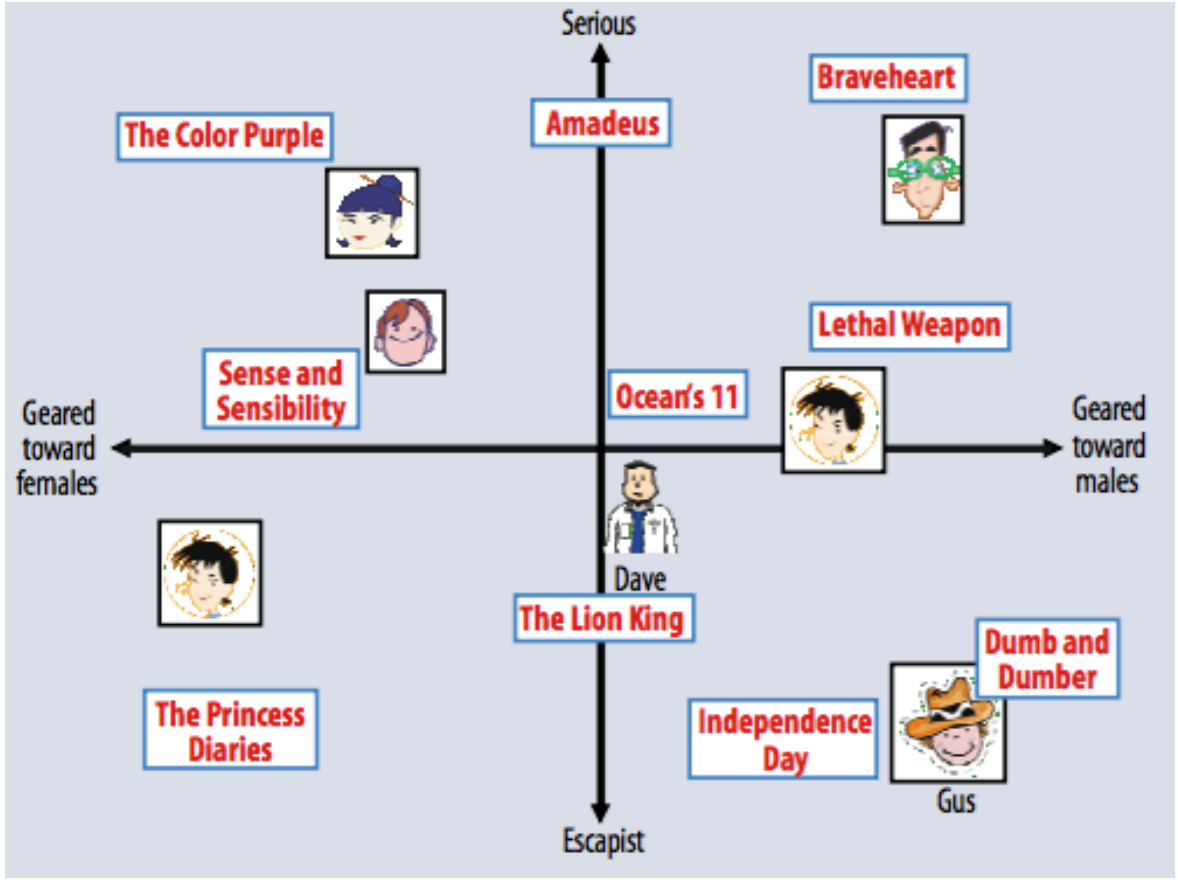


Image: Hinton & Salakhutdinov. *Science* 313.5786 (2006): 504-507.

Recommender Systems

Matrix Factorization

$K=2$



U

V

Figures from Koren et al. (2009)

Piazza Poll 2

Are recommender systems an example of unsupervised learning?

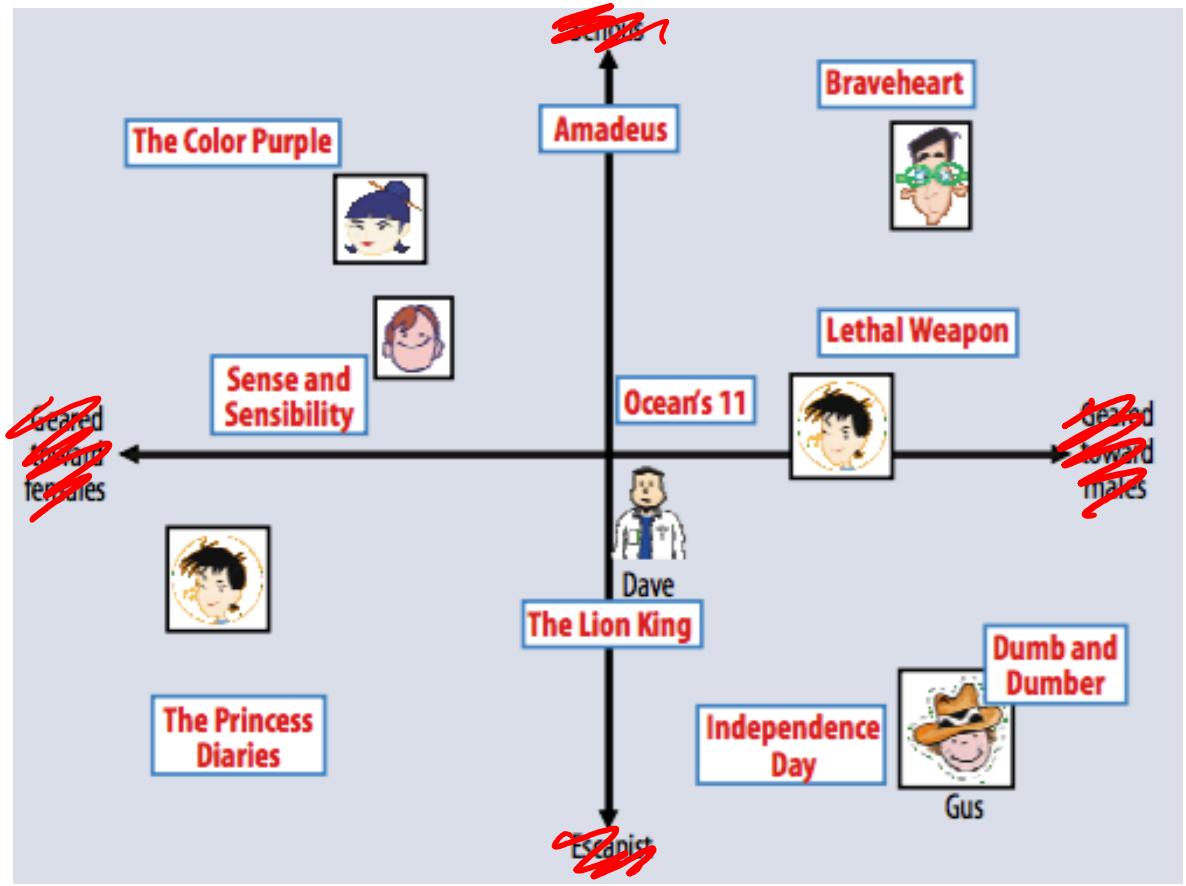
A. Yes

B. Calamity

C. No

$\hat{R}_{ij} \leftarrow h(i,j)$

R_{ij}



Figures from Koren et al. (2009)

Plan

Last week

- Dimensionality reduction
  - PCA
  - Autoencoders
- Recommender systems

Unsupervised

This week

- Clustering

Unsupervised, distance point is space

Next week

- Learning Theory

Introduction to Machine Learning

Clustering

Instructor: Pat Virtue

Clustering, Informal Goals

Goal: Automatically partition unlabeled data into groups of similar datapoints.

Question: When and why would we want to do this?

Useful for:

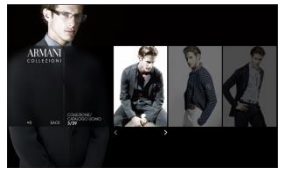
- Automatically organizing data.
- Understanding hidden structure in data.
- Preprocessing for further analysis.
    - Representing high-dimensional data in a low-dimensional space (e.g., for visualization purposes).

Slide credit: CMU MLD Nina Balcan

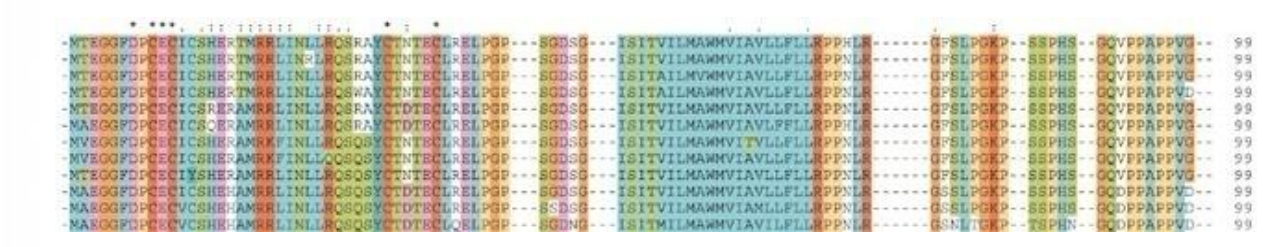
Applications (Clustering comes up everywhere…)

Cluster news articles or web pages or search results by topic.

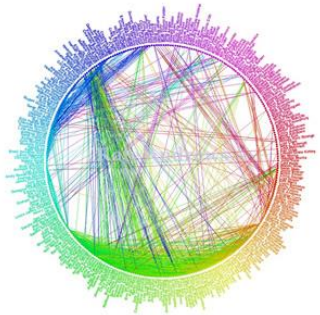




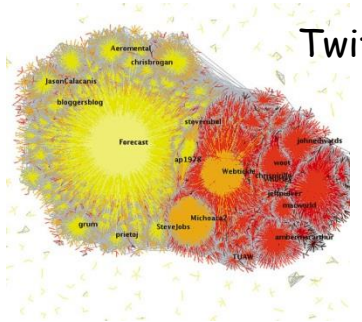
- Cluster protein sequences by function or genes according to expression profile.

- Cluster users of social networks by interest (community detection).



Facebook network

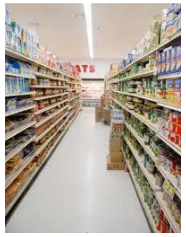


Twitter Network

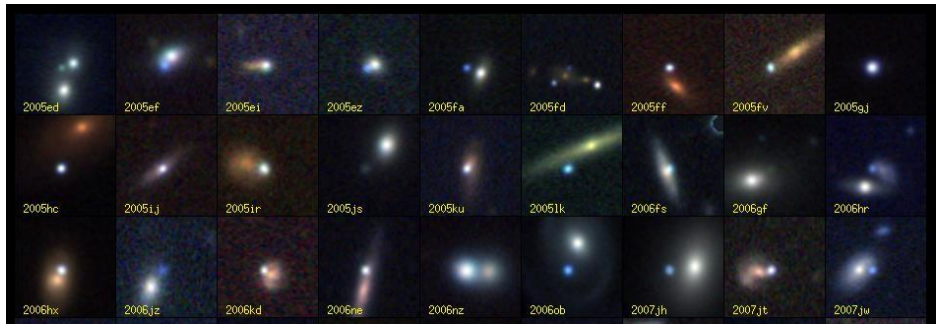
Slide credit: CMU MLD Nina Balcan

Applications (Clustering comes up everywhere…)

Cluster customers according to purchase history.



- Cluster **galaxies or nearby stars (e.g. Sloan Digital Sky Survey)**



- And many many more applications….

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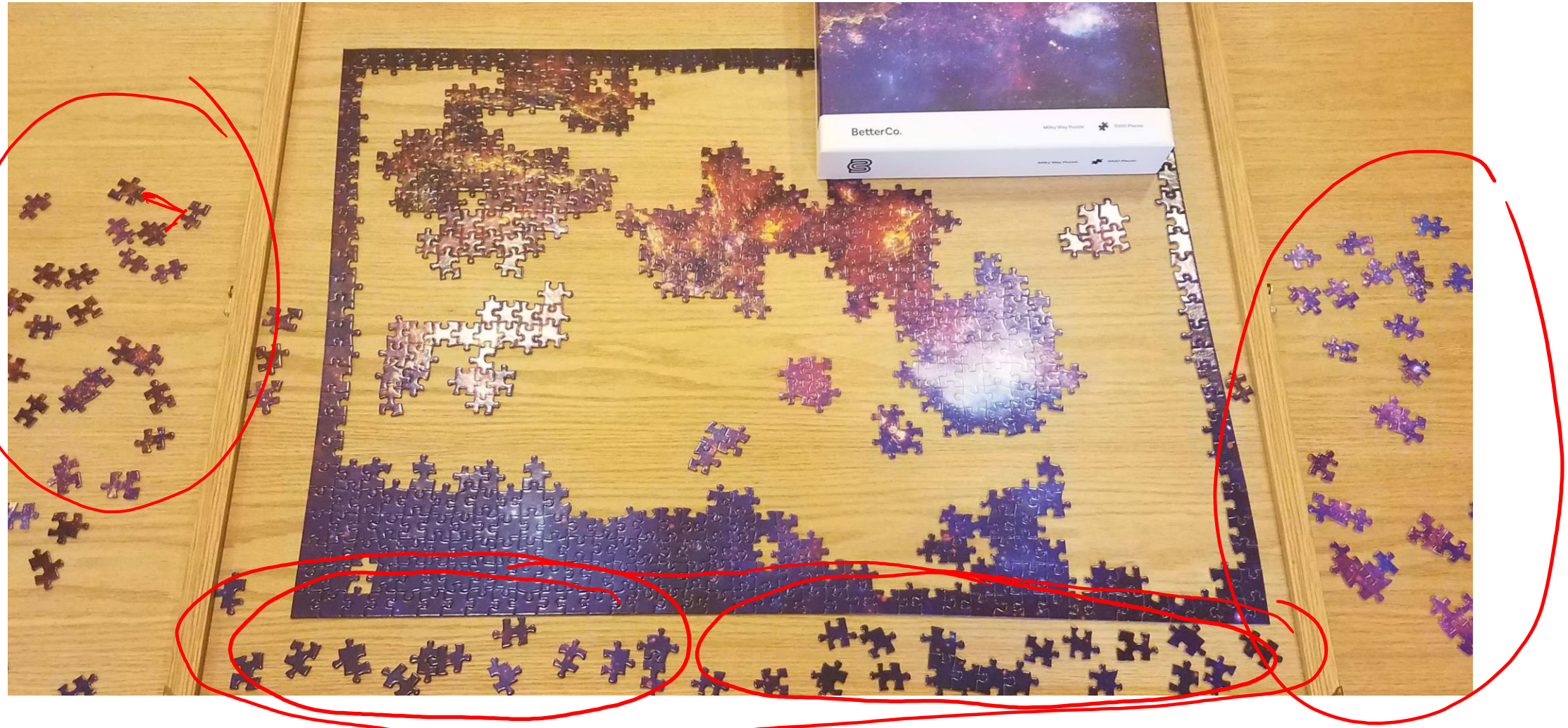
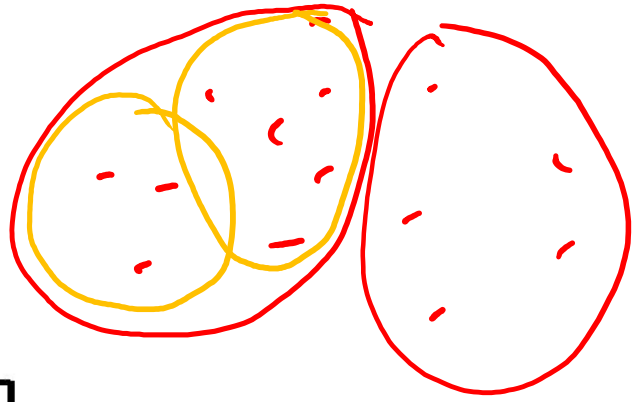
Clustering Applications

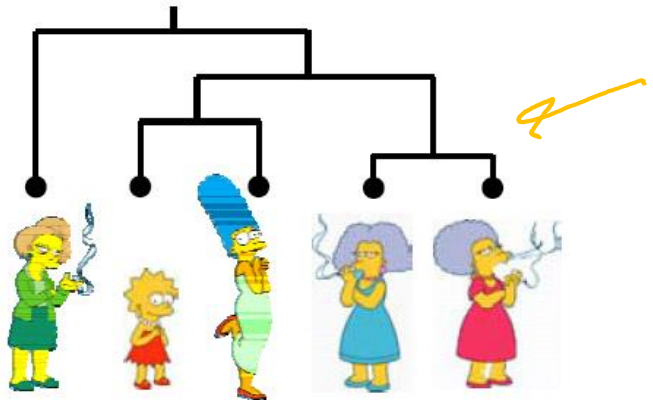
Jigsaw puzzles!



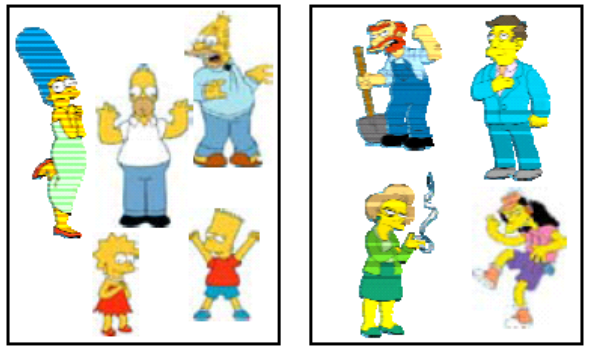
Clustering Algorithms



- Hierarchical algorithms
  - Bottom-up: Agglomerative Clustering
  - Top-down: Divisive



- Partition algorithms
  - K means clustering
  - Mixture-Model based clustering



Slide credit: CMU MLD Aarti Singh and Eric Xing

Hierarchical Clustering

- Bottom-Up Agglomerative Clustering

  Starts with each object in a separate cluster, and repeat:

  – Joins the most similar pair of clusters, $\|x^{(1)} - x^{(2)}\|_2$

  – Update the similarity of the new cluster to others

  until there is only one cluster.

  Greedy – less accurate but simple to implement

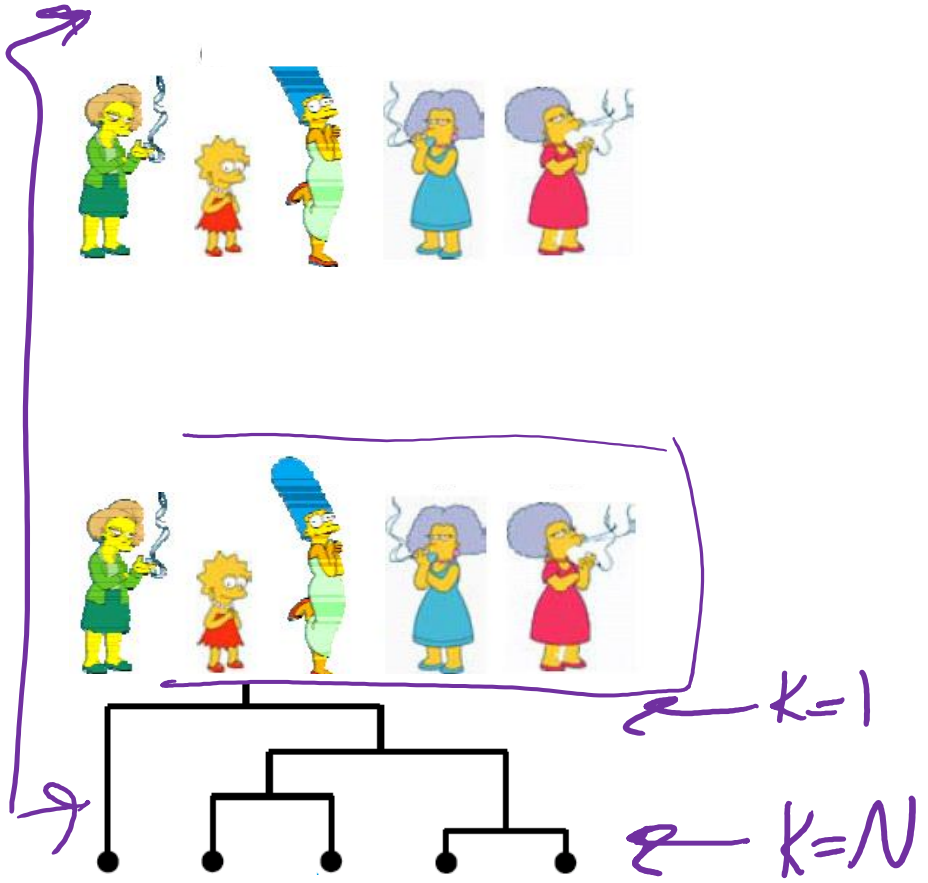
- Top-Down divisive

  Starts with all the data in a single cluster, and repeat:

  – Split each cluster into two using a partition algorithm

  Until each object is a separate cluster.

  More accurate but complex to implement

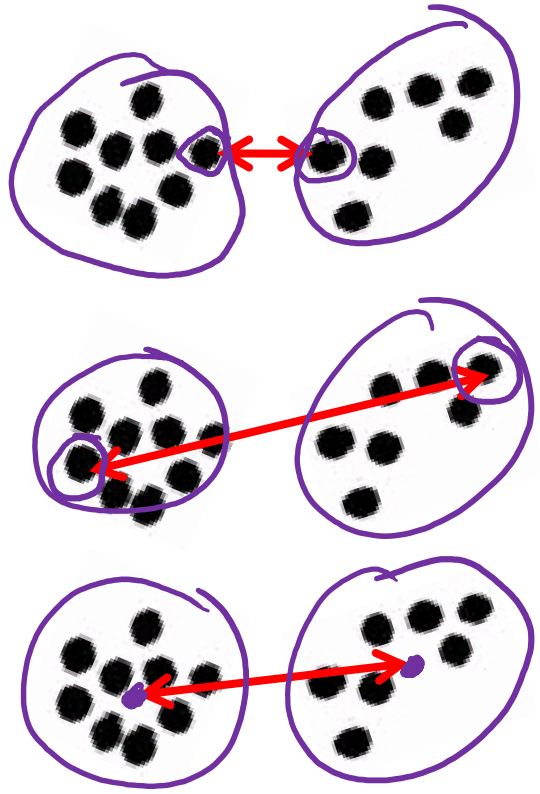


Slide credit: CMU MLD Aarti Singh and Eric Xing

Bottom-up Agglomerative clustering

Different algorithms differ in how the similarities are defined (and hence updated) between two clusters

- Single-Linkage
  - Nearest Neighbor: similarity between their closest members.
- Complete-Linkage
  - Furthest Neighbor: similarity between their furthest members.
- Centroid
  - Similarity between the centers of gravity
- Average-Linkage
  - Average similarity of all cross-cluster pairs.



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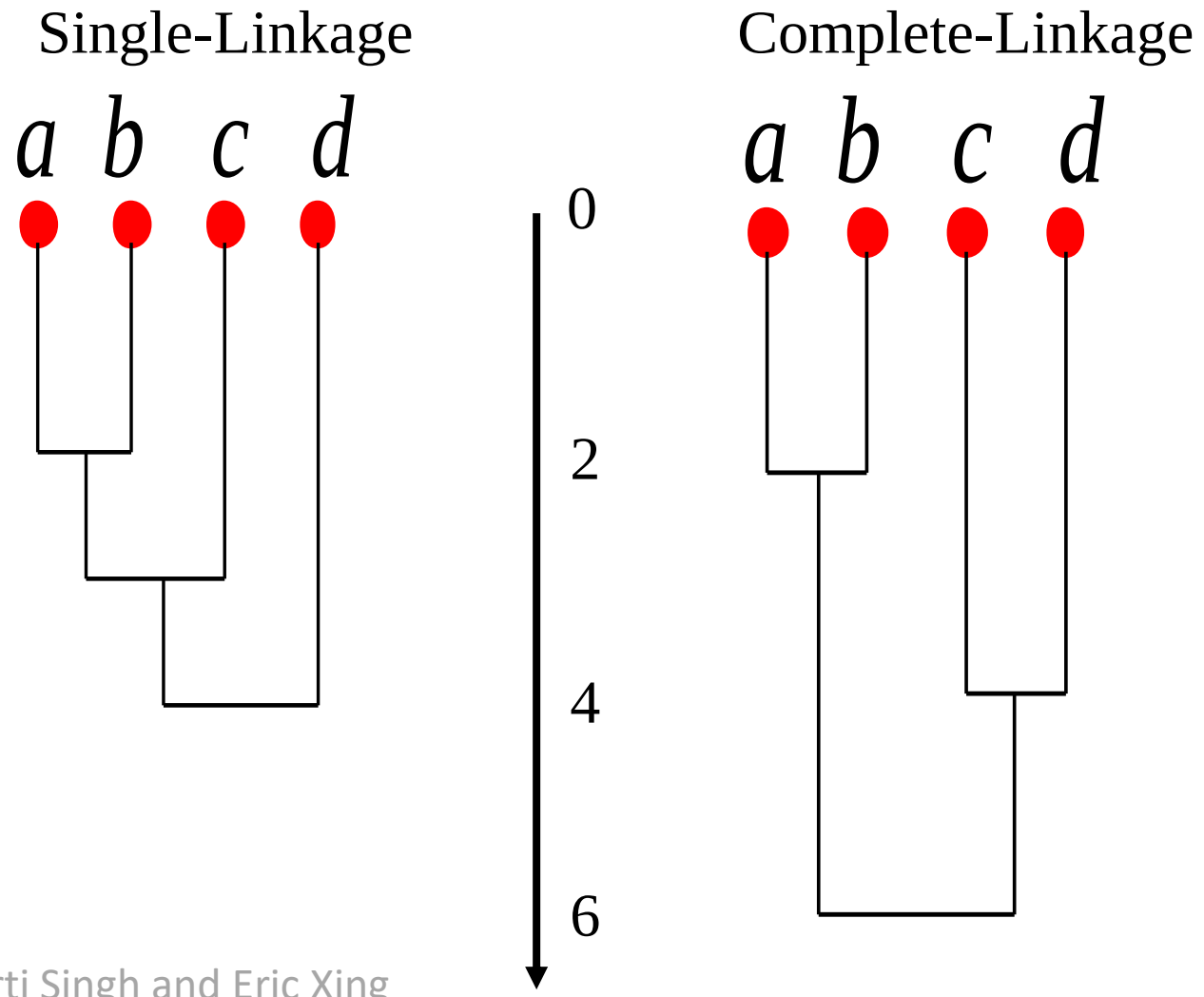
Dendrograms



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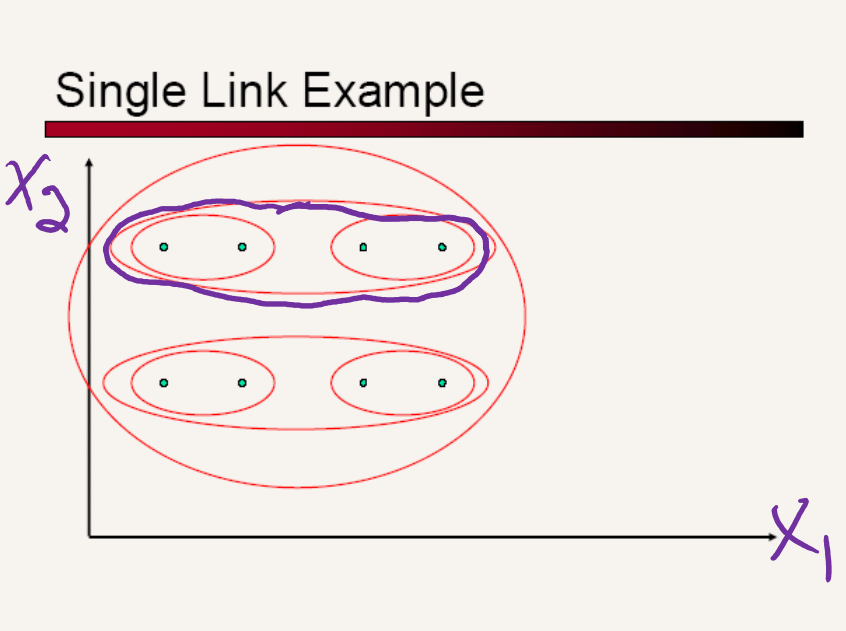
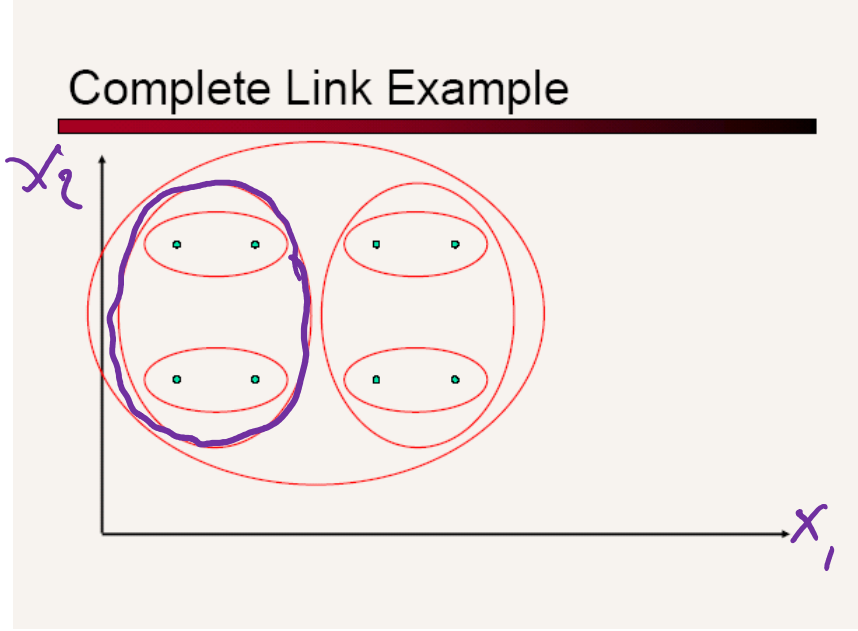
Another Example





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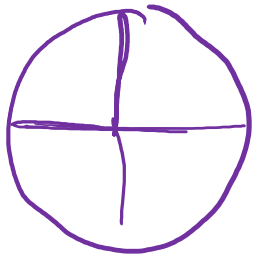
Single vs. Complete Linkage

	Shape of clusters
Single-linkage	allows anisotropic and non-convex shapes
Complete-linkage	assumes isotopic, convex shapes



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Partitioning Algorithms

- Partitioning method: Construct a partition of *N* objects into a set of *K* clusters

- Given: a set of objects and the number *K*

- Find: a partition of *K* clusters that optimizes the chosen partitioning criterion
  - Globally optimal: exhaustively enumerate all partitions NP-hard
  - Effective heuristic method: K-means algorithm

K-Means

Algorithm

Input – Data, $\boldsymbol{x}^{(i)}$, Desired number of clusters, K

Initialize – the K cluster centers (randomly if necessary)

Iterate –

1. Assign points to the nearest cluster centers

2. Re-estimate the K cluster centers (aka the centroid or mean), by assuming the memberships found above are correct.

Termination –

If none of the objects changed membership in the last iteration, exit. Otherwise go to 1.

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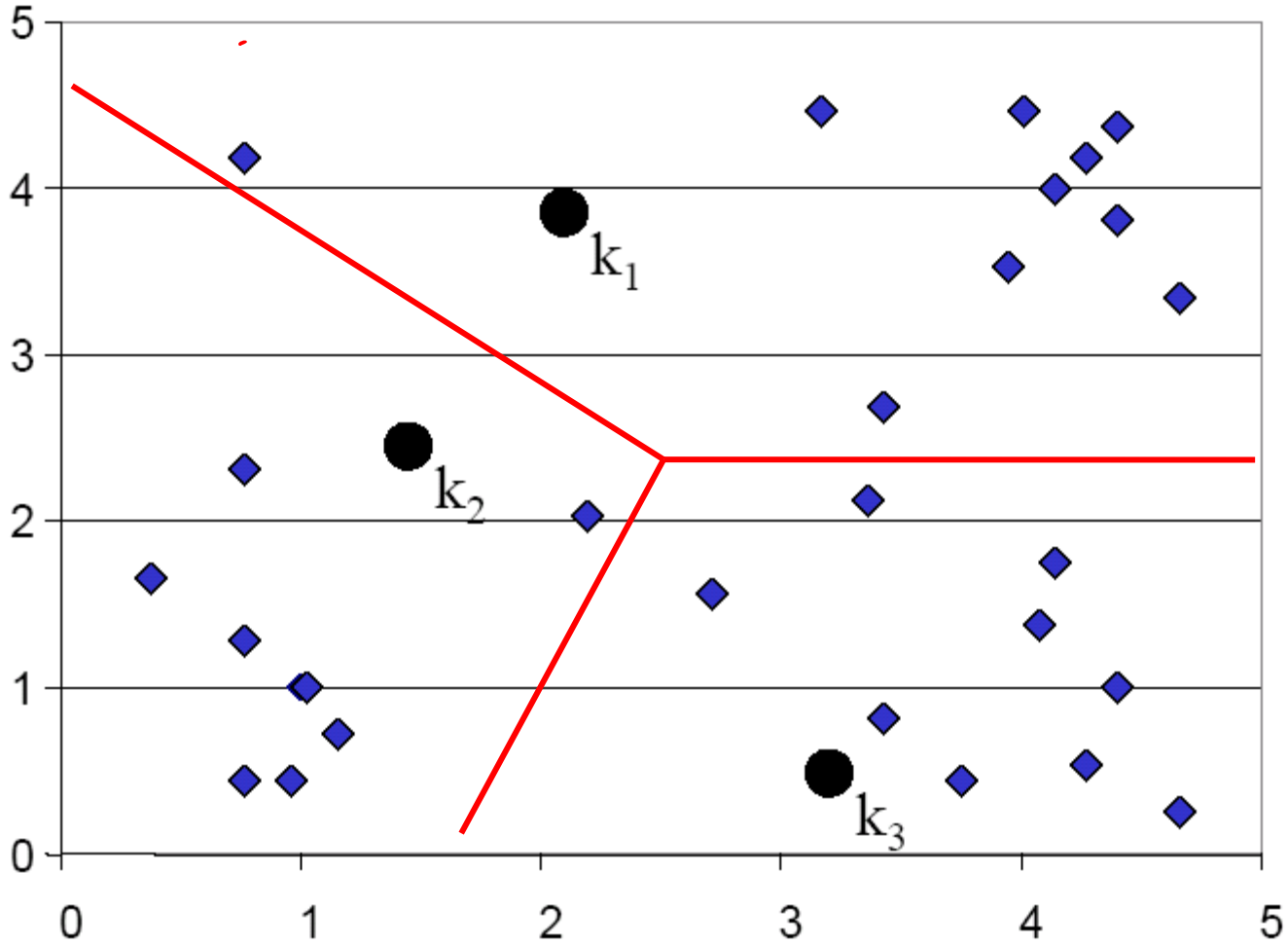
K-means Clustering: Step 1



Voronoi diagram

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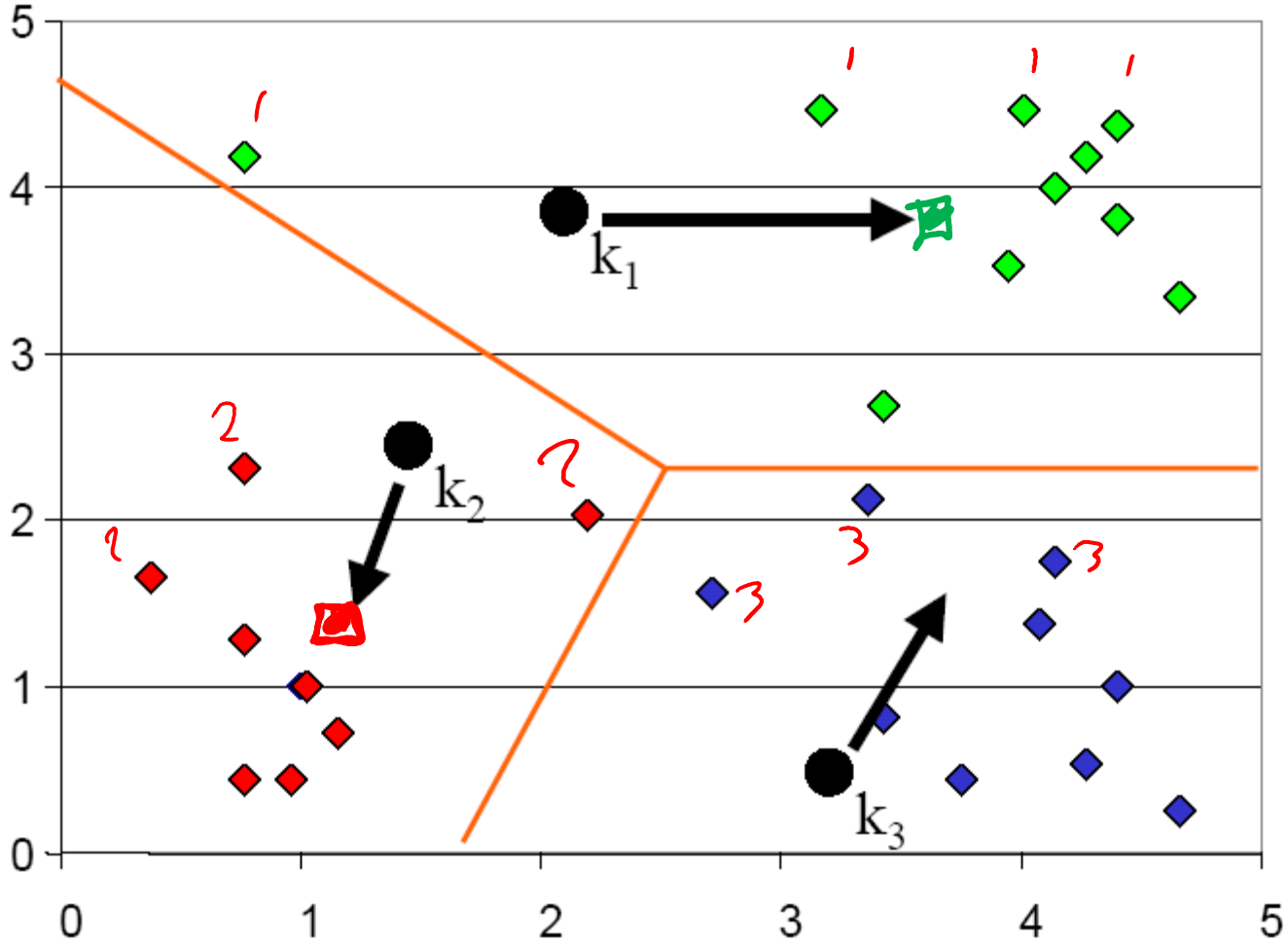
K-means Clustering: Step 2



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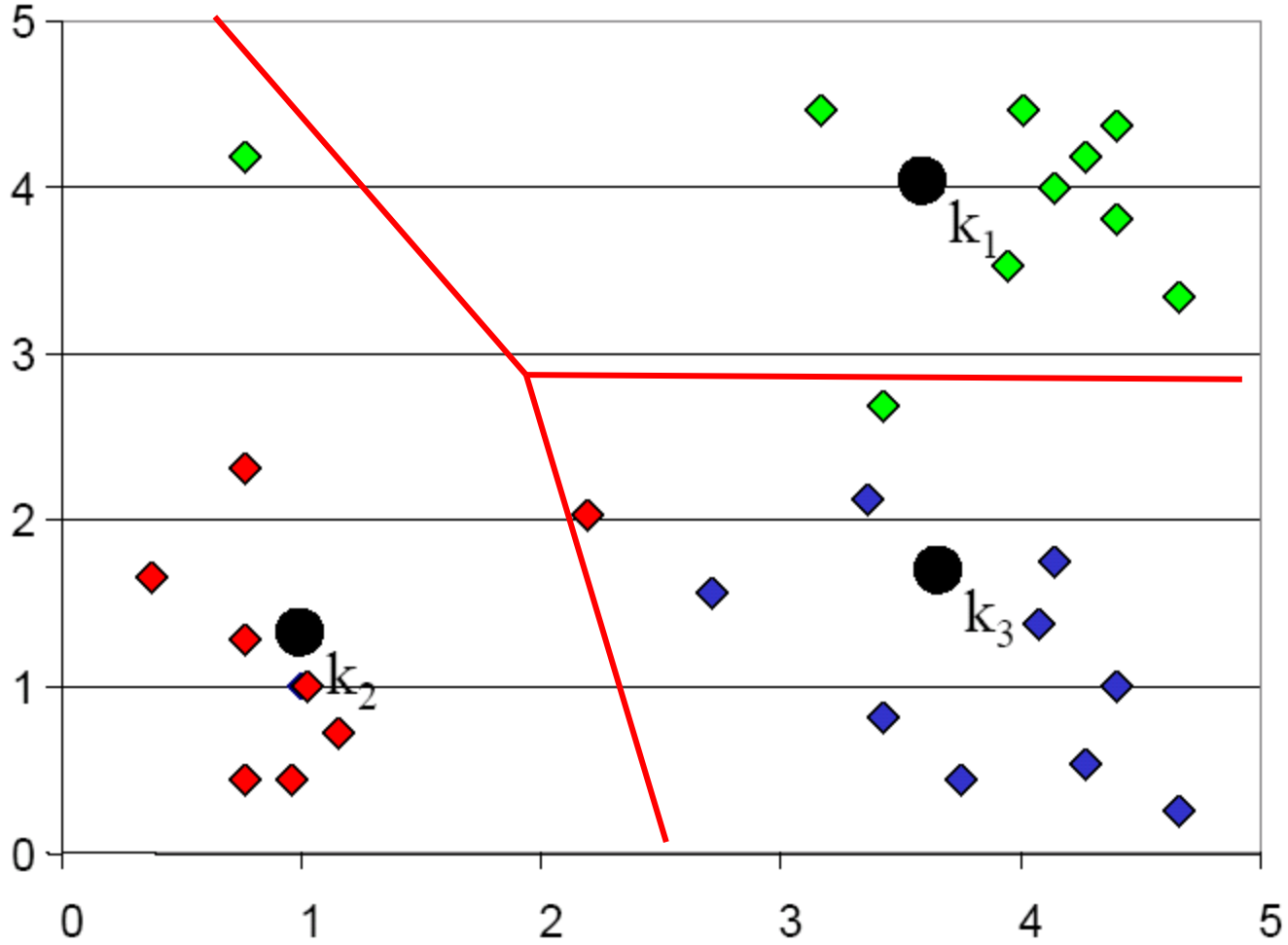
K-means Clustering: Step 3



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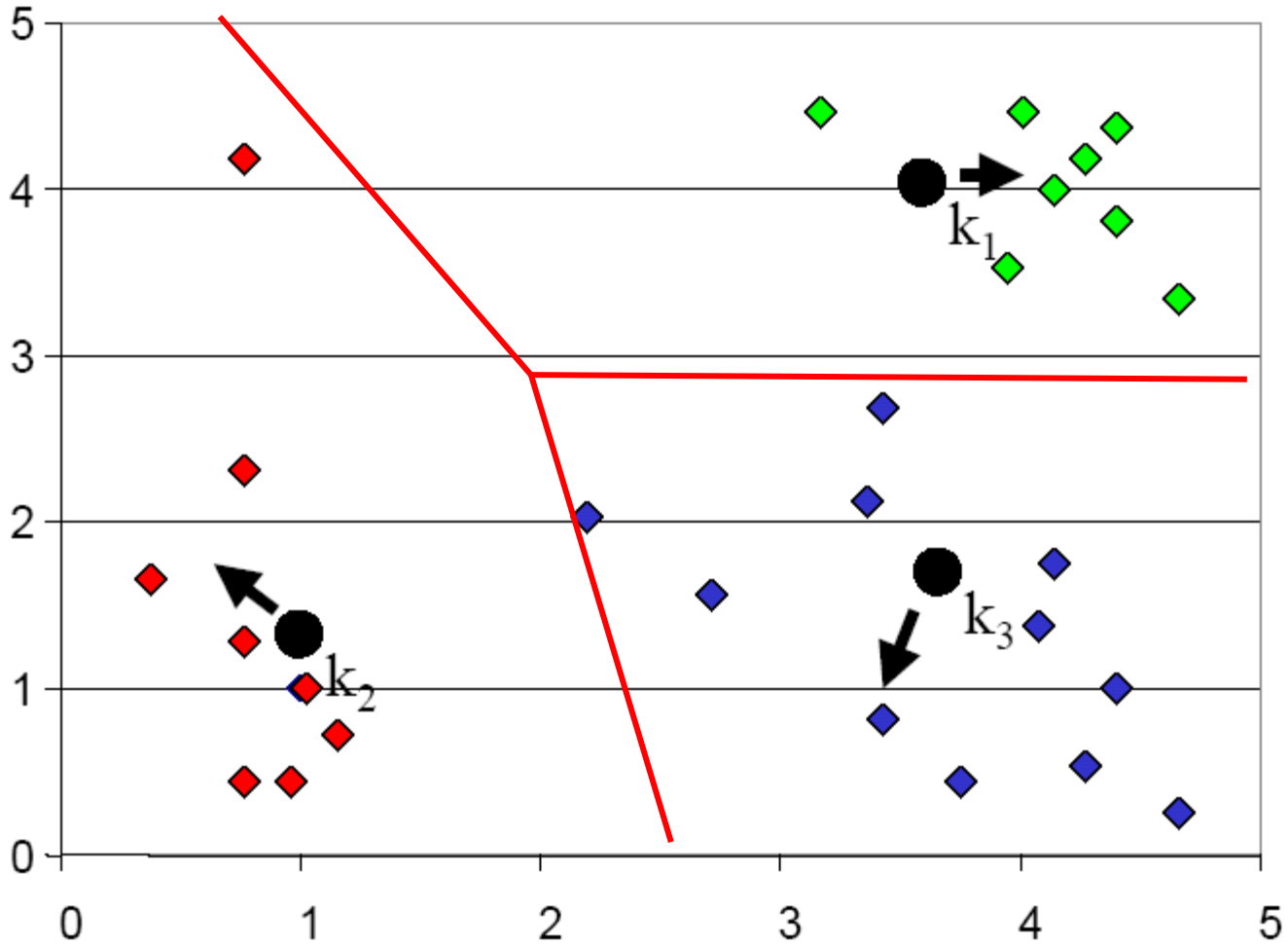
K-means Clustering: Step 4



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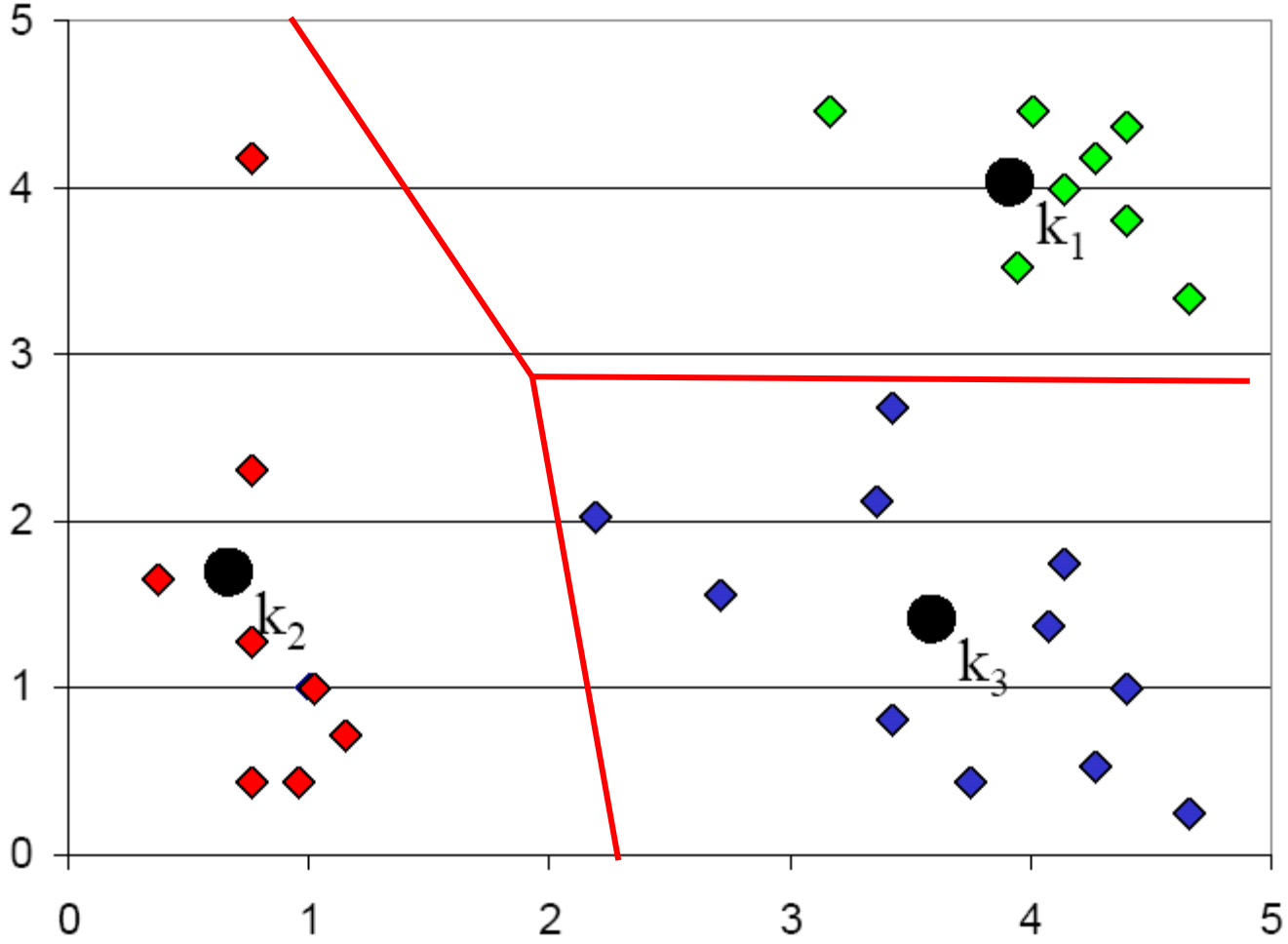
K-means Clustering: Step 5



Slide credit: CMU MLD Eric Xing

K-means Optimization

Optimization recipe

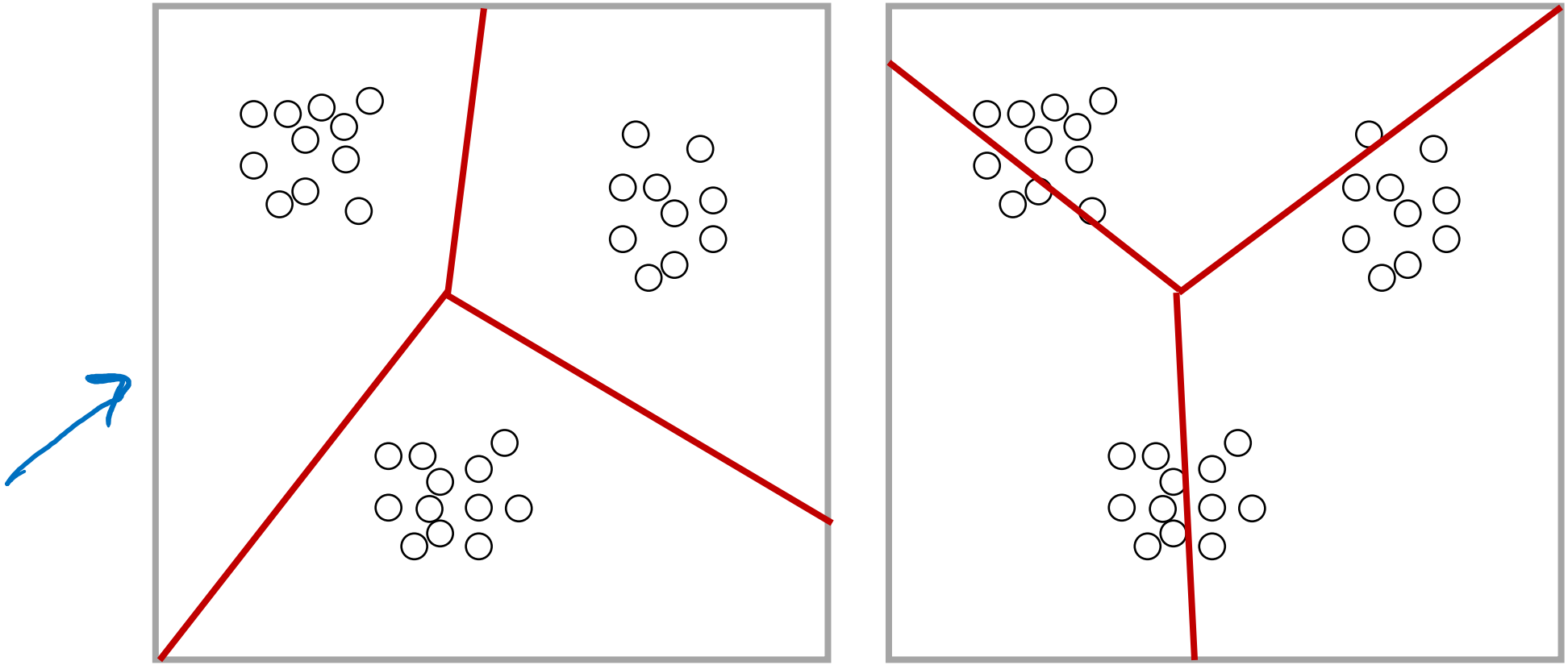
1. Form objective
2. Minimize objective

Slide credit: CMU MLD Matt Gormley

K-means Optimization

Question: Which of these partitions is “better”?

min



K-means Optimization

Input: $\vec{x}^{(1)} \dots \vec{x}^{(N)}$ K $x^{(i)} \in \mathbb{R}^M$

Output: $\vec{z}^{(1)}, \dots \vec{z}^{(N)}$

$\vec{c}_1, \dots \vec{c}_K$ C $\vec{c}_k \in \mathbb{R}^M$

$$C = \underset{C}{\operatorname{argmin}} \sum_{i=1}^{N} \min_{j \in \{1..K\}} \|\vec{x}^{(i)} - \vec{c}_j\|_2^2$$

$$C, \vec{z} = \underset{C}{\operatorname{argmin}} \sum_{i=1}^{N} \min_{z^{(i)} \in \{1..K\}} \|\vec{x}^{(i)} - \vec{c}_{z^{(i)}}\|_2^2$$

$$= \underset{C, \vec{z}}{\operatorname{argmin}} \sum_{i=1}^{N} \|\vec{x}^{(i)} - \vec{c}_{z^{(i)}}\|_2^2$$

Slide credit: CMU MLD Matt Gormley

K-means Optimization

Computational complexity

$$\boldsymbol{C}, \boldsymbol{z} = \underset{\boldsymbol{C}, \boldsymbol{z}}{\operatorname{argmin}} \sum_{i=1}^{N} \left\| \boldsymbol{x}^{(i)} - \boldsymbol{c}_{z^{(i)}} \right\|_2^2$$

NP-hard, $K \geq 2$ or $M \geq 2$

Easy $K=1$

$$\vec{c}_1 = \underset{c_1}{\operatorname{argmin}} \sum_{i=1}^{N} \| x^{(i)} - c_1 \|_2^2$$

$$\vec{c}_1 = \frac{1}{N} \sum_{i=1}^{N} x^{(i)} \leftarrow \text{mean}$$

Not convex ☹

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K-means Optimization

Alternating minimization

a) $\vec{z} = \underset{z}{\operatorname{argmin}} \sum_{i=1}^{N} \|x^i - c_{z^i}\|_2^2$

b) $C = \underset{C}{\operatorname{argmin}} \sum_{i=1}^{N} \|x^i - c_{z^i}\|_2^2$

---

a) $z^{(1)} = \underset{k}{\operatorname{argmin}} \|x^{(1)} - c_k\|_2^2$

$\vdots$

$z^{(N)} = \quad "$

b) $\vec{c}_1 = \underset{c_1}{\operatorname{argmin}} \sum_{i=z^{(i)}=1} \|x^{(i)} - c_1\|_2^2$

$\vdots$

$\vec{c}_K = \underset{c_K}{\operatorname{argmin}} \sum_{i=z^{(i)}=K} \|x^{(i)} - c_k\|_2^2$

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K-means Optimization

Alternating minimization

Alternating minimization

Where have we seen this before?

Recommender Systems

$$\min_{\boldsymbol{U},\boldsymbol{V}} J(\boldsymbol{U},\boldsymbol{V}) \qquad J(\boldsymbol{U},\boldsymbol{V}) = \sum_{i,j\in\mathcal{S}} \left(R_{ij} - \boldsymbol{u}^{(i)T}\boldsymbol{v}^{(j)}\right)^2$$

① $\min_{U} J(U, V)$ $\quad U^{t+1} \leftarrow U^t - \alpha \nabla_U J$

② $\min_{V} J(U, V)$ $\quad V \leftarrow V - \alpha \nabla_V J$

Alternating minimization

Two different approaches

$$\min_{\alpha,\beta} \; J(\alpha, \beta)$$

1) Gradient decent
   a) $\alpha \leftarrow \alpha - \eta \nabla_\alpha J$
   b) $\beta \leftarrow \beta - \eta \nabla_\beta J$

   step η

2) Block coordinate decent
   a) $\alpha = \underset{\alpha}{\operatorname{argmin}} \; J(\alpha, \beta)$
   b) $\beta = \underset{\beta}{\operatorname{argmin}} \; J(\alpha, \beta)$

   no hyperparameters!

Alternating minimization

Two different approaches

$$\min_{\theta_1,\theta_2} J(\theta_1, \theta_2)$$

1) Gradient descent

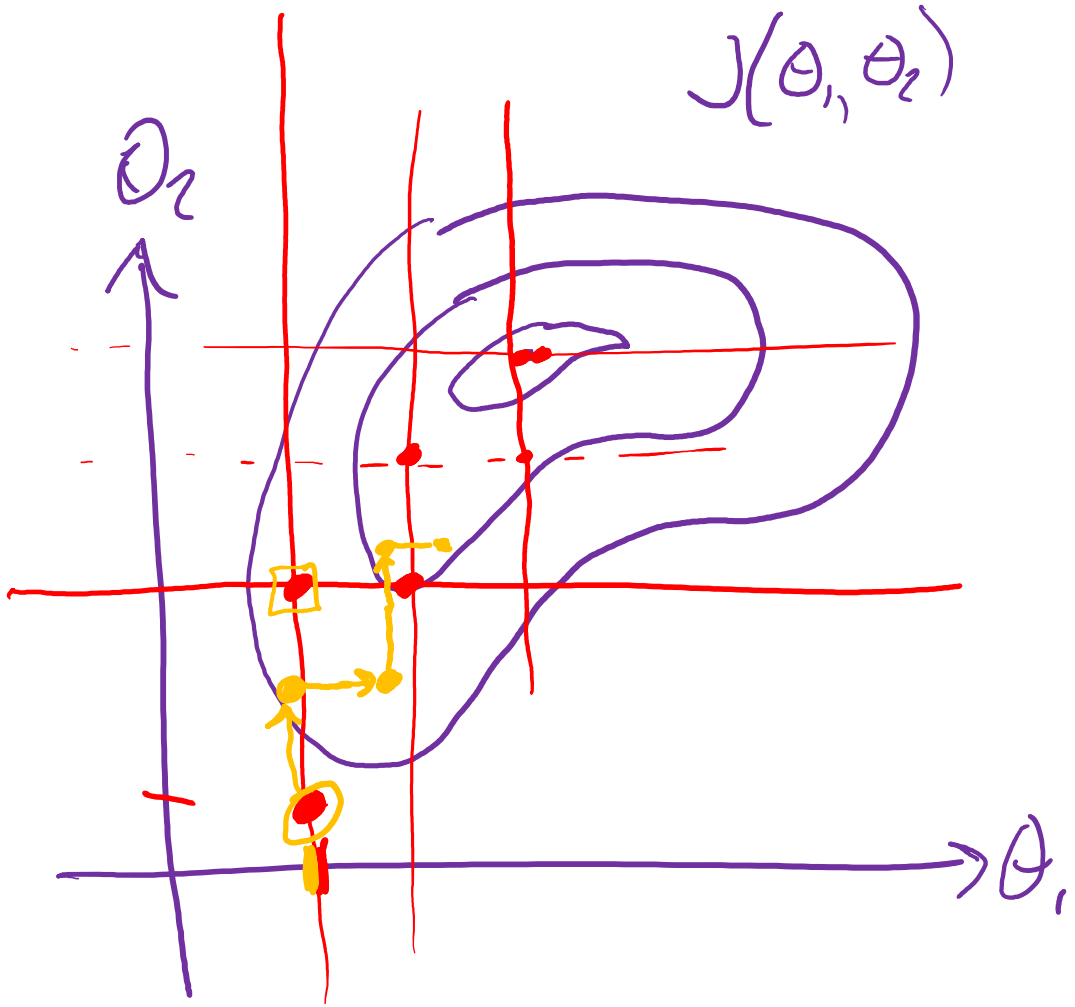
a) $\theta_1 = \theta_1 - \eta \frac{dJ}{d\theta_1}$

→ b) $\theta_2 = \theta_2 - \eta \frac{dJ}{d\theta_2}$

2) Coordinate descent

→ a) $\theta_1 = \text{argmin}_{\theta_1} J(\theta_1, \theta_2)$

b) $\theta_2 = \text{argmin}_{\theta_2} J(\theta_1, \theta_2)$



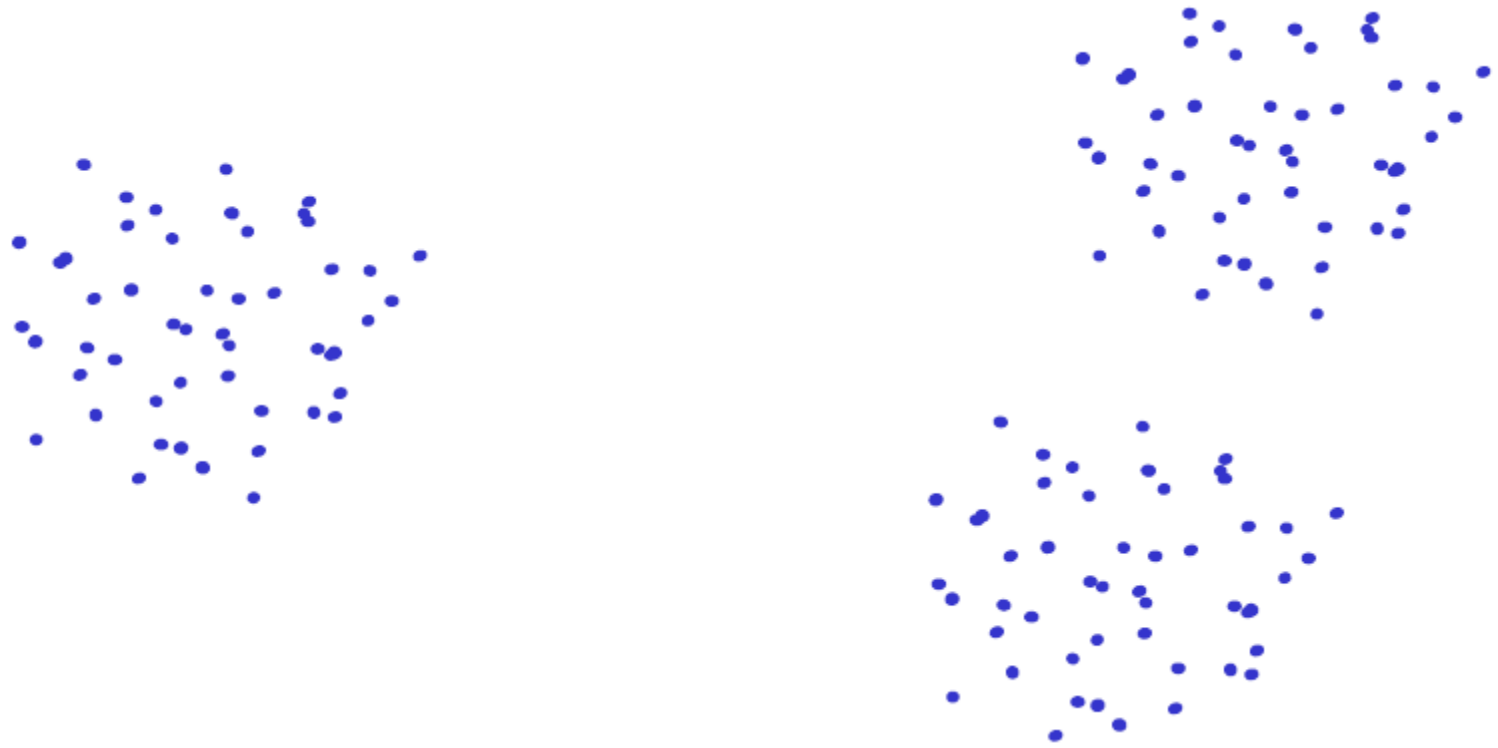
Computational Complexity

- At each iteration,
  - Computing cluster centers: Each object gets added once to some cluster: O(N)
  - Computing distance between each of the N objects and the K cluster centers is O(KN)

- Assume these two steps are each done once for l iterations: O(lKN)

Issues: Seed Choice

- Results are quite sensitive to seed selection.



Slide credit: CMU MLD Aarti Singh

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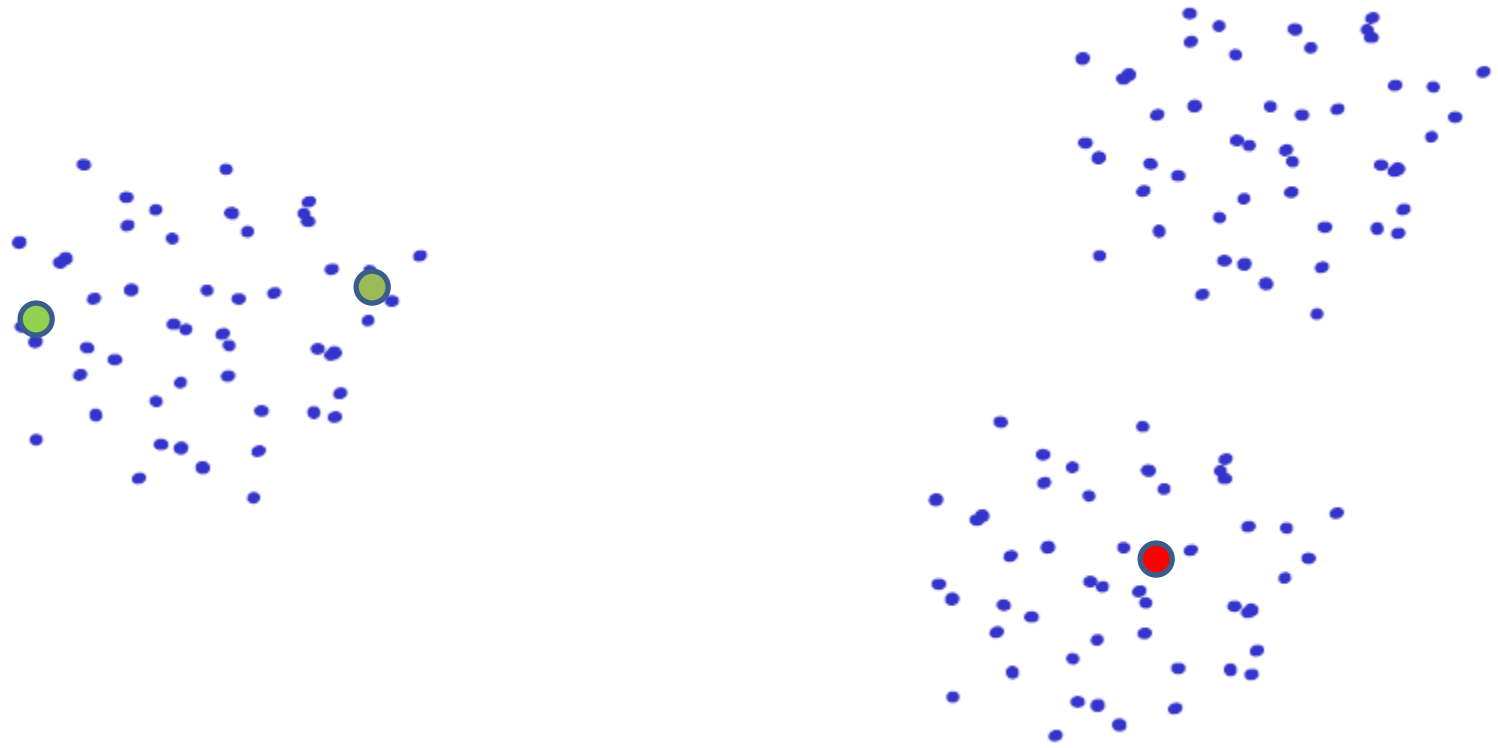

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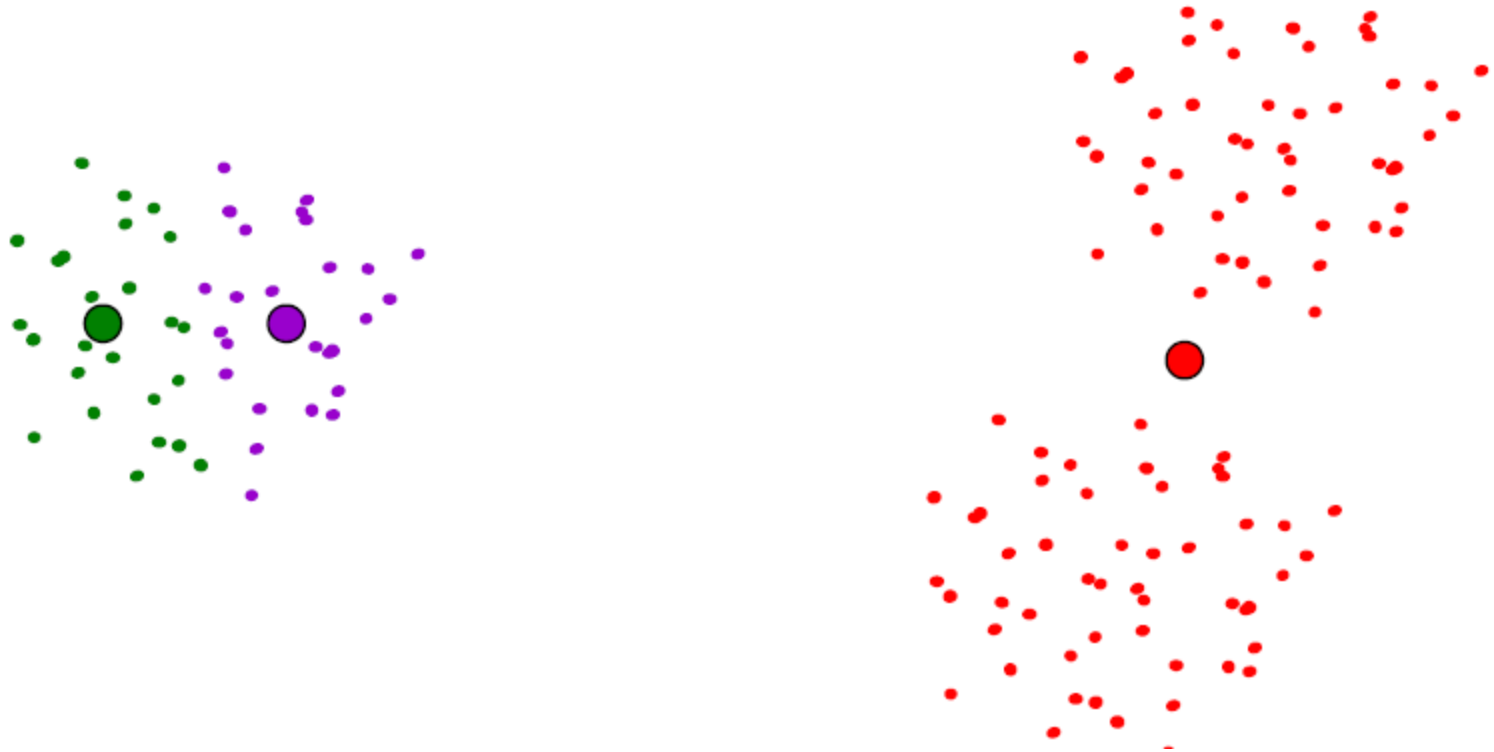

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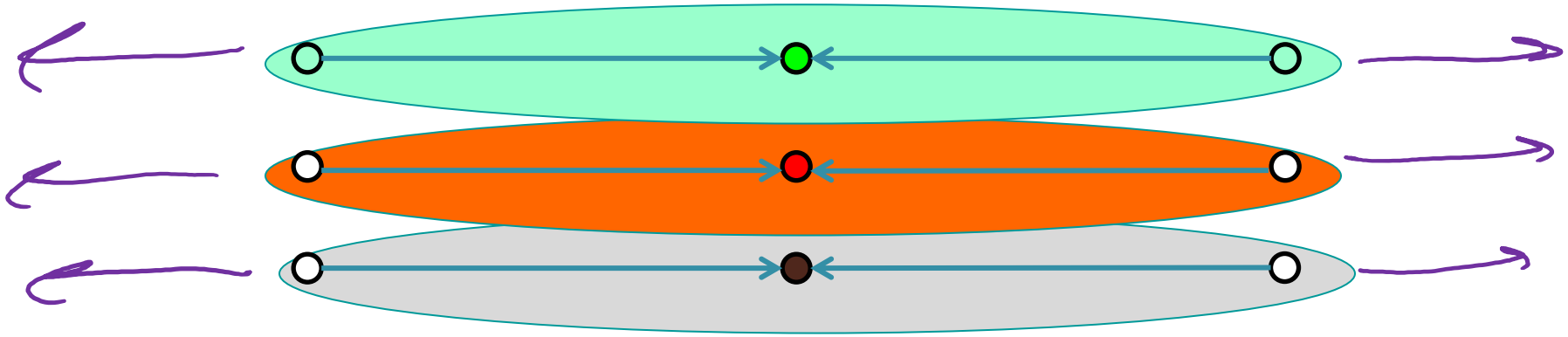
Issues: Seed Choice



K-means always converges, but it may converge at a local optimum that is different from the global optimum, and in fact could be arbitrarily worse in terms of its objective.

Slide credit: CMU MLD Nina Balcan

Issues: Seed Choice

- Results can vary based on random seed selection.

- Some seeds can result in poor convergence rate, or convergence to sub-optimal clustering.
  - Try out multiple starting points (very important!!!)
  - k-means ++ algorithm of Arthur and Vassilvitskii

    key idea: choose centers that are far apart

    (probability of picking a point as cluster center $\propto$ distance from nearest center picked so far)

Other Issues

- Shape of clusters
  - Assumes isotropic, equal variance, convex clusters

- Sensitive to Outliers
  - use K-medoids

Slide credit: CMU MLD Aarti Singh

K-medoids

median

Use actual training point as cluster center (medoid) rather than mean

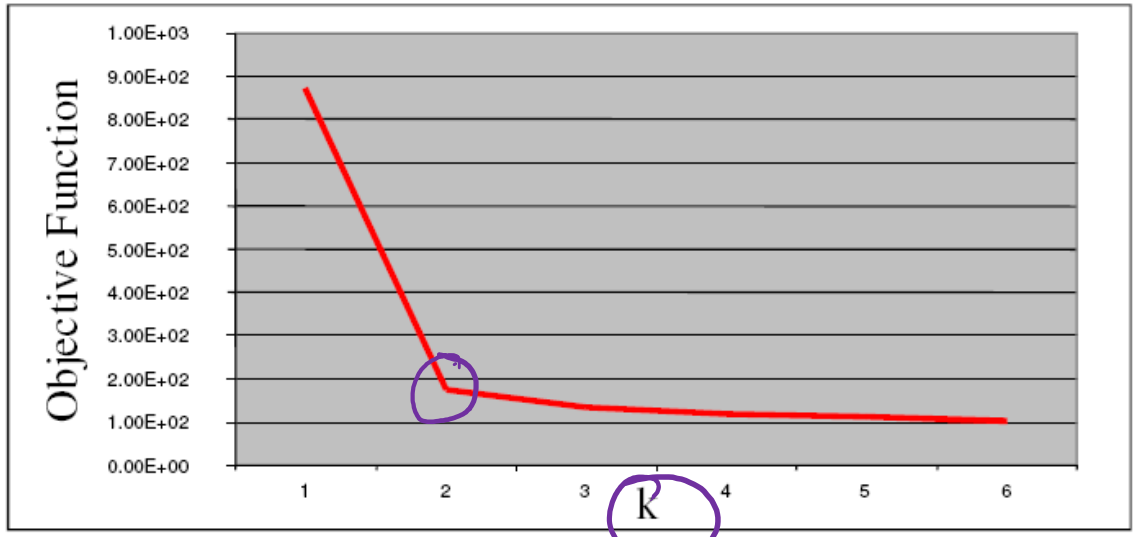
- More robust to outliers pulling the mean away
- Better interpretability, can “visualize” the medoid
- More work to compute medoid than mean

Other Issues

- Number of clusters K
  - Objective function

$$\sum_{j=1}^{m} ||\mu_{C(j)} - x_j||^2$$

  - Look for "Knee" in objective function



  - Can you pick K by minimizing the objective over K?

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K-means algorithm

- Optimize potential function:

$$\min_{\mu} \min_{C} F(\mu, C) = \min_{\mu} \min_{C} \sum_{i=1}^{k} \sum_{j:C(j)=i} ||\mu_i - x_j||^2$$

- **K-means algorithm:** (coordinate descent on F)

(1) Fix μ, optimize C — **Expected** cluster assignment

(2) Fix C, optimize μ — **Maximum** likelihood for center

Next lecture, we will see a generalization of this approach:

EM algorithm

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